



Module 02: Numerical Methods

Unit 07: Partial Differential Equation: Numerical Stability of IBVP

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Learning Objective

- To analyze the numerical stability of the discretized PDE.



Problem Definition

Governing equation

A two-dimensional (in space) IBVP can be written as,

$$\Omega : \quad \Lambda_{\phi} \frac{\partial \phi}{\partial t} = \Gamma_x \frac{\partial^2 \phi}{\partial x^2} + \Gamma_y \frac{\partial^2 \phi}{\partial y^2} + S_{\phi}(x, y)$$



Problem Definition

subject to

Initial Condition

$$\phi(x, y, 0) = \phi_0(x, y)$$

and

Boundary Condition

$$\Gamma_D^1 : \quad \phi(0, y, t) = \phi_1$$

$$\Gamma_D^2 : \quad \phi(L_x, y, t) = \phi_2$$

$$\Gamma_N^3 : \quad \left. \frac{\partial \phi}{\partial y} \right|_{(x, 0, t)} = 0$$

$$\Gamma_N^4 : \quad \left. \frac{\partial \phi}{\partial y} \right|_{(x, L_y, t)} = 0$$



Errors

Discretization Error (Biswas, 2003)

Discretization Error =

Analytical Solution of PDE - Exact Solution of the Finite Difference Equation
(obtained on a hypothetical infinite precision computer)

= Truncation Error + Error due to treatment of boundary conditions



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Analytical Solution of PDE - Exact Solution of the Finite Difference Equation
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= Truncation Error + Error due to treatment of boundary conditions

Round-off Error

Round-off Error (ϵ) =

Numerical Solution of the Finite Difference Equation (obtained from finite
precision computer) - Exact Solution of the Finite Difference Equation
(obtained on a hypothetical infinite precision computer)



Numerical Errors

- Every algorithm requires repeated operations (e.g., \pm , \times). There is an accumulation of round-off error.



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- Numerical Stability/ Instability is a property of the algorithm and discretization of PDE+BCs.



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- In time-stepping algorithm, accumulated round-off error may magnify/reduce with every step.
- Error may increase exponentially. It is known as *Numerical Instability*.
- Numerical Stability/ Instability is a property of the algorithm and discretization of PDE+BCs.
- It does not depend on the computer used.



Stability Analysis

In stability analysis of linear PDE, we analyze only one arbitrary Fourier mode (Biswas, 2003).



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Let us consider that the error can be represented in the form of Fourier Series and single arbitrary term can be written as,

$$\epsilon_{i,j}^n = A^n e^{\sqrt{-1}i\omega_x \Delta x + \sqrt{-1}j\omega_y \Delta y}$$

where

ω_x and ω_y are wave numbers corresponding to x and y directions respectively.



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Note that, $|\epsilon_{i,j}^n| = |A^n|$.



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where

ω_x and ω_y are wave numbers corresponding to x and y directions respectively.

Note that, $|\epsilon_{i,j}^n| = |A^n|$.

In simplified form, error can be written as,

$$\epsilon_{i,j}^n = A^n e^{\sqrt{-1}i\varphi_x + \sqrt{-1}j\varphi_y}$$

where

φ_x and φ_y are phase values corresponding to x and y directions respectively.



von Neumann Stability Analysis

Define

$$G = \frac{A^{n+1}}{A^n}$$

where G is an amplification factor. It governs the growth of the Fourier component.



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The von Neumann Stability Condition is given by $|G| \leq 1$.

$|G| > 1 \Rightarrow$ Error grows (Unstable Scheme).

$|G| < 1 \Rightarrow$ Error reduces (Stable Scheme).

$|G| = 1 \Rightarrow$ Error remains same (Neutrally Stable Scheme).



Explicit Scheme

The discretized governing equation for IBVP with explicit scheme can be written as,

$$\Lambda_{\phi} \frac{\phi_{i,j}^{n+1} - \phi_{i,j}^n}{\Delta t} = \Gamma_x \frac{\phi_{i-1,j}^n - 2\phi_{i,j}^n + \phi_{i+1,j}^n}{\Delta x^2} + \Gamma_y \frac{\phi_{i,j-1}^n - 2\phi_{i,j}^n + \phi_{i,j+1}^n}{\Delta y^2} + S_{\phi}|_{i,j}^n$$



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The general variable ϕ can be written as,

$$\phi_{i,j}^n = \hat{\phi}_{i,j}^n + \epsilon_{i,j}^n$$

where

$\phi_{i,j}^n$ = Numerical solution obtained from finite precision computer

$\hat{\phi}_{i,j}^n$ = Exact discrete solution obtained on a hypothetical infinite precision computer

$\epsilon_{i,j}^n$ = Accumulated round-off error at time level n .



