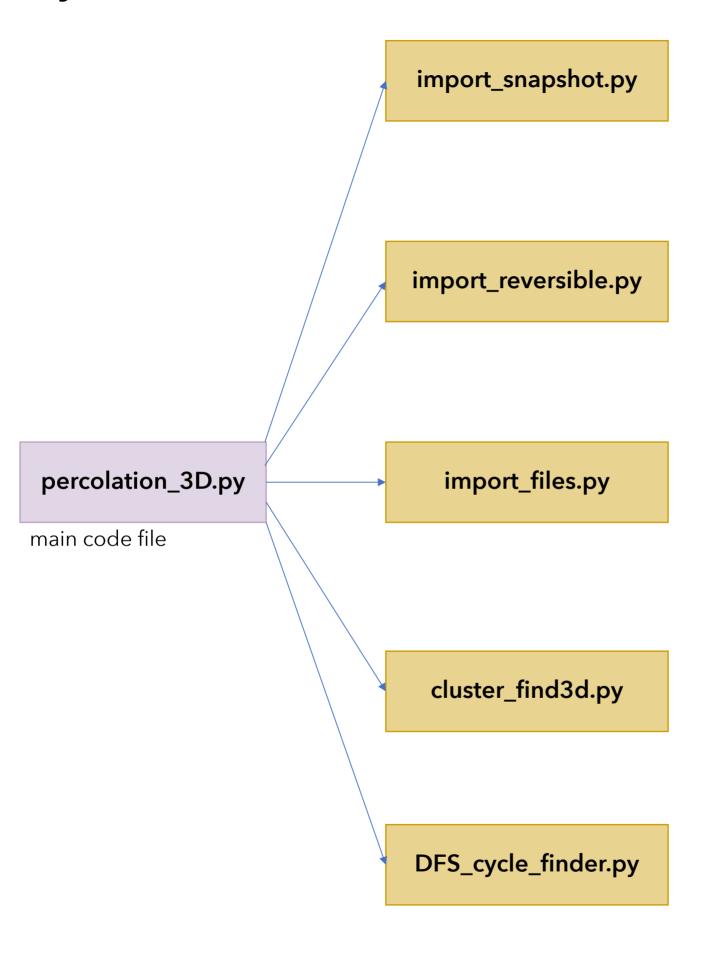
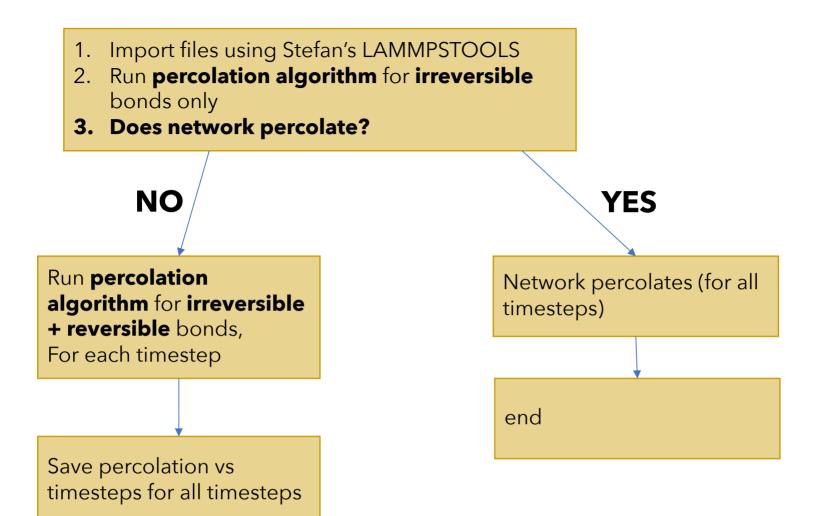
# Percolation algorithm

## Python files structure



## Steps (general)



### Steps: 1

- snapshot\_map (in import\_snapshot): makes a map from the endbead id to the star id; the resulting array is a [NatomsTot \* 1] array: the star\_id (-1) of a bead is found at i=bead\_id -1 in the array
- 2. map\_coordinates (in import\_files): function makes a map from the star id to its center coordinates (coordinates of the center bead of the star); the resulting array is a [Nstars \* 3] array: the position [x,y,z] of a star with star\_id=i is found at star\_coords[star\_id 1, :]
- 3. **store\_crosslinks1** (in **import\_files**): function makes an [N\_stars\*N\_stars] array where counter(0 or 1) c(i,j) shows if molecule i is bound to molecule j; **output**:
  - crosslinks [N\_stars\*N\_stars] array
  - crosslink\_boundaries [N\_stars\*N\_stars \* 3] array that shows, for each bond (i,j), whether it is bound across the [x,y,z] box boundaries (direction +1 or -1) \*uses crossings

crossings (in import\_files): function checks distance between the center coordinates of molcule I and j across each dimension (x,y,z) and outputs +/- 1 if their distance is > abs(boxsize/2)

