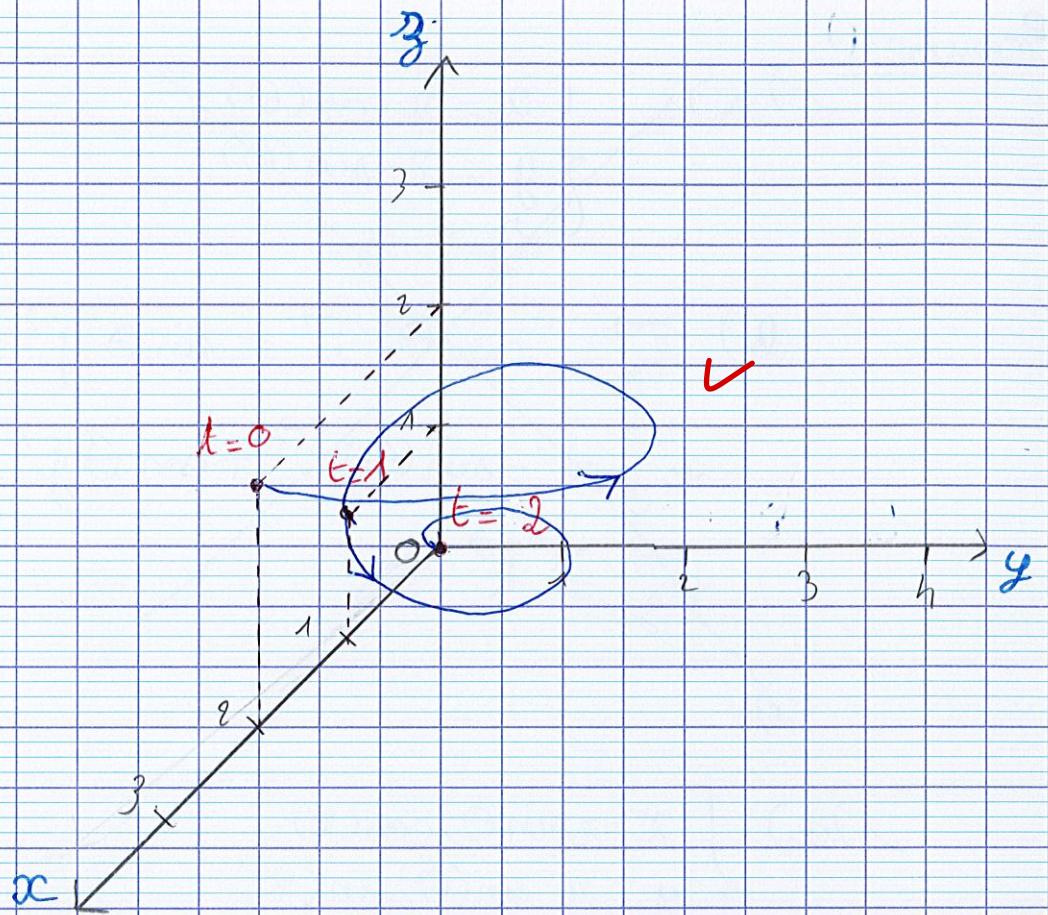


1,25

b)



0,5

$$\begin{aligned}
 c) \quad \vec{e}_r(t) &= \sin(\theta) \cos(\varphi) \vec{i} + \sin(\theta) \sin(\varphi) \vec{j} + \cos(\theta) \vec{k} \\
 &= \sin\left(\frac{\pi}{4}\right) \cos(2\pi t) \vec{i} + \sin\left(\frac{\pi}{4}\right) \sin(2\pi t) \vec{j} + \cos\left(\frac{\pi}{4}\right) \vec{k} \\
 &= \frac{\sqrt{2}}{2} \cos(2\pi t) \vec{i} + \frac{\sqrt{2}}{2} \sin(2\pi t) \vec{j} + \frac{\sqrt{2}}{2} \vec{k} \quad \checkmark
 \end{aligned}$$

