

Exercise 04

Sunday, November 5, 2023 6:13 PM

Exercise 12 (10 points)

神经病

(a) (6 points) Show that the spectral norm of a matrix A is equal to its largest singular value.

[Remark: Here you are allowed to use without proof that for real numbers a_1, \dots, a_n , a vector $x = (x_1, \dots, x_n)^T$ with $\|x\| = 1$ that maximizes $\sum_{i=1}^n a_i x_i^2$ is the standard basis vector e_k where k is the index with $a_k = \max\{a_i \mid i = 1 \dots n\}$. All the necessary arguments occurred in the proof of Theorem 1.7.12.]

(b) (4 points, tricky) Prove that the matrix Σ in a singular value decomposition $A = U\Sigma V^T$ is unique (if one demands that the diagonal entries are all positive and ordered by size).

[Hint: Use the Eckart-Young-Mirsky theorem in its version for the spectral norm, together with (a).]

$$\|A\| = \max \{ \|Av\|_2 \mid \forall v \in V, \|v\|_2 = 1 \}$$

Assume $A \in \text{Mat}_{m \times n}$, it is then a map $V \rightarrow W$,

where $\dim V = m$ and $\dim W = n$

(a) Suppose $v \in W$ is arbitrary with $\|v\| = 1$

$$\|Av\|_2^2 = \langle Av, Av \rangle = v^T A^T A v$$

$$\stackrel{\text{SVD}}{=} v^T (V \Sigma^T U^T U \Sigma V^T) v$$

$$= v^T (V \Sigma^T \Sigma V^T) v$$

$$= (V^T v)^T \cdot (\Sigma^T \Sigma) \cdot (V^T v)$$

$$\left. \begin{array}{l} U \in \text{Mat}_{m \times m} \\ \Sigma \in \text{Mat}_{m \times n} \\ V \in \text{Mat}_{n \times n} \end{array} \right\} \Sigma^T \Sigma \in \text{Mat}_{n \times n}$$

$$\text{let } x = V^T v = \{x_1, \dots, x_n\}$$

since V^T is orthogonal, it preserves length and angle.

$$\|v\|_2 = 1 \Rightarrow \|V^T v\|_2 = 1 \Rightarrow \|x\|_2 = 1$$

$$\text{so } \|Av\|^2 = x^T (\Sigma^T \Sigma) x = \sum_{i=1}^n a_i x_i^2, \text{ where } a_i (i=1, \dots, n)$$

are the diagonal entries of $\Sigma^T \Sigma$, $a_1 > a_2 > \dots > a_n$

According to the remark, for x which

$$\text{maximizes } \|Av\| \geq 0 \Rightarrow \max \{ \|Av\|^2 \}$$

$$= \max \left\{ \sum_{i=1}^n a_i x_i^2 \right\}$$

$$x = e_1, \quad \|Av\|_{\max} = \sqrt{a_1 \cdot 1 + a_2 \cdot 0 + \dots + a_n \cdot 0}$$

$$= \sqrt{a_1} = \sigma_1$$

and $\sqrt{a_1}$ is the largest singular value of A //

(b) (4 points, tricky) Prove that the matrix Σ in a singular value decomposition $A = U\Sigma V^T$ is unique (if one demands that the diagonal entries are all positive and ordered by size).

[Hint: Use the Eckart-Young-Mirsky theorem in its version for the spectral norm, together with (a).]

