

$$\frac{\sqrt{o}}{a} + 1 = 1 + \frac{os}{s}$$

$$\frac{\sqrt{o}}{a} = \frac{os}{s} \qquad -s(1)$$

Apply momentum equation

8,0 V120 +P,A, = 82 QV2n +P2 A2

Pressure wave velocity of strently compressible. 3 fluid in non-Nordpipe a et DH (Vo+AV+a)= Vota A+DA A HO + DH Ho Apply continuity equation g(vo+a)A = (g+bg)a(A+bA)divide above equation ty part  $\frac{V_0}{\alpha}$  +1 =  $\left(1+\frac{\Delta P}{P}\right)\left(1+\frac{\Delta A}{A}\right)$ 1+ \frac{1}{2} = 1 + \frac{1}{9} + \frac{1}{4} + \frac{1}{9} \frac{1}{4} - 9(7) francampressbility K = (A8/8) 2) 28 = AP K from Eq.(5)  $V_0 = \frac{QP}{ga} - \frac{g(9)}{g}$ substitute (8) 2 (9) in (7)

$$\frac{1}{\beta a^{2}} = \frac{1}{K} + \frac{0}{EL}$$

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$$a = \sqrt{\frac{K}{\rho_0}}$$

This formula is applicable only for slightly compressible fluid in a rigid pipe.

## Reynolds Transport Theorem (RTT)

$$\frac{dB_{sys}}{dt} = \frac{d}{dt} \int_{v} \beta \rho dv + (\beta \rho A V_{s})_{out} - (\beta \rho A V_{s})_{in}$$

B = extensive property

 $\beta$  = intensive property

v = Total volume

Note that the velocity  $V_s$  is with respect to the control surface since it accounts for the inflow or outflow from the control volume.

For fixed control volume,  $V_s$  = fluid flow velocity V . If control volume is moving with 'w' velocity then  $V_s = V - w$ 

$$\frac{dB_{sys}}{dt} = \frac{d}{dt} \int_{V} \beta \rho dv + \left[ \beta \rho A (V - w) \right]_{out} - \left[ \beta \rho A (V - w) \right]_{in}$$

## **Derivation of Continuity Equation**

Assumptions

- 1) Flow is slightly compressible
- 2) Conduit walls are elastic
- 3) Flow is one directional.

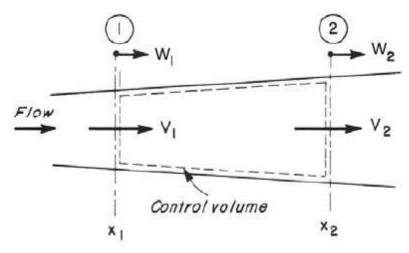


Fig. 2.9. Application of continuity equation

Control surfaces are moving with  $w_1$  and  $w_2$  velocities, that means control volume is either contracting or expanding. Rapid expansion and contraction are taken into account in this derivation.

Applying RTT,  $\beta = 1$ 

$$\frac{d}{dt} \int_{x_1}^{x_2} \rho A dx + \rho_2 A_2 (V_2 - W_2) - \rho_1 A_1 (V_1 - W_1) = 0$$

Then apply Leibnitz's rule to the first term on the LHS.

We know, Leibnitz theorem

$$\frac{d}{dt} \int_{f_1(t)}^{f_2(t)} F(x,t) dx = \int_{f_1(t)}^{f_2(t)} \frac{\partial}{\partial t} F(x,t) dx + F(f_2(t),t) \frac{df_2}{dt} - F(f_1(t),t) \frac{df_1}{dt}$$

Therefore first term on LHS can be written as

$$\frac{d}{dt} \int_{x_1}^{x_2} \rho A dx = \int \frac{\partial}{\partial t} (\rho A) dx + \rho_2 A_2 \frac{dx_2}{dt} - \rho_1 A_1 \frac{dx_1}{dt}$$

