```
arch::ROSComponent
# rosComponentDescriptor
+ ROSComponent()
+ ~ROSComponent()
+ setUp()
+ tearDown()
+ run()
+ body()
# getRosNodeName()
         Engine
  + Engine()
   + ~Engine()
  + setUp()
  + tearDown()
  + body()
  + receiveException()
  + monitor()
  + analyze()
  + plan()
  + execute()
```