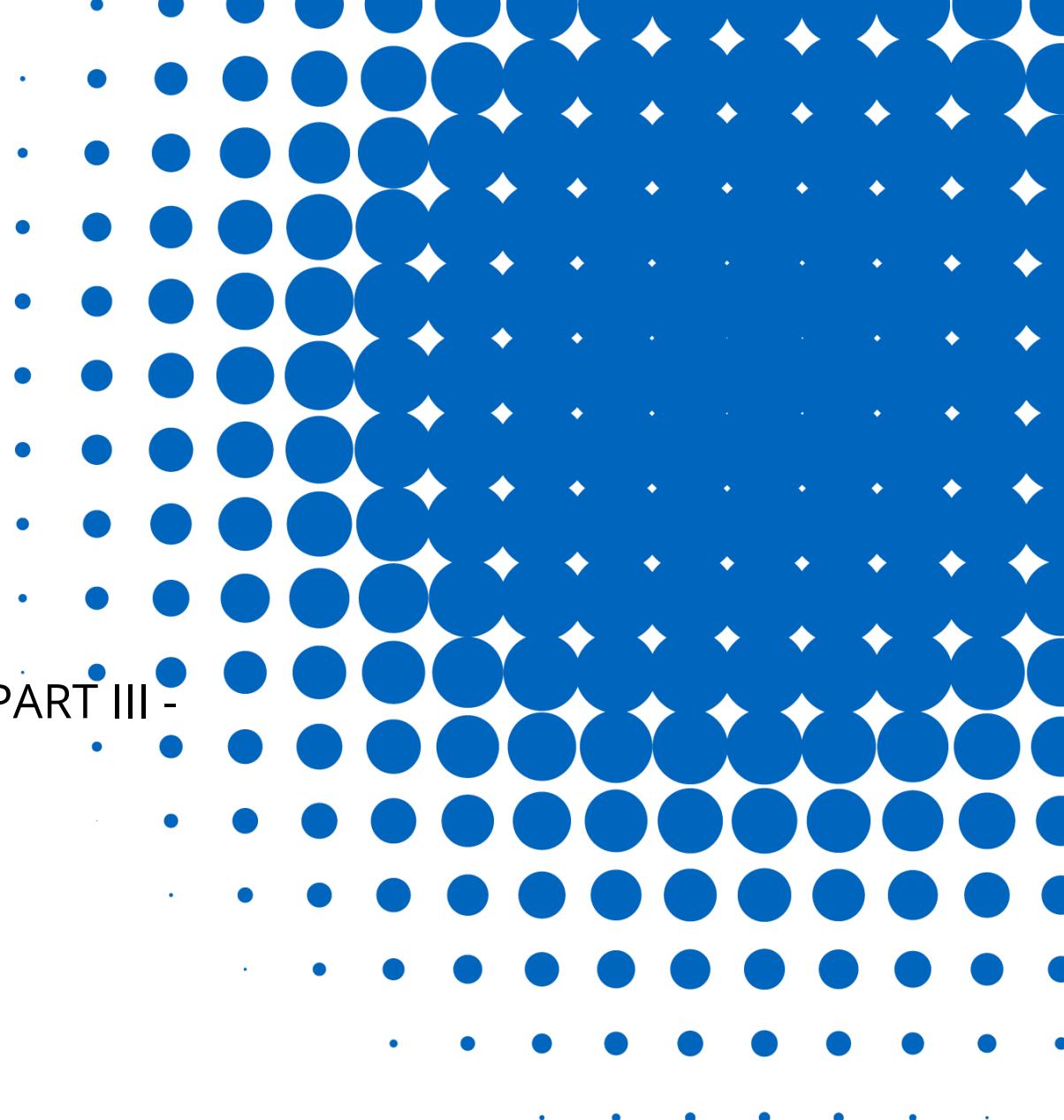


# **DATA MODELLING IN ENGINEERING**

MODELING BASED ON LOGIC PROGRAMMING – PART III –

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2024 - 2025



# Contents



## ➤ PROLOG

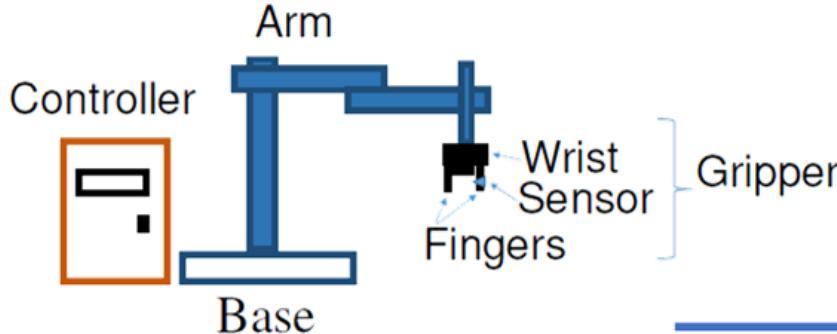
- ❖ Unification
- ❖ Backtracking mechanism
- ❖ Recursion mechanism
- ❖ Facts / Rules / Queries
- ❖ Structures
- ❖ Combined Queries
- ❖ Changing the memory of PROLOG
- ❖ INPUT / OUTPUT
- ❖ Directed Graph
- ❖ Lists in Prolog
- ❖ Lists and Graphs

# Facts / Rules / Queries

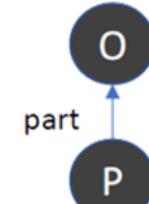
... from previous class ...

