

Longitudinal mediation analysis with missing not at random data

Supplementary Material

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Appendix A Proof of Proposition 3.1

It should be noted that the identifiability of the model at subsequent moments depends on the consistency of the estimators of the parameters at previous moments, and the consistency of the estimators of the parameters at each moment also depends on the identifiability of the model at that moment.

We first give a proof of the identifiability of the outcome model at time t with the assumption that the parameter estimates of the outcome models at the first $t-1$ time points are consistent. In other words, we only need to prove the identifiability of $P(Y_t = 1 \mid A = a, M_t = m, X = x, Y_{t-1} = y_{t-1})$ for any given (a, m, x, y_{t-1}) without missing data before time t . Following the idea of Li and Zhou^[1], we use a proof by contradiction to show this result.

Suppose there are two parameters underlying the observed data distribution:

$$\begin{aligned} & P_1(R_t = 1 \mid A, M_t, Y_t = y_t, U)P_1(Y_t = y_t \mid A, M_t, Y_{t-1}, U, V) \\ &= P_2(R_t = 1 \mid A, M_t, Y_t = y_t, U)P_2(Y_t = y_t \mid A, M_t, Y_{t-1}, U, V). \end{aligned}$$

For simplicity, we omit a , m , and u in the corresponding expressions. For $j = 1, 2$, denote

$$p_{ij}(y_t) = P_i(Y_t = y_t \mid V = v_j, Y_{t-1} = y_{t-1})$$

and

$$Q(y_t) = P_1(R_t = 1 \mid Y_t = y_t)/P_2(R_t = 1 \mid Y_t = y_t) - 1,$$

we have

$$P_1(R_t = 1 \mid Y_t = y_t)p_{11}(y_t) = P_2(R_t = 1 \mid Y_t = y_t)p_{21}(y_t) \quad (\text{S.1})$$

and

$$P_1(R_t = 1 \mid Y_t = y_t)p_{12}(y_t) = P_2(R_t = 1 \mid Y_t = y_t)p_{22}(y_t). \quad (\text{S.2})$$

Let $y_t = 0, 1$ in equations (S.1) and (S.2), we have

$$\begin{cases} P_1(R_t = 1 \mid Y_t = 0)p_{11}(0) = P_2(R_t = 1 \mid Y_t = 0)p_{21}(0), \\ P_1(R_t = 1 \mid Y_t = 1)p_{11}(1) = P_2(R_t = 1 \mid Y_t = 1)p_{21}(1), \\ P_1(R_t = 1 \mid Y_t = 0)p_{12}(0) = P_2(R_t = 1 \mid Y_t = 0)p_{22}(0), \\ P_1(R_t = 1 \mid Y_t = 1)p_{12}(1) = P_2(R_t = 1 \mid Y_t = 1)p_{22}(1), \end{cases} \quad (\text{S.3})$$

i.e.,

$$\begin{cases} (Q_1(0) + 1)p_{11}(0) = p_{21}(0), \\ (Q_1(1) + 1)p_{11}(1) = p_{21}(1), \\ (Q_1(0) + 1)p_{12}(0) = p_{22}(0), \\ (Q_1(1) + 1)p_{12}(1) = p_{22}(1). \end{cases} \quad (\text{S.4})$$

Since $p_{ij}(0) + p_{ij}(1) = 1$ for $i = 1, 2$ and $j = 1, 2$, we have

$$Q(0)p_{11}(0) + Q(1)p_{11}(1) = 0, \quad (\text{S.5})$$

$$Q(0)p_{12}(0) + Q(1)p_{12}(1) = 0. \quad (\text{S.6})$$

Consequently,

$$(Q(1) - Q(0))(p_{12}(1) - p_{11}(1)) = 0.$$

From the definition of the shadow variable, we know that there exists v_1 and v_2 such that $p_{12}(1) - p_{11}(1) \neq 0$. So $Q(1) - Q(0) = 0$, which implies $Q(1) = Q(0) = 0$ because they couldn't have the same signs according to equations (S.5) and (S.6). In other words,