$$\begin{aligned}
 ① \quad d) \quad \frac{d\vec{e}_r}{dt} &= \frac{-\sqrt{2} \times 2\pi \sin(2\pi t)}{2} \vec{i} + \frac{\sqrt{2} \times 2\pi \cos(2\pi t)}{2} \vec{j} \\
 &= -\sqrt{2}\pi \sin(2\pi t) \vec{i} + \sqrt{2}\pi \cos(2\pi t) \vec{j} \\
 &= \sqrt{2}\pi (-\sin(2\pi t) \vec{i} + \cos(2\pi t) \vec{j}) \\
 &= \sqrt{2}\pi (-\sin(\varphi(t)) \vec{i} + \cos(\varphi(t)) \vec{j}) \\
 &= \sqrt{2}\pi \vec{e}_\varphi \quad \checkmark
 \end{aligned}$$

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January 10
2019

20,00

Exercise 2) Define $\omega = df$

$$\omega = \frac{yz + xy + 1}{x+y} dx + \frac{xy}{x+y} dy + \frac{1}{x+y} dz$$

$$② \quad 1) \quad \frac{d^2f}{dx dy} = 1 \quad \checkmark$$

$$\frac{d^2f}{dy dx} = \frac{xy}{x+y} = 1 \quad \checkmark$$

$$\frac{d^2f}{dz dy} = 0 \quad \checkmark$$

$$\frac{d^2f}{dy dz} = 0 \quad \checkmark$$

$$\frac{d^2f}{dx dz} = -\frac{1}{(x+y)^2}$$

$$\begin{aligned}
 \frac{d^2f}{dz dx} &= \frac{y(x+y) + 1 \times (yz + xy + 1)}{(x+y)^2} \\
 &= \frac{xy + yz - yz - xy - 1}{(x+y)^2} = -\frac{1}{(x+y)^2}
 \end{aligned}$$

Thus, we have:

$$\begin{aligned}
 \frac{d^2f}{dx dy} &= \frac{d^2f}{dy dx} \\
 \frac{d^2f}{dz dy} &= \frac{d^2f}{dy dz} \\
 \frac{d^2f}{dx dz} &= \frac{d^2f}{dz dx}
 \end{aligned}$$

Thus, ω is a closed form. \checkmark

1.15 2) condition?

Integrate df by y:

$$f = xy + g(x) + h(y)$$

Differentiate by z:

$$\frac{df}{dz} = 0 + 0 + h'(z), \text{ hence } h'(z) = \frac{1}{x+z}$$

$$\text{Hence } h(z) = \ln(x+z)$$

Integrate by z:

$$f = xy + \ln(x+z) + h(z)$$

Differentiate by x:

$$\frac{df}{dx} = y + \frac{1}{x+z} + h'(z) = yx + yz + 1 + h'(z)$$

$$\text{Hence } h'(z) = 0$$

$$\text{Hence } h(z) = C, C \in \mathbb{R}$$

$$\text{Hence } f(x, y, z) = xy + \ln(x+z) + C \quad \checkmark$$

\rightarrow this is a consequence!

Thus, there exists a function f defined on D such that $df = \omega$, hence we can conclude ω is an exact form. \times

Exercise 1)

1) a) $\begin{cases} x = r \cos(\theta) \\ y = r \sin(\theta) \\ z = z \end{cases}$

b) $\vec{e}_r = \cos(\theta) \vec{i} + \sin(\theta) \vec{j}$

$\vec{e}_\theta = -\sin(\theta) \vec{i} + \cos(\theta) \vec{j}$

$\vec{e}_z = \vec{k}$

1.15 1) a) $\begin{cases} x = r \sin(\theta) \cos(\varphi) \\ y = r \sin(\theta) \sin(\varphi) \\ z = r \cos(\theta) \end{cases}$

b) $\vec{e}_r = \sin(\theta) \cos(\varphi) \vec{i} + \sin(\theta) \sin(\varphi) \vec{j} + \cos(\theta) \vec{k}$