Suppose for $A \in \text{Mat}_{m \times n}$, $\exists \Sigma' \neq \Sigma$, s.t. $A = U' \Sigma' V'^T$ is another SVD

We assume diagonal entries of Σ : $\sigma_1, \dots, \sigma_r, \sigma_1, \dots, \sigma_r \in \mathbb{R}_{>0}$, $\sigma_1 > \dots > \sigma_r$, $r = \min\{n, m\}$

$$\Sigma': \sigma'_1, \dots, \sigma'_r, \sigma'_1, \dots, \sigma'_r \in \mathbb{R}_{>0}, \sigma'_1 > \dots > \sigma'_r$$

1. from (a) we know $\|A\| = \sigma_1$ and $\|A\| = \sigma'_1 \Rightarrow \sigma_1 = \sigma'_1$

2. for $\forall i, 1 \leq i \leq r-1$: $\|A - A^{(i)}\| = \|\Sigma - \Sigma^{(i)}\| = \|\Sigma' - \Sigma'^{(i)}\|$

$$\text{we define } B := \Sigma - \Sigma^{(i)}, B' := \Sigma' - \Sigma'^{(i)}$$

$$\text{from (a) we know } \|B\| = \max \{ \sigma_{i+1}, \dots, \sigma_r \} = \sigma_{i+1}$$

$$\text{similarly } \|B'\| = \sigma'_{i+1} = \|A - A^{(i)}\| = \|B\| = \sigma_{i+1}$$

Therefore, for $\forall k, 1 \leq k \leq r$: $\sigma_k = \sigma'_k$

$$\Rightarrow \Sigma = \Sigma' \quad \text{! contradiction!}$$

Other ideas

$$\|A - A^{(k)}\| \leq \|A - U \Sigma^{(k)} V^T\|$$

$$\sigma_{RH} \leq \|\Sigma - \Sigma^{(k)}\|$$

\Downarrow

$$\max \left(\sum_{i=1}^k (\sigma_i - \sigma'_i)^2 v_i^2 + \sum_{i=k+1}^r \sigma_i^2 v_i^2 \right)$$

This might not work

Exercise 13 (10 points)

Compute a singular value decomposition of the following matrix:

$$A = \begin{pmatrix} 2 & -2 & 1 \\ -4 & -8 & -8 \end{pmatrix}$$

$$A^T = \begin{pmatrix} 2 & -4 \\ -2 & -8 \\ 1 & -8 \end{pmatrix} \quad A = \begin{pmatrix} 2 & -2 & 1 \\ -4 & -8 & -8 \end{pmatrix}$$

we find SVD of A^T and then transpose the result to reduce calculation in eigenvalues

$$(A^T)^T A^T = A A^T = \begin{pmatrix} 4+4+1 & -8+16-8 \\ -8+16-8 & 16+64+64 \end{pmatrix} \\ = \begin{pmatrix} 9 & 0 \\ 0 & 144 \end{pmatrix} \Rightarrow \lambda_{1,2} = 144, 9$$

$$\lambda_2 = 9: \text{eigenvector } v_2 = (a, b)^T \\ \begin{pmatrix} 0 & 0 \\ 0 & 135 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$b = 0, \text{ let } a = 1 \Rightarrow v_2 = (1, 0)^T \\ \lambda_1 = 144: v_1 = (c, d)^T \\ \begin{pmatrix} -135 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} c \\ d \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \left\{ \begin{array}{l} \langle v_1, v_2 \rangle = 0 \\ \|v_1\| = \|v_2\| = 1 \end{array} \right. \\ c = 0, \text{ let } d = 1 \Rightarrow v_1 = (0, 1)^T$$

$$\Sigma = \begin{pmatrix} \sqrt{144} & 0 \\ 0 & \sqrt{9} \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 12 & 0 \\ 0 & 3 \\ 0 & 0 \end{pmatrix}$$

so the right orthogonal matrix for A^T can be

$$V = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad A^T = \begin{pmatrix} 2 & -4 \\ -2 & -8 \\ 1 & -8 \end{pmatrix}$$

$$A^T v_1 = \begin{pmatrix} -4 \\ -8 \\ -8 \end{pmatrix} \quad u_1 = \frac{A^T v_1}{\|A^T v_1\|} = \begin{pmatrix} -\frac{1}{3} \\ -\frac{2}{3} \\ -\frac{2}{3} \end{pmatrix} \quad \langle e_2, u_1 \rangle = \langle e_2, u_2 \rangle = -\frac{2}{3}$$

