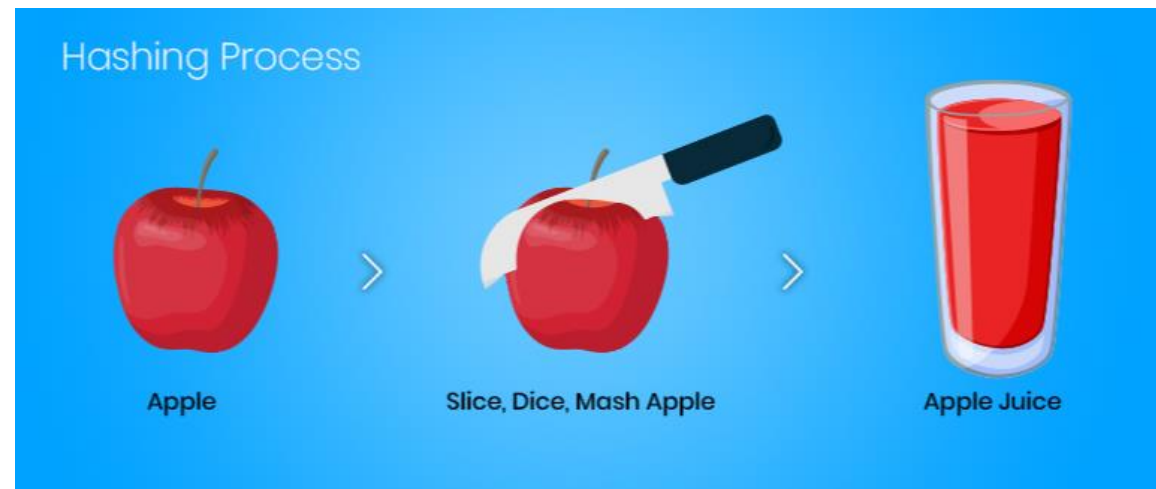
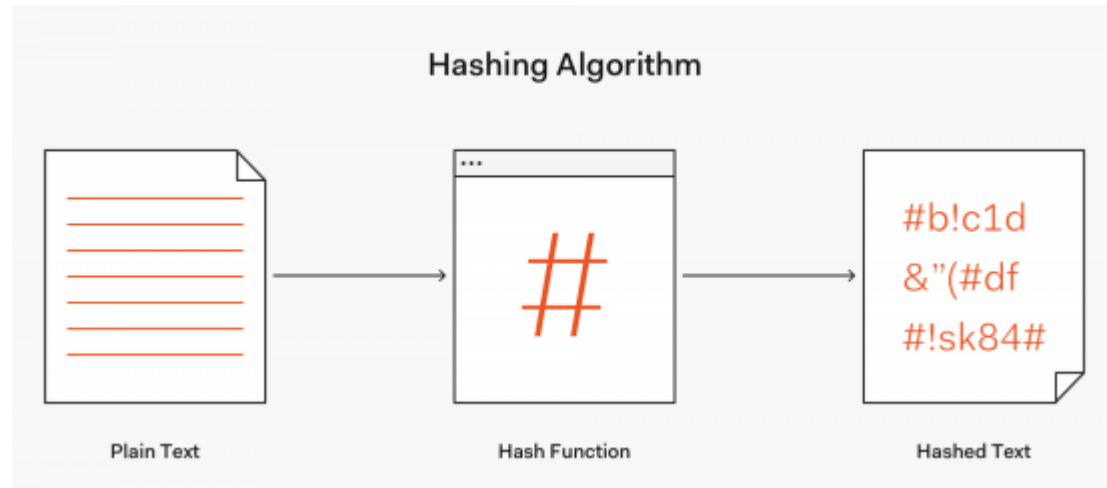


# MAPS AND HASH TABLES

School of Artificial Intelligence

# PREVIOUSLY ON DS&A

- Maps/dictionaries
- Hash Tables
- Hash Functions
  - Hashing
  - Compressing



# MAPS AND DICTIONARIES

- Key->Value pairing
- Keys are (assumed) to be unique, values are not necessarily unique
- Retrieve value with key using  $m[k]$
- Map implementation
  - Unsorted: with underlying array
- Hash function
  - Hashing: produce an integer based on the key
  - Compressing: compress the hash code to fit into  $[0, N-1]$ ,  $N$  = capacity of underlying array

# HASH CODES (哈希码)

- Hashing: treating the bit representation as an integer
- For any data type X, its representation in memory can be considered an integer
  - For integer 314,  $h(314) = 314$
  - For floating-point number 3.14,  $h(3.14)$  will use its memory representation as an integer
- For type that uses longer than a desired hash code
  - E.g. if we want a 32-bit hash code, if a floating-point number uses a 64-bit representation
  - Approaches: take the first/last 32 bit; add the first/last 32 bit, take exclusive-or of the first/last 32 bits

# POLYNOMIAL HASH CODES

## (多项式哈希码)

- Summation and exclusive-or: NOT good choices for character strings or other variable-length objects that can be viewed as tuples of the form  $(x_0, x_1, \dots, x_{n-1})$ , where the order of  $x$  is significant.
  - E.g. 16-bit hash code for a character string  $s$  that sums the Unicode values of the characters in  $s$ .
  - “temp01” and “temp10” produces the same hash code.
  - “stop”, “tops”, “pots”, and “spot” produces the same hash code
- A more complicated hashing function is needed, such as

$$x_0a^{n-1} + x_1a^{n-2} + \dots + x_{n-2}a + x_{n-1}.$$

- This hash code is called a polynomial hash code

# CYCLIC SHIFT HASH CODES

- Replaces multiplication by a with a cyclic shift of a partial sum by a certain number of bits
- 5-bit cyclic shift:
- 0011110110010110101010001010100 to 1011001011010101000101010000111
- Table: comparison of collision behavior for the cyclic-shift hash code to a list of 230,000 English words

```
def hash_code(s):  
    mask = (1 << 32) - 1  
    h = 0  
    for character in s:  
        h = (h << 5 & mask) | (h >> 27)  
        h += ord(character)  
    return h
```

