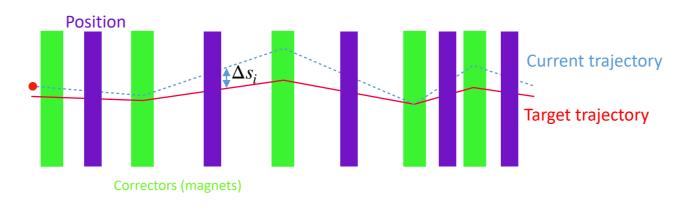
CERN AWAKE steering problem

Markov decision process: (S, A, R, P, ρ_0 , γ)



- 10 continuous states S and actions $A \in [-1,1]$ (actions are bounded/constraints) (10 DoF problem observation is state)
- . Rewards R negative of RMS of states $r_i \propto -\sqrt{\sum \Delta s_i^2}$
- Actions are done in $s_{t+1} = \mathbf{R}a_t + s_t$
- Episodic training
- ullet Initial criteria: Initial distribution ho_0 is away from low RMS to make problem a bit challenging
- Termination criteria:
 - Maximal number of interactions (truncation)
 - → RMS below measurement uncertainty (successful termination)
 - ightharpoonup States s_i > beam pipe (termination or clipping)
- Transitions P are deterministic os stochastic, $\gamma = 1$
- ullet If we speak about different tasks i (MPDs) we mean different matrices ${f R}_i$





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Motivation



