

# Assist Robot

Phase I

Project Report

**Project Team – 8**

*Team Members*

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## Table of Contents

Section	Description
<b>1</b>	Introduction
<b>2</b>	Project Goal and Objectives
<b>3</b>	Project Plan
	3.1 Schedule
	3.2 Project Timelines
	3.2.1 Team Members
	3.2.2 Tasks and Responsibilities
	3.3 Burndown Chart
<b>4</b>	First Increment Report
	4.1 Existing API
	4.2 Design of Features
	4.3 Implementation
	4.4 Deployment
<b>5</b>	Project Management
	5.1 Implementation Status Reports
<b>6</b>	Bibliography

## **1. Introduction:**

The main goal of the project is to help people in finding their misplaced objects. Basically humans have a tendency to forget their belongings somewhere in their house and search for it for hours together. For example, if I have an important business meeting to attend, but I don't remember where I placed my car keys, then I will be in huge loss. So to prevail in these circumstances here comes our Friendly Robot- My Friend which could assist me in keeping track of my personal things. So what this robot will do is that it will have entire map (laser scan) of the building and objects in the building in its memory. So we will feed the robot with the objects that are highly important to us, like car keys, some files, phone and laptop. This robot will keep its eye on these objects and notify their location to its master upon request.

## **2. Project Goal and Objectives:**

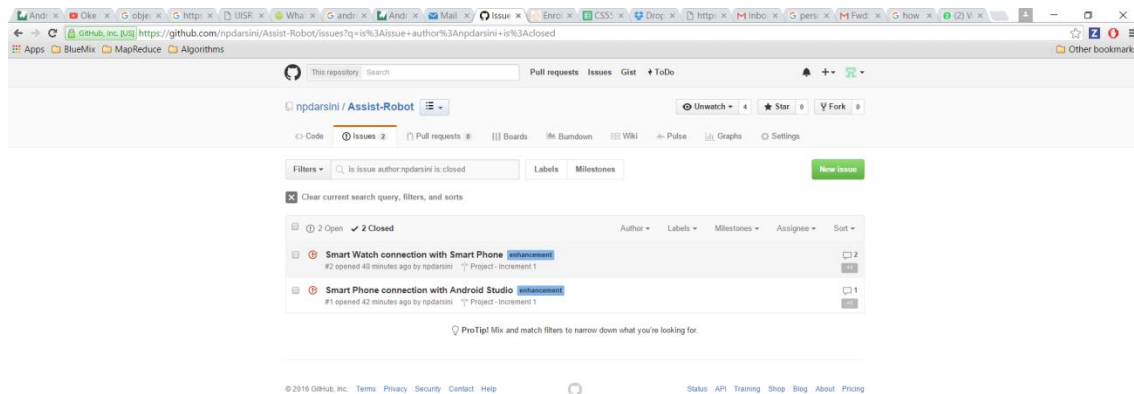
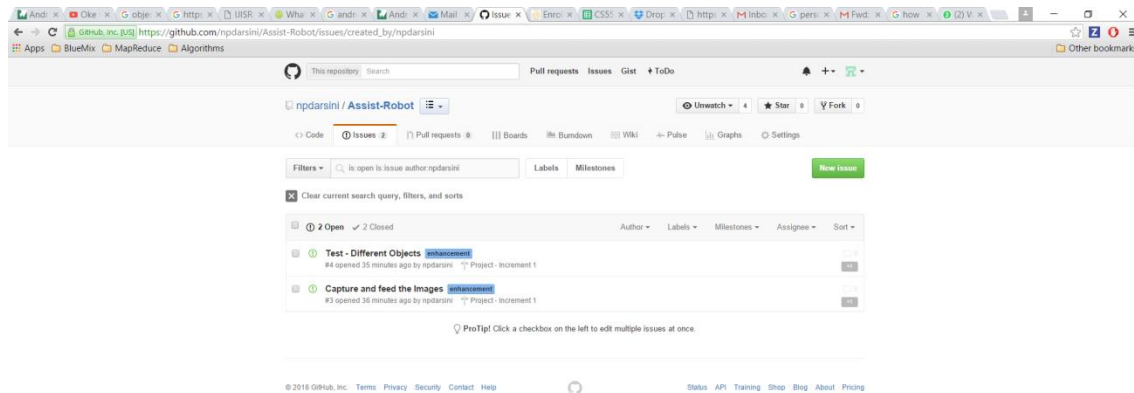
The primary goals of our project is described below:

- To implement a module which has an interaction with robot. Eg: You can ask few questions to the robot and the Robot will be responding to you back. You can ask the robot about your misplaced phone. So that it will answer you after it had found the phone.
- To make the robot learn about the personal items like laptops, phones, watch, keys etc.
- To design a robot which can find the learned objects that are misplaced in a building.
- To send a notification to your smart watch when it finds the lost object.
- To remind the user about his day to day events that were previously taught.
- To make the robot act as an assistant in getting things specified by the user. ( Mr Robot – Get me my phone).
- To make a single robot act as assistant to all the people living in same house. It recognizes the user first and then assists that particular user in finding the belongings.