Shift	Collisions	
	Total	Max
0	234735	623
1	165076	43
2	38471	13
3	7174	5
4	1379	3
5	190	3
6	502	2
7	560	2
8	5546	4
9	393	3
10	5194	5
11	11559	5
12	822	2
13	900	4
14	2001	4
15	19251	8
16	211781	37



# COMPRESSION FUNCTIONS

- The hash code for a key  $k$  may not be suitable for use in a bucket array
- It be negative or may exceed the capacity of the bucket array
- Therefore an additional computation is needed to map the integer into the range  $[0, N-1]$  – the **compression function**
- Division method
  - **$i \bmod N$** ,  $N$  = size of the bucket array
  - Choice of  $N$ : often prefer prime numbers
  - $\{200, 205, 210, 215, 220, \dots, 600\}$  into a bucket array of size 100
  - $\{200, 205, 210, 215, 220, \dots, 600\}$  into a bucket array of size 101

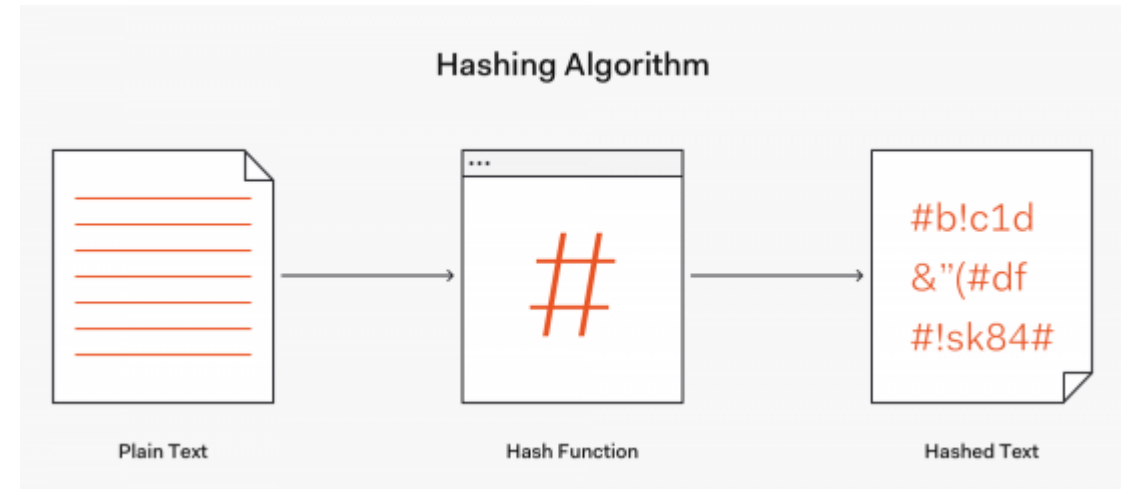
# COMPRESSION FUNCTIONS

- MAD (Multiply Add and Divide) method
  - **$((ai+b) \bmod p) \bmod N$** ,  $N$  = size of the bucket array,  $p$  is a prime number larger than  $N$ ,  $a$  and  $b$  are integers chosen at random from  $[0, p-1]$ , with  $a > 0$
  - Finding  $p$ : in polynomial time
  - Worst case keys  $k1 \neq k2$ ,  $\Pr(h(k1) == h(k2)) = 1/N$
- Multiplication method
  - $h(k) = ((a.k) \bmod 2^w) \gg (w-r)$ ,  $w$  =  $w$  bits computer, bucket array size  $N = 2^r$
  - $A$  better be odd, and should not be close to powers of 2



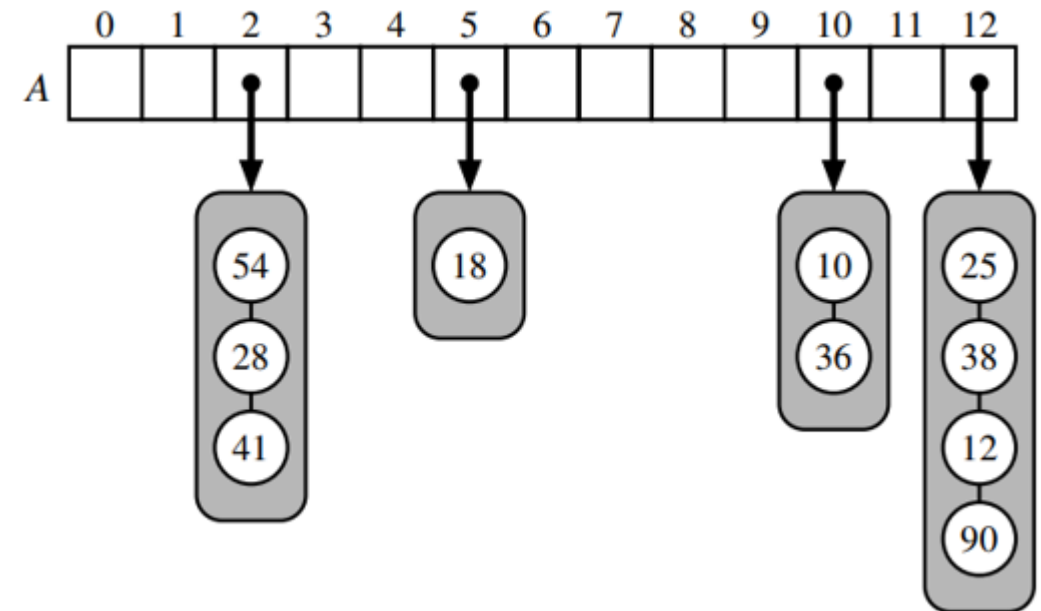
# THIS LECTURE

- Collision handling
  - Open addressing
- Efficiency of Hash Tables
- Python Hash Table Implementation
- Separate chaining
- Sorted maps
- Application of sorted maps



