Structured Field Testing Framework - Feedback Survey				
Nr	Date	Interviewee		
Expe	rience in Testing/Fie	Id Testing: (field test creation, test conduct, data analysis)		
Part 1	: Introduction, Gen	eral questions about as-is-situation (~10 min)		
1	How are you curre	ntly preparing for Field Tests?		
	_	ies, and processes are you using for preparation)		
2		periences in Field Testing - What is currently working well you need additional support?		
3	Have you experience	etionality are currently challenging? eed any concrete problems, issues, etc., e.g., due to the lack of . (loss of information after a test at the field)		

	Part 2: Description of envisioned approach (~5 min)
Part :	3: Perceived Usefulness of our approach and its Features (~10 min)
4	To what extent could a structured test description help to better prepare for Field Tests? (Why/Why Not / How)
5a	Are the presented concepts and requirements (roles/tasks/conditions)
Ja	sufficient to describe realistic tests?
	(Consider features/functionality to add for describing a test scenario?)
FI.	Will-like Landscape and Anna Anna Anna Anna Anna Anna Anna
5b	Which language constructs/expressions are required/desirable to represent field test scenarios for multi-drone missions? (task description, conditions)
6	What advantages/disadvantages do you see when using a structured field testing approach? Which of the features presented could be the most useful/helpful?

7	Where would you be using a structured field testing approach if available?
	(Are you aware of anyone else (any other application area) where such an approach
	could be helpful/beneficial)
	(Recommend persons who could be interested)
Dort /	1: Test specification and data collection concerns (-10 min)
rait 4	4: Test specification and data collection concerns (~10 min)
8	Which elements/features should a task history timeline represent (i) to orient a
	•
	field tester, (ii) a test manager, or (iii) a test data analyst?
	(data collection, representation, e.g., similar to a social media or Jira timeline)
	(data sensetion, representation, e.g., emiliar to a sesial media of one amount)
	Which of them would be most useful?
1	
1	

Part 2: Description of the proposed approach

Setting up and executing a field test is commonly a rather time- and resource-intensive task.

Field testing requires preparing physical hardware, deriving test scenarios, and setting up equipment as a basis to execute tests in the field.

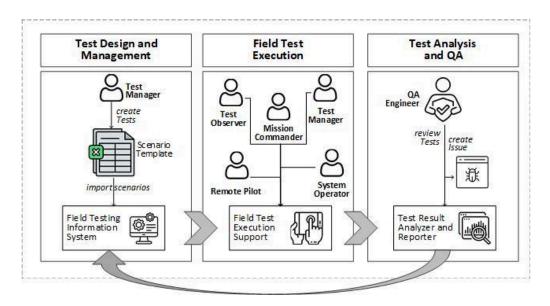
A field test needs to be thoroughly planned and validated as the test poses a significant risk to the involved humans in case something goes wrong.

Field test results need to be properly documented, and once the field test is completed, results need to be analyzed to improve detected bugs.

To provide holistic support for all three parts, we envision a *structured field test* framework that consists of

- (1) *Test Design and Management.* An information system shall facilitate the definition and management of structured, flexible, and reusable test scenarios.
- (2) Field Test Execution. A field-test information system shall provide role-specific task guidance for test scenarios to collect field data by human and machine actors.
- (3) *Test Analysis and QA.* Test data analysis shall process, aggregate, and visualize the field test data in an analysis component.

All three parts shall work together, facilitating end-to-end field test definition, execution, and analysis, with information being fed back into, for example, an issue-tracking system for iterative improvement of the system under test, the structured field test specification, and field test support.



