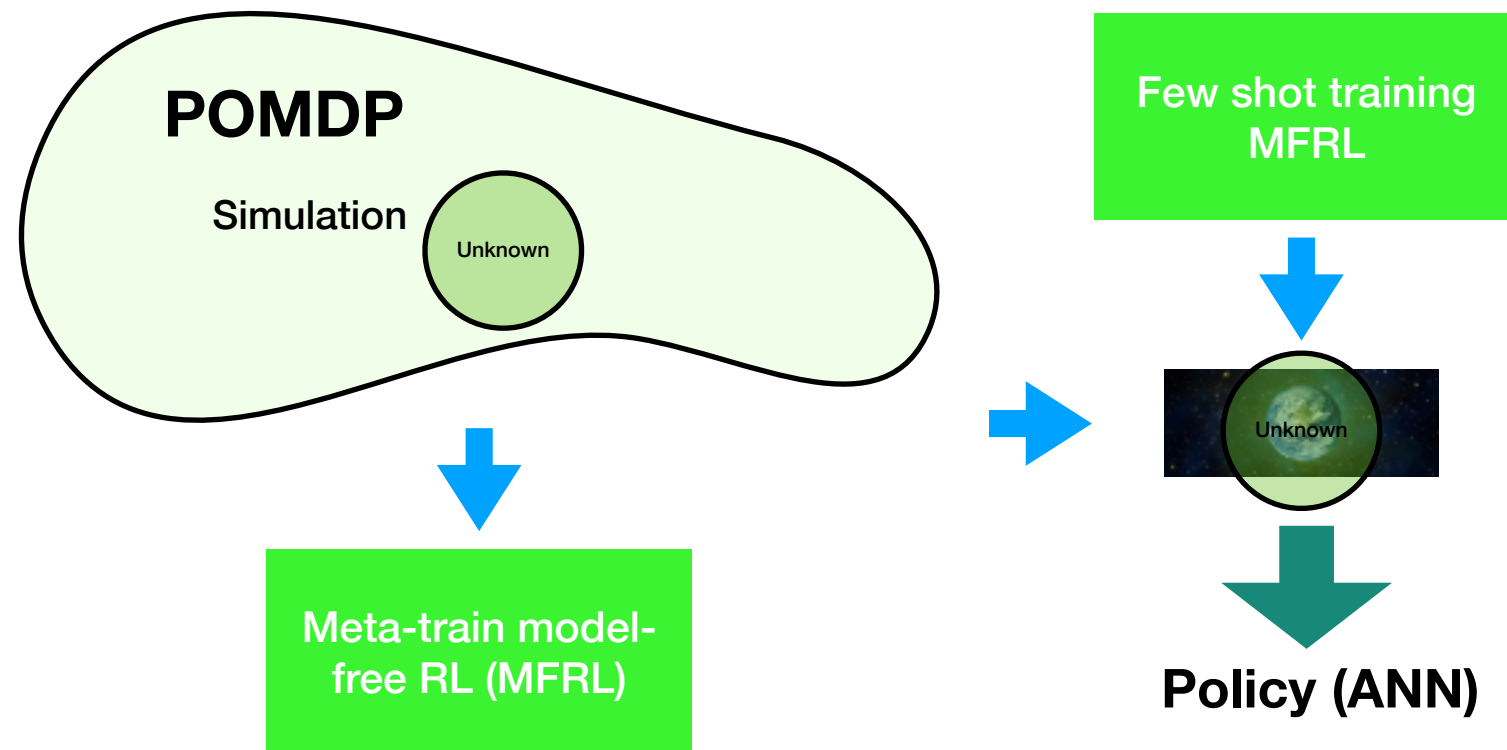# Meta RL (in accelerator control)

- Possible scenarios:

    - Inaccurate simulation → Prepare agent for real training in reliable and fast way

    - Non-stationarity → Environment changes regularly, fast, stable retraining

    - Several similar computational demanding problems → Common pre-training

    - …

Experiments