



# 人工智能 I

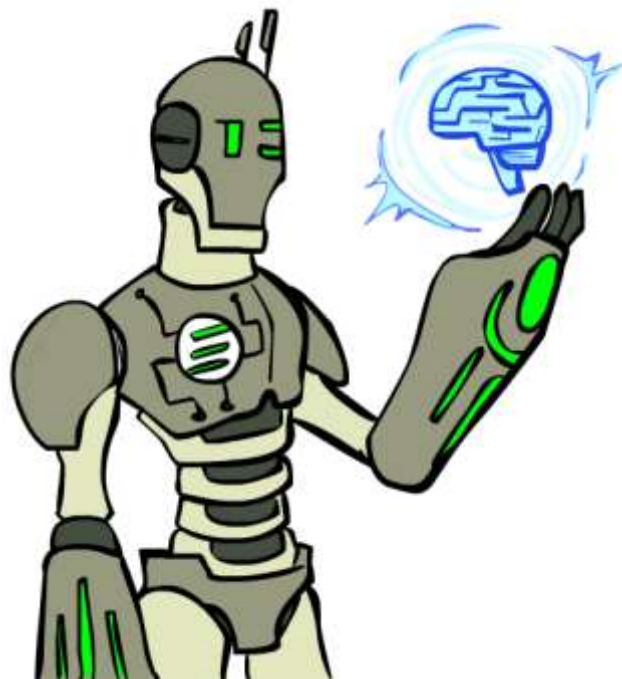
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# 本节课安排

- 博弈搜索问题  
**Game Search Problem**  
**Adversarial Search Problem**
- 极小极大搜索  
**Minimax Search**
- $\alpha$ - $\beta$  剪枝
- 练习





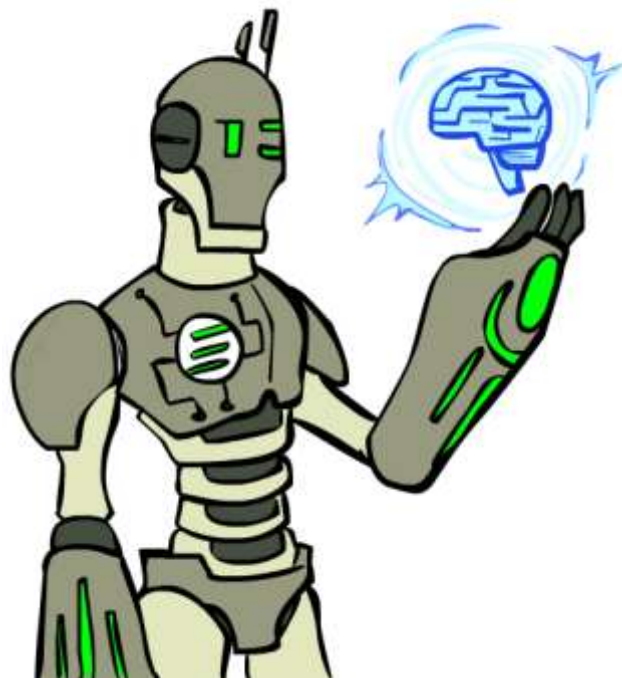
# 本周五实验课安排

周次	5
日期	2025/10/24
星期	星期五
时间	8:00-12:15
机房地点	五五楼435-软实七
实验任务	有信息搜索



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# 例子：棋类游戏

- 西洋跳棋 (1962, IBM)
  - Chinook VS. Marion Tinsley
  - 提出机器学习、强化学习
  
- 国际象棋 (1997, IBM)
  - DeepBlue VS. 卡斯帕罗夫
  - 硬件加速搜索
  - 超级专家系统
  
- 围棋 (2016, DeepMind)
  - AlphaGo VS. 李世石
  - DL + RL + 蒙特卡洛方法





# 任务环境的属性

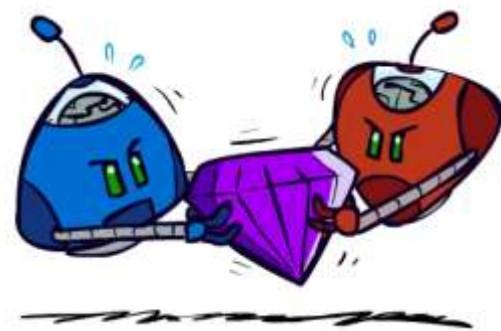
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- 完全可观测 **V.S.** 部分可观测
- 单体 **V.S.** 多体
- 静态 **V.S.** 动态
- 确定性 **V.S.** 随机性
- 周期性 **V.S.** 序贯性
- 离散 **V.S.** 连续



# 博弈

人工智能中“博弈”通常专指博弈论专家们称为**有完整信息的、确定性的、轮流行动的、两个游戏者的零和 (Zero-Sum) 游戏。**





# 博弈问题(Game)的描述

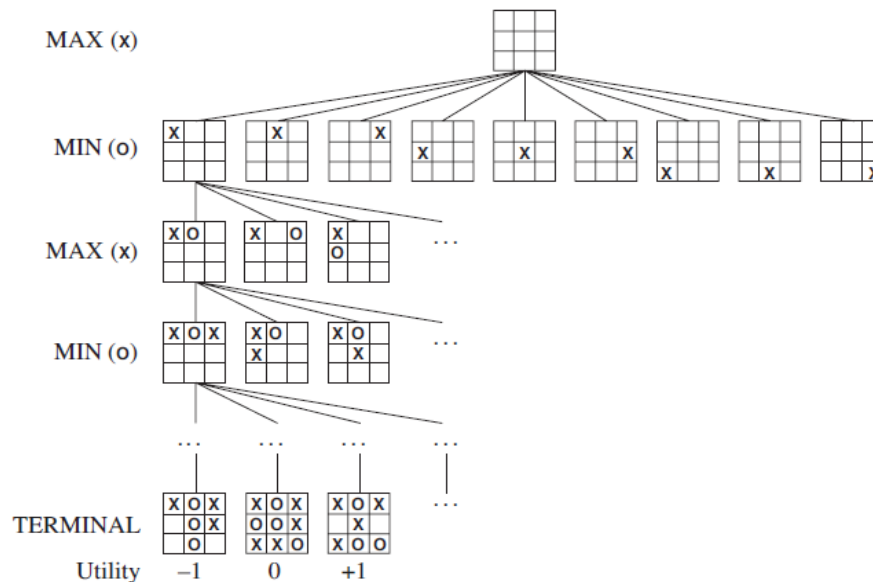
- $S_0$ : 初始状态
- $\text{Player}(s)$ : 状态 $s$ 下, 由哪个玩家行动
  - MAX (先行)
  - MIN
- $\text{Actions}(s)$ : 状态 $s$ 下的动作
- $\text{Result}(s, a)$ : 后继函数
- $\text{Terminal\_Test}(s)$ : 判断 $s$ 是否为终止状态
- $\text{Utility}(s, p)$ : 终止状态 $s$ 对于玩家 $p$ 的效用 (得分)
  - $p = \text{MAX}$
  - $\text{Utility}(s)$





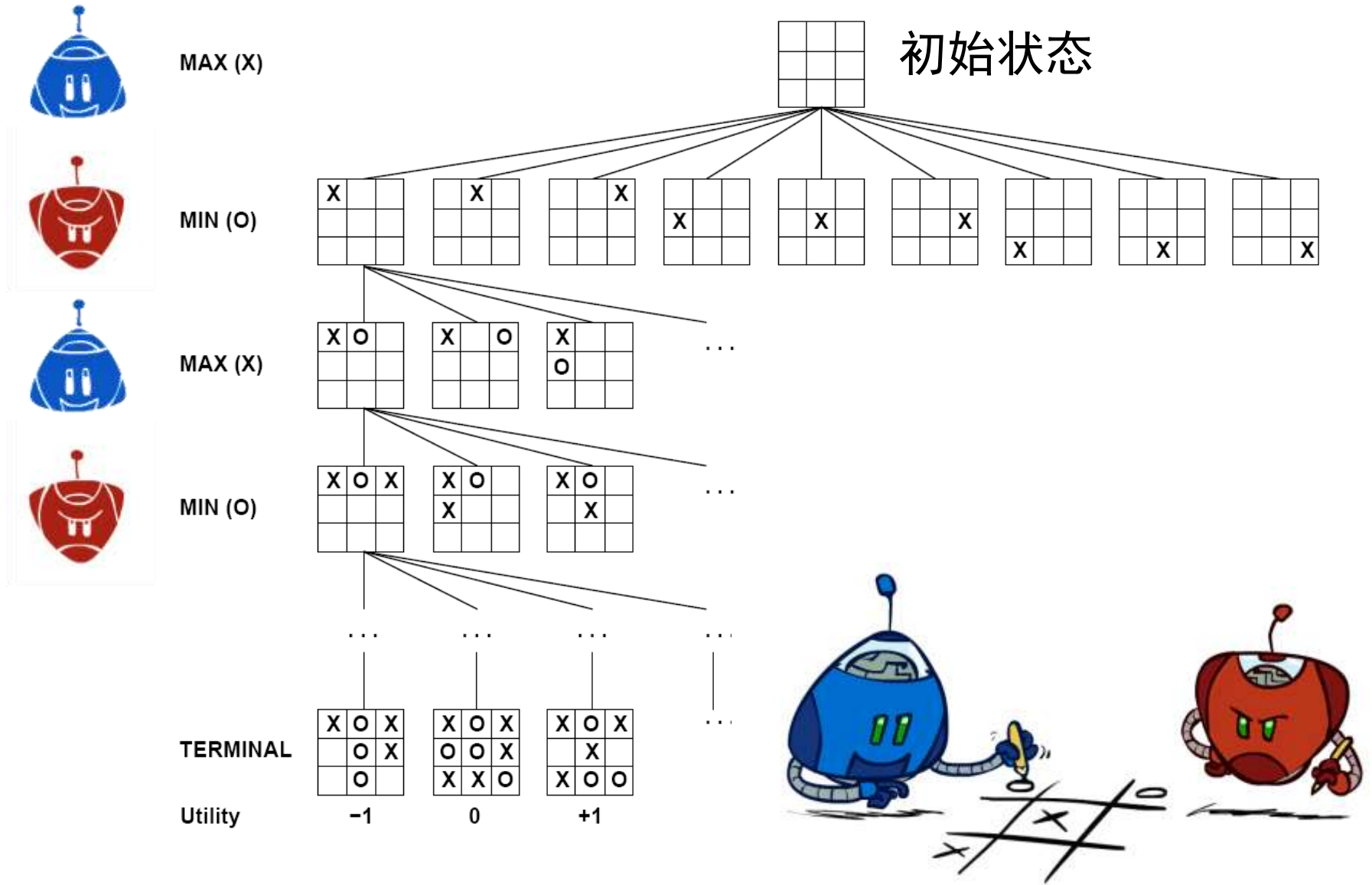
# 博弈树 (Game Tree)

- ❑ 根节点：初始状态，行为决策节点
- ❑ 叶子节点：终止状态（终局）
- ❑ 中间节点
- ❑ 与搜索树类似，主要不同点：
  - 博弈树：有MAX与MIN两位玩家，深度有限
  - 搜索树：一位玩家，动态、可无限延伸





# 三子棋的博弈树





# 博弈问题 (Game) 的求解

- 问题：初始状态的行为决策
- 基本思路：
  - 玩家根据当前状态，向对自己**有利**的终局采取行动（为最大效用而行动）
  - 终局的效用：**已知**
  - 中间节点的效用：**难点**





# 例子：取石子

- ❑ 盘子中有4颗石子，两个玩家轮流从中取出。至少取1颗，至多取2颗。不能继续操作的玩家输
  - MAX、MIN两个玩家，MAX先走，MAX赢的效用为1，输为-1



MAX



MIN



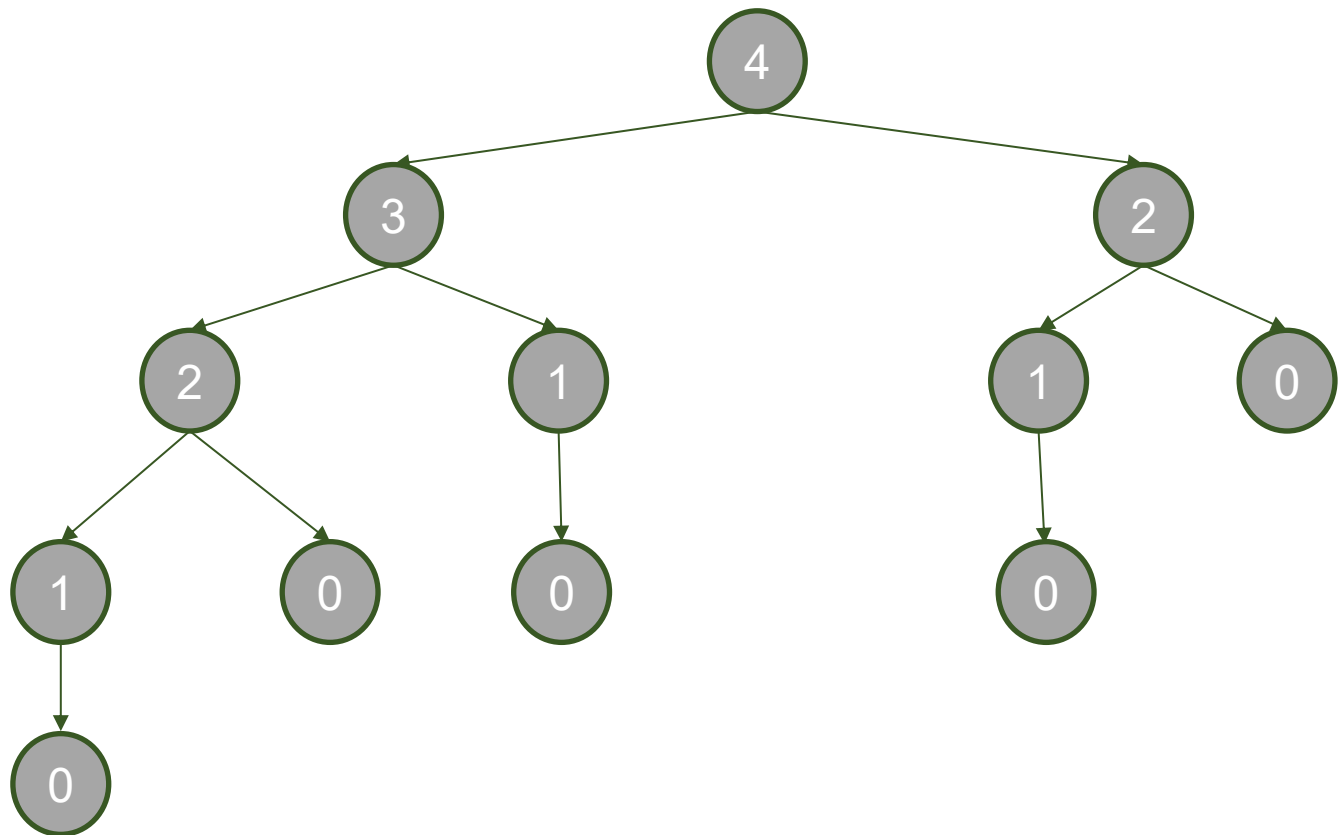
MAX



MIN



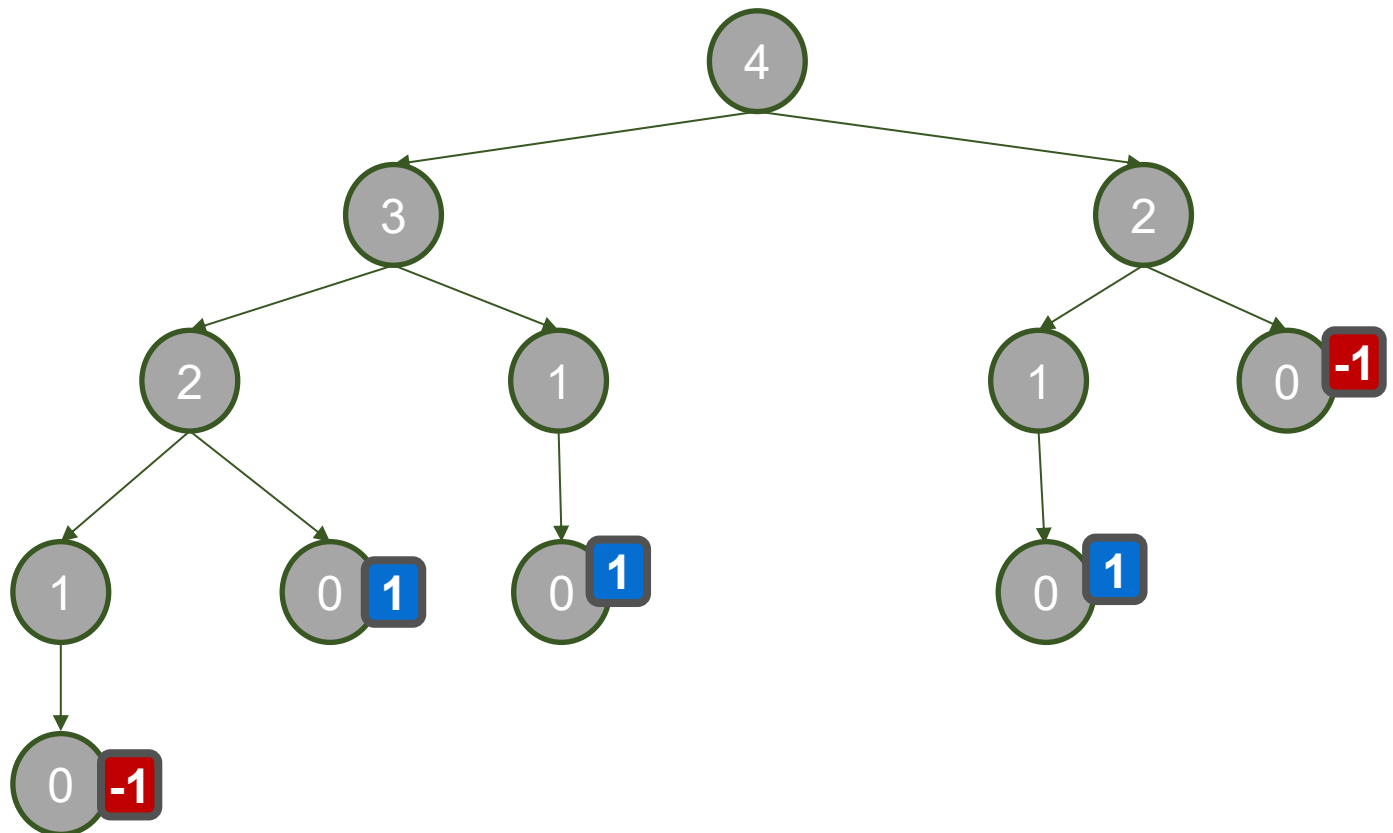
MAX





# 例子：取石子

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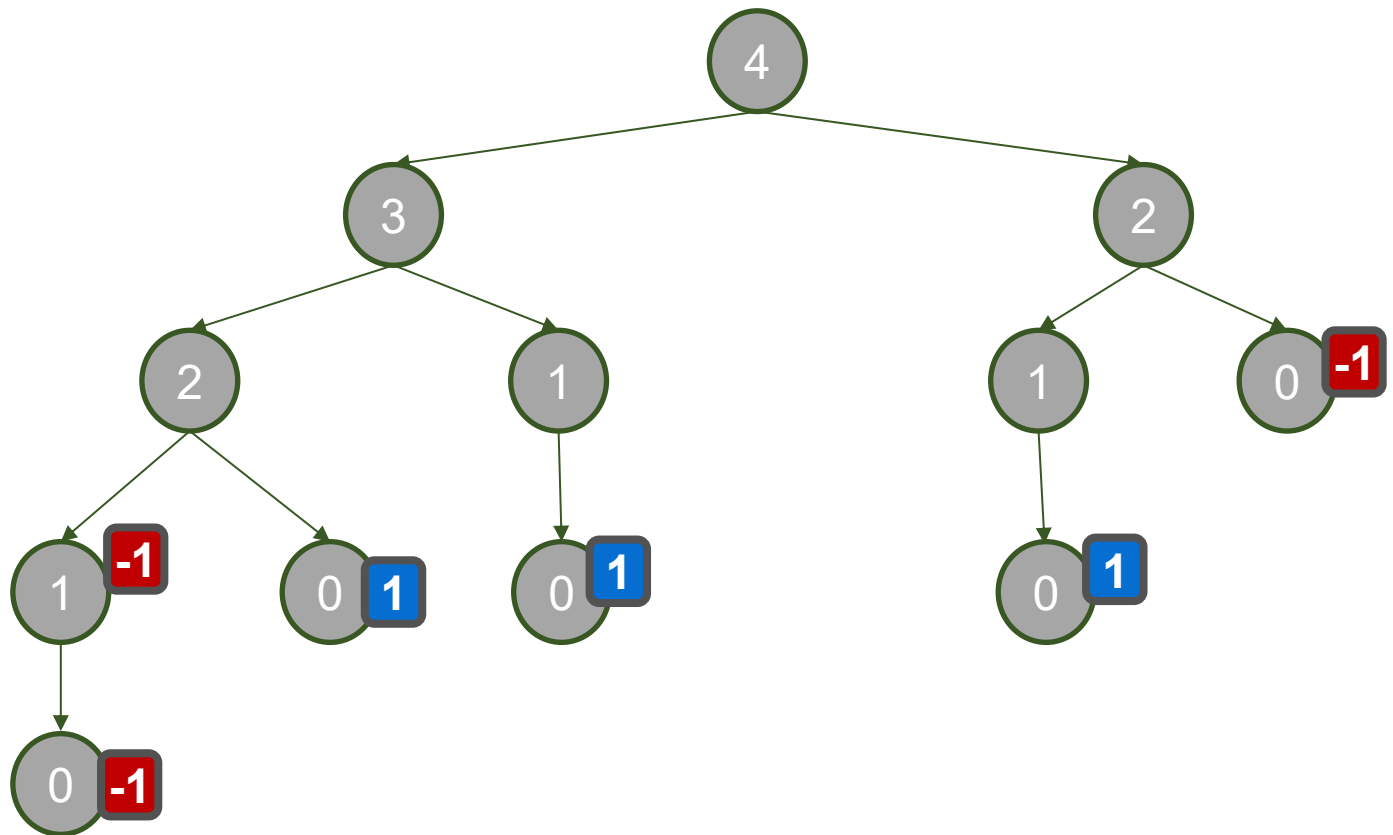