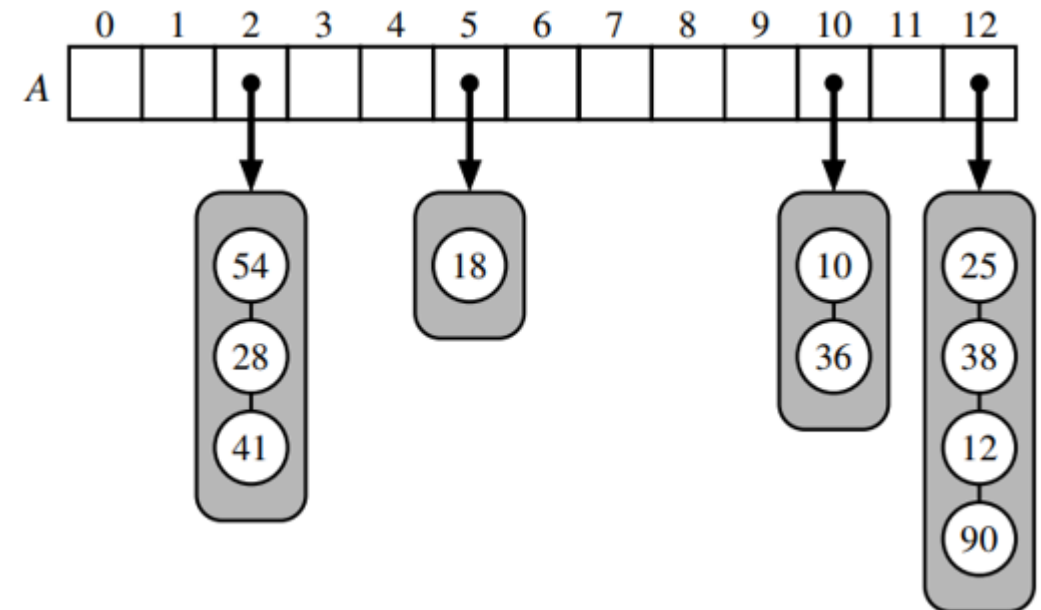
# COLLISION HANDLING

- Hash table
  - A bucket array A
  - A hash function h
  - Map to store (k, v) items in the bucket  $A[h(k)]$
- Problem: two distinct keys,  $k_1$  and  $k_2$ , such that  $h(k_1) = h(k_2)$  (hash collision)
- Solution: secondary container at each index (bucket)
- This is often referred to as **separate chaining** (分离链表)



# COLLISION HANDLING

- Separate chaining
- Operations on an individual index (bucket) take time proportional to the size of the bucket
- “Good” hash function:
  - expected size of a bucket:  $n/N$
  - $n$  = number of items in the map
  - $N$  = capacity of the bucket array
  - Core map operations run in  $O(\text{ceiling}(n/N))$
- Load factor (负载因子) :  $\lambda = n/N$
- When  $\lambda$  is  $O(1)$ , operations on the hash table run in  $O(1)$

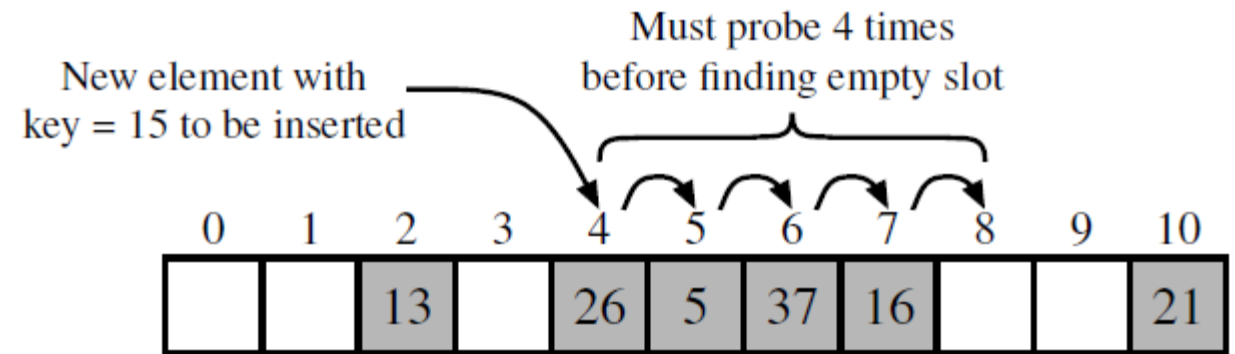


# COLLISION HANDLING

- Separate chaining （分离链表）：
  - Advantage: simple implementation
  - Disadvantage: relies on auxiliary data structure - list to hold items with colliding keys
- Alternative approach: open addressing （开放寻址）
  - Always store each item directly in a table slot
  - No auxiliary structures are used
  - Load factor is ways at most 1 and items are stored directly in the cells of the bucket array

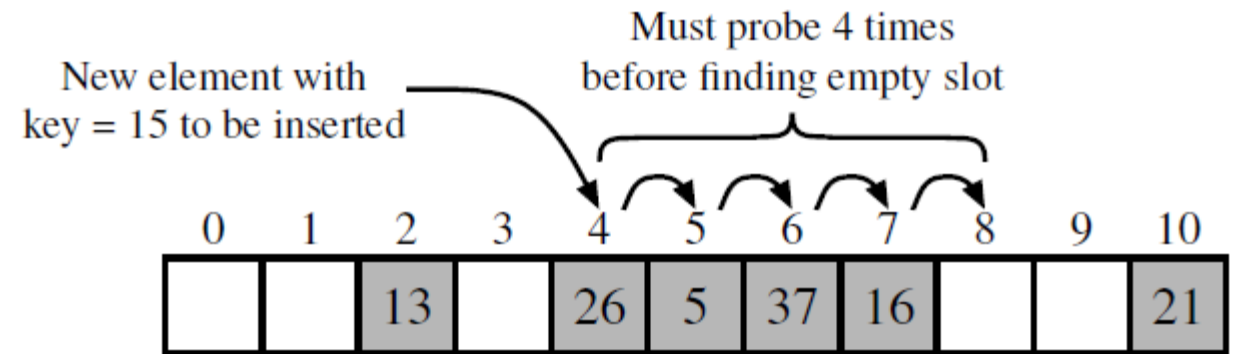
# LINEAR PROBING (线性探索)

