

1. Producer1 running & semaphore changes

According to .map file, the address of _Producer1 is 0014, so I set a breakpoint there. Red block corresponds to the variable initialization $ch='A'$, and blue block is the assembly code of SemaphoreWaitBody and decrease Semaphore 'empty' ($addr = 22H$) by 1

Version 2.1.32 & Dynamic Interface x | test3threads.hex

System Clock (MHz): 11.0592 | 1000 | Update Freq

SBUS: R/O W/O TH0 TL0 R7: 0x08 B: 0x00
 RXD TXD TMOD: 0x20 R6: 0x00 ACC: 0x00
 SCON: 0x50 TCON: 0xD0 R5: 0x00 PSW: 0x10
 pins bits TH1 TL1 PC: 0x0014 PSW: 0 0 0 1 0 0 0 0
 0xFF 0xFF P2: 0xFF 0xFF P1: 0xFF 0xFF P0: 0xFF 0xFF

Modify RAM: addr: 0x00 value: 0x00

Data Memory:

0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
00	30	31	00	01	03	01	00	00	31	32	00	00	07	00	04
10	32	30	00	00	07	00	00	08	00	00	00	00	00	00	00
20	01	01	02	30	00	01	00	48	31	00	00	00	00	00	00
30	46	56	66	00	02	07	02	20	00	00	00	00	51	52	
40	4B	00	00	00	02	00	00	00	00	00	00	00	00	00	00
50	98	00	31	00	00	09	00	00	00	00	00	00	00	00	00
60	14	00	00	00	00	10	00	00	00	00	00	00	00	00	00
70	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00

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Assembly Code:

```

ORG 0000H
0000: LJMP 011BH
0003: RETI
ORG 000BH
000B: LJMP 0122H
000E: LJMP 00DDH
0011: LJMP 000EH
0014*: MOV 28H, #41H
0017: MOV A, 22H
0019: JZ 0FCH
001B: JB 0E7H, 0F9H
001E: DEC 22H
0020: CLR 0AFH
0022: MOV A, 20H
0024: JZ 0FCH
0026: JB 0E7H, 0F9H
0029: DEC 20H
002B: MOV A, 26H
002D: ADD A, #23H
  
```

I/O Map:

- P0.7: Display-select Decoder CS/DAC WR
- P0.6: Keypad Column 2
- P0.5: Keypad Column 1
- P0.4: Keypad Column 0
- P0.3: Keypad Row 3
- P0.2: Keypad Row 2
- P0.1: Keypad Row 1
- P0.0: Keypad Row 0
- P1.7: LED 7/Seg. d1/DAC DB7/LCD DB7
- P1.6: LED 6/Seg. d1/DAC DB6/LCD DB6
- P1.5: LED 5/Seg. d1/DAC DB5/LCD DB5
- P1.4: LED 4/Seg. d1/DAC DB4/LCD DB4
- P1.3: LED 3/Seg. d1/DAC DB3/LCD DB3
- P1.2: LED 2/Seg. d1/DAC DB2/LCD DB2
- P1.1: LED 1/Seg. d1/DAC DB1/LCD DB1
- P1.0: LED 0/Seg. d1/DAC DB0/LCD DB0
- P2.7: SW 7/ADC DB7
- P2.6: SW 6/ADC DB6
- P2.5: SW 5/ADC DB5
- P2.4: SW 4/ADC DB4
- P2.3: SW 3/ADC DB3
- P2.2: SW 2/ADC DB2
- P2.1: SW 1/ADC DB1
- P2.0: SW 0/ADC DB0
- P3.7: ADC RD/Comparator Output
- P3.6: ADC WR
- P3.5: Motor Sensor
- P3.4: Display-select Input 1
- P3.3: AND Gate Output/Display-select Input 0
- P3.2: ADC INTR
- P3.1: Motor Control Bit 1/Ext. UART Rx
- P3.0: Motor Control Bit 0/Ext. UART Tx

Hardware Components:

- DI, LD, AND Gate Enabled, Key Bounce Enabled, Pulse, Rx, Tx, Scope, DAC, ADC, Motor Enabled

2. Producer2 running & semaphore changes

According to .map file, the address of _Producer2 is 0057, so I set a breakpoint there. Red block corresponds to the variable initialization $num='0'$, and blue block is the assembly code of SemaphoreWaitBody and decrease Semaphore 'empty' ($addr = 22H$) by 1

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3. Consumer running & semaphore changes

