



人工智能 I





本节课安排

- 博弈搜索问题

Game Search Problem

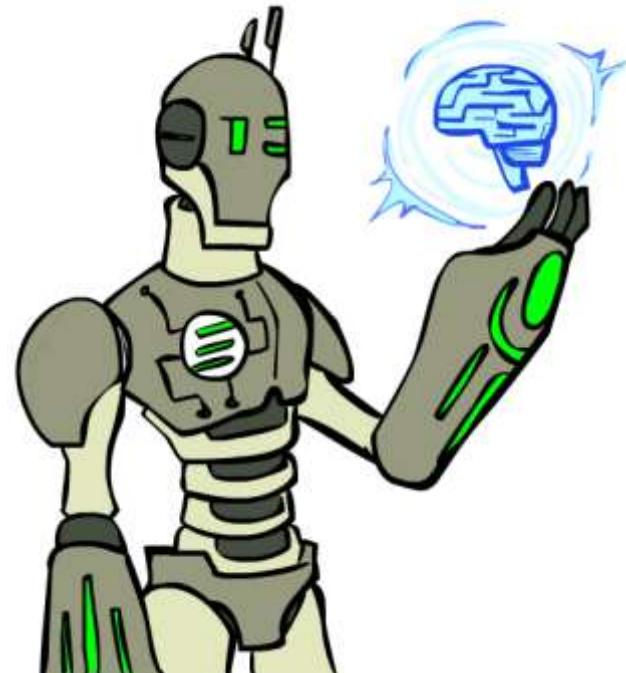
Adversarial Search Problem

- 极小极大搜索

Minimax Search

- α - β 剪枝

- 练习





本周五实验课安排

周次	5
日期	2025/10/24
星期	星期五
时间	8:00-12:15
机房地点	五五楼435-软实七
实验任务	有信息搜索



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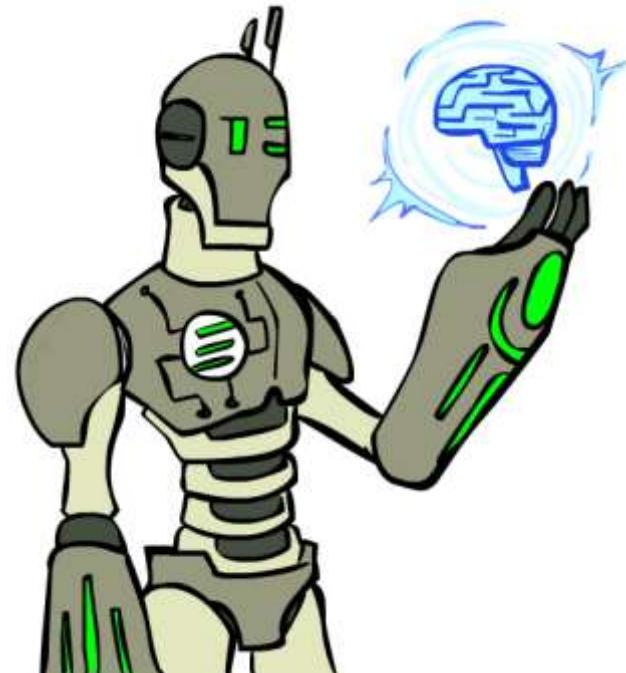
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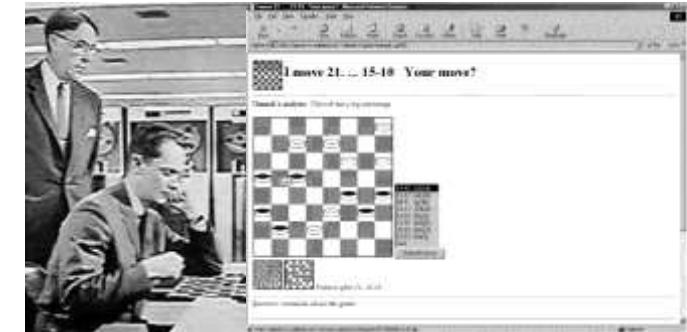




例子：棋类游戏

□ 西洋跳棋 (1962, IBM)

- Chinook VS. Marion Tinsley
- 提出机器学习、强化学习



□ 国际象棋 (1997, IBM)

- DeepBlue VS. 卡斯帕罗夫
- 硬件加速搜索
- 超级专家系统



□ 围棋 (2016, DeepMind)

- AlphaGo VS. 李世石
- DL+ RL + 蒙特卡洛方法





任务环境的属性

- 完全可观测 *V.S.* 部分可观测
- 单体 *V.S.* 多体
- 静态 *V.S.* 动态
- 确定性 *V.S.* 随机性
- 周期性 *V.S.* 序贯性
- 离散 *V.S.* 连续



博弈

人工智能中“博弈”通常专指博弈论专家们
称为**有完整信息的、确定性的、轮流行动的、两
个游戏者的零和 (Zero-Sum)** 游戏。





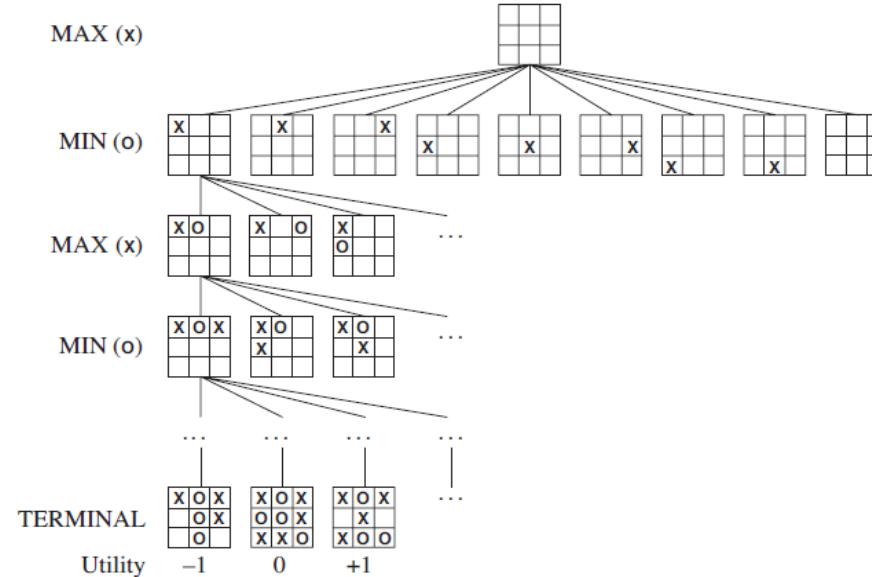
博弈问题(Game)的描述

- S_0 : 初始状态
- Player(s): 状态 s 下，由哪个玩家行动
 - MAX (先行)
 - MIN
- Actions(s): 状态 s 下的动作
- Result(s, a): 后继函数
- Terminal_Test(s): 判断 s 是否为终止状态
- Utility(s, p): 终止状态 s 对于玩家 p 的效用 (得分)
 - $p = \text{MAX}$
 - Utility(s)



博弈树 (Game Tree)

- 根节点：初始状态，行为决策节点
- 叶子节点：终止状态（终局）
- 中间节点
- 与搜索树类似，主要不同点：
 - 博弈树：有MAX与MIN两位玩家，深度有限
 - 搜索树：一位玩家，动态、可无限延伸





三子棋的博弈树



MAX (X)

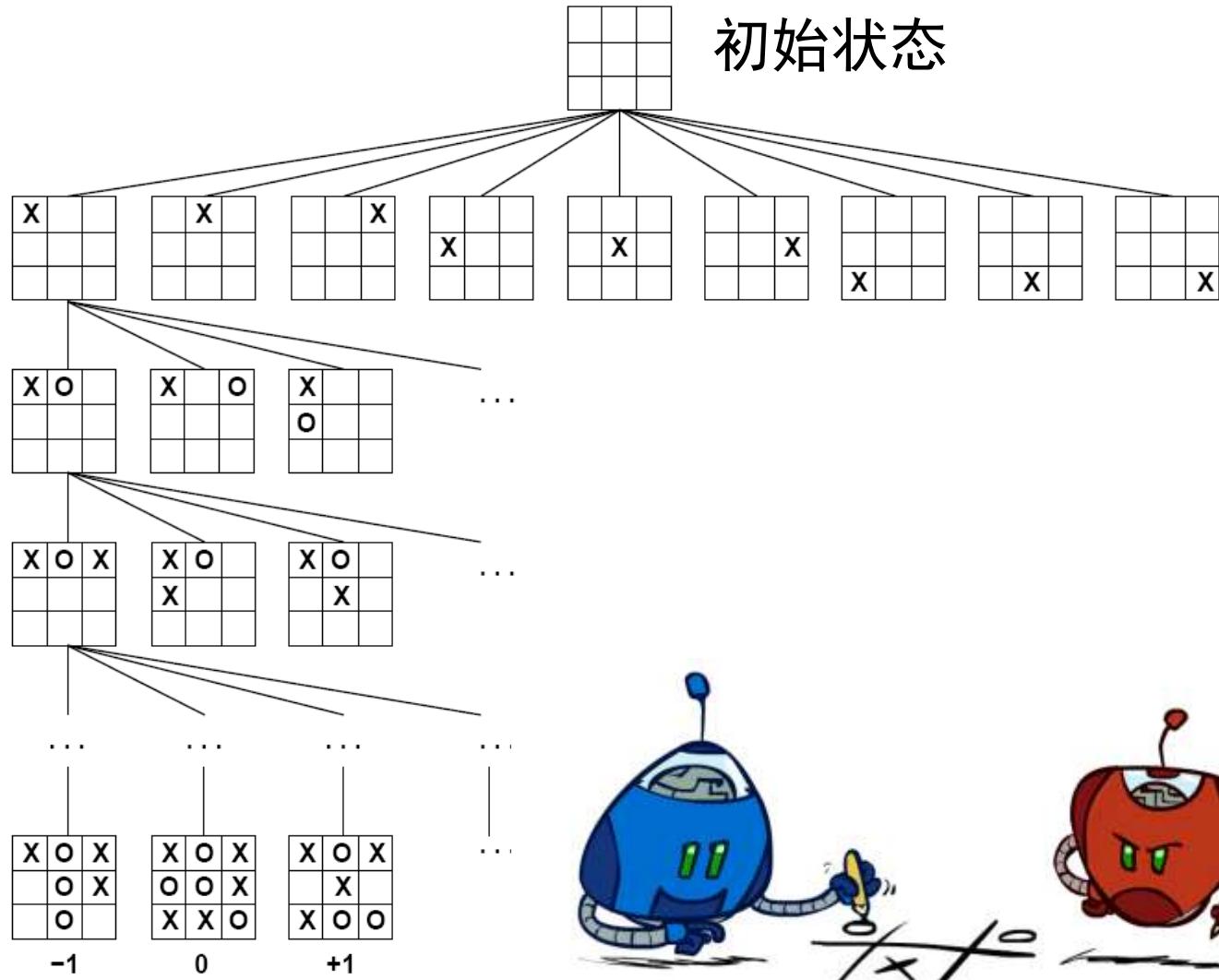
MIN (O)

MAX (X)

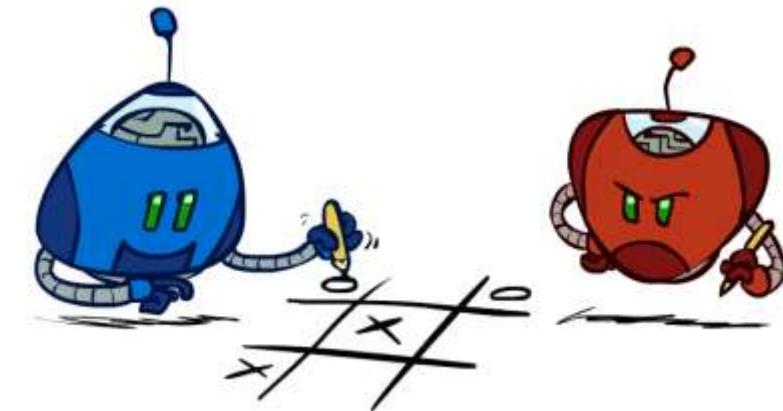
MIN (O)

TERMINAL

Utility



初始状态





博弈问题 (Game) 的求解

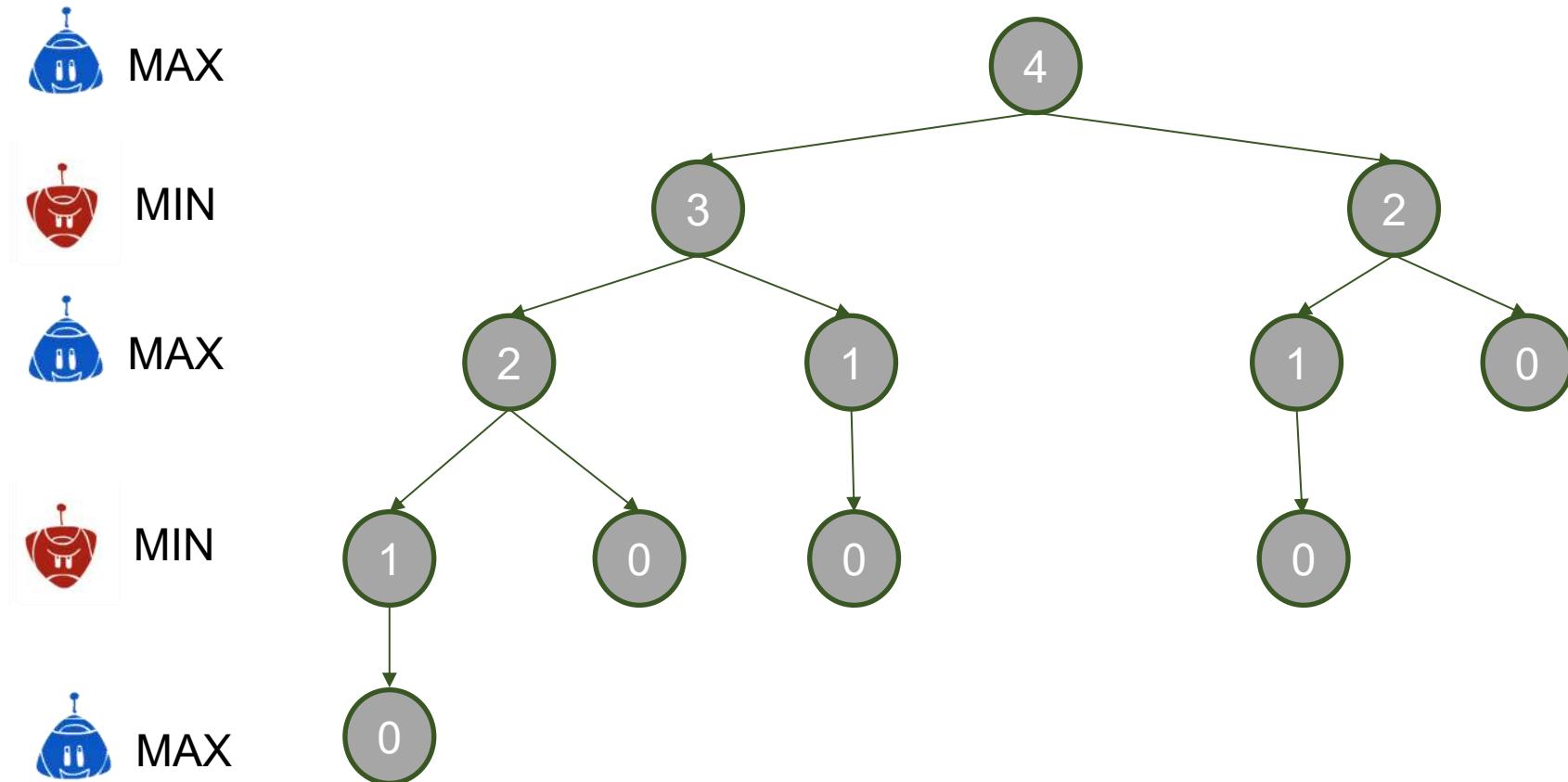
- 问题：初始状态的行为决策
- 基本思路：
 - 玩家根据当前状态，向对自己有利的终局采取行动（为最大效用而行动）
 - 终局的效用：已知
 - 中间节点的效用：难点





例子：取石子

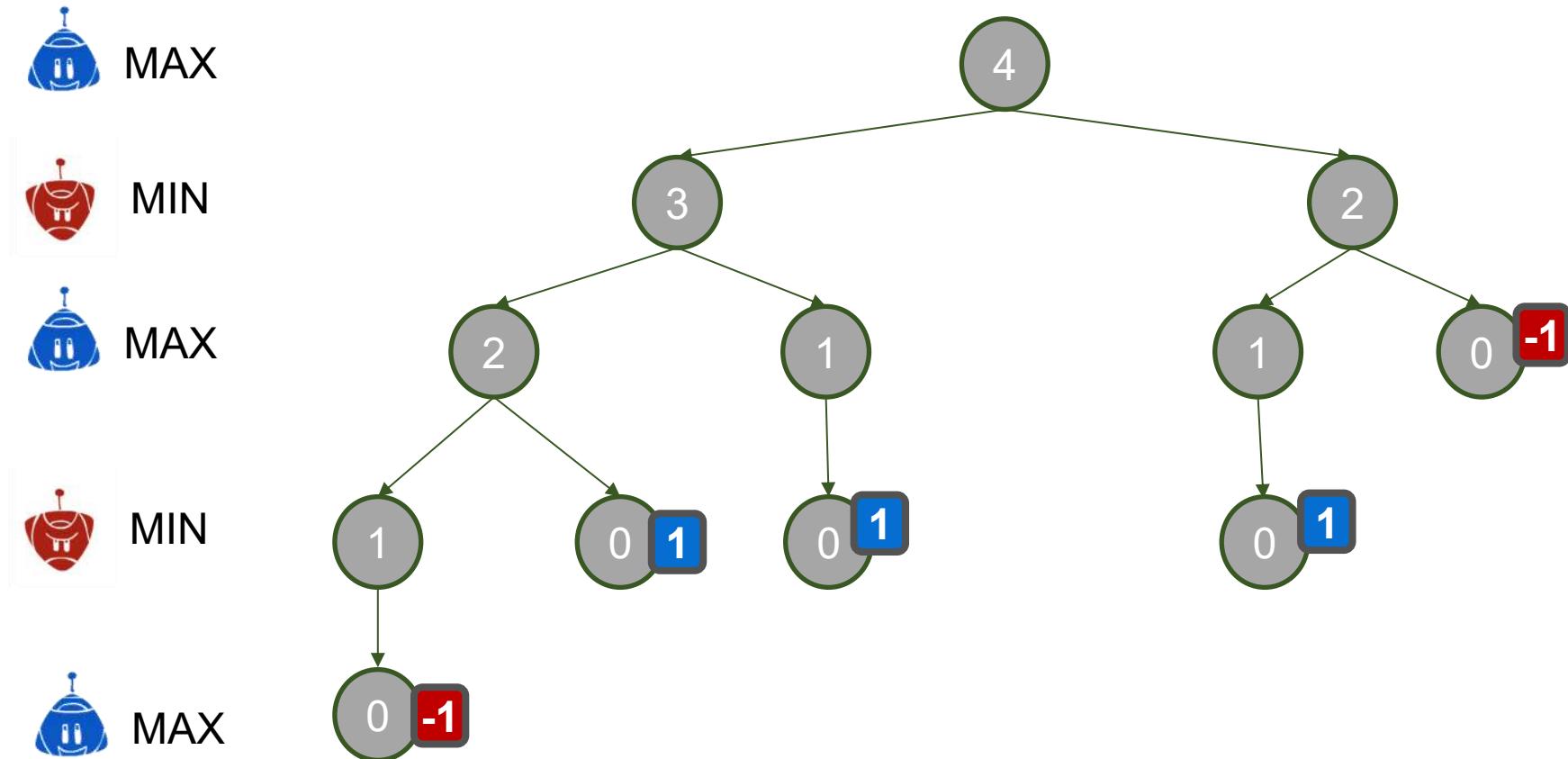
- 盘子中有4颗石子，两个玩家轮流从中取出。至少取1颗，至多取2颗。
不能继续操作的玩家输
 - MAX、MIN两个玩家，MAX先走，MAX赢的效用为1，输为-1





