

## Module 02: Numerical Methods

### Unit 01: Overview

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## Learning Objective

- To identify the connection between governing equation and numerical discretizations.



# Introduction

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- Ordinary and Partial Differential Equations (ODE & PDE) are defined for continuous domain.
- Continuous domain can be divided into parts/ sub-parts for discrete representation.
- Numerical discretization defines the mathematical relation between parts or sub-parts in terms of field variables.



# Problem Definition to Solution

## Problem Definition

Hydraulic System



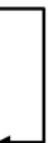
# Problem Definition to Solution

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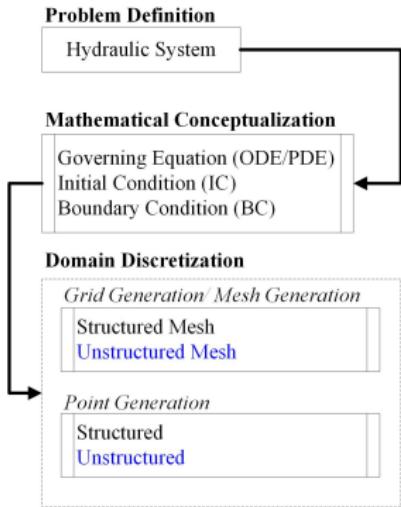
Hydraulic System

## Mathematical Conceptualization

Governing Equation (ODE/PDE)  
Initial Condition (IC)  
Boundary Condition (BC)

