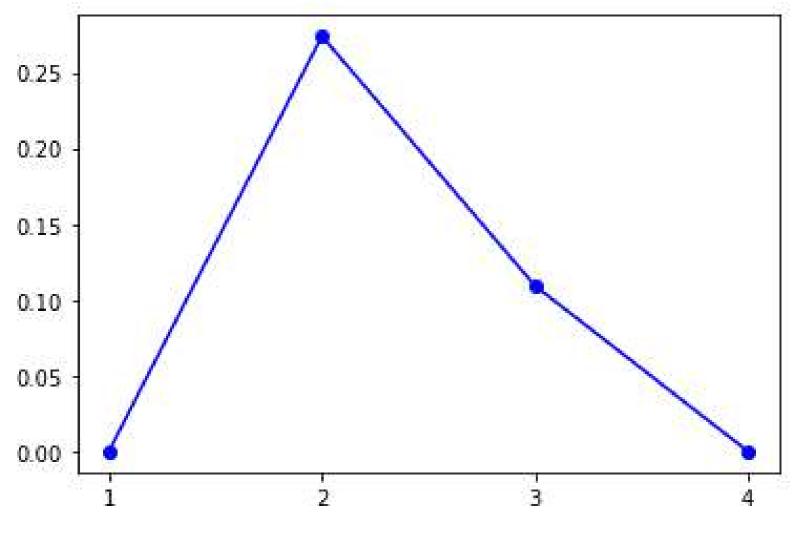
Task 1 a) 1st, we randomly choose A, B as Ct. C2 2nd, calculate the Euclidean olistance between C.D to each A, B regardely den = N4 +0.46 = 2.088, des = Noo4+2.85 = 1.513 don = 11+005 = 1.118 dos = 1064+256 x 1.789 C is closer to B. D is closer to A. We assign C to cluster K2. D to duster k1. 3rd, calculate the now cluster centroids $C_1 = \frac{(1.2+0.5, 0.8+0.3)}{2} = (0.7, 0.95),$ $C_2 = \frac{(-0.6 - 0.8, -1.3 + 0.2)}{2} = (-0.7, -0.55)$ 4th, we calculate the Euclidean distance between A.B.C.D and C1. Co. alace = 10.25 + 0.0625 ≈ 0.559, alacs = 1.92 + 0.005 ≈ 1.916 decr = 11.3 + 185 = 2.261 , decs = Noot+0.75 20.757 dect = N13° +035° = 1.54 , dea = Nov1 +075° = 0.757 doc1 = No.25 +015 = 0.559, docs = Nos1 +07205 = 1.238 Assign A.D to K+. B.C to k2, as in 2nd step. Converge. b) see the code C) Silhouettes are for evaluating the result of clustering. d(A,0) shows the distances between target mode and other nooles in the same cluster. the smaller d(A, 0) is, the more similar o is with other nodes of the same cluster. In convert, And d(B,0) shows the distance to nodes in other cluster. $S(0) = \frac{d(B,0) - d(A,0)}{max 3d(A,0), d(B,0)} = \begin{cases} 1 - \frac{d(A,0)}{d(B,0)} & \text{if } d(B,0) > d(B,0) \\ -1 + \frac{d(B,0)}{d(B,0)} & \text{if } d(A,0) > d(B,0) \end{cases}$ $0 \qquad \text{if } d(A,0) = d(B,0)$ if $S(0) \rightarrow 1$, it says $d(B,0) \gg d(A,0)$, the result of clustering is quite good. $S(0) \rightarrow -1$, it says $d(A, O) \Rightarrow d(B, O)$, o supposed to be classified to other cluster. if so) =0, it says there is no much difference if 0 in advocument cluster or other cluster or might be a boundary point

Exercise 4



Task 2 a) see the picture b) for partitioning methods, the clusters are not overlapping. However, hierarchy methods are consist of nested clusters, the higher lovel clusters based on clusters from previous levels. For hard clustering, the class of an object is certain, it can only assigned to one cluster. Meanwhile, soft clustering assign an obeject the probabilities belong to different clusters. The sum of an object in different clusters is 1. d) In the case that the shapes of different clusters are complicated, not regular, or there are not much space of gap between different dusters, we could consider density—based methods, as it is used despite the shapes and sizes of clusters. it could detect different clusters despite shapes and Advantages: size of clusters. Disadvantage: If the distribution of density inside a cluster is not even, then it might misclassify.