例子：取石子

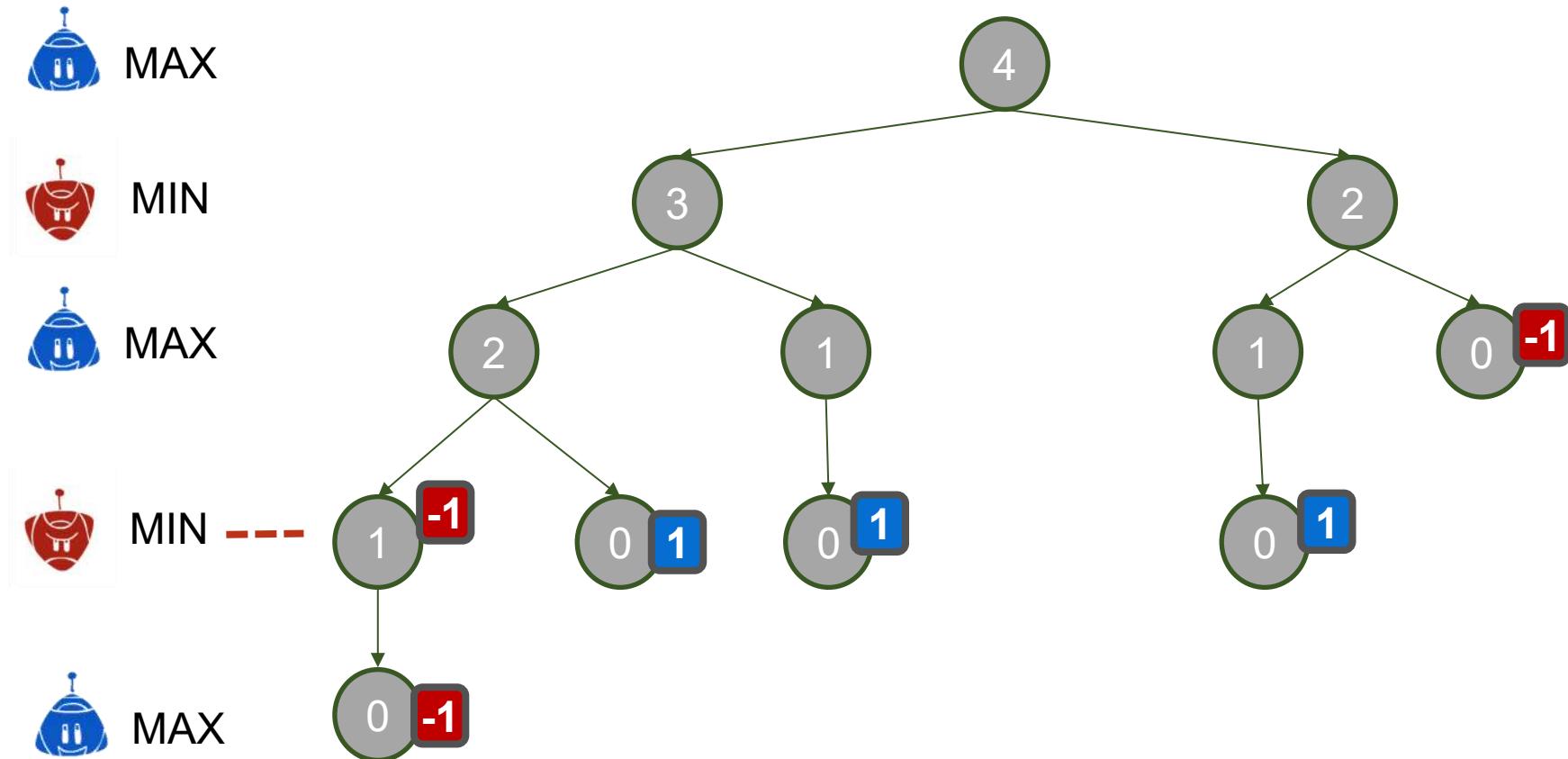
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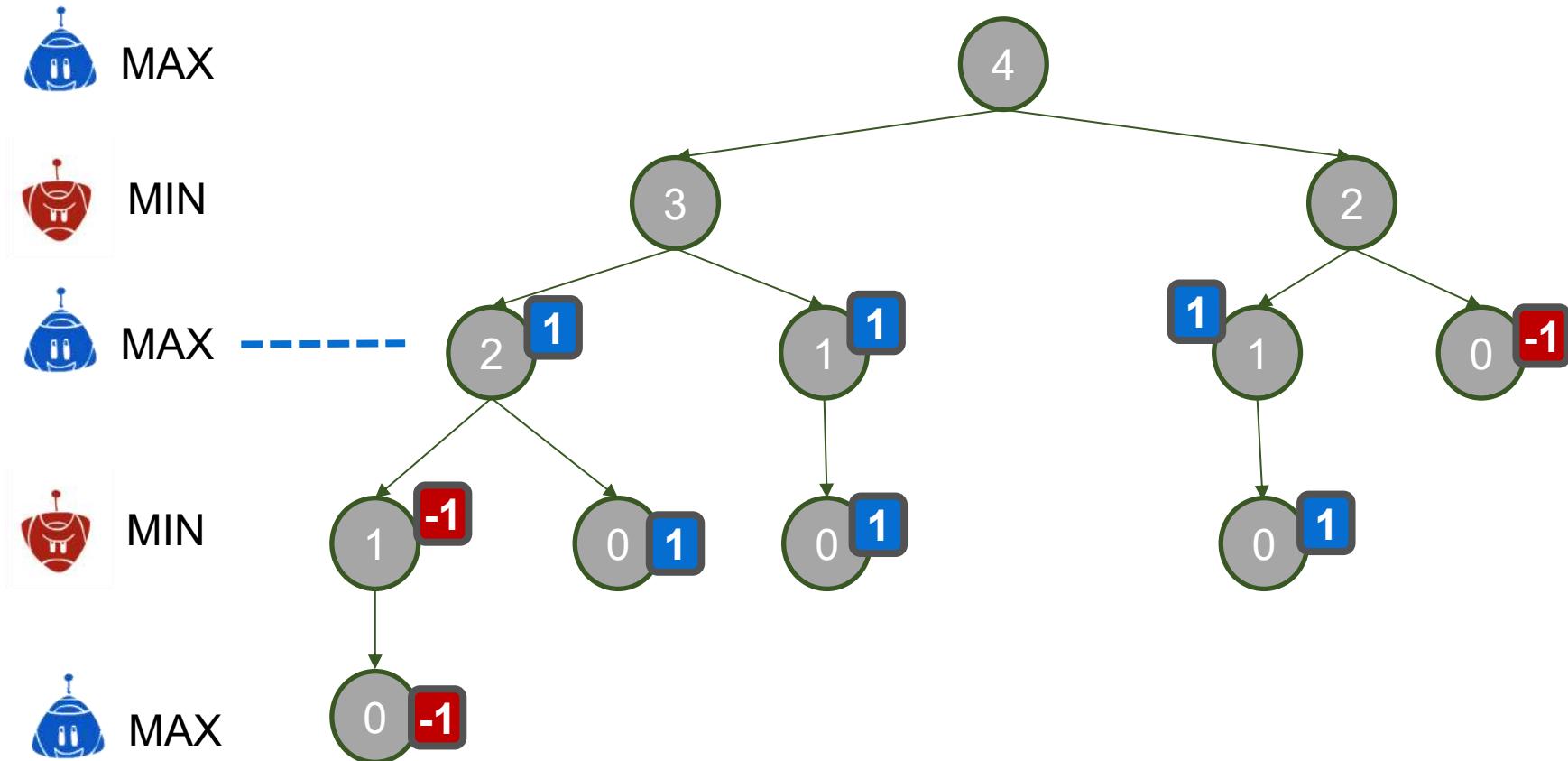
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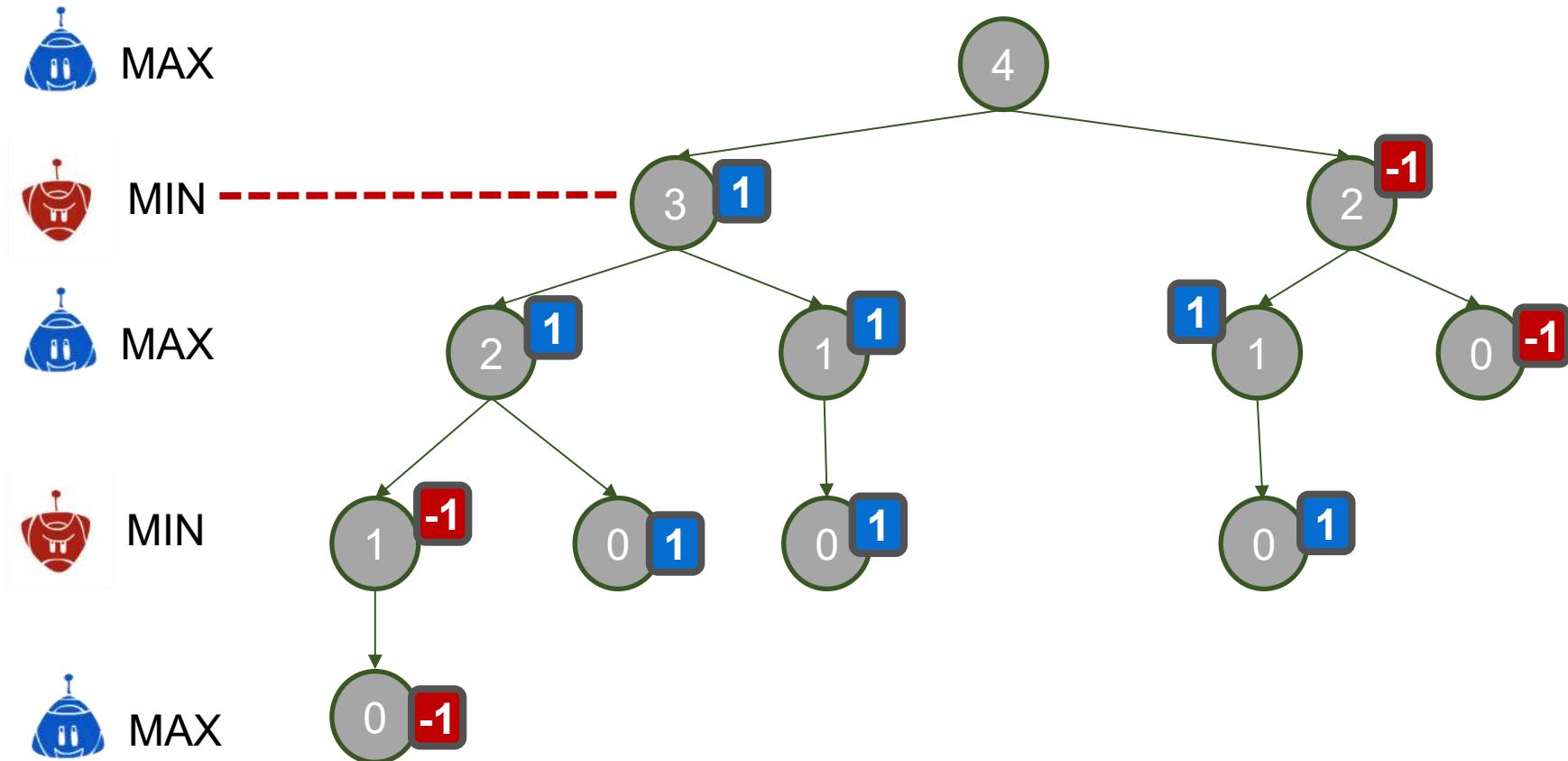
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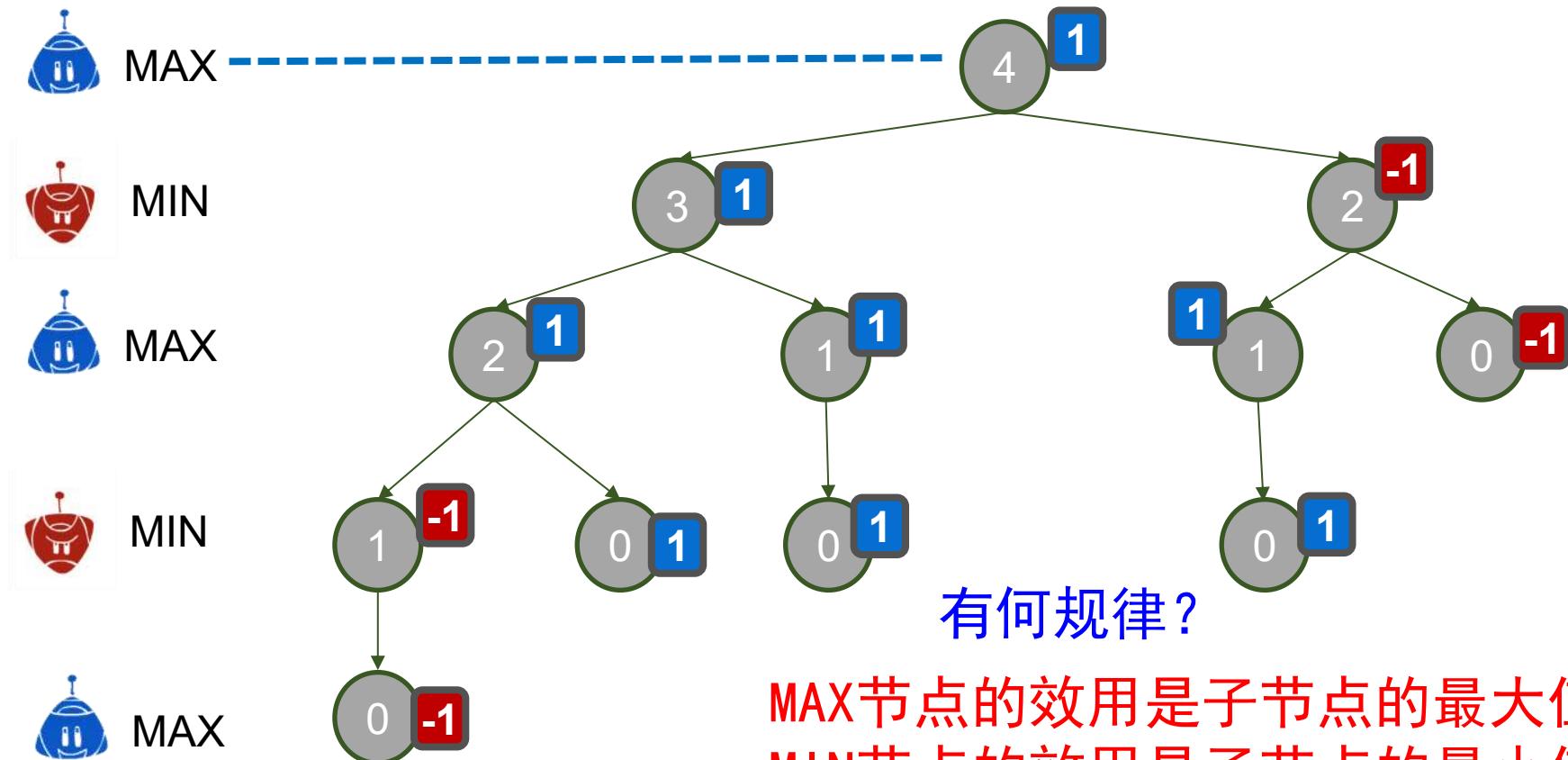
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Game Search Problem

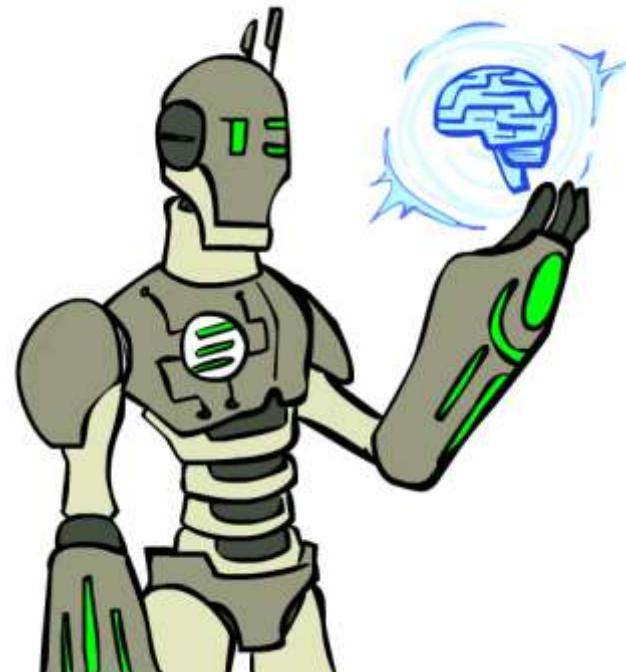
Adversarial Search Problem

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极小极大搜索

□ MiniMax值：

MiniMax(s)

$$= \begin{cases} \text{Utility}(s), & \text{if Terminal_Test}(s), \\ \max_a \text{MiniMax}(\text{Result}(s, a)), & \text{if Player}(s) = \text{MAX}, \\ \min_a \text{MiniMax}(\text{Result}(s, a)), & \text{if Player}(s) = \text{MIN}. \end{cases}$$

□ MiniMax决策（最优决策）：

```
function MiniMax-Decision(state)
    If player(state) = MAX
        return  $\arg \max_a \text{MiniMax}(\text{Result}(state, a))$ 
    If player(state) = MIN
        return  $\arg \min_a \text{MiniMax}(\text{Result}(state, a))$ 
```



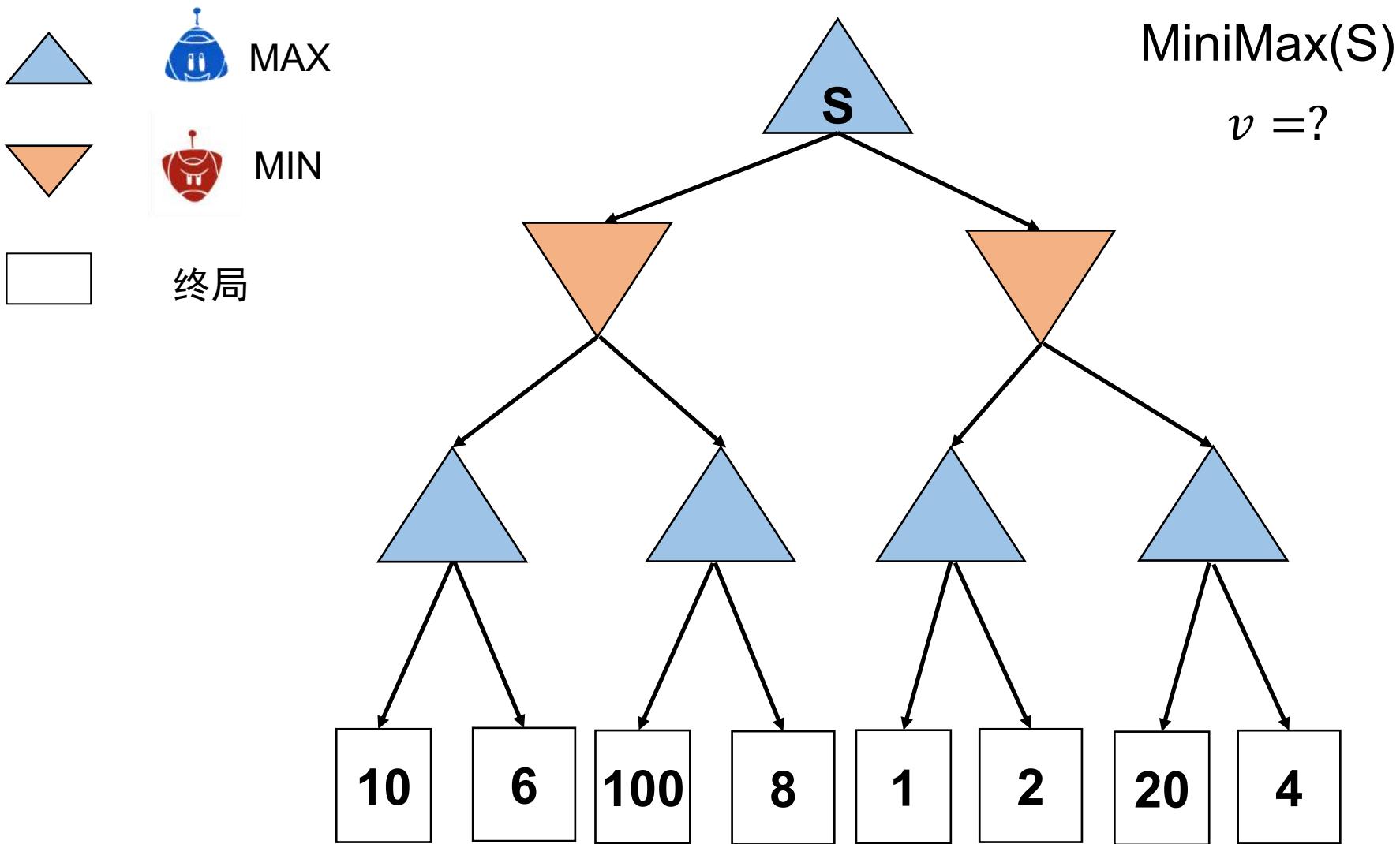
极小极大搜索：算法

```
function MiniMax(state)
    If Terminal-Test(state) return Utility(state)
    If player(state) = MAX {
        v = -∞
        for each child {
            v = max(v, MiniMax(child))
        }
    } else {
        v = ∞
        for each child {
            v = min(v, MiniMax(child))
        }
    }
    return v // 返回值
```