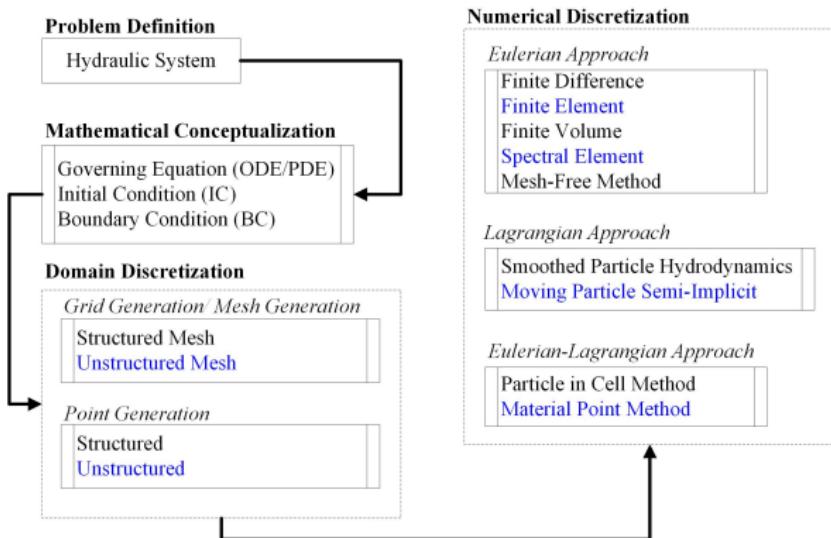


# Problem Definition to Solution



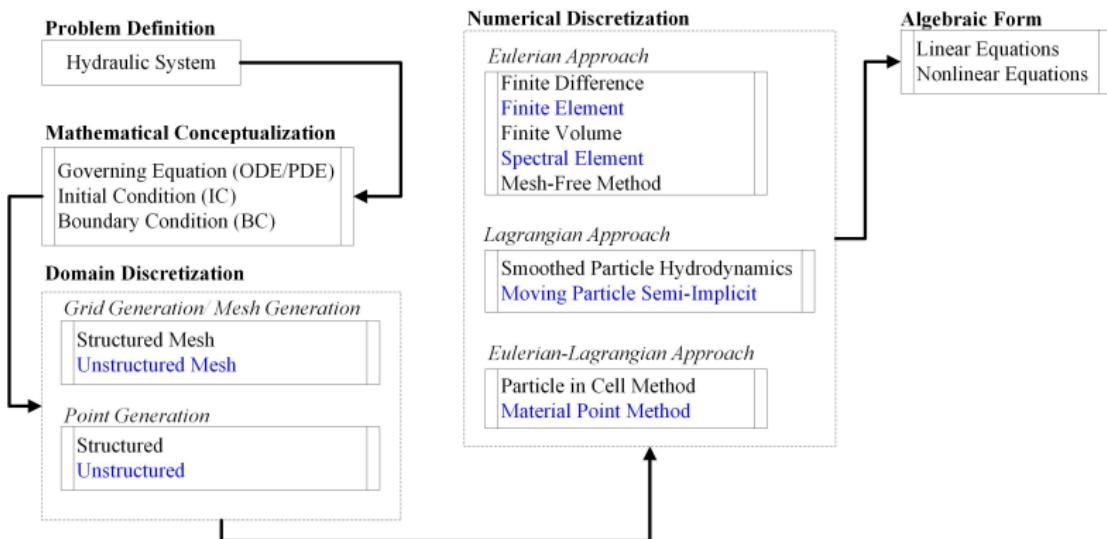


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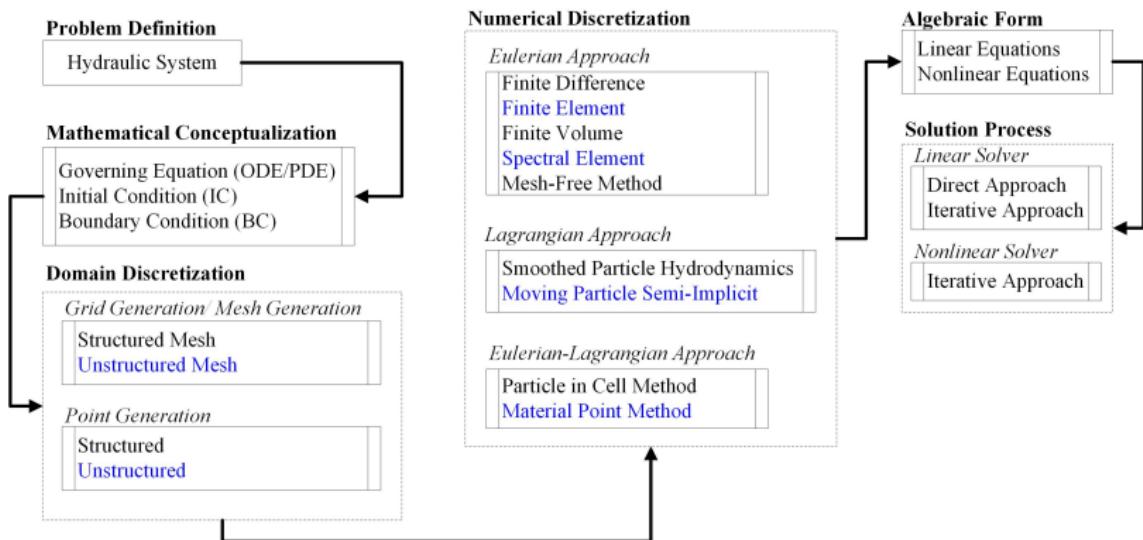


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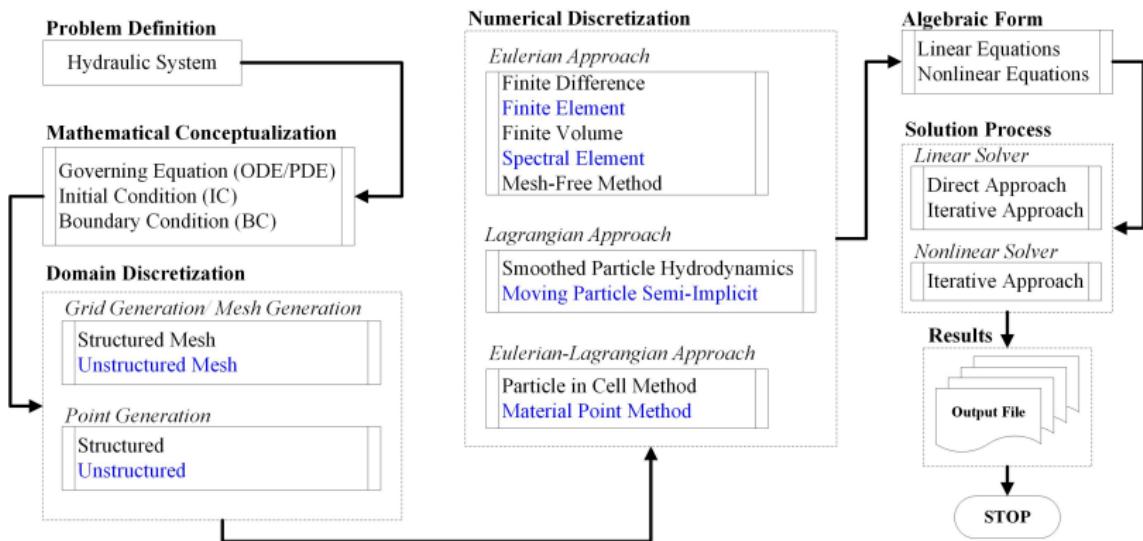