The focus of the current work: Part 1 - Test Scenario Management

Requirements / Capabilities:

- **(C1) Formal test description:** tests shall be defined in a testable, reusable, and concise manner that captures relevant preconditions, tester actions, and expected outcomes.
- (C2) Actor roles: Each test and constituent step requires roles associated with them - Responsibilities are clearly defined, and each participant is aware of his duties, and events to be aware of.
- **(C3)** Role-specific tasks in field test state: Each role shall receive a list of relevant next tasks, which consider the operational context conditions.
- **(C4)** Link test activity to resources: A test activity shall be connected via a task description to the relevant resources, e.g., which button to press, or which switch on a handheld to flip), to provide visual cues.
- (C5) Feedback of field test issues: Testers shall receive tool support to report deviations from expected behavior, or issues with conducting the test due to a mismatch between assumptions in the test specification and the operation resources and/or conditions.
- **(C6) Validated field test data collection:** Test execution information shall be related with diverse other sources such as flight controller logs, or system outputs for validating collected data.
- (C7) Test data analysis support: After finishing the field test, analysis support shall provide the data analyst, developer, or quality engineer, with information on which parts of a test for example have been completed successfully, and where issues have been reported, as a foundation for focusing on the most relevant parts of the test data and reduce analysis complexity.

Concern candidates

- (1) base case function: tasks to cook the soft-boiled egg
- **(2) collect data for test/experiment analysis, and compliance (**Data collection, e.g., read wind speed from an external device display.)
- (3) validation with observer (4 eyes), compliance
- (4) coordination with parallel tasks (task dependencies, attention cycle time, signals)
- **(5) validate the feasibility of conducting the tasks with available resources** (cognitive load, trade-offs, degraded performance)
- (6) further systems engineering concerns (e.g., safety, IT security)

				Process Setup					
ID	UC1								
Name	e Test Case-01: Single UAV Takeoff-Waypoints-Land								
Description	A simple Test Case v	where a single UAV takes off, flies to a series of wa	aypoints, and returns to launch.						
Primary Actor	mission_commande	, UAV (controller ?)							
porting Actors	pilot_1								
ariable Imports	waypoints: List <way< td=""><td>point></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></way<>	point>							
ndition Imports									
				Process Definition					
	Phase	Given	When	Then	Responsible	Priority	Dur	ation Subprocess	Subprocess Pa
1	preflight-check	UAV <uav_1> is available at test site.</uav_1>	RPIC <pilot_1> shall place UAV</pilot_1>	UAV <uav_1> is placed in its launch</uav_1>	pilot_1	~)	50		
2	preflight-check	UAV <uav_1> is disabled.</uav_1>	RPIC <pilot_1> shall activate a</pilot_1>	UAV <uav_1> is activated and arme</uav_1>	pilot_1	•	50	ActivateAndArm	{"drone": "uav_
3	mission-planning		MCOM <mission_commander< td=""><td>The waypoints are marked complet</td><td>mission_co</td><td>▼)</td><td>50</td><td></td><td></td></mission_commander<>	The waypoints are marked complet	mission_co	▼)	50		
4	mission-planning	UAV <uav_1> is activated and armed.</uav_1>	MCOM <mission_commander< td=""><td>UAV <uav_1> hovers over the launc</uav_1></td><td>mission_co</td><td>▼)</td><td>70</td><td></td><td></td></mission_commander<>	UAV <uav_1> hovers over the launc</uav_1>	mission_co	▼)	70		
5	takeoff		UAV <uav_1> shall take off to i</uav_1>	UAV <uav_1> has reached takeoff a</uav_1>		•	50		
6	mission-execution	UAV <uav_1> has reached takeoff altitude.</uav_1>	UAV <uav_1> shall switch to in</uav_1>	UAV <uav_1> is in-flight mode.</uav_1>		▼)	10		
7	mission-execution		{{ foreach waypoint in waypoir	ts }}		▼)	10		
7.1	mission-execution		UAV <uav_1> shall cruise to the</uav_1>	UAV <uav_1> has reached {{waypoi</uav_1>		→	50		
8	mission-execution	UAV <uav_1> has reached the last waypoint.</uav_1>	UAV <uav_1> shall switch to he</uav_1>	UAV is at the last {{waypoint}}.		▼)	10		
9	RTL		MCOM <mission_commander< td=""><td>shall issue a command to return to</td><td>mission_co</td><td>₩</td><td>70</td><td></td><td></td></mission_commander<>	shall issue a command to return to	mission_co	₩	70		
10	RTL		UAV <uav_1> shall switch to R</uav_1>	ΓL mode, shall ascend to its predefir		▼)	10		
11	land	UAV <uav_1> has reached the start location</uav_1>	UAV <uav_1> shall switch to la</uav_1>	nding mode.		•	50		
12	land	UAV <uav_1> has landed</uav_1>	UAV <uav_1> shall switch to or</uav_1>	n-ground mode.		▼)	50		
13	post-flight	UAV <uav_1> is disarmed.</uav_1>				▼)	10		
	post-flight	UAV <uav_1> is disarmed.</uav_1>	RPIC <pilot_1> for UAV <uav_1< td=""><td></td><td>pilot_1</td><td>▼)</td><td>10</td><td></td><td></td></uav_1<></pilot_1>		pilot_1	▼)	10		
15	post-flight			UAV <uav_1> has landed at the oriç</uav_1>		•	10		
			TOBS <test observer=""> shall me</test>			▼)			
			TOBS <test observer=""> shall me</test>			•			
				ort an issue if a UAV <x> does not a</x>		•			
			TOBS <test observer=""> shall rep</test>	ort an issue if a process or resource		▼			