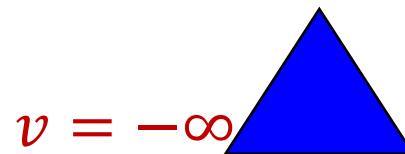


极小极大搜索：算法测试



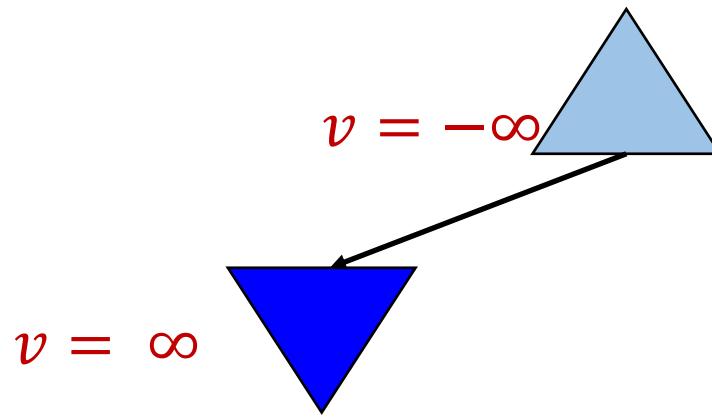


极小极大搜索：算法测试



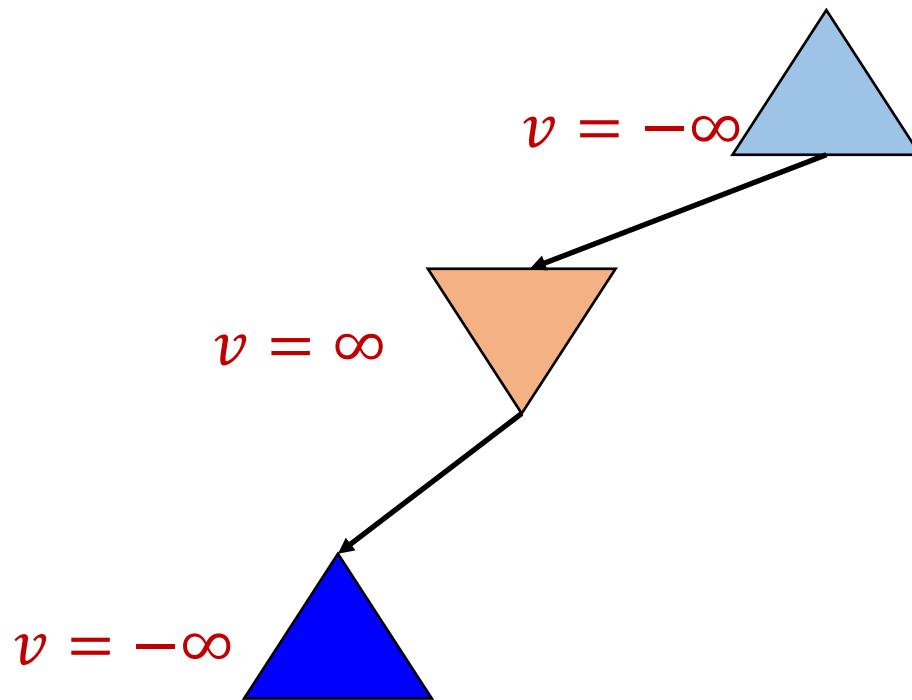


极小极大搜索：算法测试



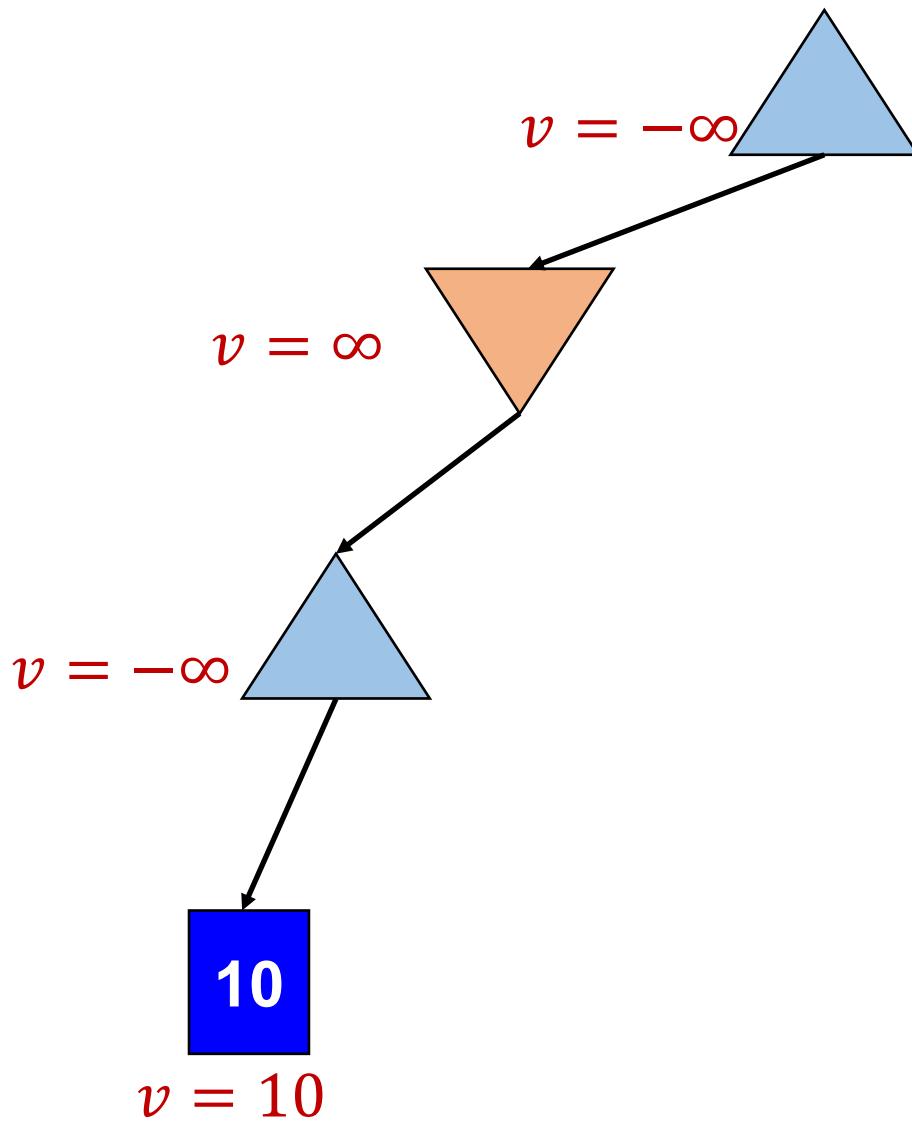


极小极大搜索：算法测试



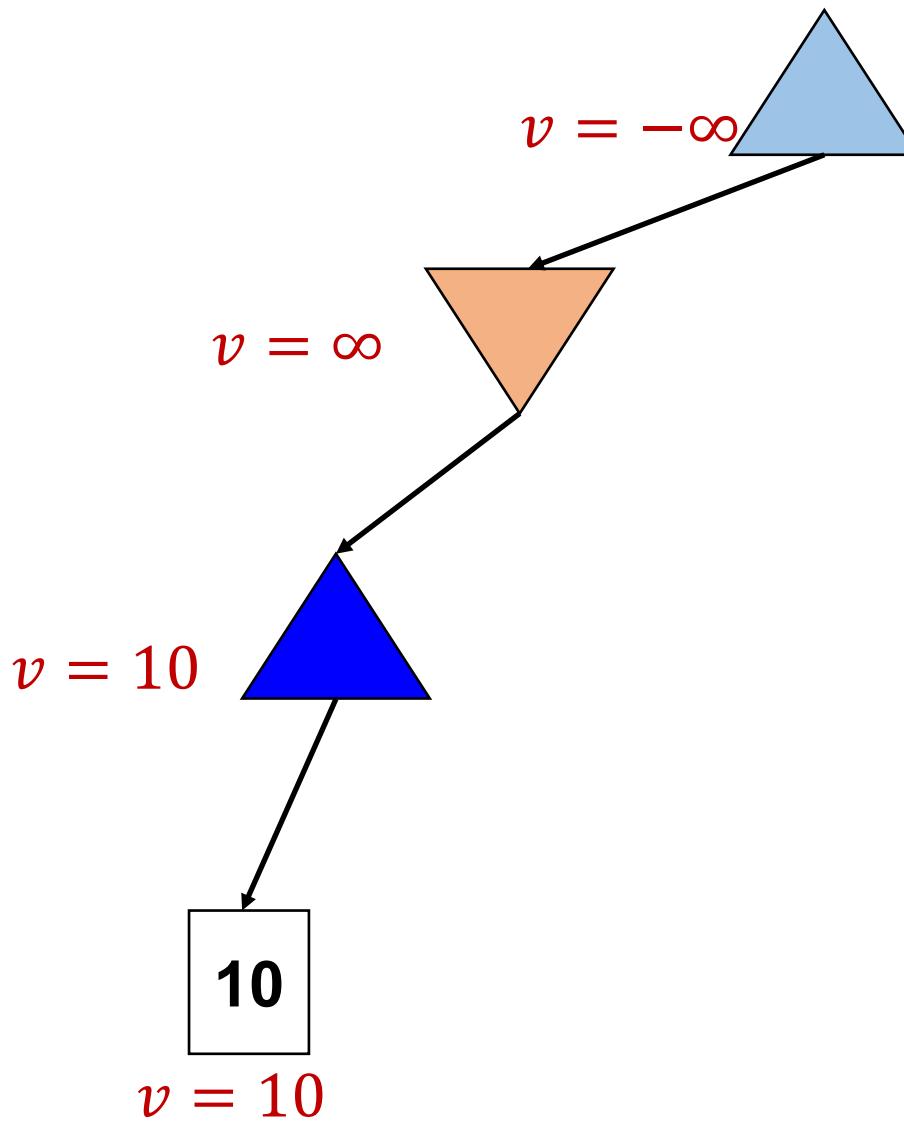


极小极大搜索：算法测试



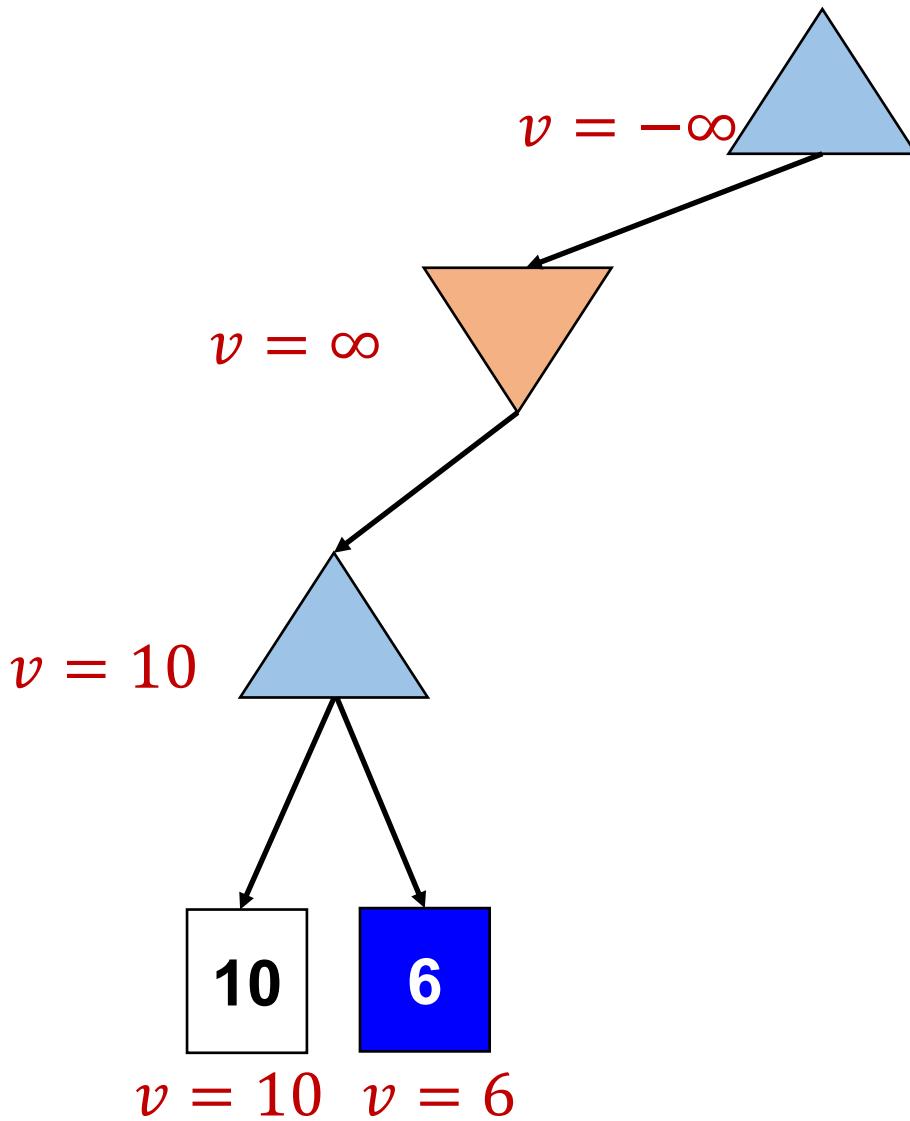


极小极大搜索：算法测试



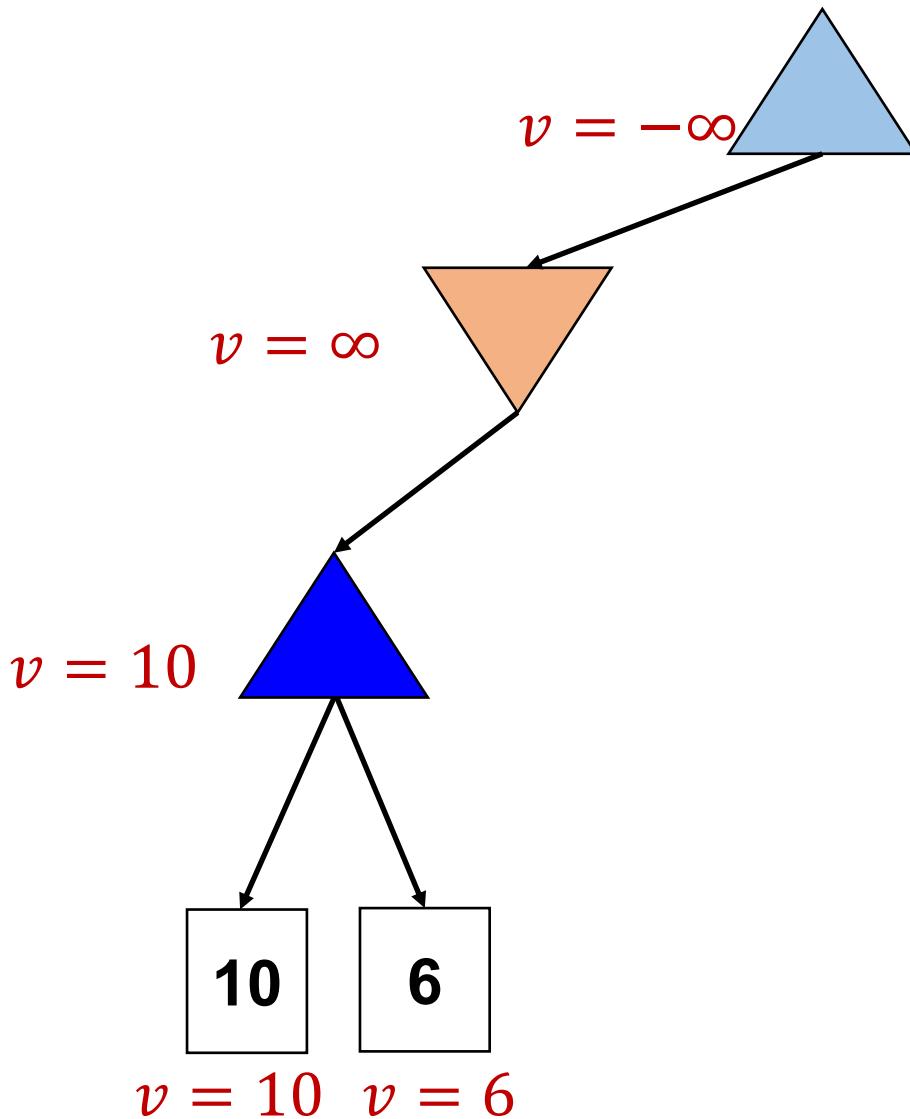


极小极大搜索：算法测试



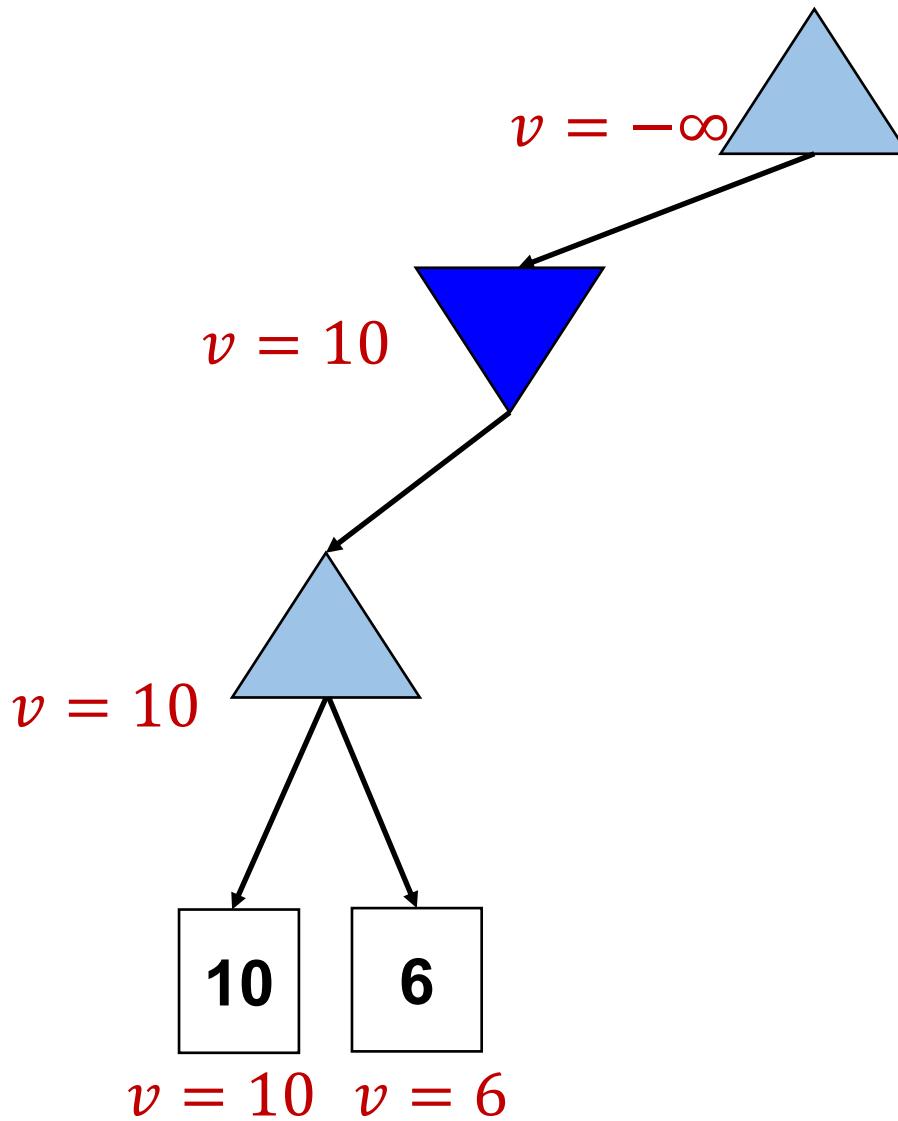


极小极大搜索：算法测试



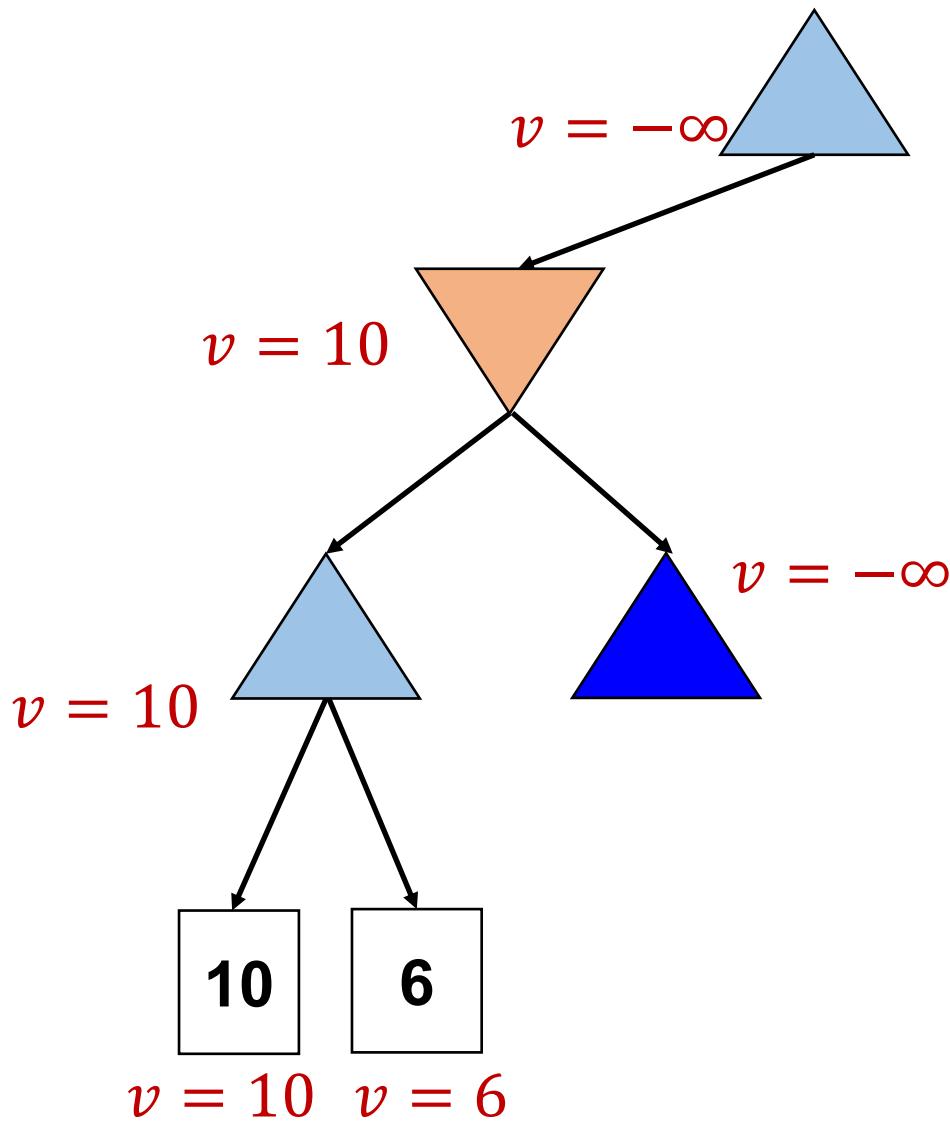


极小极大搜索：算法测试



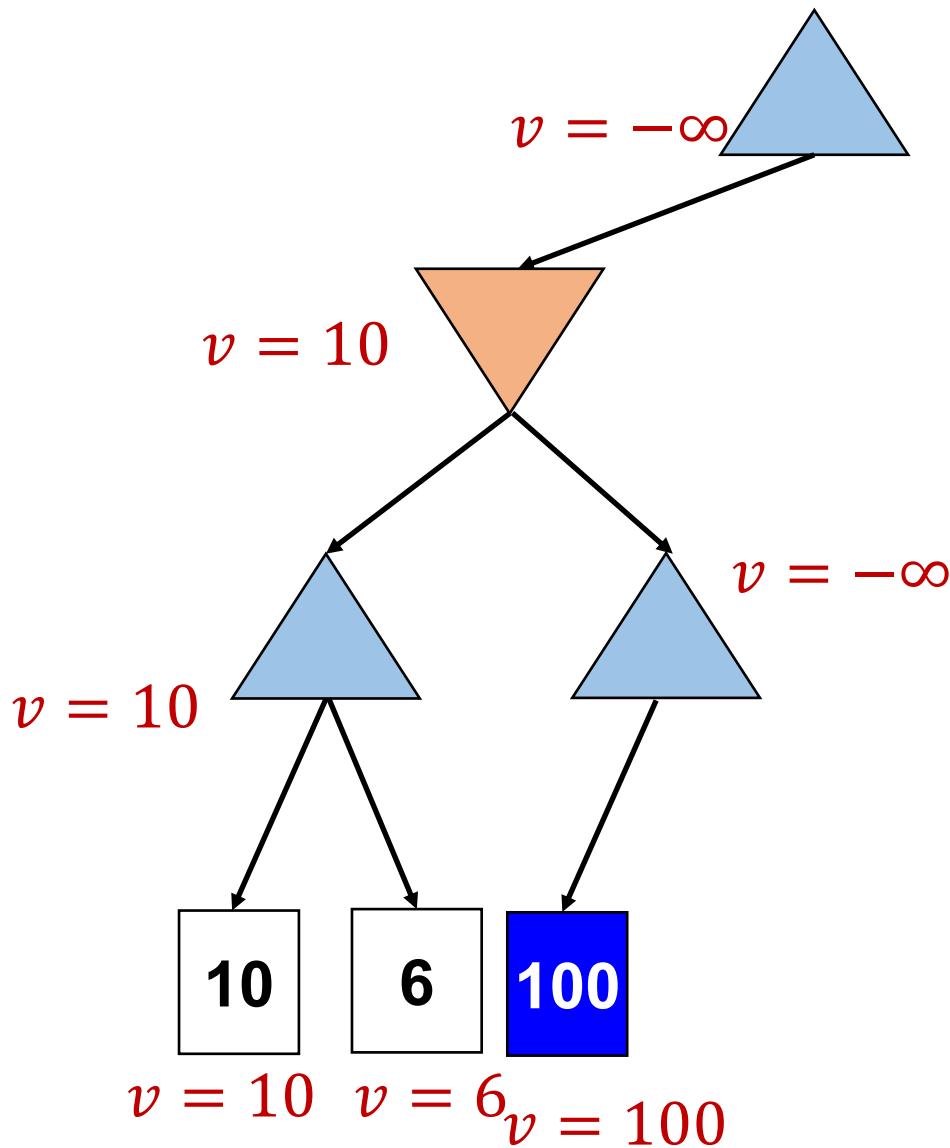


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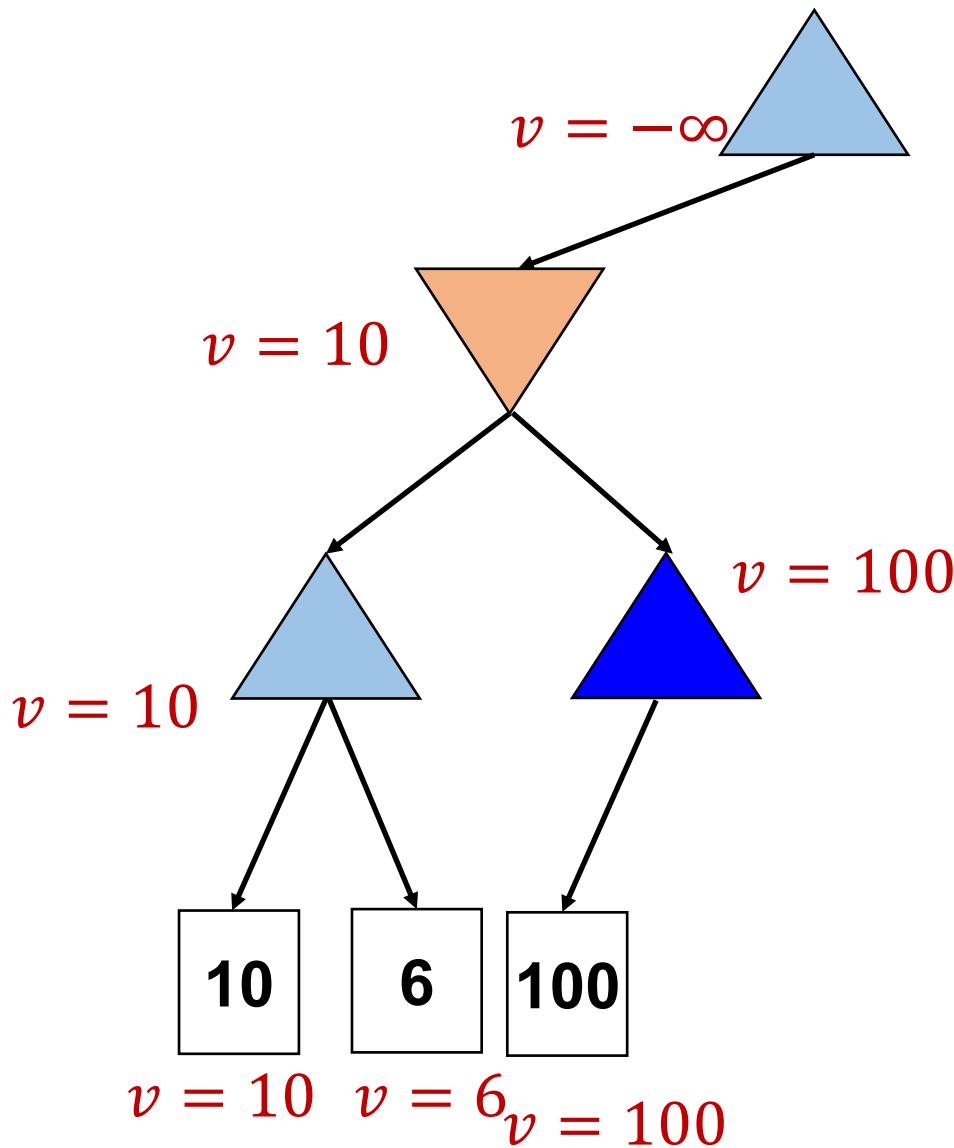