Going back to the robot model example:

We can generalize the rule



`includes(O,P) :- part(O,P).`  
`includes(O, P) :- part(O,Z), part(Z,P).`



*/\* O includes P if O has a part P \*/*  
*/\* O includes P if O has a part Z and Z has a part P \*/*

transitivity

One possible solution:

`part(robot, base).`  
`part(robot, arm).`  
`part(robot, gripper).`  
`part(robot, controller).`  
`part(gripper, wrist).`  
`part(gripper, fingers).`  
`part(gripper, sensor).`

A more generic solution



`contains(O,P) :- part(O,P).`  
`contains(O,P) :- part(Z,P), contains(O,Z).`

*/\* O contains P if O has part P \*/*  
*/\* O contains P if Z has part P and O contains Z \*/*

The 2<sup>nd</sup> rule is defined in +  
... i.e. recursive definition

recursion mechanism

# Structures / Combined Queries

... from previous class ...

```
/*      #id,      name, age, birthdate, address */
person(31267389, john, birthdate(24,11,2000), address('R Bernardo Marques', 7, 'Caprica')).
person(43261876, mary, birthdate(16,06,2001), address('R Francisco Costa', 5, 'Caprica')).
person(36482754, jane, birthdate(30,01,2004), address('R Garcia de Orta', 3, 'Almada')).
person(37392715, thomas, birthdate(05,03,2000), address('R Alfredo Cunha', 9, 'Caprica')).  
...
```

Identify by name, people that live in Almada:

```
?- person(_, N, _, address(_, _, 'Almada')).
```

N = jane.

```
/*      Nr, Name, gender, year      */
student(65200, 'Ademir Paulo Santos Caetano', m, 3).
student(65145, 'Afonso Aleixo Vieira Gonçalves Varela', m, 3).
student(65405, 'André Filipe Freitas Mendes', m, 3).
student(65368, 'André Gomes Antunes', m, 3).
student(54543, 'António Manuel Sebastião Ferreira Deveza', m, 3).
student(65499, 'Beatriz Flórido Pereira', f, 3).
student(65243, 'Bernardo de Oliveira Lopes Garcia Barata', m, 3).
% ...
student(66092, 'Vasco Cananão Mendes', m, 3).

gender(f, female).
gender(m, male).
```

What is the gender of student nº 65405 ?

What are the numbers female students ?

?- student(65405, \_, G, \_), gender(G, Gender).

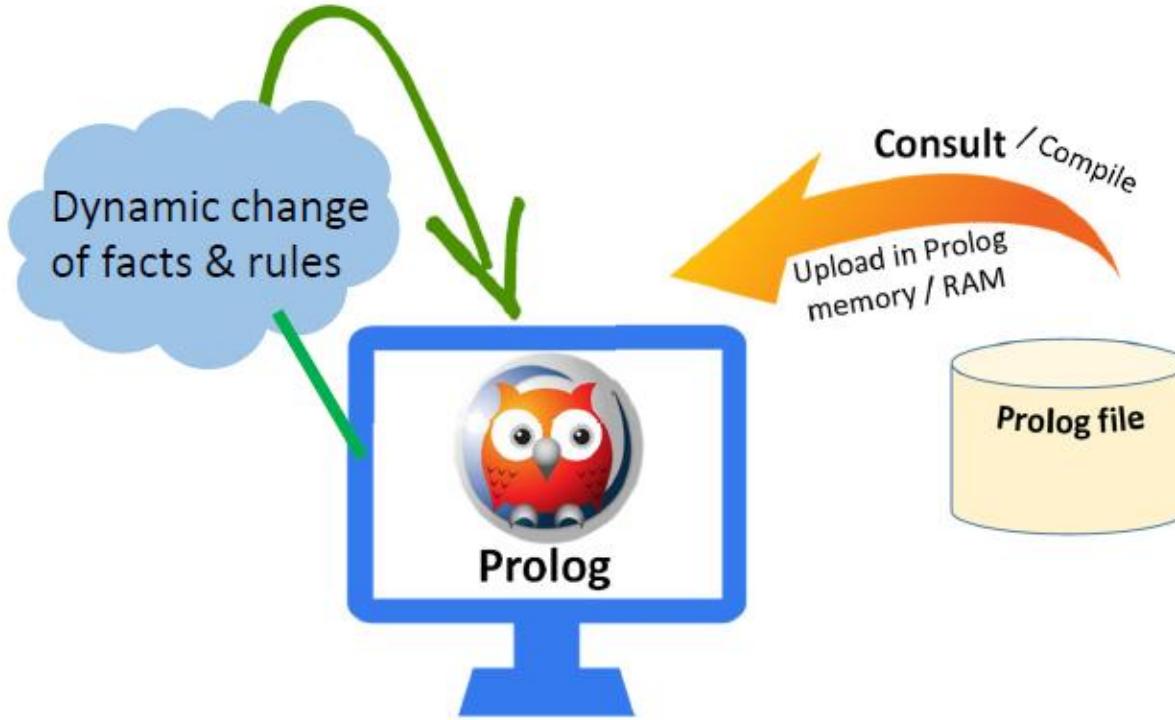
G = m , Gender = male.

?- gender(G, female), student(N, \_, G, \_).

G = f , N = 65499.

# Changing the Memory in Prolog

... from previous class ...



`assert(S)`

`asserta(S)`

`assertz(S)`

`retract(S)`

`Retractall(S)`

*To add facts / rules*

*To remove/delete facts / rules*

Informs the interpreter that the definition of the predicate(s) may change during execution (using assert/1 and/or retract/1)

`:dynamic fact/args`

List matching clauses

`listing(X)`

# Input / Output

... from previous class ...

## Exercise

Let's get back to the example of fathers and create a menu for a “FATHERS MANAGEMENT SYSTEM ☺”

```
gmenu:- nl,nl,write('FATHERS MANAGEMENT SYSTEM :)'),nl,  
        menu(Op), execute(Op).  
  
menu(Op):- write('1. List fathers'),nl,  
          write('2. Insert father'),nl,  
          write('3. Delete fathers'),nl,  
          write('4. Exit'), nl, readoption(Op).  
  
readoption(Op):- read(Op),valid(Op),nl.  
readoption(Op):- nl, write('*** Invalid option. Try again: '), readoption(Op).  
  
valid(Op):- Op >=1, Op=<4.  
  
execute(4). % exit condition  
execute(Op):- exec(Op),nl,  
           menu(NOp),execute(NOp).  
  
exec(1) :- listing(father).  
exec(2) :- read_fathers.  
exec(3) :- delete_fathers.
```

FATHERS MANAGEMENT SYSTEM :)

1. List fathers
2. Insert father
3. Delete fathers
4. Exit

Here we use some pre-defined rules of SWI-Prolog:

*read* – reads a string ended by “.”