$$P_1(R_t = 1 \mid Y_t = y_t) = P_2(R_t = 1 \mid Y_t = y_t),$$

so

$$\begin{aligned} & P_1(Y_t = y_t \mid A = a, M_t = m, Y_{t-1} = y_{t-1}, U = u, V = v) \\ &= P_2(Y_t = y_t \mid A = a, M_t = m, Y_{t-1} = y_{t-1}, U = u, V = v) \end{aligned}$$

for any (a, m, y_{t-1}, u, v) , this creates a contradiction. As a result, $P(Y_t = 1 \mid A = a, M_t = m, X = x, Y_{t-1} = y_{t-1})$ is identifiable.

We then establish the consistency of the parameter estimators under the identifiability assumptions. By the condition that the matrices

$$\frac{\partial \omega_{R_t}(\beta_t)}{\partial \beta_t} R_t h_1^\tau \text{ and } -\frac{\partial E(Y_t \mid A, M_t, U, V, Y_{t-1}; \gamma_t)}{\partial \gamma_t} h_2^\tau$$

are invertible, we have that

$$E \begin{pmatrix} \frac{\partial \omega_{R_t}(\beta_t)}{\partial \beta_t} R_t h_1^\tau & 0 \\ \frac{\partial \omega_{R_t}(\beta_t)}{\partial \beta_t} R_t h_2^\tau & -\frac{\partial E(Y_t \mid A, M_t, U, V, Y_{t-1}; \gamma_t)}{\partial \gamma_t} h_2^\tau \end{pmatrix}$$

is invertible. Consequently,

$$\text{equations (7) and (9) have (locally) unique solutions.} \quad (\text{S.7})$$

Let $L_t = (A, M_t, U, V)$ and omits variables in $h_1(\cdot)$ and $h_2(\cdot)$. First,

$$\begin{aligned} & E[\{\omega_{R_t}(A, M_t, Y_t, U; \beta_t) R_t - 1\} h_1] \\ &= E[E[\{\omega_{R_t}(A, M_t, Y_t, U; \beta_t) R_t - 1\} h_1 \mid A, M_t, Y_t, U, V]], \\ &= E[\{1/E(R_t \mid A, M_t, Y_t, U, V) E(R_t \mid A, M_t, Y_t, U, V) - 1\} h_1] = 0. \end{aligned} \quad (\text{S.8})$$

Second,

$$\begin{aligned}
& E[\{\omega_{R_t}(A, M_t, Y_t, U; \beta_t)R_tY_t - E(Y_t \mid L_t, Y_{t-1}; \gamma_t)\}h_2] \\
&= E[E[\{\omega_{R_t}(A, M_t, Y_t, U; \beta_t)R_tY_t - E(Y_t \mid L_t, Y_{t-1}; \gamma_t)\}h_2 \mid L_t, Y_t, Y_{t-1}]] \\
&= E[\{1/E(R_t \mid L_t, Y_t, Y_{t-1}; \beta_t)E(R_t \mid L_t, Y_t, Y_{t-1}; \beta_t)Y_t - E(Y_t \mid L_t, Y_{t-1}; \gamma_t)\}h_2] \\
&= E[\{Y_t - E(Y_t \mid L_t, Y_{t-1}; \gamma_t)\}h_2] \\
&= E[E[\{Y_t - E(Y_t \mid L_t, Y_{t-1}; \gamma_t)\}h_2 \mid L_t, Y_{t-1}]] \\
&= E[\{E(Y_t \mid L_t, Y_{t-1}; \gamma_t) - E(Y_t \mid L_t, Y_{t-1}; \gamma_t)\}h_2] \\
&= 0.
\end{aligned} \tag{S.9}$$

The second part of the proposition follows from (S.7)-(S.9) by the standard limit theorem for estimation equation.

