

## Exercise 04

Sunday, November 5, 2023 6:13 PM

### Exercise 12 (10 points)

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(a) (6 points) Show that the spectral norm of a matrix  $A$  is equal to its largest singular value.

[Remark: Here you are allowed to use without proof that for real numbers  $a_1, \dots, a_n$ , a vector  $x = (x_1, \dots, x_n)^T$  with  $\|x\| = 1$  that maximizes  $\sum_{i=1}^n a_i x_i^2$  is the standard basis vector  $e_k$  where  $k$  is the index with  $a_k = \max\{a_i \mid i = 1 \dots n\}$ . All the necessary arguments occurred in the proof of Theorem 1.7.12.]

(b) (4 points, tricky) Prove that the matrix  $\Sigma$  in a singular value decomposition  $A = U\Sigma V^T$  is unique (if one demands that the diagonal entries are all positive and ordered by size).

[Hint: Use the Eckart-Young-Mirsky theorem in its version for the spectral norm, together with (a).]

$$\|A\| = \max \{ \|Av\|_2 \mid \forall v \in V, \|v\|_2 = 1 \}$$

Assume  $A \in \text{Mat}_{m \times n}$ , it is then a map  $V \rightarrow W$ ,

where  $\dim V = m$  and  $\dim W = n$

(a) Suppose  $v \in W$  is arbitrary with  $\|v\| = 1$

$$\begin{aligned} \|Av\|_2^2 &= \langle Av, Av \rangle = v^T A^T A v \\ &\stackrel{\text{SVD}}{=} v^T (V \Sigma^T U^T U \Sigma V^T) v \\ &= v^T (V \Sigma^T \Sigma V^T) v \\ &= (V^T v)^T \cdot (\Sigma^T \Sigma) \cdot (V^T v) \end{aligned}$$

$$\left. \begin{array}{l} U \in \text{Mat}_{m \times m} \\ \Sigma \in \text{Mat}_{m \times n} \\ V \in \text{Mat}_{n \times n} \end{array} \right\} \Sigma^T \Sigma \in \text{Mat}_{n \times n}$$

$$\text{let } x = V^T v = \{x_1, \dots, x_n\}$$

since  $V^T$  is orthogonal, it preserves length and angle.

$$\|v\|_2 = 1 \Rightarrow \|V^T v\|_2 = 1 \Rightarrow \|x\|_2 = 1$$

$$\text{so } \|Av\|^2 = x^T (\Sigma^T \Sigma) x = \sum_{i=1}^n a_i x_i^2, \text{ where } a_i (i=1, \dots, n)$$

are the diagonal entries of  $\Sigma^T \Sigma$ ,  $a_1 > a_2 > \dots > a_n$

According to the remark, for  $x$  which

$$\begin{aligned} \text{maximizes } \|Av\| &\geq 0 \Rightarrow \max \{ \|Av\|^2 \} \\ &= \max \left\{ \sum_{i=1}^n a_i x_i^2 \right\} \end{aligned}$$

$$\begin{aligned} x = e_1, \quad \|Av\|_{\max} &= \sqrt{a_1 \cdot 1 + a_2 \cdot 0 + \dots + a_n \cdot 0} \\ &= \sqrt{a_1} = \sigma_1 \end{aligned}$$

and  $\sqrt{a_1}$  is the largest singular value of  $A$  //

(b) (4 points, tricky) Prove that the matrix  $\Sigma$  in a singular value decomposition  $A = U\Sigma V^T$  is unique (if one demands that the diagonal entries are all positive and ordered by size).

[Hint: Use the Eckart-Young-Mirsky theorem in its version for the spectral norm, together with (a).]