- Linear probing
- Insert an item  $(k, v)$  into a bucket  $A[j]$
- If  $a[j]$  is occupied,  $j = h(k)$ , then try  $A[(j+1) \bmod N]$
- If  $A[(j+1) \bmod N]$  is occupied, try  $A[(j+2) \bmod N]$ , so on
- Need to change the implementation of functions such as `__getitem__`, `__setitem__`, `__delitem__`



# LINEAR PROBING (线性探索)

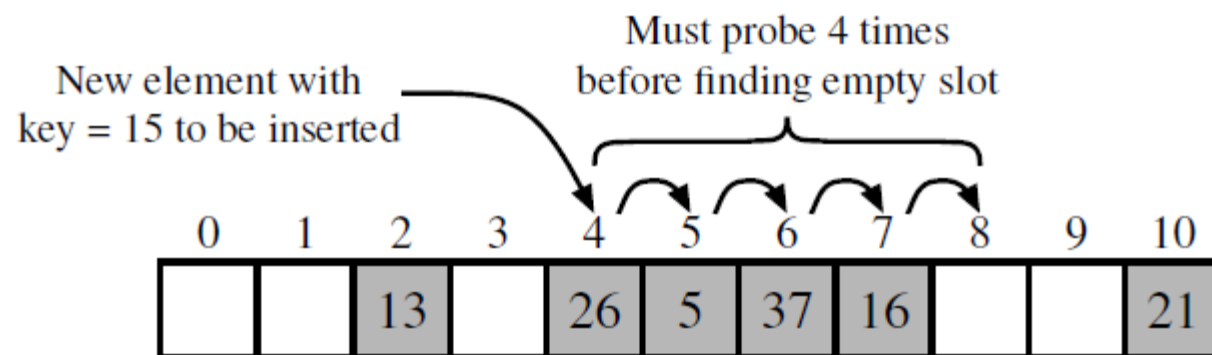
- Deletion – slightly more complicated
- After insertion for item  $k=15$  deleting 37 ( $A[6]$ ), a search for  $k=15$  fails
- Probing 4, 5, 6 – empty cell
- Solution: place a 'available' marker at  $A[6]$ , so search for  $k=15$  will pass  $A[6]$  until desired item (or empty)
- `__setitem__` should remember an available cell, so that a new item ( $k, v$ ) can be placed there





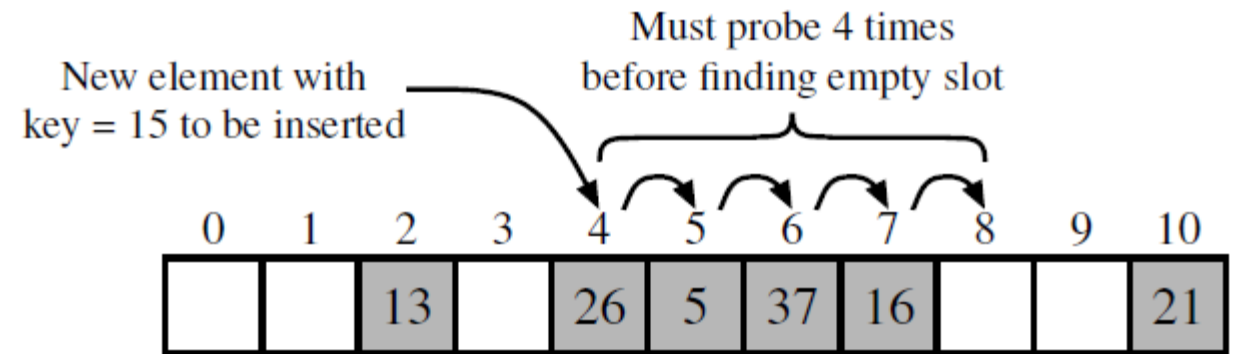
# LINEAR PROBING (线性探索)

- Disadvantage?
- Probing takes time proportional to N
- Complicated implementation
- Clustering (聚集): items tend to stick together due to the probing algorithm



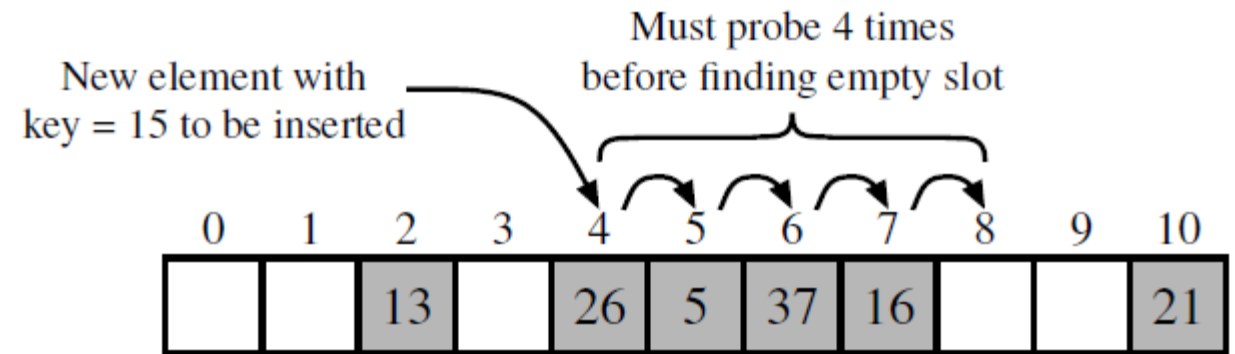
# QUADRATIC PROBING (二次探索)