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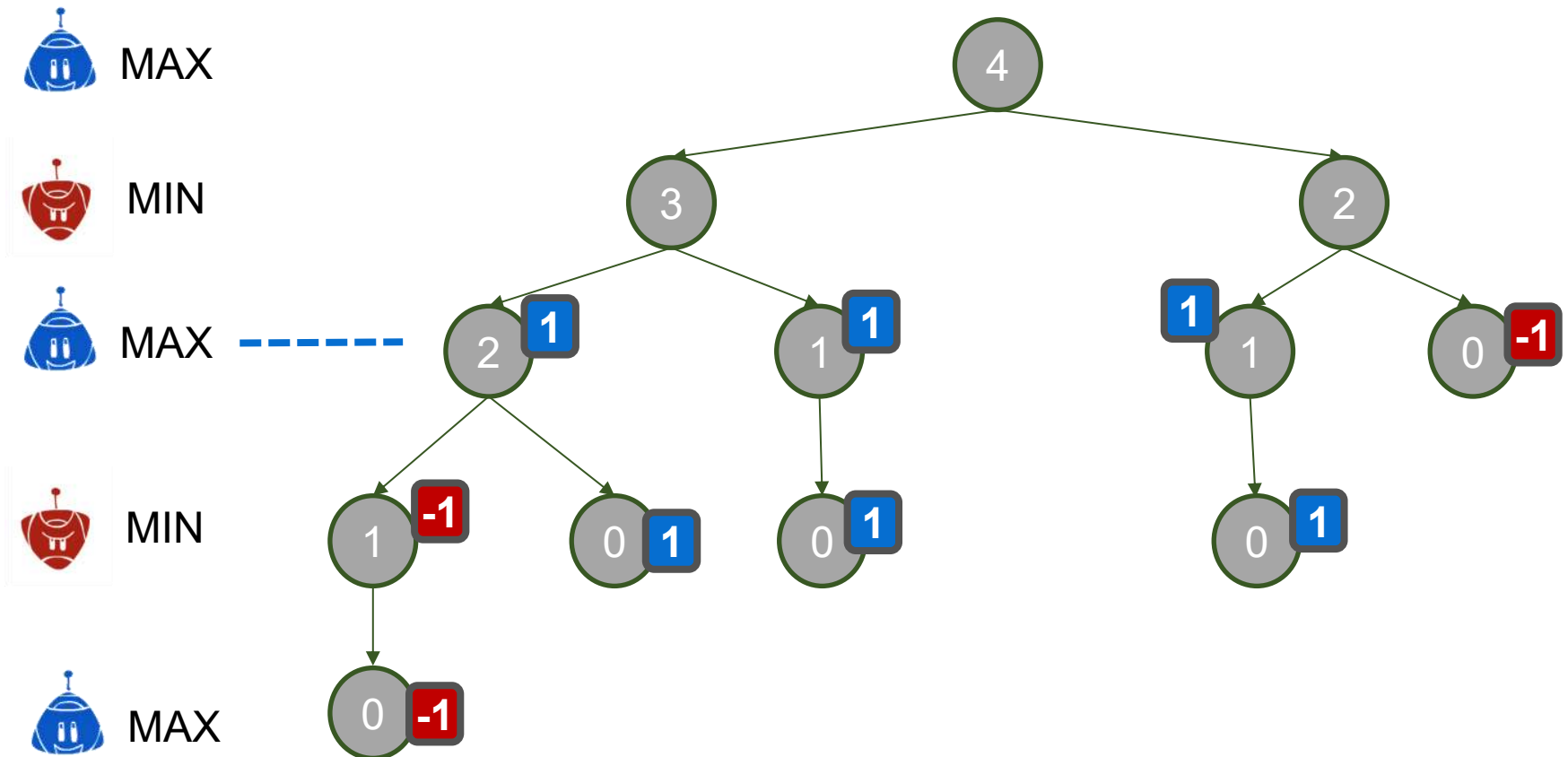
MAX





# 例子：取石子

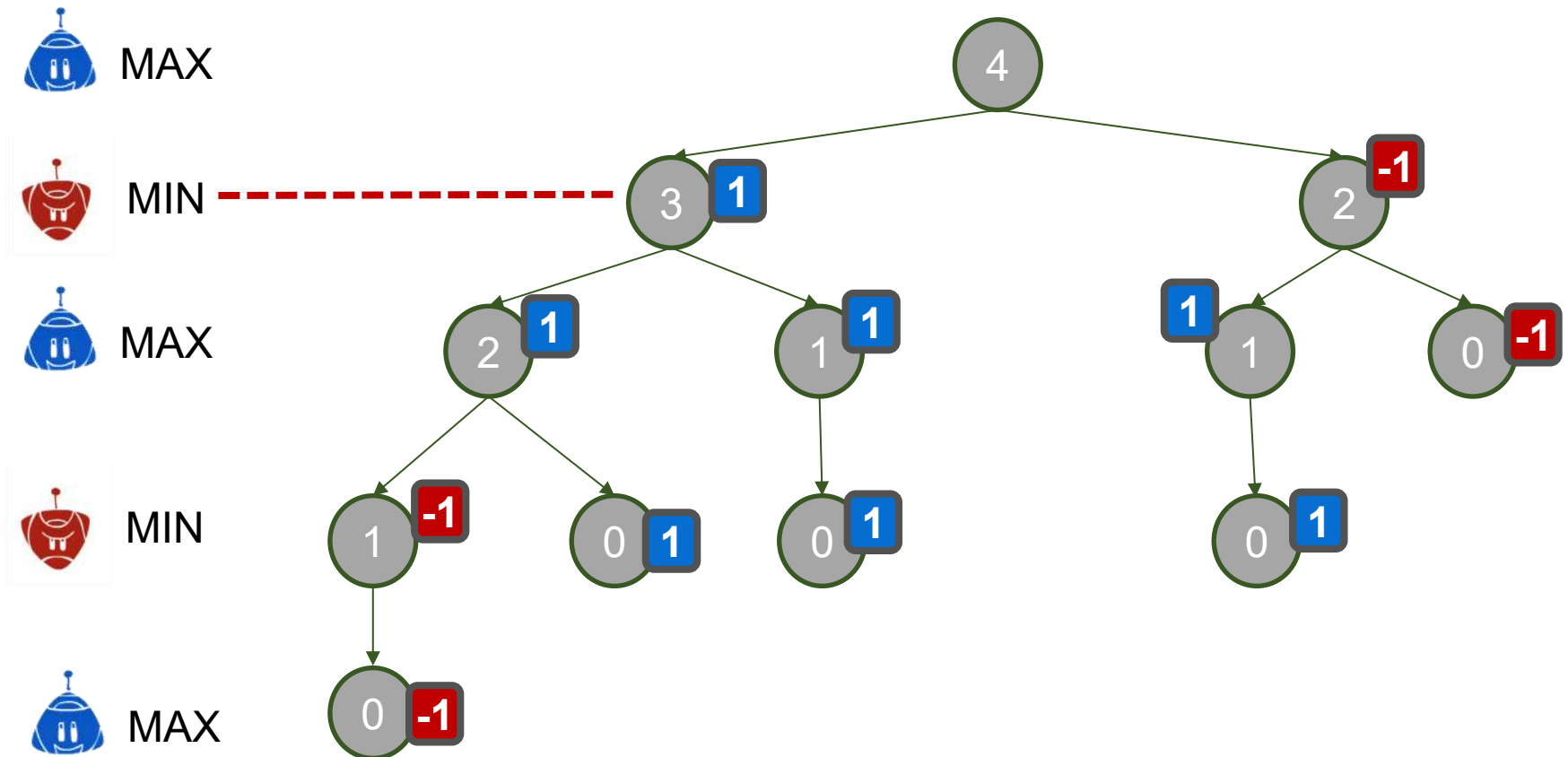
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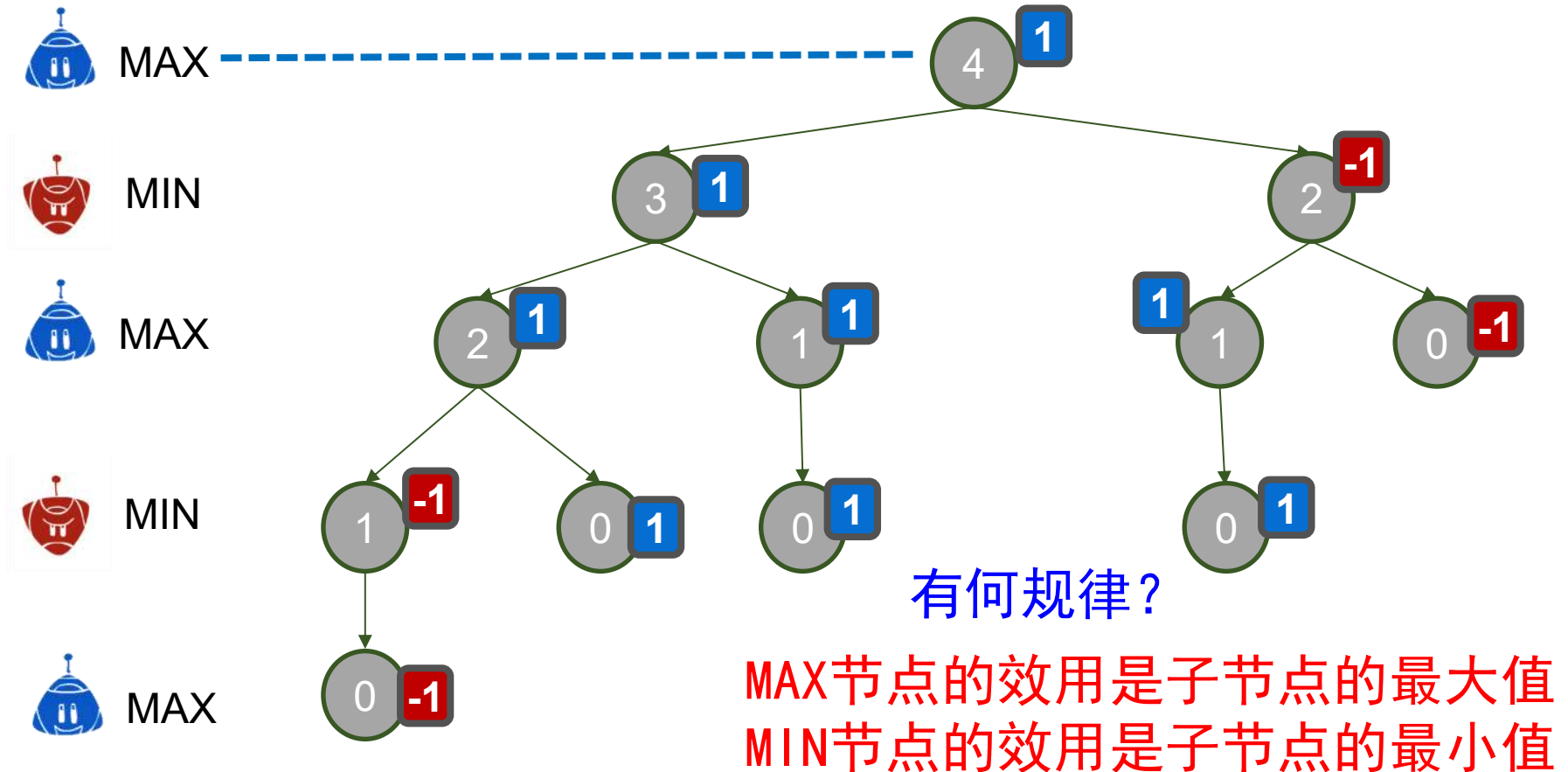






# 例子：取石子

- ❑ 盘子中有4颗石子，两个玩家轮流从中取出。至少取1颗，至多取2颗。不能继续操作的玩家输
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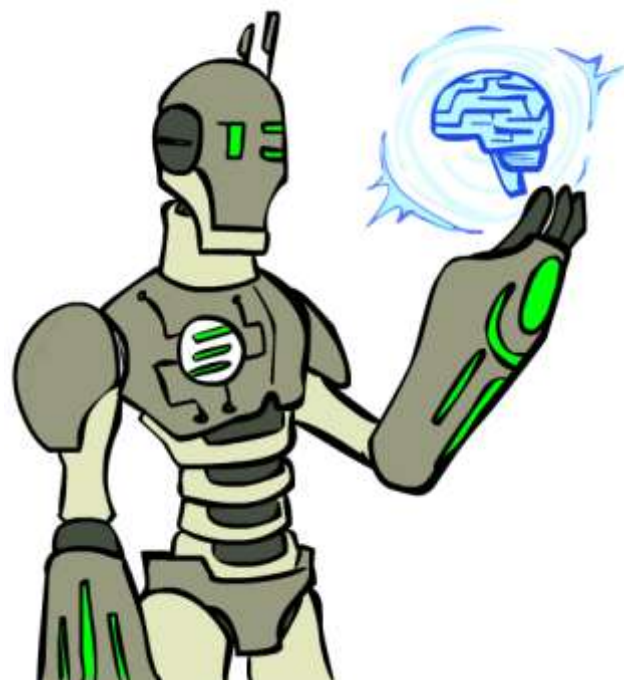






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# 极小极大搜索

## □ MiniMax值:

MiniMax( $s$ )

$$= \begin{cases} \text{Utility}(s), & \text{if Terminal\_Test}(s), \\ \max_a \text{MiniMax}(\text{Result}(s, a)), & \text{if Player}(s) = \text{MAX}, \\ \min_a \text{MiniMax}(\text{Result}(s, a)), & \text{if Player}(s) = \text{MIN}. \end{cases}$$

## □ MiniMax决策 (最优决策) :

```
function MiniMax-Decision(state)
  If player(state) = MAX
    return  $\arg \max_a \text{MiniMax}(\text{Result}(\text{state}, a))$ 
  If player(state) = MIN
    return  $\arg \min_a \text{MiniMax}(\text{Result}(\text{state}, a))$ 
```



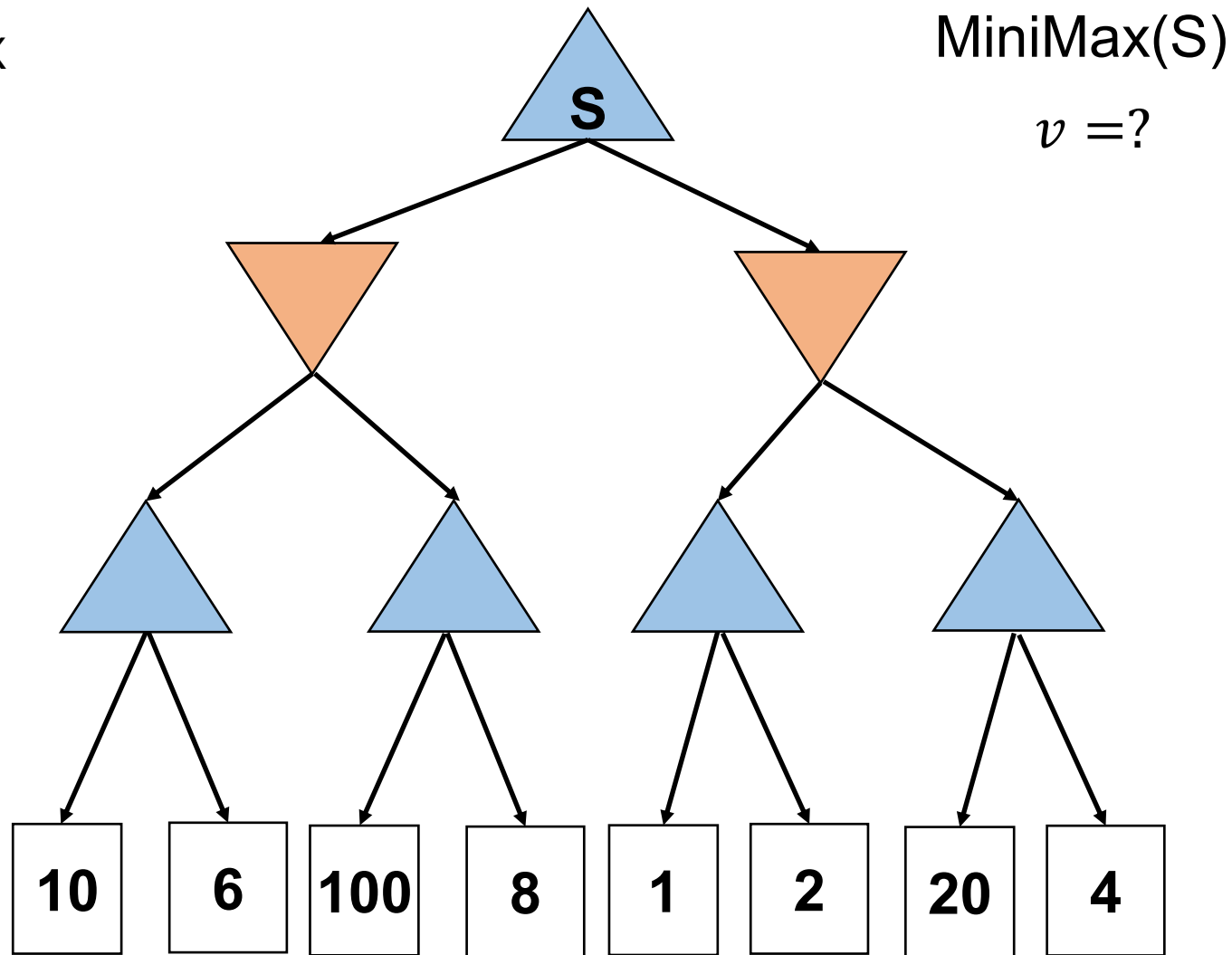
# 极小极大搜索：算法

```
function MiniMax(state)
  If Terminal-Test(state) return Utility(state)
  If player(state) = MAX {
     $v = -\infty$ 
    for each child {
       $v = \max(v, \text{MiniMax}(\text{child}))$ 
    }
  }
  else {
     $v = \infty$ 
    for each child {
       $v = \min(v, \text{MiniMax}(\text{child}))$ 
    }
  }
  return v //返回值
```





# 极小极大搜索：算法测试

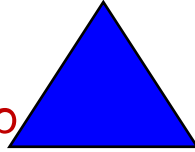




# 极小极大搜索：算法测试

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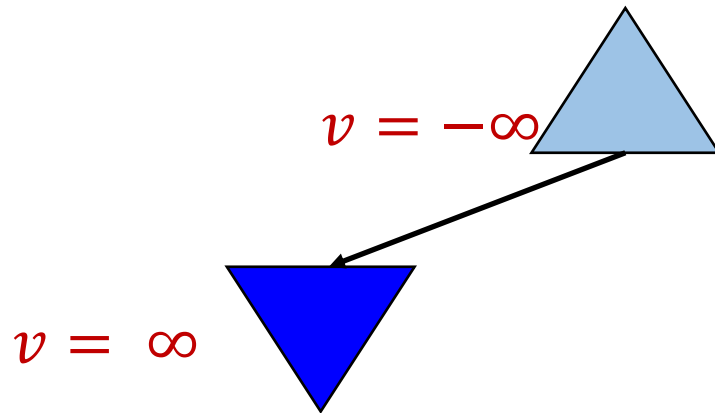
$$v = -\infty$$