Appendix B Other simulation results

Appendix B.1 Verification of natural effect model (14)

The distributions of A , C_1 , and C_2 in this section are the same as those in Section 4.1. We considered time-varying binary mediators and binary outcomes for $T = 5$ time points. The mediator and outcome were generated from models

$$\text{logit}(P(M_1 = 1)) = \delta_0 + \delta_1 A + \delta_2 C_1 + \delta_3 C_2 \tag{S.10}$$

and

$$\text{logit}(P(Y_1 = 1)) = \gamma_0 + \gamma_1 A + \gamma_M M_1 + \gamma_2 C_1 + \gamma_3 C_2 \tag{S.11}$$

for $t = 1$ and models

$$\text{logit}(P(M_t = 1)) = \delta_0 + \delta_1 A + \delta_M M_{t-1} + \delta_Y Y_{t-1} + \delta_2 C_1 + \delta_3 C_2 \tag{S.12}$$

and

$$\text{logit}(P(Y_t = 1)) = \gamma_0 + \gamma_1 A + \gamma_M M_t + \gamma_Y Y_{t-1} + \gamma_2 C_1 + \gamma_3 C_2 \tag{S.13}$$

for $t = 2, \dots, 5$. We considered two parameter settings for mediator and outcome models. For setting 1,

$$(\delta_0, \delta_1, \delta_2, \delta_3, \delta_M, \delta_Y) = (0.3, -0.8, 0.5, 1, 0.1, 0.1),$$

and

$$(\gamma_0, \gamma_1, \gamma_2, \gamma_3, \gamma_M, \gamma_Y) = (-0.4, 1.5, -0.4, 1.2, -1, 0.3).$$

For setting 2,

$$(\delta_0, \delta_1, \delta_2, \delta_3, \delta_M, \delta_Y) = (0.7, -0.5, 0.5, 0.5, 0.15, 0.15),$$

and

$$(\gamma_0, \gamma_1, \gamma_2, \gamma_3, \gamma_M, \gamma_Y) = (1, -1.5, 0.4, 0.8, 1.2, 0.3).$$

We generated $B = 500$ samples with sample size $N = 10^6$ and the natural effects (see Table S.1) were calculated by definition ((4)-(6)). It's obvious that the natural effects at time $t = 2, \dots, 5$ are very close to each other.

Table S.1: True values of the natural effects at five time points under two parameter settings 1 and 2 ($T = 5$).

Natural effect	$t = 1$	$t = 2$	$t = 3$	$t = 4$	$t = 5$
Setting 1					
DE_t	1.304	1.368	1.370	1.370	1.370
IDE_t	0.154	0.162	0.162	0.162	0.162
TE_t	1.458	1.530	1.532	1.532	1.532
Setting 2					
DE_t	-1.303	-1.384	-1.384	-1.383	-1.383
IDE_t	-0.132	-0.141	-0.140	-0.140	-0.140
TE_t	-1.435	-1.525	-1.524	-1.524	-1.524

Appendix B.2 Additional simulations for comparison of models (14) and (13)

First, we conducted some additional simulations as supplements of Section 4.1. The distribution of A, C_1, C_2 in this section is the same as Section 4.1. We consider two parameter settings in models (15)-(18) for $T = 3$. For setting 1,

$$(\delta_0, \delta_1, \delta_2, \delta_3, \delta_M, \delta_Y) = (0.5, 0.5, 1.5, -1, 0.25, 0.25),$$

and

$$(\gamma_0, \gamma_1, \gamma_2, \gamma_3, \gamma_M, \gamma_Y) = (0.4, 1.2, -0.8, 1.2, 1.2, 0.3).$$

For setting 2,

$$(\delta_0, \delta_1, \delta_2, \delta_3, \delta_M, \delta_Y) = (0.7, -0.5, 0.5, 0.5, 0.15, 0.15),$$

and

$$(\gamma_0, \gamma_1, \gamma_2, \gamma_3, \gamma_M, \gamma_Y) = (1, -1.5, 0.4, 0.8, 1.2, 0.3).$$

We generated $B = 500$ samples with sample size $n = 2000$ or 5000 and estimated natural effects through fitting the natural effect models (13) and (14) using complete data. The results at time $t = 2, \dots, T = 3$ under settings 1 and 2 are shown in Tables S.2 and S.3, respectively. The estimation biases based on model (13) are much larger than (14) for most natural effects. The RMSEs and SEs of the effects estimated using models (13) and (14) are similar to the results in Section 4.1.

