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# CSE211-Formal Languages and Automata Theory

## U3L2 – Introduction to Turing Machines

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# Agenda

- Recap of CSG and LBA
- Computational models
- Why Turing Machines?
- What is Turing Machine?
- How does Turing machine work?

# Natures of computational model

- *Predicate calculus* --- declarative
  - *Partial-recursive functions* --- computational (a programming-language-like notion)
  - *Turing machine* --- computational (computer-like)
- (invented by **Alan Turing** several years before true computers were invented)

# Equivalence of *maximal* computational models

- *All maximal computational models*
  - *compute the same functions*  
*(or )*
  - *recognize the same languages,*  
*having the same power of computation.*

# Why Turing Machines?

- The **study of decidability** provides guidance to programmers about what **they might** or **might not** be able to accomplish through programming
- **Previous problems** are **dealt** with programs
- But **not all problems** can be solved by programs
- We **need a simple model** to deal with other decision problems (like grammar ambiguity problems)
- The ***Turing machine*** is one of such models, whose **configuration is easy to describe**, but whose function is the most versatile

# Why Turing Machines?

- Why not deal with C programs or something like that?
- **Answer:** You can, but **it is easier** to prove things about TM's, because they are **so simple**
  - And yet they are as powerful as any computer.
    - More so, in fact, since they have infinite memory.

# Then Why Not Finite-State Machines to Model Computers?

- In principle, you could, but it is not instructive.
- Programming models don't build in a limit on memory.
- In practice, you can go to Fry's and buy another disk.
- But finite automata vital at the chip level (model-checking).

# Hypothesis

*All computations done by a modern computer can be done by a Turing machine.*

- (a hypothesis which is not proved but believed so far!)



# Turing-Machine Formal def.

- A Turing machine (TM) is a 7-tuple  $M = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$  where
  1.  $Q$ : A finite set of *states*
  2.  $\Sigma$ : An *input alphabet*
  3.  $\Gamma$ : A *tape alphabet* (with  $\Sigma$  being a *subset* of it).
  4.  $\delta$ : A *transition function*,  $\delta(q, X) = (p, Y, D)$
  5.  $q_0$ : A *start state*
  6.  $B$ : A *blank symbol* ( $B$ , in  $\Gamma - \Sigma$ , typically).
    1. All tape except for the input is blank initially.
  7.  $F$ : A set of *final states* ( $F \subseteq Q$ , typically).

# Conventions

- $a, b, \dots$  are input symbols.
- $\dots, X, Y, Z$  are tape symbols.
- $\dots, w, x, y, z$  are strings of input symbols.
- $\alpha, \beta, \dots$  are strings of tape symbols.

# The Transition Function

- $\delta$ : a transition function  $\delta (q, X) = (p, Y, D)$  where
- Takes two arguments:
  1. A state  $q$ , in  $Q$ .
  2. A tape symbol  $X$  in  $\Gamma$ .
- $\delta(q, Z)$  is either undefined or a triple of the form  $(p, Y, D)$ .
  - $p$  is a state.
  - $Y$  is the new tape symbol.
  - $D$  is a *direction*, L or R.

# Actions of the Turing Machines

- If  $\delta(q, X) = (p, Y, D)$  then, in state  $q$ , scanning  $Z$  under its tape head, the TM:
  1. Changes the state to  $p$ .
  2. Replaces  $X$  by  $Y$  on the tape.
  3. Moves the head one square in direction  $D$ .
    - ◆  $D = L$ : move left;  $D = R$ : move right.

# Example: Turing Machine

- This TM scans its input right, looking for a 1.
- If it finds one, it changes it to a 0, goes to final state  $f$ , and halts.
- If it reaches a blank, it changes it to a 1 and moves left.

## Example: Turing Machine – (2)

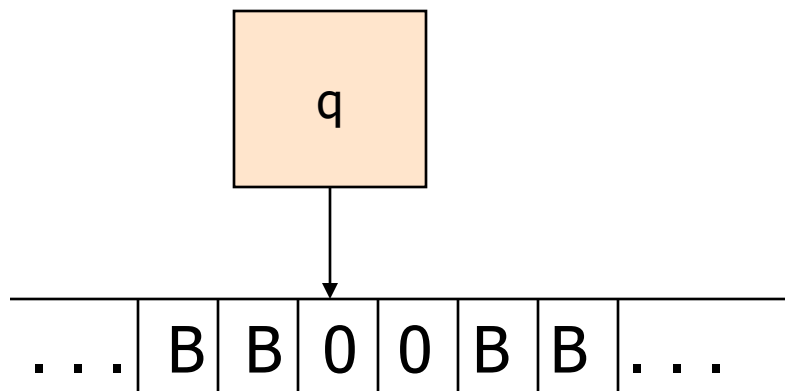
- States =  $\{q \text{ (start)}, f \text{ (final)}\}$ .
- Input symbols =  $\{0, 1\}$ .
- Tape symbols =  $\{0, 1, B\}$ .
- $\delta(q, 0) = (q, 0, R)$ .
- $\delta(q, 1) = (f, 0, R)$ .
- $\delta(q, B) = (q, 1, L)$ .