- Iteratively tries  $A[h(k) + f(i) \bmod N]$  for  $i = 0, 1, 2, \dots$ ,  $f(i) = i^2$
- Spreads the probing distance over the length  $N$
- Deletion – same strategy as linear probing
- Problems again: secondary clustering (二次聚集)
- When the bucket array is half full, or  $N$  is not a prime, quadratic probing does not guarantee to find an empty slot



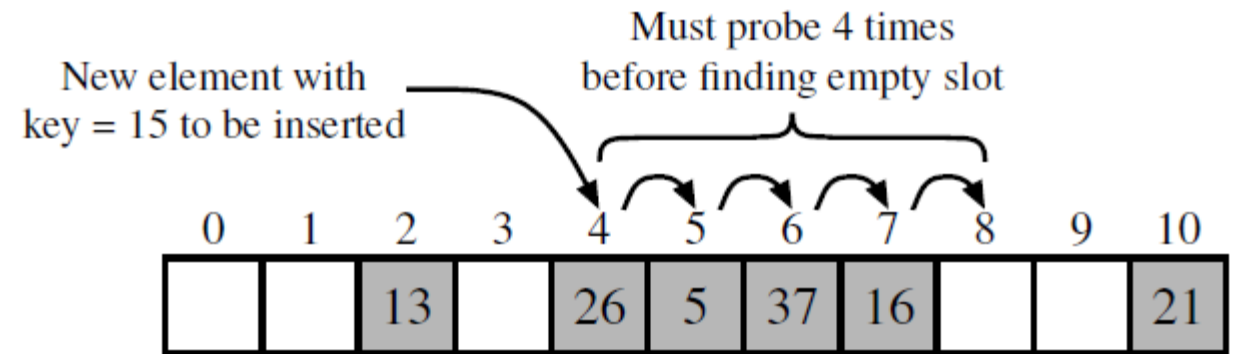
# DOUBLE HASHING (二次哈希)

- Secondary hash function  $h'$
- If  $h$  maps some key  $k$  to a bucket  $A[h(k)]$  that is occupied, try  $A[h(k) + f(i) \bmod N]$ , for  $i = 1, 2, 3, \dots$
- $f(i) = i * h'(k)$
- $h'(k)$  cannot be 0
- $h'(k) = q - (k \bmod q)$ ,  $q, N$  are prime numbers and  $q < N$



# ADDITIONAL OPEN ADDRESSING

- $A[h(k) + f(i) \bmod N]$  where  $f(i)$  produces a pseudo-random number
- Repeatable random number



# LOAD FACTORS AND REHASHING

- Load factor (负载因子) :  $\lambda = n/N$  should be kept below 1
- Separate chaining:  $\lambda \rightarrow 1$  the probability of a collision increases greatly
  - $\lambda < 0.9$  for separate chaining
- Open addressing
  - When  $\lambda$  grows beyond 0.5 and approaches 1, clusters start to show
  - Linear probing:  $\lambda < 0.5$
  - Other open addressing:  $\lambda < 2/3$
- What happens if an insertion causes the load factor to go beyond 0.5 for linear probing and  $2/3$  for other open addressing means?
- **Rehashing**: resize the table + reinsert all objects into new table
  - Resize: how?
  - new compression function  $\rightarrow$  why?

# EFFICIENCY OF HASH TABLES

- “good” hash function: entries to be uniformly distributed across  $N$  cells
- To store  $n$  entries, the expected number of keys in a bucket would be  $\text{ceiling}(n/N) - O(1)$  if  $n$  is  $O(N)$
- Rehashing  $\rightarrow$  dynamically growing and shrinking the underlying array
  - `__setitem__` and `__getitem__`:  $O(1)$  amortised
- “poor” hash function: all items in the same bucket
  - $O(n)$  performance for separate chaining and open addressing

Operation	List	Hash Table	
		expected	worst case
<code>__getitem__</code>	$O(n)$	$O(1)$	$O(n)$
<code>__setitem__</code>	$O(n)$	$O(1)$	$O(n)$
<code>__delitem__</code>	$O(n)$	$O(1)$	$O(n)$
<code>__len__</code>	$O(1)$	$O(1)$	$O(1)$
<code>__iter__</code>	$O(n)$	$O(n)$	$O(n)$