Shown in Tables S.4-S.6 are the results of $T = 5$. Evidently, the biases of model (13) were much larger than model (14) for most effects. For $t = 2, 3$, some RMSEs of model (13) were smaller than model (14) due to smaller SEs of model (13). As t increased to 5, the RMSEs of model (13) were much larger than (14).

Overall, model (14) outperformed model (13) in terms of the estimation of natural effects with complete data.

Next, we conducted some simulations with $T = 5$ as supplements of Section 4.2. The results are presented in Tables S.7 and S.8. The biases of all three methods got larger. As a result, M-EE showed poor CPs for some effects. The biases of O-EE were again much larger than M-EE for most effects, and M-Heck performed poorly in all aspects. RMSE showed a pattern similar to the complete data case.

Table S.2: Comparison of models (13) and (14) in terms of natural effects with complete data under parameter setting 1 ($T = 3$).

Natural	True	Model (13)			Model (14)		
effect	value	Bias	RMSE	SE	Bias	RMSE	SE
$n = 2000$							
DE ₂	1.167	-0.014	0.091	0.090	0.004	0.115	0.115
DE ₃	1.161	0.021	0.149	0.148	0.009	0.115	0.115
IDE ₂	0.093	-0.000	0.016	0.016	0.000	0.022	0.022
IDE ₃	0.092	0.001	0.029	0.029	0.001	0.022	0.022
TE ₂	1.260	-0.014	0.091	0.091	0.004	0.115	0.115
TE ₃	1.253	0.022	0.149	0.147	0.010	0.116	0.115
$n = 5000$							
DE ₂	1.167	-0.023	0.063	0.059	-0.002	0.074	0.074
DE ₃	1.161	0.016	0.098	0.097	0.003	0.074	0.074
IDE ₂	0.093	-0.001	0.010	0.010	-0.001	0.013	0.013
IDE ₃	0.092	0.000	0.017	0.017	0.000	0.013	0.013
TE ₂	1.260	-0.024	0.064	0.059	-0.003	0.074	0.074
TE ₃	1.253	0.016	0.099	0.098	0.003	0.074	0.074

Bias, estimated natural effect minus the true value; RMSE, root mean square error; SE, empirical standard error; DE _{t} , direct effect at time t ; IDE _{t} , indirect effect at time t ; TE _{t} , total effect at time t .

Table S.3: Comparison of models (13) and (14) in terms of natural effects with complete data under parameter setting 2 ($T = 3$).

Natural	True	Model (13)			Model (14)		
effect	value	Bias	RMSE	SE	Bias	RMSE	SE
$n = 2000$							
DE ₂	-1.384	0.025	0.073	0.068	-0.005	0.088	0.088
DE ₃	-1.384	-0.023	0.112	0.110	-0.005	0.088	0.088
IDE ₂	-0.141	0.010	0.022	0.019	0.007	0.026	0.025
IDE ₃	-0.140	0.005	0.032	0.032	0.006	0.025	0.025
TE ₂	-1.525	0.035	0.076	0.067	0.002	0.086	0.086
TE ₃	-1.524	-0.018	0.109	0.108	0.001	0.086	0.086
$n = 5000$							
DE ₂	1.167	0.022	0.048	0.043	-0.005	0.050	0.050
DE ₃	1.161	-0.023	0.069	0.065	-0.005	0.050	0.050
IDE ₂	0.093	0.011	0.016	0.012	0.008	0.016	0.015
IDE ₃	0.092	0.006	0.020	0.019	0.007	0.016	0.015
TE ₂	1.260	0.032	0.054	0.043	0.003	0.051	0.051
TE ₃	1.253	-0.017	0.068	0.066	0.002	0.051	0.051

Bias, estimated natural effect minus the true value; RMSE, root mean square error; SE, empirical standard error; DE_{*t*}, direct effect at time *t*; IDE_{*t*}, indirect effect at time *t*; TE_{*t*}, total effect at time *t*.