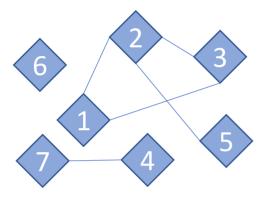
- 4. **drop** (in **cluster\_find3d**): function checks the crosslink\_boundaries array and makes a temporary crosslinks () array of ; **output**:
  - crosslink\_tmp [N\_stars\*N\_stars] array (crosslinks) where crosslinks across the boundaries have been removed
  - dropped\_list [N\_dropped\_bonds/2 \* 5] array that lists, for each dropped bond (i,j), whether it is bound across the [x,y,z] box boundaries (direction +1 or -1) [i, j, x, y, z]

no Dropped bonds? yes

### Steps: neighbours/clusters

number of arms (maximum bonds per star)

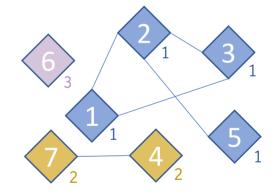
5. **store\_neighbours** (in **cluster\_find3d**): using the crosslinks (or crosslinks\_tmp) info, makes an array with a list of neighbours for every star (see example)



star ID	bound star ID (1)	bound star ID (2)	bound star ID ()	bound star ID (max)
1	2	3	-1	-1
2	1	3	5	-1
3	1	2	-1	-1
4	7	-1	-1	-1
5	2	-1	-1	-1
6	-1	-1	-1	-1
7	4	-1	-1	-1

#### \*colouring algorithm:

- 6. cluster\_find (in cluster\_find3d): function makes an [N\_stars] array where each star i is assigned a colorID; output:
  - list\_color, Ncolors \*uses coloring



coloring (in import\_files): recursive function, assigns
the same colorID to stars that are connected (i.e.
part of the same cluster)

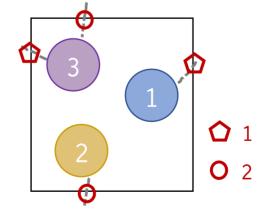
#### Steps: neighbours/clusters

\*reintroduce dropped bonds, make neighbours list:

- 7. **molid\_to\_clusterid** (in **cluster\_find3d**): uses list\_color to change the starID in dropped\_list (see 4.) to clusterID (i.e. color); returns dropped\_list
- 8. **neighbour\_clusters** (in **cluster\_find3d**): similar to 5., uses dropped\_list to form a neighbour list of clusters connected across the boundaries; ; **output**:
  - Cneighbors [Nclusters \* max\_links] array with a list of neighbours for every cluster
  - Ccrossings [Nclusters \* max\_links \* 3] array that shows across what [x,y,z] box boundaries (direction +1 or -1) each "bond" is, for each "bond" between two clusters i and j([x,y,z] crossing is found at position [i,j] in the array)
  - edges\_list [Nclusters \* max\_links] array, same shape as Cneighbors, but contains the id of the linkers (edges) between clusters (across the boundary)

#### Cneighbors

cluster ID	bound cluster ID (1)	bound cluster ID (2)	bound cluster ID (max)
1	3	-1	-1
2	3	-1	-1
3	1	2	-1



#### Ccrossings

cluster ID	bound cluster ID (1)	bound cluster ID (2)	bound cluster ID (max)
1	[1, 0]	[0,0]	[0,0]
2	[0,-1]	[0,0]	[0,0]
3	[-1, 0]	[0,1]	[0,0]

edges\_list

cluster ID	link ID (1)	link ID (2)	link ID (max)
1	1	-1	-1
2	2	-1	-1
3	1	2	-1

## Steps: DFS algorithm

- 9. launch\_dfs (in DFS\_cycle\_finder):
  - clusters=nodes, linkers=edges
    - i. initialises "blank" (everything set to -1) arrays:visited\_nodes (length:Nclusters) and visited\_edges(length: number of edges)
    - ii. for all nodes in range Nclusters, checks if node was already visited:
      - > YES: skip, next node
      - NO: proceed:
        - crossing\_sum = [[0,0,0]] every time I start visiting a new network (that has never been visited before), I set the sum of crossings to 0 (this is a counter of how many times I'm crossing the boundaries and in which dimension and direction, as I go through the search)
        - Also set to 0: current\_crossing, loops\_temp (temporary list of loops found in the current network), discovery\_timeC (counter for when the cluster/node was "discovered"/touched), discovery\_timeE (counter for when the an edge was "discovered"/touched),
        - START dfs function (recursive) ends at the end of the tree
        - dfs updates
          - loops,discovery\_timeC,discovery\_timeE
        - update discovery\_timeC, add +1
        - END: use linearly\_independent (in DFS\_cycle\_finder) to get the number of independent loops

dfs (in DFS\_cycle\_finder) - see code

- 10. **launch\_dfs** returns the number of independent loops; does the network percolate in 3 independent directions?
  - YES: percolation!
  - ➤ NO: no percolation > add REVERSIBLE and check percolation for each timestep



#### Extra: reversible bonds

- 1. combine ends\_to\_star mas for reversible and irreversible ends
- 2. **synchro** (in **import\_files**): synchronize timesteps of all files
- 3. find desired timestep
- 4. **import\_rev** (in **import\_reversible**): make list of end\_beads ID that are bound (extracted from the "revBonds\_count" file from LAMMPS) > output: reversible\_bonds, bound
- 5. map\_coords (in import\_reversible): makes a map from the bead id to its center coordinates
- 6. make\_revbondlist (in reversible\_bonds): makes list of bonds by checking distance between all endbeads in revList (uses make\_revbondlist (in reversible\_bonds) )
- 7. make total list for reversible + irreversible bonds
- 8. same as for irreversible bonds, check percolation