$\vec{e}_\theta = \cos(\theta) \cos(\varphi) \vec{i} + \cos(\theta) \sin(\varphi) \vec{j} - \sin(\theta) \vec{k}$

$\vec{e}_\varphi = -\sin(\varphi) \vec{i} + \cos(\varphi) \vec{j}$

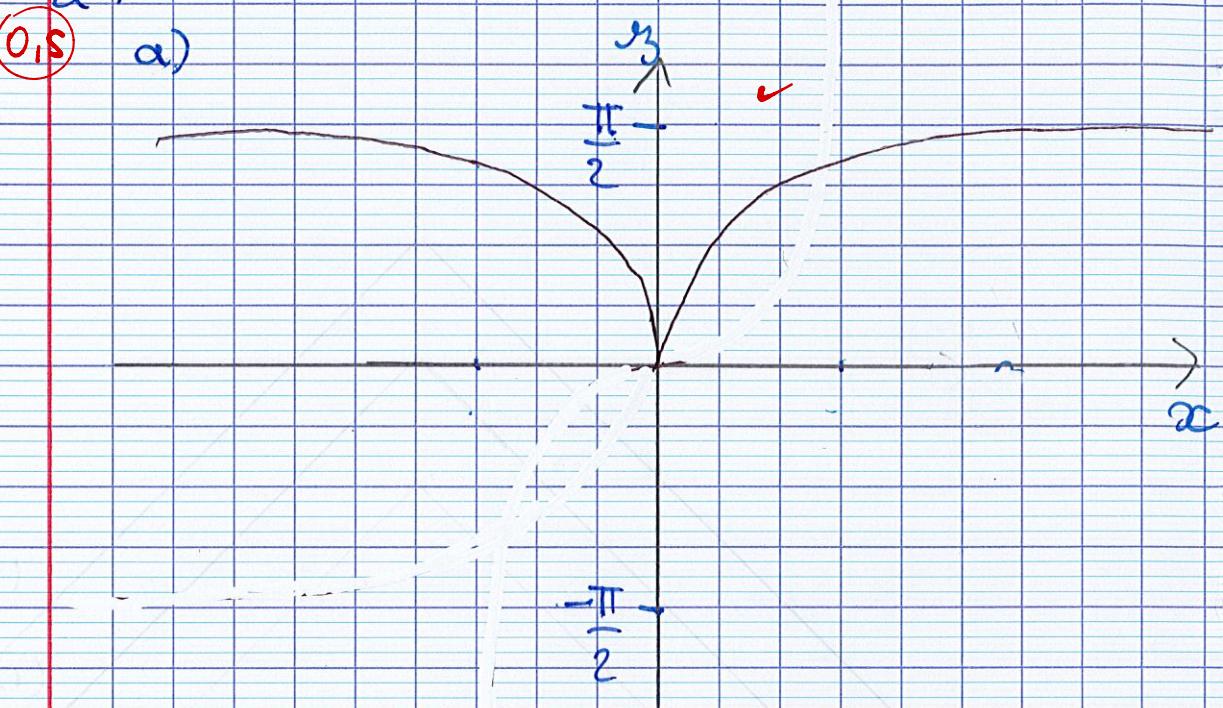
c) $\vec{OM} = r \vec{e}_r$

2) $\begin{cases} x(t) = (2-t)\sqrt{2} \\ \theta(t) = \frac{\pi}{4} \\ \varphi(t) = 2\pi t \end{cases}$