Suppose for  $A \in \text{Mat}_{m \times n}$ ,  $\exists \Sigma' \neq \Sigma$ , s.t.  $A = U' \Sigma' V'^T$  is another SVD

We assume diagonal entries of  $\Sigma$ :  $\sigma_1, \dots, \sigma_r, \sigma_1, \dots, \sigma_r \in \mathbb{R}_{>0}$ ,  $\sigma_1 > \dots > \sigma_r$ ,  $r = \min\{n, m\}$

$$\Sigma': \sigma'_1, \dots, \sigma'_r, \sigma'_1, \dots, \sigma'_r \in \mathbb{R}_{>0}, \sigma'_1 > \dots > \sigma'_r$$

1. from (a) we know  $\|A\| = \sigma_1$  and  $\|A\| = \sigma'_1 \Rightarrow \sigma_1 = \sigma'_1$

2. for  $\forall i, 1 \leq i \leq r-1$ :  $\|A - A^{(i)}\| = \|\Sigma - \Sigma^{(i)}\| = \|\Sigma' - \Sigma'^{(i)}\|$

$$\text{we define } B := \Sigma - \Sigma^{(i)}, B' := \Sigma' - \Sigma'^{(i)}$$

$$\text{from (a) we know } \|B\| = \max \{ \sigma_{i+1}, \dots, \sigma_r \} = \sigma_{i+1}$$

$$\text{similarly } \|B'\| = \sigma'_{i+1} = \|A - A^{(i)}\| = \|B\| = \sigma_{i+1}$$

Therefore, for  $\forall k, 1 \leq k \leq r$ :  $\sigma_k = \sigma'_k$

$$\Rightarrow \Sigma = \Sigma' \quad \perp \text{ contradiction.}$$

Other ideas

$$\|A - A^{(k)}\| \leq \|A - U \Sigma^{(k)} V^T\|$$

$$\sigma_{RH} \leq \|\Sigma - \Sigma^{(k)}\|$$

$\Downarrow$

$$\max \left( \sum_{i=1}^k (\sigma_i - \sigma'_i)^2 v_i^2 + \sum_{i=k+1}^r \sigma_i^2 v_i^2 \right)$$

This might not work

### Exercise 13 (10 points)

Compute a singular value decomposition of the following matrix:

$$A = \begin{pmatrix} 2 & -2 & 1 \\ -4 & -8 & -8 \end{pmatrix}$$

$$A^T = \begin{pmatrix} 2 & -4 \\ -2 & -8 \\ 1 & -8 \end{pmatrix} \quad A = \begin{pmatrix} 2 & -2 & 1 \\ -4 & -8 & -8 \end{pmatrix}$$

we find SVD of  $A^T$  and then transpose the result to reduce calculation in eigenvalues

$$(A^T)^T A^T = A A^T = \begin{pmatrix} 4+4+1 & -8+16-8 \\ -8+16-8 & 16+64+64 \end{pmatrix} \\ = \begin{pmatrix} 9 & 0 \\ 0 & 144 \end{pmatrix} \Rightarrow \lambda_{1,2} = 144, 9$$

$$\lambda_2 = 9: \text{eigenvector } v_2 = (a, b)^T \\ \begin{pmatrix} 0 & 0 \\ 0 & 135 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$b = 0, \text{ let } a = 1 \Rightarrow v_2 = (1, 0)^T \\ \lambda_1 = 144: v_1 = (c, d)^T \\ \begin{pmatrix} -135 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} c \\ d \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \left\{ \begin{array}{l} \langle v_1, v_2 \rangle = 0 \\ \|v_1\| = \|v_2\| = 1 \end{array} \right. \\ c = 0, \text{ let } d = 1 \Rightarrow v_1 = (0, 1)^T$$

$$\Sigma = \begin{pmatrix} \sqrt{144} & 0 \\ 0 & \sqrt{9} \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 12 & 0 \\ 0 & 3 \\ 0 & 0 \end{pmatrix}$$

so the right orthogonal matrix for  $A^T$  can be

$$V = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad A^T = \begin{pmatrix} 2 & -4 \\ -2 & -8 \\ 1 & -8 \end{pmatrix}$$

