Avionics Reference Document

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- 1.1 Purpose
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2 Hardware

2.1 Pressure Transducers

Model Number	MLH05KPSB01G
Serial Number	F8CEA38AA5
Usage	Helium Pressure PT
Datasheet Link	Link
Sensing Units	PSIG
Pressure Port Type	1/4-18 NPT (ANSI B1.20.1)
Accuracy	$\pm 0.25\%$
Pressure Range	0PSIG to 5000PSIG
Sample Rate	50Hz
Output Voltage Range	1.0 to 5.0 Volts
Input Voltage Range	8.0 to 30.0 Volts
Temperature Range	-40°to +125°Celcius

Model Number	ASUHGP1K55A1AA1A20000
Serial Number	E5C0ADEA35
Usage	LOX Pressure PT
Datasheet Link	Link
Sensing Units	PSIG
Pressure Port Type	3/8 Inch 24 UNF Dash 3 (SAE J514)
Accuracy	$\pm 0.25\%$
Pressure Range	0PSIG to 1500PSIG
Sample Rate	50Hz
Output Voltage Range	0.5 to 4.5 Volts
Input Voltage Range	8.0 to 16.0 Volts
Temperature Range	-40° to +150° Celcius

2.2 Thermocouples

Model Number	240-080
Serial Number	BB510C3CE3
Usage	Upper Air Frame Temperature
Datasheet Link	Link
Type	K
Sensing Units	Celcius
Sample Rate	10Hz
Temperature Range	-73°to +150°Celcius

Model Number	240-080
Serial Number	BB51033CE3
Usage	Unused
Datasheet Link	Link
Type	K
Sensing Units	Celcius
Sample Rate	10Hz
Temperature Range	-73°to +150°Celcius



2.3 RTDs

Model Number	1PT100K2515
Serial Number	8105874731
Usage	LOX Tank Temperature
Datasheet Link	Link
Type	PT100
Sensing Units	Celcius
Sample Rate	10Hz
Temperature Range	-200° to +150° Celcius

2.4 Hall Effect Sensors

Model Number	TCS40DPR
Serial Number	6D65BA9367
Usage	LOX Fill Valve Hall Effect
Datasheet Link	Link
Sensing Units	mT
Output Type	Push-Pull
Trip	$\pm 4.4 \mathrm{mT}$
Release	$\pm 0.9 \mathrm{mT}$
Input Voltage Range	8.0 to 16.0 Volts
Sample Rate	10Hz
Temperature Range	-40° to +150° Celcius



3 EEPROM Layouts

3.1 Layout Version IDs

VersionID	Version Name
1	Sensor Board Layout Rev 1
2	Power Distro Board Layout Rev 1



3.2 Sensor Board Layout Rev 1

Byte #	Usage	Byte #	Usage	Byte #	Usage
0		48		96	
1	Layout Rev Number	49	PT0 Calibration	97	PT1 Data CanID
2		50	Polyfit p1	98	I II Bata Camb
3		51		99	
4		52		100	
5	EEPROM Layout	53	PT0 Calibration	101	PT1 Current CanID
6	Compile Time	54	Polyfit p2	102	1 11 Current Camb
7		55		103	
8		56		104	
9	Board Status	57	PT0 Calibration	105	PT1 Data Frequency
10	Board Status	58	Polyfit p3	106	1 11 Data Frequency
11		59		107	
12		60		108	
13	Board VIN Voltage	61	PT0 Calibration	109	PT1 Max Output
14	CanID	62	Polyfit p4	110	Voltage
15		63		111	
16		64		112	
17	Board current CanID	65	PT0 Calibration	113	PT1 Min Output
18	Board current Canib	66	Polyfit p5	114	Voltage
19		67		115	
20		68		116	
21	DEC D . G ID	69	PT0 Calibration	117	DELA D
22	PT0 Data CanID	70	Polyfit p6	118	PT1 Max Pressure
23		71		119	
24		72		120	
25	DEED G + G ID	73	PT0 Calibration	121	DEL M. D
26	PT0 Current CanID	(lani)	122	PT1 Min Pressure	
27		75	_	123	
28		76		124	
29	DEC D . D	77	PT0 Biguad Filter	125	PT1 Calibration
30	PT0 Data Frequency	78	b0	126	Polyfit p1
31		79		127	
32		80			
33	DEED M. M. II	81	PT0 Biquad Filter		
34	PT0 Max Voltage	82	b1		
35		83			
36		84			
37	DTO Min Voltage	85	PT0 Biquad Filter		
38	PT0 Min Voltage	86	b2		
39		87			
40		88		1	
41	PT0 Max Pressure	89	PT0 Biquad Filter		
42	FIU Max Pressure	90	a1		
43		91			
44		92			
45	DEC M: D	93	PT0 Biquad Filter		
46	PT0 Min Pressure	94	a2		
		95	·	1.1	1



