arch::ROSComponentDescriptor + ROSComponentDescriptor() + ~ROSComponentDescriptor() + setName() + getName() + setFreq() + getFreq() #rosComponentDescriptor arch::ROSComponent + ROSComponent() + ~ROSComponent() + setUp() + tearDown() + run() + body() # getRosNodeName() Enactor + Enactor() + ~Enactor() + setUp() + tearDown() + body() + receiveStatus() + receiveEvent() + receiveStrategy() + sendInfo() + apply_strategy() + print()