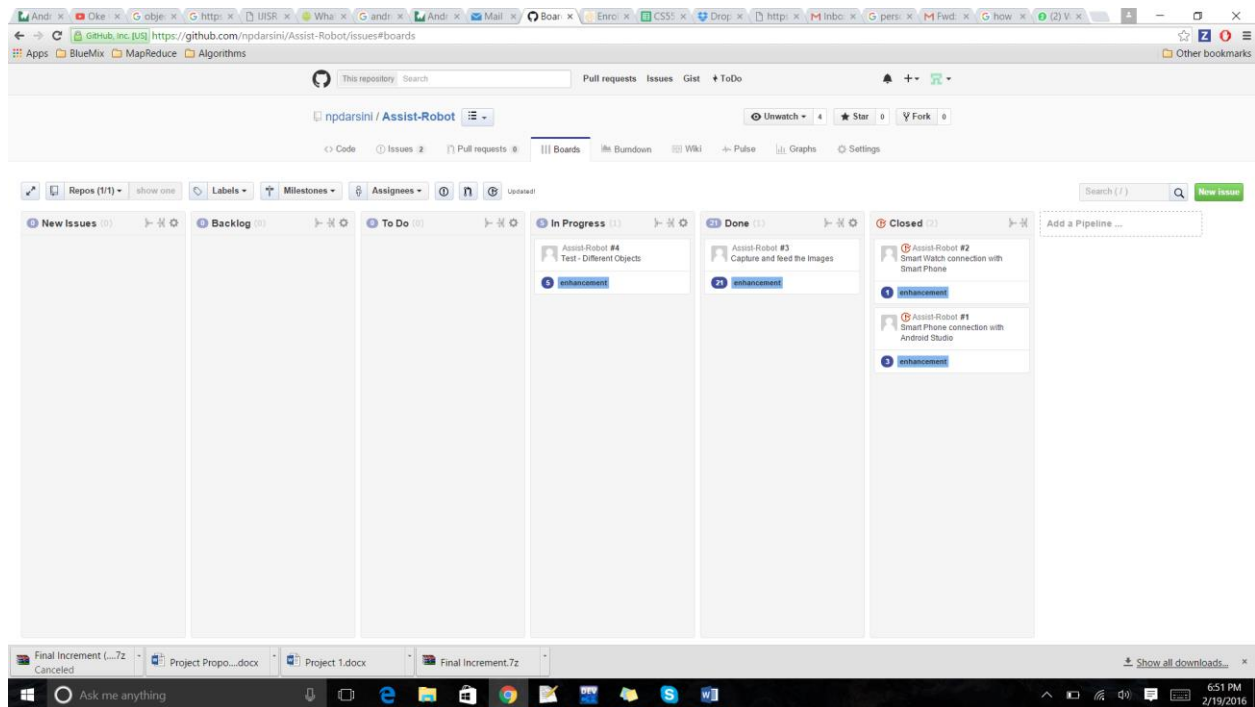
## 3. Project Plan:

### 3.1 Schedule:

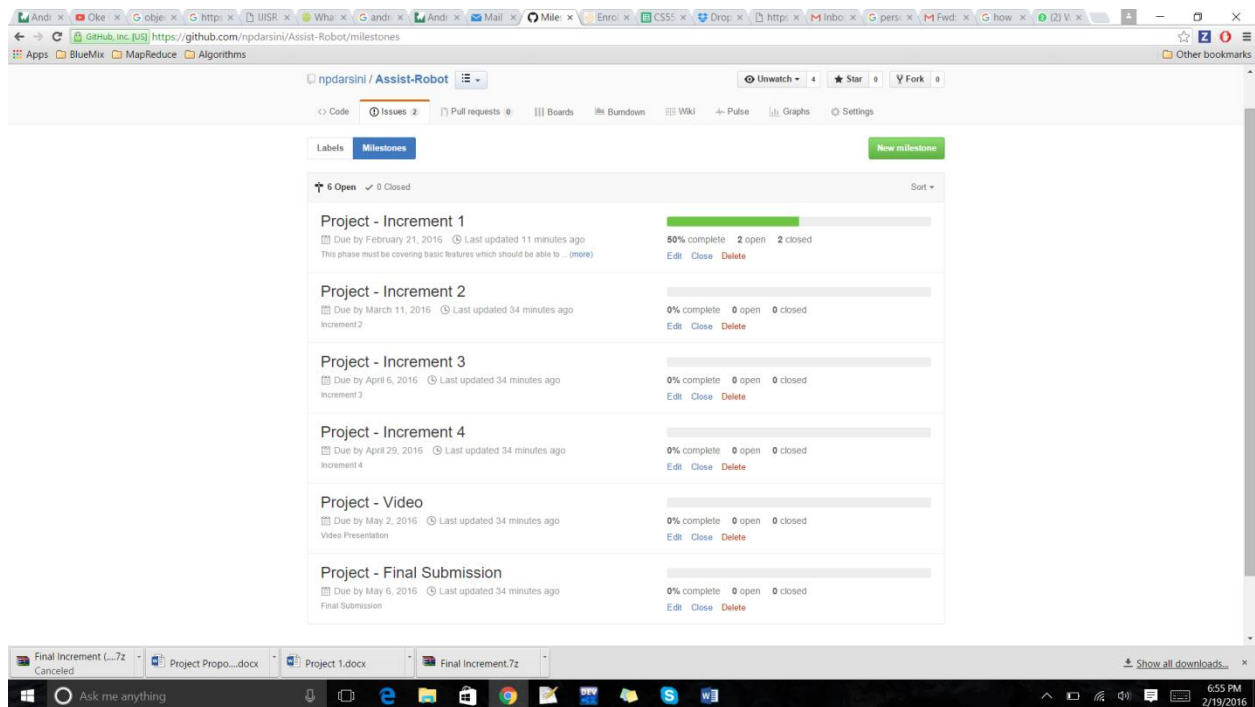
**Stories:** Four user stories had been created as part of Iteration 1. Here are the snapshots for the stories which are in closed and opened state.



