What if we'd know the model: optimal control

Three main ingredients

- Mathematical description of the system to be controlled (state-space models)

  ➡ We use MDPs

- Specification of a performance criterion (the cost function)

  ➡ The reward designed by us (or emitted by the environment in RL setting)

- Specification of constraints

  ➡ Control or state constraints

IDALAB

PARIS
LODRON
UNIVERSITÄT
SALZBURG