```
arch::ROSComponent
# rosComponentDescriptor
+ ROSComponent()
+ ~ROSComponent()
+ setUp()
+ tearDown()
+ run()
+ body()
# getRosNodeName()
         Enactor
   + Enactor()
   + ~Enactor()
   + setUp()
   + tearDown()
   + body()
   + receiveStatus()
   + receiveEvent()
   + receiveStrategy()
   + sendInfo()
   + apply strategy()
   + print()
```