		Sensor Bo	ard Layout Rev 1 Page #1		
Byte #	Usage	Byte #	Usage	Byte #	Usage
128 129 130 131	PT1 Calibration Polyfit p2	176 177 178 179	PT2 Current CanID	224 225 226 227	PT2 Calibration Polyfit p7
132 133 134 135	PT1 Calibration Polyfit p3	180 181 182 183	PT2 Data Frequency	228 229 230 231	PT2 Biquad Filter b0
136 137 138 139	PT1 Calibration Polyfit p4	184 185 186 187	PT2 Max Voltage	232 233 234 235	PT2 Biquad Filter b1
140 141 142 143	PT1 Calibration Polyfit p5	188 189 190 191	PT2 Min Voltage	236 237 238 239	PT2 Biquad Filter b2
144 145 146 147	PT1 Calibration Polyfit p6	192 193 194 195	PT2 Max Pressure	240 241 242 243	PT2 Biquad Filter a1
148 149 150 151	PT1 Calibration Polyfit p7	196 197 198 199	PT2 Min Pressure	244 245 246 247	PT2 Biquad Filter a2
152 153 154 155	PT1 Biquad Filter b0	200 201 202 203	PT2 Calibration Polyfit p1	248 249 250 251	Hall Effect 0 Data CanID
156 157 158 159	PT1 Biquad Filter b1	204 205 206 207	PT2 Calibration Polyfit p2	252 253 254 255	Hall Effect 0 Current CanID
160 161 162 163	PT1 Biquad Filter b2	208 209 210 211	PT2 Calibration Polyfit p3		
164 165 166 167	PT1 Biquad Filter a1	212 213 214 215	PT2 Calibration Polyfit p4		
168 169 170 171	PT1 Biquad Filter a2	216 217 218 219	PT2 Calibration Polyfit p5		
172 173 174 175	PT2 Data CanID	220 221 222 223	PT2 Calibration Polyfit p6		



			ard Layout Rev 1 Page #2		
Byte #	Usage	Byte #	Usage	Byte #	Usage
256		304		352	
257	Hall Effect 0 Data	305	TC0 Biquad Filter	353	RTD0 Biquad Filter
258	Frequency	306	a1	354	b1
259		307		355	
260		308		356	
261	Hall Effect 1 Data	309	TC0 Biquad Filter	357	RTD0 Biquad Filter
262	CanID	310	a2	358	b2
263	Camb	310	a2	359	02
$\frac{263}{264}$		312		360	
	Hall Effect 1	11 -			DED O D: 1 F:14
265		313	TC1 Data CanID	361	RTD0 Biquad Filter
266	Current CanID	314		362	a1
267		315		363	
268		316		364	
269	Hall Effect 1 Data	317	TC1 Data Frequency	365	RTD0 Biquad Filter
270	Frequency	318	1C1 Data Frequency	366	a2
271		319		367	
272		320		368	
273	Hall Effect 2 Data	321	TC1 Biquad Filter	369	
274	CanID	322	b0	370	RTD1 Data CanID
275		323		371	
276		324		372	
277	Hall Effect 2	325	TC1 Biquad Filter	373	RTD1 Data
	Current CanID	11	b1	11	
278	Current Canib	326	DI DI	374	Frequency
279		327		375	
280		328		376	
281	Hall Effect 2 Data	329	TC1 Biquad Filter	377	RTD1 Biquad Filter
282	Frequency	330	b2	378	b0
283		331		379	
284		332		380	
285	TC0 Data CanID	333	TC1 Biquad Filter	381	RTD1 Biquad Filter
286	1 Co Data Camib	334	a1	382	b1
287		335		383	
288		336		1	
289		337	TC1 Biquad Filter		
290	TC0 Data Frequency	338	a2		
291		339	~~		
292	1	340		+	
292 293	TC0 Biquad Filter	341			
293 294	b0	341	RTD0 Data CanID		
	D0	11 -			
295		343		4	
296		344	D		
297	TC0 Biquad Filter	345	RTD0 Data		
298	b1	346	Frequency		
299		347			
300		348			
301	TC0 Biquad Filter	349	RTD0 Biquad Filter		
302	b2	350	b0		
303	1	351		- 11	