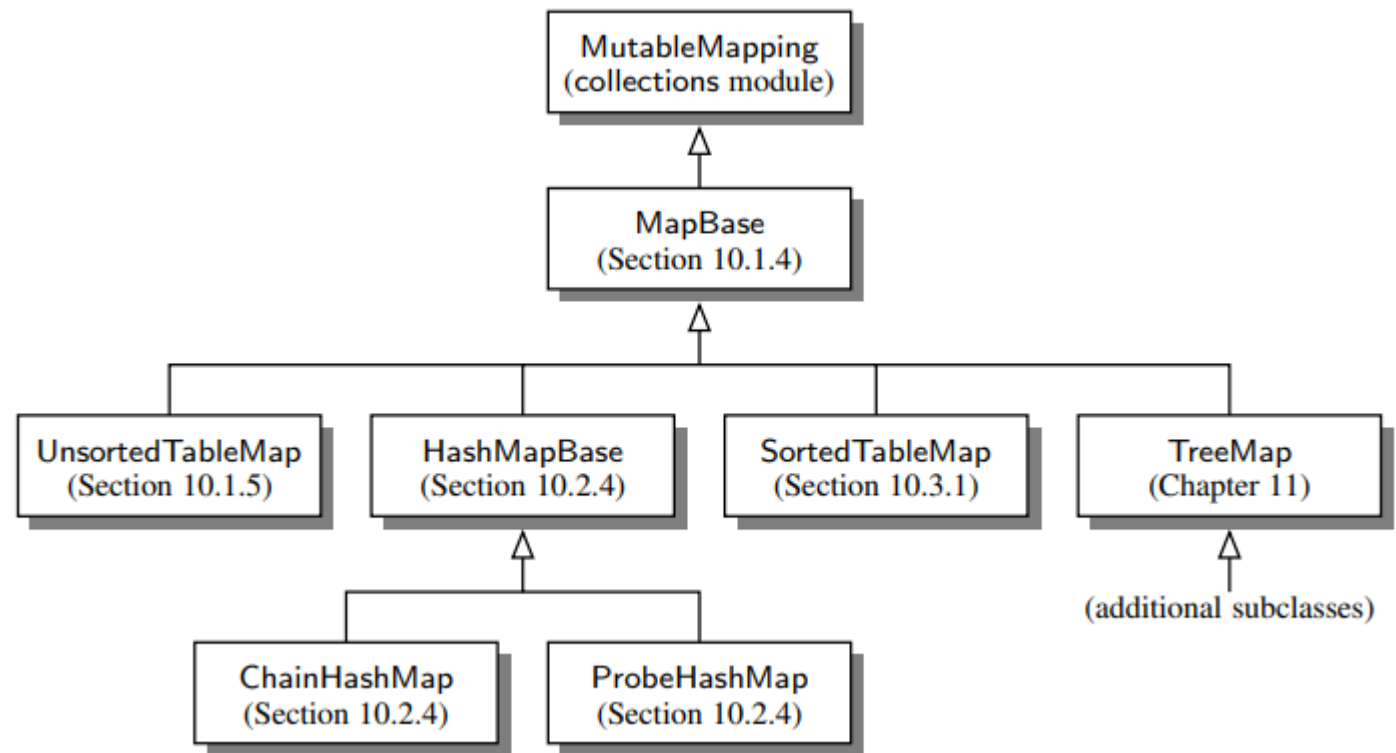
# EFFICIENCY OF HASH TABLES

- Python's dict class: implemented with hashing
- Python interpreter
  - Dictionaries to retrieve an object referenced by an identifier in a given namespace
  - `c = a + b`: `__getitem__` for a and b, and `__setitem__` for c

Operation	List	Hash Table	
		expected	worst case
<code>__getitem__</code>	$O(n)$	$O(1)$	$O(n)$
<code>__setitem__</code>	$O(n)$	$O(1)$	$O(n)$
<code>__delitem__</code>	$O(n)$	$O(1)$	$O(n)$
<code>__len__</code>	$O(1)$	$O(1)$	$O(1)$
<code>__iter__</code>	$O(n)$	$O(n)$	$O(n)$

# HASH TABLE IMPLEMENTATION IN PYTHON

- HashMap base to extend MapBase
- Bucket array represented by a python list
- `_n`: number of distinct items stored in the hash table
- Table doubling when load factor grows larger than 0.5
- `_hash_function`: Python's built-in hash function and MAD for compression



# HASH TABLE IMPLEMENTATION IN PYTHON

- `_bucket_getitem(j, k)`: search bucket `j` for an item having key `k`, then returns the associated value, otherwise error
- `_bucket_setitem(j, k, v)`: modify bucket `j` so that key `k` is associated with value `v`. if a new item is inserted, `_n` is increased
- `_bucket_delitem(j, k)`: removes the item from bucket `j` with key `k`. Error if no such item exists
- `__iter__`: iterator through all keys of the map

# HASH TABLE IMPLEMENTATION IN PYTHON

- Constructor: init \_table, \_n, set \_prime, \_scale, \_shift
- Hash function:
  - MAD formular
  - **$((ai+b) \bmod p) \bmod N$**

```
1 class HashMapBase(MapBase):
2     """Abstract base class for map using hash-table with MAD compression."""
3
4     def __init__(self, cap=11, p=109345121):
5         """Create an empty hash-table map."""
6         self._table = cap * [ None ]
7         self._n = 0                # number of entries in the map
8         self._prime = p            # prime for MAD compression
9         self._scale = 1 + randrange(p-1) # scale from 1 to p-1 for MAD
10        self._shift = randrange(p)    # shift from 0 to p-1 for MAD
11
12    def _hash_function(self, k):
13        return (hash(k)*self._scale + self._shift) % self._prime % len(self._table)
```

# HASH TABLE IMPLEMENTATION IN PYTHON

- `Len()`: returns `_n`
- `__getitem__()`: get item with key `k`
- `__setitem__()`: set/add item, grown array when necessary

```
15 def __len__(self):
16     return self._n
17
18 def __getitem__(self, k):
19     j = self._hash_function(k)
20     return self._bucket_getitem(j, k)           # may raise KeyError
21
22 def __setitem__(self, k, v):
23     j = self._hash_function(k)
24     self._bucket_setitem(j, k, v)              # subroutine maintains self._n
25     if self._n > len(self._table) // 2:        # keep load factor <= 0.5
26         self._resize(2 * len(self._table) - 1) # number 2^x - 1 is often prime
```

# HASH TABLE IMPLEMENTATION IN PYTHON

- `_resize()`:
  - Get old array
  - Create new array
  - Reset `_n`
  - Insert items

```
28 def __delitem__(self, k):
29     j = self._hash_function(k)
30     self._bucket_delitem(j, k)           # may raise KeyError
31     self._n -= 1
32
33 def _resize(self, c):                    # resize bucket array to capacity c
34     old = list(self.items())             # use iteration to record existing items
35     self._table = c * [None]            # then reset table to desired capacity
36     self._n = 0                          # n recomputed during subsequent adds
37     for (k,v) in old:
38         self[k] = v                     # reinsert old key-value pair
```





# SEPARATE CHAINING

- `_bucket_getitem`:
  - Get bucket, raise error when necessary
  - Return value associated with `k`
- `_bucket_setitem`:
  - Create bucket when `j` does not exist
  - Insert `(k, v)`
  - Update `_n` if necessary

[illegible]