极小极大搜索：算法测试



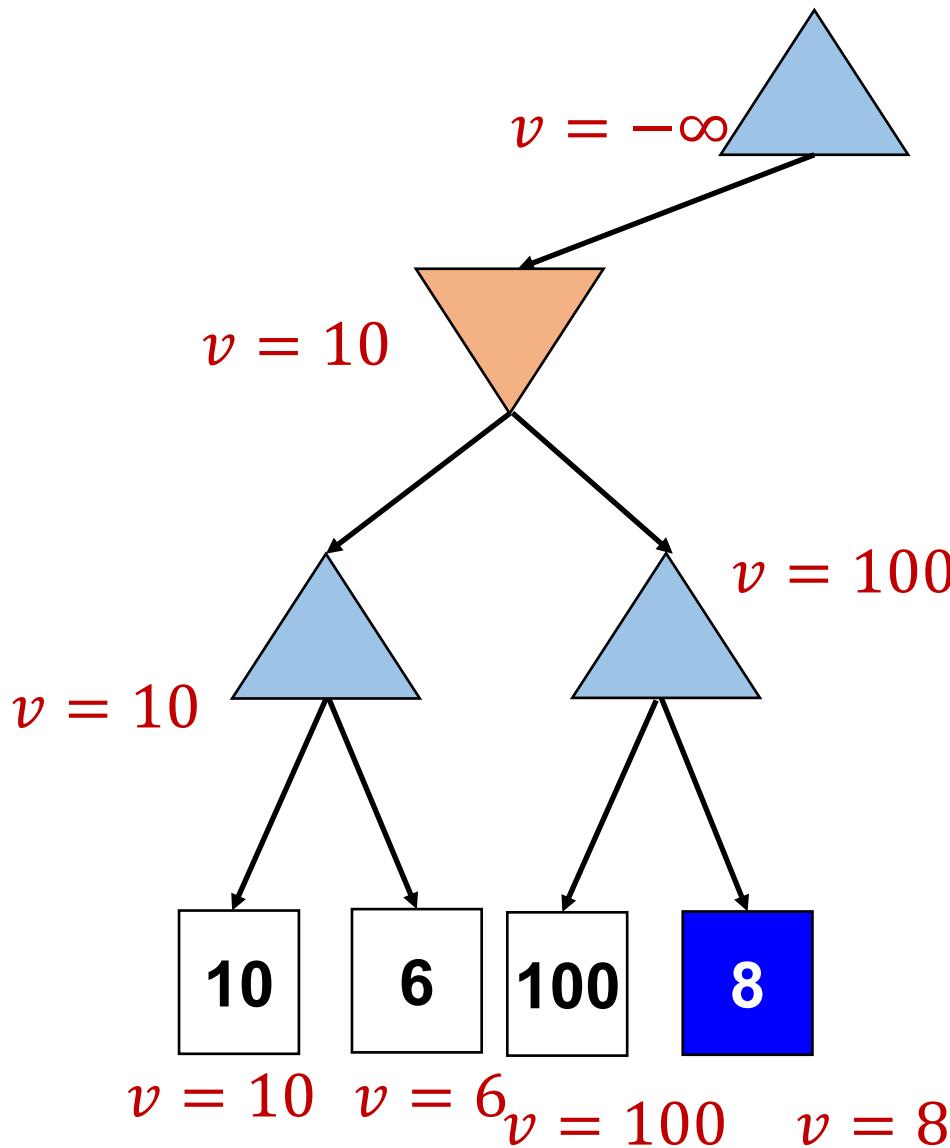


极小极大搜索：算法测试



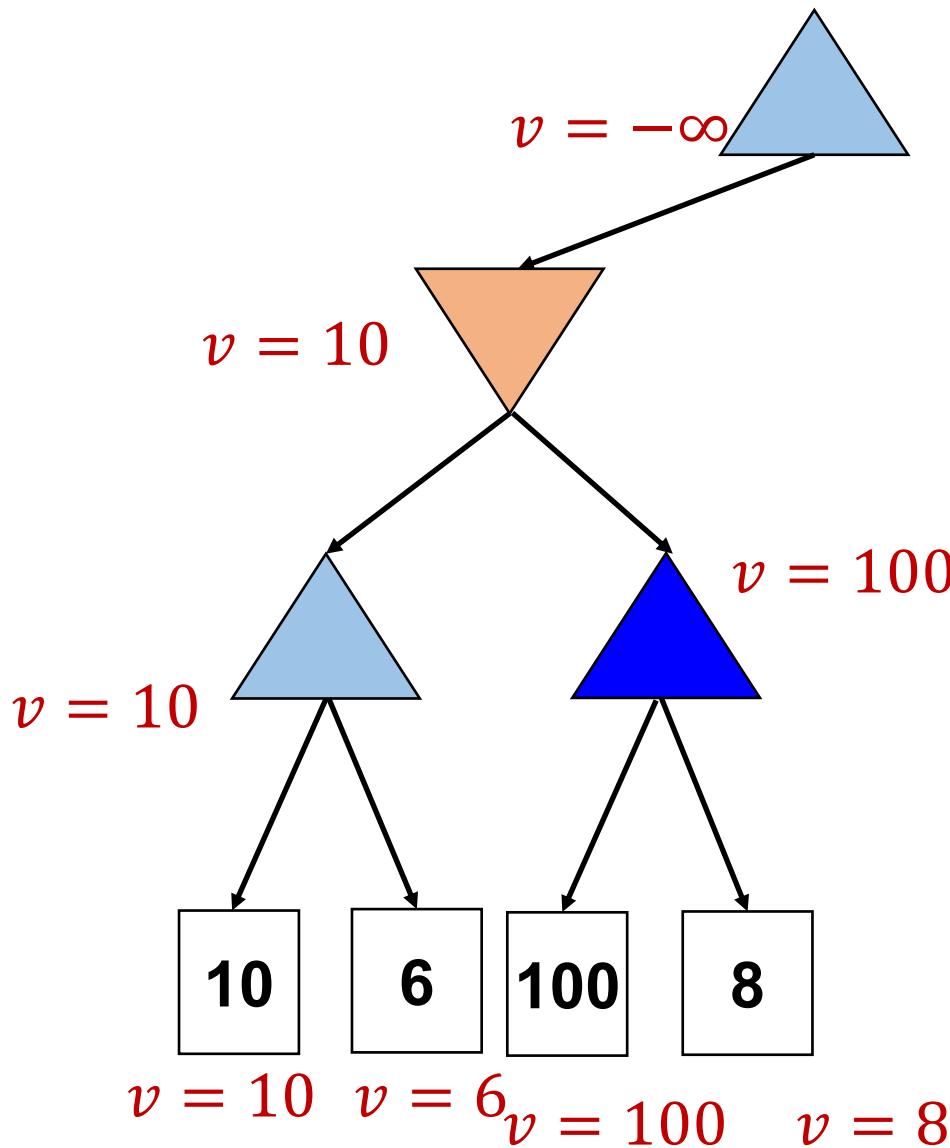


极小极大搜索：算法测试



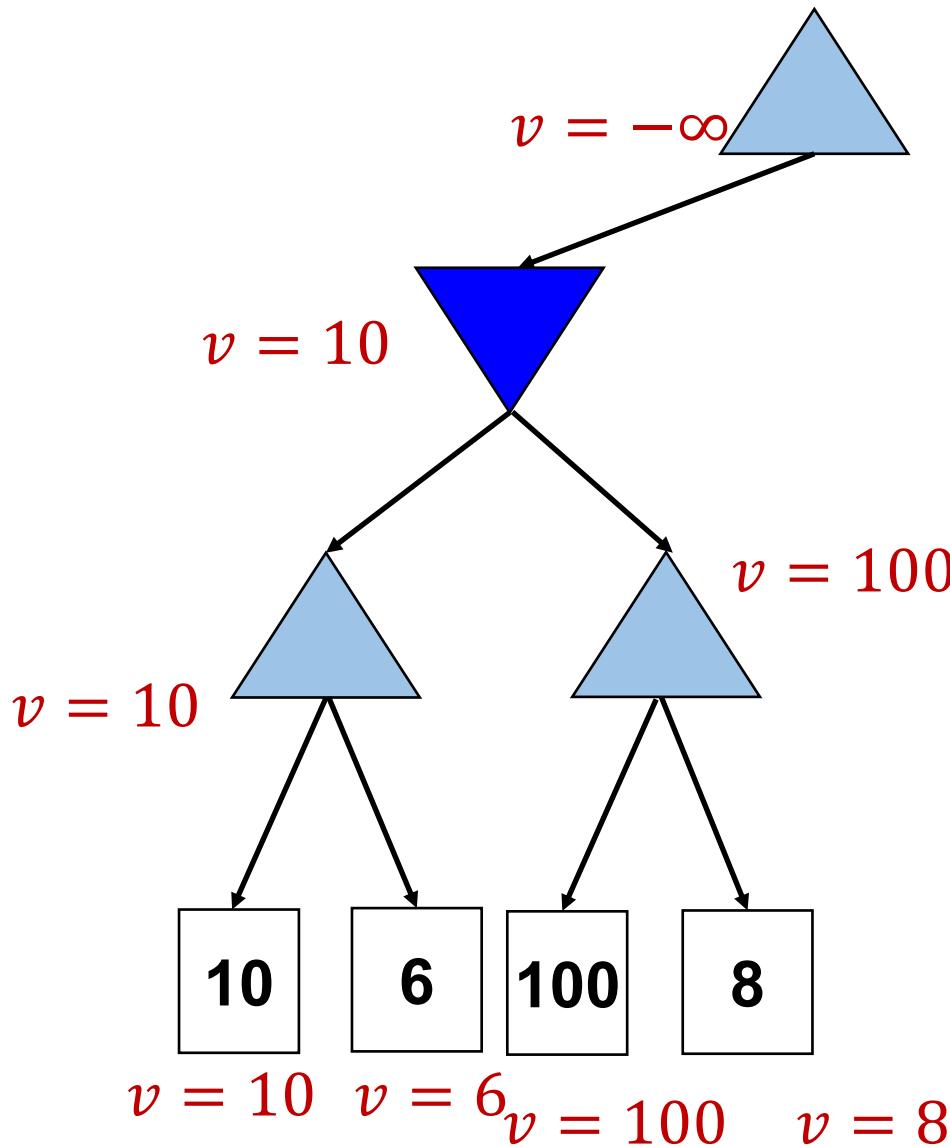


极小极大搜索：算法测试



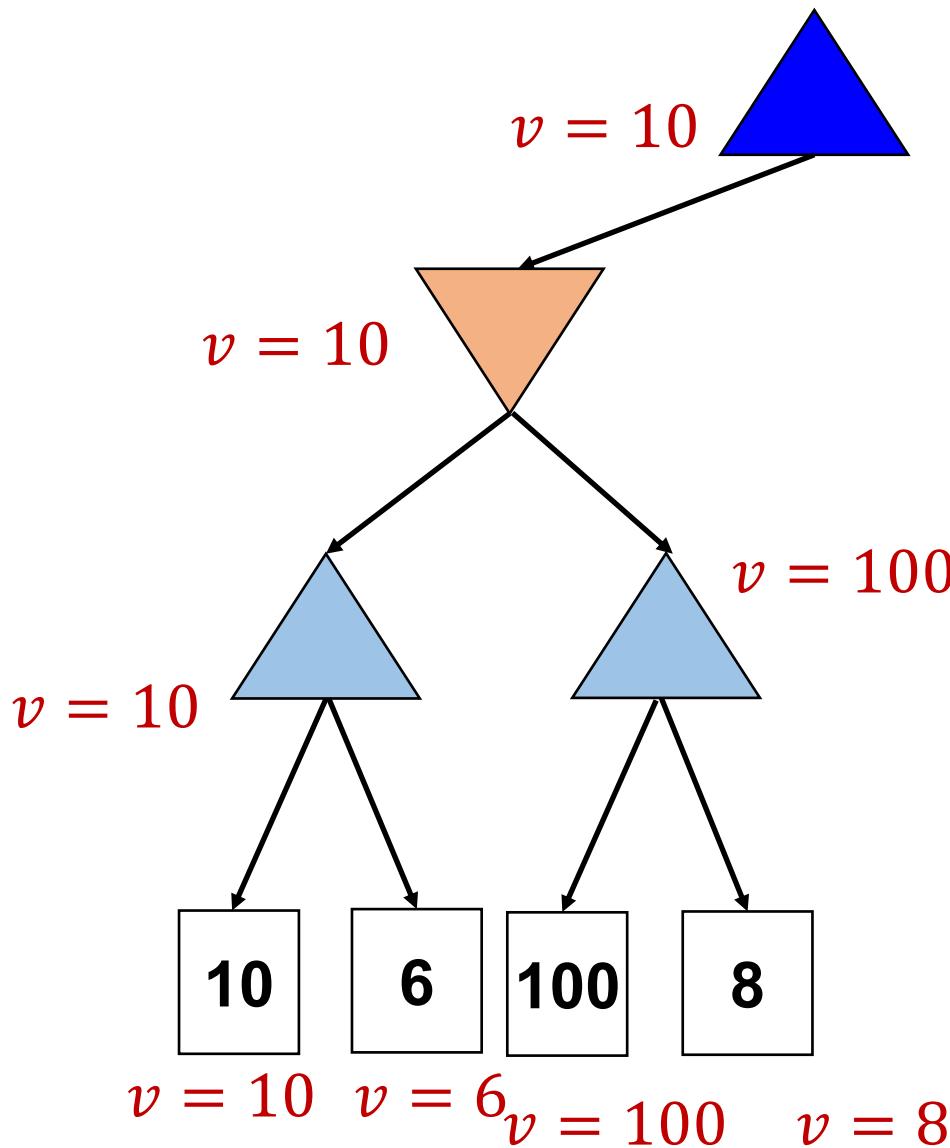


极小极大搜索：算法测试



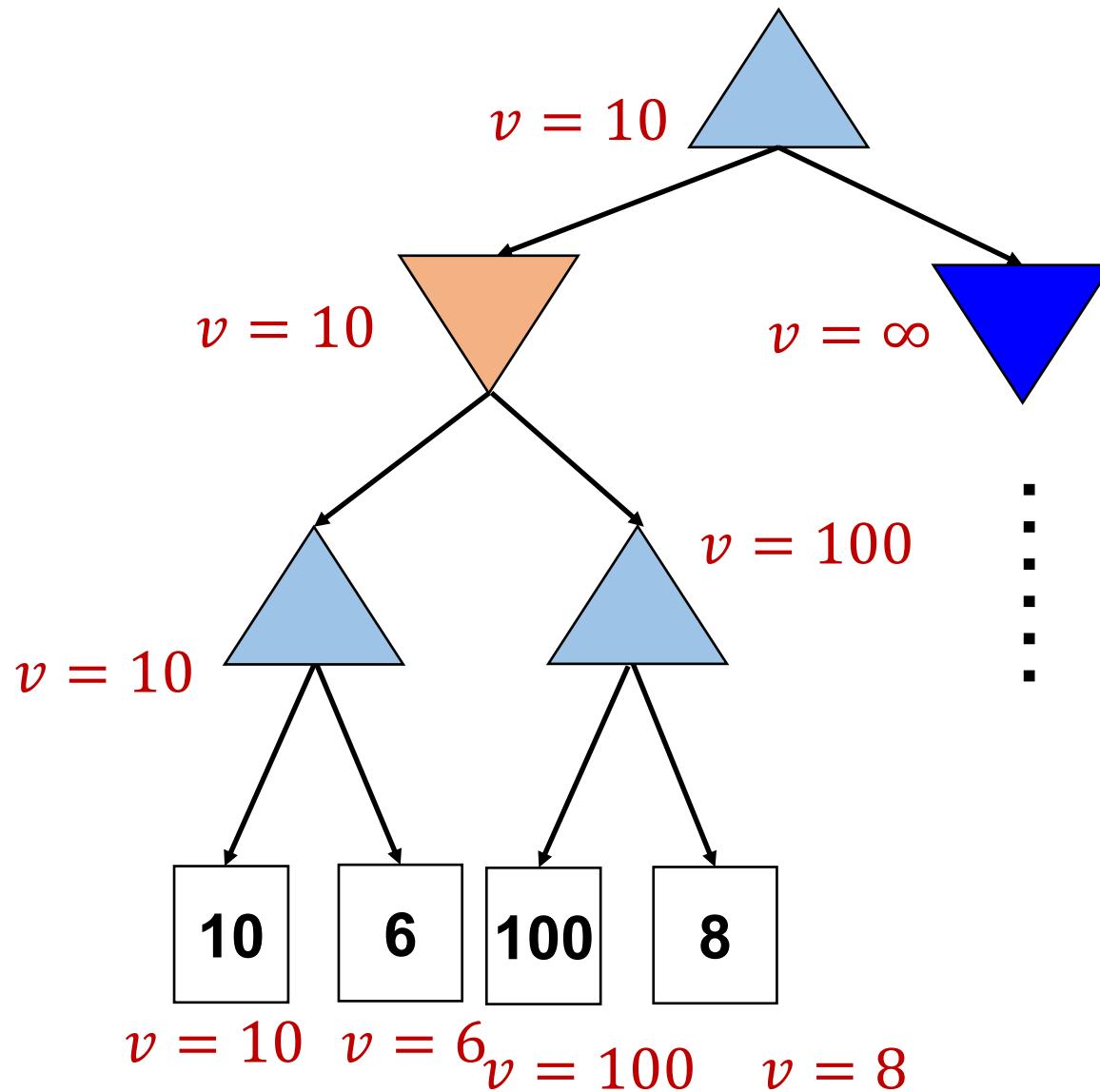


极小极大搜索：算法测试



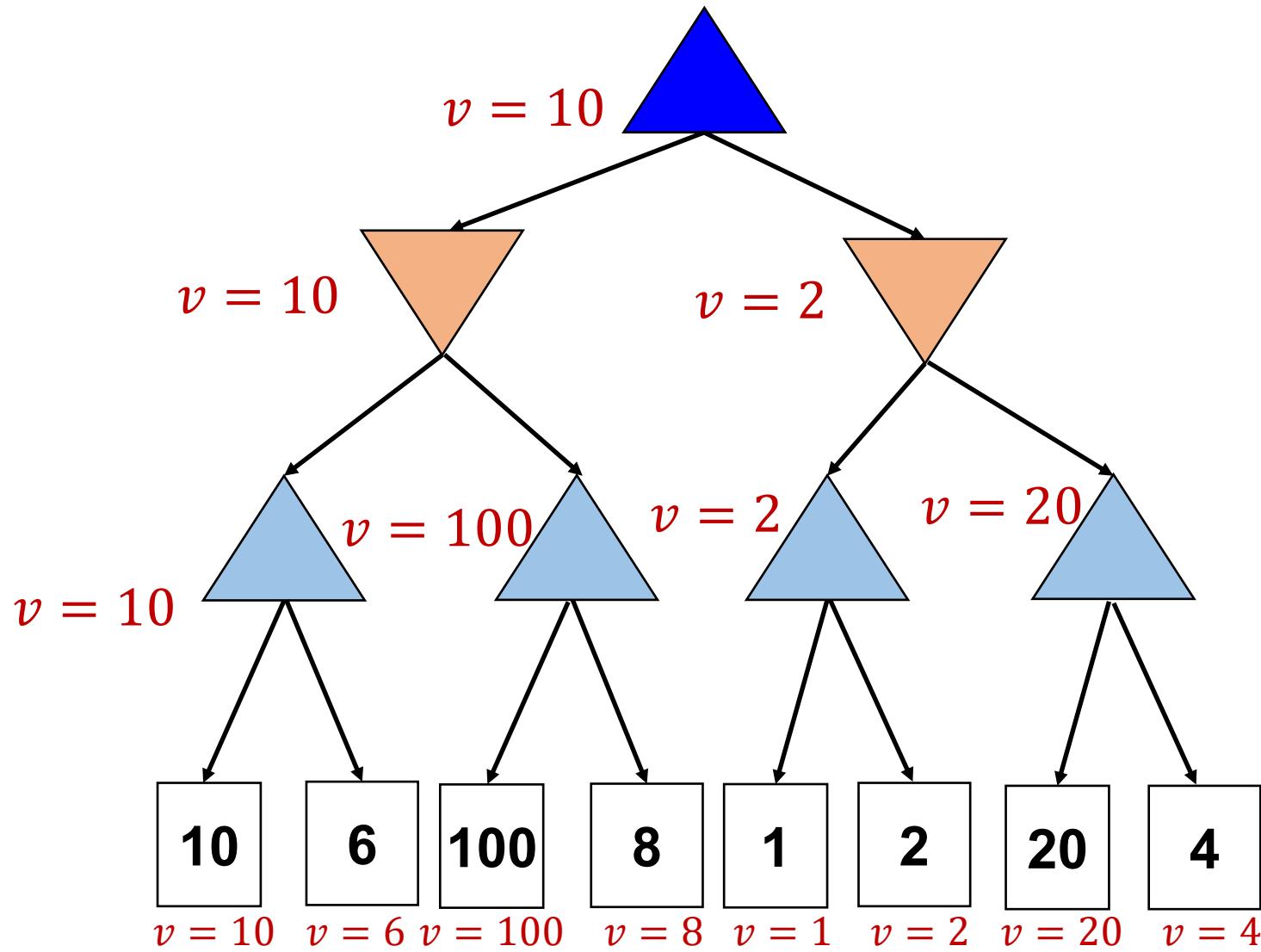


极小极大搜索：算法测试



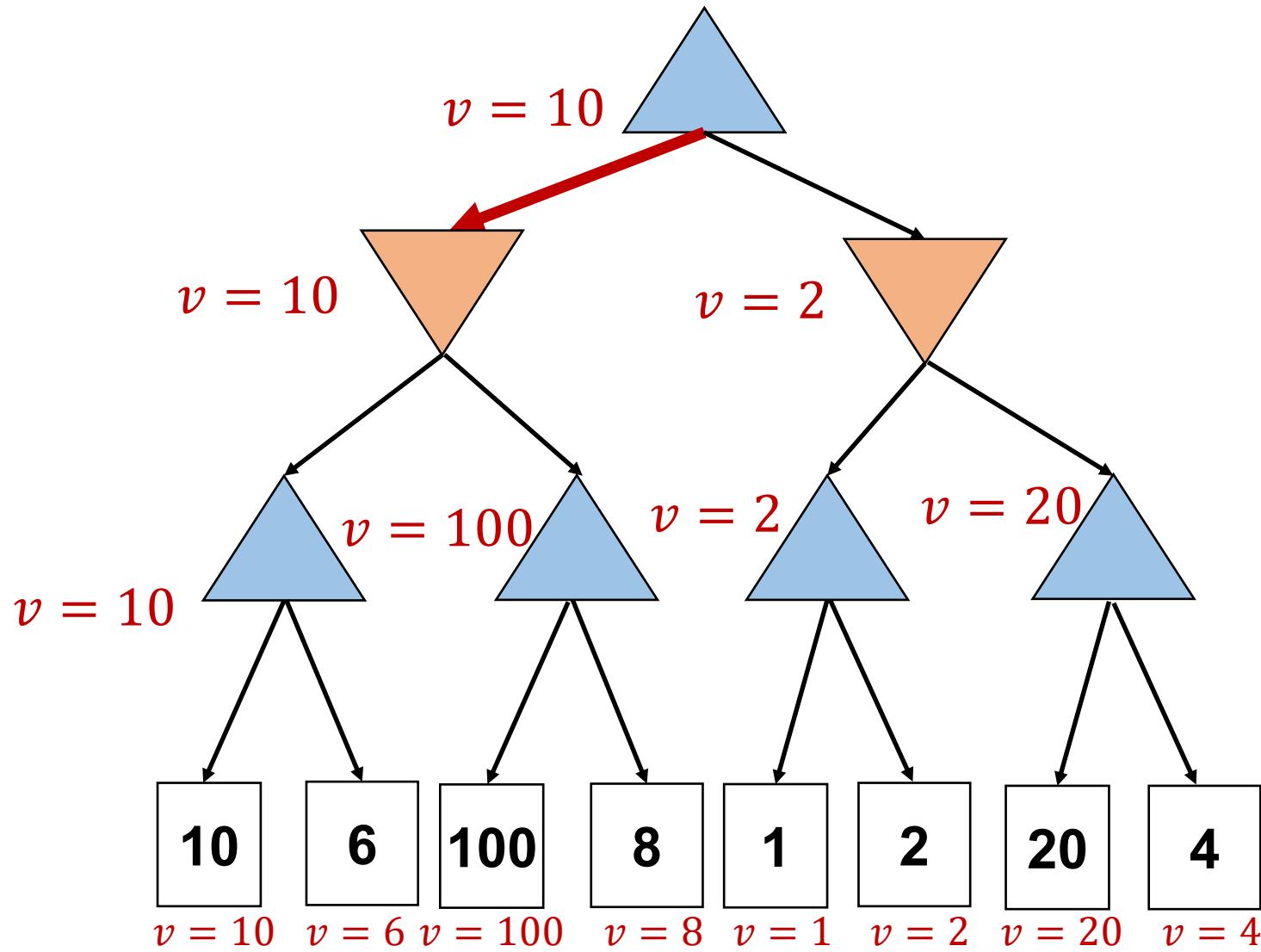


极小极大搜索：算法测试





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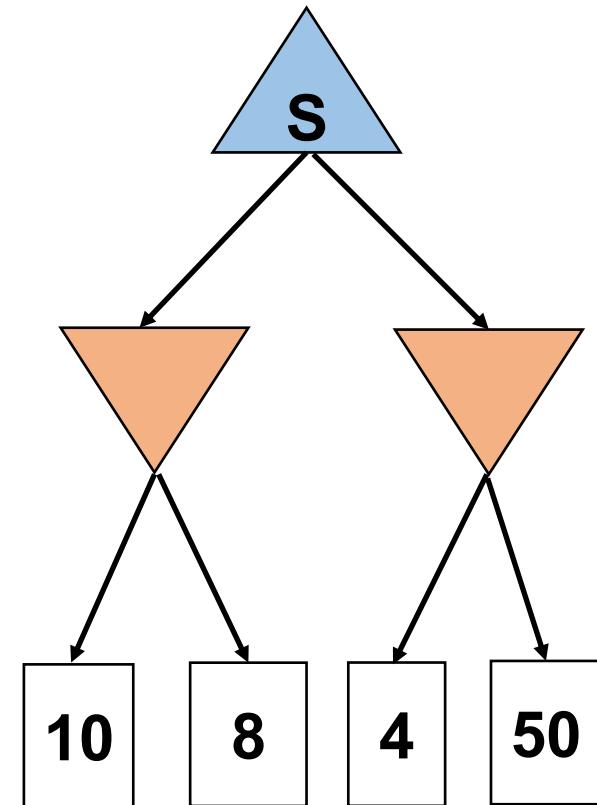