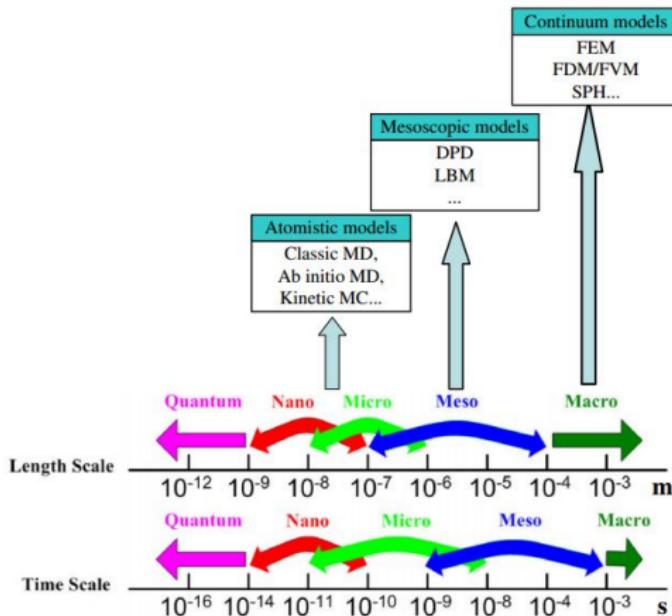


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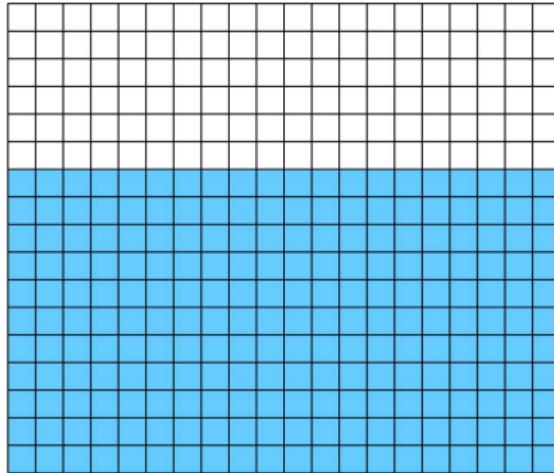