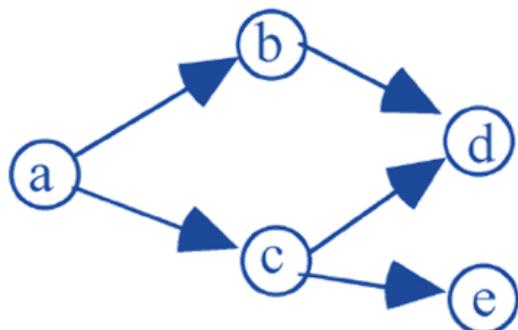
*write* – writes a string

*nl* – new line

# Directed Graph

## Back to modeling....

Examples of application: road maps (one direction), electric circuits, energy distribution, ...



One possible representation:

Facts:

- arc(a,b).
- arc(a,c).
- arc(b,d).
- arc(c,d).
- arc(c,e).

- R1
- R2

Rules:

connected(X,Y) :- arc(X,Y).

connected(X,Y) :- arc(X,Z), connected(Z,Y).

*Recursive definition*

?- connected(a,b).

Rule 1: connected(a,b) :- arc(a,b) → succeeds

true

?- connected(a,d).

Rule 1: connected(a,d) :- arc(a,d) → fails

Rule 2: connected(a,d) :- arc(a,Z), connected(Z,d)

Z=b

Rule 1: connected(b,d) :- arc(b,d)  
→ succeeds

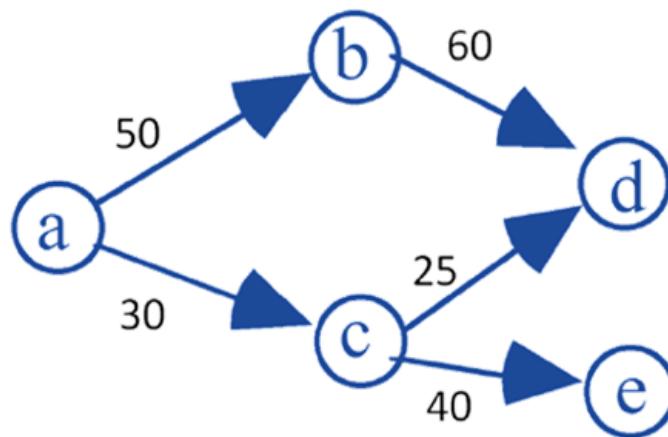
true

from @L.M. Camarinha-Matos 2023

# Directed Graph

## Back to modeling....

Arcs with distance



dist(a,b,50).  
dist(a,c,30).  
dist(b,d,60).  
dist(c,d,25).  
dist(c,e,40).

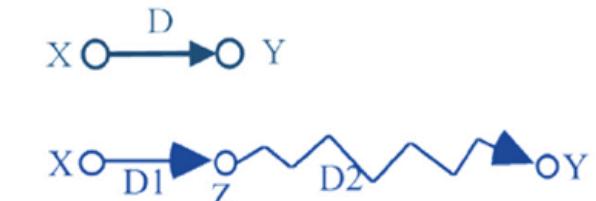
R1  
R2

distance(X,Y,D) :- dist(X,Y,D).  
distance(X,Y,D) :- dist(X,Z,D1),  
distance(Z,Y,D2),  
D is D1 + D2.

?- distance(a,d,D).

Rule 1: distance(a,d,D) :- dist(a,d,D)  $\rightarrow$  fails  
Rule 2: distance(a,d,D) :- dist(a, Z, D1), distance(Z,d, D2), D is D1+D2

D = 110 ;  
D = 55      Try another solution



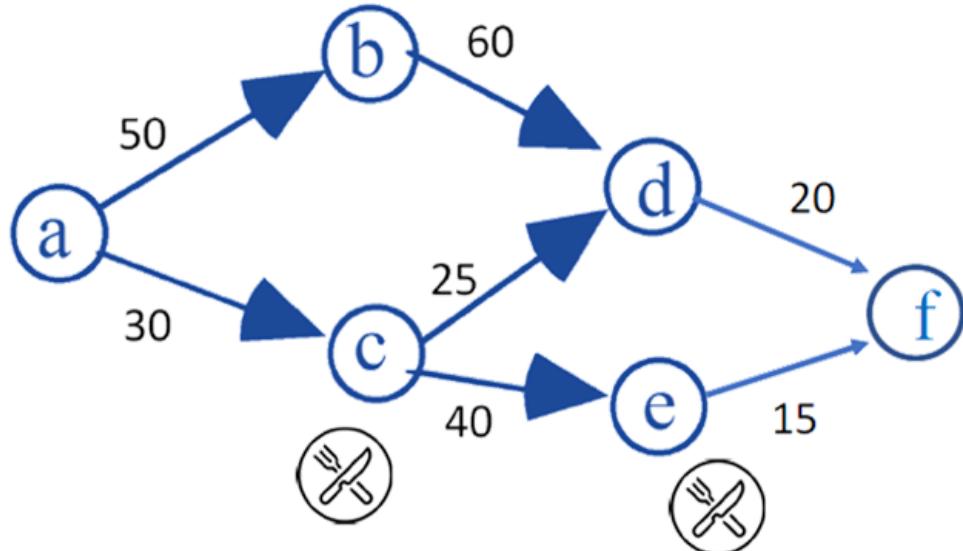
from @L.M. Camarinha-Matos 2023

# Directed Graph

## Back to modeling....

Variant:

Imagine that the graph represents a road map (nodes represent cities, arcs represent roads). In order to go from city X to city Y, either there is a direct road, or in case we must pass by intermediate cities we only want to pass by cities with a restaurant. Some cities have restaurants, others not.