## Board:

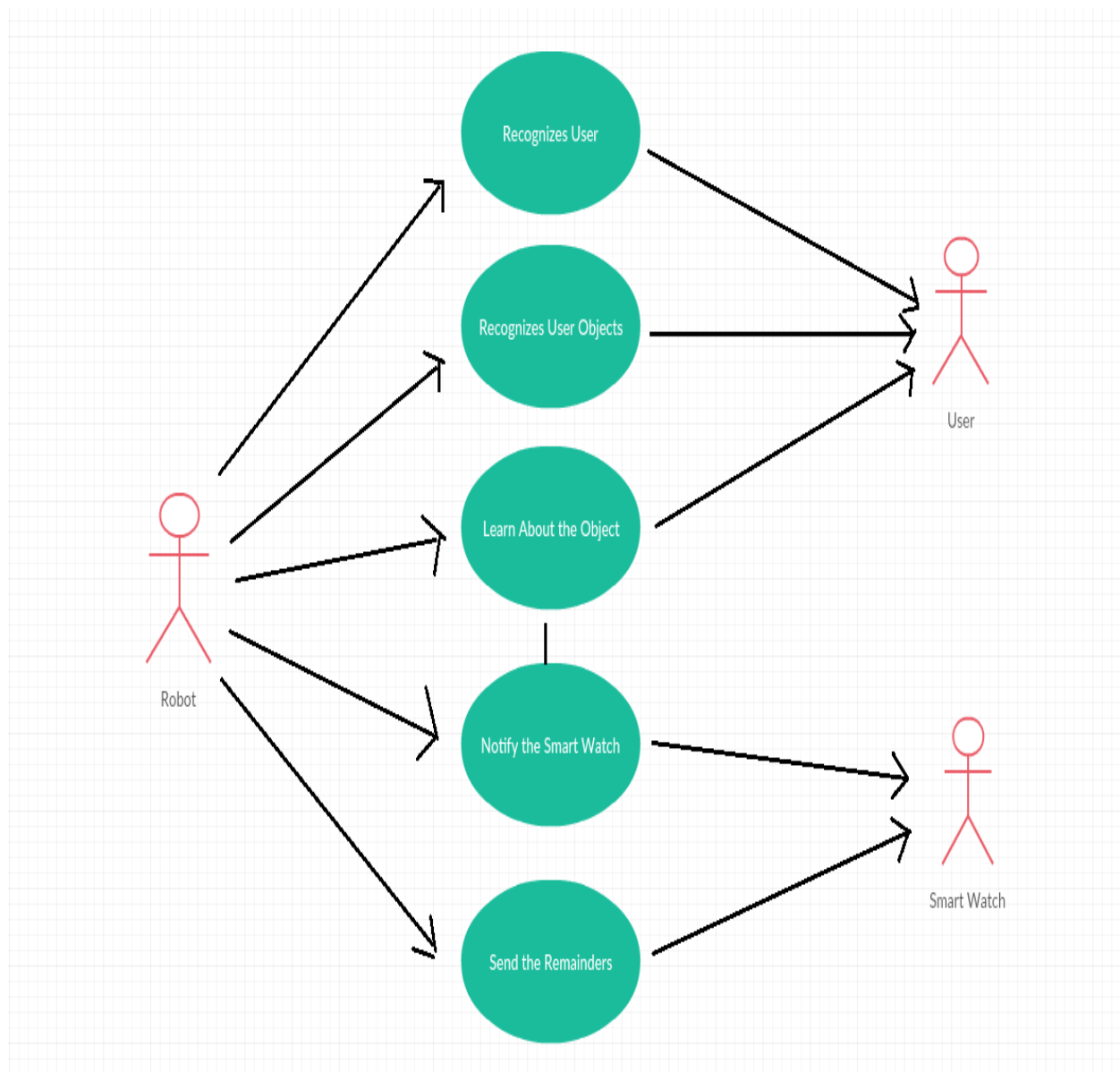


## Milestones:

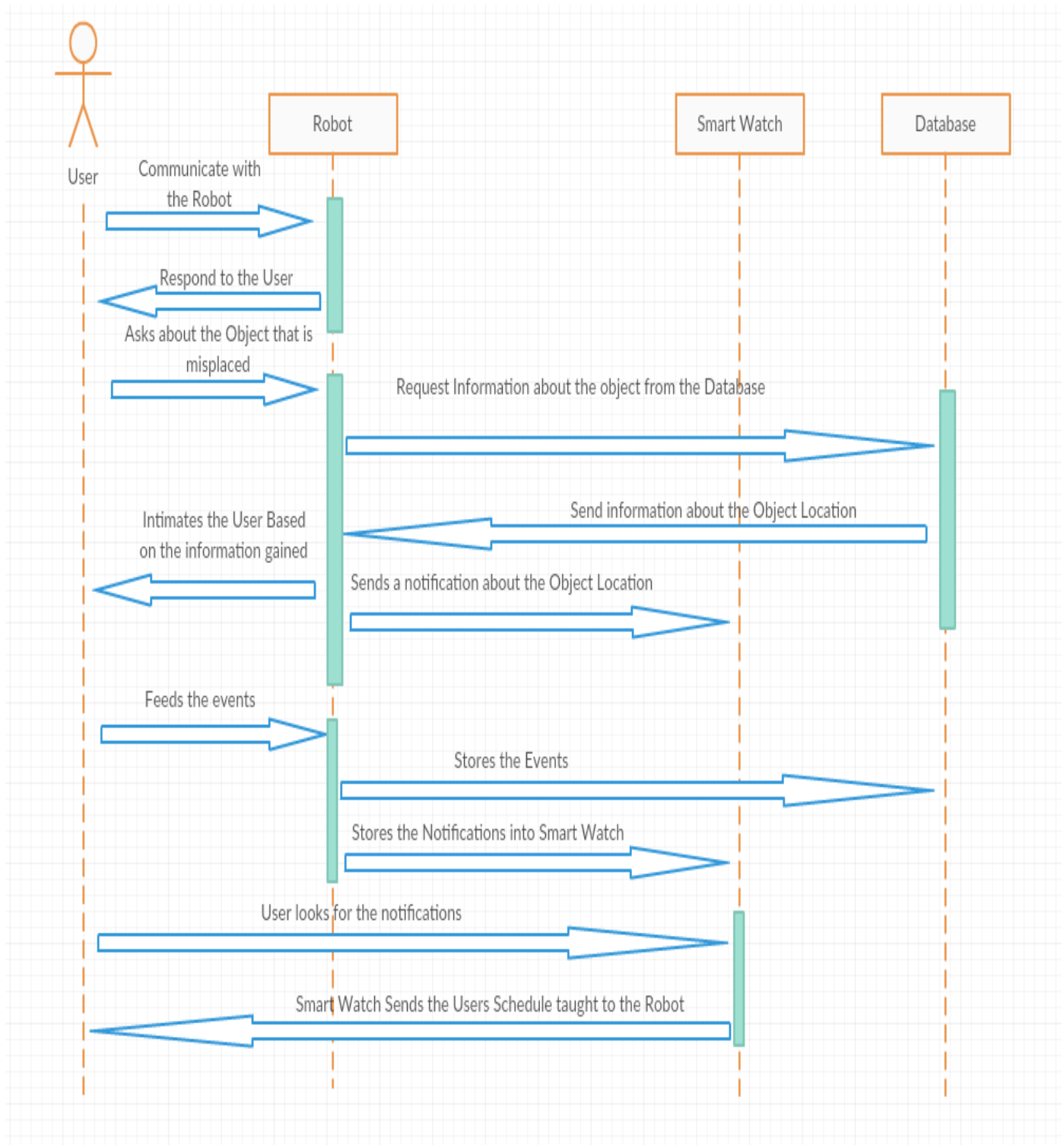


### 3.1.1 UML Diagrams:

#### Use Case Diagram



## Sequence Diagram:



### 3.2 Project Timelines:

Increment	Deadline
Increment 1	19 February 2015
Increment 2	11 March 2016
Increment 3	6 April 2016
Increment 4	29 April 2016
Final Submission	6 May 2016

#### 3.2.1 Team Members:

1. Priyadarsini Nidadavolu – 17