**Figure:** Different length, time scales and corresponding computational methods (Liu et al., 2014)

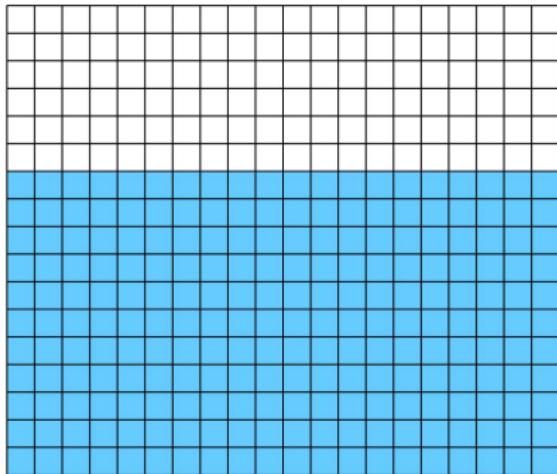


# Eulerian Description

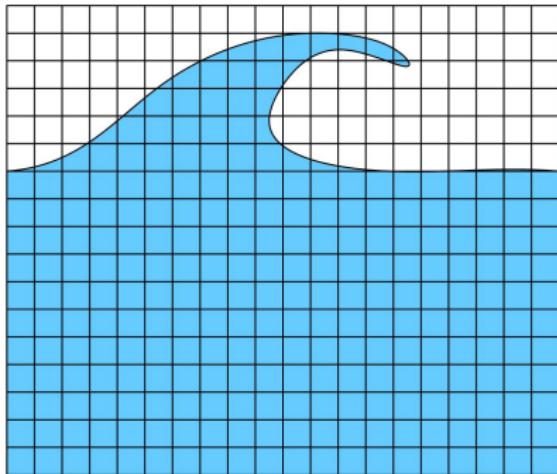


(a) Reference Condition

## Eulerian Description

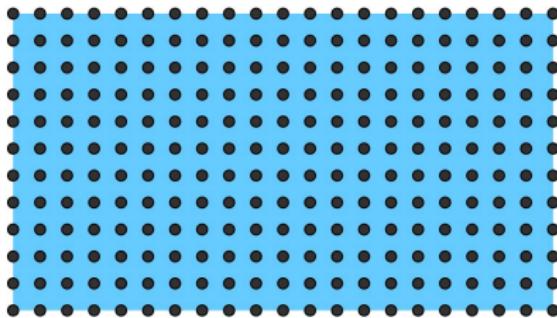


(a) Reference Condition



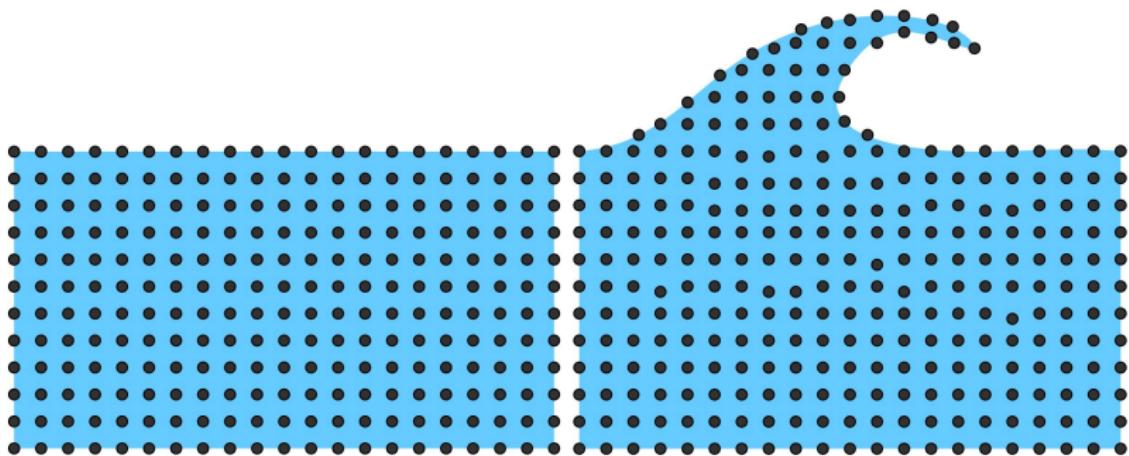
(b) Current Condition

# Lagrangian Description



(a) Reference Condition

# Lagrangian Description

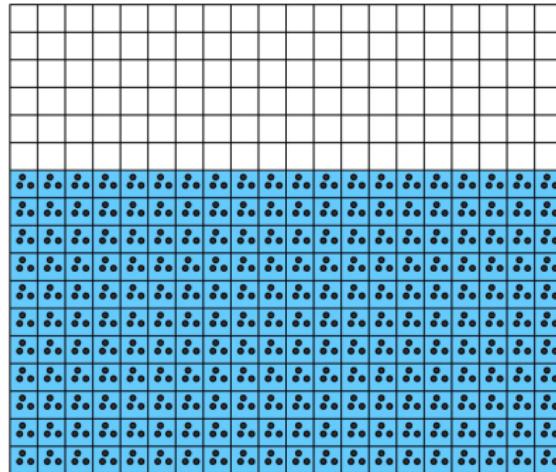