According to .map file, the address of _Consumer is 009A, so I set a breakpoint there. Red block corresponds to the initialization of TMOD, TH1..., and blue block is the assembly code of SemaphoreWaitBody and decrease Semaphore 'full'(addr = 21H) by 1

Version 2.1.32 & Dynamic Interface x | test3threads.hex

4. Before: Unfair version

If Producer1 is spawned before Producer2, then UART would only output characters(as shown below)

The screenshot shows the EdSim51DI v2.1.32 interface. The assembly window displays the following instructions:

```

ORG 0000H
0000H  LJMP 0143H
0003H  RETI
ORG 000BH
000BH  LJMP 014AH
000EH  LJMP 00FEH
0011H  LJMP 000EH
0014H  MOV 28H,#41H
0017H  MOV A,22H
0019H  JZ 0FCH
001BH  JB 0E7H,0F9H
001EH  DEC 22H
0020H  MOV R7,#01H
0022H  JBC 0AFH,02H
0025H  MOV R7,#00H
0027H  MOV A,20H
0029H  JZ 0FCH
002BH  JB 0E7H,0F9H
002EH  DEC 20H
  
```

The UART window shows the output 'ABCDEFHIJKLMNOPQRS'. The DAC window shows the output '0.0 V'. The scope window shows a square wave. The motor window shows 'Motor Enabled'.

If Producer2 is spawned before Producer1, then UART would only output numbers(as shown below)

The screenshot shows the EdSim51DI v2.1.32 interface. The assembly window displays the following instructions:

```

ORG 0000H
0000H  LJMP 0143H
0003H  RETI
ORG 000BH
000BH  LJMP 014AH
000EH  LJMP 00FEH
0011H  LJMP 000EH
0014H  MOV 28H,#41H
0017H  MOV A,22H
0019H  JZ 0FCH
001BH  JB 0E7H,0F9H
001EH  DEC 22H
0020H  MOV R7,#01H
0022H  JBC 0AFH,02H
0025H  MOV R7,#00H
0027H  MOV A,20H
0029H  JZ 0FCH
002BH  JB 0E7H,0F9H
002EH  DEC 20H
  
```

The UART window shows the output '012345678901234567890'. The DAC window shows the output '0.0 V'. The scope window shows a square wave. The motor window shows 'Motor Enabled'.

5. After: fair version & Fairness

I add an explicit `ThreadYield()` at the end of `Producer1` and `2` to force real round-robin, so that after each producer went through 1 iteration, it will switch to the other thread by calling `ThreadYield()` explicitly. The screenshot below take `Producer1` as example(`Producer2` the same).