Represent the case illustrated in the figure.

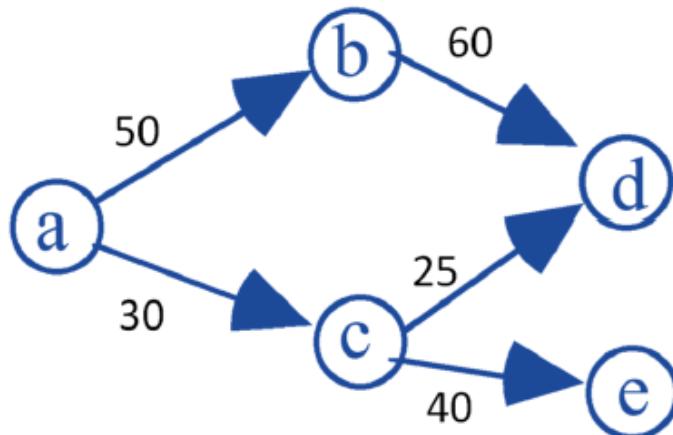
Modify the rule distance in order to consider the constraint indicated above (i.e., only passing by intermediate nodes with a restaurant).

How many valid paths between a and f?

from @L.M. Camarinha-Matos 2023

# Directed Graph

Back to modeling....



Facts:

- |           |               |
|-----------|---------------|
| arc(a,b). | dist(a,b,50). |
| arc(a,c). | dist(a,c,30). |
| arc(b,d). | dist(b,d,60). |
| arc(c,d). | dist(c,d,25). |
| arc(c,e). | dist(c,e,40). |

Rules:

connected(X,Y) :- arc(X,Y).

connected(X,Y) :- arc(X,Z), connected(Z,Y).

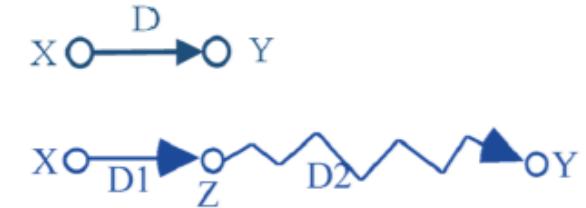
*Recursive definition*

distance(X,Y,D) :- dist(X,Y,D).

distance(X,Y,D) :- dist(X,Z,D1),

distance(Z,Y,D2),

D is D1 + D2.



**But what if we want to know the names of all nodes in the path between two nodes X and Y?**

The answer can be of a variable length, depending on X, Y and the followed path => thus, **we need another data structure** to represent such answers with variable length

from @L.M. Camarinha-Matos 2023



# Lists in PROLOG

**List:** a data structure that can contain a variable number of elements

Some notation:

**[]**      empty list

**[a]**      list with 1 element

**[a, b]**      list with 2 elements

**[a, [b, c], d]**      list with 3 elements

**[a, date(11,3,94), b]**      list with 3 elements

**[H | R]**      list with at least 1 element

H – first element (head)

R - list with remaining elements (excluding head)

**[X1, X2 | R]**      list with at least 2 elements

from @L.M. Camarinha-Matos 2023

# Lists: examples

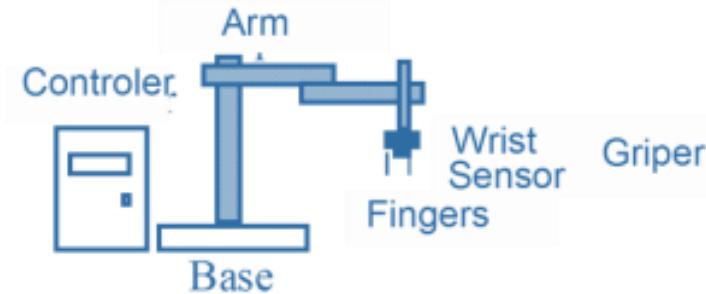
Example:

```
components(robot, [base, arm, gripper, controller]).  
components(gripper, [wrist, fingers, sensor]).
```

```
?-components(robot, L).  
L = [base, arm, gripper, controller]
```

```
?-components(gripper, [C|R]).  
C = wrist  
R = [finger, sensor]
```

```
?-components(X, [base | _]).  
X = robot
```



from @L.M. Camarinha-Matos 2023

# Lists: examples

Example: Is the element E a member of a given list?

```
is_member(E, [E|_]).
```

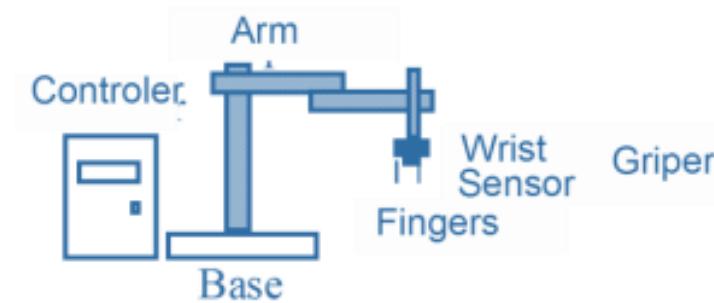
```
is_member(E, [_|R]) :- is_member(E,R).
```

```
has(O,C) :- components(O,L), is_member(C,L).
```

```
?-has(gripper, fingers).
```

```
true
```

```
components(robot, [base, arm, gripper, controller]).  
components(gripper, [wrist, fingers, sensor]).
```



```
?-components(robot,L), is_member(E,L).
```

```
L = [base, arm, gripper, controller],
```

```
E = base ;
```

```
L = [base, arm, gripper, controller],
```

```
E = arm ;
```

```
L = [base, arm, gripper, controller],
```

```
E = gripper ;
```

```
L = [base, arm, gripper, controller],
```

```
E = controller ;
```

```
false.
```