$$A^T v_1 = \begin{pmatrix} -4 \\ -8 \\ -8 \end{pmatrix} \quad u_1 = \frac{A^T v_1}{\|A^T v_1\|} = \begin{pmatrix} -\frac{1}{3} \\ -\frac{2}{3} \\ -\frac{2}{3} \end{pmatrix} \quad \langle e_2, u_1 \rangle = \langle e_2, u_2 \rangle = -\frac{2}{3}$$

$$A^T v_2 = \begin{pmatrix} 2 \\ -2 \\ 1 \end{pmatrix} \quad u_2 = \frac{A^T v_2}{\|A^T v_2\|} = \begin{pmatrix} \frac{2}{3} \\ -\frac{2}{3} \\ \frac{1}{3} \end{pmatrix}$$

$$\tilde{u}_0 = e_2 - \langle e_2, u_1 \rangle u_1 - \langle e_2, u_2 \rangle u_2$$

$$= \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} - \begin{pmatrix} \frac{2}{3} \\ \frac{4}{3} \\ \frac{2}{3} \end{pmatrix} - \begin{pmatrix} -\frac{4}{3} \\ \frac{4}{3} \\ -\frac{2}{3} \end{pmatrix} = \begin{pmatrix} \frac{2}{3} \\ \frac{1}{3} \\ -\frac{2}{3} \end{pmatrix}$$

$$\|\tilde{u}_0\| = \sqrt{\frac{4}{9} + \frac{1}{9} + \frac{4}{9}} = \frac{1}{3} \quad u_0 = \frac{\tilde{u}_0}{\|\tilde{u}_0\|} = \begin{pmatrix} \frac{2}{3} \\ \frac{1}{3} \\ -\frac{2}{3} \end{pmatrix}$$

$$\text{so left orthogonal matrix } U = \begin{pmatrix} -\frac{1}{3} & \frac{2}{3} & \frac{2}{3} \\ -\frac{2}{3} & -\frac{2}{3} & \frac{1}{3} \\ -\frac{2}{3} & \frac{1}{3} & -\frac{1}{3} \end{pmatrix}$$

so left orthogonal matrix  $U = \begin{pmatrix} -\frac{1}{3} & \frac{2}{3} & \frac{2}{3} \\ -\frac{2}{3} & -\frac{2}{3} & \frac{1}{3} \\ -\frac{2}{3} & \frac{1}{3} & -\frac{2}{3} \end{pmatrix}$

$$A^T = U \Sigma V^T$$

$$\Rightarrow A = (A^T)^T = V \Sigma^T U^T$$

$$= \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 12 & 0 & 0 \\ 0 & 3 & 0 \end{pmatrix} \begin{pmatrix} -\frac{1}{3} & -\frac{2}{3} & -\frac{2}{3} \\ \frac{2}{3} & -\frac{2}{3} & \frac{1}{3} \\ \frac{2}{3} & \frac{1}{3} & -\frac{2}{3} \end{pmatrix}$$

easy to forget the 0s

#### Exercise 14 (10 points)

Find the polynomial of degree 2 in one variable that best approximates (in the sense of least squares) a function whose graph passes through the points  $(-1, 0)$ ,  $(2, 1)$ ,  $(1, -1)$  and  $(0, 1)$  in  $\mathbb{R}^2$ . Use the idea of exercise 2 for this!

[Remark: It is up to you how you solve the exercise. One way is to use that the best approximate solution  $x$  to the equation  $Ax = y$  is given by  $A^+ y$ , where  $A^+$  denotes the pseudoinverse of  $A$  – we will discuss this on Tuesday, it's Theorem 1.8.4. If you want to solve the exercise before Tuesday, you can simply use that. In the lecture I briefly showed the proof of Thm 1.8.2, i.e. how to compute a pseudoinverse in general. Alternatively, you have already seen how to compute a pseudoinverse for a full rank matrix in exercise 5. You can do it either way, but if you use the approach of exercise 5, don't forget to check that you actually have a full rank matrix. The method of exercise 5 then involves inverting a matrix – you don't need to show your calculations on how to find that inverse (e.g. you can let a computer find it). You can simply write down the inverse, preferably in the form  $\frac{1}{20}$  times an integer matrix.]