		Sensor Bo	ard Layout Rev 1 Pa	ge #3	
Byte #	Usage	Byte #	Usage	Byte #	Usage
384		432		480	
385	RTD1 Biquad Filter	433		481	
386	b2	434		482	
387		435		483	
388		436		484	
389	RTD1 Biquad Filter	437		485	
390	a1	438		486	
391		439	İ	487	
392		440		488	
393	RTD1 Biquad Filter	441		489	
394	a2	442		490	
395		443		491	
396		T 444		492	
397		445		493	
398		446		494	
399		447		495	
400		448		496	
401		449		497	
402		450		498	
403		451		499	
404		452		500	
405		453		501	
406		454		502	
407		455		503	
408		456		504	
409		457		505	
410		458		506	
411		459		507	
412		460		508	
413		461		509	
414		462		510	
415		463		511	
416		464		011	
417		465			
418		466			
419		467			
420		468			
421		469			
422		470			
423		471			
424		472			
425		473			
426		474			
427		475			
427		476			
428		477			
430		11			
430		478			
431		479	1	11	



${\bf 3.3} \quad {\bf Power~Distro~Board~Layout~Rev~1}$

		Power Distro	Board Layout Rev	v 1 Page #0	
Byte #	Usage	Byte #	Usage	Byte #	Usage
0		48		96	
1	Board Status	49		97	
2	Board Status	50		98	
3		51		99	
4		52		100	
5	Offboard Battery	53		101	
6	Voltage CANID	54		102	
7		55		103	
8		56		104	
9	Offboard Battery	57		105	
10	Current CANID	58		106	
11		59		107	
12		60		108	
13	Onboard Battery	61		109	
14	Voltage CANID	62		110	
15		63		111	
16		64		112	
17	Onboard Battery	65		113	
18	Current CANID	66		114	
19		67		115	
20		68		116	
21	Helix Loop CW	69		117	
22	Voltage CANID	70		118	
23		71		119	
24		72		120	
25	Helix Loop CW	73		121	
26	Current CANID	74		122	
27		75		123	
28		76		124	
29	Helix Loop CCW	77		125	
30	Voltage CANID	78		126	
31		79		127	
32		80			
33	Helix Loop CCW	81			
34	Current CANID	82			
35		83			
36		84			
37		85			
38		86			
39		87			
40		88			
41		89			
42		90			
43		91			
44		92			
45		93			
46		94			
47		95			



4 CAN IDs

4.1 CAN Bus Load Calculations

The current CAN Bus config requires between 20532 bits and 24636 bits to be sent on the CAN bus every second.

Frequency	Best Case	Worst Case
100KHz	21.0%	25.0%
$250 \mathrm{KHz}$	8.0%	10.0%
500KHz	4.0%	5.0%
1MHz	2.0%	2.0%

4.2 ID 0 - Clock Sync

Frequency: 50Hz

Byte	Bit	Signed	Range	Units	Description
0-3		False	0 to 4294967295	Milliseconds	UTC time

4.3 ID 1 - Emergency Signal

Frequency: 50Hz

	Byte	Bit	Signed	Range	Units	Description
	0		False			Status
Ì		0-1				System Status

4.4 ID 100 - Helium Pressure PT Data

Frequency: 50Hz

Byte	Bit	Signed	Range	Units	Description
0-3		False		Milliseconds	UTC time
4-5		False		PSIG	Helium Pressure

4.5 ID 101 - LOX Pressure PT Data

Frequency: 50Hz

Byte	Bit	Signed	Range	Units	Description
0-3		False		Milliseconds	UTC time
4-5		False		PSIG	LOX Pressure

4.6 ID 102 - Methane Pressure PT Data

Frequency: 50Hz

Byte	Bit	Signed	Range	Units	Description
0-3		False		Milliseconds	UTC time
4-5		False		PSIG	Methane Pressure

4.7 ID 103 - Chamber Pressure PT Data

Frequency: 50Hz

Byte	Bit	Signed	Range	Units	Description
0-3		False		Milliseconds	UTC time
4-5		False		PSIG	Chamber Pressure