from @L.M. Camarinha-Matos 2023

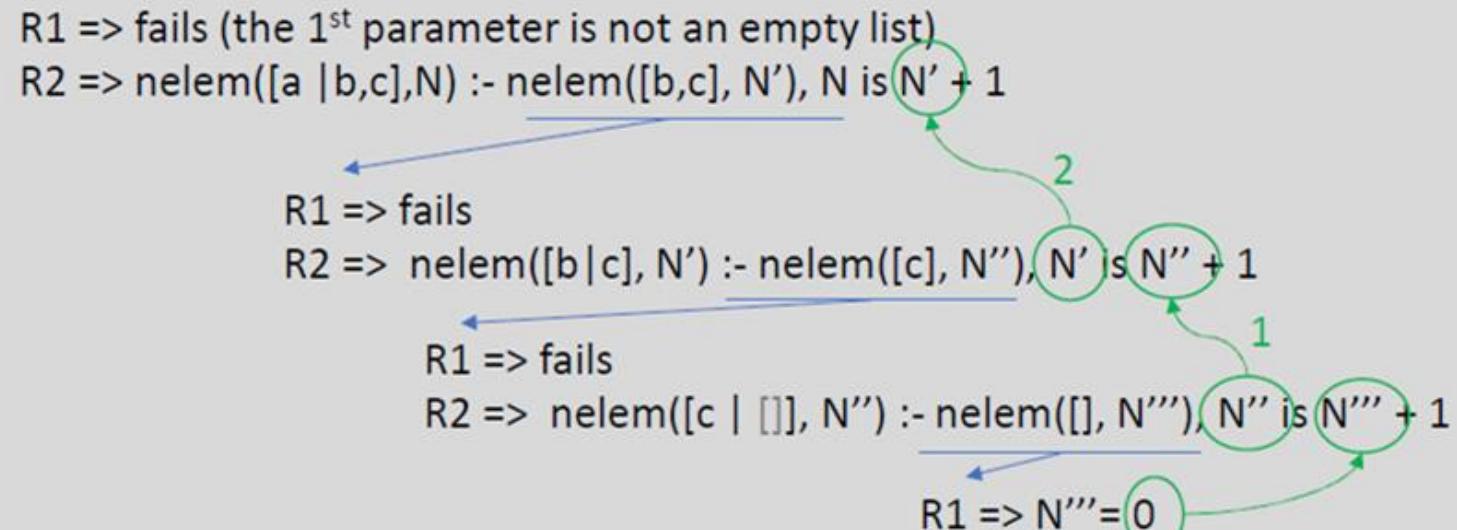
# Lists: examples

Example: Length or number of elements of a list

R1 nelem([], 0).  
R2 nelem([\_|R],N) :- nelem(R, N1), N is N1 + 1.

?- nelem([a, b, c], N).

Invisible to the user



N = 3

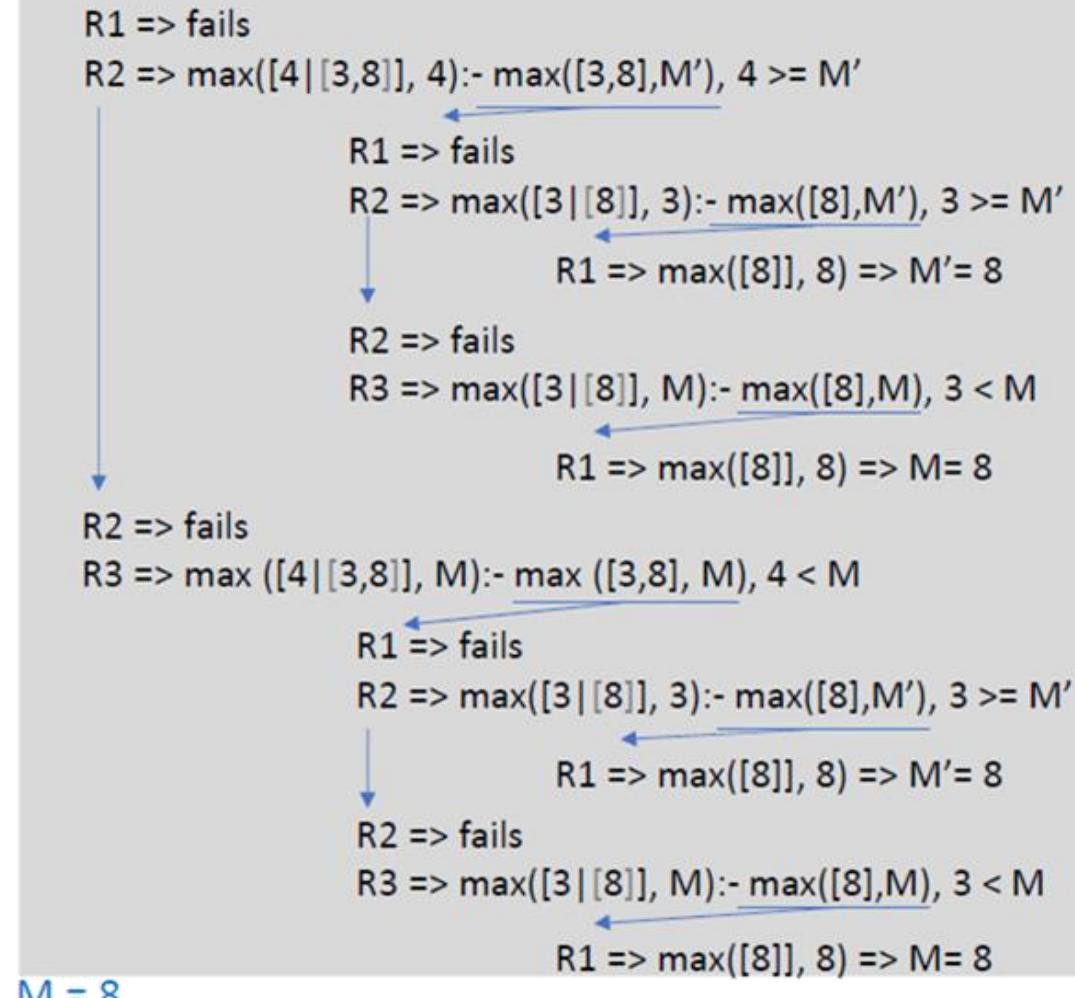
from @L.M. Camarinha-Matos 2023

# Lists: examples

Example: Rule to find the maximum of a list

- R1 max([X], X).
- R2 max([X | R], X) :- max(R, M), X >= M.
- R3 max([X | R], M) :- max(R, M), X < M.