2. Deepthi Priyadarshini Penmetsa – 22
3. Dheeraja Vallabhaneni – 28
4. Tej Kumar Yentrapragada – 33

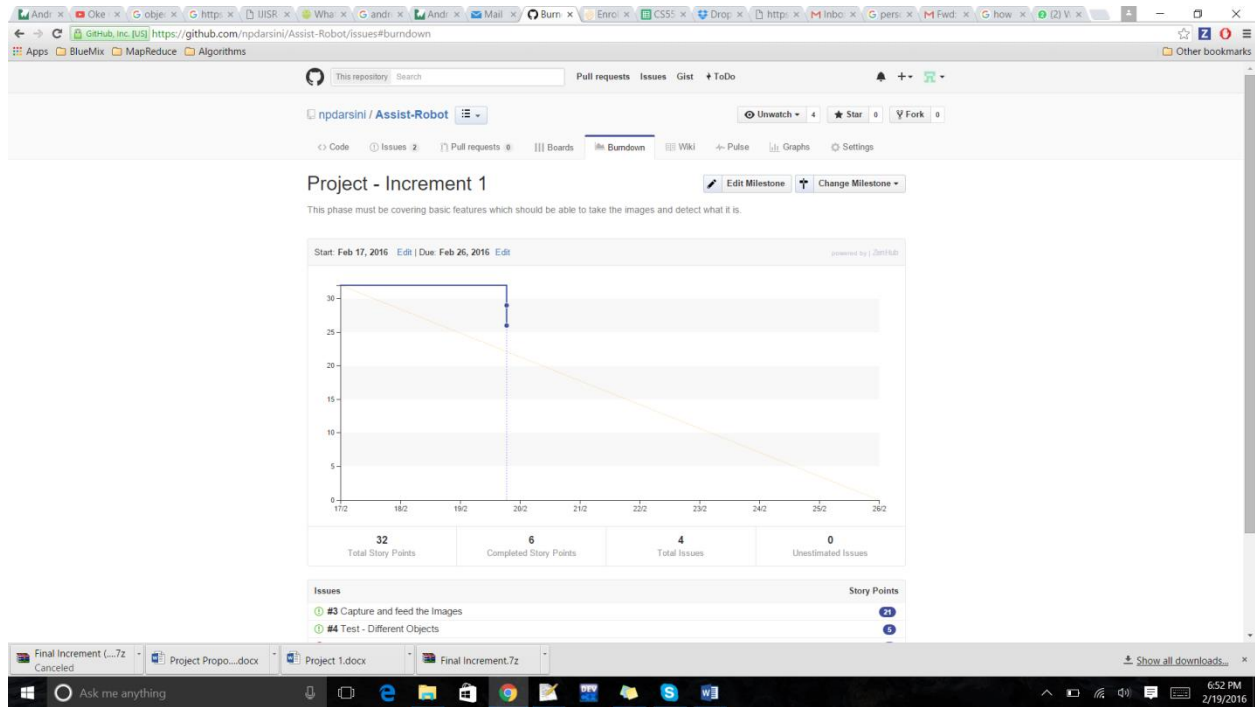
#### 3.2.2 Tasks and Responsibilities:

- **Machine Learning and R Programming** – Deepthi Priyadarshini Penmetsa
- **Spark and Hadoop Technologies** – Priyadarsini Nidadavolu
- **Objective C and IOS Programming** – Tej Kumar Yentrapragada
- **Android Programming** - Dheeraja Vallabhaneni