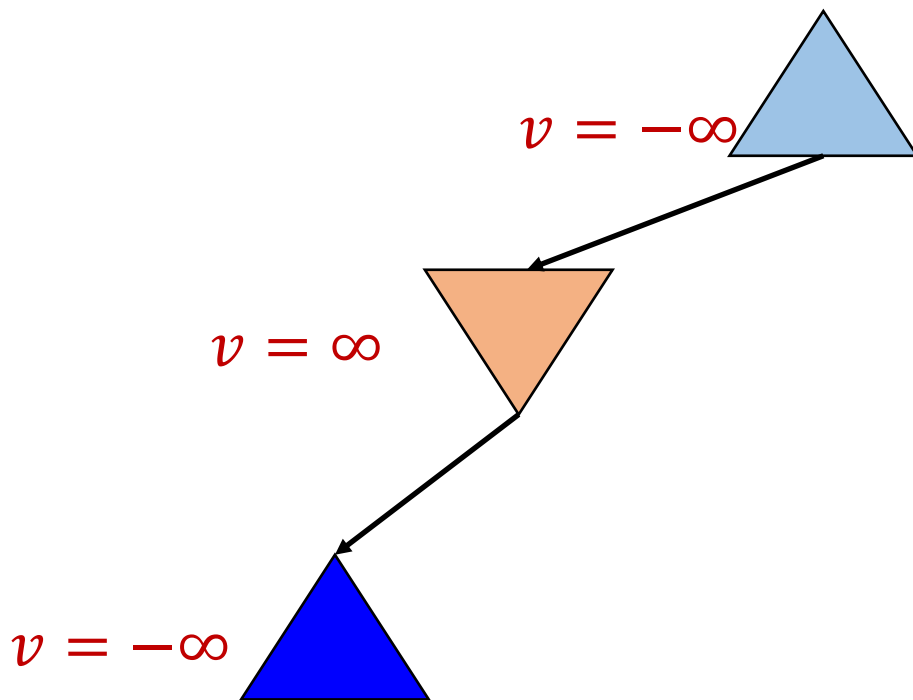


# 极小极大搜索：算法测试



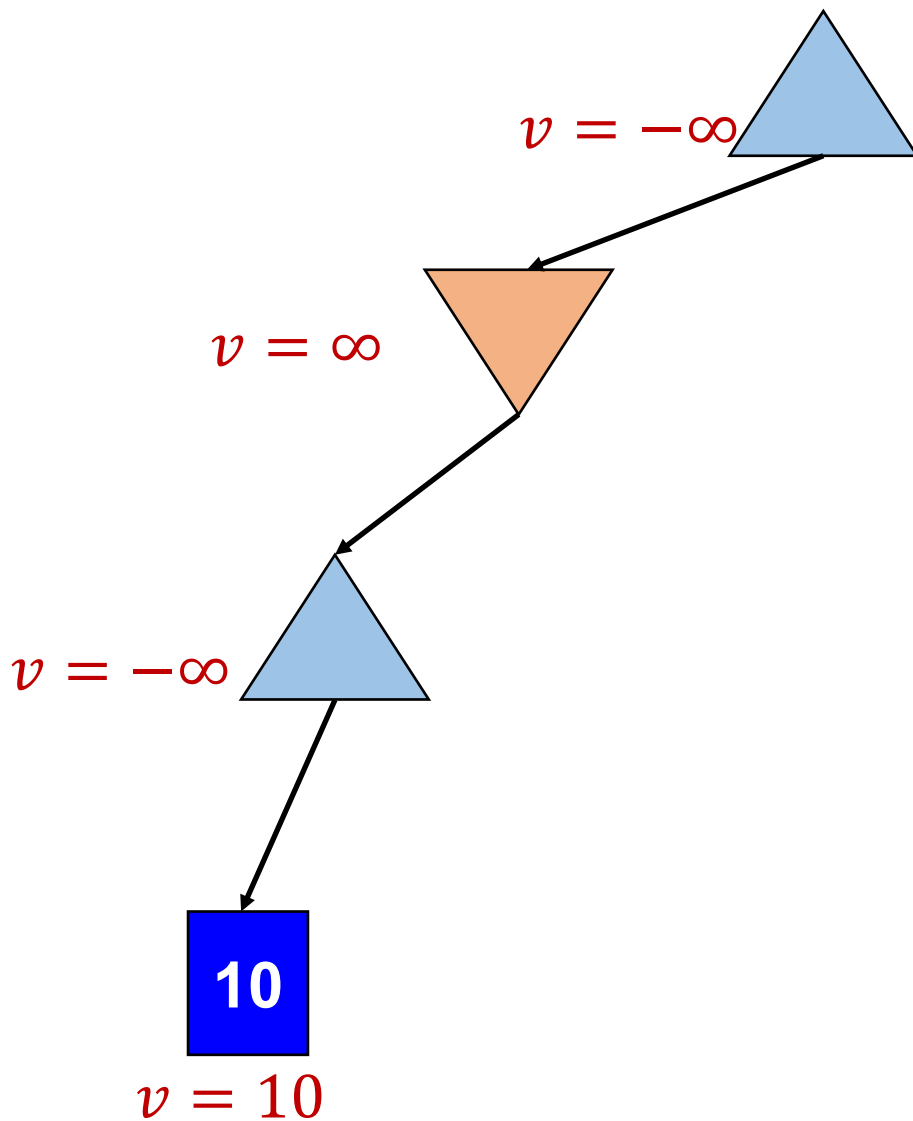


# 极小极大搜索：算法测试



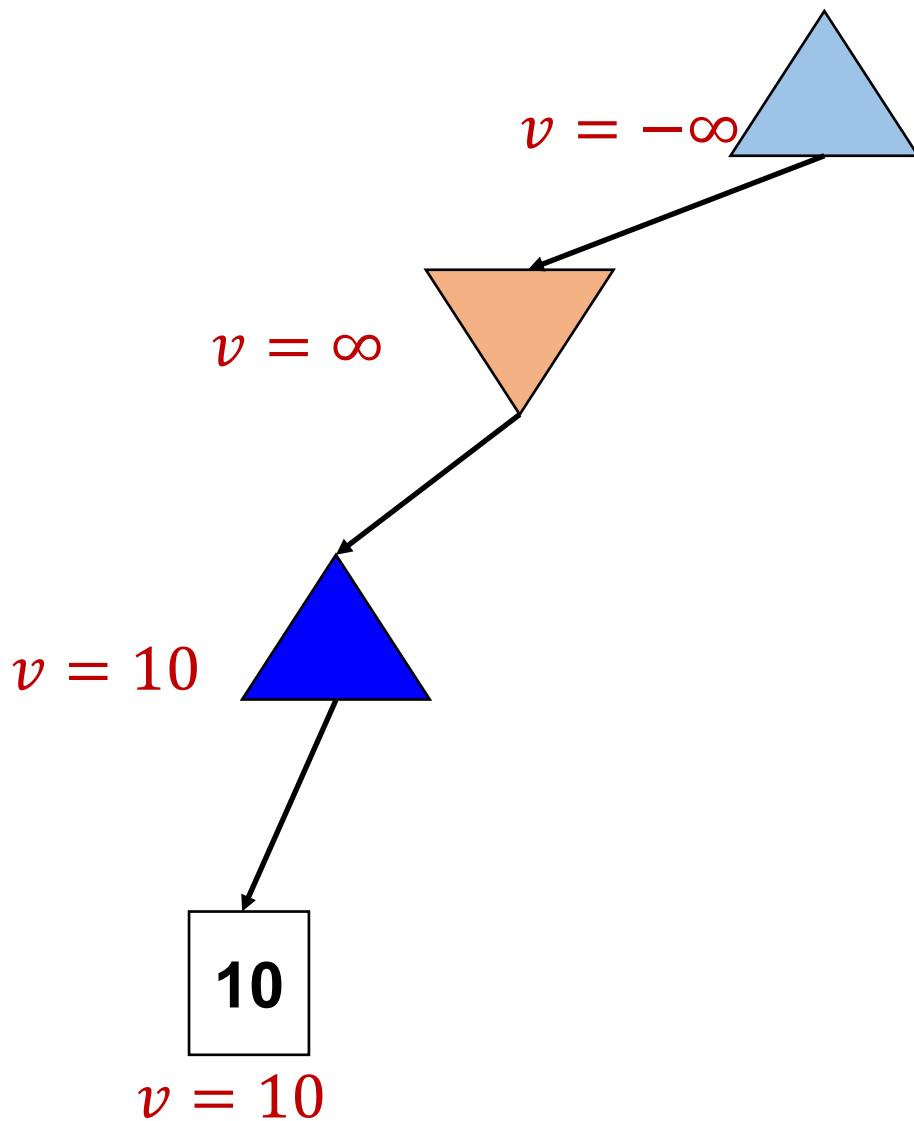


# 极小极大搜索：算法测试



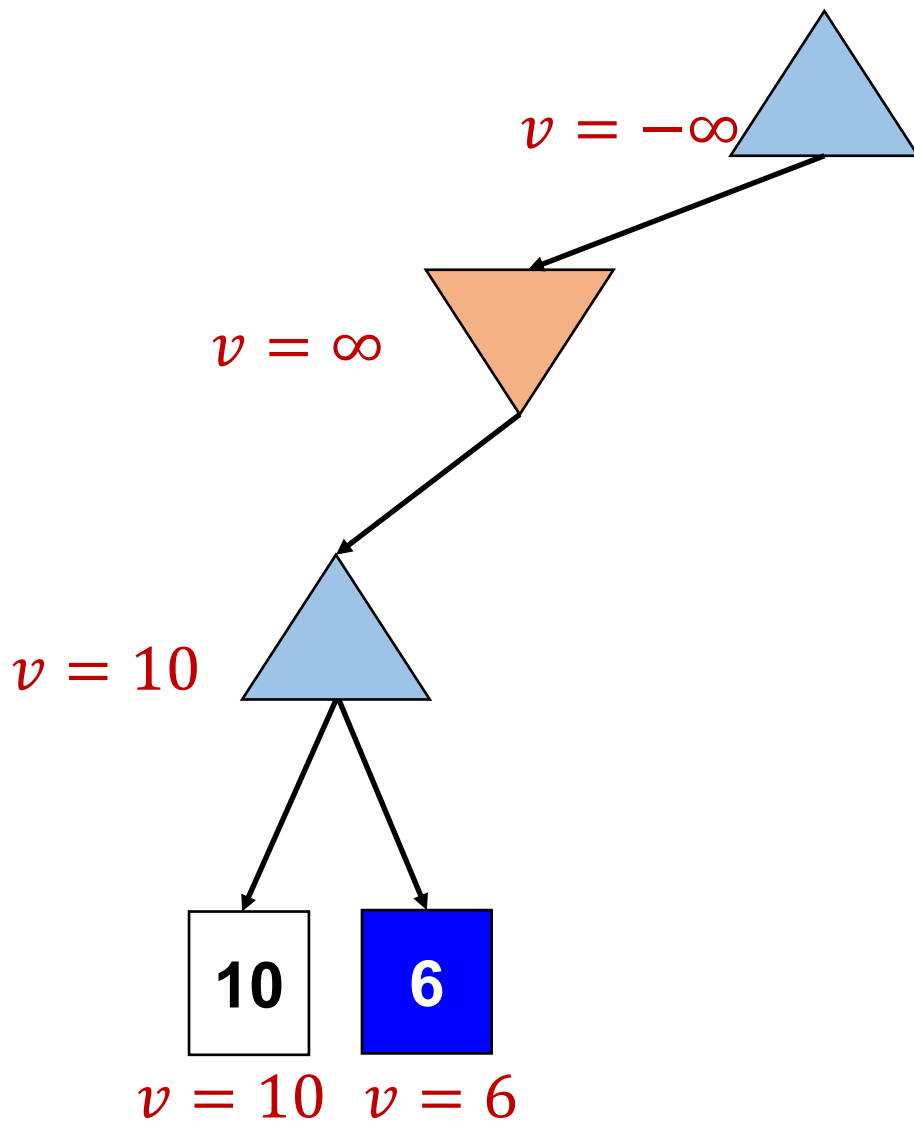


# 极小极大搜索：算法测试



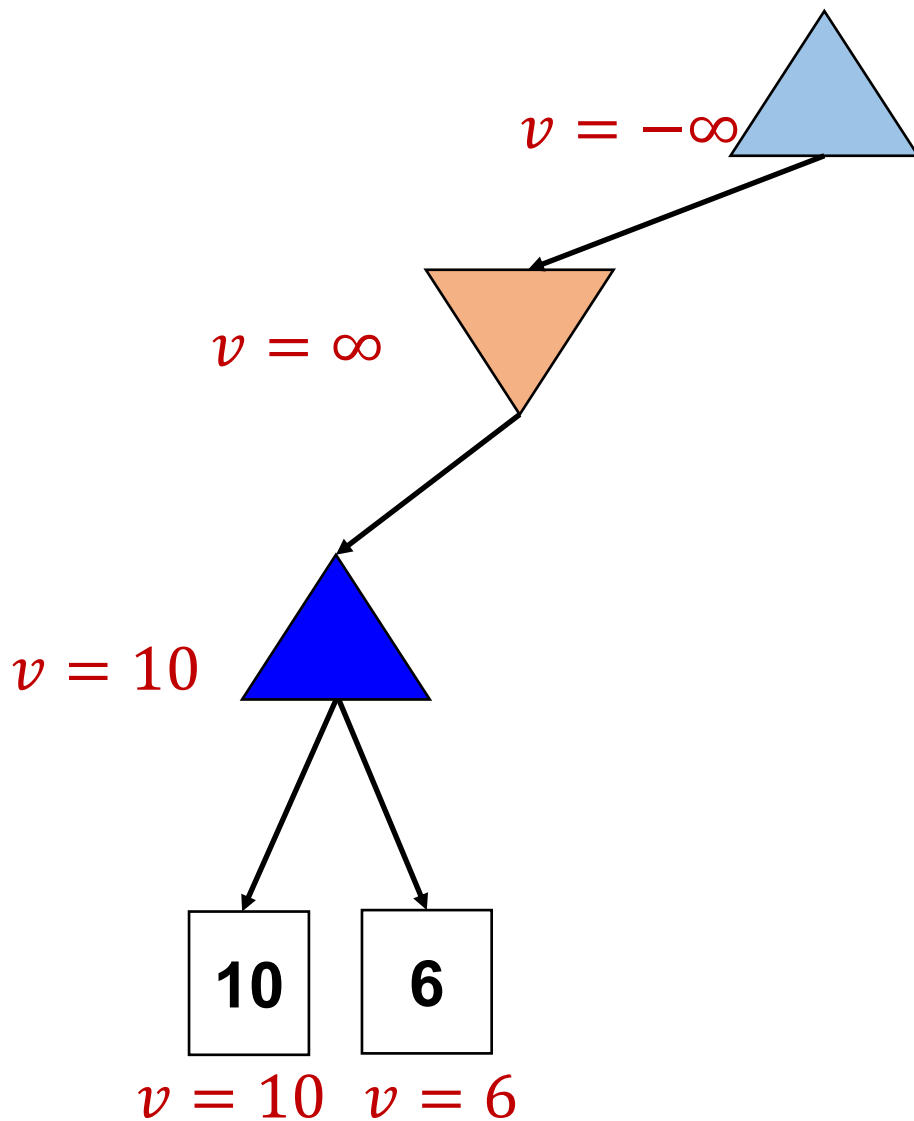


# 极小极大搜索：算法测试



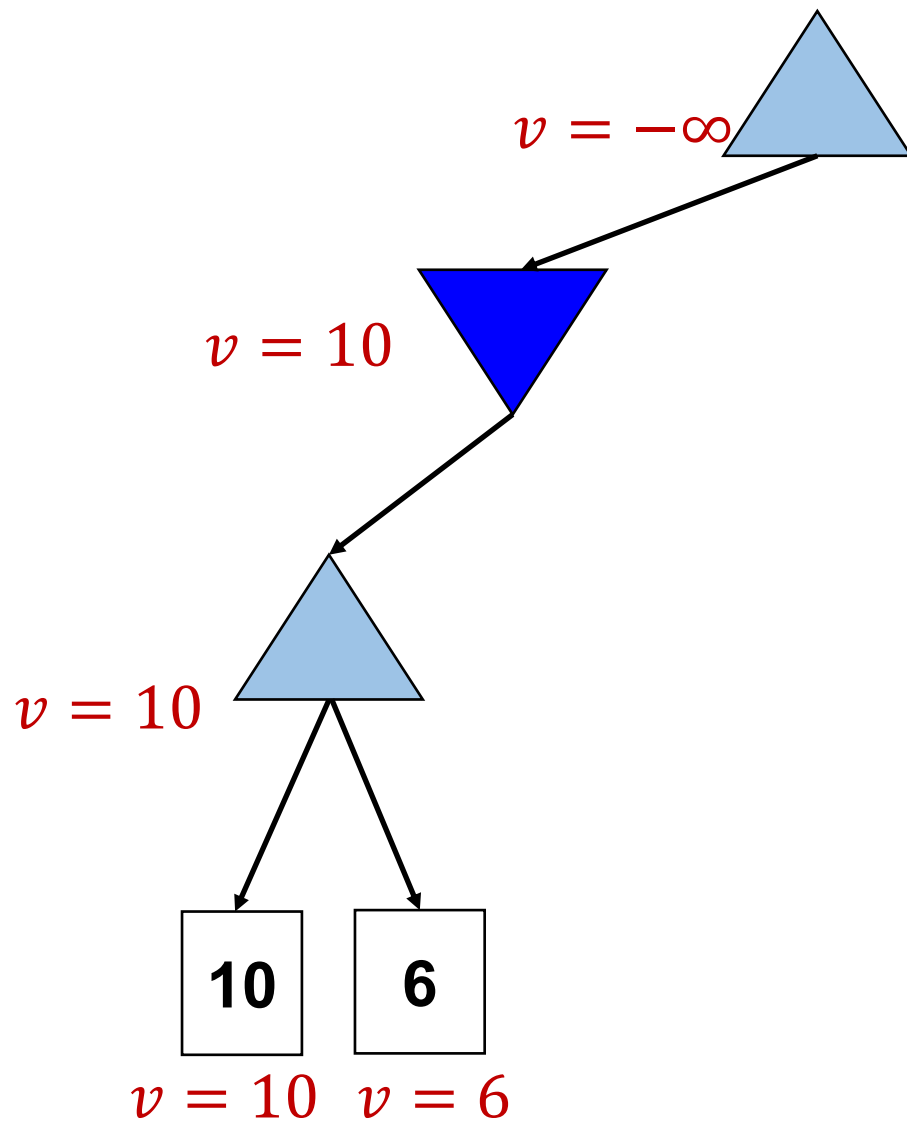


# 极小极大搜索：算法测试



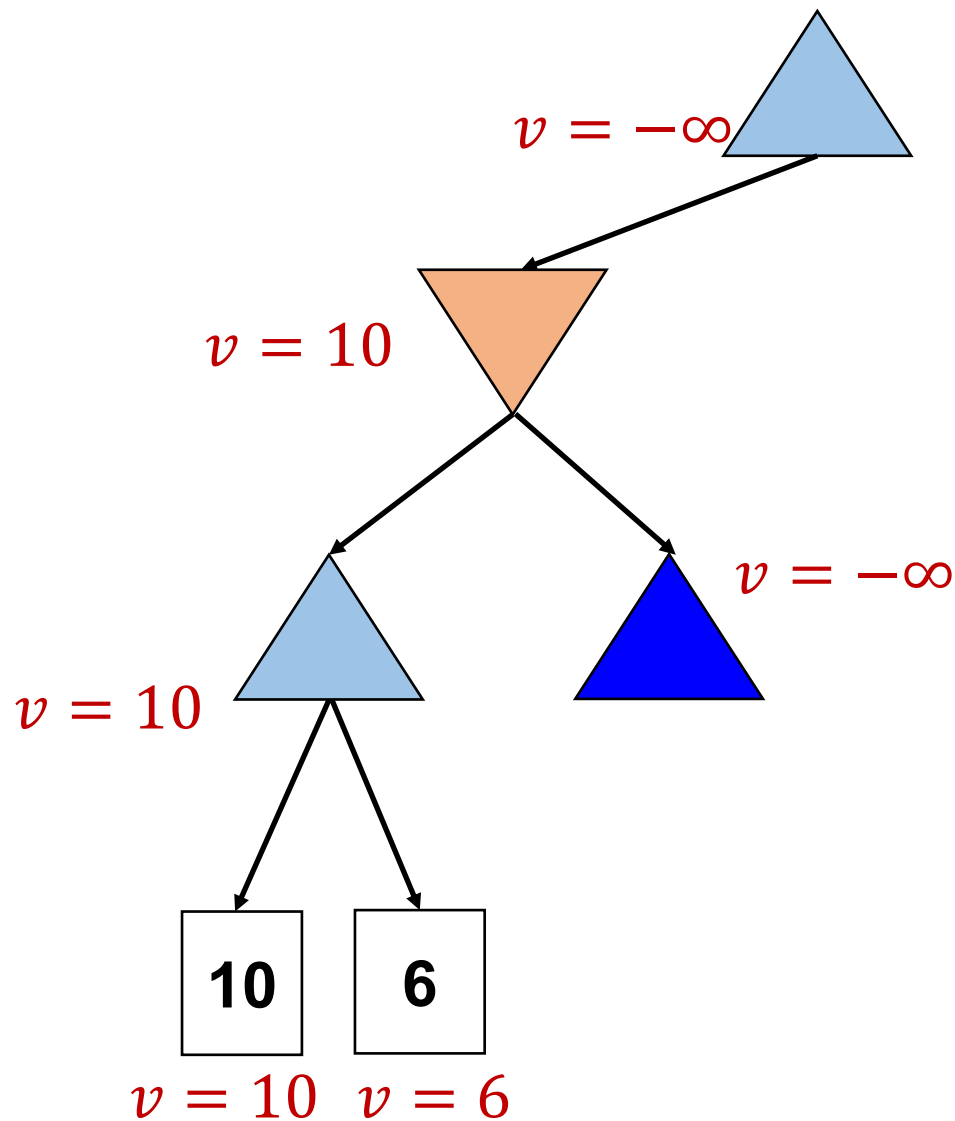


# 极小极大搜索：算法测试





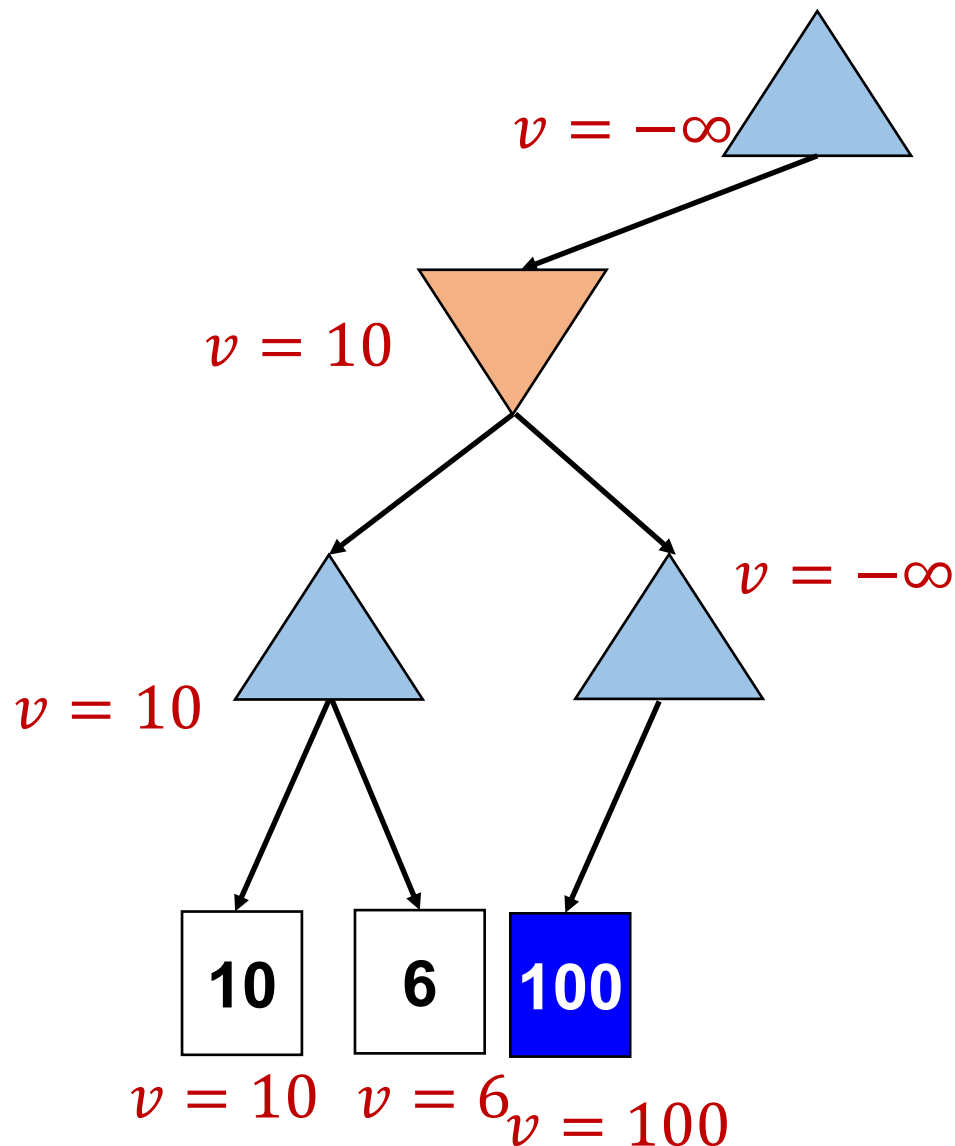
# 极小极大搜索：算法测试





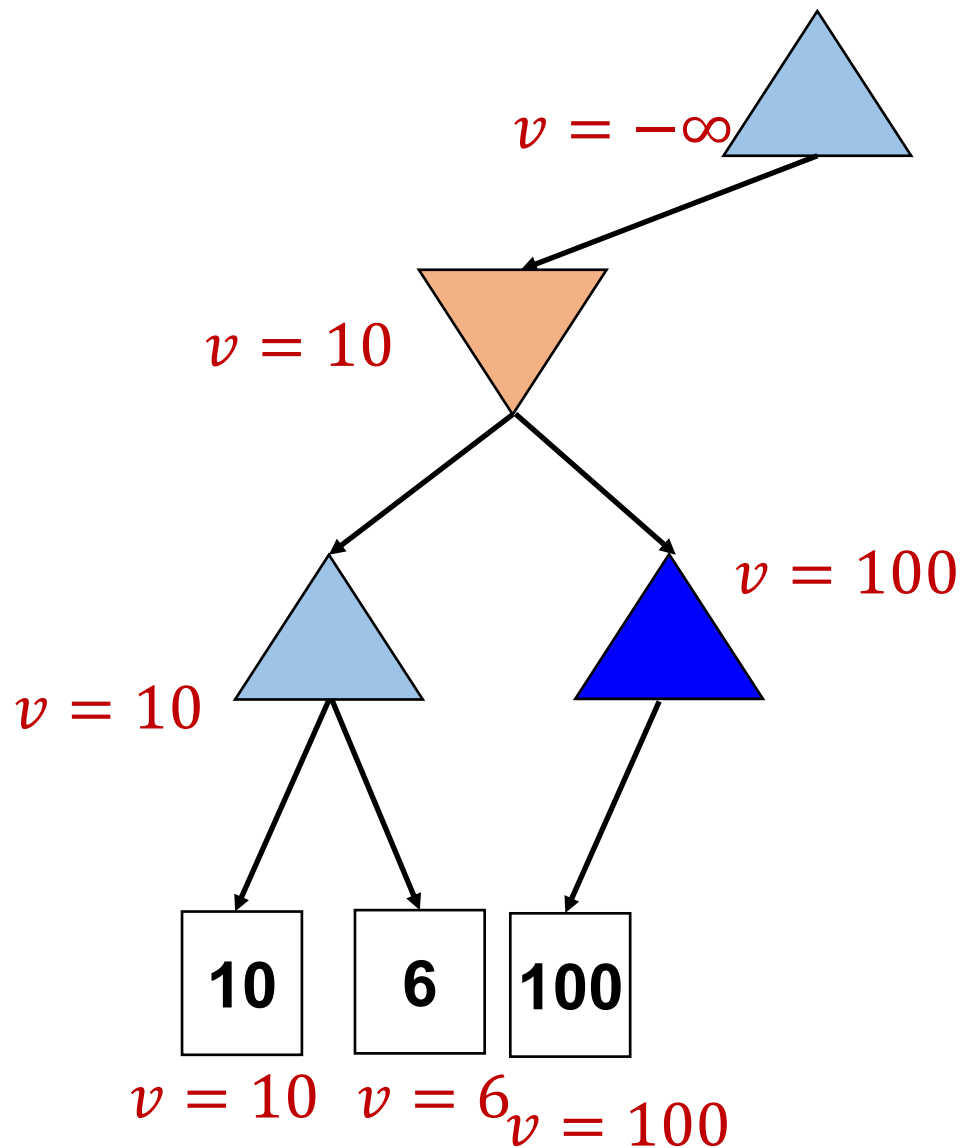


# 极小极大搜索：算法测试



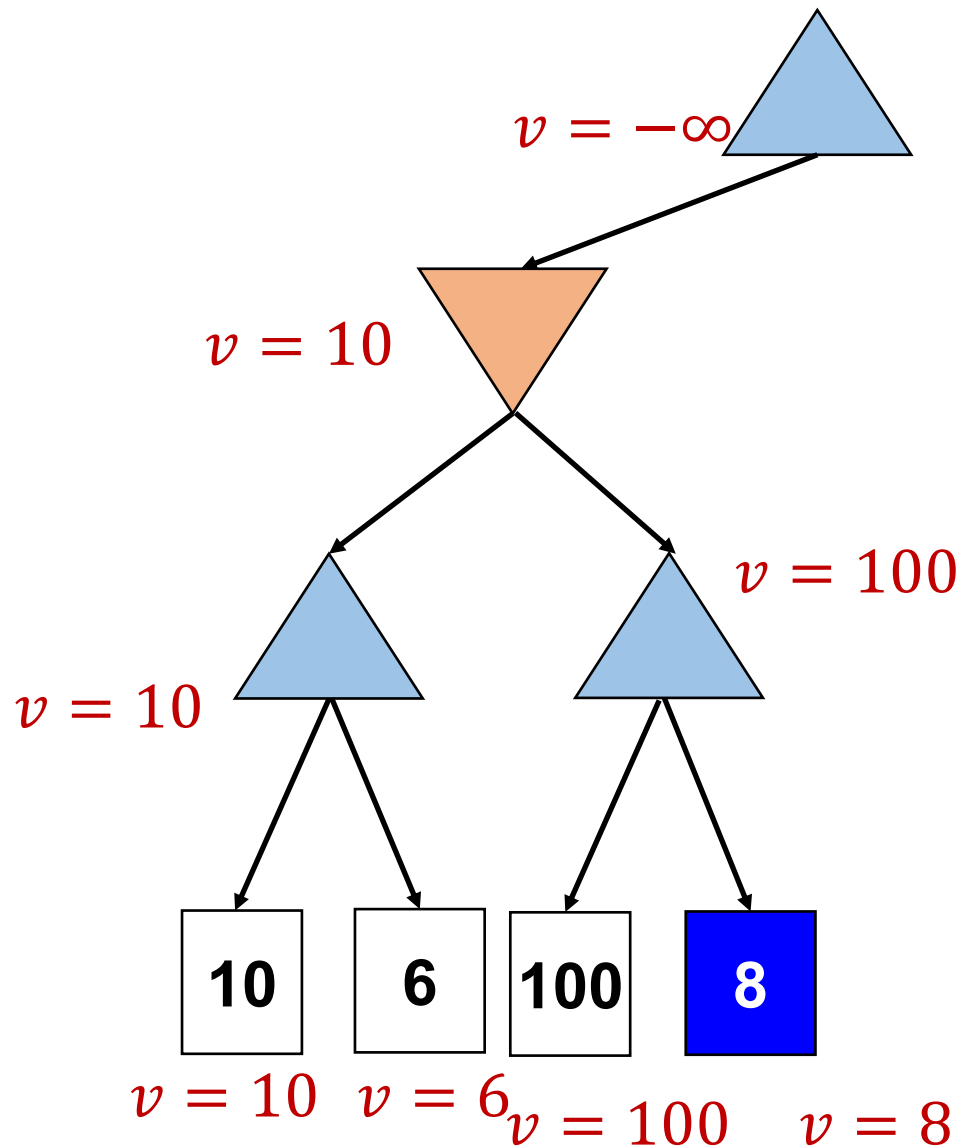


# 极小极大搜索：算法测试



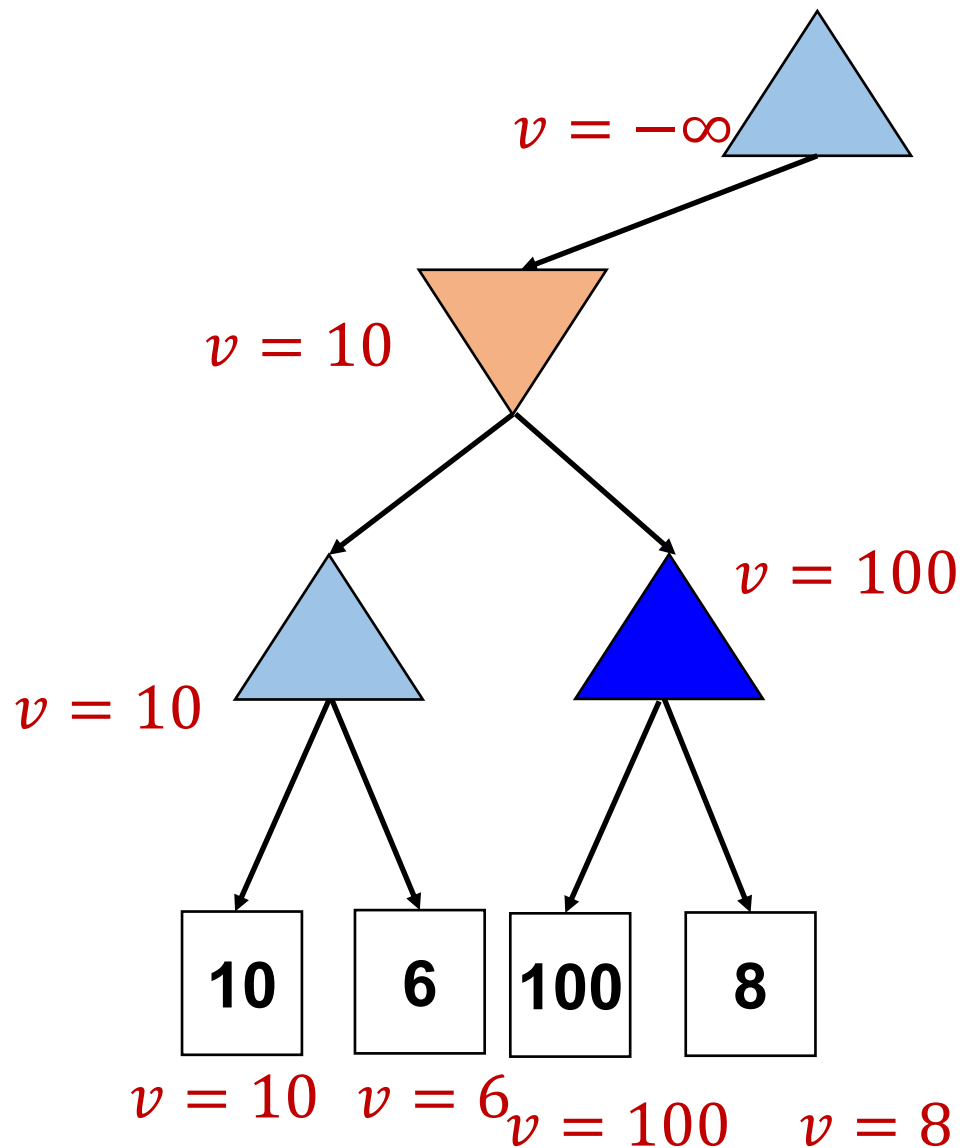


# 极小极大搜索：算法测试



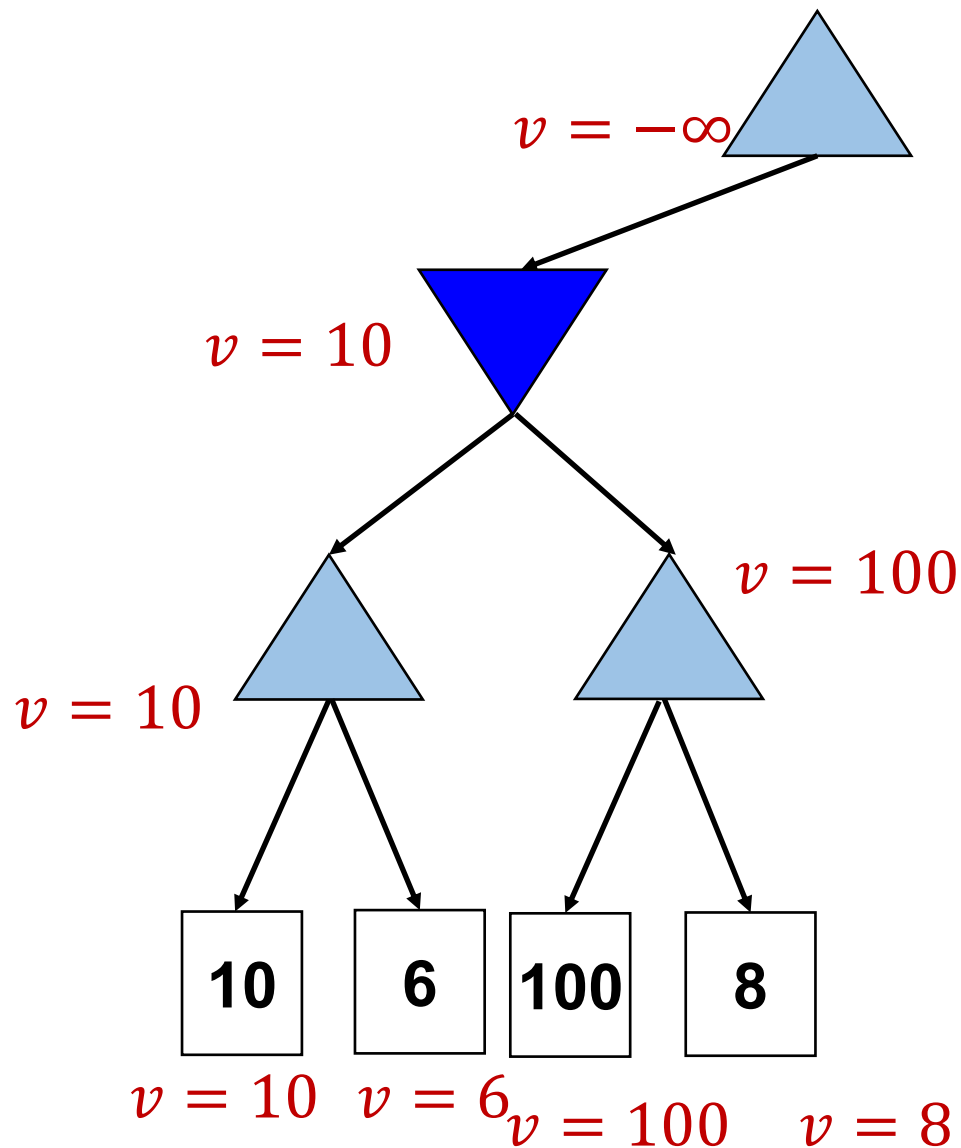


# 极小极大搜索：算法测试



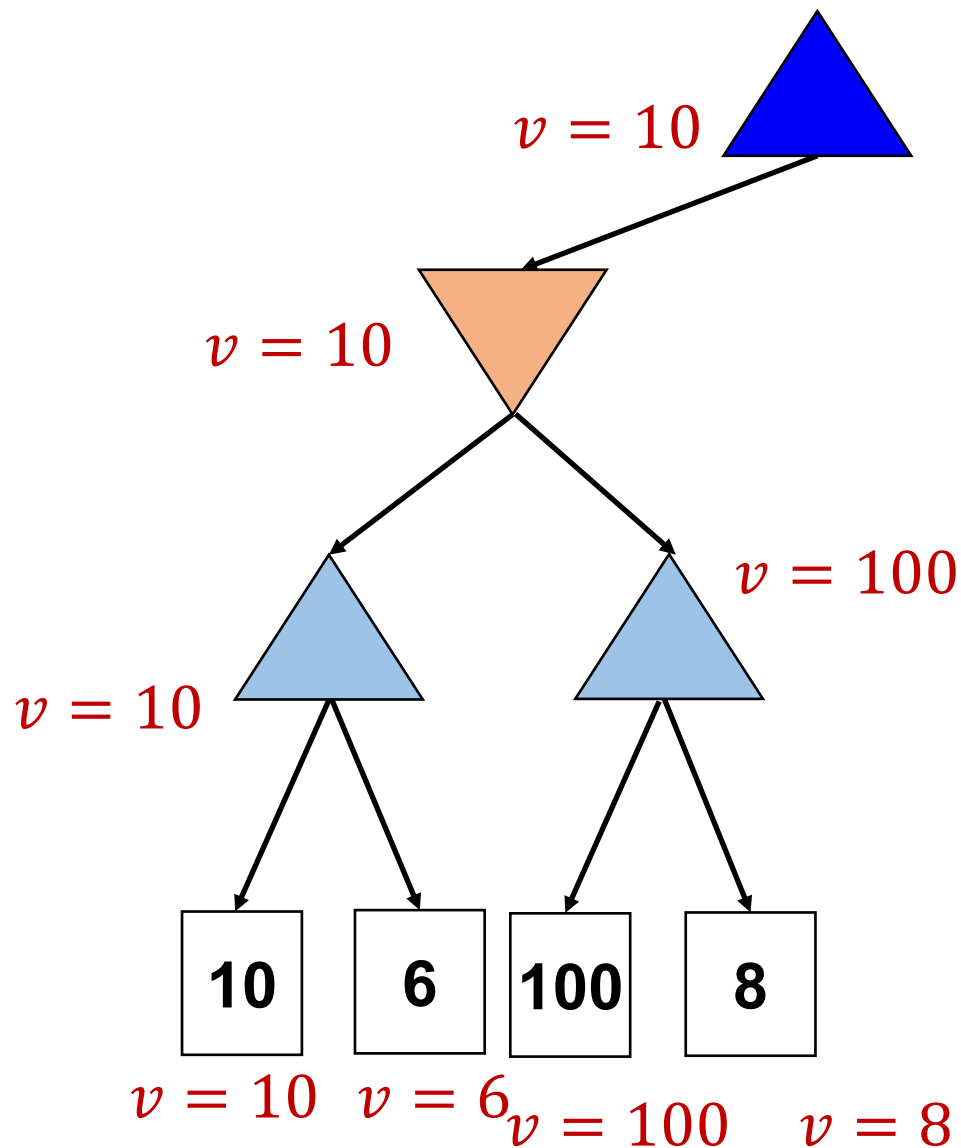


# 极小极大搜索：算法测试



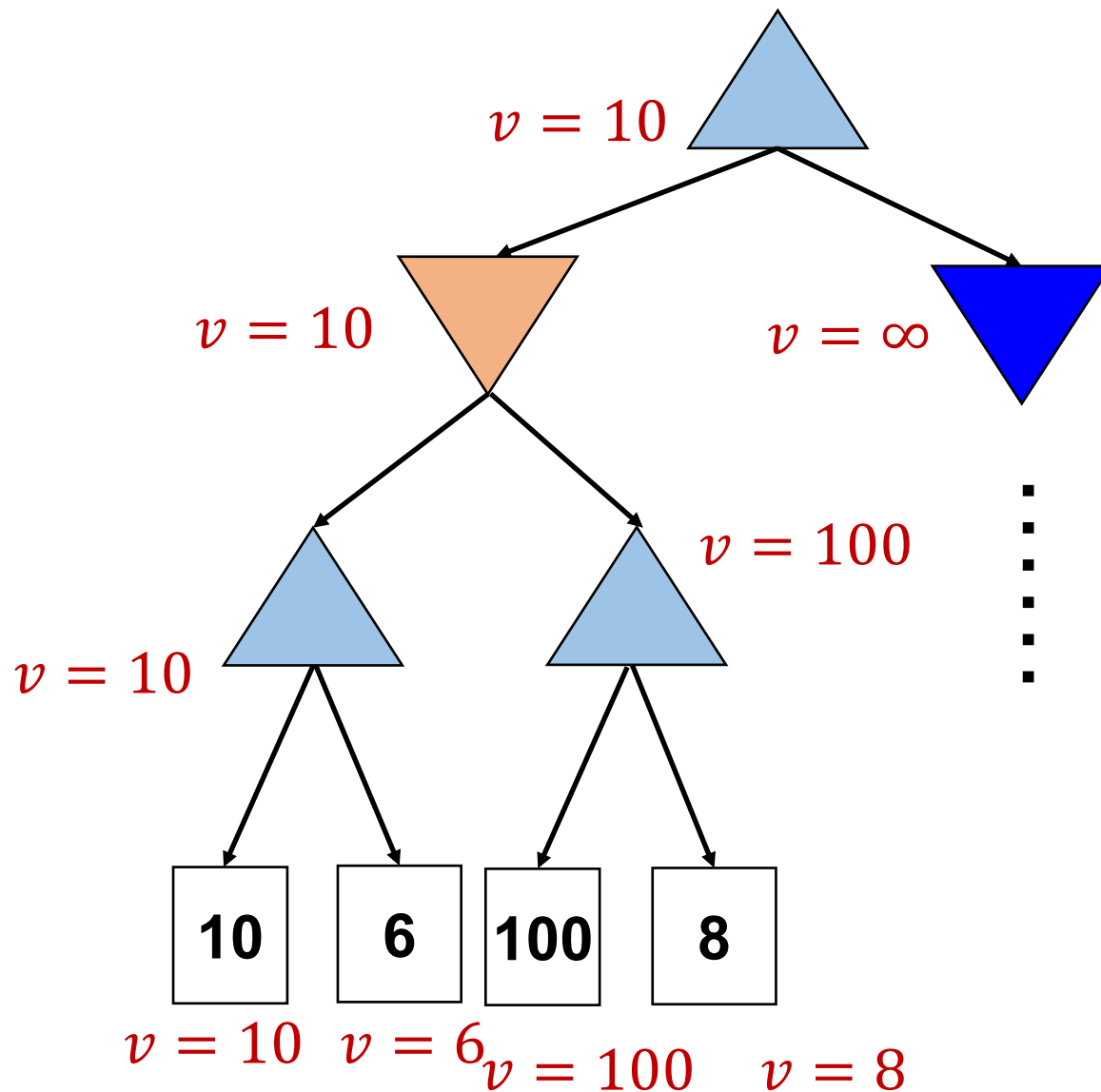


# 极小极大搜索：算法测试



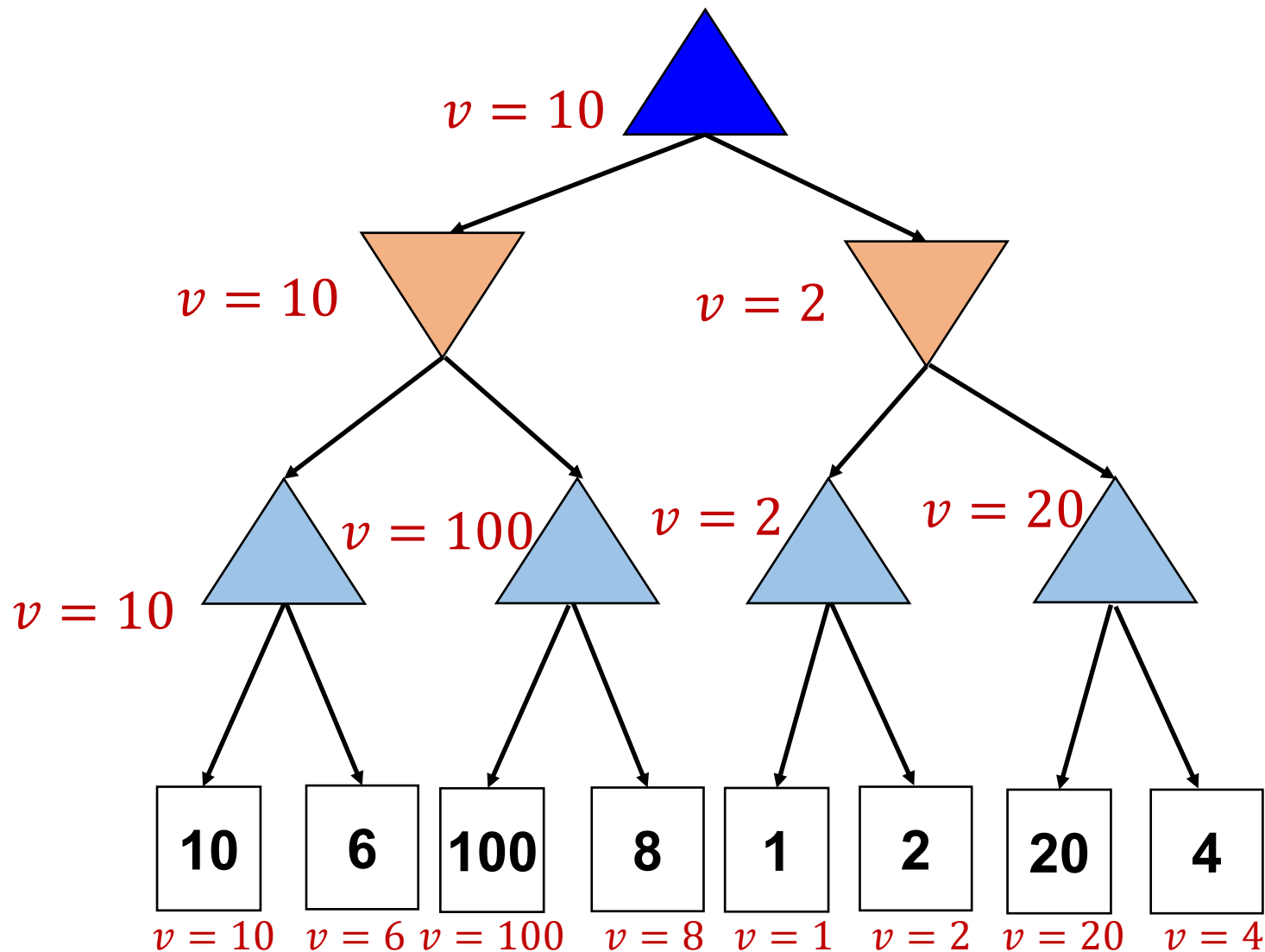


# 极小极大搜索：算法测试





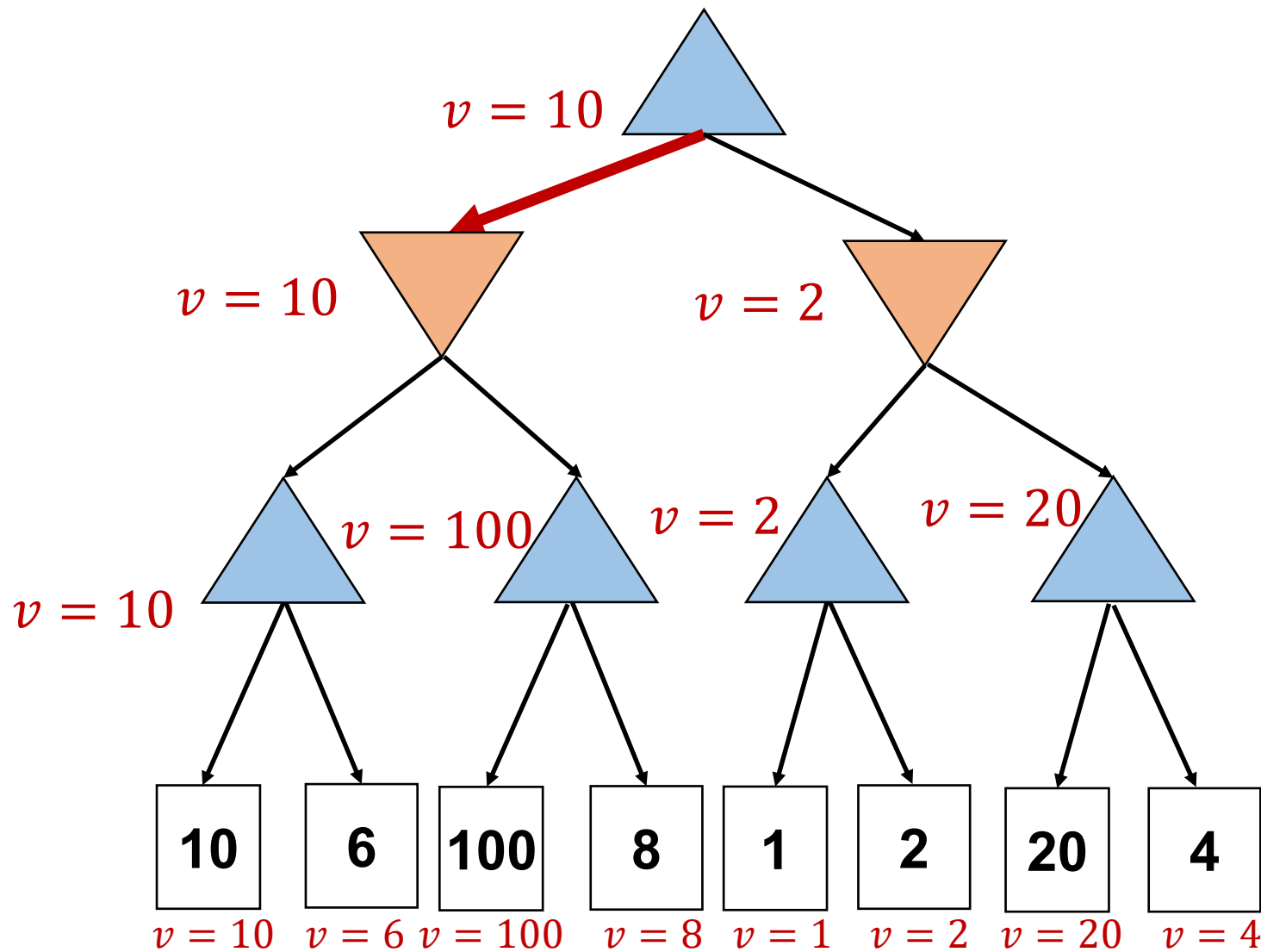
# 极小极大搜索：算法测试







# 极小极大搜索：算法测试





# 极小极大搜索：练习

```
function MiniMax(state)
```