Total equation can be written as

$$\int \frac{\partial}{\partial t} (\rho A) dx + \rho_2 A_2 w_2 - \rho_1 A_1 w_1 + \rho_2 A_2 (V_2 - w_2) - \rho_1 A_1 (V_1 - w_1) = 0$$

$$\frac{\partial}{\partial t} (\rho A) \Delta x + \rho_2 A_2 V_2 - \rho_1 A_1 V_1 = 0$$

$$\frac{\partial}{\partial t}(\rho A) + \frac{\partial}{\partial x}(\rho AV) = 0$$

Expansion of terms inside the parenthesis

$$A\frac{\partial \rho}{\partial t} + \rho \frac{\partial A}{\partial t} + \rho A \frac{\partial V}{\partial x} + \rho V \frac{\partial A}{\partial x} + A V \frac{\partial \rho}{\partial x} = 0$$

Divide it by  $(\rho A)$ 

$$\frac{1}{\rho} \frac{\partial \rho}{\partial t} + \frac{1}{A} \frac{\partial A}{\partial t} + \frac{\partial V}{\partial x} + \frac{V}{A} \frac{\partial A}{\partial x} + \frac{V}{\rho} \frac{\partial \rho}{\partial x} = 0$$

$$\frac{1}{\rho} \frac{d\rho}{dt} + \frac{1}{A} \frac{dA}{dt} + \frac{\partial V}{\partial x} = 0$$

We need to convert the above equation in terms of pressure and velocity V.

The bulk modulus of Elasticity, 
$$K = \frac{dP}{\frac{d\rho}{\rho_0}} = -\frac{dP}{\frac{\Delta V}{V_0}}$$

The equation may be written as  $\frac{d\rho}{dt} = \rho \frac{dP}{Kdt}$ 

For circular conduits,  $A = \pi R^2$ , R = radius.

$$\frac{dA}{dt} = 2\pi R \frac{dR}{dt}$$

The above equation may be written as

$$\frac{dA}{dt} = 2\pi R^2 \frac{1}{R} \frac{dR}{dt}$$

$$\frac{dR}{R} = d\varepsilon$$
 Where  $\varepsilon = \text{Strain}$ 

$$\frac{1}{A}\frac{dA}{dt} = 2 \cdot \frac{d\varepsilon}{dt}$$

For circular conduits,  $\varepsilon = \frac{\sigma_h - \sigma_a \mu}{E}$ 

Where  $\sigma_h$  = hoops stress,  $\sigma_a$  = axial stress and  $\mu$  = poison ratio.

Pipe has expansion joints, therefore  $\sigma_a = 0$ .

So, 
$$\varepsilon = \frac{\sigma_h}{E}$$

Hoop stress is defined as,  $\sigma_h = \frac{PD}{2e}$ 

By taking the time derivative on both sides, we can get

$$\frac{d\sigma_h}{dt} = \frac{P}{2e}\frac{dD}{dt} + \frac{D}{2e}\frac{dP}{dt}$$

 $\sigma_h = E\varepsilon$ , where E is a constant.

$$E\frac{d\varepsilon}{dt} = \frac{P}{2e}\frac{dD}{dt} + \frac{D}{2e}\frac{dP}{dt}$$

We know that,  $\frac{1}{A}\frac{dA}{dt} = 2 \cdot \frac{d\varepsilon}{dt} \implies \frac{1}{\frac{\pi D^2}{4}} \cdot \frac{1}{4}\frac{d(\pi D^2)}{dt} = 2\frac{d\varepsilon}{dt}$ 

$$\frac{1}{D}\frac{dD}{dt} = \frac{d\varepsilon}{dt}$$

$$E\frac{d\varepsilon}{dt} = \frac{P}{2e}D\frac{d\varepsilon}{dt} + \frac{D}{2e}\frac{dP}{dt}$$

$$\frac{d\varepsilon}{dt} = \frac{\frac{D}{2e}\frac{dP}{dt}}{E - \frac{PD}{2e}}$$