Table S.4: Comparison of models (13) and (14) in terms of natural effects with complete data under parameter setting in Section 4.1 ($T = 5$).

Natural	True	Model (13)			Model (14)		
effect	value	Bias	RMSE	SE	Bias	RMSE	SE
$n = 2000$							
DE ₂	1.368	-0.025	0.059	0.053	0.006	0.051	0.050
DE ₃	1.370	-0.010	0.046	0.045	0.004	0.050	0.050
DE ₄	1.370	0.006	0.057	0.056	0.004	0.050	0.050
DE ₅	1.370	0.023	0.082	0.079	0.004	0.050	0.050
IDE ₂	0.162	-0.002	0.018	0.018	0.000	0.022	0.022
IDE ₃	0.162	-0.002	0.019	0.019	-0.000	0.022	0.022
IDE ₄	0.162	-0.001	0.027	0.027	-0.000	0.022	0.022
IDE ₅	0.162	-0.001	0.038	0.038	-0.000	0.022	0.022
TE ₂	1.530	-0.027	0.058	0.052	0.006	0.048	0.047
TE ₃	1.532	-0.012	0.044	0.042	0.003	0.047	0.047
TE ₄	1.532	0.005	0.052	0.052	0.003	0.047	0.047
TE ₅	1.532	0.022	0.077	0.074	0.003	0.047	0.047
$n = 5000$							
DE ₂	1.368	-0.030	0.046	0.035	-0.001	0.034	0.034
DE ₃	1.370	-0.017	0.034	0.030	-0.003	0.034	0.034
DE ₄	1.370	-0.002	0.037	0.037	-0.003	0.034	0.034
DE ₅	1.370	0.013	0.053	0.051	-0.003	0.034	0.034
IDE ₂	0.162	-0.002	0.011	0.010	0.003	0.015	0.014
IDE ₃	0.162	-0.000	0.012	0.012	0.002	0.015	0.014
IDE ₄	0.162	0.003	0.018	0.017	0.002	0.015	0.014
IDE ₅	0.162	0.005	0.025	0.024	0.002	0.015	0.014
TE ₂	1.530	-0.032	0.048	0.035	0.002	0.032	0.032
TE ₃	1.532	-0.017	0.033	0.029	-0.001	0.032	0.032
TE ₄	1.532	0.001	0.034	0.035	-0.001	0.032	0.032
TE ₅	1.532	0.018	0.052	0.049	-0.001	0.032	0.032

Bias, estimated natural effect minus the true value; RMSE, root mean square error; SE, empirical standard error; DE_{*t*}, direct effect at time *t*; IDE_{*t*}, indirect effect at time *t*; TE_{*t*}, total effect at time *t*.

Table S.5: Comparison of models (13) and (14) in terms of natural effects with complete data under parameter setting 1 ($T = 5$).