### 3.3 Burndown Chart:

#### Burndown:



### 4. First Increment Report

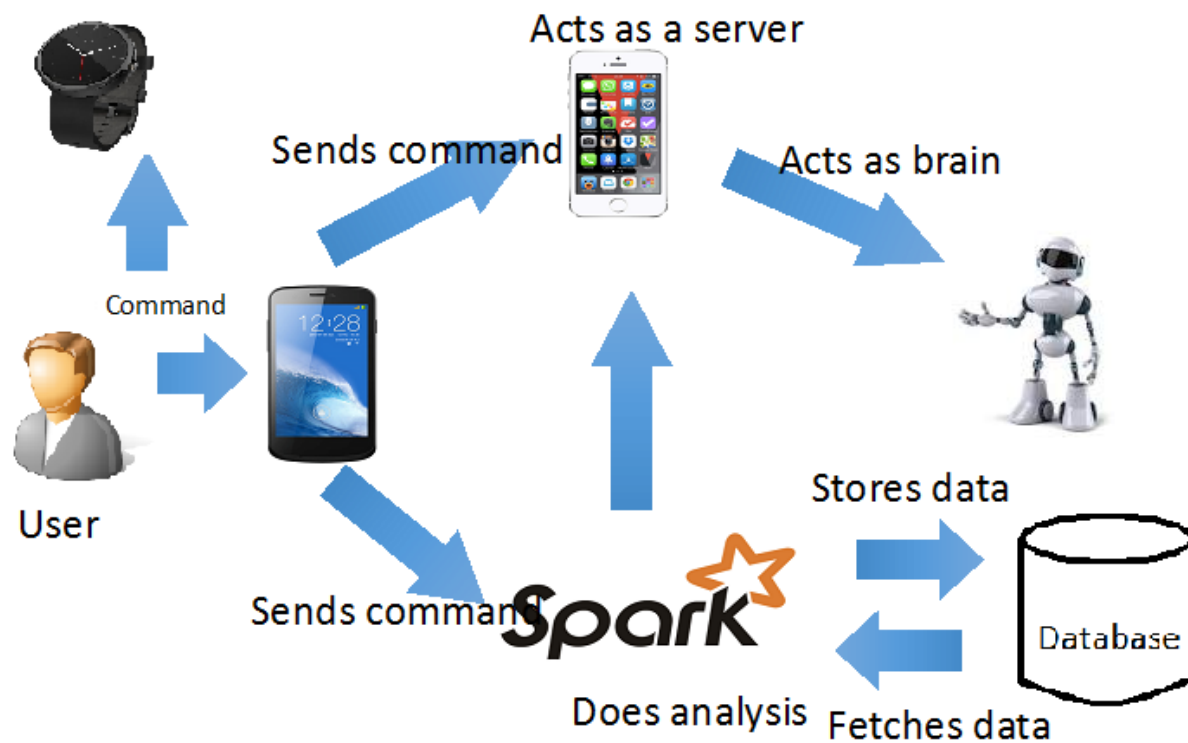
#### 4.1 Existing API:

##### IBM Alchemy API

This API basically performs machine learning and natural language processing techniques. Some of its features include semantic text analysis, sentimental analysis, deep learning, face detection and reorganization, speech to text and vice versa conversions etc. In this we had used this API in order to recognize the objects that we want to teach the Robot.

Achievements upon using this API – The Robot could identify basic objects like laptop, phone, bottle etc.

## 4.2 Design of Features:



The architecture of our system could be like the user can give commands to the client device which is android phone. Further the Iphone which acts as a server could take commands from the android phone and passes it to the Robot. The Robot performs the necessary actions of the received command and return back to the Android Phone. It also sends the notifications to the Android Smart Watch. The Android device can also pass the command to the Spark and fetch the data from the database (MongoDB, Hadoop DB).

### System Features

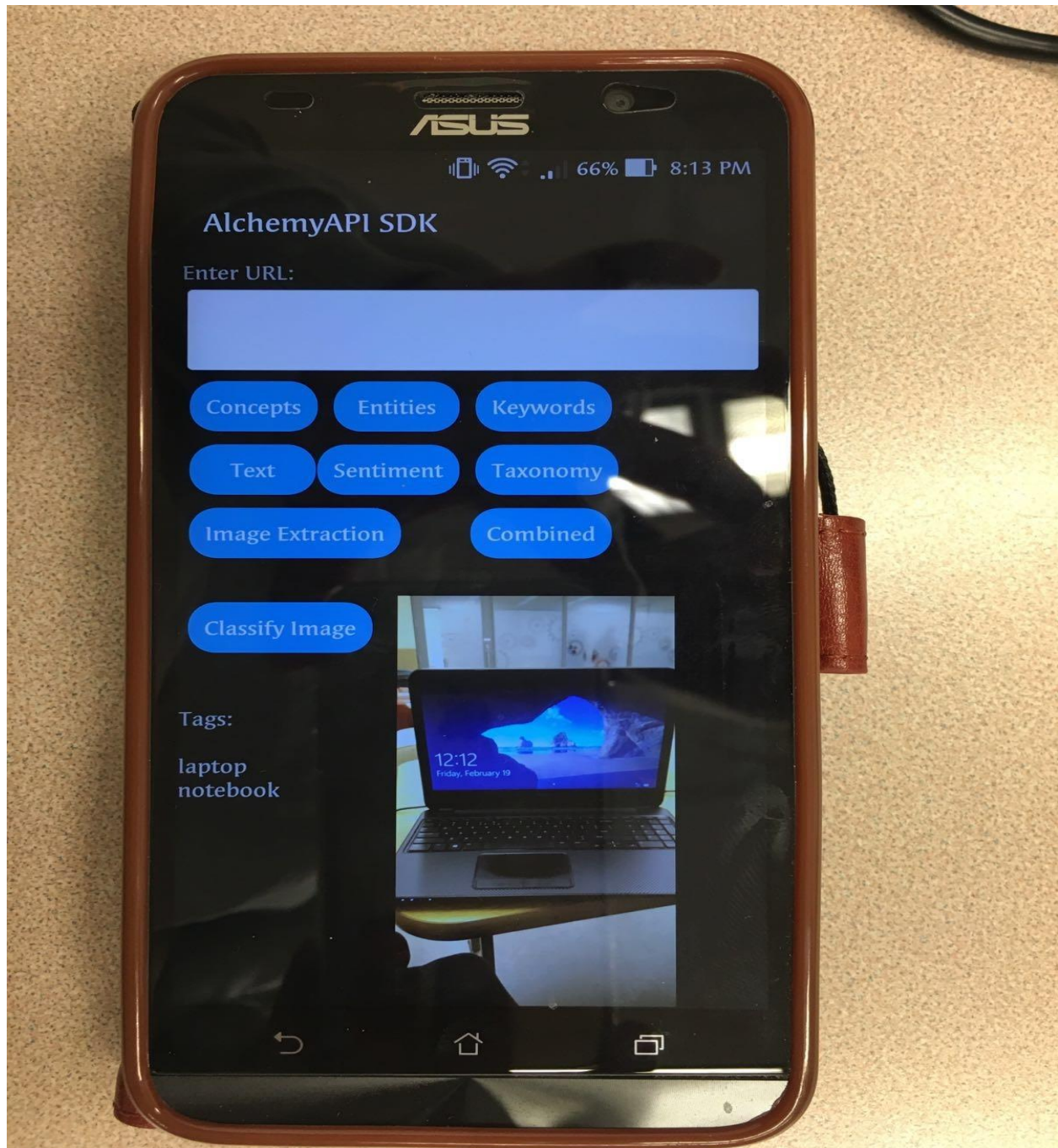
These are the following features we developed as part of this phase:

We had used IBM's Alchemy API and able to make our Robot to detect the object and return the object name as a result.