We already know that,  $\frac{1}{A}\frac{dA}{dt} = 2 \cdot \frac{d\varepsilon}{dt}$ 

$$\frac{1}{2A}\frac{dA}{dt} = \frac{\frac{D}{2e}\frac{dP}{dt}}{E - \frac{PD}{2e}}$$

Continuity equation

$$\frac{1}{\rho} \frac{d\rho}{dt} + \frac{1}{A} \frac{dA}{dt} + \frac{\partial V}{\partial x} = 0$$

$$\frac{d\rho}{dt} = \frac{\rho}{K} \frac{dP}{dt}$$

$$\frac{1}{\rho} \frac{\rho}{K} \frac{dP}{dt} + \left( \frac{\frac{D}{e}}{E - \frac{PD}{2e}} \right) \cdot \frac{dP}{dt} + \frac{\partial V}{\partial x} = 0$$

$$\left(\frac{1}{K} + \frac{1}{\frac{eE}{D} - \frac{P}{2}}\right) \cdot \frac{dP}{dt} + \frac{\partial V}{\partial x} = 0, \quad \text{Where } \frac{P}{2} << \frac{eE}{D}$$

$$\frac{1}{K} \left( 1 + \frac{DK}{eE} \right) \cdot \frac{dP}{dt} + \frac{\partial V}{\partial x} = 0$$

$$\frac{K}{\left(1 + \frac{DK}{eE}\right)} \cdot \frac{\partial V}{\partial x} + \frac{dP}{dt} = 0$$

$$\rho \frac{\frac{K}{\rho}}{\left(1 + \frac{DK}{eE}\right)} \cdot \frac{\partial V}{\partial x} + \frac{\partial P}{\partial t} + V \frac{\partial P}{\partial x} = 0$$

$$\Rightarrow \rho a^2 \cdot \frac{\partial V}{\partial x} + \frac{\partial P}{\partial t} + V \frac{\partial P}{\partial x} = 0$$

## **Derivation of momentum equation**

$$\frac{d}{dt} \int_{V} \beta \rho dv + \beta \rho (V - w) A \Big|_{outlet} - \beta \rho (V - w) A \Big|_{inlet} = 0$$

For momentum equation  $\beta = V$ 

$$\frac{d}{dt} \int_{V} V \rho dv + V \rho (V - w) A \Big|_{outlet} - V \rho (V - w) A \Big|_{inlet} = \sum F$$

By applying Leibnitz rule to the first term

$$\sum F = \int_{x}^{x_2} \frac{\partial}{\partial t} (\rho AV) dx + \rho AV \Big|_{out} \frac{dx_2}{dt} - \rho AV \Big|_{in} \frac{dx_1}{dt} + \rho A(V - w)V \Big|_{2} - \rho A(V - w)V \Big|_{1}$$

$$\sum F = \int_{x_1}^{x_2} \frac{\partial}{\partial t} (\rho A V) dx + (\rho A V)_2 w_2 - (\rho A V)_1 w_1 + \left[ \rho A (V - w) V \right]_2 - \left[ \rho A (V - w) V \right]_1$$

$$\frac{\sum F}{\Delta r} = \frac{\partial}{\partial t} (\rho A V) + \frac{(\rho A V^2)_2 - (\rho A V^2)_1}{\Delta r}$$

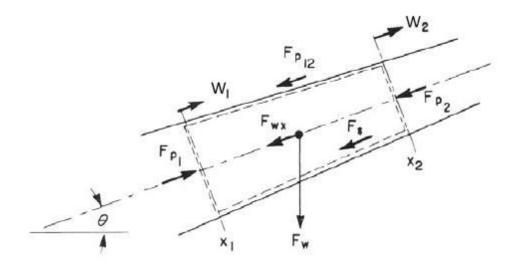


Fig. 2.10. Application of momentum equation