Explicit Scheme

The discretized governing equation for IBVP with explicit scheme can be written as,

$$\begin{aligned} \Lambda_{\phi} \frac{(\hat{\phi}_{i,j}^{n+1} + \epsilon_{i,j}^{n+1}) - (\hat{\phi}_{i,j}^n + \epsilon_{i,j}^n)}{\Delta t} = \\ \Gamma_x \frac{(\hat{\phi}_{i-1,j}^n + \epsilon_{i-1,j}^n) - 2(\hat{\phi}_{i,j}^n + \epsilon_{i,j}^n) + (\hat{\phi}_{i+1,j}^n + \epsilon_{i+1,j}^n)}{\Delta x^2} + \\ \Gamma_y \frac{(\hat{\phi}_{i,j-1}^n + \epsilon_{i,j-1}^n) - 2(\hat{\phi}_{i,j}^n + \epsilon_{i,j}^n) + (\hat{\phi}_{i,j+1}^n + \epsilon_{i,j+1}^n)}{\Delta y^2} \\ + S_{\phi}|_{i,j}^n \end{aligned} \quad (1)$$



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The discretized governing equation for IBVP with explicit scheme can be written as,

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By definition, $\hat{\phi}$ is the exact discrete solution of the finite difference equation. Thus, the discretized finite difference equation can be written as,

$$\begin{aligned} \Lambda_\phi \frac{\hat{\phi}_{i,j}^{n+1} - \hat{\phi}_{i,j}^n}{\Delta t} = \\ \Gamma_x \frac{\hat{\phi}_{i-1,j}^n - 2\hat{\phi}_{i,j}^n + \hat{\phi}_{i+1,j}^n}{\Delta x^2} + \Gamma_y \frac{\hat{\phi}_{i,j-1}^n - 2\hat{\phi}_{i,j}^n + \hat{\phi}_{i,j+1}^n}{\Delta y^2} + S_\phi|_{i,j}^n \end{aligned} \quad (2)$$



Explicit Scheme

By subtracting Equation 2 from Equation 1, we get the error equation

$$\Lambda_{\phi} \frac{\epsilon_{i,j}^{n+1} - \epsilon_{i,j}^n}{\Delta t} = \Gamma_x \frac{\epsilon_{i-1,j}^n - 2\epsilon_{i,j}^n + \epsilon_{i+1,j}^n}{\Delta x^2} + \Gamma_y \frac{\epsilon_{i,j-1}^n - 2\epsilon_{i,j}^n + \epsilon_{i,j+1}^n}{\Delta y^2} \quad (3)$$



Explicit Scheme

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$$\Lambda_{\phi} \frac{\epsilon_{i,j}^{n+1} - \epsilon_{i,j}^n}{\Delta t} = \Gamma_x \frac{\epsilon_{i-1,j}^n - 2\epsilon_{i,j}^n + \epsilon_{i+1,j}^n}{\Delta x^2} + \Gamma_y \frac{\epsilon_{i,j-1}^n - 2\epsilon_{i,j}^n + \epsilon_{i,j+1}^n}{\Delta y^2} \quad (3)$$

In simplified form, this can be written as,

$$\epsilon_{i,j}^{n+1} = \alpha_y \epsilon_{i,j-1}^n + \alpha_x \epsilon_{i-1,j}^n + [1 - 2(\alpha_x + \alpha_y)] \epsilon_{i,j}^n + \alpha_x \epsilon_{i+1,j}^n + \alpha_y \epsilon_{i,j+1}^n$$

$$\text{with } \alpha_x = \frac{\Gamma_x \Delta t}{\Lambda_{\phi} \Delta x^2} \text{ and } \alpha_y = \frac{\Gamma_y \Delta t}{\Lambda_{\phi} \Delta y^2}.$$



