

Agent Based Software Engineering Lab LabTask 02

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1. Reactive Agent

```
def reactive_agent(environment_state):
    if environment_state == 'Obstacle on left':
        print(f"Perception: {environment_state}. Action: Move Right")
        return 'Move Right'
    elif environment_state == 'Obstacle on right':
        print(f"Perception: {environment_state}. Action: Move Left")
        return 'Move Left'
    else:
        print(f"Perception: {environment_state}. Action: Move Right (default)")
        return 'Move Right'

# --- Example Usage ---
print("--- Reactive Agent Demo ---")
reactive_agent('Obstacle on left')
reactive_agent('Obstacle on right')
reactive_agent('Clear')
```

```
--- Reactive Agent Demo ---
Perception: Obstacle on left. Action: Move Right
Perception: Obstacle on right. Action: Move Left
Perception: Clear. Action: Move Right (default)
```

2. Task Sequencing Agent

```
class TaskSequencingAgent:
     def __init__(self, task_list):
         self.pending_tasks = task_list
         self.completed_tasks = []
         print(f"Agent initialized. Goal: Complete tasks in order -> {self.pending_tasks}")
     def perform_next_task(self):
         if not self.pending_tasks:
            print("Goal achieved! All tasks are complete.")
        next_task = self.pending_tasks.pop(0)
         print(f"Performing task: '{next_task}'...")
         self.completed_tasks.append(next_task)
         print(f"Completed Tasks: {self.completed_tasks}")
print(f"Remaining Tasks: {self.pending_tasks}\n")
 agent = TaskSequencingAgent(tasks)
while agent.pending_tasks:
     agent.perform_next_task()
agent.perform_next_task()
```

```
--- Goal-Based Agent Demo ---
Agent initialized. Goal: Complete tasks in order -> ['Gather requirements', 'Design system', 'Implement features', 'Test and deploy']
Performing task: 'Gather requirements'...
Completed Tasks: ['Gather requirements']
Remaining Tasks: ['Design system', 'Implement features', 'Test and deploy']

Performing task: 'Design system'...
Completed Tasks: ['Gather requirements', 'Design system']
Remaining Tasks: ['Implement features', 'Test and deploy']

Performing task: 'Implement features'...
Completed Tasks: ['Gather requirements', 'Design system', 'Implement features']
Remaining Tasks: ['Test and deploy'...
Completed Tasks: ['Gather requirements', 'Design system', 'Implement features', 'Test and deploy']

Remaining Tasks: ['Gather requirements', 'Design system', 'Implement features', 'Test and deploy']

Remaining Tasks: ['Gather requirements', 'Design system', 'Implement features', 'Test and deploy']

Goal achieved! All tasks are complete.
```

3. Simple Utility Shopper

```
🕏 Simple_Utility_Agent.py > ..
     class SimpleUtilityShopper:
         def __init__(self, utility_scores):
             self.utility_scores = utility_scores
             print(f"Agent initialized with utility scores: {self.utility scores}")
         def decide_to_buy(self, item_category, utility_threshold=50):
             utility = self.utility_scores.get(item_category, 0)
             if utility >= utility_threshold:
                                   '{item_category}'. (Utility: {utility} >= Threshold: {utility_threshold})"
                 decision = f"Buy
                  decision = f"Don't buy '{item_category}'. (Utility: {utility} < Threshold: {utility_threshold})"</pre>
             print(decision)
             return decision
     print("\n--- Simple Utility-Based Agent Demo ---")
     scores = {'electronics': 90, 'food': 70, 'clothes': 45}
     shopper = SimpleUtilityShopper(scores)
     shopper.decide_to_buy('electronics')
     shopper.decide_to_buy('food')
     shopper.decide_to_buy('clothes')
```

```
--- Simple Utility-Based Agent Demo ---
Agent initialized with utility scores: {'electronics': 90, 'food': 70, 'clothes': 45}
Buy 'electronics'. (Utility: 90 >= Threshold: 50)
Buy 'food'. (Utility: 70 >= Threshold: 50)
Don't buy 'clothes'. (Utility: 45 < Threshold: 50)
```

4. Calculate Shift Utility

```
femployee_Scheduling_agentpy>_
    def calculate_shift_utility(shift, employee):
    weights = ('skill': 0.5, 'availability': 0.3, 'preference': 0.2)
    skill_score = 1 if shift['required_skill'] in employee['skills'] else 0
    availability_score = 1 if shift['time'] in employee['preferences'] else 0

preference_score = 1 if shift['time'] in employee['preferences'] else 0

utility = (weights['skill'] * skill_score +
    weights['availability'] * availability_score +
    weights['availability'] * availability_score +
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```

```
--- Employee Scheduling Agent Demo ---

- Checking Alice for Morning Shift: Utility = 1.00

- Checking Bob for Morning Shift: Utility = 0.30

- Checking Charlie for Morning Shift: Utility = 0.70

-> Best assignment for Morning Shift: Alice (Score: 1.00)

- Checking Alice for Evening Shift: Utility = 0.30

- Checking Bob for Evening Shift: Utility = 1.00

- Checking Charlie for Evening Shift: Utility = 0.00

-> Best assignment for Evening Shift: Bob (Score: 1.00)

--- Final Schedule ---

Morning Shift: Alice
Evening Shift: Bob
```

5. Shopping Assistant Agent

```
--- Shopping Assistant Agent Demo ---
Shopping Assistant activated. Budget: $200.00

Evaluating items based on value (Utility/Price ratio):
- Considering 'Mouse' (Price: $32.00, Utility: 50, Value Ratio: 1.56)
-> ADDED to cart.
- Considering 'Keyboard' (Price: $80.00, Utility: 70, Value Ratio: 0.88)
-> ADDED to cart.
- Considering 'Headphones' (Price: $135.00, Utility: 90, Value Ratio: 0.67)
-> SKIPPED. Not enough budget.
- Considering 'Smartwatch' (Price: $250.00, Utility: 95, Value Ratio: 0.38)
-> SKIPPED. Not enough budget.
--- Purchase Summary ---
Items in Cart: ['Mouse', 'Keyboard']
Total Cost: $112.00
Total Utility Maximized: 120
```