```
  If Terminal-Test(state) return Utility(state)
```

```
  If player(state) = MAX {
```

```
     $v = -\infty$ 
```

```
    for each child {
```

```
       $v = \max(v, \text{MiniMax}(\text{child}))$ 
```

```
    }
```

```
  else {
```

```
     $v = \infty$ 
```

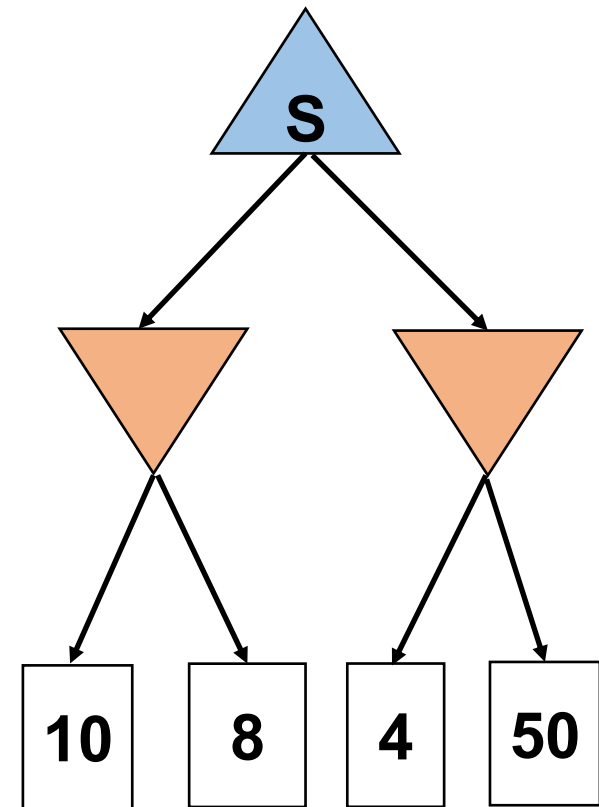
```
    for each child {
```

```
       $v = \min(v, \text{MiniMax}(\text{child}))$ 
```

```
    }
```

```
  return  $v$  //返回值
```

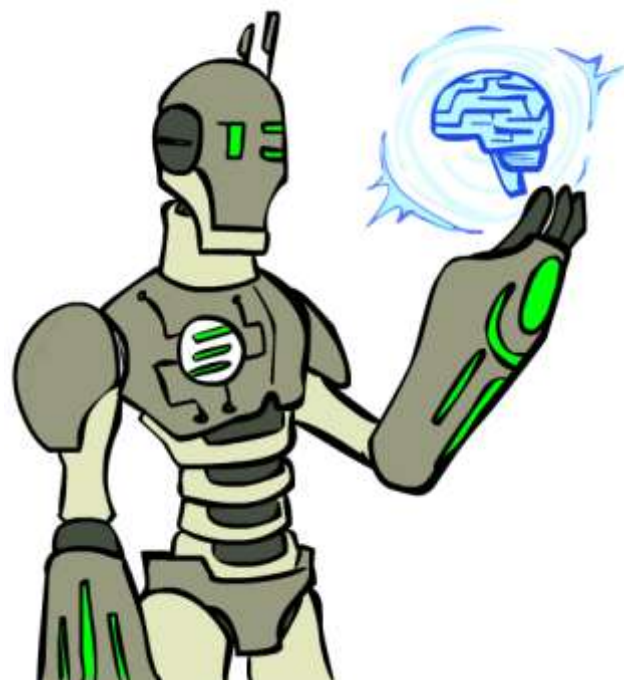
MiniMax(S)





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# 极小极大搜索的效率

## □ 与深度优先遍历相同：

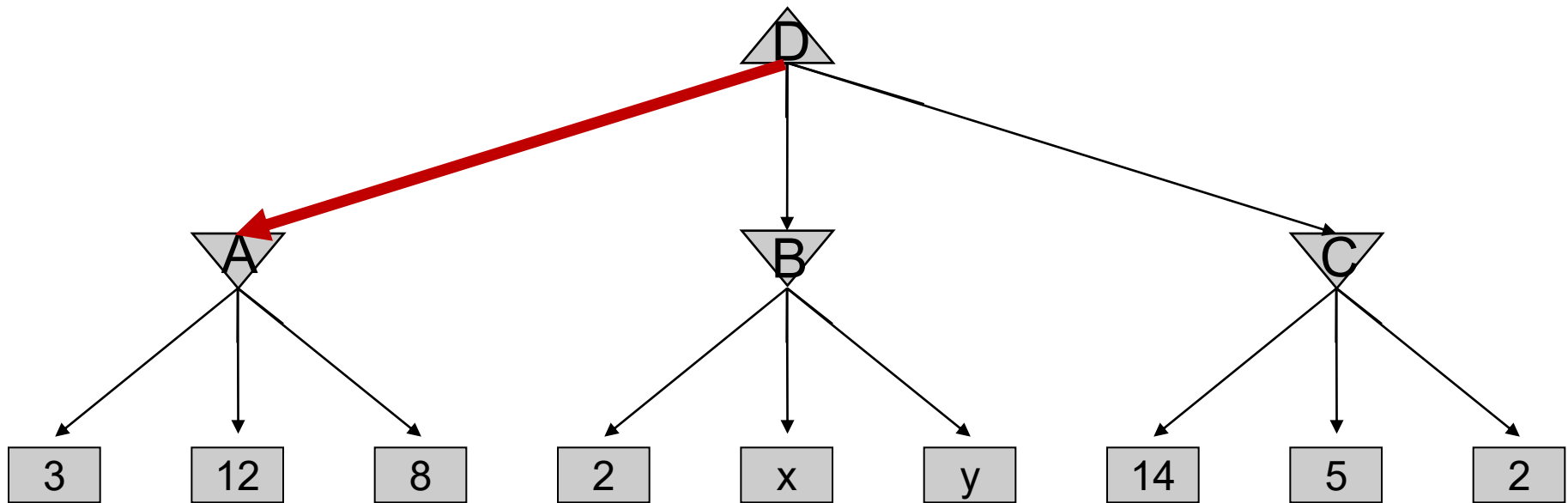
- $m$ 层（到达终局的步数）， $b$ 分支(行动个数)
- 时间复杂度:  $O(b^m)$
- 空间复杂度:  $O(bm)$
- 结论：很多情况下无法运行（比如：围棋）

## □ 在初始状态做出最优行为决策是否有必要遍历整棵树？





# 是否有必要遍历整棵树?



$$\begin{aligned} & \text{MiniMax}(D) \\ &= \max(\min(3, 12, 8), \min(2, x, y), \min(14, 5, 2)) \\ &= \max(3, \min(2, x, y), 2) = 3 \end{aligned}$$

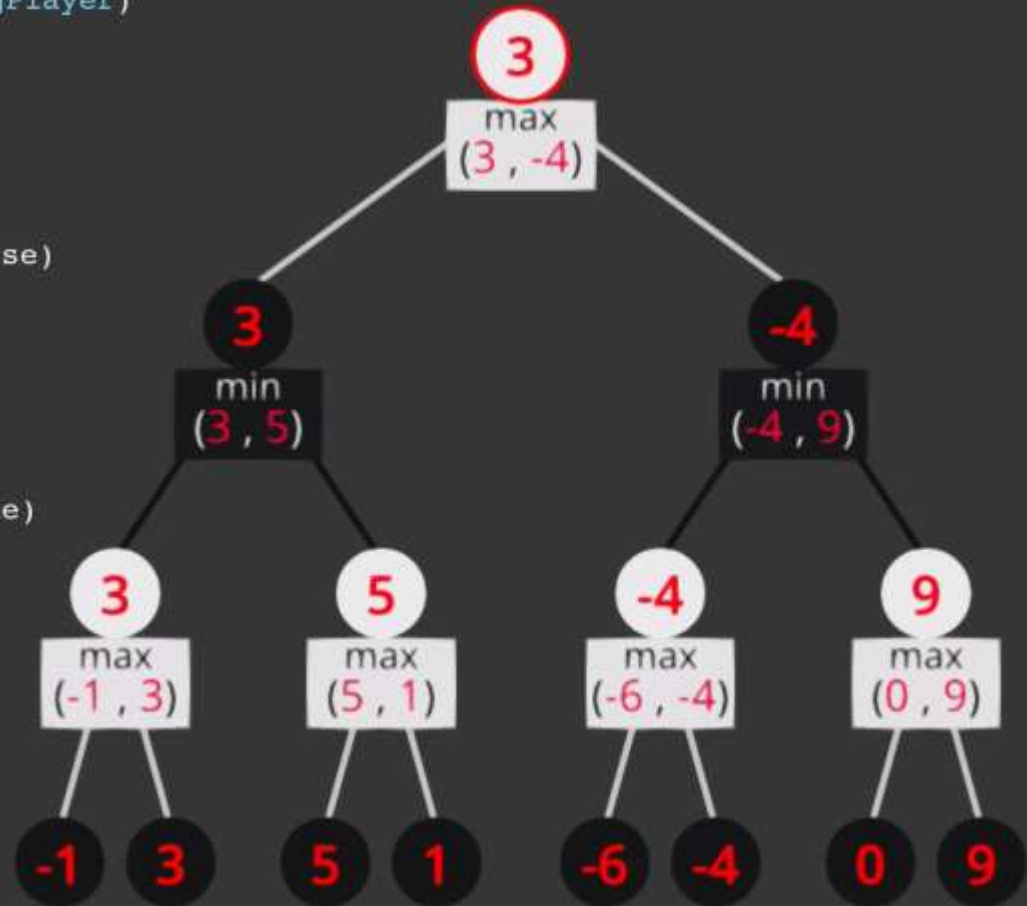


```
function minimax(position, depth, maximizingPlayer)