$$A^T v_2 = \begin{pmatrix} 2 \\ -2 \\ 1 \end{pmatrix} \quad u_2 = \frac{A^T v_2}{\|A^T v_2\|} = \begin{pmatrix} \frac{2}{3} \\ -\frac{2}{3} \\ \frac{1}{3} \end{pmatrix}$$

$$\tilde{u}_0 = e_2 - \langle e_2, u_1 \rangle u_1 - \langle e_2, u_2 \rangle u_2$$

$$= \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} - \begin{pmatrix} \frac{2}{3} \\ -\frac{2}{3} \\ \frac{1}{3} \end{pmatrix} - \begin{pmatrix} -\frac{2}{3} \\ \frac{2}{3} \\ -\frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{2}{3} \\ \frac{1}{3} \\ -\frac{2}{3} \end{pmatrix}$$

$$\|\tilde{u}_0\| = \sqrt{\frac{4}{9} + \frac{1}{9} + \frac{4}{9}} = \frac{1}{3} \quad u_0 = \frac{\tilde{u}_0}{\|\tilde{u}_0\|} = \begin{pmatrix} \frac{2}{3} \\ \frac{1}{3} \\ -\frac{2}{3} \end{pmatrix}$$

$$\text{so left orthogonal matrix } U = \begin{pmatrix} -\frac{1}{3} & \frac{2}{3} & \frac{2}{3} \\ -\frac{2}{3} & -\frac{2}{3} & \frac{1}{3} \\ -\frac{2}{3} & \frac{1}{3} & -\frac{1}{3} \end{pmatrix}$$

so left orthogonal matrix $U = \begin{pmatrix} -\frac{1}{3} & \frac{2}{3} & \frac{2}{3} \\ -\frac{2}{3} & -\frac{2}{3} & \frac{1}{3} \\ -\frac{2}{3} & \frac{1}{3} & -\frac{2}{3} \end{pmatrix}$

$$A^T = U \Sigma V^T$$

$$\Rightarrow A = (A^T)^T = V \Sigma^T U^T$$

$$= \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 12 & 0 & 0 \\ 0 & 3 & 0 \end{pmatrix} \begin{pmatrix} -\frac{1}{3} & -\frac{2}{3} & -\frac{2}{3} \\ \frac{2}{3} & -\frac{2}{3} & \frac{1}{3} \\ \frac{2}{3} & \frac{1}{3} & -\frac{2}{3} \end{pmatrix}$$

easy to forget the 0s

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Exercise 14 (10 points)

Find the polynomial of degree 2 in one variable that best approximates (in the sense of least squares) a function whose graph passes through the points $(-1, 0)$, $(2, 1)$, $(1, -1)$ and $(0, 1)$ in \mathbb{R}^2 . Use the idea of exercise 2 for this!

[Remark: It is up to you how you solve the exercise. One way is to use that the best approximate solution x to the equation $Ax = y$ is given by $A^+ y$, where A^+ denotes the pseudoinverse of A – we will discuss this on Tuesday, it's Theorem 1.8.4. If you want to solve the exercise before Tuesday, you can simply use that. In the lecture I briefly showed the proof of Thm 1.8.2, i.e. how to compute a pseudoinverse in general. Alternatively, you have already seen how to compute a pseudoinverse for a full rank matrix in exercise 5. You can do it either way, but if you use the approach of exercise 5, don't forget to check that you actually have a full rank matrix. The method of exercise 5 then involves inverting a matrix – you don't need to show your calculations on how to find that inverse (e.g. you can let a computer find it). You can simply write down the inverse, preferably in the form $\frac{1}{20}$ times an integer matrix.]

