Matrix Theory EE5609 - Assignment 7

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Abstract-Find foot of the perpendicular using SVD

Download python code from

https://github.com/SANDHYA-A/Assignment7

1 PROBLEM

Find the foot of the perpendicular for a point on the line of intersection of planes $9x^2 - 4y^2 + z^2 - 6xz - 4y - 1 = 0$ on to the plane containing the point (-1, -4, 3).

2 SOLUTION

Given the equation of two intersecting planes is

$$9x^2 - 4y^2 + z^2 - 6xz - 4y - 1 = 0 (2.0.1)$$

1) Second order equation in terms of matrices:

The general equation of a second order algebraic surface is given by

$$ax^{2} + by^{2} + cz^{2} + 2dxy + 2exz$$
$$+ 2fyz + 2lx + 2my + 2nz + q = 0. \quad (2.0.2)$$

This equation can be written as:-

$$\mathbf{x}^T \mathbf{V} \mathbf{x} + 2\mathbf{u}^T \mathbf{x} + f = 0 \qquad (2.0.3)$$

$$\mathbf{V} = \begin{pmatrix} a & d & e \\ d & b & f \\ e & f & c \end{pmatrix} \quad \mathbf{u} = \begin{pmatrix} l \\ m \\ n \end{pmatrix} \quad (2.0.4)$$

Substituting values from the given equation (2.0.1), we get,

$$\mathbf{x}^{T} \begin{pmatrix} 9 & 0 & -6 \\ 0 & -4 & 0 \\ -6 & 0 & 1 \end{pmatrix} \mathbf{x} + 2 \begin{pmatrix} 0 \\ -2 \\ 0 \end{pmatrix}^{T} \mathbf{x} - 1 = 0$$
(2.0.5)

$$\mathbf{V} = \begin{pmatrix} 9 & 0 & -6 \\ 0 & -4 & 0 \\ -6 & 0 & 1 \end{pmatrix} \quad \mathbf{u} = \begin{pmatrix} 0 \\ -2 \\ 0 \end{pmatrix} \quad f = -1$$
(2.0.6)

2) Finding equation of individual planes:

Let the two normals for these planes be $\mathbf{n_1}$ and $\mathbf{n_2}$

$$a_1x + b_1y + c_1z + d_1 = 0 (2.0.7)$$

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$$a_2x + b_2y + c_2z + d_2 = 0 (2.0.8)$$

We have,

$$(a_1x + b_1y + c_1z + d_1)(a_2x + b_2y + c_2z + d_2) = 0$$
(2.0.9)

From equation (2.0.1) and (2.0.9) we get the equations of two planes as:

$$(3x - 2y - z - 1)(3x + 2y - z + 1) = 0$$

$$(2.0.10)$$

$$3x - 2y - z - 1 = 0$$

$$(2.0.11)$$

$$3x + 2y - z + 1 = 0$$

$$(2.0.12)$$

3) Equation of normal to individual planes:

Let equation (2.0.11) and (2.0.12) be denoted as E_1 and E_2 . Let k_1 and k_2 be two arbitrary constants. Then,

$$k_1 E_1 + k_2 E_2 = 0 (2.0.13)$$

represents a linear equation and this equation will be satisifed by coordinates of the points that lie on both these planes.

Let us assume the constants $k_1 = 1$ and $k_2 = 1$. Then the resultant equation from (2.0.13) represents a plane through the line of intersection of the planes E_1 and E_2 and is given by:

$$1.(3x - 2y - z - 1) + 1.(3x + 2y - z + 1) = 0 (2.0.14)$$

$$3x = z$$
 (2.0.15)

$$(3 \ 0 \ -1) \mathbf{x} = 0 \tag{2.0.16}$$

4) Equation of line of intersection of planes:

Equation (2.0.16) is the equation of the normal to E_1 and E_2 . Also, from equation (2.0.11) and (2.0.12), we obtain the equation of line of intersection of the given planes as

$$3x = z \text{ and } y = \frac{-1}{2}$$
 (2.0.17)

5) Equation of plane passing through point (-1, -4,3) and perpendicular to plane at (2.0.16):

Let, r be $(x \ y \ z)$. Now, the equation of the plane passing through the point Q(-1, -4,3) can be obtained by

$$\mathbf{n}.(\mathbf{r} - \mathbf{Q}) = 0 \tag{2.0.18}$$

$$(3 \quad 0 \quad -1) \begin{pmatrix} x+1 \\ y+4 \\ z-3 \end{pmatrix} = 0$$
 (2.0.19)