  if depth == 0 or game over in position
    return static evaluation of position
```

```
  if maximizingPlayer
    maxEval = -infinity
    for each child of position
      eval = minimax(child, depth - 1, false)
      maxEval = max(maxEval, eval)
    return maxEval
```

```
  else
    minEval = +infinity
    for each child of position
      eval = minimax(child, depth - 1, true)
      minEval = min(minEval, eval)
    return minEval
```

```
// initial call
minimax(currentPosition, 3, true)
```





# $\alpha$ - $\beta$ 决策

## □ $\alpha$ - $\beta$ 决策:

- 类似MiniMax决策
- $\alpha$ : MiniMax的下界, 初始值=  $-\infty$
- $\beta$ : MiniMax的上界, 初始值=  $\infty$
- 减少博弈树的分枝, 不影响决策的最优性, 即: 等同于MiniMax决策

```
function AlphaBeta-Decision(state)
```

```
  If player(state) = MAX
```

```
    return  $\arg \max_a$  AlphaBeta(Result(state, a),  $-\infty$ ,  $\infty$ )
```

```
  If player(state) = MIN
```

```
    return  $\arg \min_a$  AlphaBeta(Result(state, a),  $-\infty$ ,  $\infty$ )
```

如何实现AlphaBeta(state,  $\alpha$ ,  $\beta$ )函数?