## 4.3 Implementation:

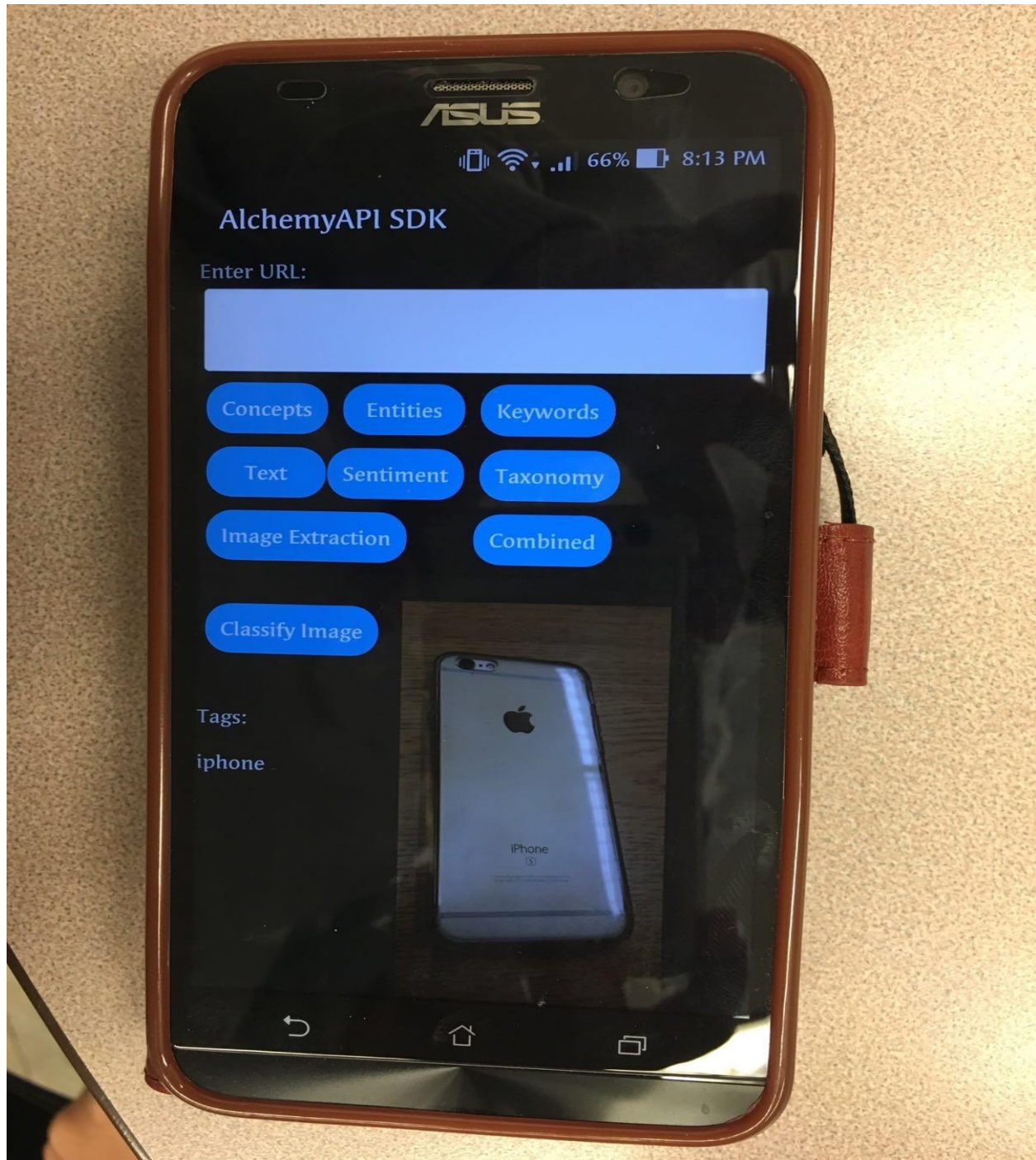
### Mobile Client Implementation – Snapshots

This snapshot shows us that the application is able to identify the object and names its Laptop.