Natural	True	Model (13)			Model (14)		
effect	value	Bias	RMSE	SE	Bias	RMSE	SE
$n = 2000$							
DE ₂	1.166	-0.025	0.087	0.084	0.001	0.084	0.084
DE ₃	1.161	-0.006	0.072	0.071	0.006	0.084	0.084
DE ₄	1.161	0.010	0.095	0.094	0.007	0.084	0.084
DE ₅	1.161	0.025	0.138	0.136	0.007	0.084	0.084
IDE ₂	0.093	-0.001	0.016	0.016	-0.000	0.017	0.017
IDE ₃	0.092	0.000	0.015	0.015	0.000	0.017	0.017
IDE ₄	0.092	0.001	0.020	0.020	0.000	0.017	0.017
IDE ₅	0.092	0.001	0.028	0.028	0.000	0.017	0.017
TE ₂	1.260	-0.026	0.088	0.084	0.001	0.082	0.082
TE ₃	1.253	-0.005	0.071	0.071	0.006	0.082	0.082
TE ₄	1.253	0.011	0.092	0.092	0.007	0.082	0.082
TE ₅	1.252	0.026	0.134	0.132	0.007	0.082	0.082
$n = 5000$							
DE ₂	1.166	-0.025	0.059	0.054	-0.001	0.053	0.053
DE ₃	1.161	-0.009	0.047	0.047	0.004	0.053	0.053
DE ₄	1.161	0.004	0.061	0.061	0.005	0.053	0.053
DE ₅	1.161	0.015	0.088	0.087	0.005	0.053	0.053
IDE ₂	0.093	-0.001	0.009	0.009	-0.001	0.011	0.011
IDE ₃	0.092	-0.000	0.009	0.009	-0.001	0.011	0.011
IDE ₄	0.092	-0.001	0.013	0.013	-0.000	0.011	0.011
IDE ₅	0.092	-0.001	0.019	0.019	-0.000	0.011	0.011
TE ₂	1.260	-0.026	0.059	0.053	-0.002	0.053	0.053
TE ₃	1.253	-0.009	0.047	0.046	0.004	0.053	0.053
TE ₄	1.253	0.003	0.061	0.061	0.005	0.053	0.053
TE ₅	1.252	0.014	0.087	0.086	0.005	0.053	0.053

Bias, estimated natural effect minus the true value; RMSE, root mean square error; SE, empirical standard error; DE_{*t*}, direct effect at time *t*; IDE_{*t*}, indirect effect at time *t*; TE_{*t*}, total effect at time *t*.

Table S.6: Comparison of models (13) and (14) in terms of natural effects with complete data under parameter setting 2 ($T = 5$).

Natural	True	Model (13)			Model (14)		
effect	value	Bias	RMSE	SE	Bias	RMSE	SE
$n = 2000$							
DE ₂	-1.384	0.029	0.069	0.063	-0.005	0.065	0.065
DE ₃	-1.384	0.011	0.058	0.057	-0.006	0.065	0.065
DE ₄	-1.383	-0.006	0.075	0.075	-0.006	0.065	0.065
DE ₅	-1.383	-0.023	0.108	0.105	-0.006	0.065	0.065
IDE ₂	-0.141	0.010	0.020	0.017	0.007	0.020	0.019
IDE ₃	-0.140	0.008	0.018	0.016	0.007	0.020	0.019
IDE ₄	-0.140	0.007	0.022	0.021	0.007	0.020	0.019
IDE ₅	-0.140	0.005	0.030	0.029	0.007	0.020	0.019
TE ₂	-1.525	0.039	0.074	0.063	0.002	0.064	0.064
TE ₃	-1.524	0.019	0.059	0.056	0.001	0.064	0.064
TE ₄	-1.524	0.001	0.073	0.073	0.000	0.064	0.064
TE ₅	-1.524	-0.018	0.105	0.103	0.000	0.064	0.064
$n = 5000$							
DE ₂	-1.384	0.035	0.055	0.042	-0.005	0.043	0.043
DE ₃	-1.384	0.014	0.041	0.038	-0.005	0.043	0.043
DE ₄	-1.383	-0.007	0.048	0.048	-0.005	0.043	0.043
DE ₅	-1.383	-0.028	0.071	0.065	-0.005	0.043	0.043
IDE ₂	-0.141	0.012	0.016	0.011	0.008	0.014	0.011
IDE ₃	-0.140	0.009	0.013	0.010	0.008	0.014	0.011
IDE ₄	-0.140	0.007	0.015	0.013	0.008	0.014	0.011
IDE ₅	-0.140	0.005	0.019	0.018	0.008	0.014	0.011
TE ₂	-1.525	0.047	0.063	0.042	0.004	0.043	0.043
TE ₃	-1.524	0.023	0.044	0.038	0.003	0.043	0.043
TE ₄	-1.524	0.000	0.047	0.047	0.002	0.043	0.043
TE ₅	-1.524	-0.023	0.069	0.065	0.002	0.043	0.043

Bias, estimated natural effect minus the true value; RMSE, root mean square error; SE, empirical standard error; DE_{*t*}, direct effect at time *t*; IDE_{*t*}, indirect effect at time *t*; TE_{*t*}, total effect at time *t*.