# $\alpha$ - $\beta$ 剪枝

```
function AlphaBeta(state,  $\alpha$ ,  $\beta$ )
```

```
If Terminal-Test(state) return Utility(state)
```

```
If player(state) = MAX {
```

```
     $v = -\infty$ 
```

```
    for each child {
```

```
         $v = \max(v, \text{AlphaBeta}(\text{child}, \alpha, \beta))$ 
```

```
         $\alpha = \max(\alpha, v)$ 
```

```
        if  $\beta \leq \alpha$  then break // 裁剪 }
```

```
    else {
```

```
         $v = \infty$ 
```

```
        for each child {
```

```
             $v = \min(v, \text{AlphaBeta}(\text{child}, \alpha, \beta))$ 
```

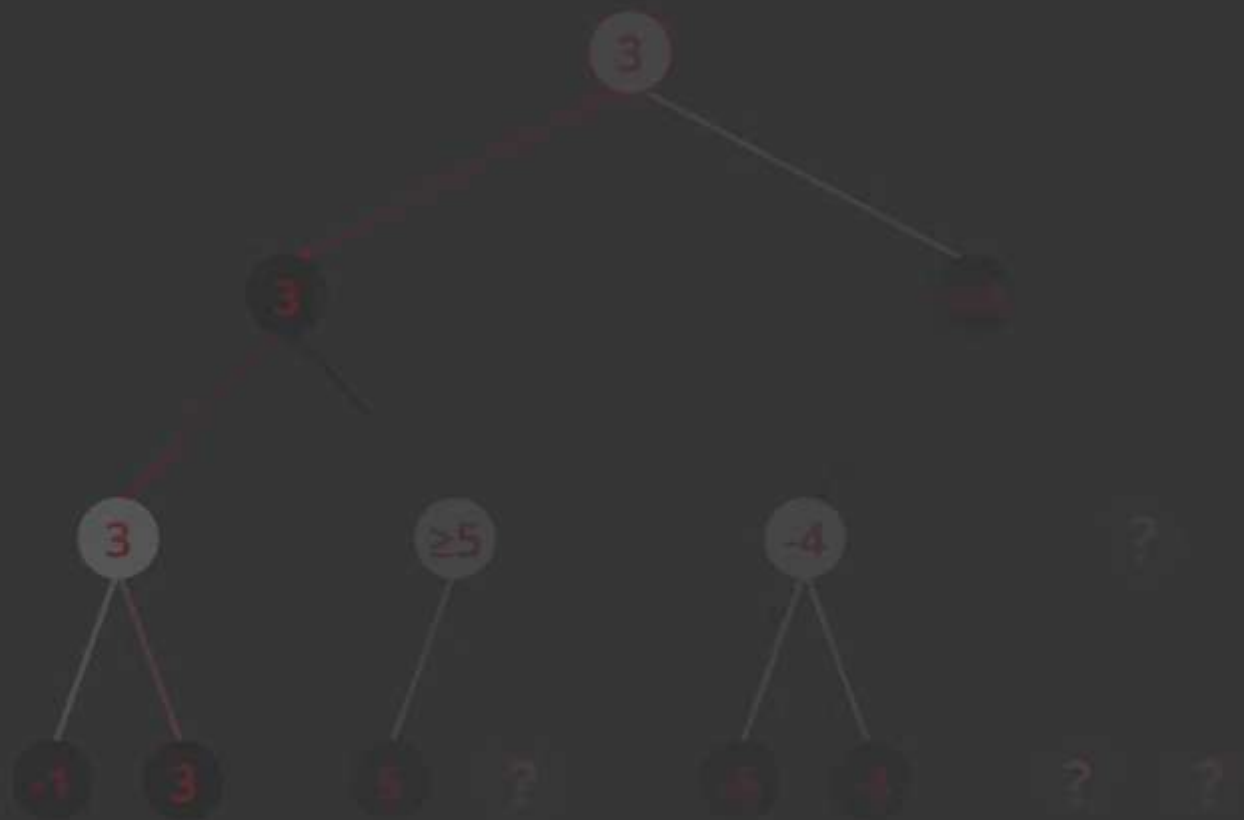
```
             $\beta = \min(\beta, v)$ 
```

```
            if  $\beta \leq \alpha$  then break // 裁剪 }
```

```
    return  $v$  // 返回值
```

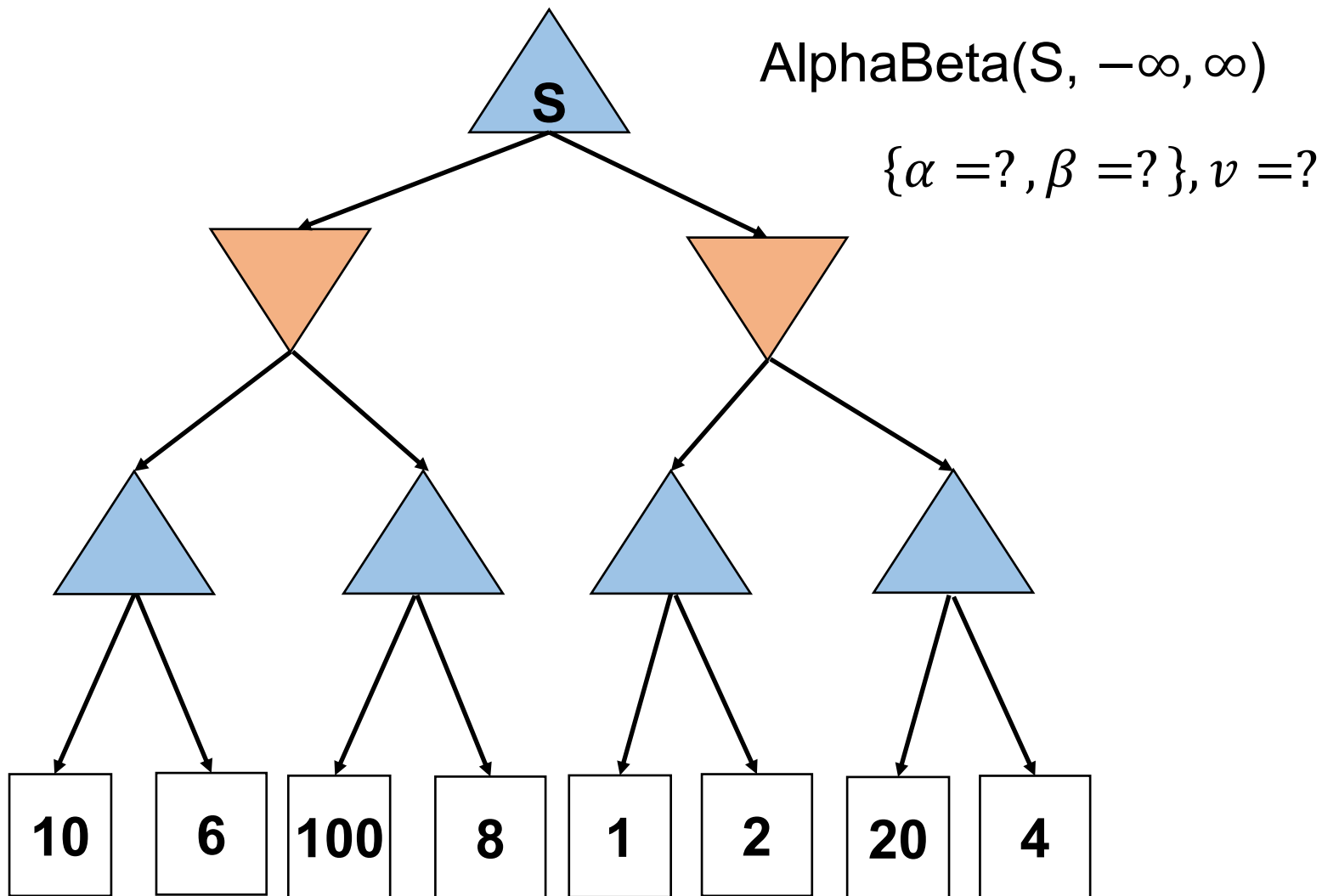
- $\alpha$ : MiniMax值的下界, 不断增加
- $\beta$ : MiniMax值的上届, 不断减小
- 裁剪条件:  
 $\beta \leq \alpha$
- 关注每个状态:
  - 向子节点传递 $\alpha$ 与 $\beta$
  - 接受子节点的返回值 $v$ , 更新 $\alpha$  (MAX) 或 $\beta$  (MIN)
  - 返回值 $v$







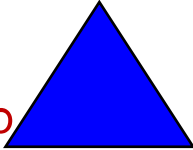
# $\alpha$ - $\beta$ 剪枝: 算法测试





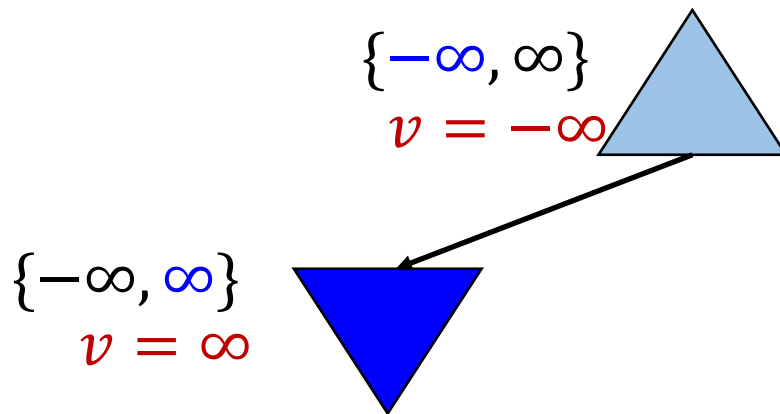
# $\alpha$ - $\beta$ 剪枝：算法测试

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$$\{\textcolor{blue}{-}\infty, \infty\}$$
$$\textcolor{red}{v} = \textcolor{red}{-}\infty$$
A solid blue equilateral triangle pointing upwards, positioned to the right of the mathematical expressions.