(a) Reference Condition

(b) Current Condition

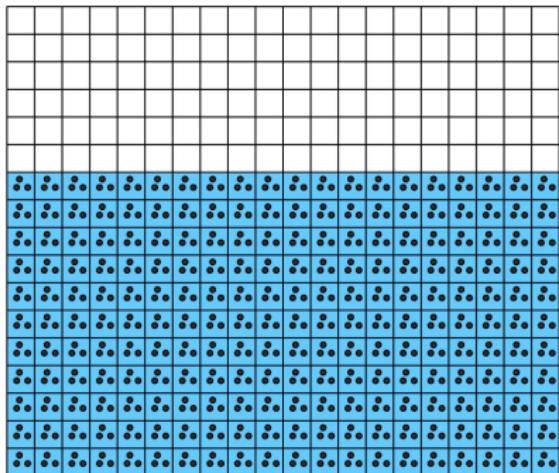


# Eulerian-Lagrangian Description

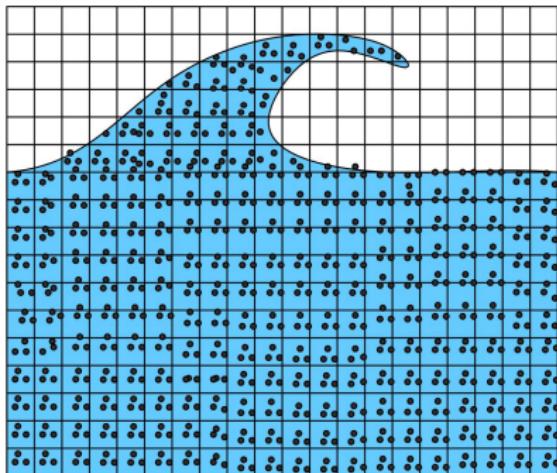


(a) Reference Condition

# Eulerian-Lagrangian Description



(a) Reference Condition

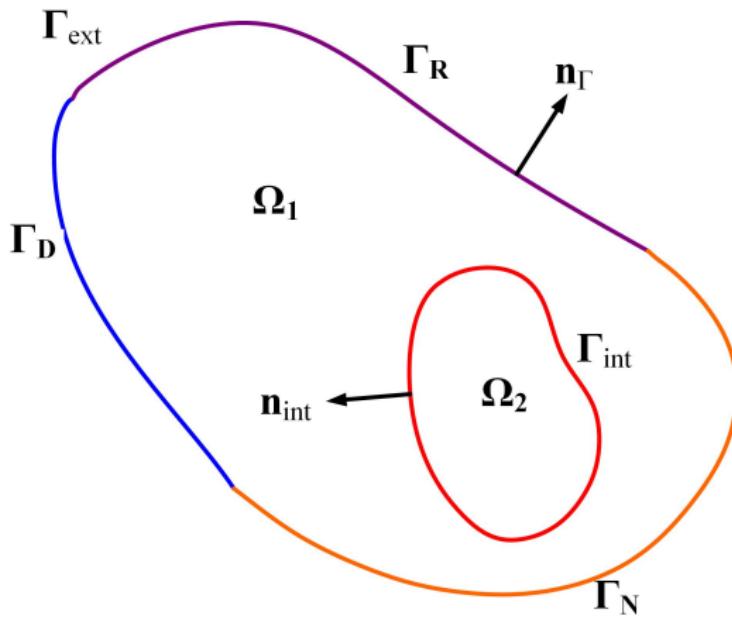


(b) Current Condition

# Physical Domain

Continuous

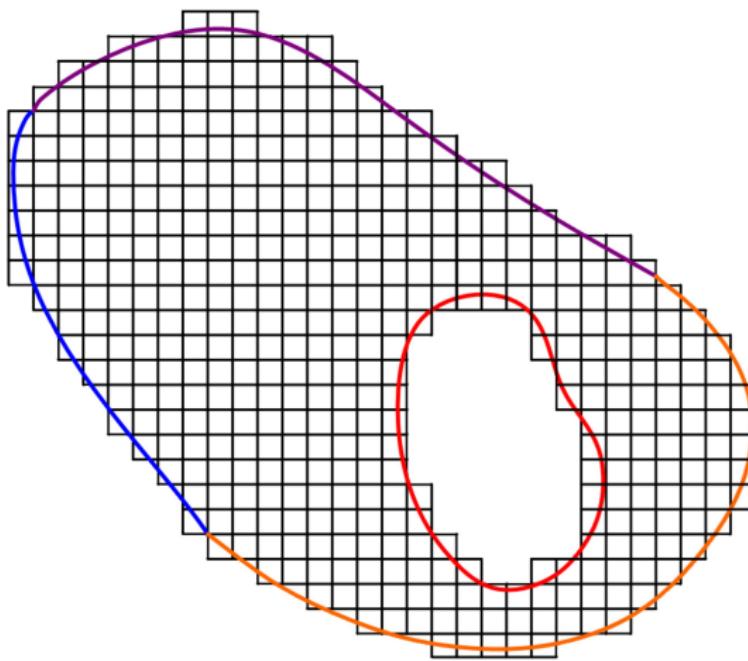
$$\phi(x, y, z, t) \rightarrow \phi(x_i, y_j, z_k, t_l)$$