?- max([4, 3, 8], M).



from @L.M. Camarinha-Matos 2023

# Lists: examples

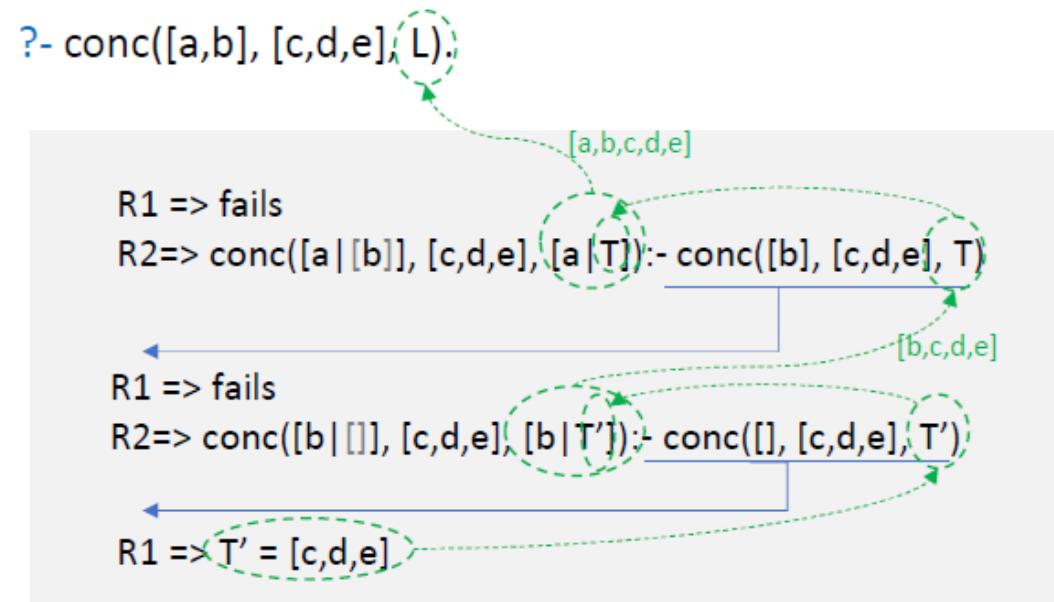
Example: concatenate two lists

$[a, b] + [c, d, e] \Rightarrow [a, b, c, d, e]$

`conc([], L, L).`

`conc([C|R], L, [C|T]) :- conc(R, L, T).`

?- `conc([a,b], [c,d,e], L).`



`L = [a,b,c,d,e]`

Example: invert a list

`invert([], [])`

`invert([C|R], I) :- invert(R, Ri), conc(Ri, [C], I).`

?- `invert([a,b,c], I).`  
`I = [c,b,a]`

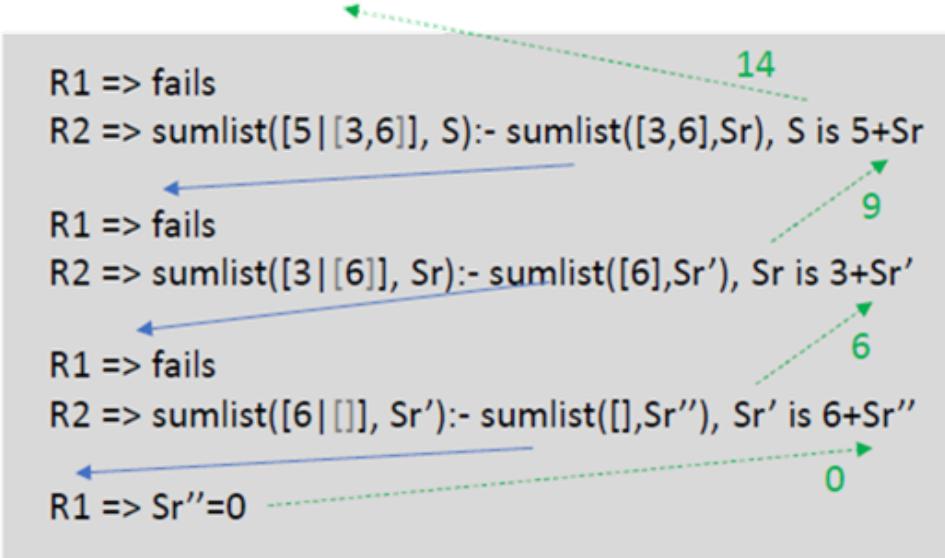
from @L.M. Camarinha-Matos 2023

# Lists: examples

Given a list of numbers, **add** those numbers.

```
sumlist([],0).  
sumlist([X|R], S):- sumlist(R,Sr), S is X + Sr.
```

?-sumlist([5,3,6], S).



S = 14

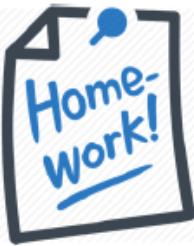
Given a list of numbers, calculate the **average** of those numbers.

```
avglist([],0).  
avglist(L,A):- sumcount(L,N,S), A is S/N.  
sumcount([],0,0).  
sumcount([X|R],N,S):- sumcount(R,Nr,Sr),  
N is Nr+1,S is Sr+X.
```

?-avglist([6,8,10],A).  
A= 8

from @L.M. Camarinha-Matos 2023

# Lists: examples



## Proposed exercises:

**E1:** Consider a list in which elements might appear repeated. Write a set of rules to calculate the number of times one element E appears repeated in a given list.