Thus, equation of the plane containing the point(-1, -4, 3) is obtained as

$$(3 \ 0 \ -1) \mathbf{x} = -6 \tag{2.0.20}$$

6) Finding normal vectors:

The equation of the plane at (2.0.20) can be expressed as:

$$\mathbf{n}^T \mathbf{x} = c \tag{2.0.21}$$

Rewriting given equation of plane in (2.0.21) form

$$\begin{pmatrix} 3 & 0 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = -6 \tag{2.0.22}$$

where the value of

$$\mathbf{n} = \begin{pmatrix} 3 \\ 0 \\ -1 \end{pmatrix} \tag{2.0.23}$$

$$\mathbf{x} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} \tag{2.0.24}$$

$$c = -6 (2.0.25)$$

The two vectors \mathbf{q} and \mathbf{r} which are \perp to \mathbf{n} can be obtained by

$$\begin{pmatrix} 3 & 0 & -1 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 0 \tag{2.0.26}$$

$$\implies 3a - c = 0 \tag{2.0.27}$$

Put
$$a=0$$
 and $b=1$ in (2.0.27), $\implies c=0$
Put $a=1$ and $b=0$ in (2.0.27), $\implies c=3$

Hence

$$\mathbf{q} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \mathbf{r} = \begin{pmatrix} 1 \\ 0 \\ 3 \end{pmatrix} \tag{2.0.28}$$

An arbitrary point on line of intersection of two planes at equation (2.0.1) can be taken as:

$$\mathbf{b} = \begin{pmatrix} 1\\ \frac{-1}{2}\\ 3 \end{pmatrix} \tag{2.0.29}$$

7) Solution using Singular Value Decomposition:

So, now we have two orthogonal vectors \mathbf{q} and \mathbf{r} and \mathbf{M} is the matrix of these orthogonal vectors. We can solve the equation :

$$\mathbf{M}\mathbf{x} = \mathbf{b} \tag{2.0.30}$$

Substituting the values of normal vectors and the point on the plane in (2.0.30), we get,

$$\begin{pmatrix} 0 & 1 \\ 1 & 0 \\ 0 & 3 \end{pmatrix} \mathbf{x} = \begin{pmatrix} 1 \\ \frac{-1}{2} \\ 3 \end{pmatrix} \tag{2.0.31}$$

To solve the above equation, we perform Singular Value Decomposition on M as follows,

$$\mathbf{M} = \mathbf{U}\mathbf{S}\mathbf{V}^T \tag{2.0.32}$$

Where the columns of V are the eigen vectors of M^TM , the columns of U are the eigen vectors of MM^T and S is diagonal matrix of singular value of eigenvalues of M^TM .

$$\mathbf{M}^T \mathbf{M} = \begin{pmatrix} 1 & 0 \\ 0 & 10 \end{pmatrix} \tag{2.0.33}$$

$$\mathbf{M}\mathbf{M}^T = \begin{pmatrix} 1 & 0 & 3 \\ 0 & 1 & 0 \\ 3 & 0 & 9 \end{pmatrix} \tag{2.0.34}$$

As we know that,

$$\mathbf{USV}^{T}\mathbf{x} = \mathbf{b}$$

$$\implies \mathbf{x} = \mathbf{VS}_{+}\mathbf{U}^{T}\mathbf{b}$$
 (2.0.35)

Where S_+ is Moore-Penrose Pseudo-Inverse of S.

a) Calculating eigenvalues and eigen vectors of $\mathbf{M}\mathbf{M}^T$:

$$\begin{vmatrix} \mathbf{M}\mathbf{M}^T - \lambda \mathbf{I} | = 0 \\ \Rightarrow \begin{vmatrix} 1 - \lambda & 0 & 3 \\ 0 & 1 - \lambda & 0 \\ 3 & 0 & 9 - \lambda \end{vmatrix} = 0 \\ \Rightarrow -\lambda^3 + 11\lambda^2 - 10\lambda = 0$$

Hence eigenvalues of MM^T are,

$$\lambda_1 = 10; \quad \lambda_2 = 1; \quad \lambda_3 = 0 \quad (2.0.36)$$

And the corresponding eigenvectors are,

$$\mathbf{u_1} = \begin{pmatrix} \frac{1}{3} \\ 0 \\ 1 \end{pmatrix}; \quad \mathbf{u_2} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}; \quad \mathbf{u_3} = \begin{pmatrix} -3 \\ 0 \\ 1 \end{pmatrix}$$
(2.0.37)