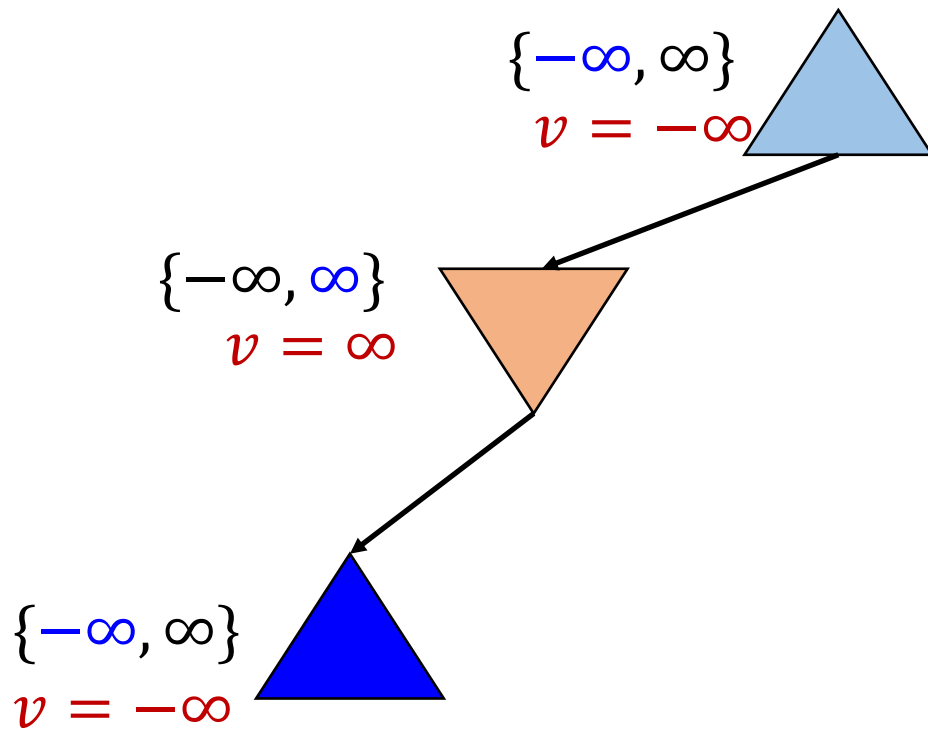


# $\alpha$ - $\beta$ 剪枝：算法测试



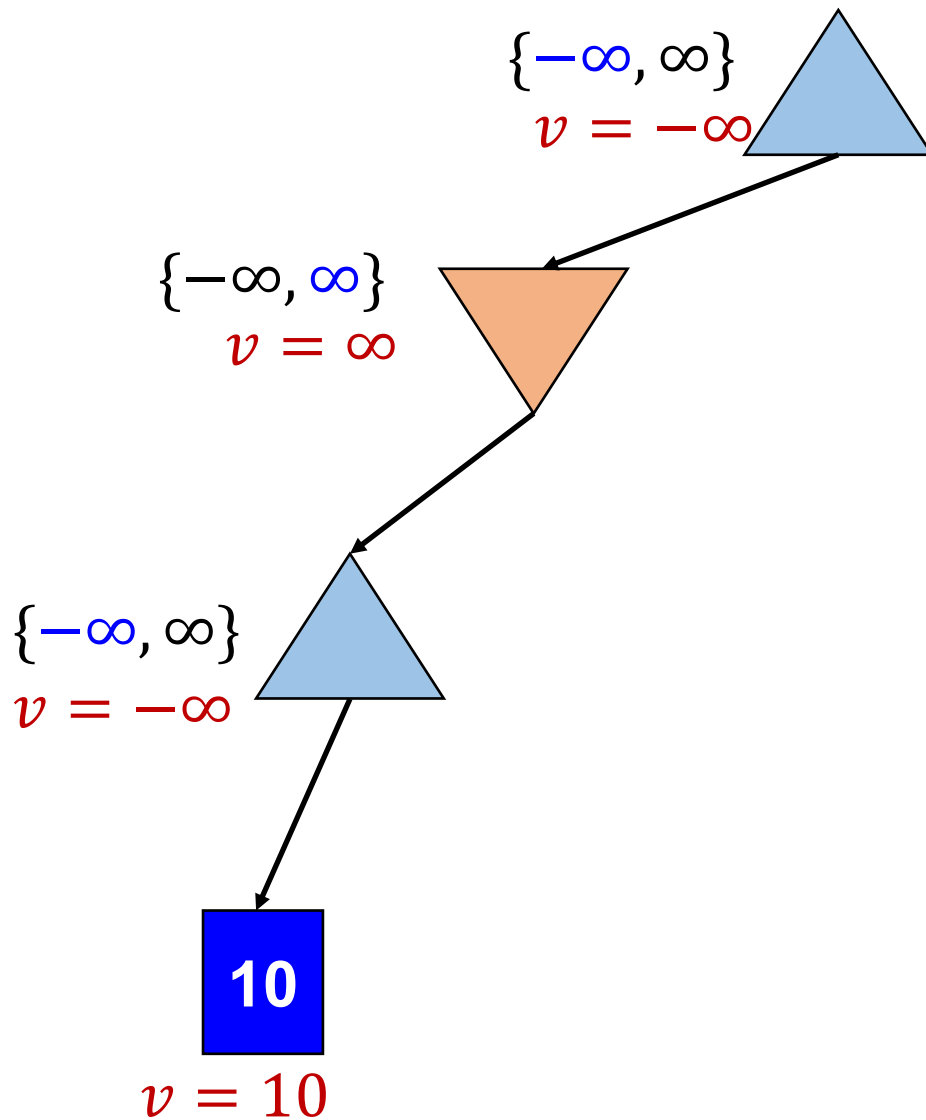


# $\alpha$ - $\beta$ 剪枝：算法测试



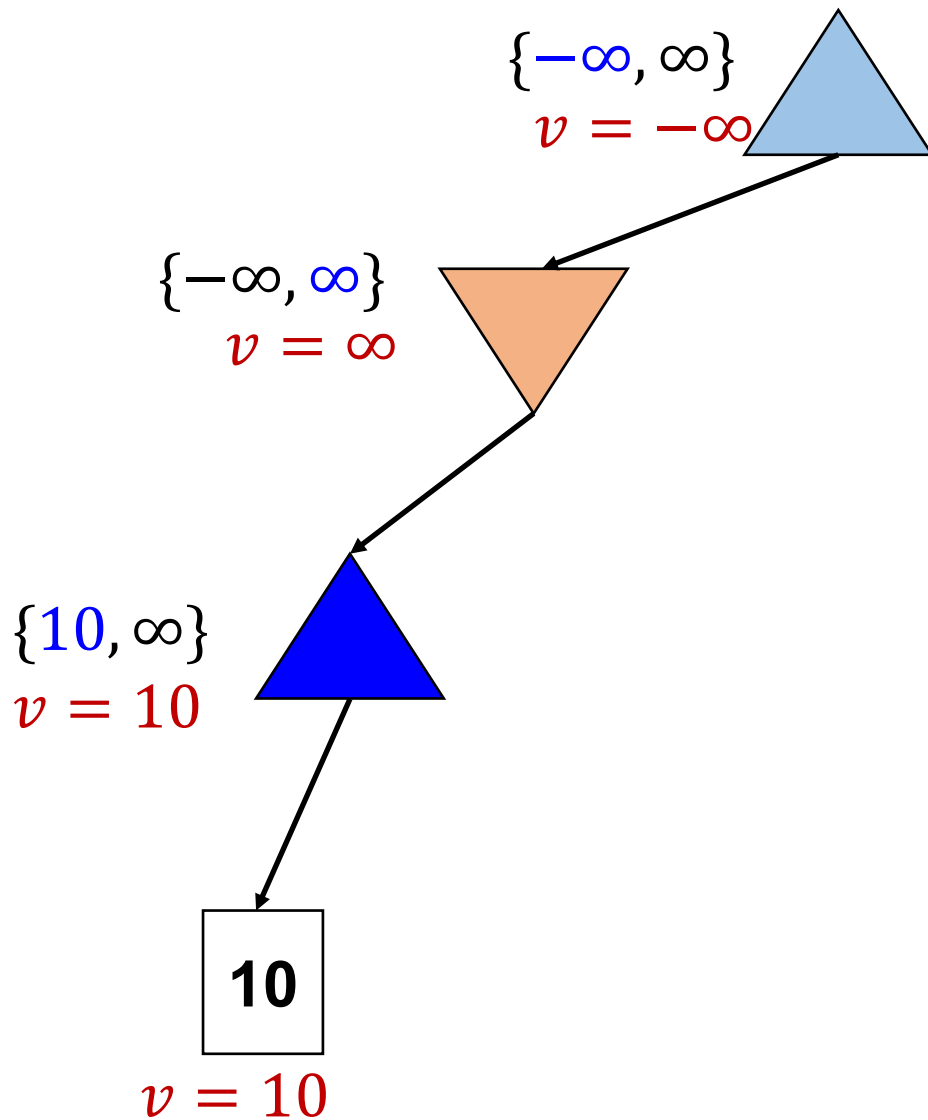


# $\alpha$ - $\beta$ 剪枝：算法测试



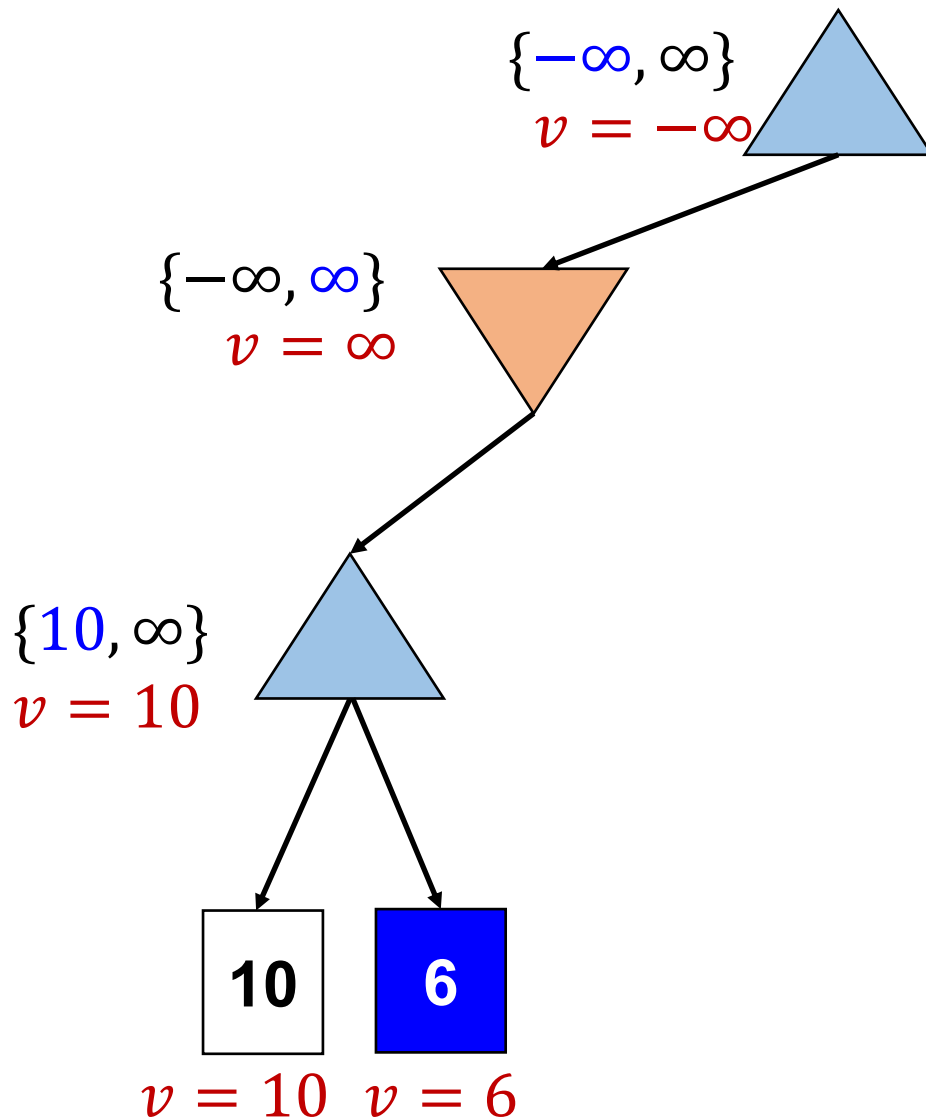


# $\alpha$ - $\beta$ 剪枝：算法测试





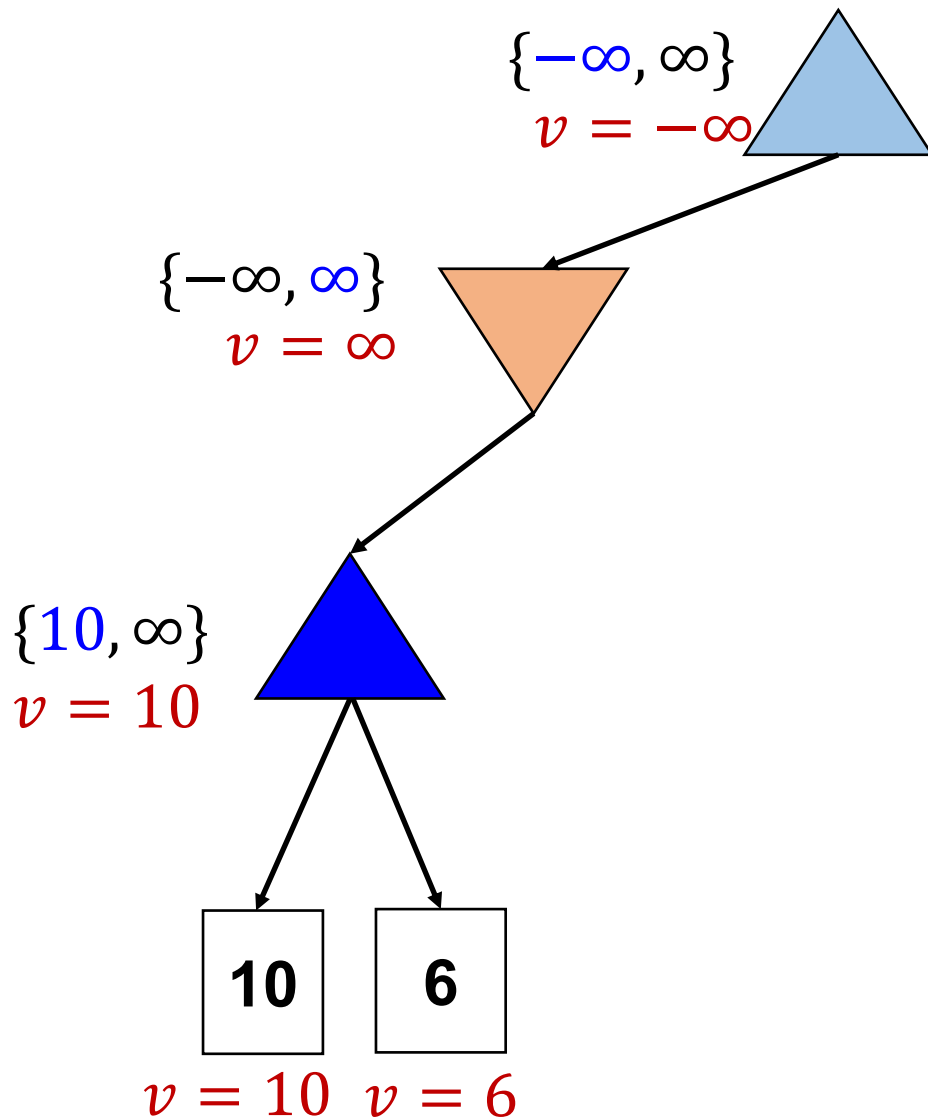
# $\alpha$ - $\beta$ 剪枝: 算法测试





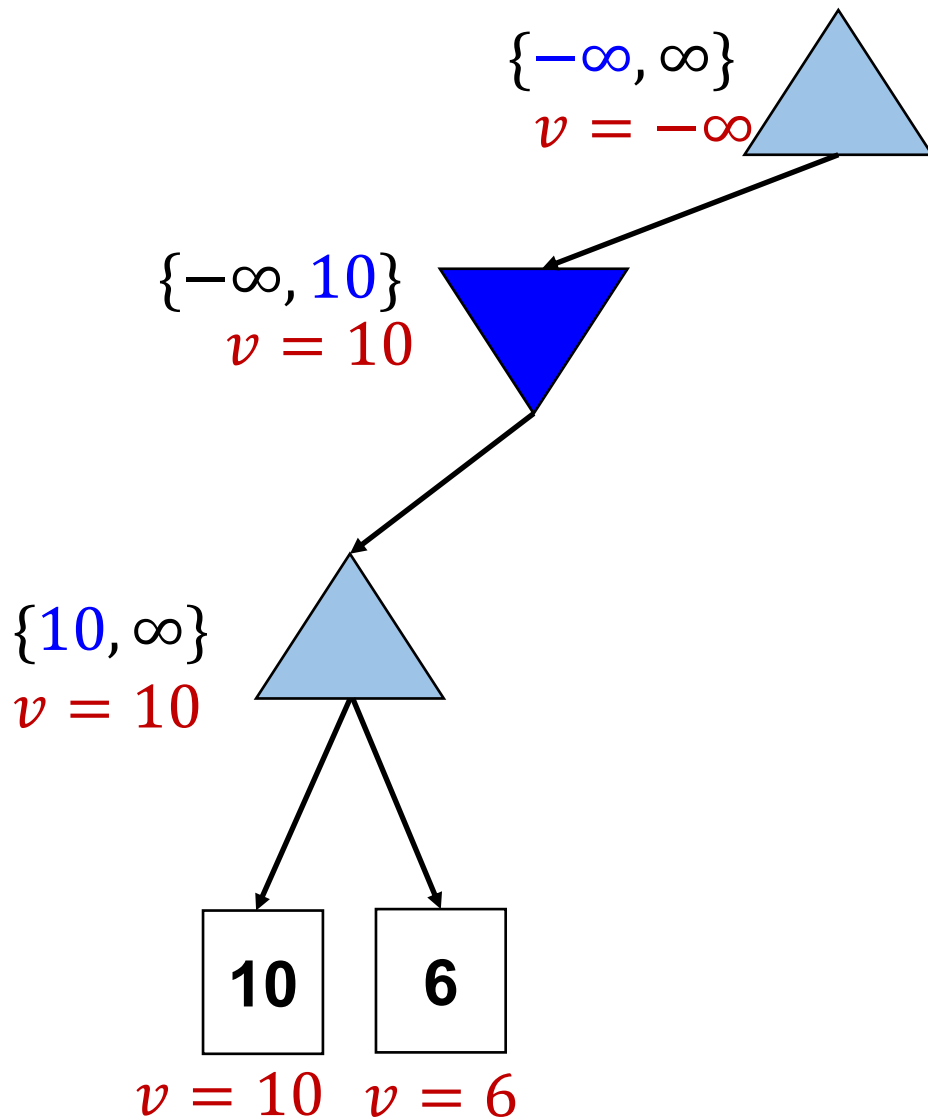


# $\alpha$ - $\beta$ 剪枝: 算法测试



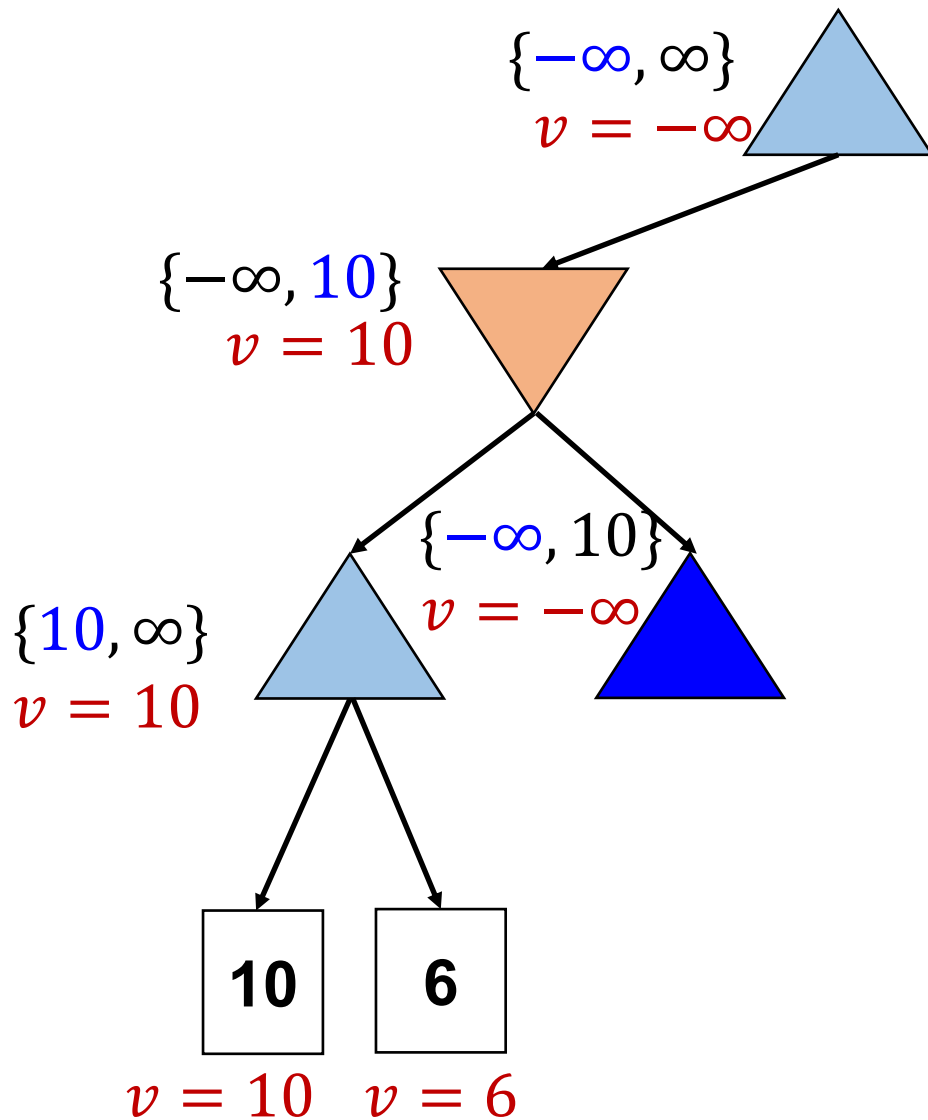


# $\alpha$ - $\beta$ 剪枝：算法测试



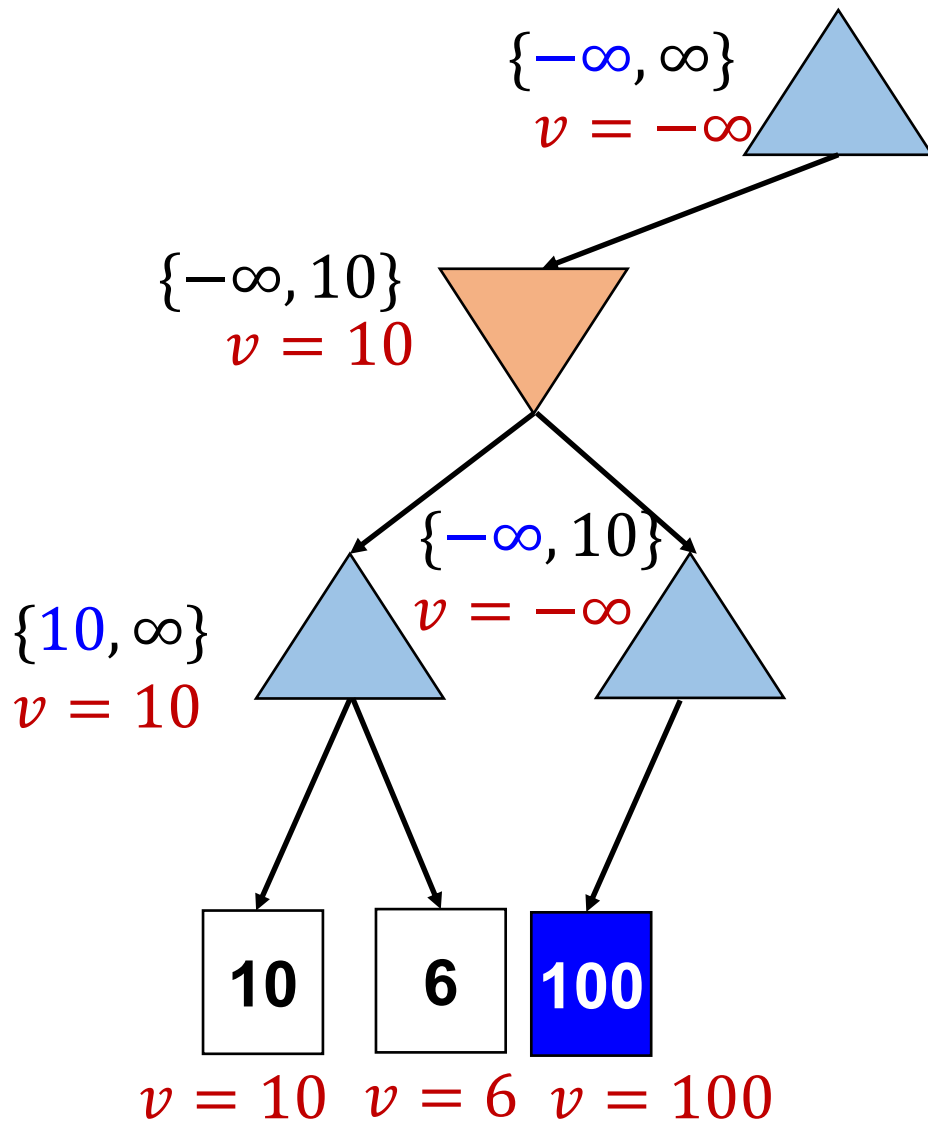


