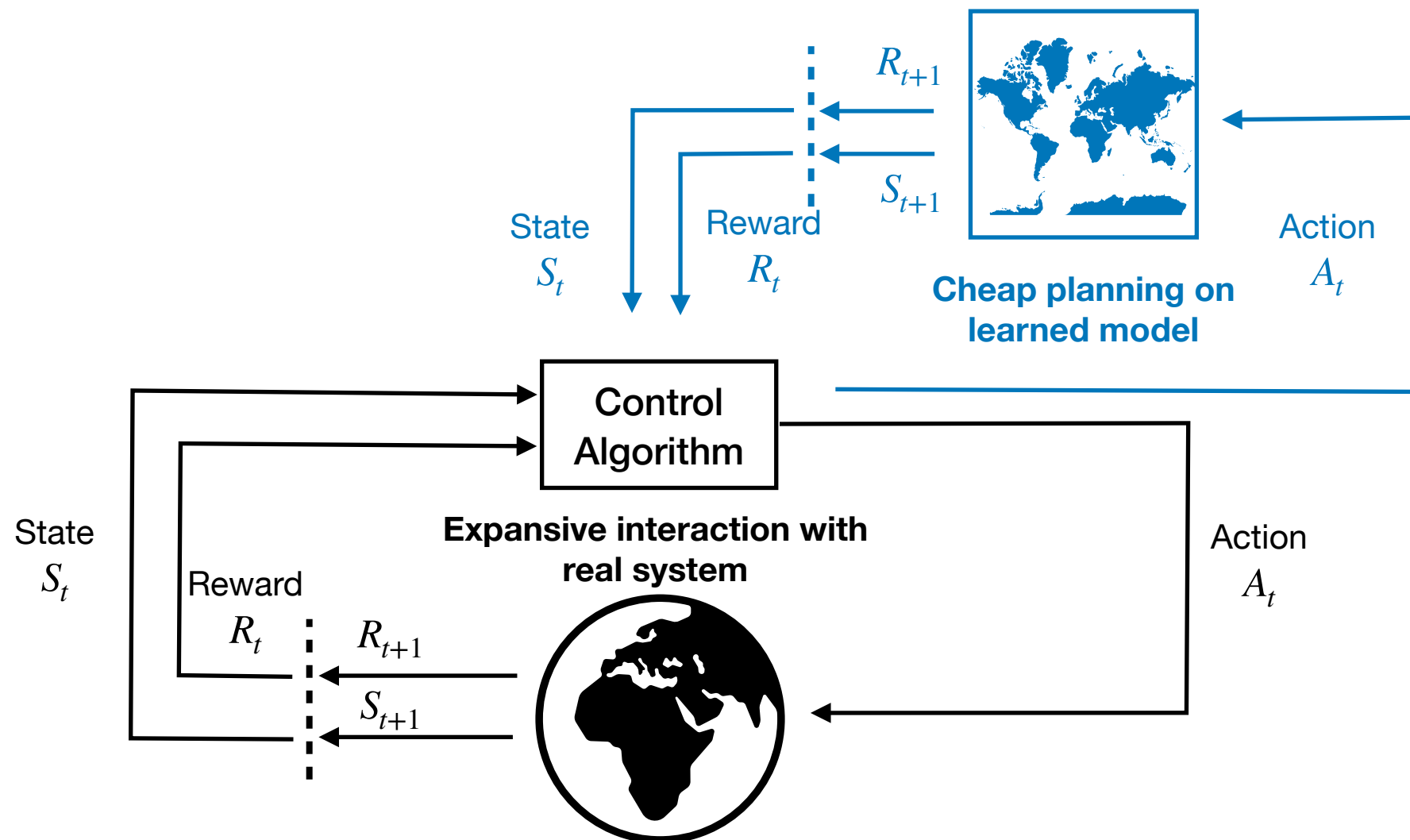# Back to RL - no model

GP-MPC the BO of RL

- Setup the dynamics-reward model

- Use PMP to obtain sparse optimization with gradient information

- Choose optimization algorithm

- Consider safety (constraints)

- Set up training