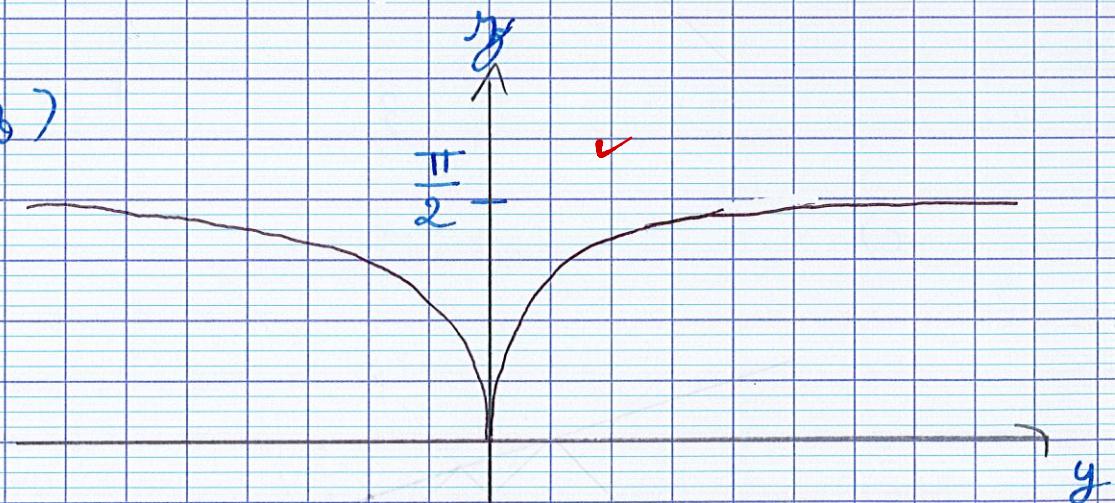
$t \in [0, 2]$

0.5 a) Since θ is constant, this trajectory is on a cone. \checkmark , missing more details on the cone shape!

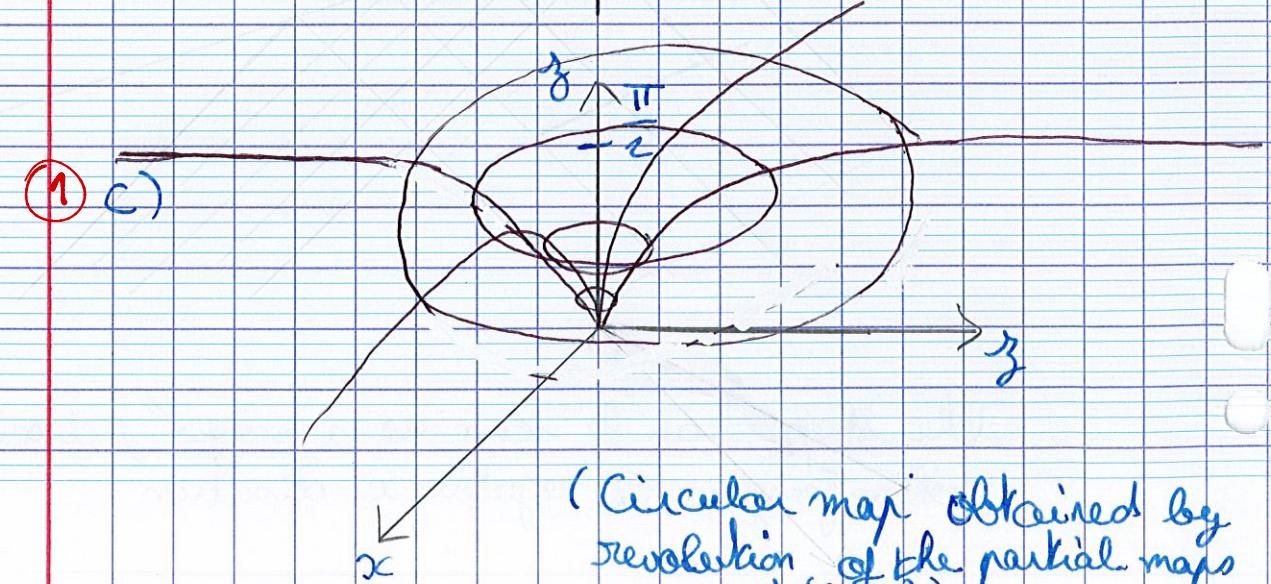
2)
0.15 a)