**E2:** Write a set of rules to find the minimum of a list.

**E3:** Find the last element of a list.

Example:

?- my\_last(X,[a,b,c,d]).

X = d

**E4:** Duplicate the elements of a list.

Example:

?- dupli([a,b,c,c,d],X).

X = [a,a,b,b,c,c,c,c,d,d]

**E5:** Extract a slice from a list.

Given two indices, I and K, the slice is the list containing the elements between the I'th and K'th element of the original list (both limits included). Start counting the elements with 1.

Example:

?- slice([a,b,c,d,e,f,g,h,i,k],3,7,L).

X = [c,d,e,f,g]

from @L.M. Camarinha-Matos 2023

# Lists: examples



**E6:** Suppose we are given a knowledge base with the following facts:

```
tran(um,one).  
tran(dois,two).  
tran(tres,three).  
tran(quatro,four).  
tran(cinco,five).  
tran(seis,six).  
tran(sete,seven).  
tran(oito,eight).  
tran(nove,nine).
```

Write a predicate `listtran(G,E)` which translates a list of Portuguese number words to the corresponding list of English number words. For example:

```
listtran([um,nove,dois],X).
```

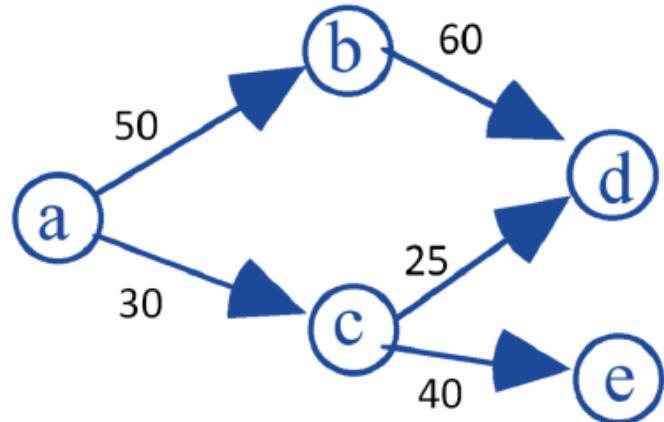
should give:

```
X = [one,nine,two].
```

from @L.M. Camarinha-Matos 2023

# Lists and Graphs

Graph revisited:



```
dist(a,b,50).  
dist(a,c,30).  
dist(b,d,60).  
dist(c,d,25).  
dist(c,e,40).
```

Obtain, in a list, the arcs of the **path** between two nodes X, Y

Solution 1:

R1      path(X,Y, [dist(X,Y,D)]) :- dist(X,Y,D).  
R2      path(X,Y, [dist(X,Z,D) | R]) :- dist(X,Z,D), path(Z,Y,R).

?- path(a, d, P).

R1=> path(a, d, [dist(a, d, D)]) :- dist(a, d, D) => fails

R2=> path(a, d, [dist(a,Z,D) | R]) :- dist(a,Z,D), path(Z,d,R)

Z=b, D=50

R1=> path(b, d, [dist(b, d, D')]) :- dist(b, d, D')

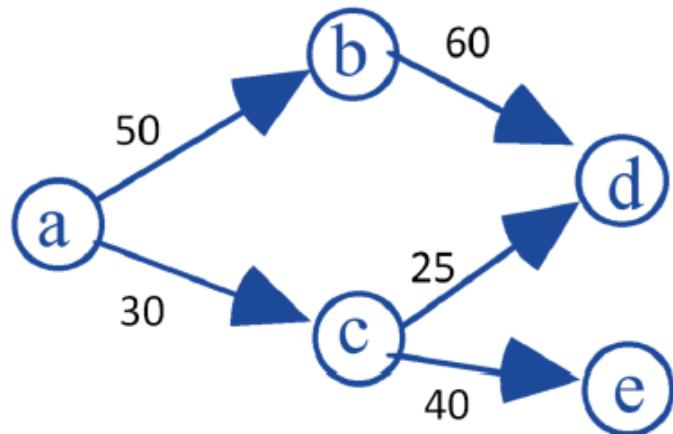
D'=60

P = [dist(a,b,50), dist(b,d,60)] ; Try another solution  
P = [dist(a,c,30), dist(c,d,25)]

from @L.M. Camarinha-Matos 2023

# Lists and Graphs

Graph revisited:



```
dist(a,b,50).  
dist(a,c,30).  
dist(b,d,60).  
dist(c,d,25).  
dist(c,e,40).
```

Obtain, in a list, the arcs of the path between two nodes X, Y

Solution 2:

```
path(X,Y, [via(X,Y)]) :- dist(X,Y,_).  
path(X,Y, [via(X,Z) | R]) :- dist(X,Z,_), path(Z,Y,R).
```

?- path(a, d, P).

P = [via(a,b), via(b,d)] ;  
P = [via(a,c), via(c,d)]

Solution 3:

```
path(X,Y, [(X,Y)]) :- dist(X,Y,_).  
path(X,Y, [(X,Z) | R]) :- dist(X,Z,_), path(Z,Y,R).
```

?- path(a, d, P).

P = [(a,b), (b,d)] ;  
P = [(a, c), (c, d)] ;  
false.

*There are no more solutions*

from @L.M. Camarinha-Matos 2023

# Lists and Graphs

Write another version of path with the following behavior:

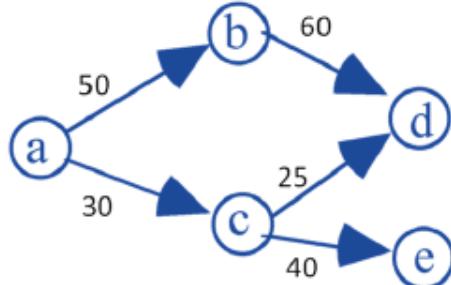
?-path3(a,e,P).

