

archlib/include/archlib  
/ROSComponentDescriptor.hpp

```
graph TD; A["archlib/include/archlib  
/ROSComponentDescriptor.hpp"] --> B["string"]; A --> C["ros/ros.h"]
```

The diagram illustrates the dependencies of the header file `archlib/include/archlib/ROSComponentDescriptor.hpp`. Two blue arrows originate from the bottom of the top box and point to two separate boxes below: `string` on the left and `ros/ros.h` on the right.

string

ros/ros.h