0.15 b)



c)



(Circular map obtained by revolution of the partial maps)

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$$\begin{aligned} \textcircled{1} \quad \vec{v}(t) &= \vec{OM}'(t) = \frac{d\vec{OM}}{dt} = \frac{d(x\vec{e}_x)}{dt} \\ &= \frac{dx}{dt}\vec{e}_x(t) + \frac{d\vec{e}_x}{dt}x(t) \checkmark \\ &= -\sqrt{2}\vec{e}_x(t) + \sqrt{2}\pi\cdot\vec{e}_y(2-t)\sqrt{2} \\ &= -\sqrt{2}\vec{e}_x(t) + 2\pi(2-t)\vec{e}_y(t) \checkmark \end{aligned}$$

(with \vec{e}_x and \vec{e}_y defined previously)

Exercise 3)

$$C = R \left(\frac{1}{R_1} - \frac{1}{R_2} \right)^{-1} = \frac{k R_1 R_2}{R_2 - R_1} \checkmark$$

$$\begin{aligned} \textcircled{3} \quad 1) SC &= \frac{R_1 R_2}{R_2 - R_1} \delta k + \frac{k R_2 (R_2 - R_1) - k R_1 R_2 \times 1}{(R_2 - R_1)^2} \delta R_2 \\ &\quad + \frac{k R_1 (R_2 - R_1) - k R_1 R_2 \times 1}{(R_2 - R_1)^2} \delta R_2 \end{aligned}$$

$$SC = \frac{R_1 R_2}{R_2 - R_1} \delta k + \frac{k R_2^2}{(R_2 - R_1)^2} \delta R_1 - \frac{k R_1^2}{(R_2 - R_1)^2} \delta R_2$$

Hence (NA):

$$SC = \frac{1 \times 2 \times 10^{-3}}{2-1} + \frac{1 \times 2^2}{(2-1)^2} \delta R_1 - \frac{1 \times 1^2 \times 48 R_1}{(2-1)^2}$$

$$\delta C = 0,002 + 4\delta R_1 - 4\delta R_2 = 0,002 \quad \text{units?}$$

0,75

b)

$$② \Delta C = \left| \frac{R_1 R_2}{R_2 - R_1} \right| \Delta k + \left| \frac{k R_2^2}{(R_2 - R_1)^2} \right| \Delta R_1 + \left| \frac{k R_1^2}{(R_2 - R_1)^2} \right| \Delta R_2$$

Thus, (N.A.), we have:

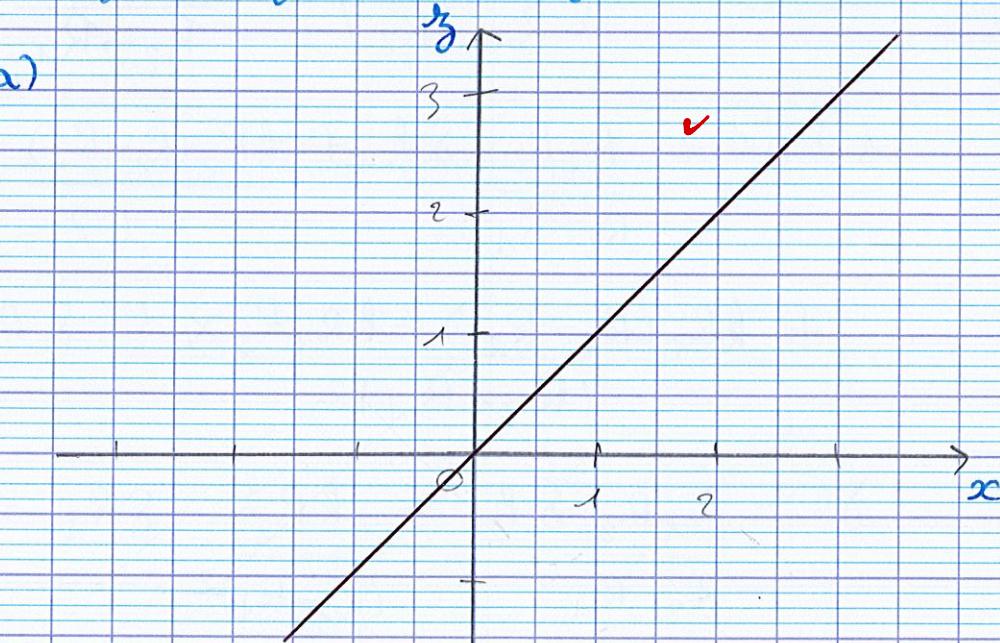
$$\Delta C = \left| \frac{1 \times 2}{2-1} \right| 10^{-3} + \left| \frac{1 \times 2^2}{(2-1)^2} \right| 10^{-3} + \left| \frac{1 \times 1^2}{(2-1)^2} \right| 10^{-3}$$

