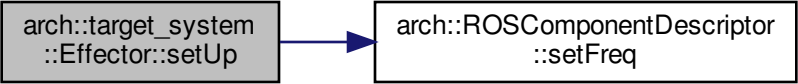


arch::target\_system  
::Effector::setUp



```
graph LR; A["arch::target_system::Effector::setUp"] --> B["arch::ROSCoordinateDescriptor::setFreq"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box has a light gray background and a black border, containing the text 'arch::target\_system' on the top line and '::Effector::setUp' on the bottom line. The right box has a white background and a black border, containing the text 'arch::ROSCoordinateDescriptor' on the top line and '::setFreq' on the bottom line. A blue arrow points from the right side of the left box to the left side of the right box.

arch::ROSCoordinateDescriptor  
::setFreq