极小极大搜索：练习

```
function MiniMax(state)
If Terminal-Test(state) return Utility(state)
If player(state) = MAX {
    v = -∞
    for each child {
        v = max(v, MiniMax(child))
    }
} else {
    v = ∞
    for each child {
        v = min(v, MiniMax(child))
    }
}
return v //返回值
```

MiniMax(S)





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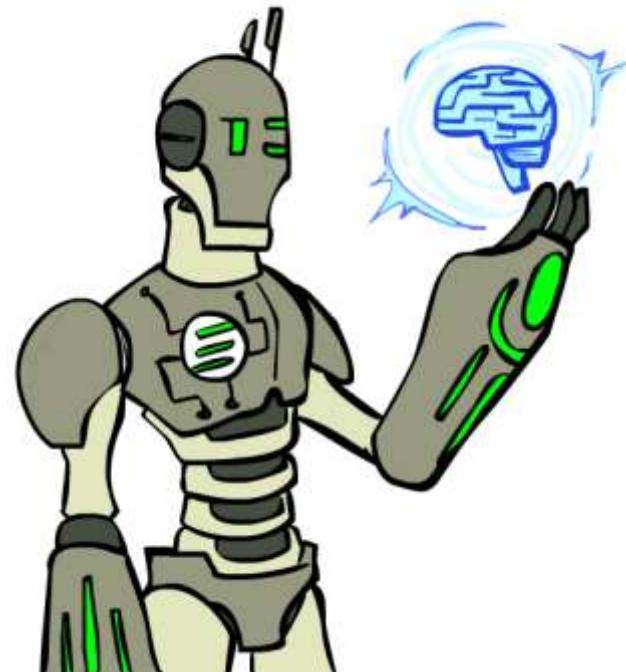
Adversarial Search Problem

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极小极大搜索的效率

□ 与深度优先遍历相同：

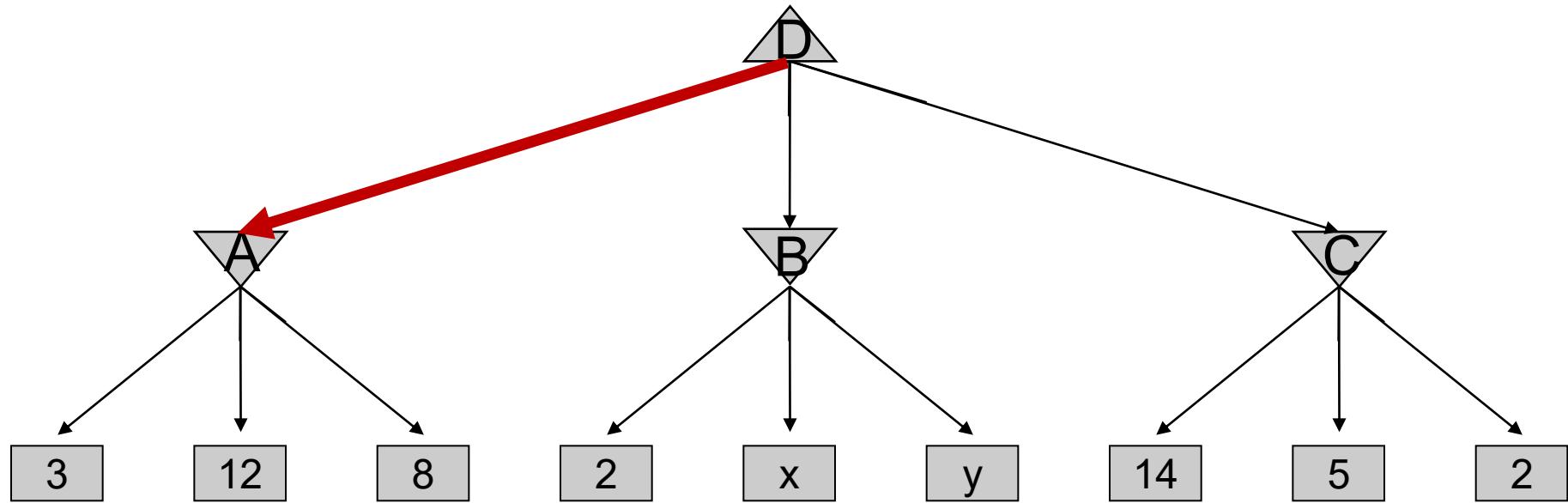
- m 层 (到达终局的步数) , b 分支(行动个数)
- 时间复杂度: $\mathcal{O}(b^m)$
- 空间复杂度: $\mathcal{O}(bm)$
- 结论: 很多情况下无法运行 (比如: 围棋)

□ 在初始状态做出最优行为决策是否有必要遍历整棵树?





是否有必要遍历整棵树？



MiniMax(D)

$$= \max(\min(3, 12, 8), \min(2, x, y), \min(14, 5, 2))$$

$$= \max(3, \min(2, x, y), 2) = 3$$

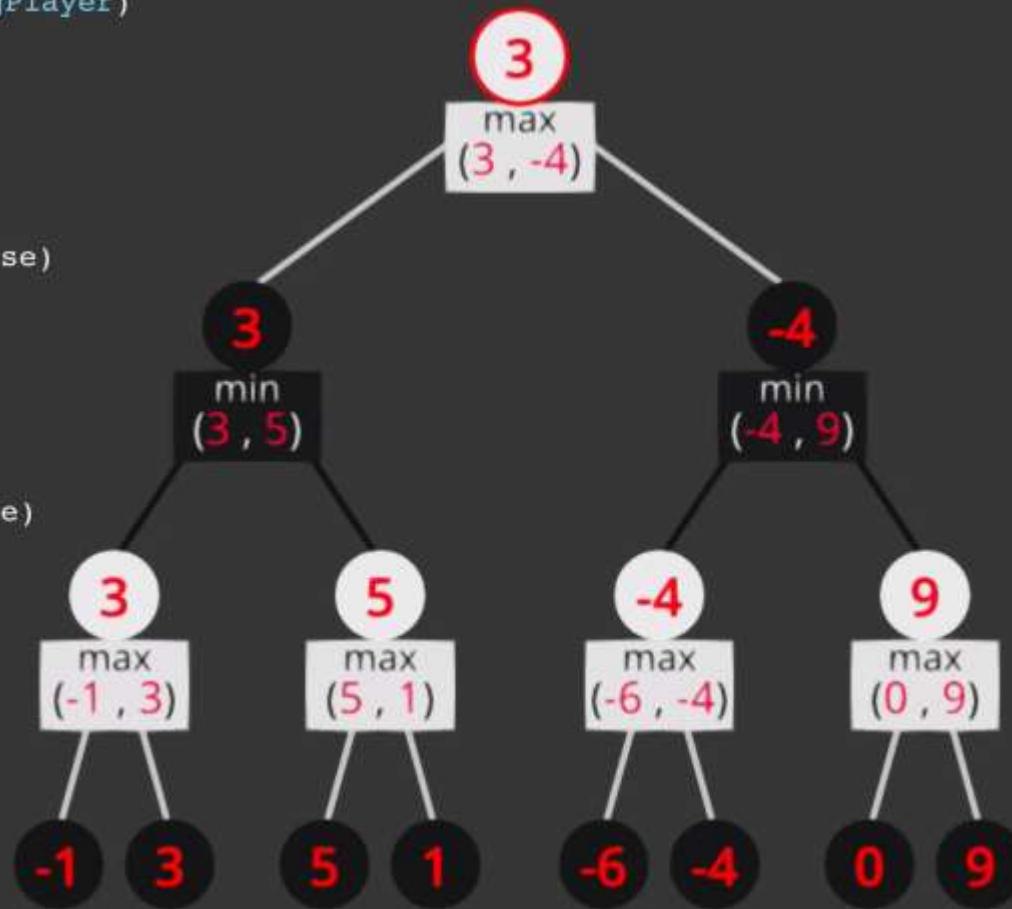


```
function minimax(position, depth, maximizingPlayer)
    if depth == 0 or game over in position
        return static evaluation of position

    if maximizingPlayer
        maxEval = -infinity
        for each child of position
            eval = minimax(child, depth - 1, false)
            maxEval = max(maxEval, eval)
        return maxEval

    else
        minEval = +infinity
        for each child of position
            eval = minimax(child, depth - 1, true)
            minEval = min(minEval, eval)
        return minEval

// initial call
minimax(currentPosition, 3, true)
```





α - β 决策

□ α - β 决策：

- 类似Minimax决策
- α : Minimax的下界，初始值= $-\infty$
- β : Minimax的上界，初始值= ∞
- 减少博弈树的分枝，不影响决策的最优性，即：等同于Minimax决策

```
function AlphaBeta-Decision(state)
If player(state) = MAX
    return arg maxa AlphaBeta(Result(state, a),  $-\infty$ ,  $\infty$ )
If player(state) = MIN
    return arg mina AlphaBeta(Result(state, a),  $-\infty$ ,  $\infty$ )
```

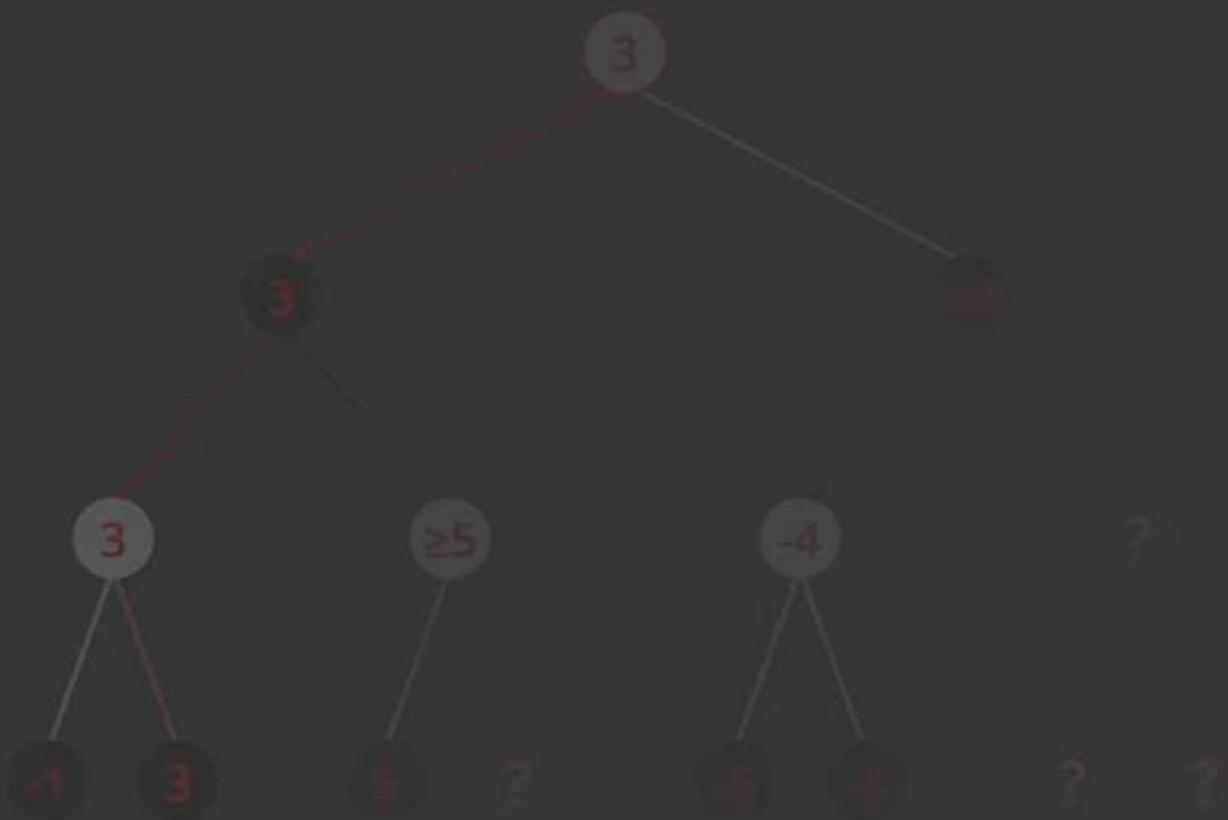
如何实现AlphaBeta(state, α , β)函数？



α - β 剪枝

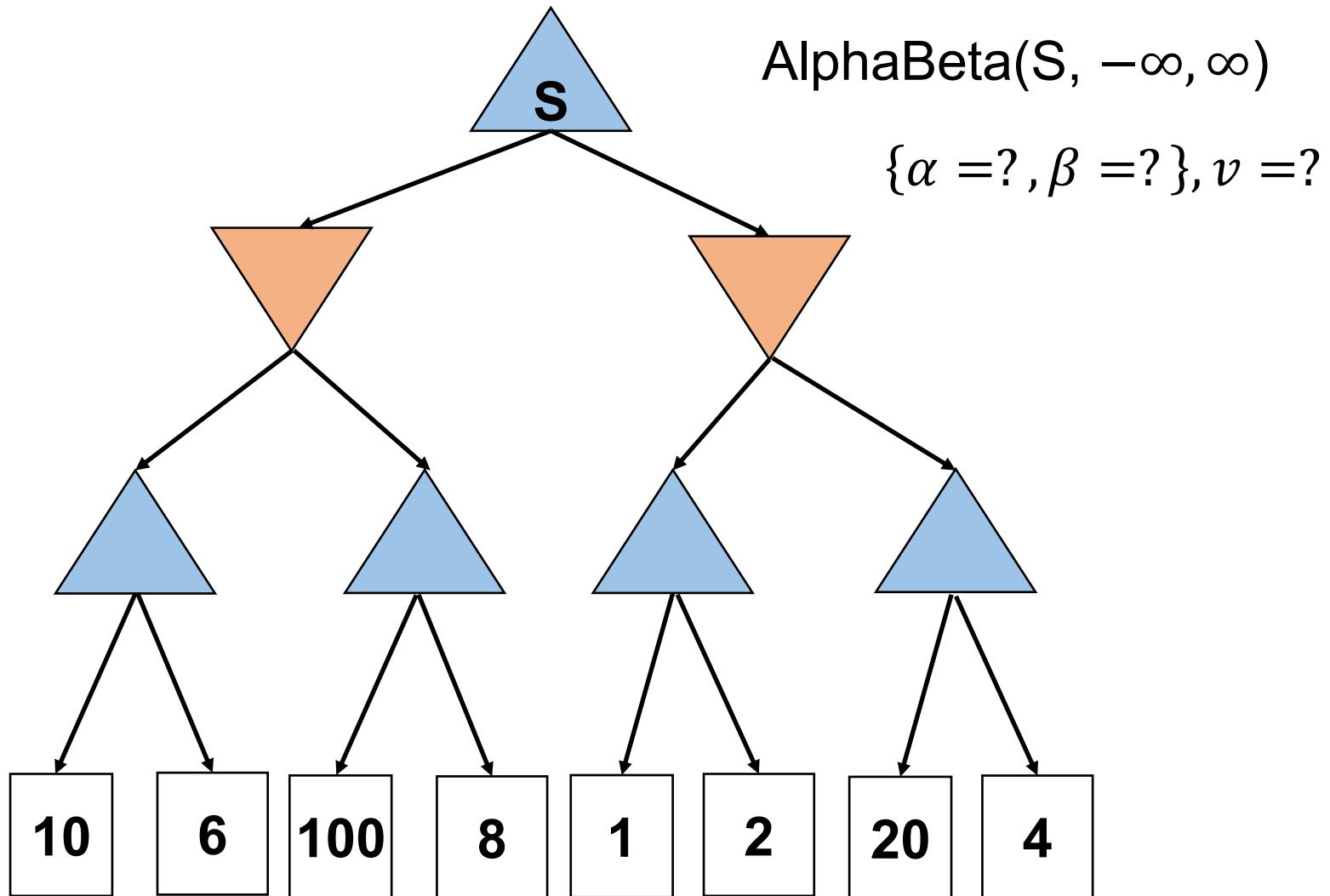
```
function AlphaBeta(state,  $\alpha$ ,  $\beta$ )
If Terminal-Test(state) return Utility(state)
If player(state) = MAX {
    v =  $-\infty$ 
    for each child {
        v = max(v, AlphaBeta(child,  $\alpha$ ,  $\beta$ ))
         $\alpha$  = max( $\alpha$ , v)
        if  $\beta \leq \alpha$  then break // 裁剪 }
    }
else {
    v =  $\infty$ 
    for each child {
        v = min(v, AlphaBeta(child,  $\alpha$ ,  $\beta$ ))
         $\beta$  = min( $\beta$ , v)
        if  $\beta \leq \alpha$  then break // 裁剪 }
    }
return v // 返回值
```

- α : MiniMax 值的下界，不断增加
- β : MiniMax 值的上届，不断减小
- 裁剪条件：
$$\beta \leq \alpha$$
- 关注每个状态：
 - 向子节点传递 α 与 β
 - 接受子节点的返回值 v ，更新 α (MAX) 或 β (MIN)
 - 返回值 v