$$\Delta C = 2 \times 10^{-3} + 4 \times 10^{-3} + 1 \times 10^{-3}$$

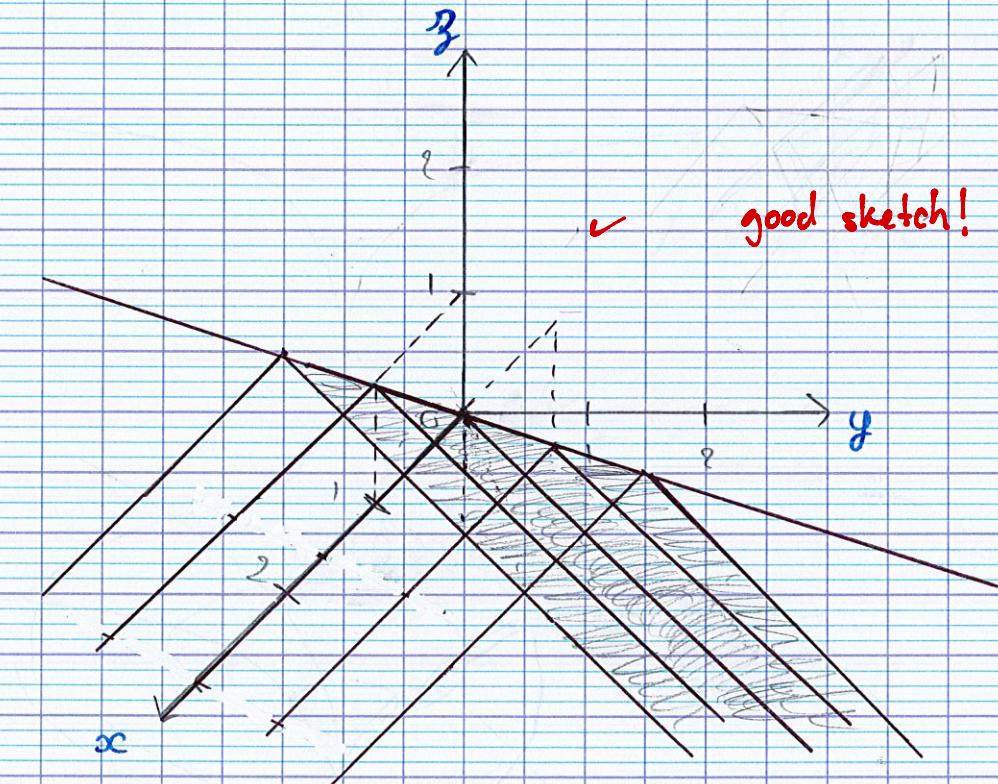
$$\Delta C = 0,007 \quad \text{units?}$$

Exercise 1) 1) $f_i: (x, y) \mapsto x - ly$

0,75 a)



1 c)



The shape can be seen as a "rug", descending when going in the negative x direction.