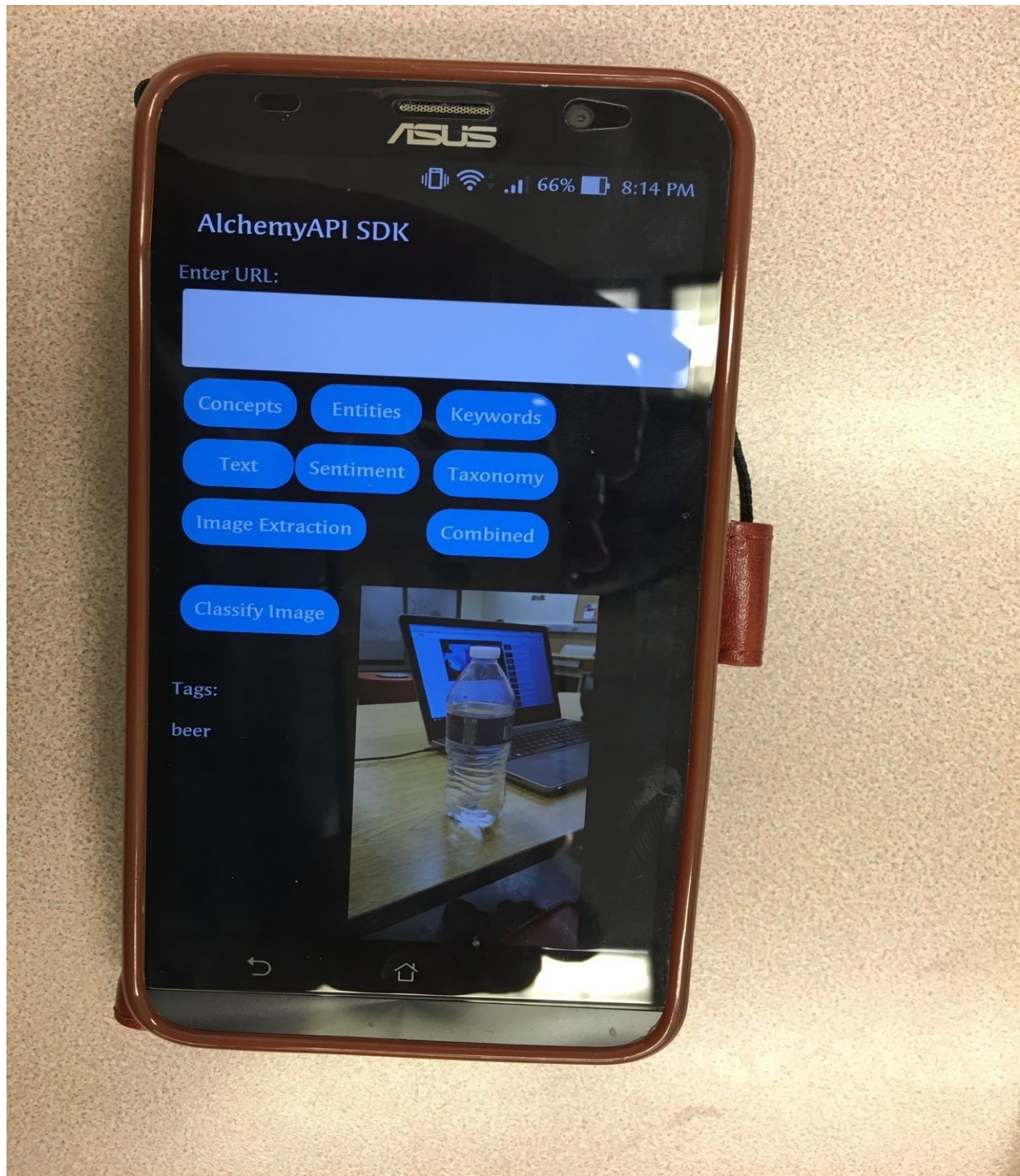




This snapshot shows us that the application is able to identify the object and names it as an Iphone.



This snapshot shows us that the application is able to identify the bottle.



## 4.4 Deployment:

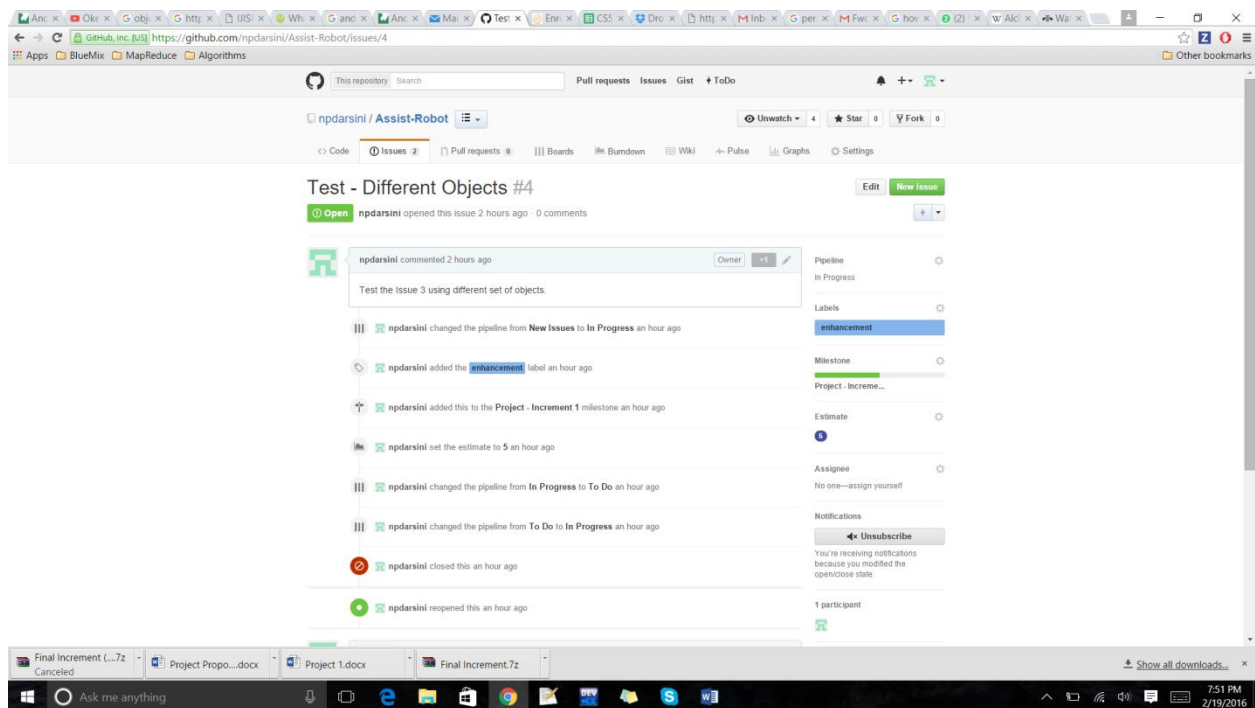
### Git Hub Link:

<https://github.com/npdarsini/Assist-Robot>

## 5. Project Management:

### 5.1 Implementation status report:

20% implementation has been implemented. This phase involves the basic object identification that is required for finding and location the objects. The team members has an equal contribution towards the development and it took around 2 complete days to give an outlook for this phase.