α - β 剪枝：算法测试

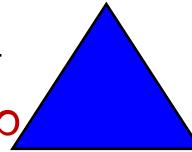




α - β 剪枝：算法测试

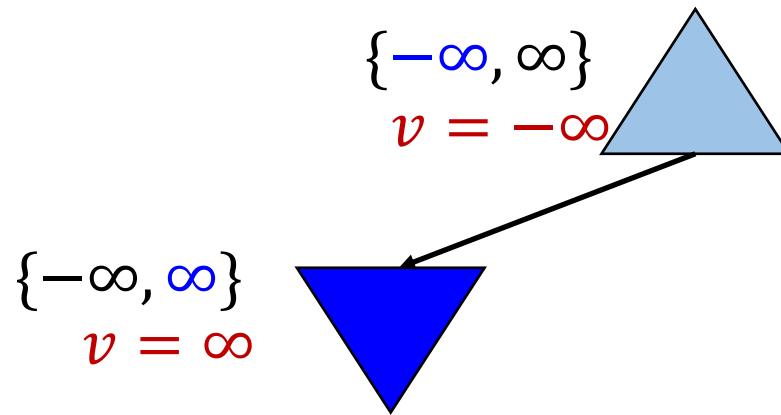
$\{-\infty, \infty\}$

$v = -\infty$



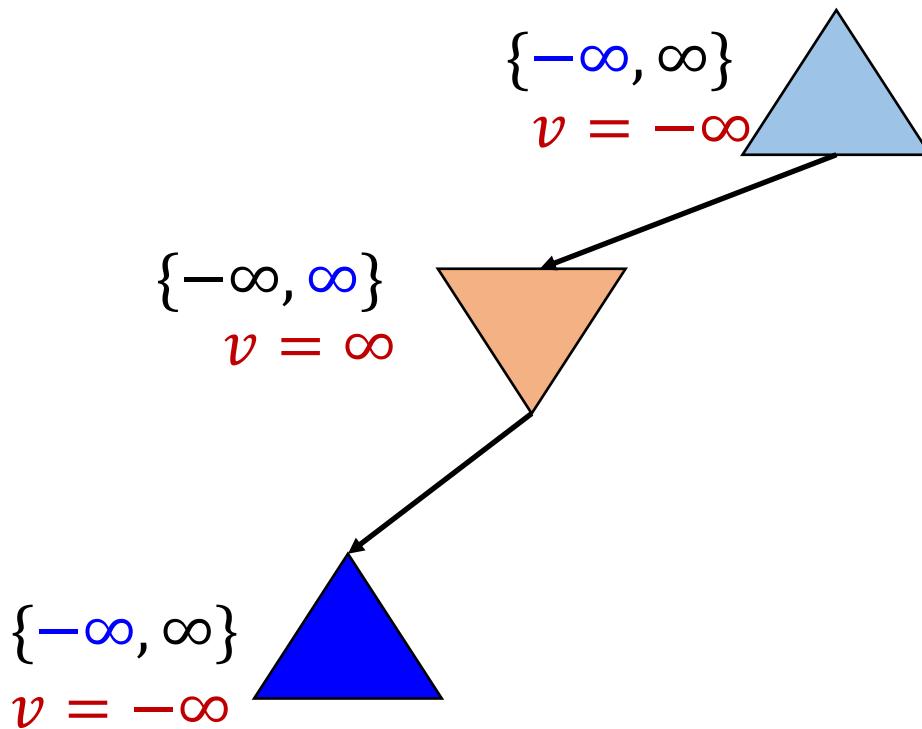


α - β 剪枝：算法测试



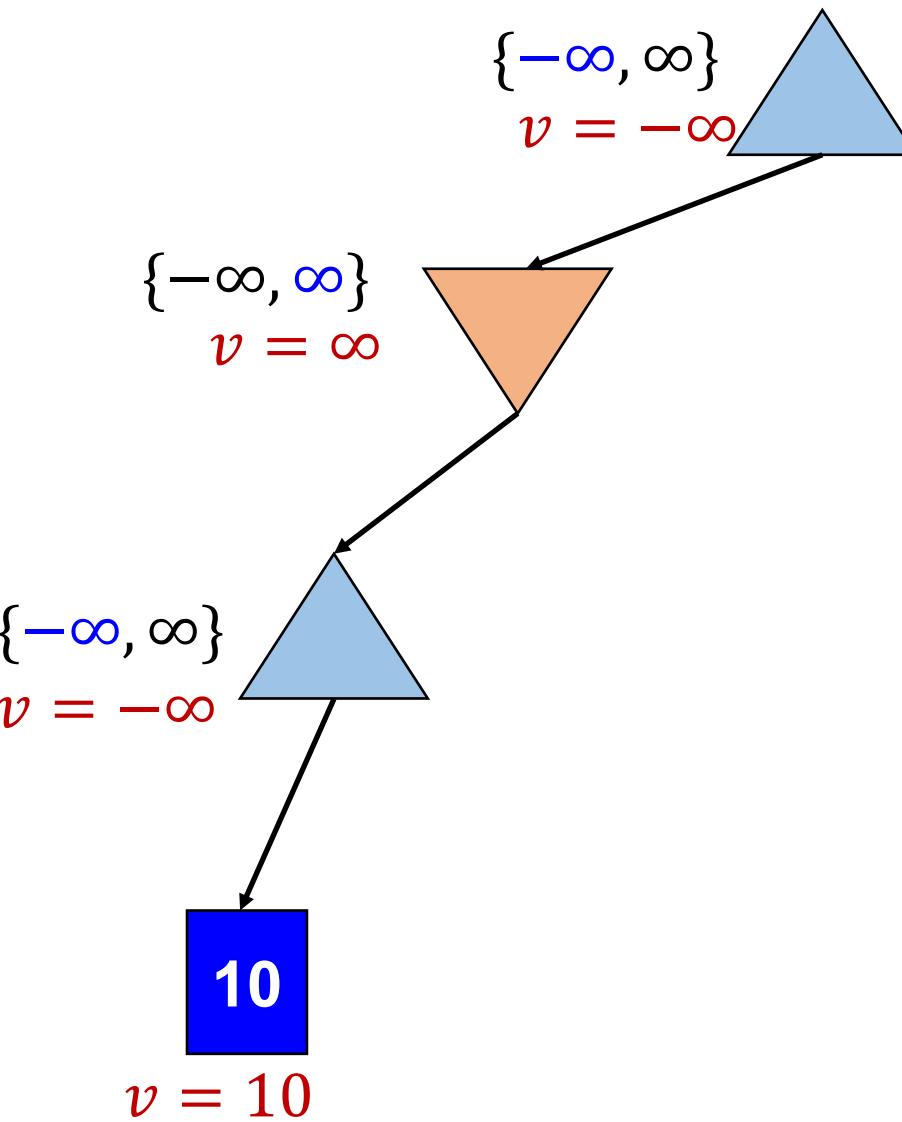


α - β 剪枝：算法测试



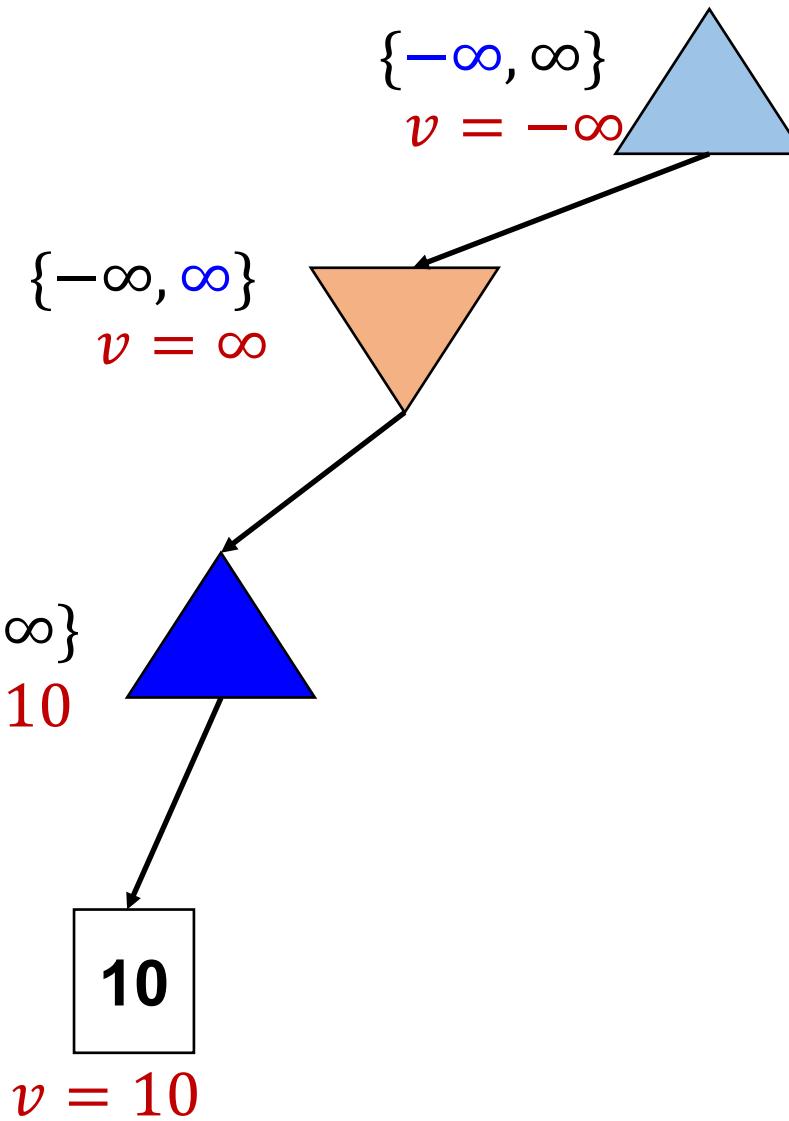


α - β 剪枝：算法测试



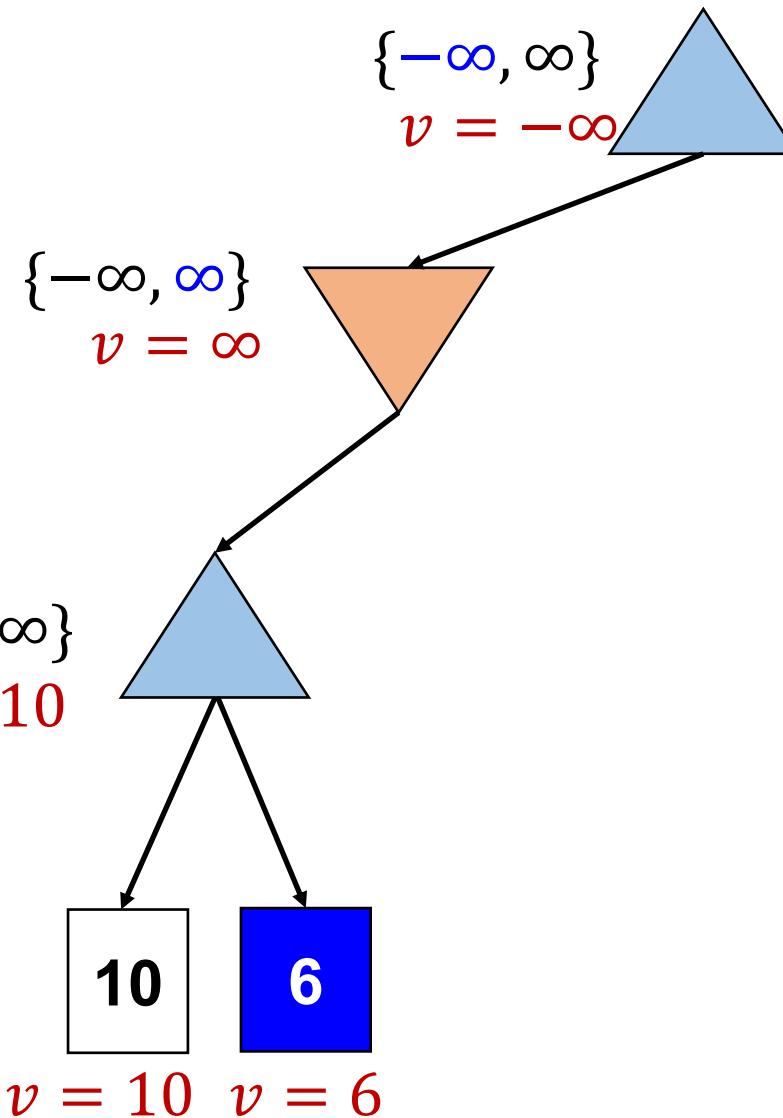


α - β 剪枝：算法测试



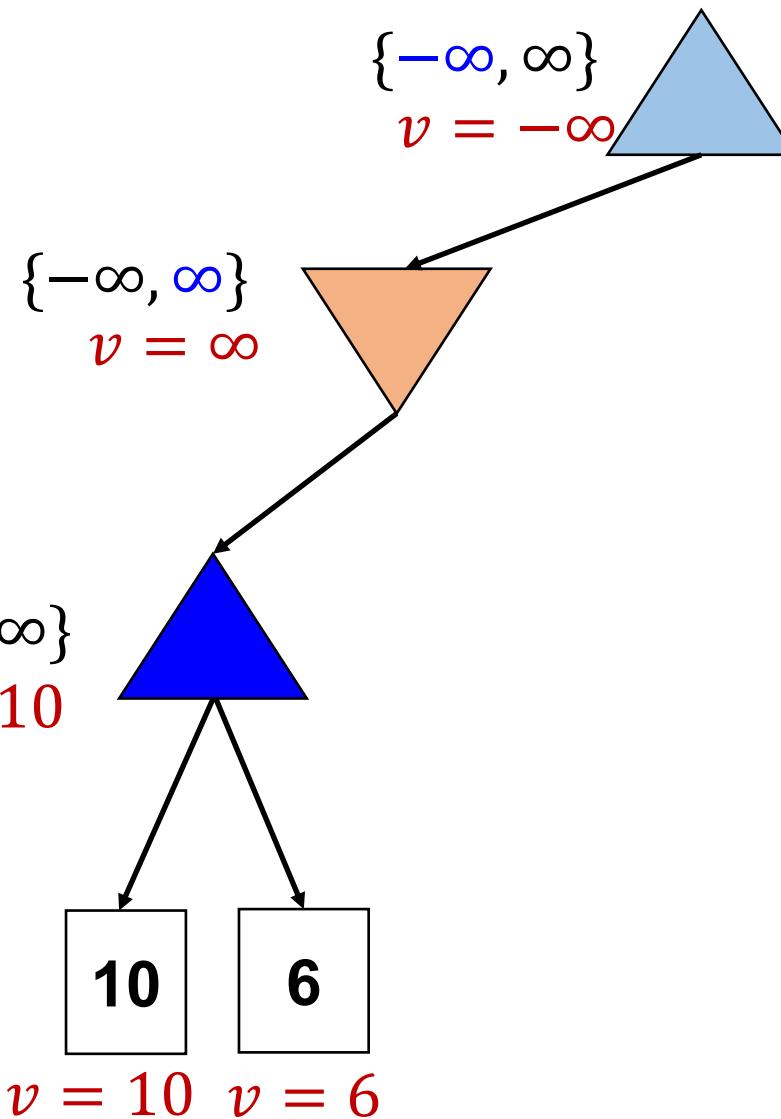


α - β 剪枝：算法测试



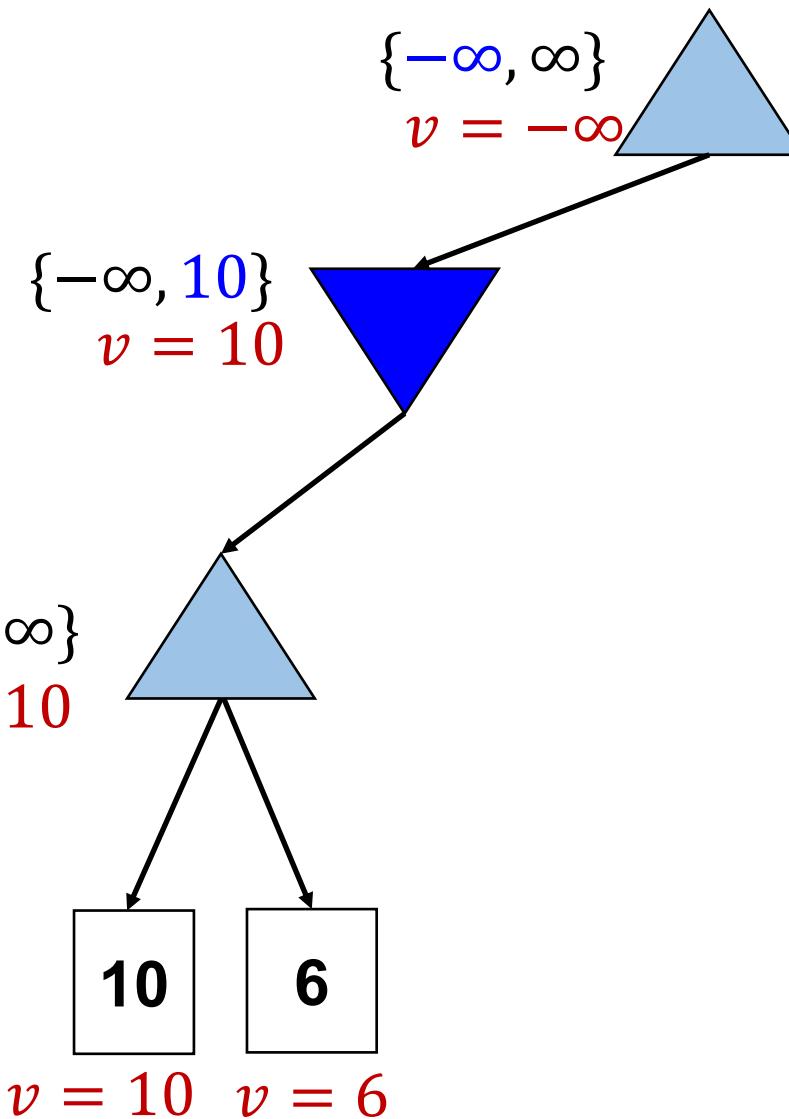


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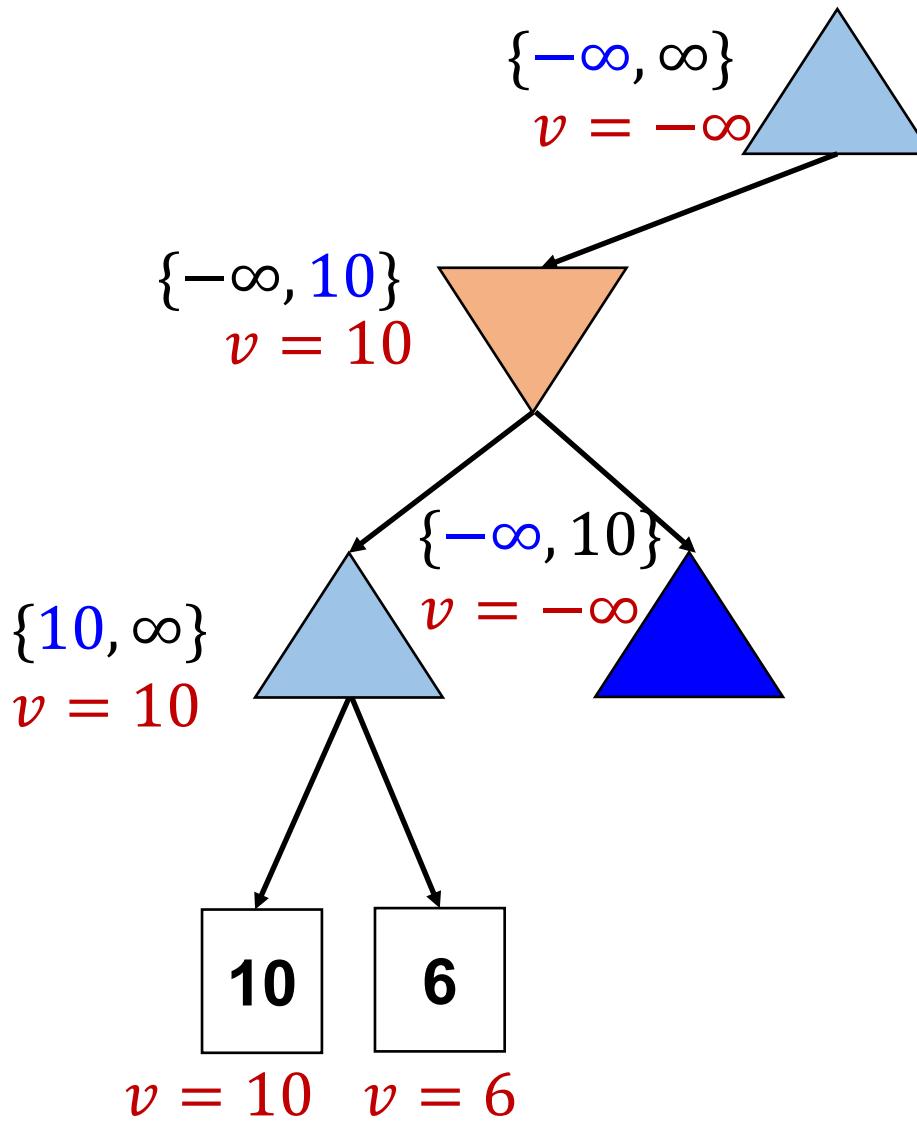