Normalizing the eigen vectors we get,

$$\mathbf{u}_{1} = \begin{pmatrix} \frac{1}{\sqrt{10}} \\ 0 \\ \frac{3}{\sqrt{10}} \end{pmatrix}, \mathbf{u}_{2} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \mathbf{u}_{3} = \begin{pmatrix} -\frac{3}{\sqrt{10}} \\ 0 \\ \frac{1}{\sqrt{10}} \end{pmatrix}$$
(2.0.38)

U is obtained as follows,

$$\mathbf{U} = \begin{pmatrix} \frac{1}{\sqrt{10}} & 0 & -\frac{3}{\sqrt{10}} \\ 0 & 1 & 0 \\ \frac{3}{\sqrt{10}} & 0 & \frac{1}{\sqrt{10}} \end{pmatrix}$$
 (2.0.39)

Using values from (2.0.36),

$$\mathbf{S} = \begin{pmatrix} \sqrt{10} & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix} \tag{2.0.40}$$

b) Calculating eigen values and eigen vectors of M^TM :

$$\begin{vmatrix} \mathbf{M}^T \mathbf{M} - \lambda \mathbf{I} | = 0 \\ \implies \begin{vmatrix} 1 - \lambda & 0 \\ 0 & 10 - \lambda \end{vmatrix} = 0 \\ \implies \lambda^2 - 11\lambda + 10 = 0$$

Hence, eigenvalues of M^TM are,

$$\lambda_4 = 10; \quad \lambda_5 = 1$$

And the corresponding eigenvectors are,

$$\mathbf{v}_1 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}; \quad \mathbf{v}_2 = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \tag{2.0.41}$$

From (2.0.41) we obtain V as,

$$\mathbf{V} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \tag{2.0.42}$$

Hence we obtain SVD of M as:

$$\mathbf{M} = \begin{pmatrix} \frac{1}{\sqrt{10}} & 0 & -\frac{3}{\sqrt{10}} \\ 0 & 1 & 0 \\ \frac{3}{\sqrt{10}} & 0 & \frac{1}{\sqrt{10}} \end{pmatrix} \begin{pmatrix} \sqrt{10} & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$
(2.0.43)

Moore-Penrose Pseudo inverse of S is obtained as,

$$\mathbf{S}_{+} = \begin{pmatrix} \frac{1}{\sqrt{10}} & 0 & 0\\ 0 & 1 & 0 \end{pmatrix} \tag{2.0.44}$$

Using equation (2.0.29),(2.0.39),(2.0.42) and (2.0.44) in equation (2.0.35) we obtain value of x as:

$$\mathbf{U}^T \mathbf{b} = \begin{pmatrix} \sqrt{10} \\ \frac{-1}{2} \\ 0 \end{pmatrix} \tag{2.0.45}$$

$$\mathbf{S}_{+}\mathbf{U}^{T}\mathbf{b} = \begin{pmatrix} 1\\ \frac{-1}{2} \end{pmatrix} \tag{2.0.46}$$

$$\mathbf{x} = \mathbf{V}\mathbf{S}_{+}\mathbf{U}^{T}\mathbf{b} = \begin{pmatrix} \frac{-1}{2} \\ 1 \end{pmatrix}$$
 (2.0.47)

8) Solution verification:

We can verify the obtained solution,

$$\mathbf{M}^T \mathbf{M} \mathbf{x} = \mathbf{M}^T \mathbf{b} \tag{2.0.48}$$

Computing the RHS values in equation 2.0.48, we get,

$$\mathbf{M}^T \mathbf{M} \mathbf{x} = \begin{pmatrix} \frac{-1}{2} \\ 10 \end{pmatrix} \tag{2.0.49}$$

$$\implies \begin{pmatrix} 1 & 0 \\ 0 & 10 \end{pmatrix} \mathbf{x} = \begin{pmatrix} \frac{-1}{2} \\ 10 \end{pmatrix} \tag{2.0.50}$$

The values of x is obtained as:

$$\mathbf{x} = \begin{pmatrix} \frac{-1}{2} \\ 1 \end{pmatrix} \tag{2.0.51}$$

Comparing equation (2.0.47) and (2.0.51) solution is verified.