The screenshot displays a web browser window showing the GitHub repository page for `npdarsini/Assist-Robot`. The browser's address bar shows the URL `https://github.com/npdarsini/Assist-Robot/issues/4`. The repository page includes a search bar, navigation tabs for `Code`, `Issues` (selected), `Pull requests`, `Boards`, `Burndown`, `Wiki`, `Pulse`, `Graphs`, and `Settings`. The issue titled "Test - Different Objects #4" is open, with a green "Open" status indicator. The issue description states: "Test the issue 3 using different set of objects." The issue history shows several updates by user `npdarsini`, including changes to the pipeline (from `New Issues` to `In Progress` and `To Do`), adding labels (`enhancement`), and setting milestones (`Project - Increment 1`). The issue is currently assigned to `npdarsini` and has a status of `In Progress`. The right sidebar shows the issue's progress, including a progress bar, labels, milestones, and a list of participants. The bottom of the screen shows a Windows taskbar with various application icons and the system clock indicating 7:51 PM on 2/19/2016.



npdarsini / Assist-Robot

### Capture and feed the Images #3

npdarsini opened this issue 2 hours ago · 0 comments

npdarsini commented 2 hours ago

Capture the images of the objects that needs to be identified and ensure that your Robot is able to recognize them. Use IBM- Alchemy API.

npdarsini changed the pipeline from **New Issues** to **In Progress** an hour ago

npdarsini added the **enhancement** label an hour ago

npdarsini added this to the **Project - Increment 1** milestone an hour ago

npdarsini set the estimate to **21** an hour ago

npdarsini changed the pipeline from **In Progress** to **Done** an hour ago

npdarsini changed the pipeline from **Done** to **In Progress** an hour ago

npdarsini changed the pipeline from **In Progress** to **Done** an hour ago

Write Preview

Final Increment (...7z) Canceled

Project Propo...docx

Project 1.docx

Final Increment.7z

7:52 PM 2/19/2016

npdarsini / Assist-Robot

### Smart Watch connection with Smart Phone #2

npdarsini opened this issue 2 hours ago · 2 comments

npdarsini commented 2 hours ago

Connect the watch with any android phone using Android Wear through Bluetooth connectivity Service.

npdarsini changed the pipeline from **New Issues** to **In Progress** an hour ago

npdarsini added the **enhancement** label an hour ago

npdarsini added this to the **Project - Increment 1** milestone an hour ago

npdarsini set the estimate to **3** an hour ago

npdarsini self-assigned this an hour ago

npdarsini removed their assignment an hour ago

DheerajUnkc was assigned by npdarsini an hour ago

DheerajUnkc was unassigned by npdarsini an hour ago

npdarsini self-assigned this an hour ago

npdarsini commented an hour ago

Connecting with smart watch and android mobile

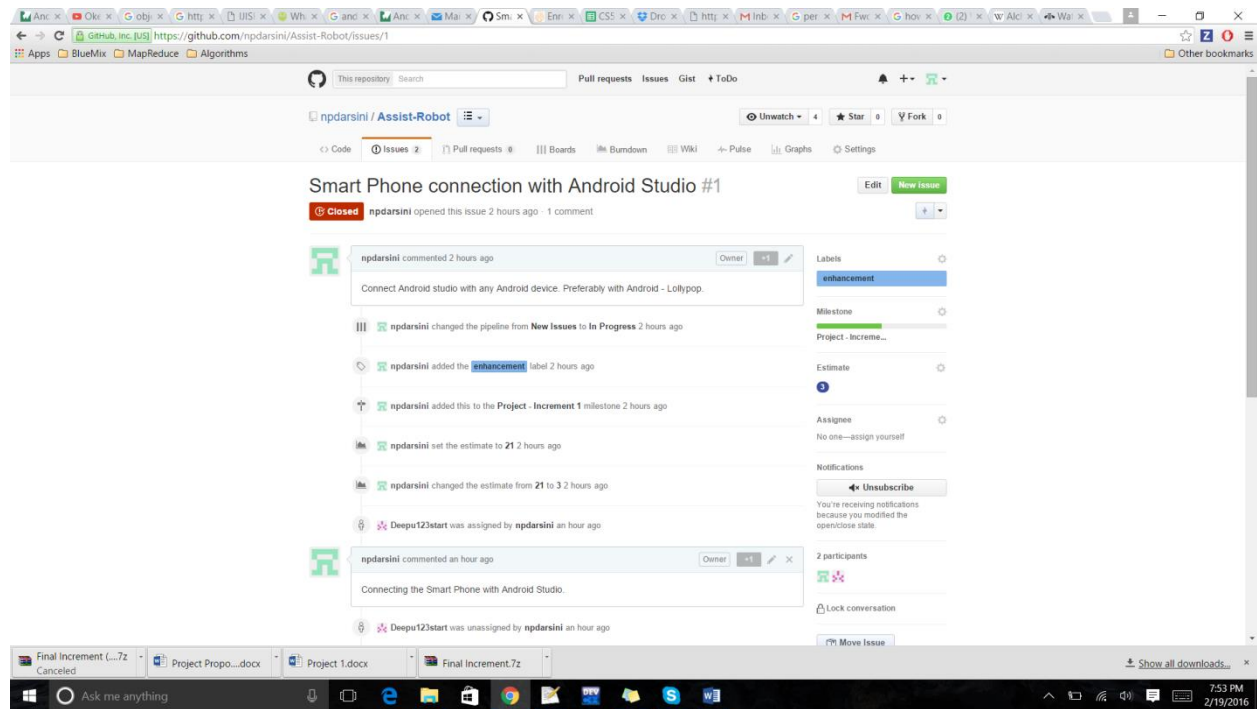
Final Increment (...7z) Canceled

Project Propo...docx

Project 1.docx

Final Increment.7z

7:52 PM 2/19/2016



## Bibliography:

Lab Tutorials and the material provided by Dr. Lee.