# Discretized Domain

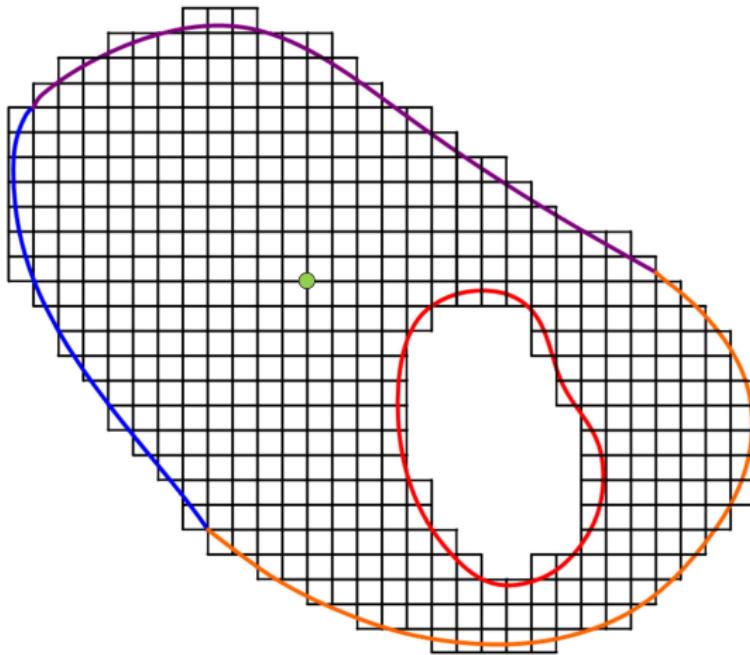
## Finite Difference Method



# Discretized Domain

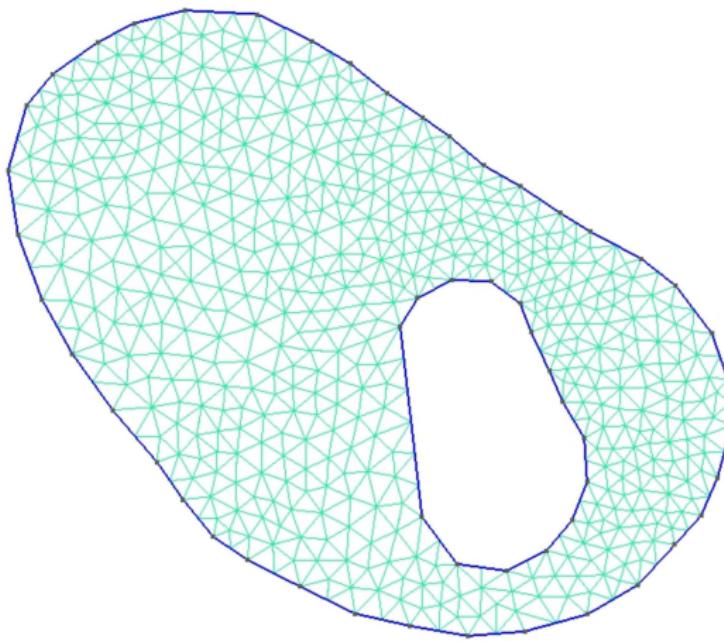
Finite Difference Method

$$\phi(x, y, z, t) \rightarrow \phi(x_i, y_j, z_k, t_l)$$



# Discretized Domain

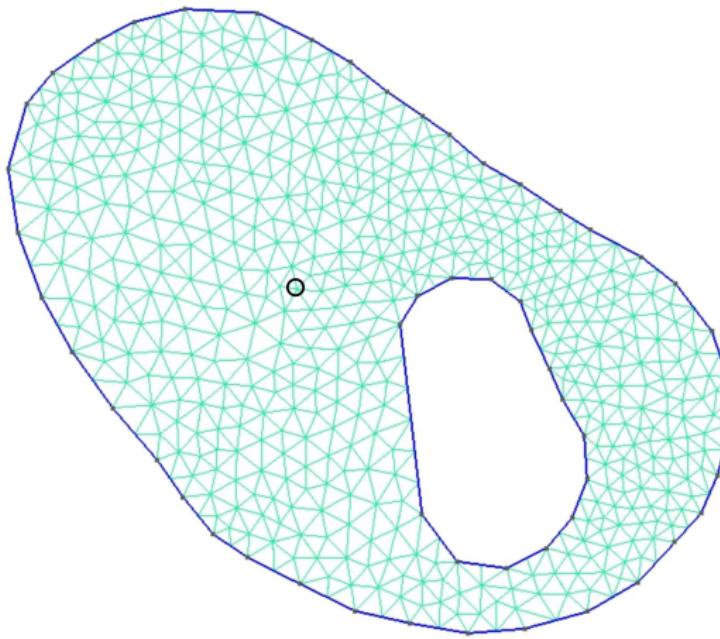
Finite Volume Method



# Discretized Domain

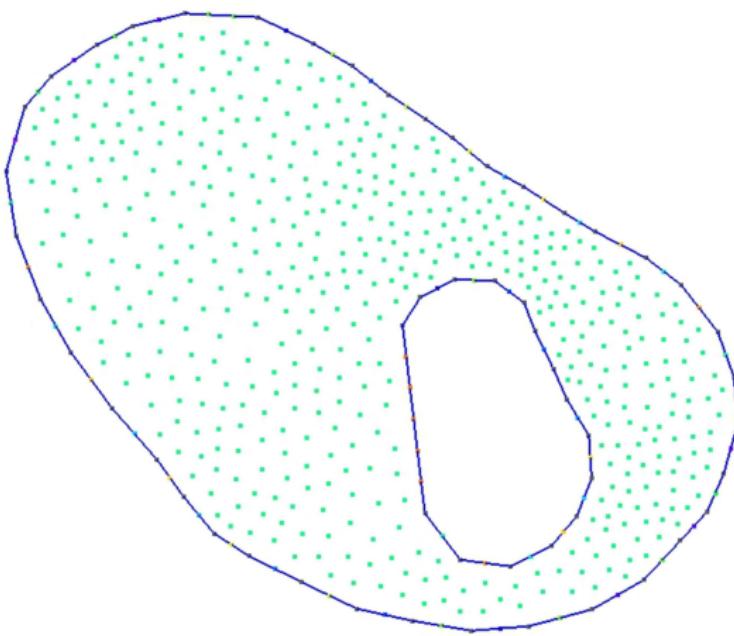
Finite Volume Method