Table S.7: Comparison of three methods in terms of natural effects ($T = 5$ and $n = 2000$).

Natural effect	True value	M-EE					O-EE					M-Heck				
		Bias	RMSE	CP	SE	SEE	Bias	RMSE	CP	SE	SEE	Bias	RMSE	CP	SE	SEE
$n = 2000$																
DE ₂	1.368	-0.015	0.062	0.976	0.060	0.064	-0.042	0.078	0.906	0.066	0.066	-0.074	0.098	0.910	0.064	0.077
DE ₃	1.370	-0.017	0.063	0.974	0.060	0.064	-0.029	0.062	0.934	0.055	0.058	-0.077	0.100	0.902	0.064	0.077
DE ₄	1.370	-0.017	0.063	0.974	0.060	0.064	-0.014	0.069	0.974	0.067	0.070	-0.077	0.100	0.902	0.064	0.077
DE ₅	1.370	-0.017	0.063	0.974	0.060	0.064	0.001	0.095	0.960	0.095	0.095	-0.077	0.100	0.902	0.064	0.077
IDE ₂	0.162	-0.003	0.022	0.966	0.022	0.023	-0.004	0.019	0.904	0.019	0.016	-0.022	0.036	0.878	0.028	0.026
IDE ₃	0.162	-0.004	0.022	0.964	0.022	0.023	-0.005	0.019	0.952	0.018	0.019	-0.023	0.036	0.874	0.028	0.026
IDE ₄	0.162	-0.004	0.022	0.964	0.022	0.023	-0.004	0.026	0.970	0.026	0.028	-0.023	0.036	0.874	0.028	0.026
IDE ₅	0.162	-0.004	0.022	0.964	0.022	0.023	-0.004	0.036	0.980	0.036	0.039	-0.023	0.036	0.874	0.028	0.026
TE ₂	1.530	-0.018	0.058	0.978	0.056	0.066	-0.046	0.078	0.920	0.063	0.068	-0.097	0.115	0.856	0.063	0.080
TE ₃	1.532	-0.021	0.059	0.974	0.056	0.066	-0.033	0.062	0.956	0.052	0.061	-0.099	0.117	0.844	0.063	0.080
TE ₄	1.532	-0.021	0.059	0.974	0.056	0.066	-0.018	0.064	0.972	0.061	0.072	-0.099	0.117	0.844	0.063	0.080
TE ₅	1.532	-0.021	0.059	0.974	0.056	0.066	-0.003	0.086	0.970	0.086	0.095	-0.099	0.117	0.844	0.063	0.080

Bias, estimated natural effect minus the true value; RMSE, root mean square error; CP, the coverage probability of 95% confidence intervals; SE, empirical standard error; SEE, average estimated standard error; DE_{*t*}, direct effect at time *t*; IDE_{*t*}, indirect effect at time *t*; TE_{*t*}, total effect at time *t*; M-EE, our proposed method; O-EE, using our proposed multiple imputation but using natural effect model proposed by Mittinty and Vansteelandt^[2] when estimating natural effects; M-Heck, using the theory based on Heckman model^[17] to do multiple imputation and using our natural effect model when estimating natural effects.

Table S.8: Comparison of three methods in terms of natural effects ($T = 5$, $n = 5000$).

