Automatic container model crane

Gruppe 633

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Improvements

- ▶ Modeling for additional outputs allows correction of the model using an estimator

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▶ A multiple output model that adequatley captures the dynamics of the system could be used in a Kalman filter to create a state estimate

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- ▶ A multiple output model that adequatley captures the dynamics of the system could be used in a Kalman filter to create a state estimate
- ▶ The state estimates can be used in a state feedback loop to change system dynamics
- ▶ This means that reference following capabilities can be added to the system, dispite the nonlinear characteristics of the dynamics

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- ▶ While the transient behaviour of the reference value is replicated, offsets and parasitic gains need to be compensated
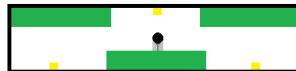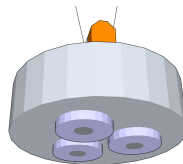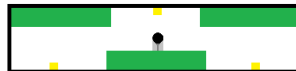
Improvements

- ▶ Trolley

- Trolley
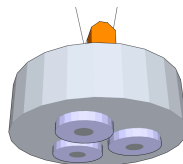
- Elektromagnet
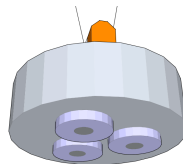
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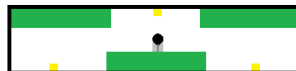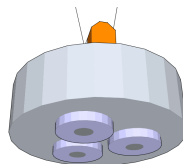
► Vinkel sensor
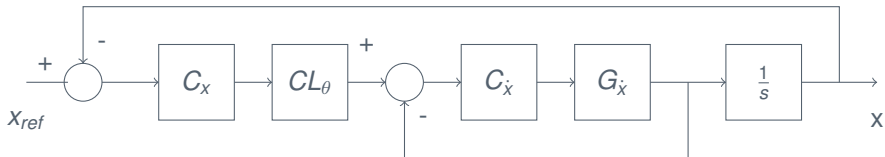
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- ► Kaskade kobling

- Kontrol lab