Explicit Scheme

With

$$\epsilon_{i,j}^{n+1} = A^{n+1} e^{\sqrt{-1}i\varphi_x + \sqrt{-1}j\varphi_y}$$

$$\epsilon_{i,j}^n = A^n e^{\sqrt{-1}i\varphi_x + \sqrt{-1}j\varphi_y}$$

$$\epsilon_{i-1,j}^n = A^n e^{\sqrt{-1}(i-1)\varphi_x + \sqrt{-1}j\varphi_y}$$

$$\epsilon_{i+1,j}^n = A^n e^{\sqrt{-1}(i+1)\varphi_x + \sqrt{-1}j\varphi_y}$$

$$\epsilon_{i,j-1}^n = A^n e^{\sqrt{-1}i\varphi_x + \sqrt{-1}(j-1)\varphi_y}$$

$$\epsilon_{i,j+1}^n = A^n e^{\sqrt{-1}i\varphi_x + \sqrt{-1}(j+1)\varphi_y}$$



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$$\epsilon_{i,j+1}^n = A^n e^{\sqrt{-1}i\varphi_x + \sqrt{-1}(j+1)\varphi_y}$$

By substituting all terms in the error equation,

$$\begin{aligned} \frac{A^{n+1}}{A^n} = & \alpha_y e^{-\sqrt{-1}\varphi_y} + \alpha_x e^{-\sqrt{-1}\varphi_x} + [1 - 2(\alpha_x + \alpha_y)] \\ & + \alpha_x e^{\sqrt{-1}\varphi_x} + \alpha_y e^{\sqrt{-1}\varphi_y} \end{aligned}$$



Explicit Scheme

The Growth Factor can be written as,

$$G = \frac{A^{n+1}}{A^n} = 1 + 2\alpha_y(\cos\varphi_y - 1) + 2\alpha_x(\cos\varphi_x - 1)$$

$$G = 1 - 4\alpha_y \sin^2\left(\frac{\varphi_y}{2}\right) - 4\alpha_x \sin^2\left(\frac{\varphi_x}{2}\right)$$



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The von Neumann Stability condition

$$|1 - 4\alpha_y \sin^2\left(\frac{\varphi_y}{2}\right) - 4\alpha_x \sin^2\left(\frac{\varphi_x}{2}\right)| \leq 1$$

$$-1 \leq 1 - 4\alpha_y \sin^2\left(\frac{\varphi_y}{2}\right) - 4\alpha_x \sin^2\left(\frac{\varphi_x}{2}\right) \leq 1$$



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Two Cases:

- $\sin\left(\frac{\varphi_x}{2}\right) = 0$ and $\sin\left(\frac{\varphi_y}{2}\right) = 0 \Rightarrow G = 1$



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$$G = \frac{A^{n+1}}{A^n} = 1 + 2\alpha_y(\cos\varphi_y - 1) + 2\alpha_x(\cos\varphi_x - 1)$$

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$$\begin{aligned} |1 - 4\alpha_y \sin^2\left(\frac{\varphi_y}{2}\right) - 4\alpha_x \sin^2\left(\frac{\varphi_x}{2}\right)| &\leq 1 \\ -1 &\leq 1 - 4\alpha_y \sin^2\left(\frac{\varphi_y}{2}\right) - 4\alpha_x \sin^2\left(\frac{\varphi_x}{2}\right) \leq 1 \end{aligned}$$

Two Cases:

- $\sin\left(\frac{\varphi_x}{2}\right) = 0$ and $\sin\left(\frac{\varphi_y}{2}\right) = 0 \Rightarrow G = 1$
- $\sin\left(\frac{\varphi_x}{2}\right) = 1$ and $\sin\left(\frac{\varphi_y}{2}\right) = 1 \Rightarrow G = 1 - 4(\alpha_x + \alpha_y) \Rightarrow (\alpha_x + \alpha_y) \leq \frac{1}{2}$



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The von Neumann Stability condition

$$|1 - 4\alpha_y \sin^2\left(\frac{\varphi_y}{2}\right) - 4\alpha_x \sin^2\left(\frac{\varphi_x}{2}\right)| \leq 1$$

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- $\sin\left(\frac{\varphi_x}{2}\right) = 1$ and $\sin\left(\frac{\varphi_y}{2}\right) = 1 \Rightarrow G = 1 - 4(\alpha_x + \alpha_y) \Rightarrow (\alpha_x + \alpha_y) \leq \frac{1}{2}$

Explicit scheme is **Conditionally Stable**.