Natural effect	True value	M-EE				O-EE				M-Heck						
		Bias	RMSE	CP	SE	SEE	Bias	RMSE	CP	SE	SEE	Bias	RMSE	CP	SE	SEE
$n = 5000$																
DE ₂	1.368	-0.003	0.042	0.960	0.042	0.041	-0.031	0.051	0.900	0.041	0.042	-0.056	0.071	0.916	0.045	0.055
DE ₃	1.370	-0.005	0.042	0.958	0.042	0.041	-0.019	0.040	0.924	0.035	0.037	-0.058	0.073	0.912	0.045	0.055
DE ₄	1.370	-0.005	0.042	0.958	0.042	0.041	-0.005	0.046	0.952	0.046	0.045	-0.058	0.073	0.910	0.045	0.055
DE ₅	1.370	-0.005	0.042	0.958	0.042	0.041	0.010	0.065	0.938	0.065	0.060	-0.058	0.073	0.912	0.045	0.055
IDE ₂	0.162	-0.002	0.014	0.966	0.013	0.014	-0.004	0.012	0.916	0.011	0.010	-0.015	0.025	0.876	0.020	0.019
IDE ₃	0.162	-0.0043	0.014	0.966	0.013	0.014	-0.004	0.012	0.950	0.011	0.012	-0.015	0.025	0.874	0.020	0.019
IDE ₄	0.162	-0.002	0.014	0.966	0.013	0.018	-0.003	0.016	0.972	0.016	0.016	-0.015	0.025	0.876	0.020	0.019
IDE ₅	0.162	-0.003	0.014	0.966	0.013	0.014	-0.002	0.023	0.972	0.023	0.025	-0.016	0.026	0.874	0.020	0.019
TE ₂	1.530	-0.005	0.038	0.986	0.038	0.042	-0.035	0.052	0.918	0.039	0.043	-0.071	0.083	0.870	0.044	0.056
TE ₃	1.532	-0.008	0.039	0.982	0.038	0.042	-0.023	0.040	0.952	0.033	0.039	-0.073	0.086	0.860	0.044	0.056
TE ₄	1.532	-0.008	0.039	0.982	0.038	0.042	-0.008	0.042	0.966	0.041	0.046	-0.073	0.086	0.860	0.044	0.056
TE ₅	1.532	-0.008	0.039	0.982	0.038	0.042	-0.007	0.059	0.960	0.059	0.061	-0.073	0.086	0.860	0.044	0.056

Bias, estimated natural effect minus the true value; RMSE, root mean square error; CP, the coverage probability of 95% confidence intervals; SE, empirical standard error; SEE, average estimated standard error; DE_{*t*}, direct effect at time *t*; IDE_{*t*}, indirect effect at time *t*; TE_{*t*}, total effect at time *t*; M-EE, our proposed method; O-EE, using our proposed multiple imputation but using natural effect model proposed by Mittinty and Vansteelandt^[2] when estimating natural effects; M-Heck, using the theory based on Heckman model^[17] to do multiple imputation and using our natural effect model when estimating natural effects.

Table S.9: Point estimates and 95% CIs of causal effects with 50% artificially generated MNAR data at each age (MCS data set).

	M-V	M-EE		O-EE	
	Estimate	Estimate	95 %CI, length	Estimate	95% CI, length
DE ₂	0.463	0.319	(0.087,0.551), 0.464	0.444	(0.290,0.597), 0.307
DE ₃	0.240	0.319	(0.087,0.551), 0.464	0.363	(0.050,0.676), 0.626
IDE ₂	0.136	0.093	(0.071,0.115), 0.044	0.077	(0.061,0.093), 0.032
IDE ₃	0.089	0.093	(0.071,0.115), 0.044	0.098	(0.069,0.127), 0.058
TE ₂	0.599	0.412	(0.183,0.640), 0.457	0.521	(0.369,0.672), 0.303
TE ₃	0.329	0.412	(0.183,0.640), 0.457	0.461	(0.152,0.770), 0.618

M-V, the method of Mittinty and Vansteelandt^[2]; M-EE, our proposed method; O-EE, using our proposed multiple imputation but using natural effect model proposed by Mittinty and Vansteelandt^[2] when estimating natural effects; 95%CI, 95% confidence intervals; DE, direct effect; IDE, indirect effect; TE, total effect; Subscripts 2 and 3 correspond to children ages of five and seven years.