A polynomial of degree 2 can be written as

$$y = w_2 x^2 + w_1 x + b, \quad w_2, w_1, b \in \mathbb{R}$$

Insert the known points into the equation:

$$\begin{cases} 1 \cdot w_2 + (-1) \cdot w_1 + b = 0 \\ 4 \cdot w_2 + 2 \cdot w_1 + b = 1 \\ 1 \cdot w_2 + 1 \cdot w_1 + b = -1 \\ 0 \cdot w_2 + 0 \cdot w_1 + b = 1 \end{cases}$$

$$\Rightarrow \begin{pmatrix} 1 & -1 & 1 \\ 4 & 2 & 1 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} w_2 \\ w_1 \\ b \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ -1 \\ 1 \end{pmatrix}$$

A

x

y

✓

Now perform SVD on matrix A :

$$A^T = \begin{pmatrix} 1 & 4 & 1 & 0 \\ -1 & 2 & 1 & 0 \\ 1 & 1 & 1 & 1 \end{pmatrix}$$

$$A^T A = \begin{pmatrix} 1+16+1 & -1+8+1 & 1+4+1 \\ \text{sym} & 1+4+1 & -1+2+1 \\ & & 4 \end{pmatrix}$$

$$= \begin{pmatrix} 18 & 8 & 6 \\ 8 & 6 & 2 \\ 6 & 2 & 4 \end{pmatrix}$$

$$\det(A^T A) = 18 \cdot 6 \cdot 4 + 8 \cdot 2 \cdot 6 + 8 \cdot 2 \cdot 6 - 18 \cdot 2 \cdot 2 - 8 \cdot 8 \cdot 4 - 6 \cdot 6 \cdot 6$$

$$= 432 + 96 + 96 - 72 - 256 - 216$$

$$= 80 \neq 0, \text{ therefore } A^T A \text{ is invertible}$$

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$$(A^T A)^{-1} = \frac{1}{80} \begin{pmatrix} 5 & -5 & -5 \\ -5 & 9 & 3 \\ -5 & 3 & 11 \end{pmatrix}$$

$$A^+ = (A^T A)^{-1} A^T = \frac{1}{80} \begin{pmatrix} 5 & -5 & -5 \\ -5 & 9 & 3 \\ -5 & 3 & 11 \end{pmatrix} \begin{pmatrix} 1 & 4 & 1 & 0 \\ -1 & 2 & 1 & 0 \\ 1 & 1 & 1 & 1 \end{pmatrix}$$

$$= \frac{1}{80} \begin{pmatrix} 5+5-5 & 20-10-5 & 5-5-5 & -5 \\ -5-9+3 & -20+18+3 & -5+9+3 & 3 \end{pmatrix}$$

	B_1	B_2	B_3
1	1/4	-1/4	-1/4
2	-1/4	9/20	3/20
3	-1/4	3/20	11/20

$$= \frac{1}{20} \begin{pmatrix} 5+5-5 & 20-10-5 & 5-5-5 & -5 \\ -5-9+3 & -20+18+3 & -5+9+3 & 3 \\ -5-3+11 & -20+6+11 & -5+3+11 & 11 \end{pmatrix}$$

$$= \frac{1}{20} \begin{pmatrix} 5 & 5 & -5 & -5 \\ -11 & 1 & 7 & 3 \\ 3 & -3 & 9 & 11 \end{pmatrix} \quad \checkmark \quad \begin{pmatrix} 0 \\ 1 \\ -1 \\ 1 \end{pmatrix}$$

So $\hat{x} = A^+ y$

$$= \frac{1}{20} \begin{pmatrix} 5+5-5 \\ 1-7+3 \\ -3-9+11 \end{pmatrix} = \frac{1}{20} \begin{pmatrix} 5 \\ -3 \\ -1 \end{pmatrix} \quad \checkmark$$

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Ex15:

a) and b) 6/6

c) You should have used the train and test sets provided by the instructions

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xtrain, xtest, ytrain, ytest =

train_test_split(X, y, test_size=0.25)