Implicit Scheme

The discretized governing equation for IBVP with implicit scheme can be written as,

$$\begin{aligned} \Lambda_\phi \frac{(\hat{\phi}_{i,j}^{n+1} + \epsilon_{i,j}^{n+1}) - (\hat{\phi}_{i,j}^n + \epsilon_{i,j}^n)}{\Delta t} = \\ \Gamma_x \frac{(\hat{\phi}_{i-1,j}^{n+1} + \epsilon_{i-1,j}^{n+1}) - 2(\hat{\phi}_{i,j}^{n+1} + \epsilon_{i,j}^{n+1}) + (\hat{\phi}_{i+1,j}^{n+1} + \epsilon_{i+1,j}^{n+1})}{\Delta x^2} + \\ \Gamma_y \frac{(\hat{\phi}_{i,j-1}^{n+1} + \epsilon_{i,j-1}^{n+1}) - 2(\hat{\phi}_{i,j}^{n+1} + \epsilon_{i,j}^{n+1}) + (\hat{\phi}_{i,j+1}^{n+1} + \epsilon_{i,j+1}^{n+1})}{\Delta y^2} \\ + S_\phi|_{i,j}^{n+1} \end{aligned} \quad (4)$$



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$$\begin{aligned} \Lambda_\phi \frac{(\hat{\phi}_{i,j}^{n+1} + \epsilon_{i,j}^{n+1}) - (\hat{\phi}_{i,j}^n + \epsilon_{i,j}^n)}{\Delta t} = \\ \Gamma_x \frac{(\hat{\phi}_{i-1,j}^{n+1} + \epsilon_{i-1,j}^{n+1}) - 2(\hat{\phi}_{i,j}^{n+1} + \epsilon_{i,j}^{n+1}) + (\hat{\phi}_{i+1,j}^{n+1} + \epsilon_{i+1,j}^{n+1})}{\Delta x^2} + \\ \Gamma_y \frac{(\hat{\phi}_{i,j-1}^{n+1} + \epsilon_{i,j-1}^{n+1}) - 2(\hat{\phi}_{i,j}^{n+1} + \epsilon_{i,j}^{n+1}) + (\hat{\phi}_{i,j+1}^{n+1} + \epsilon_{i,j+1}^{n+1})}{\Delta y^2} \\ + S_\phi|_{i,j}^{n+1} \end{aligned} \quad (4)$$

By definition, $\hat{\phi}$ is the exact discrete solution of the finite difference equation. Thus, the discretized finite difference equation can be written as,

$$\begin{aligned} \Lambda_\phi \frac{\hat{\phi}_{i,j}^{n+1} - \hat{\phi}_{i,j}^n}{\Delta t} = \\ \Gamma_x \frac{\hat{\phi}_{i-1,j}^{n+1} - 2\hat{\phi}_{i,j}^{n+1} + \hat{\phi}_{i+1,j}^{n+1}}{\Delta x^2} + \Gamma_y \frac{\hat{\phi}_{i,j-1}^{n+1} - 2\hat{\phi}_{i,j}^{n+1} + \hat{\phi}_{i,j+1}^{n+1}}{\Delta y^2} + S_\phi|_{i,j}^{n+1} \end{aligned} \quad (5)$$



Implicit Scheme

By subtracting Equation 5 from Equation 4, we get the error equation

$$\Lambda_{\phi} \frac{\epsilon_{i,j}^{n+1} - \epsilon_{i,j}^n}{\Delta t} = \Gamma_x \frac{\epsilon_{i-1,j}^{n+1} - 2\epsilon_{i,j}^{n+1} + \epsilon_{i+1,j}^{n+1}}{\Delta x^2} + \Gamma_y \frac{\epsilon_{i,j-1}^{n+1} - 2\epsilon_{i,j}^{n+1} + \epsilon_{i,j+1}^{n+1}}{\Delta y^2} \quad (6)$$



Implicit Scheme

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In simplified form, this can be written as,

$$\alpha_y \epsilon_{i,j-1}^{n+1} + \alpha_x \epsilon_{i-1,j}^{n+1} - [1 + 2(\alpha_x + \alpha_y)] \epsilon_{i,j}^{n+1} + \alpha_x \epsilon_{i+1,j}^{n+1} + \alpha_y \epsilon_{i,j+1}^{n+1} = -\epsilon_{i,j}^n$$

$$\text{with } \alpha_x = \frac{\Gamma_x \Delta t}{\Lambda_{\phi} \Delta x^2} \text{ and } \alpha_y = \frac{\Gamma_y \Delta t}{\Lambda_{\phi} \Delta y^2}.$$