α - β 剪枝：算法测试



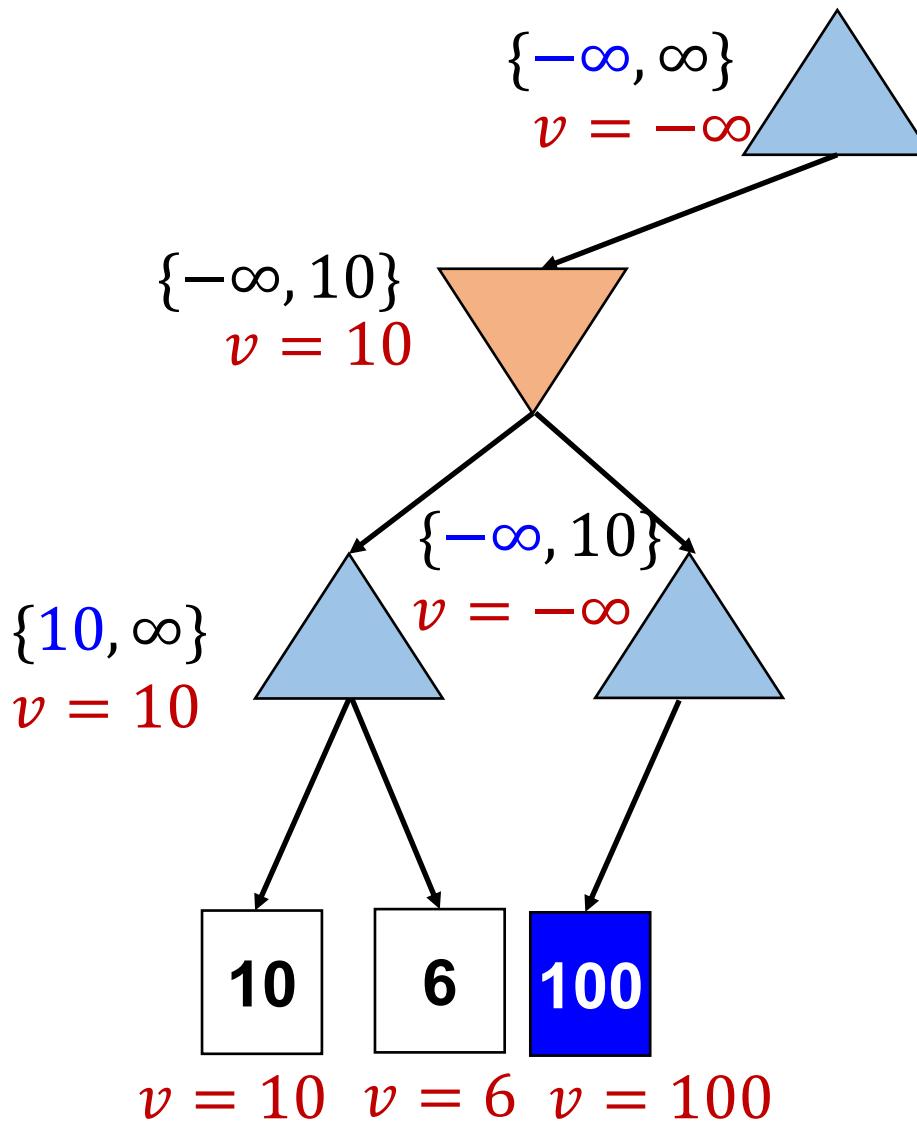


α - β 剪枝：算法测试



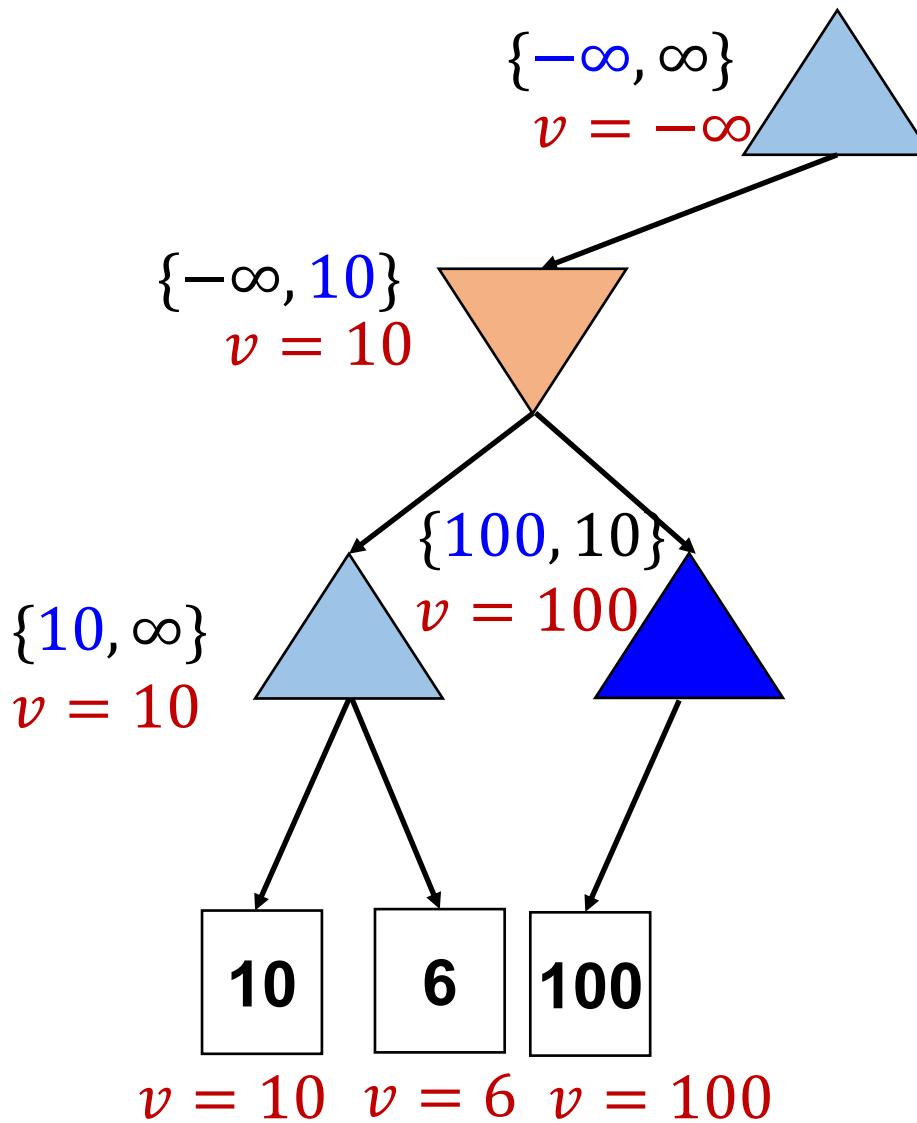


α - β 剪枝：算法测试



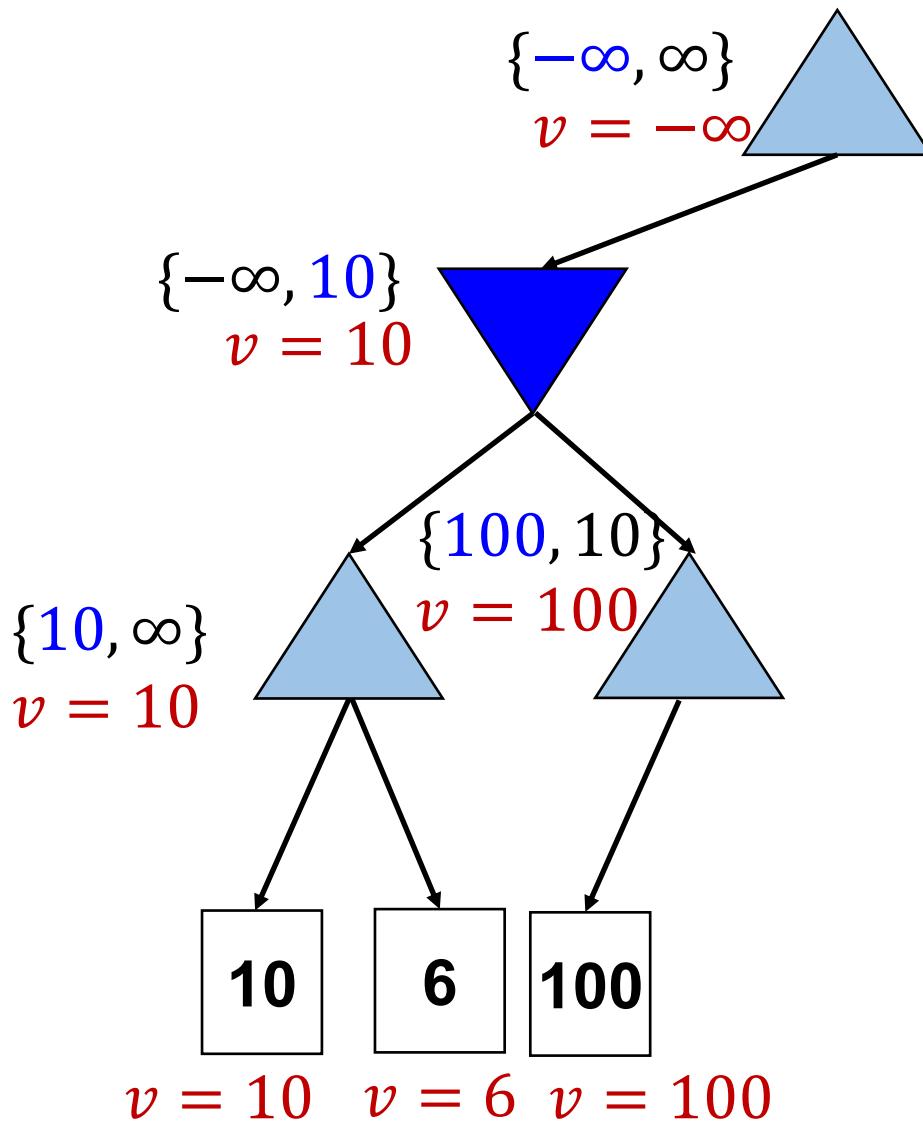


α - β 剪枝：算法测试



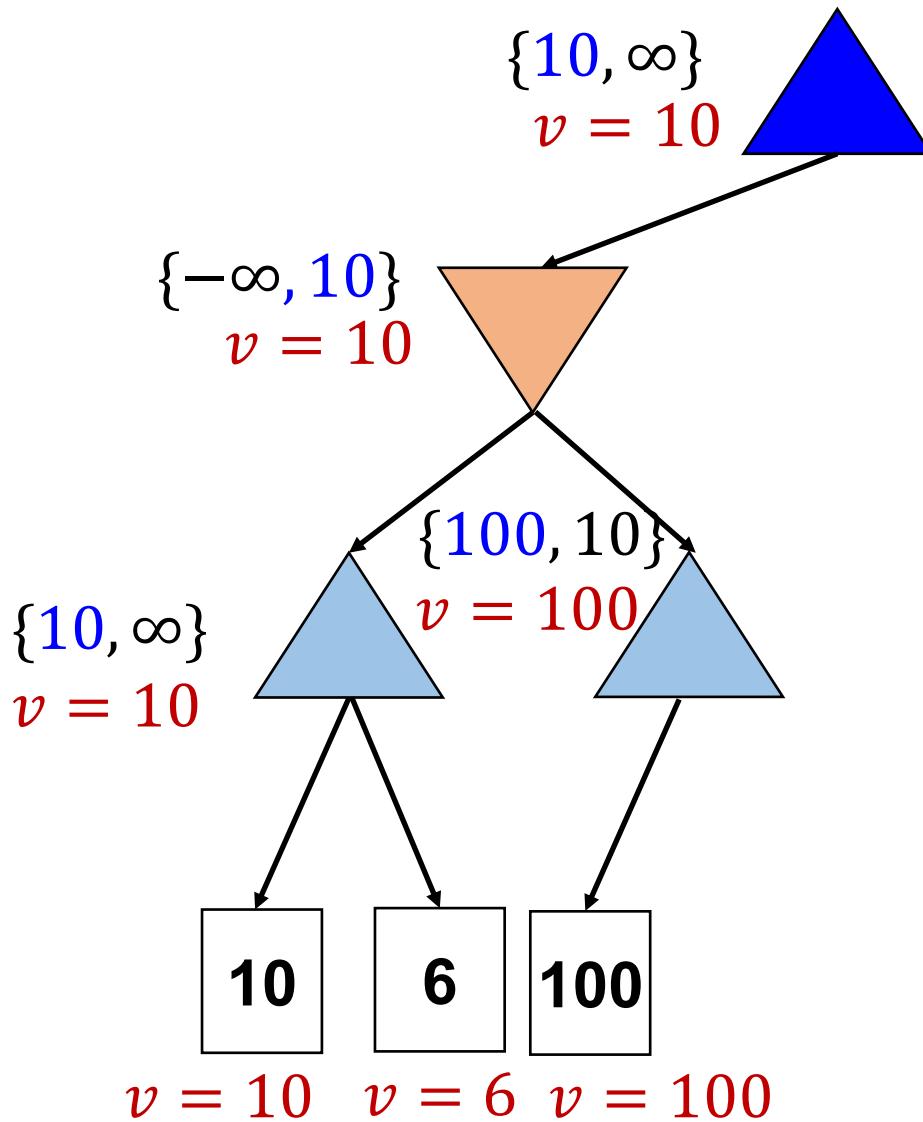


α - β 剪枝：算法测试



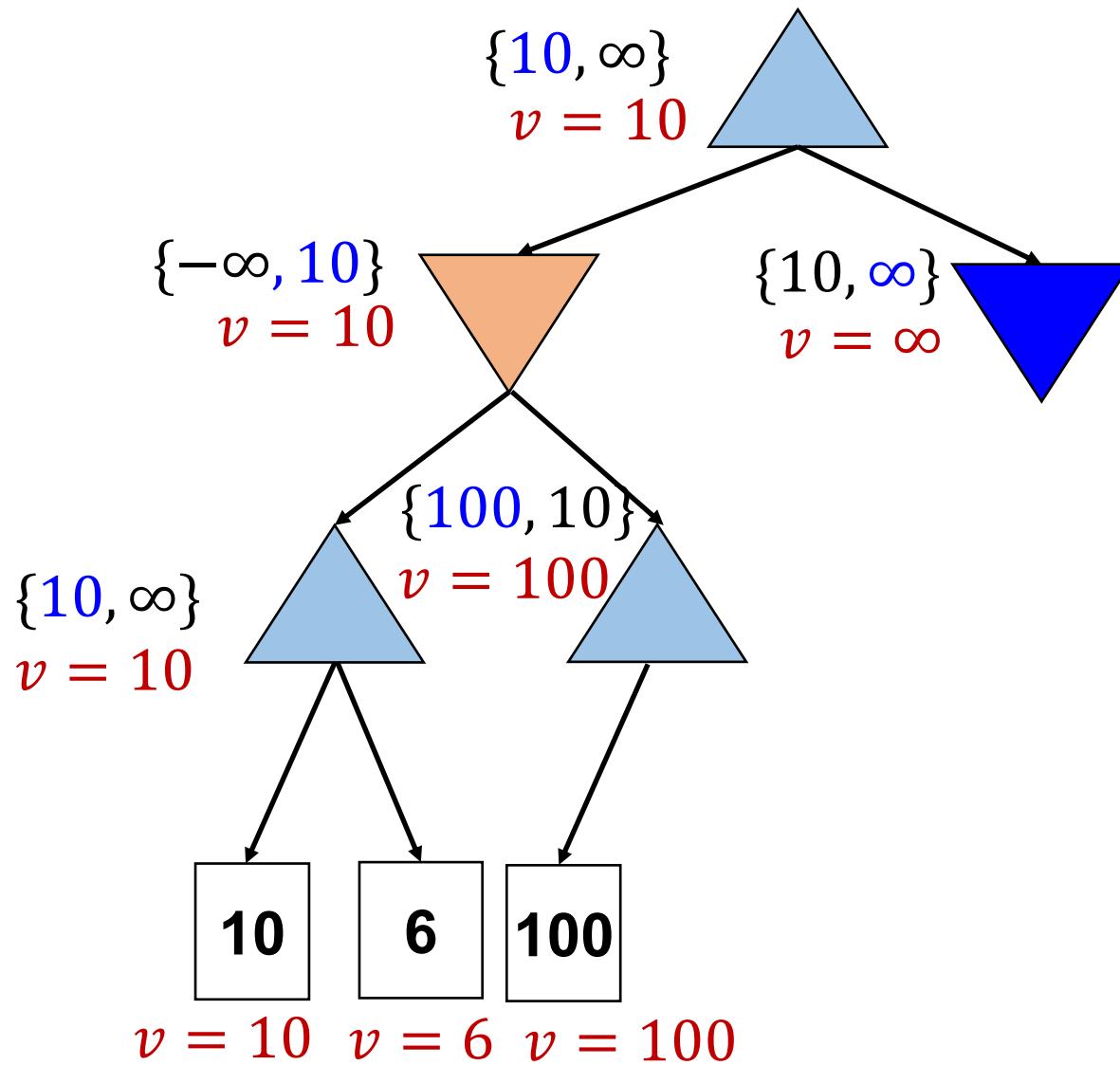


α - β 剪枝：算法测试



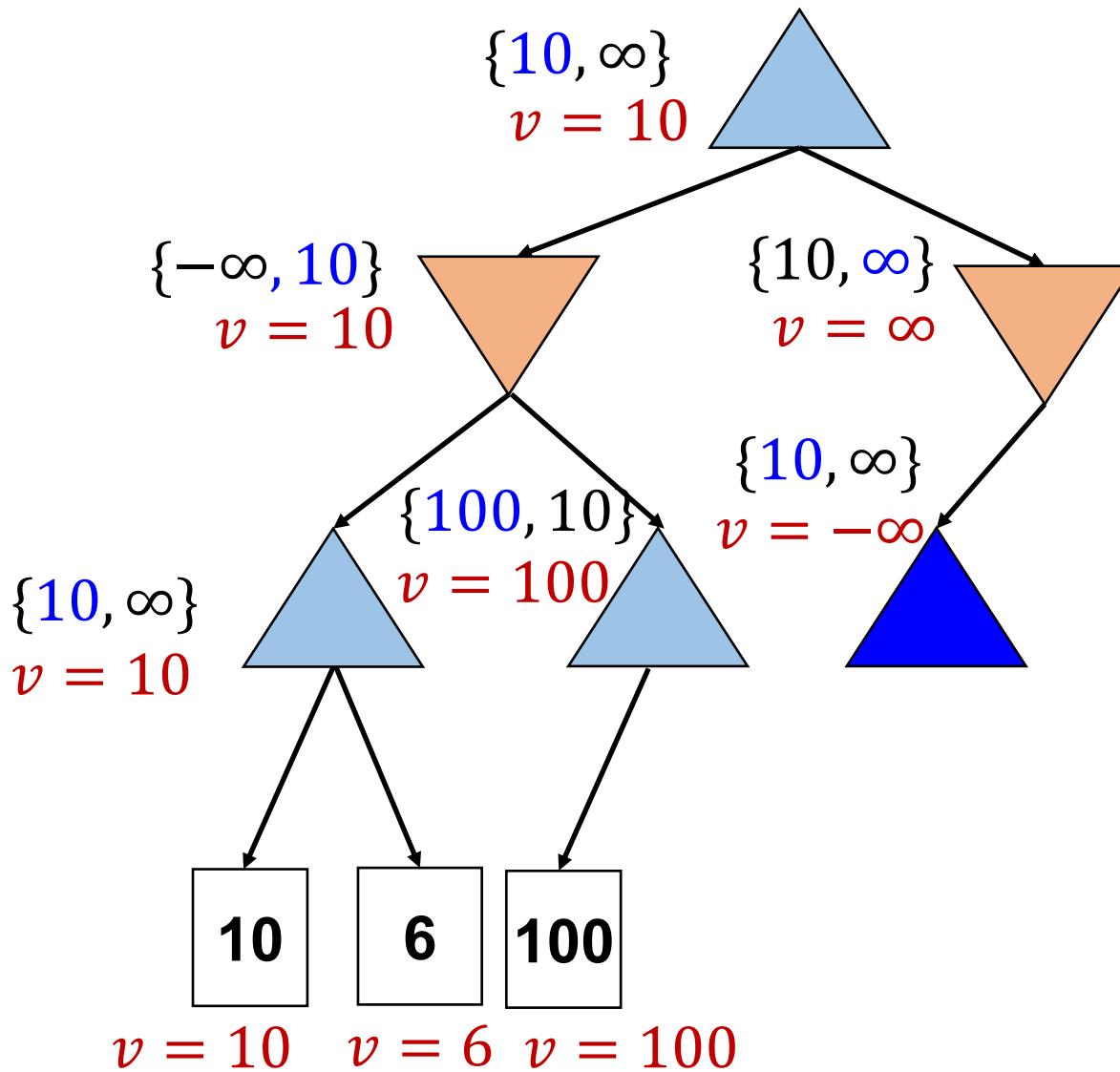


α - β 剪枝：算法测试



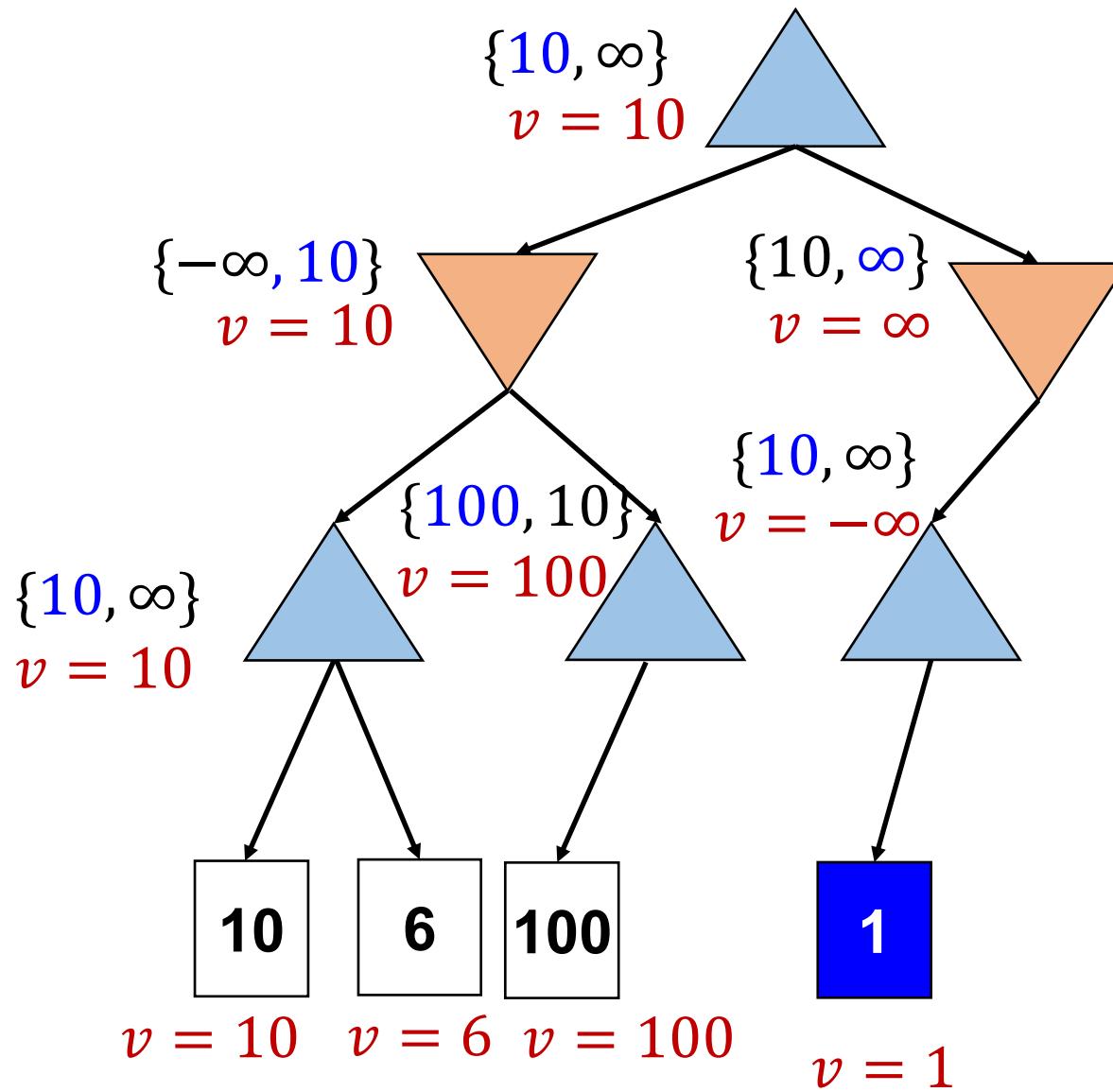


α - β 剪枝：算法测试



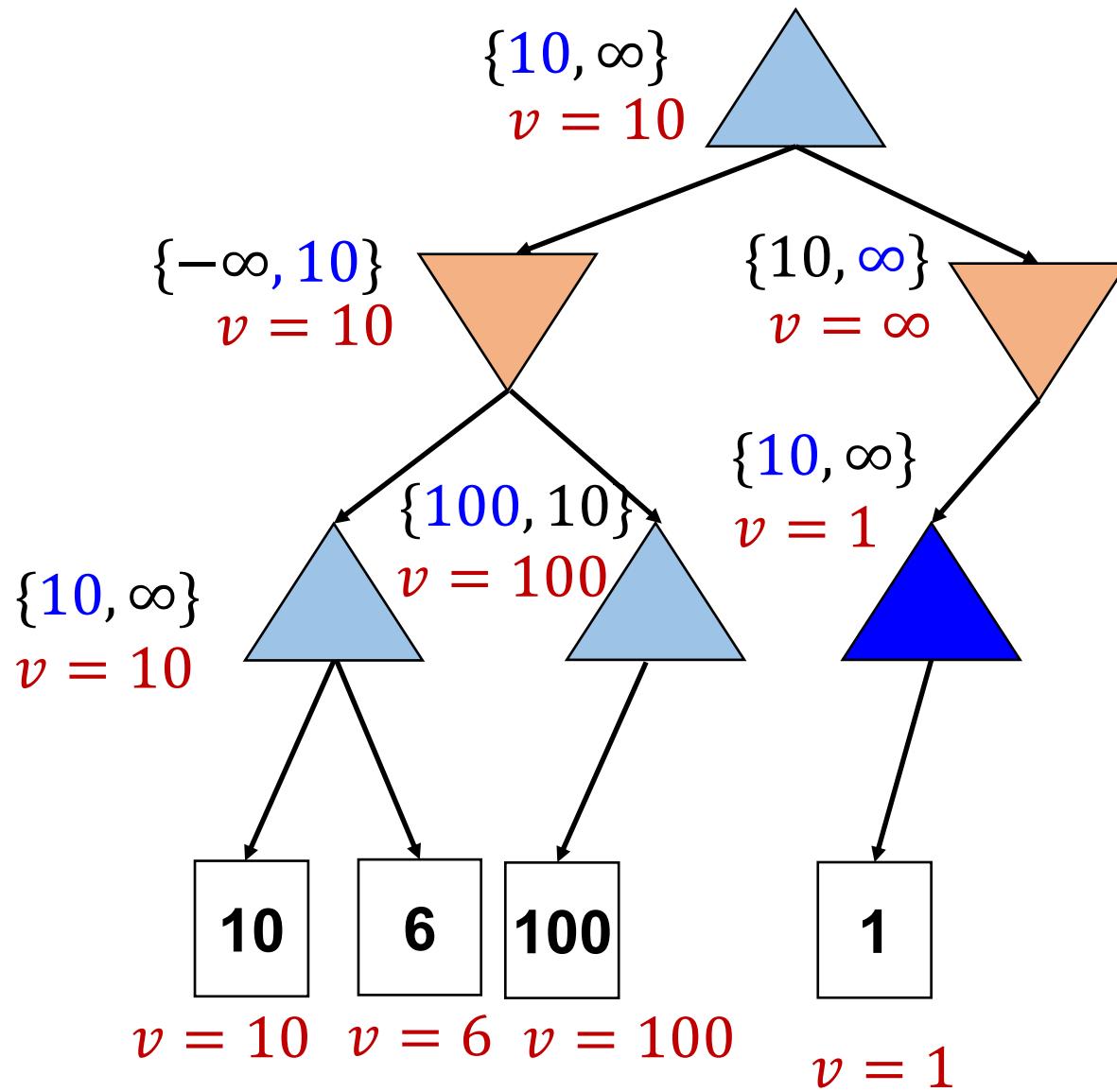


α - β 剪枝：算法测试



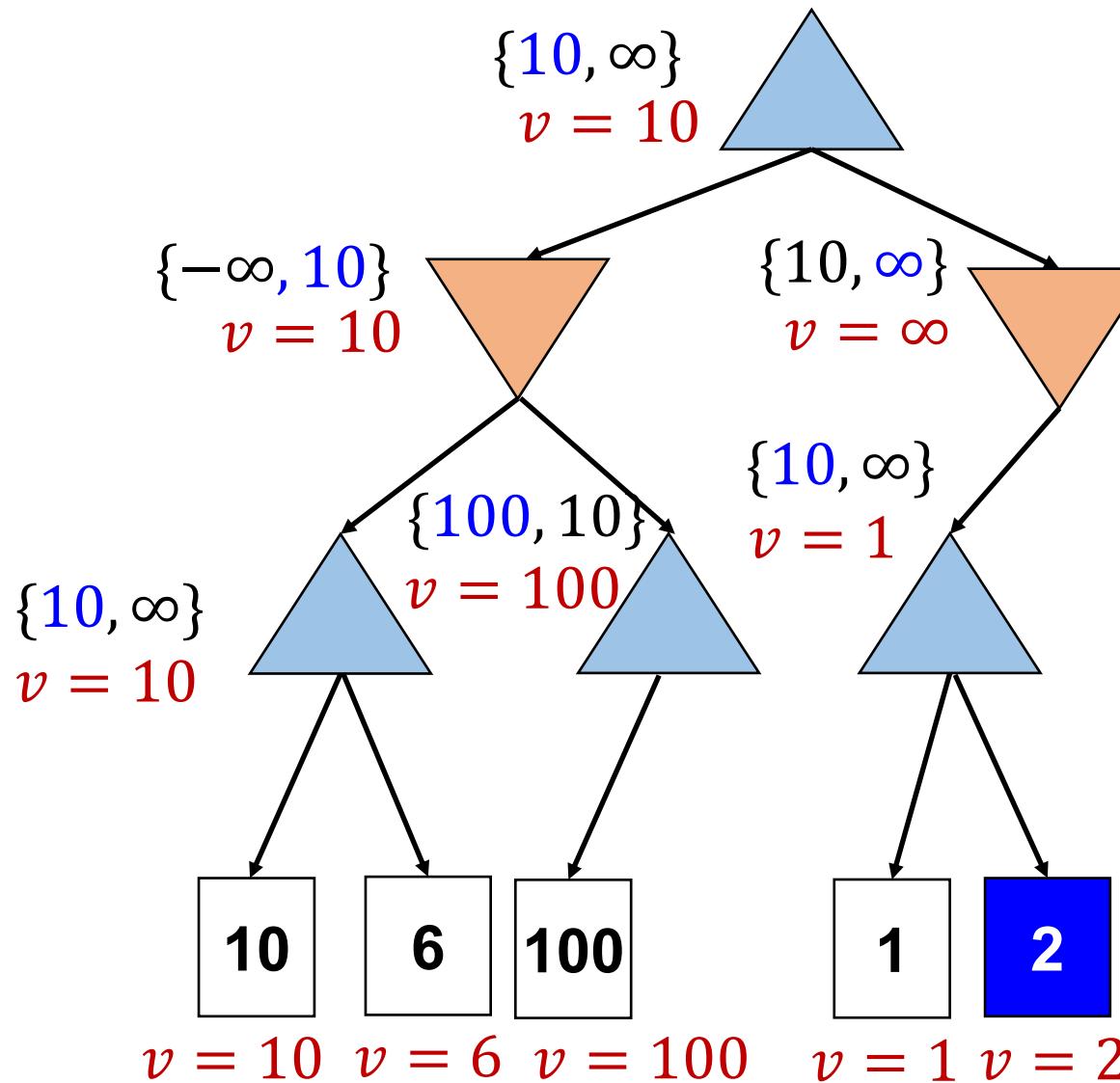


α - β 剪枝：算法测试



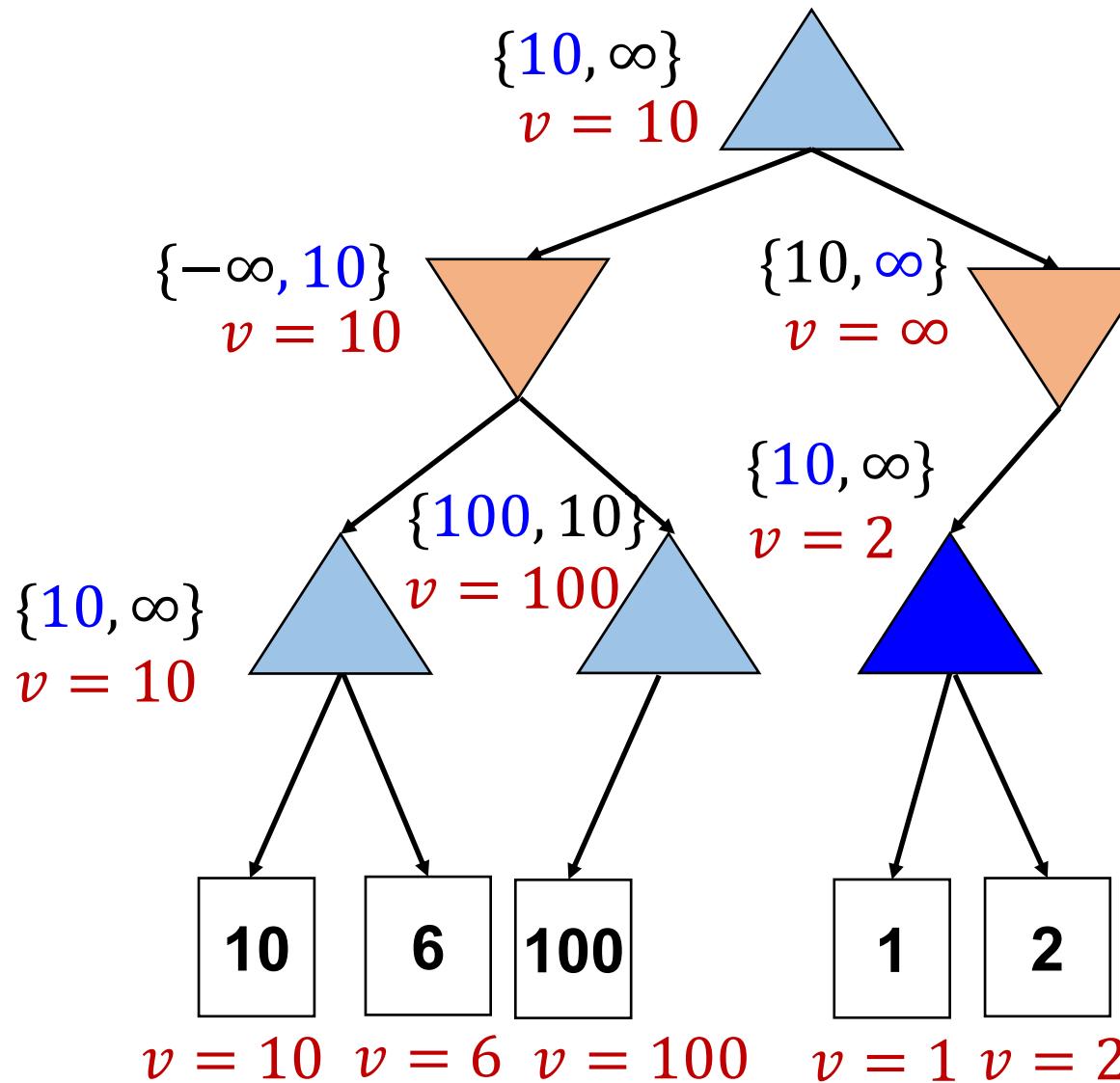


α - β 剪枝：算法测试



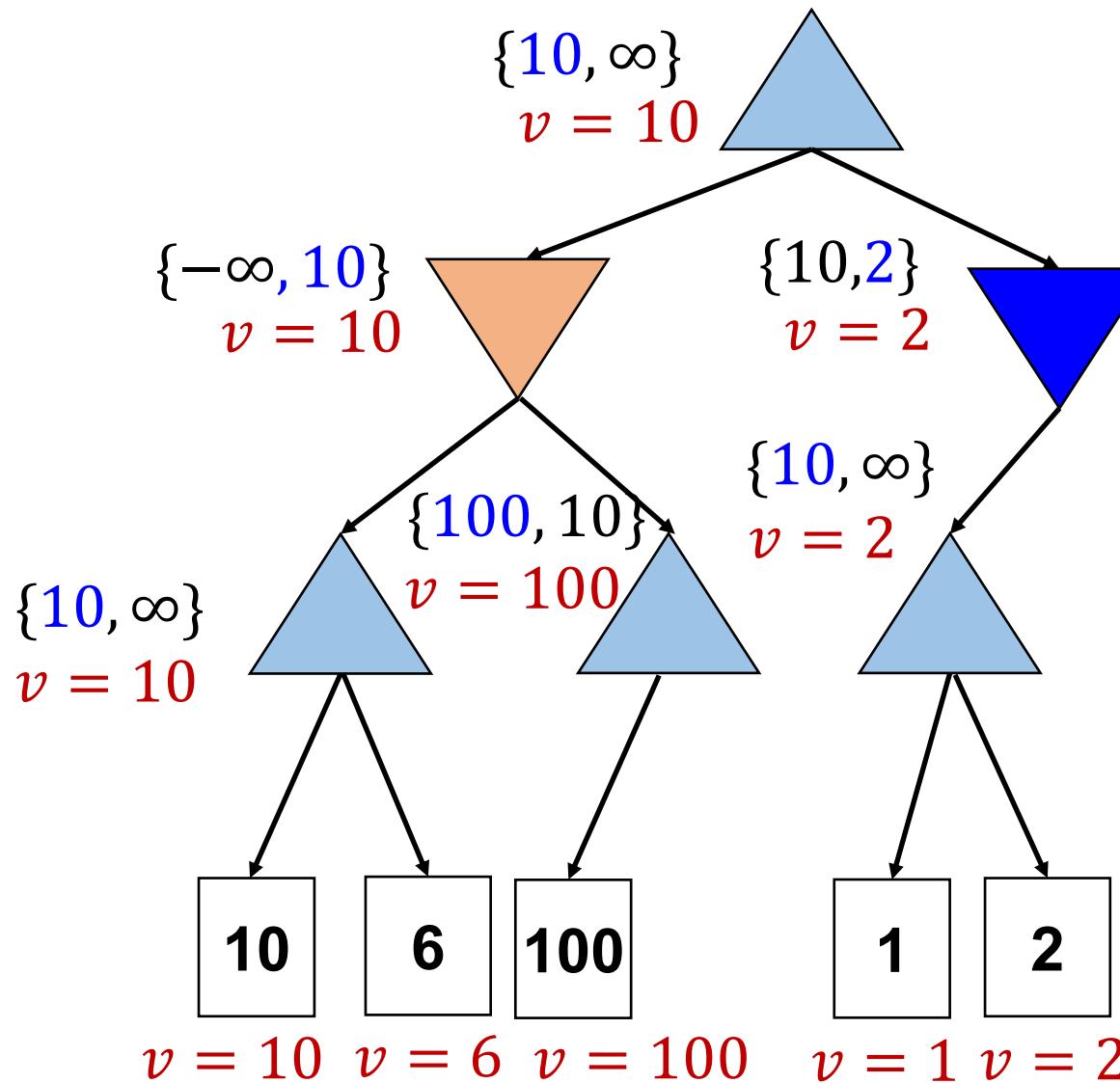


α - β 剪枝：算法测试



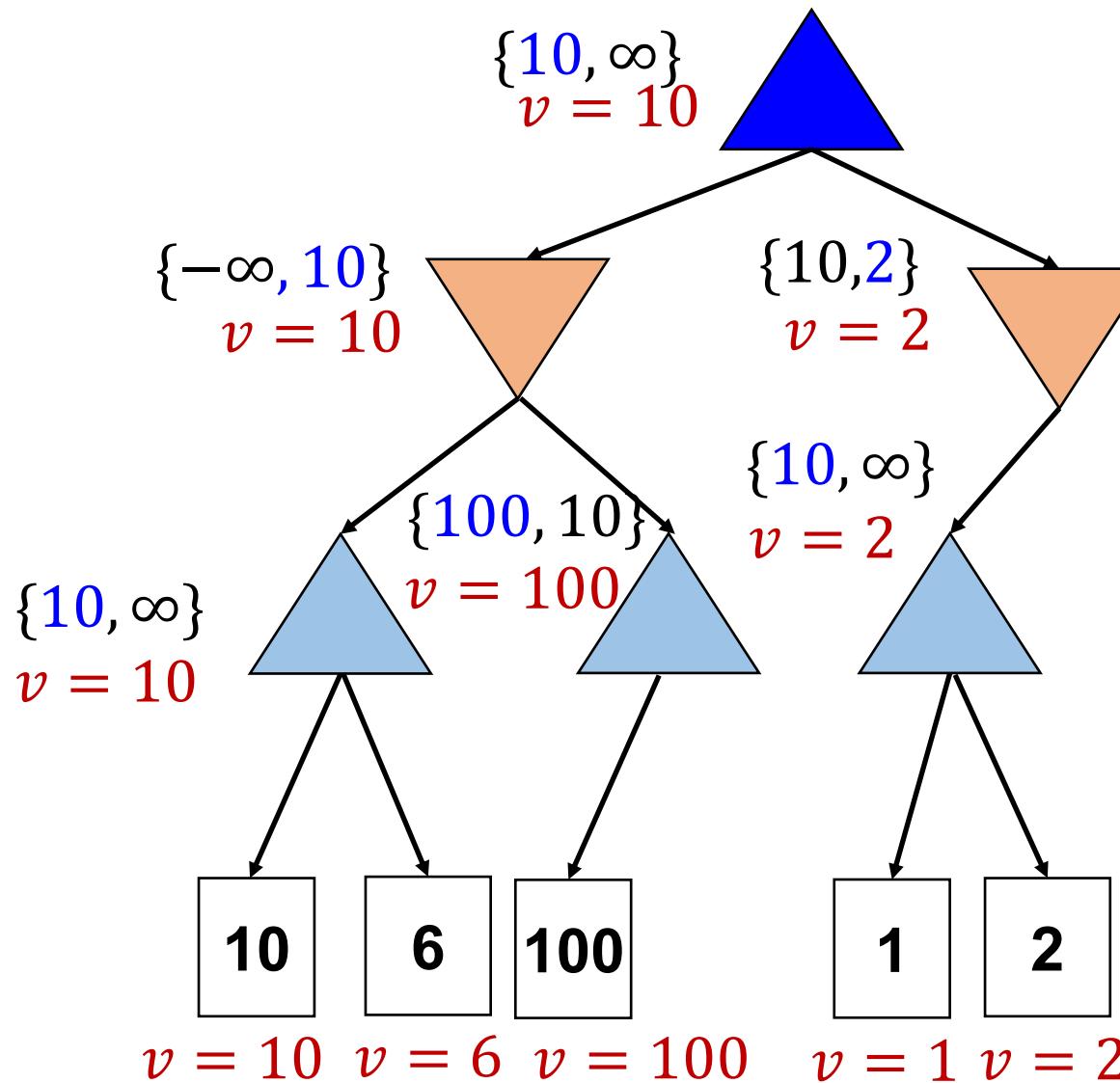


α - β 剪枝：算法测试



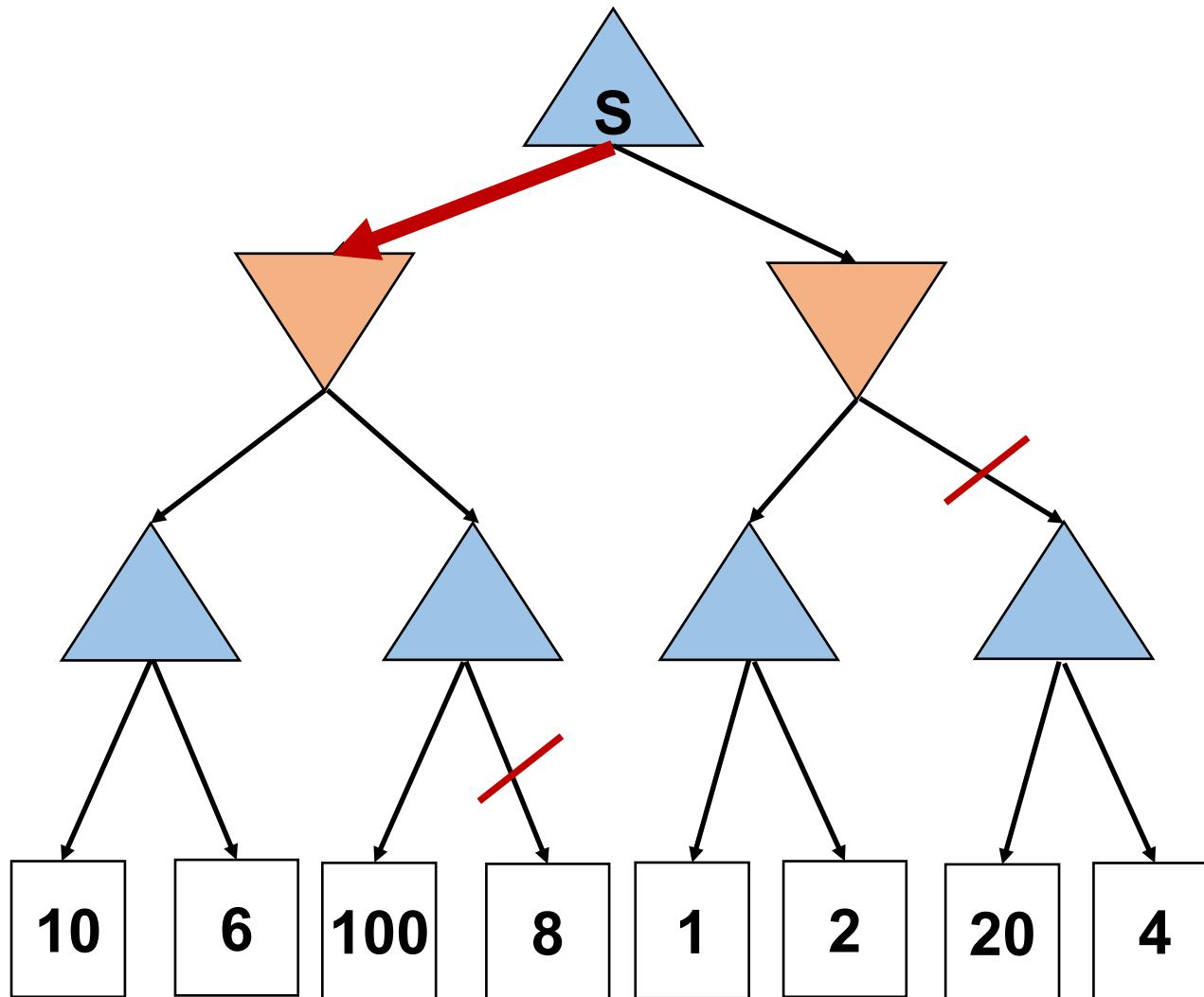


α - β 剪枝：算法测试





α - β 剪枝結果

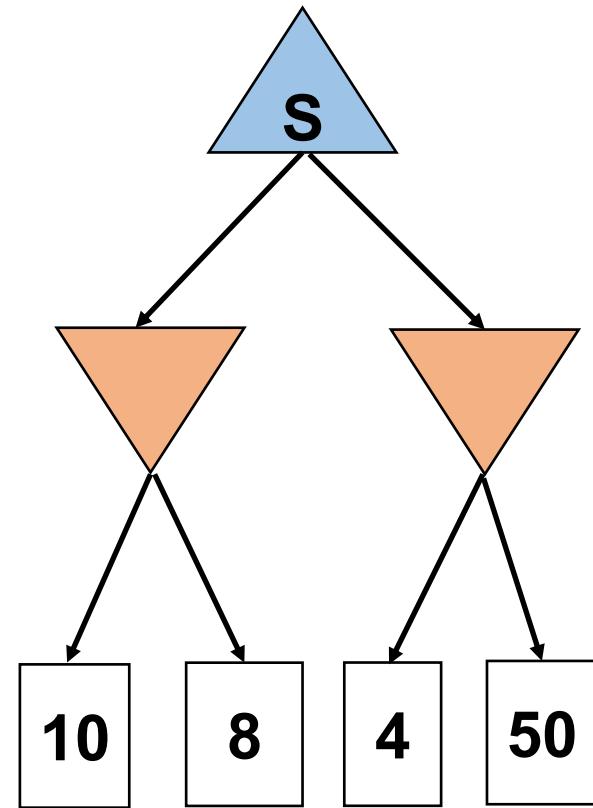




α - β 剪枝：练习

```
function AlphaBeta(state,  $\alpha$ ,  $\beta$ )
If Terminal-Test(state) return Utility(state)
If player(state) = MAX {
    v =  $-\infty$ 
    for each child {
        v = max(v, AlphaBeta(child,  $\alpha$ ,  $\beta$ ))
         $\alpha$  = max( $\alpha$ , v)
