

Exercise Sheet 6

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Generalized Linear Models

1. Newton Optimization

(a)

Proof. First we recall the Taylor expansion in vector notation:

$$f(x + \delta x) = f(x) + \sum_{j=1}^N \frac{\partial f(x)}{\partial x_j} \delta x_j + \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \frac{\partial^2 f(x)}{\partial x_i \partial x_j} \delta x_i \delta x_j + \dots$$
$$f(x + \delta x) = f(x) + \delta^T x \nabla f(x) + \frac{1}{2} \delta^T x H \delta x + \dots$$

Using the notation stated in the exercise and constructing a quadratic approximation we get:

$$L(f_0 + \delta) = \tilde{L}(f_0 + \delta) = L(f_0) + \delta^T \nabla L(f_0) + \frac{1}{2} \delta^T B(f_0) \delta$$
$$f_1 = f_0 + \delta \quad \text{which leads to:} \quad \delta = f_1 - f_0$$

Taking the derivative in respect to δ equal to zero and substituting $\delta = f_1 - f_0$ gives the following:

$$0 \stackrel{!}{=} \frac{d}{d\delta} \tilde{L}(f_0 + \delta) = \nabla L(f_0) + B(f_0) \delta$$
$$-B(f_0)(f_1 - f_0) = \nabla L(f_0)$$
$$B(f_0)(f_0 - f_1) = \nabla L(f_0)$$
$$f_0 - f_1 = B^{-1}(f_0) \nabla L(f_0)$$
$$f_1 = f_0 - B^{-1}(f_0) \nabla L(f_0)$$

□

Which shows that the minimum of this approximation lies at $f_1 = f_0 - B^{-1}(f_0) \nabla L(f_0)$ which was to be shown.

(b)

Rewriting the second-order expansion from above and setting the gradient to zero gives the following:

$$\begin{aligned}L(w + \epsilon) &= \tilde{L}(w + \epsilon) = L(\phi^T w) + \epsilon^T \nabla L(\phi^T w) + \frac{1}{2} \epsilon^T B(\phi^T w) \epsilon \\0 &\stackrel{!}{=} \frac{d}{d\epsilon} \tilde{L}(w + \epsilon) = \nabla L(\phi^T w) + B(\phi^T w) \epsilon \\-B(\phi^T w)(w - w_0) &= \nabla L(\phi^T w) \\B(\phi^T w)(w_0 - w) &= \nabla L(\phi^T w) \\w_0 - w &= B^{-1}(\phi^T w) \nabla L(\phi^T w) \\w &= w_0 - B^{-1}(\phi^T w) \nabla L(\phi^T w)\end{aligned}$$

This leads to the Newton step in w with $w = w_0 - B^{-1}(\phi^T w) \nabla L(\phi^T w)$, which was asked in the exercise.

2. Logistic Link Function

$$\frac{\partial \log \sigma(yf)}{\partial f} = \frac{ye^{yf}}{(e^{yf} + 1)^2}$$