4.8 ID 200 - Helium Fill Valve Hall Effect State

Frequency: 10Hz

Byte	Bit	Signed	Range	Units	Description
0-3		False		Milliseconds	UTC time
4		False		Open/Closed	Helium Fill Valve Hall Effect
					State

4.9 ID 201 - LOX Fill Valve Hall Effect State

Frequency: 10Hz

Byte	Bit	Signed	Range	Units	Description
0-3		False		Milliseconds	UTC time
4		False		Open/Closed	LOX Fill Valve Hall Effect State

4.10 ID 202 - Methane Fill Valve Hall Effect State

Frequency: 10Hz

Byte	Bit	Signed	Range	Units	Description
0-3		False		Milliseconds	UTC time
4		False		Open/Closed	Methane Fill Valve Hall Effect
					State

4.11 ID 300 - Helium Tank Temperature Data

Frequency: 10Hz

Byte	Bit	Signed	Range	Units	Description
0-3		False		Milliseconds	UTC time
4-5		True		Celcius	Helium Tank Temperature

4.12 ID 301 - LOX Tank Temperature Data

Frequency: 10Hz

Byte	Bit	Signed	Range	Units	Description
0-3		False		Milliseconds	UTC time
4-5		True		Celcius	LOX Tank Temperature

4.13 ID 302 - Methane Tank Temperature Data

Frequency: 10Hz

Byte	Bit	Signed	Range	Units	Description
0-3		False		Milliseconds	UTC time
4-5		True		Celcius	Methane Tank Temperature

4.14 ID 303 - Nozzle Temperature Data

Frequency: $10 \mathrm{Hz}$

Byte	Bit	Signed	Range	Units	Description
0-3		False		Milliseconds	UTC time
4-5		True		Celcius	Nozzle Temperature



4.15 ID 304 - Upper Air Frame Temperature Data

Frequency: 10Hz

Byte	Bit	Signed	Range	Units	Description
0-3		False		Milliseconds	UTC time
4-5		True		Celcius	Upper Air Frame Temperature

4.16 ID 400 - Helium Pressure PT Current

Frequency: 10Hz

Byte	Bit	Signed	Range	Units	Description
0-3		False		Milliseconds	UTC time
4-5		True		milliamps	Helium Pressure PT Current

4.17 ID 401 - LOX Pressure PT Current

Frequency: 10Hz

Byte	Bit	Signed	Range	Units	Description
0-3		False	0	Milliseconds	UTC time
4-5		True		milliamps	LOX Pressure PT Current

4.18 ID 402 - Methane Pressure PT Current

Frequency: 10Hz

Byte	Bit	Signed	Range	Units	Description
0-3		False		Milliseconds	UTC time
4-5		True		milliamps	Methane Pressure PT Current

4.19 ID 403 - Chamber Pressure PT Current

Frequency: 10Hz

110900		_			
Byte	Bit	Signed	Range	Units	Description
0-3		False		Milliseconds	UTC time
4-5		True		milliamps	Chamber Pressure PT Current

4.20 ID 404 - Helium Fill Valve Hall Effect Current

Frequency: 10Hz

Byte	Bit	Signed	Range	Units	Description
0-3		False		Milliseconds	UTC time
4-5		True		milliamps	Helium Fill Valve Hall Effect Current

4.21 ID 405 - LOX Fill Valve Hall Effect Current

Frequency: 10Hz

	1104u010y. 10111								
Byte	Bit	Signed	Range	Units	Description				
0-3		False		Milliseconds	UTC time				
4-5		True		milliamps	LOX Fill Valve Hall Effect Cur-				
					rent				



4.22 ID 406 - Methane Fill Valve Hall Effect Current

Frequency: 10Hz

Byte	Bit	Signed	Range	Units	Description
0-3		False		Milliseconds	UTC time
4-5		True		milliamps	Methane Fill Valve Hall Effect
					Current

4.23 ID 407 - Upper Air Frame VIN Current

Frequency: 10Hz

	Byte	Bit	Signed	Range	Units	Description
Ī	0-3		False		Milliseconds	UTC time
Ī	4-5		True		Milliamps	Upper Air Frame Board Current

4.24~ ID 500 - Upper Air Frame VIN Voltage

Frequency: 10Hz

Byte	Bit	Signed	Range	Units	Description
0-3		False		Milliseconds	UTC time
4-5		True		Millivolts	Upper Air Frame Board VIN
					Voltage