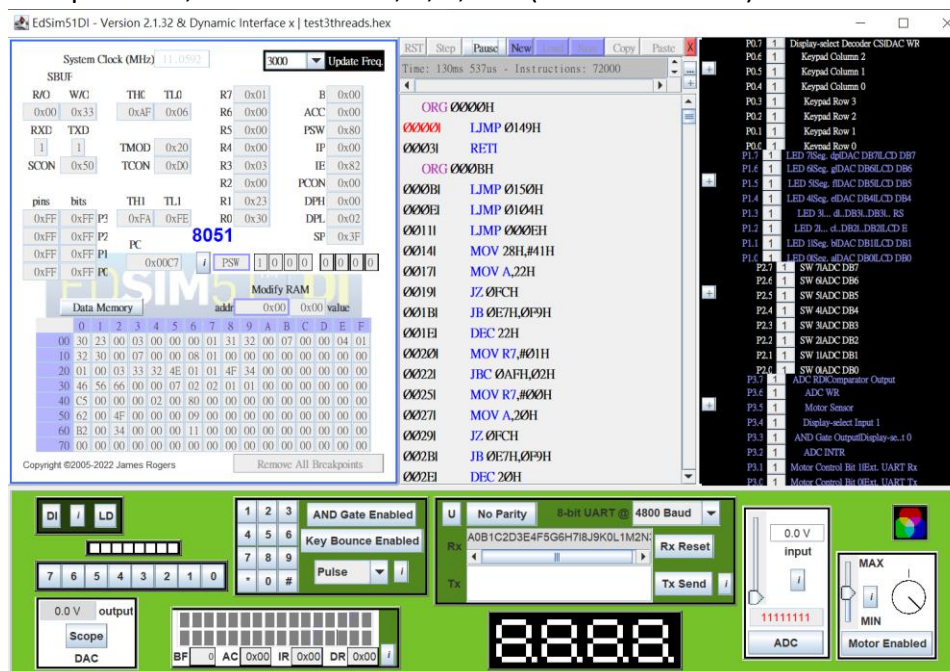
```
void Producer1(void){
    ch = 'A';
    while(1){
        SemaphoreWait(empty);

        EA=0;
        SemaphoreWait(mutex);
        buf[head] = ch;

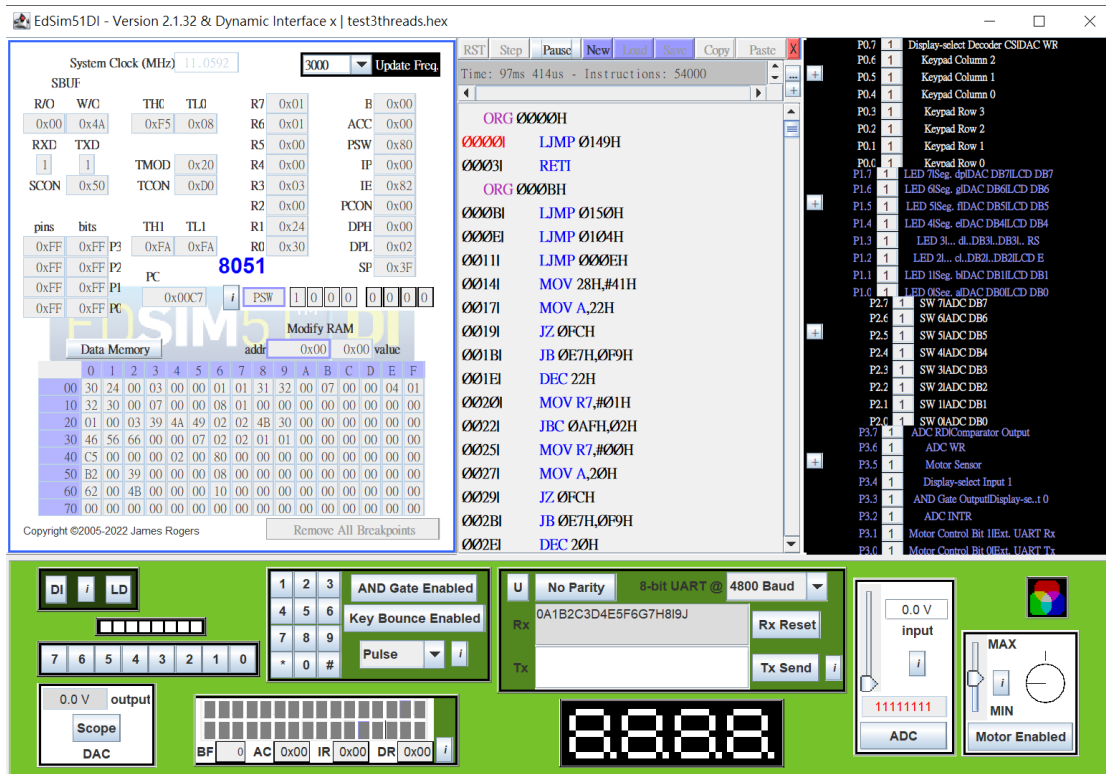
        head++;
        if(head == 3){
            head = 0;
        }
        SemaphoreSignal(mutex);
        EA=1;

        SemaphoreSignal(full);
        if(ch == 'Z'){
            ch = 'A';
        }else{
            ch += 1;
        }
        ThreadYield();
    }
}
```

If `Producer1` is spawned first in `main`, then the first character of UART output will be alphabet a, then number 0, b, 1,...etc(as shown below)



If Producer2 is spawned first in main, then the first character of UART output will be number 0, then alphabet a, 1, b,...etc(as shown below)



6. Typscript and screenshots

```
daneil@MS-DanielNB:/mnt/d/Profile/Daniel/OneDrive/桌面/OS Project/Checkpoint 4$ make clean
rm *.hex *.ihx *.lnk *.lst *.map *.mem *.rel *.rst *.sym
rm: cannot remove '*.ihx': No such file or directory
rm: cannot remove '*.lnk': No such file or directory
make: *** [Makefile:25: clean] Error 1
daneil@MS-DanielNB:/mnt/d/Profile/Daniel/OneDrive/桌面/OS Project/Checkpoint 4$ make
sdcc -c test3threads.c
test3threads.c:67: warning 158: overflow in implicit constant conversion
sdcc -c preemptive.c
preemptive.c:82: warning 85: in function ThreadCreate unreferenced function argument : 'fp'
sdcc -o test3threads.hex test3threads.rel preemptive.rel
```