

Digital Twin enabled Integrated Multiplatform Automation System For Industrial Assembly And Automated Storage And Retrieval System

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Problem statement

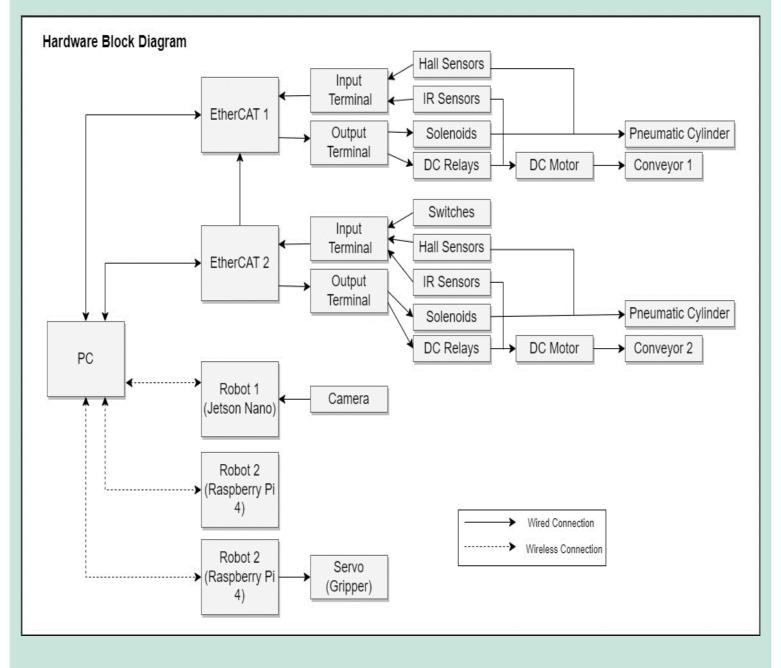
Develop an Integrated Multi-Platform Automation System that makes use of digital twinning, robotics, and computer vision to meet the demands of manufacturing customization, optimize material flow, guarantee error-free assembly, and boost operational effectiveness. Using real-time monitoring and user-friendly interfaces to revolutionize industrial automation and establish new benchmarks for accuracy, flexibility, and quality control.

Objectives

- 1) Implement strict quality control procedures in place to ensure that the products are faultless and satisfy both client and industry standards.
- 2) To ensure smooth operation and interaction, incorporate a variety of technologies, such as digital twinning, robotics, and machine learning into an unified system.
- 3) Prioritize the needs of the customer by providing products that meet their needs exactly. This will increase brand loyalty and competitiveness in the market.

Methodology

The methodology for this project involved an iterative process that began with thorough stakeholder consultations and market research to understand industry needs. It proceeded with detailed system design, incorporating digital twinning, robotics, and computer vision. Implementation followed a phased approach, integrating components systematically, with continuous testing and refinement to ensure optimal performance and adaptability to evolving requirements. Regular feedback loops from end users and iterative adjustments were key to the success of the project.



Results

- In real-time image prediction, the Cobot (Robot 1) performs exceptionally well, correctly recognizing the kind of component captured in live images. Later the faultless components are picked from conveyor 1 and placed on the pinning station.
- After pinning, the Palletizing Robot (Robot 2) is used to pick and place the pinned component on to the assembly station and when assembled product is ready, it again picks and place it on conveyor 2.
- The Cobot (Robot 3), which is assigned to the Automated Storage and Retrieval System (ASRS), arranges the perfectly assembled products in the warehouse in an orderly manner.
- The most recent data is automatically incorporated into the system thanks to real-time database updates. Operators and stakeholders can gain valuable insights from the GUI display, which offers an in-depth overview of the entire production process.

Conclusions

The Integrated multi-platform automation system signifies a major advancement in the field of industrial manufacturing. Modern manufacturing demands are not only met, but exceeded by the dynamic and adaptive solution that the team have designed by bringing together cutting-edge technologies like robotics, computer vision, and digital twinning. This project not only revolutionizes production processes but also establishes new benchmarks for innovation, dependability, and customer satisfaction in the field of industrial automation with its real-time monitoring and simplified user interfaces.