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RL Coffee

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→ Cannot handle delayed consequences → RL can

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Known reward e.g. Intensity (nevertheless hard to design)

The state defined though beam diagnostics

The actions are mostly well designed

Open issues:

Is a sufficient state available?

How to deal with non-stationarity?

How to improve the sample efficiency?

Stability - how to tune the algorithms?

What about safety?

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Some directions

- Observability (POMDPs)
- Better diagnostics
 Extend state formulation (e.g. longer history) Complication: additional prediction problem
- Sample efficiency
- Develop more sample efficient algorithms e.g. model-based Safety
- Modelling tricky in stochastic settings (accurate probabilistic models)

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- Non-stationarity (special POMDPs)
- Everyday: short horizon problems classical and Bayesian optimisation Again: extend state formulation



