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23BEC0084 - VIT Student

Problem Statement: -

Develop a simple Arduino UNO-based Automatic Dust Bin system which can open the lid when it senses the object movement nearby.

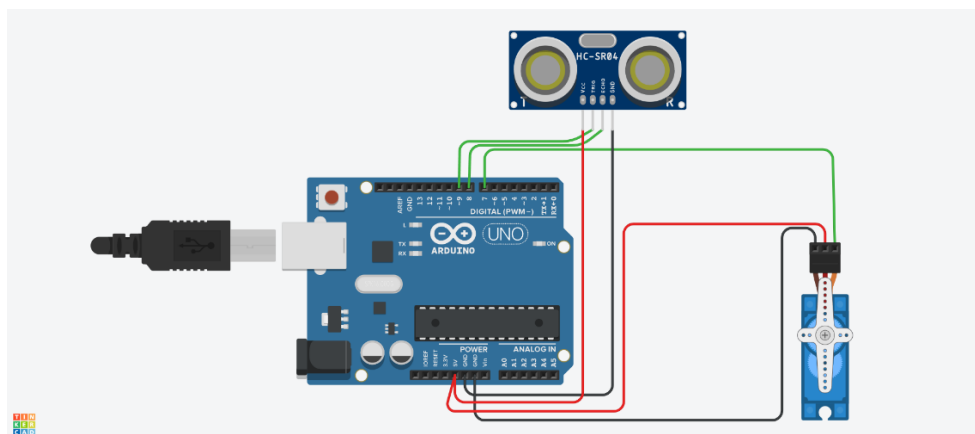
Scope of Solution: -

The proposed Arduino UNO-based Automatic Dust Bin system uses an ultrasonic sensor to detect nearby object movement. When motion is detected within a specific range, a servo motor automatically opens the dustbin lid. This hands-free system promotes hygiene, reduces contact with waste surfaces, and is ideal for homes or public places.

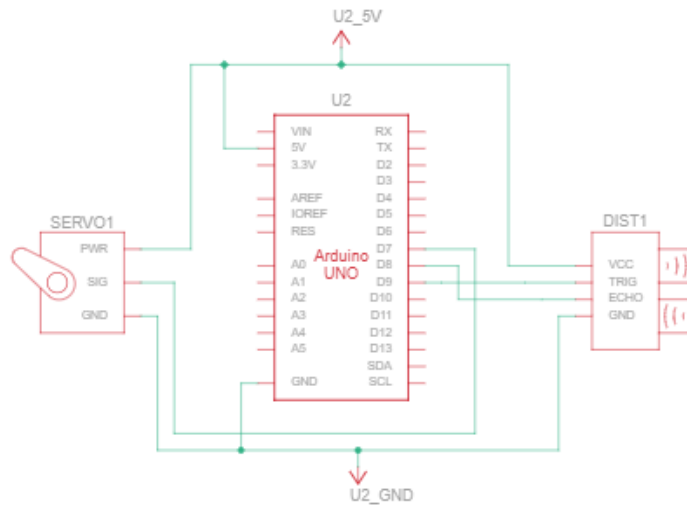
Required Components: -

- Arduino Uno
- Servo Motor
- Ultrasonic Sensor
- Jumper Wires
- Arduino IDE for writing the code
- TinkerCad for Simulation

Simulated Circuit: - (TinkerCad)



Gerber File: -



Code for the solution: -

```
#include <Servo.h>
```

```
#include <Wire.h>
```

```
Servo servo_1;
```

```
int trigPin = 9;
```

```
int echoPin = 8;
```

```
long duration;
```

```
int distance;
```

```
void setup(){  
  servo_1.attach(7, 500, 2500);  
  servo_1.write(90); //initially keeping the bin lid closed  
  delay(2000);  
  
  pinMode(trigPin, OUTPUT);  
  pinMode(echoPin, INPUT);  
  Serial.begin(9600);  
}
```

```
void loop(){  
  digitalWrite(trigPin, LOW);  
  delayMicroseconds(2);  
  digitalWrite(trigPin, HIGH);  
  delayMicroseconds(10);  
  digitalWrite(trigPin, LOW);  
  
  duration = pulseIn(echoPin, HIGH);  
  distance= duration*0.034/2;  
  
  Serial.print("Distance: ");  
  Serial.println(distance);
```

```
if ( distance <= 25 ){  
    servo_1.write(0); //when distance to bin is less than 25cm than bin opens lid  
    delay(3000);  
}  
else{  
    servo_1.write(90); //when there is more than 25cm distance to the bin than  
bin lid closes  
}  
}
```