A polynomial of degree 2 can be written as

$$y = w_2 x^2 + w_1 x + b, \quad w_1, w_2, b \in \mathbb{R}$$

Insert the known points into the equation:

$$\begin{cases} 1 \cdot w_2 + (-1) \cdot w_1 + b = 0 \\ 4 \cdot w_2 + 2 \cdot w_1 + b = 1 \\ 1 \cdot w_2 + 1 \cdot w_1 + b = -1 \\ 0 \cdot w_2 + 0 \cdot w_1 + b = 1 \end{cases}$$

$$\Rightarrow \underbrace{\begin{pmatrix} 1 & -1 & 1 \\ 4 & 2 & 1 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}}_A \underbrace{\begin{pmatrix} w_2 \\ w_1 \\ b \end{pmatrix}}_x = \underbrace{\begin{pmatrix} 0 \\ 1 \\ -1 \\ 1 \end{pmatrix}}_y$$

Now perform SVD on matrix  $A$ :

$$A^T = \begin{pmatrix} 1 & 4 & 1 & 0 \\ -1 & 2 & 1 & 0 \\ 1 & 1 & 1 & 1 \end{pmatrix}$$

$$A^T A = \begin{pmatrix} 1+16+1 & -1+8+1 & 1+4+1 \\ \text{sym} & 1+4+1 & -1+2+1 \\ & & 4 \end{pmatrix}$$

$$= \begin{pmatrix} 18 & 8 & 6 \\ 8 & 6 & 2 \\ 6 & 2 & 4 \end{pmatrix}$$

$$\det(A^T A) = 18 \cdot 6 \cdot 4 + 8 \cdot 2 \cdot 6 + 8 \cdot 2 \cdot 6$$

$$- 18 \cdot 2 \cdot 2 - 8 \cdot 8 \cdot 4 - 6 \cdot 6 \cdot 6$$

$$= 432 + 96 + 96 - 72 - 256 - 216$$

$$= 80 \neq 0, \text{ therefore } A^T A \text{ is invertible}$$

$$(A^T A)^{-1} = \frac{1}{20} \begin{pmatrix} 5 & -5 & -5 \\ -5 & 9 & 3 \\ -5 & 3 & 11 \end{pmatrix}$$

$$A^+ = (A^T A)^{-1} A^T = \frac{1}{20} \begin{pmatrix} 5 & -5 & -5 \\ -5 & 9 & 3 \\ -5 & 3 & 11 \end{pmatrix} \begin{pmatrix} 1 & 4 & 1 & 0 \\ -1 & 2 & 1 & 0 \\ 1 & 1 & 1 & 1 \end{pmatrix}$$

$$= \frac{1}{20} \begin{pmatrix} 5+5-5 & 20-10-5 & 5-5-5 & -5 \\ -5-9+3 & -20+18+3 & -5+9+3 & 3 \end{pmatrix}$$

	B <sub>1</sub>	B <sub>2</sub>	B <sub>3</sub>
1	1/4	-1/4	-1/4
2	-1/4	9/20	3/20
3	-1/4	3/20	11/20

$$= \frac{1}{20} \begin{pmatrix} 5+5-5 & 20-10-5 & 5-5-5 & -5 \\ -5-9+3 & -20+18+3 & -5+9+3 & 3 \\ -5-3+11 & -20+6+11 & -5+3+11 & 11 \end{pmatrix}$$

$$= \frac{1}{20} \begin{pmatrix} 5 & 5 & -5 & -5 \\ -11 & 1 & 7 & 3 \\ 3 & -3 & 9 & 11 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ -1 \\ 1 \end{pmatrix}$$

$$\text{So } \hat{x} = A^+ y$$

$$= \frac{1}{20} \begin{pmatrix} 5+5-5 \\ 1-7+3 \\ -3-9+11 \end{pmatrix} = \frac{1}{20} \begin{pmatrix} 5 \\ -3 \\ -1 \end{pmatrix}$$