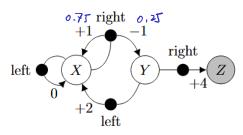
1. Three state MDP¹

Consider the MDP below, in which there are three states, $S = \{X, Y, Z\}$, two actions, $A = \{\text{left}, \text{right}\}$, and the rewards on each transition are as indicated by the numbers. Note that if action right is taken in state X, then the transition may be either to X with a reward of +1 or to Y with a reward of -1. These two possibilities occur with probabilities 0.75 (for the transition to X) and 0.25 (for the transition to state Y). The state Z is a terminal state, i.e., all transitions from Z are back to Z with a reward of 0. The initial state is always X.



(a)
$$P_0 = (1,0,0)$$

(b) For what combinations of inputs $s, s' \in \mathcal{S}$, $a \in \mathcal{A}$, $r \in \{4, 2, 1, 0, -1\}$ is the dynamics distribution p(s', r|s, a) of this MDP non-zero? Note that the distribution is discrete since the states, actions, and rewards are discrete. Write down the probabilities for these combinations.

Hint: There should be seven combinations with non-zero probability.

$$p(X, o | X, left) = 1$$
; $p(X, +1 | X, right) = 0.75$
 $p(Y, -1 | X, left) = 0.25$
 $p(X, +2 | Y, left) = 1$; $p(Z, +4 | Y, right) = 1$
 $p(Z, o | Z, left) = 1$; $p(Z, o | Z, right) = 1$

(c) Write down $\mathcal{P}(s'|s,a)$ and $\mathcal{R}(s,a)$ for all $s,s' \in \mathcal{S}, a \in \mathcal{A}$. The reward function can be derived from the dynamics distribution considered in part (b) using the formula from the lecture.

$$S = X$$
:

 $P(X|X, left) = 1$, $P(Y|X, left) = 0$, $P(Z|X, left) = 0$
 $P(X|X, right) = 0.25$, $P(Y|X, right) = 0.75$, $P(Z|X, right) = 0$
 $S = Y$:

 $P(X|Y, left) = 1$, $P(Y|Y, left) = 0$, $P(Z|Y, left) = 0$
 $P(X|Y, right) = 0$, $P(Y|Y, right) = 0$, $P(Z|Y, right) = 1$
 $S = Z$:

 $P(X|Z, left) = 0$, $P(Y|Z, left) = 0$, $P(Z|Z, left) = 1$
 $P(X|Z, right) = 0$, $P(Y|Z, right) = 0$, $P(Z|Z, right) = 1$

$$S = X$$
 $R(X, left) = 0$
 $R(X, night) = (t \mid 1) \cdot 0.7s + (-1) \cdot 0.2s = 0.s = Zr \sum P(s', r \mid s, a)$
 $S = Y$
 $R(Y, left) = +2$
 $R(Y, night) = +4$
 $S = Z$
 $R(Z, left) = 0$
 $R(Z, night) = 0$

(d) Consider the two deterministic policies π_1 and π_2 :

$$\pi_1(X) = \text{right}$$
 $\pi_2(X) = \text{left}$ $\pi_1(Y) = \text{right}$ $\pi_2(Y) = \text{right}$

Write down a typical trajectory for policy π_1 , i.e., make up a sequence of states, actions, and rewards that is likely to occur. What happens if you do this for π_2 ?

$$\pi_1: S_0 = X, Q_0 - \pi_1(X) = right, \Gamma_1 = +1$$
 $P = 0.75$
 $S_1 = X, Q_1 = \pi_1(X) = right, \Gamma_2 = -1$
 $S_0 = X, Q_0 = \pi_2(X) = left, \Gamma = 0$
 $S_0 = X, Q_0 = \pi_2(X) = left, \Gamma = 0$
 $S_0 = X, Q_0 = \pi_2(X) = left, \Gamma = 0$
 $S_0 = X, Q_0 = \pi_2(X) = left, \Gamma = 0$
 $S_0 = X, Q_0 = \pi_2(X) = left, \Gamma = 0$
 $S_0 = X, Q_0 = \pi_2(X) = left, \Gamma = 0$
 $S_0 = X, Q_0 = \pi_2(X) = left, \Gamma = 0$
 $S_0 = X, Q_0 = \pi_2(X) = left, \Gamma = 0$
 $S_0 = X, Q_0 = \pi_2(X) = left, \Gamma = 0$
 $S_0 = X, Q_0 = \pi_2(X) = left, \Gamma = 0$
 $S_0 = X, Q_0 = \pi_2(X) = left, \Gamma = 0$
 $S_0 = X, Q_0 = \pi_2(X) = left, \Gamma = 0$
 $S_0 = X, Q_0 = \pi_2(X) = left, \Gamma = 0$
 $S_0 = X, Q_0 = \pi_2(X) = left, \Gamma = 0$
 $S_0 = X, Q_0 = \pi_2(X) = left, \Gamma = 0$
 $S_0 = X, Q_0 = \pi_2(X) = left, \Gamma = 0$
 $S_0 = X, Q_0 = \pi_2(X) = left, \Gamma = 0$
 $S_0 = X, Q_0 = \pi_2(X) = left, \Gamma = 0$
 $S_0 = X, Q_0 = \pi_2(X) = left, \Gamma = 0$