# SEPARATE CHAINING

- `_bucket_delitem`:
  - Get bucket, raise error when necessary
  - Delete (k, v) from bucket
- `__iter__`:
  - Collect items from each bucket

```
18 def _bucket_delitem(self, j, k):
19     bucket = self._table[j]
20     if bucket is None:
21         raise KeyError('Key Error: ' + repr(k))      # no match found
22     del bucket[k]                                     # may raise KeyError
23
24 def __iter__(self):
25     for bucket in self._table:
26         if bucket is not None:                        # a nonempty slot
27             for key in bucket:
28                 yield key
```

# LINEAR PROBING

- `_AVAIL` = object to flag that a bucket is available
- `_is_available`: if bucket points to `None` or `_AVAIL`, returns `true`. Otherwise `false`

```
1 class ProbeHashMap(HashMapBase):
2     """Hash map implemented with linear probing for collision resolution."""
3     _AVAIL = object( )      # sentinel marks locations of previous deletions
4
5     def _is_available(self, j):
6         """Return True if index j is available in table."""
7         return self._table[j] is None or self._table[j] is ProbeHashMap._AVAIL
```

# LINEAR PROBING

- Probing algorithm
- Check if j is available
- If `_table[j]` points to `None`, search has failed (this in theory should not happen)
- Otherwise, keep probing until a match is found

```
9  def _find_slot(self, j, k):
10     """ Search for key k in bucket at index j.
11
12     Return (success, index) tuple, described as follows:
13     If match was found, success is True and index denotes its location.
14     If no match found, success is False and index denotes first available slot.
15     """
16     firstAvail = None
17     while True:
18         if self._is_available(j):
19             if firstAvail is None:
20                 firstAvail = j                # mark this as first avail
21             if self._table[j] is None:
22                 return (False, firstAvail)    # search has failed
23         elif k == self._table[j]._key:
24             return (True, j)                 # found a match
25         j = (j + 1) % len(self._table)      # keep looking (cyclically)
```

# LINEAR PROBING

- `_bucket_getitem()`:
  - Find slot first
  - If no slots found, raise error
  - Return found item
- `_bucket_setitem()`:
  - Find item with linear probing
  - If not found, create an item and update `_n`
  - Else update value on found item

```
26 def _bucket_getitem(self, j, k):
27     found, s = self._find_slot(j, k)
28     if not found:
29         raise KeyError('Key Error: ' + repr(k))           # no match found
30     return self._table[s]._value
31
32 def _bucket_setitem(self, j, k, v):
33     found, s = self._find_slot(j, k)
34     if not found:
35         self._table[s] = self._Item(k,v)                   # insert new item
36         self._n += 1                                       # size has increased
37     else:
38         self._table[s]._value = v                          # overwrite existing
```

# LINEAR PROBING

- `_bucket_delitem()`:
  - Find item
  - If not found raise error
  - If found replace item with `_AVAIL`
- `__iter__()`:
  - Return items except for `None` and `AVAIL`

```
40 def _bucket_delitem(self, j, k):
41     found, s = self._find_slot(j, k)
42     if not found:
43         raise KeyError('Key Error: ' + repr(k))      # no match found
44     self._table[s] = ProbeHashMap._AVAIL              # mark as vacated
45
46 def __iter__(self):
47     for j in range(len(self._table)):                  # scan entire table
48         if not self._is_available(j):
49             yield self._table[j]._key
```



# SORTED MAPS

- Map we covered so far – unsorted
  - Exact search: value look-up using a given key
- Sometimes, we want to search for a key from a map
  - E.g. use time stamps as keys to get events that happened in the time stamps
  - For unsorted map:  $O(N)$
- Sorted Map
  - Map with continuous keys in a sorted order
  - We can get efficient operations on Sorted Maps

# SORTED MAPS

- Sorted Maps ADT
- `M.find_min()`: returns the  $(k, v)$  pair with the minimum key
- `M.find_max()`: returns the  $(k, v)$  pair with the maximum key
- `M.find_lt(k)`: returns the  $(k, v)$  pair, such that its key is less than  $k$
- `M.find_le(k)`: returns the  $(k, v)$  pair, such that its key is less than or equal to  $k$
- `M.find_gt(k)`: returns the  $(k, v)$  pair, such that its key is greater than  $k$
- `M.find_ge(k)`: returns the  $(k, v)$  pair, such that its key is greater than or equal to  $k$
- `M.find_range(start, stop)`: get all  $(k, v)$  pairs from  $start$  to  $stop$
- `Iter(M)`
- `Reversed(M)`

- Sorted Table Map
- Binary search to find the index that stores the (k, v) pair

```

1  class SortedTableMap(MapBase):
2      """ Map implementation using a sorted table."""
3
4      #----- nonpublic behaviors -----
5      def _find_index(self, k, low, high):
6          """ Return index of the leftmost item with key greater than or equal to k.
7
8              Return high + 1 if no such item qualifies.
9
10             That is, j will be returned such that:
11                 all items of slice table[low:j] have key < k
12                 all items of slice table[j:high+1] have key >= k
13             """
14             if high < low:
15                 return high + 1                # no element qualifies
16             else:
17                 mid = (low + high) // 2
18                 if k == self._table[mid]._key:
19                     return mid                # found exact match
20                 elif k < self._table[mid]._key:
21                     return self._find_index(k, low, mid - 1)    # Note: may return mid
22                 else:
23                     return self._find_index(k, mid + 1, high)    # answer is right of mid

```

# SORTED MAPS

- Sorted Table Map
- `__init__`
- `__len__`
- `__getitem__`:
  - Use binary search to get the value associated to key k

```
26 def __init__(self):
27     """ Create an empty map."""
28     self._table = [ ]
29
30 def __len__(self):
31     """ Return number of items in the map."""
32     return len(self._table)
33
34 def __getitem__(self, k):
35     """ Return value associated with key k (raise KeyError if not found)."""
36     j = self._find_index(k, 0, len(self._table) - 1)
37     if j == len(self._table) or self._table[j]._key != k:
38         raise KeyError('Key Error: ' + repr(k))
39     return self._table[j]._value
```