P = p([via(a, c, 30), via(c, e, 40)], 70)

*Total distance*

path3(X,Y, p([via(X,Y,D)], D)) :- dist(X,Y,D).

path3(X,Y, p([via(X,Z,D1) | R], DT)) :- dist(X,Z,D1), path3(Z,Y, p(R,D2)), DT is D1+D2.



?- path3(a,d,P).

P = p([via(a, b, 50), via(b, d, 60)], 110) ;

P = p([via(a, c, 30), via(c, d, 25)], 55) ;

false.

?- path3(a,e,P).

P = p([via(a, c, 30), via(c, e, 40)], 70) ;

false.

?- path3(c,e,p([via(c,e,40)],40)).  
true

path4(X,Y, [via(X,Y,D)], D) :- dist(X,Y,D).

path4(X,Y, [via(X,Z,D1) | R], DT) :- dist(X,Z,D1),  
path4(Z,Y, R, DT), DT is D1+D2.

?-path4(a,d,P, D).

P= [via(a,b,50), via(b,d,60)].

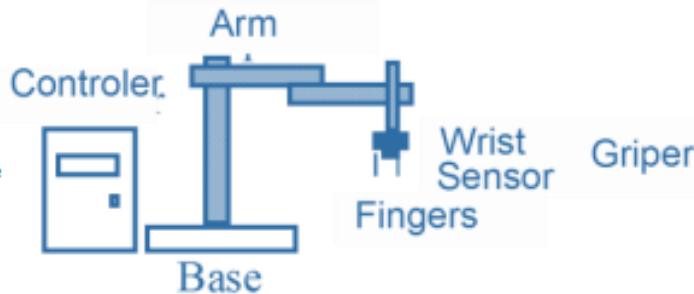
D=110

# Lists -> Multiple Solutions: findall

Remember the Robot example:

```
% modeling robot example
part(robot,base).
part(robot,arm).
part(robot,griper).
part(robot,controller).
part(griper,wrist).
part(griper,fingers).
part(griper,sensor).
part(sensor,glass).

(...)
```



Variable for which we want to find the value

findall(V, query, LA)

Query, involving variable V

A pre-defined rule in Prolog

List containing all possible values for V

?-findall(P,part(\_,\_),L).  
L = [base,arm,griper,controller,wrist,fingers,sensor,glass].

?-findall(part(C,P),part(C,P),L).  
L = [part(robot,base), part(robot,arm), part(robot,griper), part(robot,controller), part(griper,wrist), part(griper,fingers), part(griper,sensor), part(sensor,glass)].

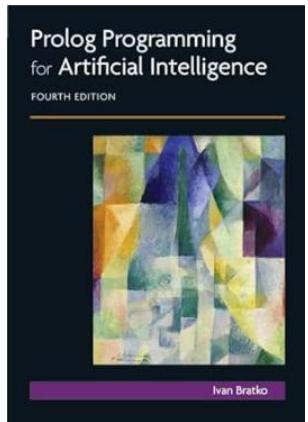
?-findall([C,P],part(C,P),L).  
L = [[robot,base], [robot,arm], [robot,griper], [robot,controller], [griper,wrist], [griper,fingers], [griper,sensor], [sensor,glass]].

findall(p(C,P),part(C,P),L).  
L = [p(robot,base), p(robot,arm), p(robot,griper), p(robot,controller), p(griper,wrist), p(griper,fingers), p(griper,sensor), p(sensor,glass)].

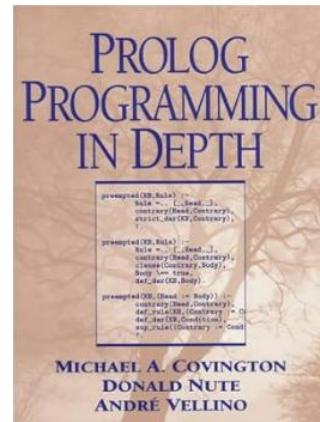
Obtaining all solutions -> ;

?- part(\_,\_).  
P = base ;  
P = arm ;  
P = griper ;  
P = controller ;  
P = wrist ;  
P = fingers ;  
P = sensor ;  
P = glass.

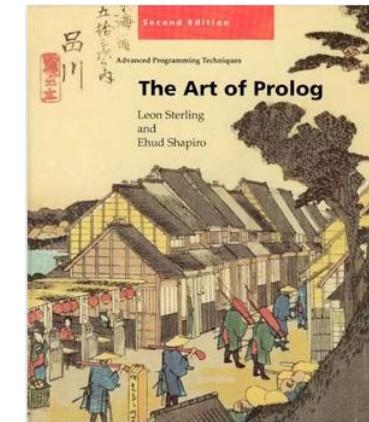
# Further reading



<https://www.amazon.com/Programming-Artificial-Intelligence-International-Computer/dp/0321417461>



[https://www.amazon.com/Prolog-Programming-Depth-Michael-Covington/dp/013138645X/ref=pd\\_sim\\_14\\_4?ie=UTF8&dpID=514M0RXA1WL&dpSrc=sims&preST= AC\\_UL160\\_SR122%2C160 &refRID=1TM7A3CEFC2BD4JA77WR](https://www.amazon.com/Prolog-Programming-Depth-Michael-Covington/dp/013138645X/ref=pd_sim_14_4?ie=UTF8&dpID=514M0RXA1WL&dpSrc=sims&preST= AC_UL160_SR122%2C160 &refRID=1TM7A3CEFC2BD4JA77WR)



<https://mitpress.mit.edu/9780262691635/the-art-of-prolog/>

(...)



[https://www.swi-prolog.org/pldoc/doc\\_for?object=manual](https://www.swi-prolog.org/pldoc/doc_for?object=manual)



<https://en.wikibooks.org/wiki/Prolog>



<https://drsmithbiology.weebly.com/further-reading.html>

# Good Work!

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