

DataAccess::body



```
graph LR; A[DataAccess::body] --> B[arch::ROSCComponentDescriptor::getFreq]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'DataAccess::body'. The right box is white with a black border and contains the text 'arch::ROSCComponentDescriptor::getFreq' on two lines. A blue arrow points from the right side of the left box to the left side of the right box.

arch::ROSCComponentDescriptor
::getFreq