$$\phi(x, y, z, t) \rightarrow \phi(x_i, y_j, z_k, t_l)$$



# Discretized Domain

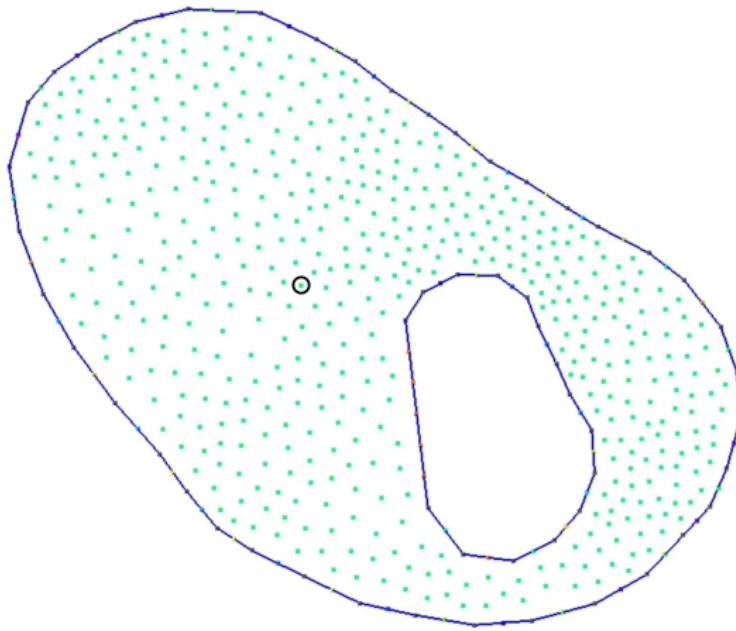
Mesh-free Method



# Discretized Domain

Mesh-free Method

$$\phi(x, y, z, t) \rightarrow \phi(x_i, y_j, z_k, t_l)$$



# Thank You

## References

Liu, M. B., Liu, G. R., Zhou, L. W., and Chang, J. Z. (2014). Dissipative Particle Dynamics (DPD): An Overview and Recent Developments. *Archives of Computational Methods in Engineering*, 22(4):529–556.