# Simulation of TM

$$\delta(q, 0) = (q, 0, R)$$

$$\delta(q, 1) = (f, 0, R)$$

$$\delta(q, B) = (q, 1, L)$$

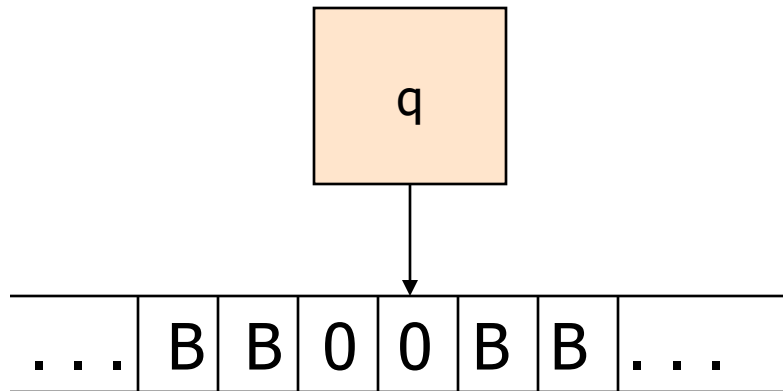


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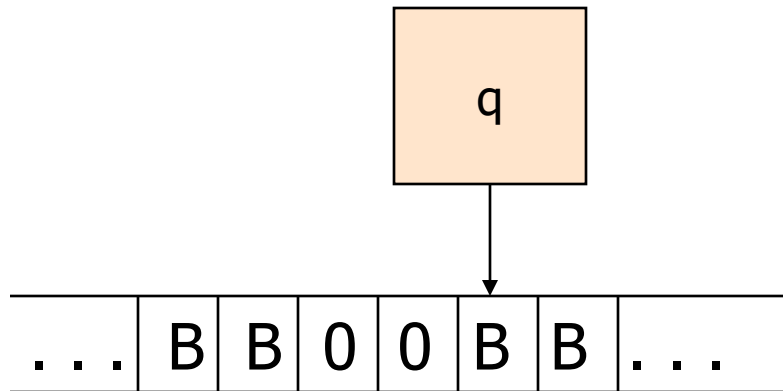


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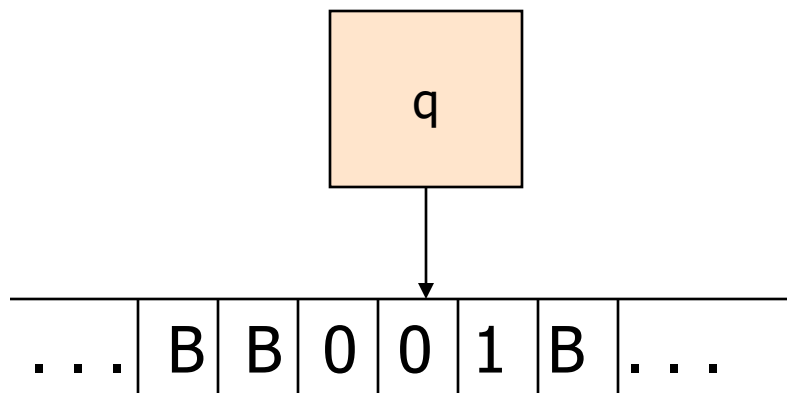


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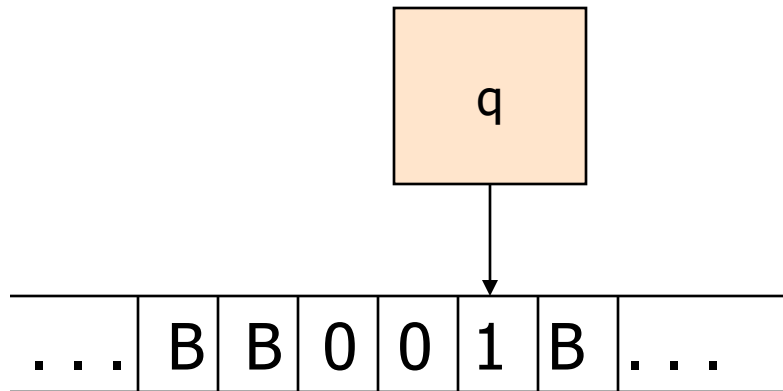


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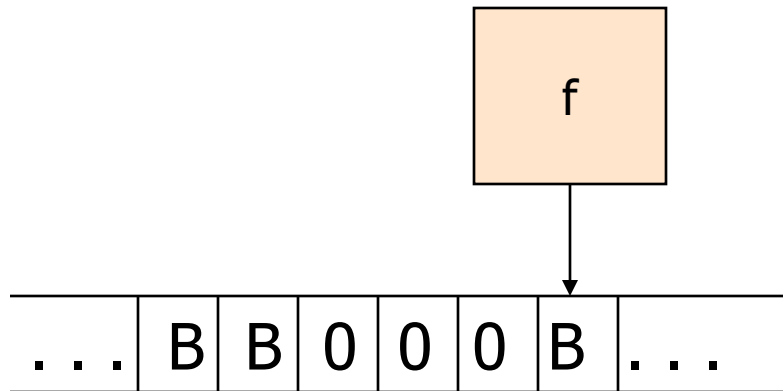


# Simulation of TM

$$\delta(q, 0) = (q, 0, R)$$

$$\delta(q, 1) = (f, 0, R)$$

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No move is possible.  
The TM halts and  
accepts.

# Summary

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- Computational models
- Why Turing Machines?
- What is Turing Machine?
- How does Turing machine work?

# References

- John E. Hopcroft, Rajeev Motwani and Jeffrey D. Ullman, *Introduction to Automata Theory, Languages, and Computation*, Pearson, 3<sup>rd</sup> Edition, 2011.
- Peter Linz, *An Introduction to Formal Languages and Automata*, Jones and Bartle Learning International, United Kingdom, 6<sup>th</sup> Edition, 2016.

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Next Class: **Unit III**

# **Instantaneous Descriptions of Turing Machines**

**Thank you.**