        if  $\beta \leq \alpha$  then break // 裁剪 } }
else {
    v =  $\infty$ 
    for each child {
        v = min(v, AlphaBeta(child,  $\alpha$ ,  $\beta$ ))
         $\beta$  = min( $\beta$ , v)
        if  $\beta \leq \alpha$  then break // 裁剪 } }
return v // 返回值
```

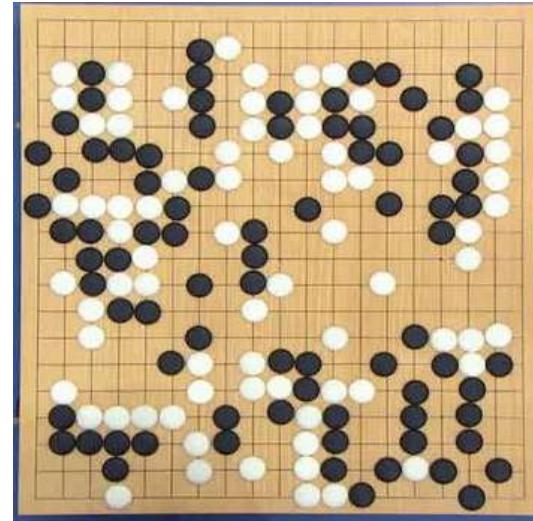
$\text{AlphaBeta}(S, -\infty, \infty)$





α - β 剪枝的特点

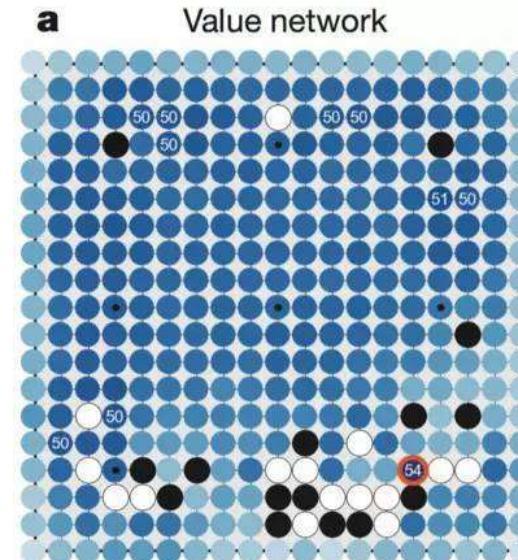
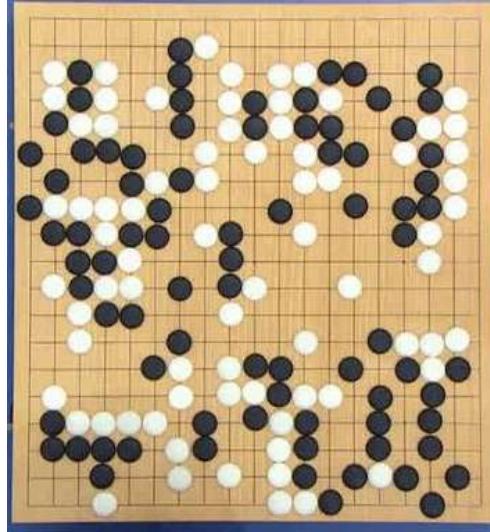
- 裁剪不影响根节点的Minimax值，不影响决策的最优性
- 中间节点的Minimax值可能不精确
- 剪枝效率和节点的访问顺序有关
 - 完美顺序下，时间复杂度 $O(b^{m/2})$ — \sqrt{b} 分支
 - 随机顺序下，时间复杂度 $O(b^{3m/4})$ — $b^{3/4}$ 分支
- 对于困难问题，计算复杂度仍然过高





状态评估

- 设计评估函数 (evaluation function) , 估计非终端节点的得分 (utilities)
- 理想：得到实际的Minimax值
- 现实：估计每个状态的获胜概率
 - Alpha Go: 机器学习





本节课安排

- 博弈搜索问题

Game Search Problem

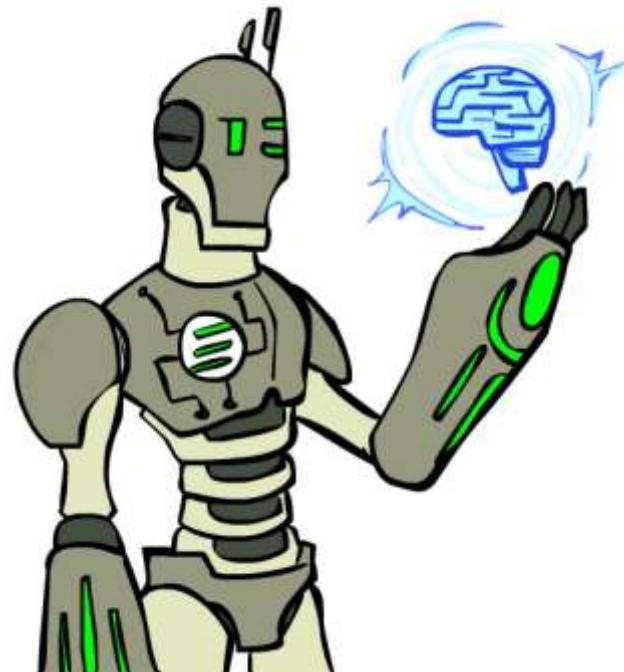
Adversarial Search Problem

- 极小极大搜索

Minimax Search

- α - β 剪枝

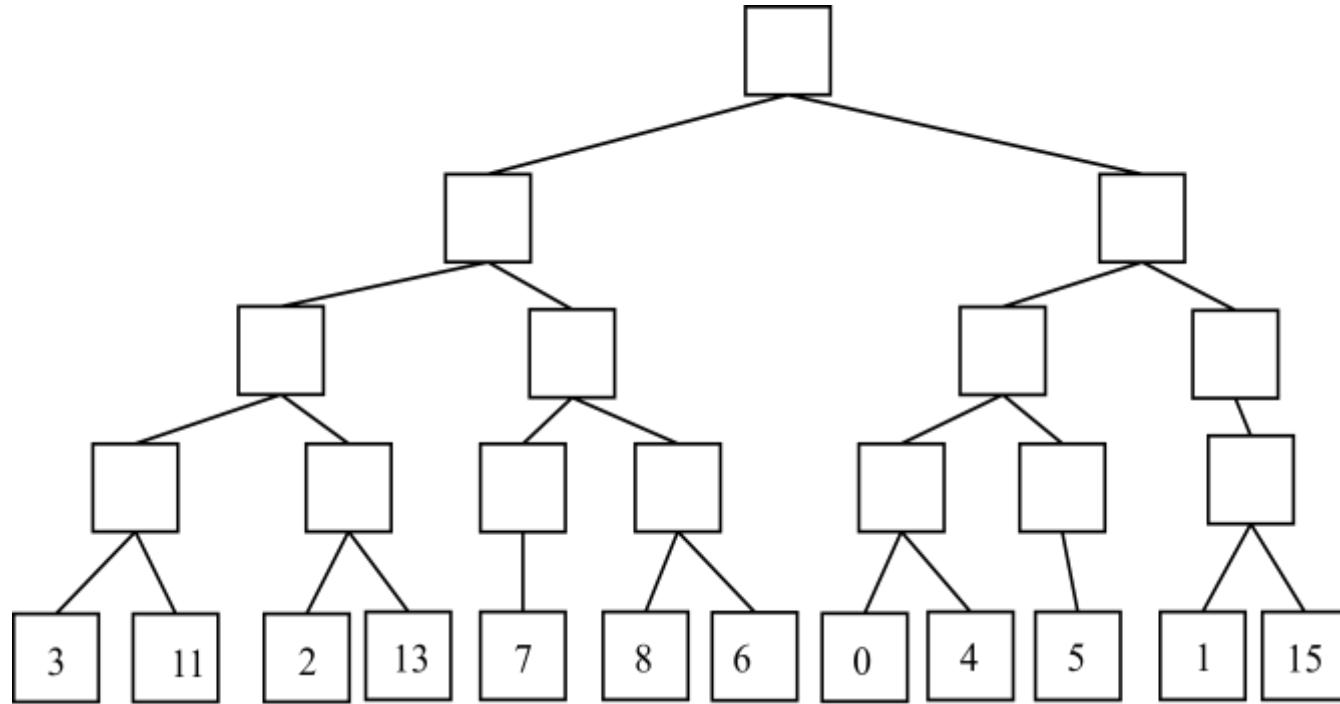
- 练习





练习

1. 考虑下图所示的零和博弈树，假设博弈树都是从MAX层出发，MAX-MIN层交替进行。如果采用 $\alpha - \beta$ 剪枝操作，请在需要剪除的分支上打×（本小题共6分）。





练习：答案

1. 考虑下图所示的零和博弈树，假设博弈树都是从MAX层出发，MAX-MIN层交替进行。如果采用 $\alpha - \beta$ 剪枝操作，请在需要剪除的分支上打×（本小题共6分）。