QUESTION 5

5A)

1- Role	pilot, test observer, others
2- Pre-condition	Has to be true to start a task, e.g., mission is in progress, UAV in state in-flight.
3- Post-condition	task success condition that a human or machine actor can evaluate, post-condition may activate next phase
4-Phase	Preflight-check, mission planning, etc. to group tasks for activation.
5-Priority	A number to rank available tasks, based on design and run-time knowledge.
6-Time window/Duration	A task may have a time window for completion, e.g., 10 minutes,to trigger a time out if not finished in time.
7-Fallback scen.	tasks to conduct if mission deviates from normal scenario, e.g., loss of a drone.
8 - Troubleshooting	tasks to conduct in case of a disturbance that requires swift, targeted action for risk mitigation, e.g., checking likely
other?	

5B)

1- Task Constructs:

<role actor=""> shall <conduct task=""></conduct></role>	MCOM <mc> shall mark UAVs in mission with "Mission A".</mc>		
Role/Actor with parameters/mapping	RPIC {{ uav.pilot }} shall arm UAV {{ uav }}.		
Sub-process with parameters	RPIC {{ uav.pilot }} shall perform a post-flight{uav.pilot,uav} inspection of UAV {{ uav }}.		
Tasks for a set of actors/object	For each <object> in <set objects="" of="">: for each UAV in (UAVs marked with "Mission A")</set></object>		
List of tasks	RPIC {{ uav.pilot }} shall check UAV {{ uav }}, shall perform a post-flight inspection of UAV {{ uav }}, and shall disable UAV {{ uav }}		
OTHER?			

2- Task Expressions:

Role/actor:	RPIC {{ uav.pilot }} shall activate and arm UAV {{ uav }}. Variable UAV related to Pilot.		
Set of roles/actors:	TOBS <test observer=""> can be assigned to one or more persons.</test>		
Recurring task:	Test observer shall record every 30 seconds the energy level of the UAV battery.		
Task object for a human or machine to interpret:	shall order UAV {{ uav }} to take off to their takeoff altitude.		
Task object for a human to interpret:	shall report whether UAV {{ uav }} has taken off to its takeoff altitude. shall report an issue if a UAV {{ uav }} does not achieve its mission contribution.		
Placeholder that may require clarification:	TOBS <test observer=""> shall measure/validate time of achieving test milestone for mission.</test>		
OTHER?			

5b.3 Condition construct

- (1) Boolean state: Phase.inprogress, UAV_at_site, UAV_mission_in-flight
- (2) Marker: UAVs marked with "Mission A"
- (x) Further condition constructs?

5b.4 Condition expression

- (1) Simple condition: Phase.inprogress = True, number > 3
- (2) Short name for condition; P03: Phase.inprogress = True
- (3) Logical combination of conditions: P03 AND (UAV_at_site = True)
- (x) Further condition expressions?

QUESTION 8