Implicit Scheme

With

$$\epsilon_{i,j}^{n+1} = A^{n+1} e^{\sqrt{-1}i\varphi_x + \sqrt{-1}j\varphi_y}$$

$$\epsilon_{i,j}^n = A^n e^{\sqrt{-1}i\varphi_x + \sqrt{-1}j\varphi_y}$$

$$\epsilon_{i-1,j}^{n+1} = A^{n+1} e^{\sqrt{-1}(i-1)\varphi_x + \sqrt{-1}j\varphi_y}$$

$$\epsilon_{i+1,j}^{n+1} = A^{n+1} e^{\sqrt{-1}(i+1)\varphi_x + \sqrt{-1}j\varphi_y}$$

$$\epsilon_{i,j-1}^{n+1} = A^{n+1} e^{\sqrt{-1}i\varphi_x + \sqrt{-1}(j-1)\varphi_y}$$

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Implicit Scheme

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$$\epsilon_{i,j-1}^{n+1} = A^{n+1} e^{\sqrt{-1}i\varphi_x + \sqrt{-1}(j-1)\varphi_y}$$

$$\epsilon_{i,j+1}^{n+1} = A^{n+1} e^{\sqrt{-1}i\varphi_x + \sqrt{-1}(j+1)\varphi_y}$$

By substituting all terms in the error equation,

$$\begin{aligned} \frac{A^{n+1}}{A^n} \left[\alpha_y e^{-\sqrt{-1}\varphi_y} + \alpha_x e^{-\sqrt{-1}\varphi_x} - [1 + 2(\alpha_x + \alpha_y)] + \alpha_x e^{\sqrt{-1}\varphi_x} + \alpha_y e^{\sqrt{-1}\varphi_y} \right] \\ = -1 \end{aligned}$$



Implicit Scheme

The Growth Factor can be written as,

$$G = \frac{A^{n+1}}{A^n} = \frac{-1}{-1 + 2\alpha_y(\cos\varphi_y - 1) + 2\alpha_x(\cos\varphi_x - 1)}$$



Implicit Scheme

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$$G = \frac{1}{1 + 4\alpha_y \sin^2\left(\frac{\varphi_y}{2}\right) + 4\alpha_x \sin^2\left(\frac{\varphi_x}{2}\right)}$$



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The von Neumann Stability condition

$$\left| \frac{1}{1 + 4\alpha_y \sin^2\left(\frac{\varphi_y}{2}\right) + 4\alpha_x \sin^2\left(\frac{\varphi_x}{2}\right)} \right| \leq 1$$



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$$G = \frac{1}{1 + 4\alpha_y \sin^2(\frac{\varphi_y}{2}) + 4\alpha_x \sin^2(\frac{\varphi_x}{2})}$$

The von Neumann Stability condition

$$\left| \frac{1}{1 + 4\alpha_y \sin^2(\frac{\varphi_y}{2}) + 4\alpha_x \sin^2(\frac{\varphi_x}{2})} \right| \leq 1$$

Two Cases:

- $\sin(\frac{\varphi_x}{2}) = 0$ and $\sin(\frac{\varphi_y}{2}) = 0 \Rightarrow G = 1$



Implicit Scheme

The Growth Factor can be written as,

$$G = \frac{A^{n+1}}{A^n} = \frac{-1}{-1 + 2\alpha_y(\cos\varphi_y - 1) + 2\alpha_x(\cos\varphi_x - 1)}$$

$$G = \frac{1}{1 + 4\alpha_y \sin^2(\frac{\varphi_y}{2}) + 4\alpha_x \sin^2(\frac{\varphi_x}{2})}$$

The von Neumann Stability condition

$$\left| \frac{1}{1 + 4\alpha_y \sin^2(\frac{\varphi_y}{2}) + 4\alpha_x \sin^2(\frac{\varphi_x}{2})} \right| \leq 1$$

Two Cases:

- $\sin(\frac{\varphi_x}{2}) = 0$ and $\sin(\frac{\varphi_y}{2}) = 0 \Rightarrow G = 1$
- $\sin(\frac{\varphi_x}{2}) = 1$ and $\sin(\frac{\varphi_y}{2}) = 1 \Rightarrow G = \frac{1}{1+4\alpha_y+4\alpha_x} < 1$



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Implicit scheme is **Unconditionally Stable**.



Thank You



References

Biswas, G. (2003). *Computational Fluid Flow and Heat Transfer*. Narosa Publishing House, New Delhi.