# SORTED MAPS

- `__setitem__`:
  - Binary search to get the index
  - Update value if k exists
  - Insert (k, v) pair if k does not exist
- `__delitem__`:
  - Binary search to get the index
  - Pop item if index is legal

```

40 def __setitem__(self, k, v):
41     """Assign value v to key k, overwriting existing value if present."""
42     j = self._find_index(k, 0, len(self._table) - 1)
43     if j < len(self._table) and self._table[j]._key == k:
44         self._table[j]._value = v # reassign value
45     else:
46         self._table.insert(j, self._Item(k,v)) # adds new item
47
48 def __delitem__(self, k):
49     """Remove item associated with key k (raise KeyError if not found)."""
50     j = self._find_index(k, 0, len(self._table) - 1)
51     if j == len(self._table) or self._table[j]._key != k:
52         raise KeyError('Key Error: ' + repr(k))
53     self._table.pop(j) # delete item

```

# SORTED MAPS

- find\_min:
  - Get (k, v) at index 0
- find\_max:
  - Get (k, v) at index n-1

```
60 def __reversed__(self):
61     """Generate keys of the map ordered from maximum to minimum."""
62     for item in reversed(self._table):
63         yield item._key
64
65 def find_min(self):
66     """Return (key,value) pair with minimum key (or None if empty)."""
67     if len(self._table) > 0:
68         return (self._table[0]._key, self._table[0]._value)
69     else:
70         return None
71
72 def find_max(self):
73     """Return (key,value) pair with maximum key (or None if empty)."""
74     if len(self._table) > 0:
75         return (self._table[-1]._key, self._table[-1]._value)
76     else:
77         return None
```



# SORTED MAPS

- `find_ge`:
  - Binary search to get index for `k`
  - Return `(k, v)` pair if legal
- `find_lt`:
  - Binary search to get index for `k`
  - Return `(k, v)` pair before the index for `k` if index is legal

```
78 def find_ge(self, k):
79     """ Return (key,value) pair with least key greater than or equal to k."""
80     j = self._find_index(k, 0, len(self._table) - 1) # j's key >= k
81     if j < len(self._table):
82         return (self._table[j]._key, self._table[j]._value)
83     else:
84         return None
85
86 def find_lt(self, k):
87     """ Return (key,value) pair with greatest key strictly less than k."""
88     j = self._find_index(k, 0, len(self._table) - 1) # j's key >= k
89     if j > 0:
90         return (self._table[j-1]._key, self._table[j-1]._value) # Note use of j-1
91     else:
92         return None
```

- `find_gt`:
  - Binary search to get index for `k`
  - Increment index `j` by 1
  - If `j` is legal return `(k, v)` at `j`
- `find_range`:
  - Binary search to get start
  - Then collecting items from start to stop

```

94 def find_gt(self, k):
95     """Return (key,value) pair with least key strictly greater than k."""
96     j = self._find_index(k, 0, len(self._table) - 1)      # j's key >= k
97     if j < len(self._table) and self._table[j]._key == k:
98         j += 1                                             # advanced past match
99     if j < len(self._table):
100         return (self._table[j]._key, self._table[j]._value)
101     else:
102         return None
103
104 def find_range(self, start, stop):
105     """Iterate all (key,value) pairs such that start <= key < stop.
106
107     If start is None, iteration begins with minimum key of map.
108     If stop is None, iteration continues through the maximum key of map.
109     """
110     if start is None:
111         j = 0
112     else:
113         j = self._find_index(start, 0, len(self._table)-1) # find first result
114     while j < len(self._table) and (stop is None or self._table[j]._key < stop):
115         yield (self._table[j]._key, self._table[j]._value)
116         j += 1

```

# SORTED MAPS

- Analysis
- $k$  in  $M$  is  $O(\log n)$  due to binary search
- $M[k] = v$  is  $O(n)$  if  $k$  does not exist;  $O(\log n)$  otherwise
- $\text{del } M[k]$  is  $O(n)$  worst case
- $M.\text{find\_range}()$ :  $O(s + \log n)$

Operation	Running Time
$\text{len}(M)$	$O(1)$
$k$ in $M$	$O(\log n)$
$M[k] = v$	$O(n)$ worst case; $O(\log n)$ if existing $k$
$\text{del } M[k]$	$O(n)$ worst case
$M.\text{find\_min}()$ , $M.\text{find\_max}()$	$O(1)$
$M.\text{find\_lt}(k)$ , $M.\text{find\_gt}(k)$ $M.\text{find\_le}(k)$ , $M.\text{find\_ge}(k)$	$O(\log n)$
$M.\text{find\_range}(\text{start}, \text{stop})$	$O(s + \log n)$ where $s$ items are reported
$\text{iter}(M)$ , $\text{reversed}(M)$	$O(n)$

# APPLICATIONS OF SORTED MAPS

- Flight databases
- Query on flight database to find flights
  - “from” and “to” cities
  - Departure date
  - Departure time
- Flight database as map, Flight objects as keys
  - $k = (\text{from}, \text{to}, \text{date}, \text{time})$
- `find_ge`, `find_lt`, etc to get a query result
- `find_range()` to get all feasible flights

(ORD, PVD, 05May, 09:53)	:	(AA 1840, F5, Y15, 02:05, \$251),
(ORD, PVD, 05May, 13:29)	:	(AA 600, F2, Y0, 02:16, \$713),
(ORD, PVD, 05May, 17:39)	:	(AA 416, F3, Y9, 02:09, \$365),
(ORD, PVD, 05May, 19:50)	:	(AA 1828, F9, Y25, 02:13, \$186)



# QUIZ FOR THIS WEEK

- A 100 bottles
- One of them contains poison, if a rat takes the poison, it dies in 3 days
- The other 99 bottles contain just water
- Question: the minimal number of rats to determine which bottle contains the poison.



# THANKS

See you in the next session!