



#### Simon Hirländer

#### Tutorial RL4AA

# Meta RL via gradients

### MAML outline

Require 
$$\alpha, \beta$$
: step size hyper-parameters

1. randomly initialise  $\theta$ 

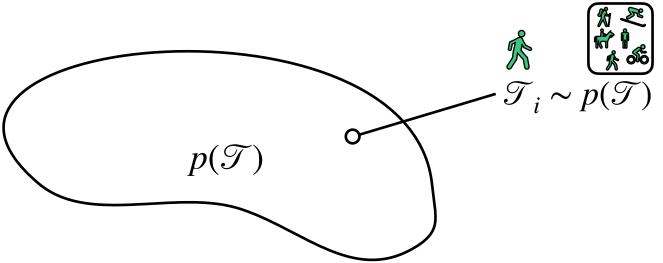
**Require**  $p(\mathcal{T})$ : distribution over tasks

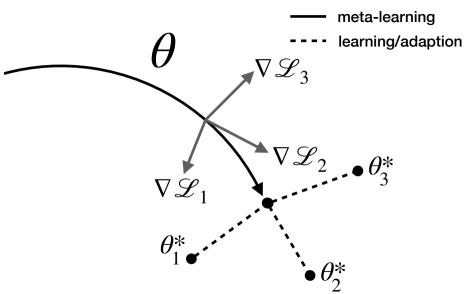
- 2. while not done do
- sample batch of tasks  $\mathcal{T}_i \sim p(\mathcal{T})$
- for each  $\mathcal{T}_i$  do
- 5.
  - Sample  $\mathscr{D}^{tr}_{\mathscr{T}_i} \sim \mathscr{D}_{\mathscr{T}_i}$
  - Sample  $\mathcal{D}_{\mathcal{T}_i}^{test} \sim \mathcal{D}_{\mathcal{T}_i}$
- 6.
- 8.
- Evaluate  $\nabla_{\theta} \mathscr{L}(\theta, \mathscr{D}^{tr}_{\mathscr{T}})$  with respect to K examples











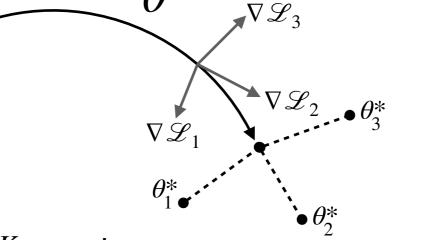
## Meta RL via gradients

### MAML outline

**Require**  $p(\mathcal{T})$ : distribution over tasks

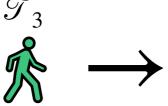
**Require**  $\alpha$ ,  $\beta$ : step size hyper-parameters

- 1. randomly initialise  $\theta$
- 2. while not done do
- sample batch of tasks  $\mathcal{T}_i \sim p(\mathcal{T})$
- for each  $\mathcal{T}_i$  do
- Sample  $\mathscr{D}_{\mathscr{T}_i}^{tr} \sim \mathscr{D}_{\mathscr{T}_i}$
- Sample  $\mathcal{D}_{\mathcal{T}_i}^{test} \sim \mathcal{D}_{\mathcal{T}_i}$
- Evaluate  $\nabla_{\theta} \mathcal{L}(\theta, \mathcal{D}_{\mathcal{T}_{i}}^{tr})$  with respect to K examples
- Compute adapted parameters with gradient descent:  $\phi_i = \theta \alpha \nabla_{\theta} \mathcal{L}(\theta, \mathcal{D}_{\mathcal{T}}^{tr})$ 8.
- Update  $\theta \leftarrow \theta \beta \nabla_{\theta} \sum_{i} \mathcal{L}(\phi_{i}, \mathcal{D}_{\mathcal{T}_{i}}^{test})$

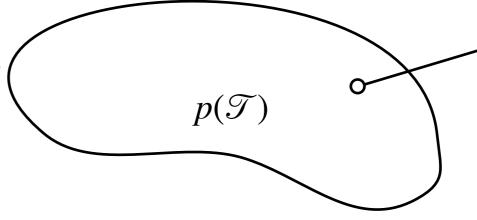














learning/adaption



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# Why MAML is a good idea

- MAML is universally applicable beyond our specific scenario:
  - → It can be implemented across various optimization problems.
  - → The required gradients (to second order) can be efficiently computed using automatic differentiation.

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