# $\alpha$ - $\beta$ 剪枝: 算法测试



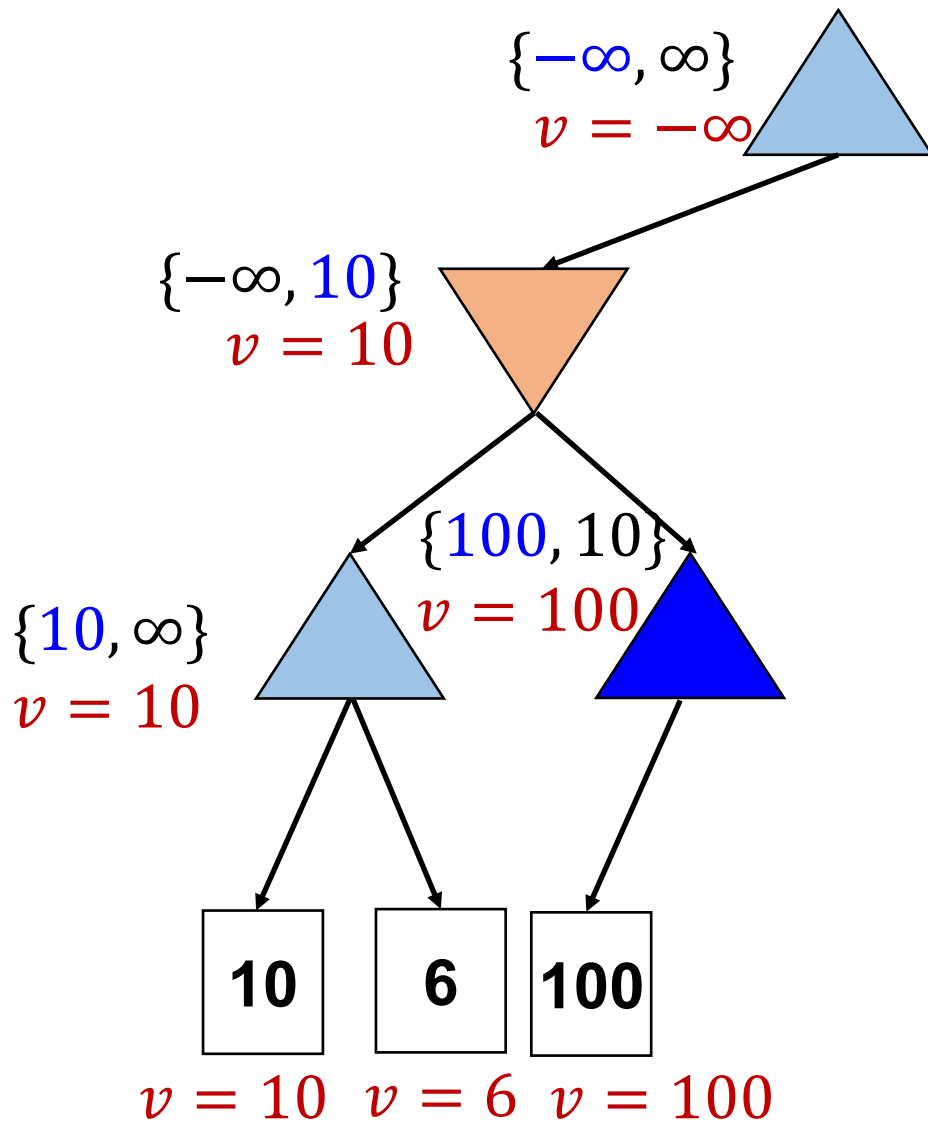


# $\alpha$ - $\beta$ 剪枝：算法测试



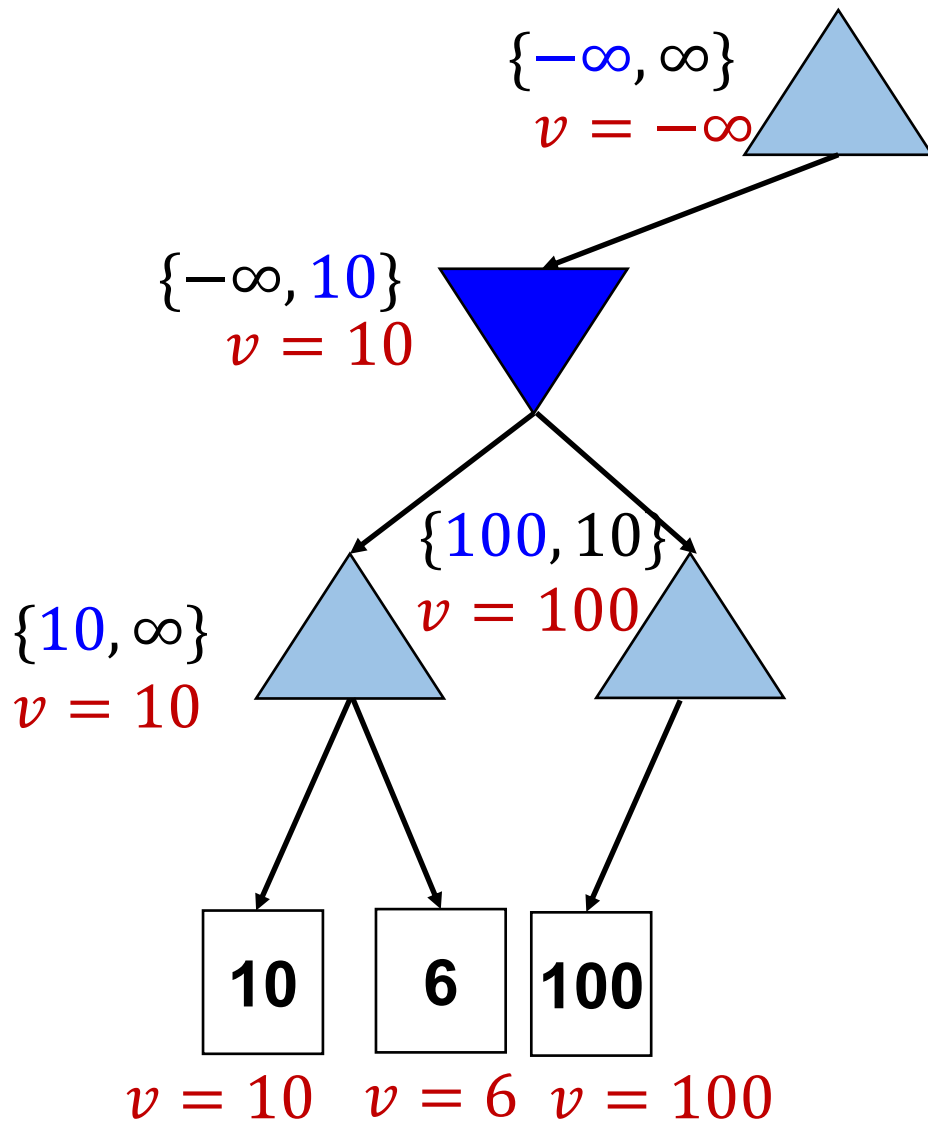


# $\alpha$ - $\beta$ 剪枝：算法测试



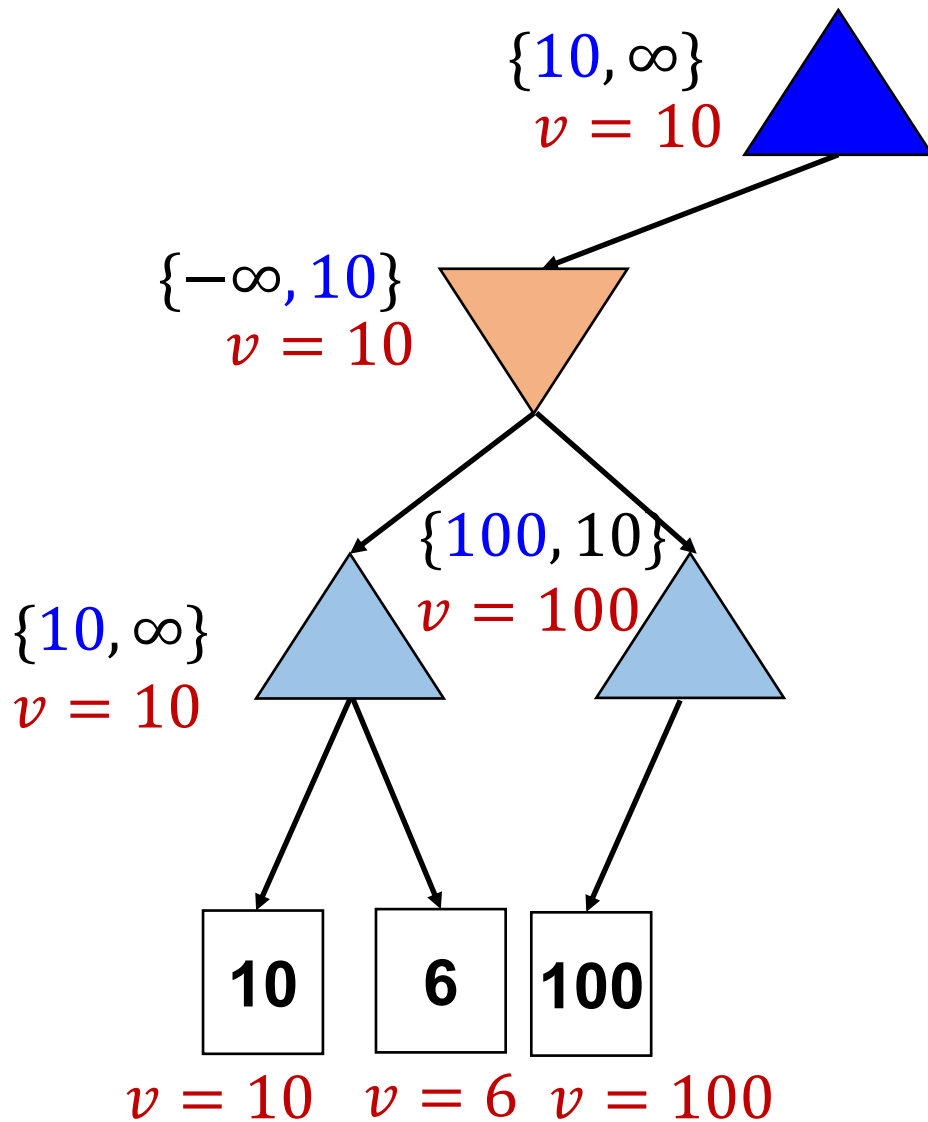


# $\alpha$ - $\beta$ 剪枝：算法测试



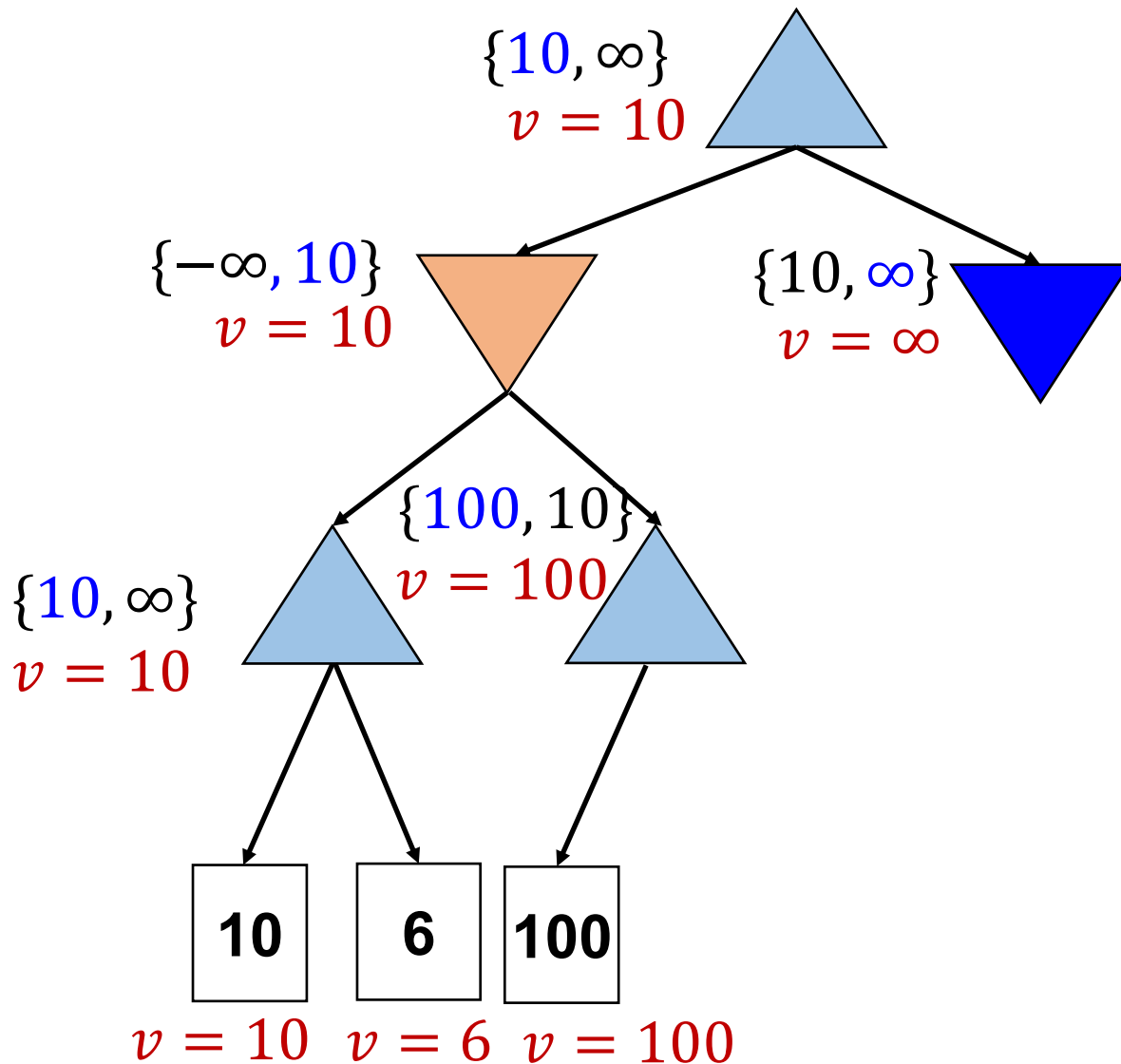


# $\alpha$ - $\beta$ 剪枝：算法测试





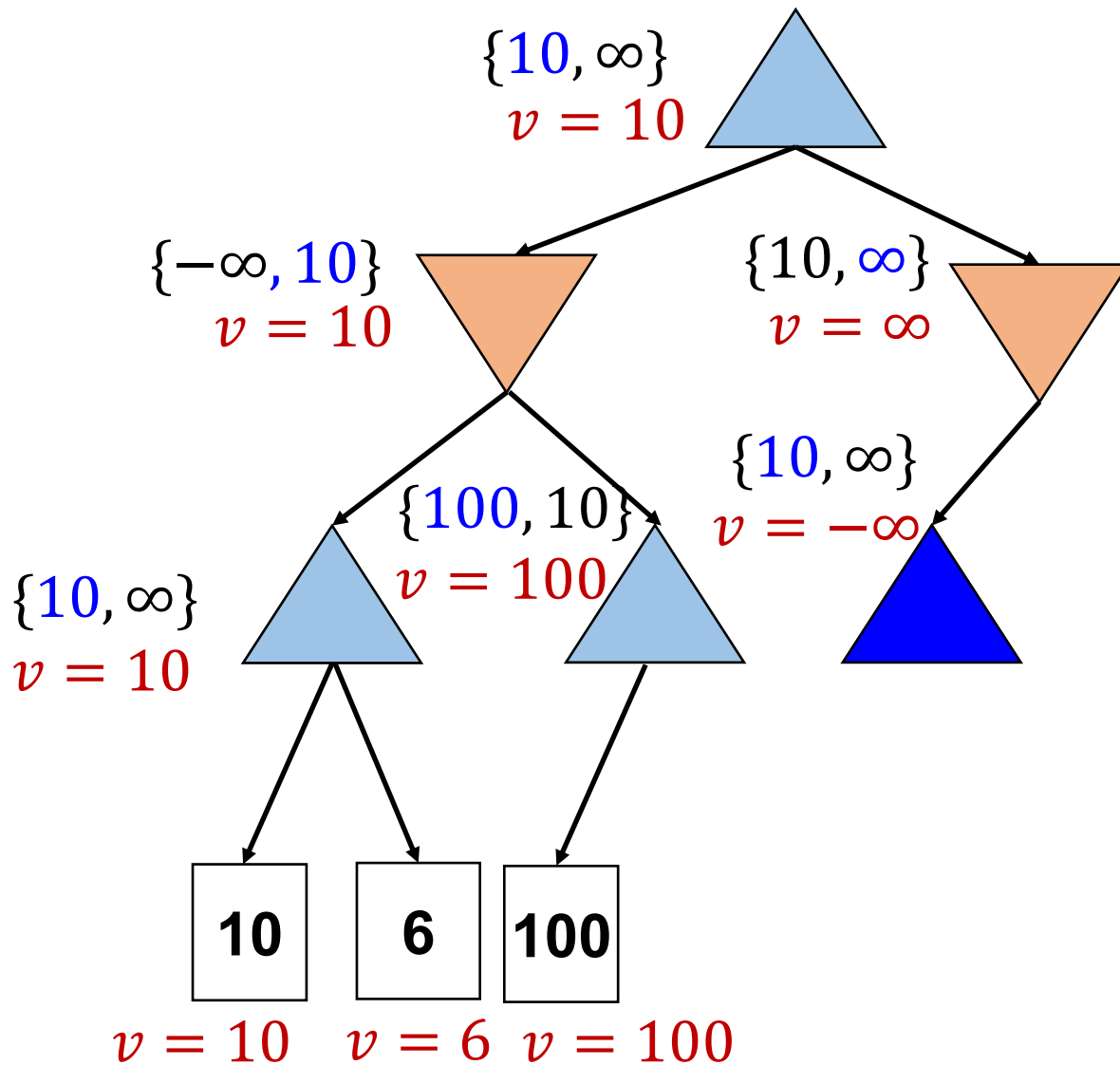
# $\alpha$ - $\beta$ 剪枝：算法测试





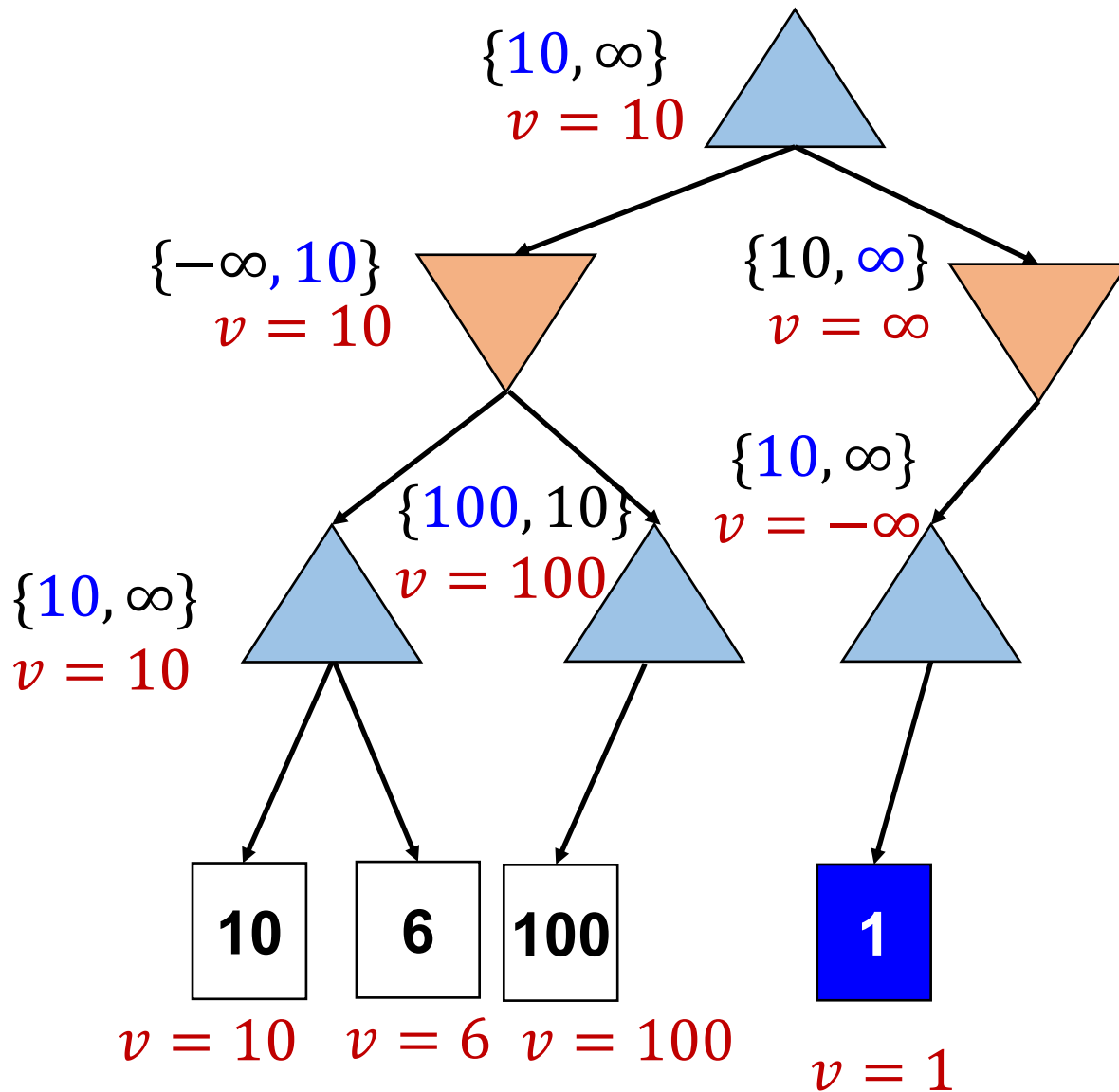


# $\alpha$ - $\beta$ 剪枝：算法测试



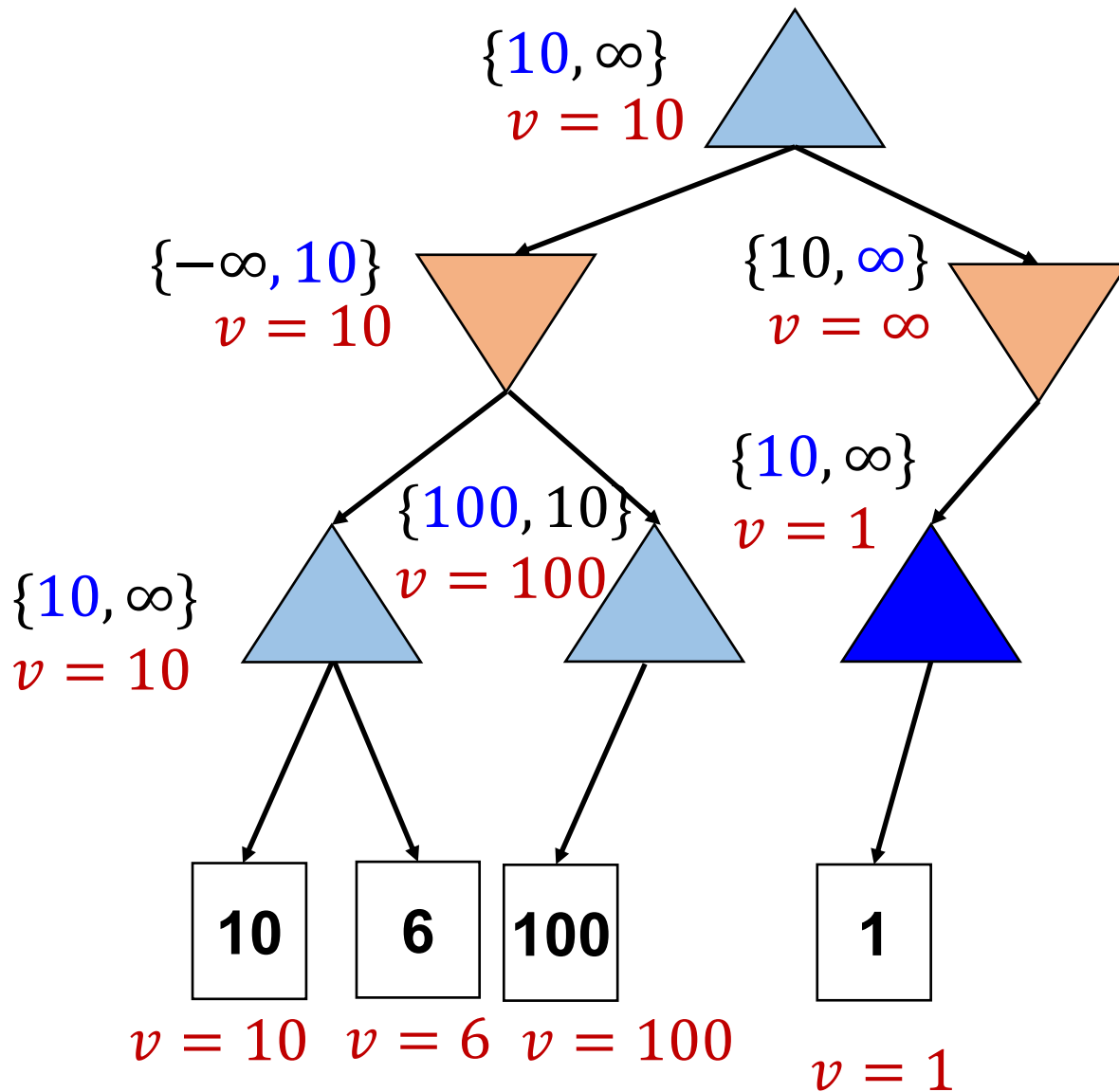


# $\alpha$ - $\beta$ 剪枝：算法测试



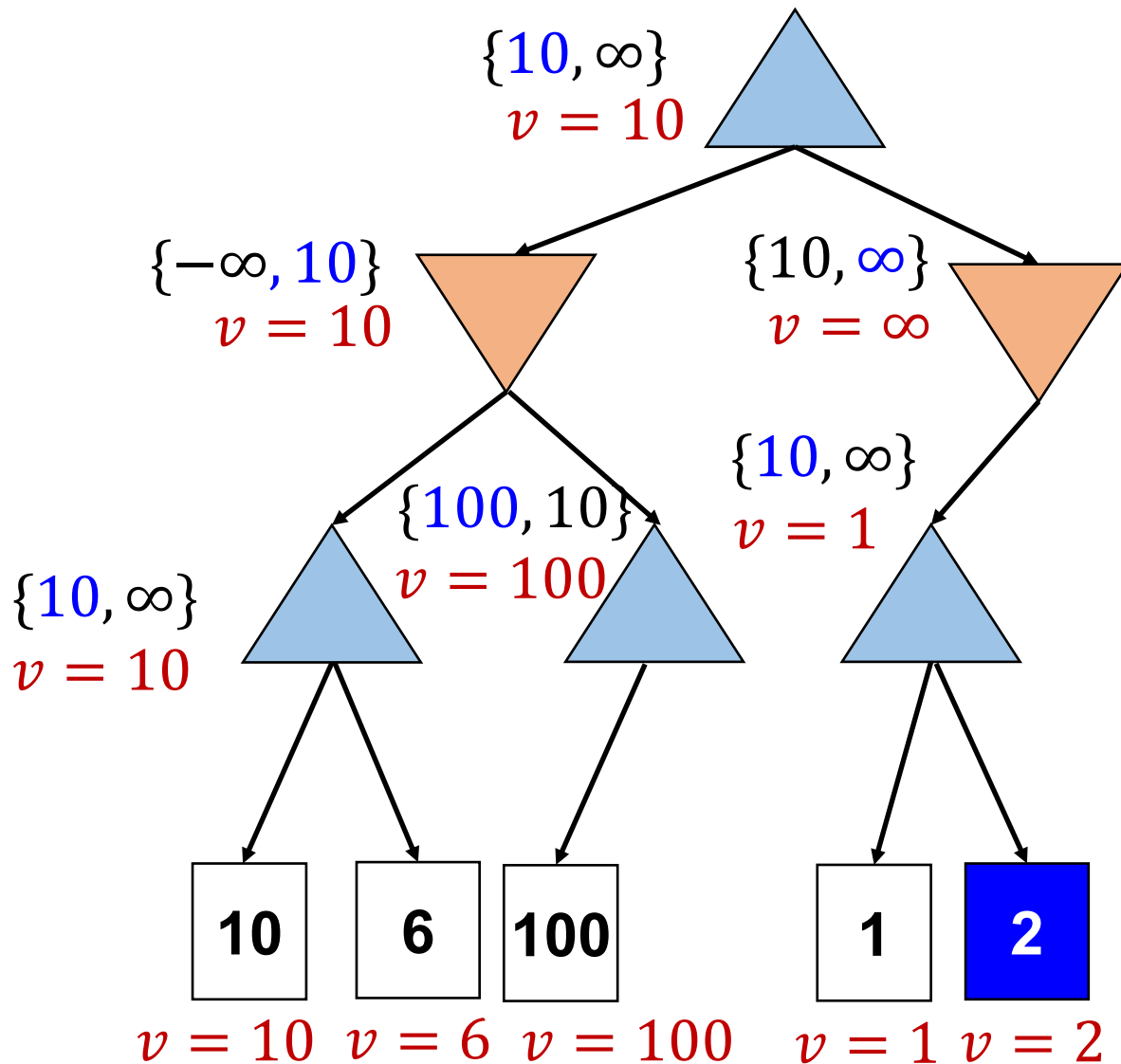


# $\alpha$ - $\beta$ 剪枝：算法测试



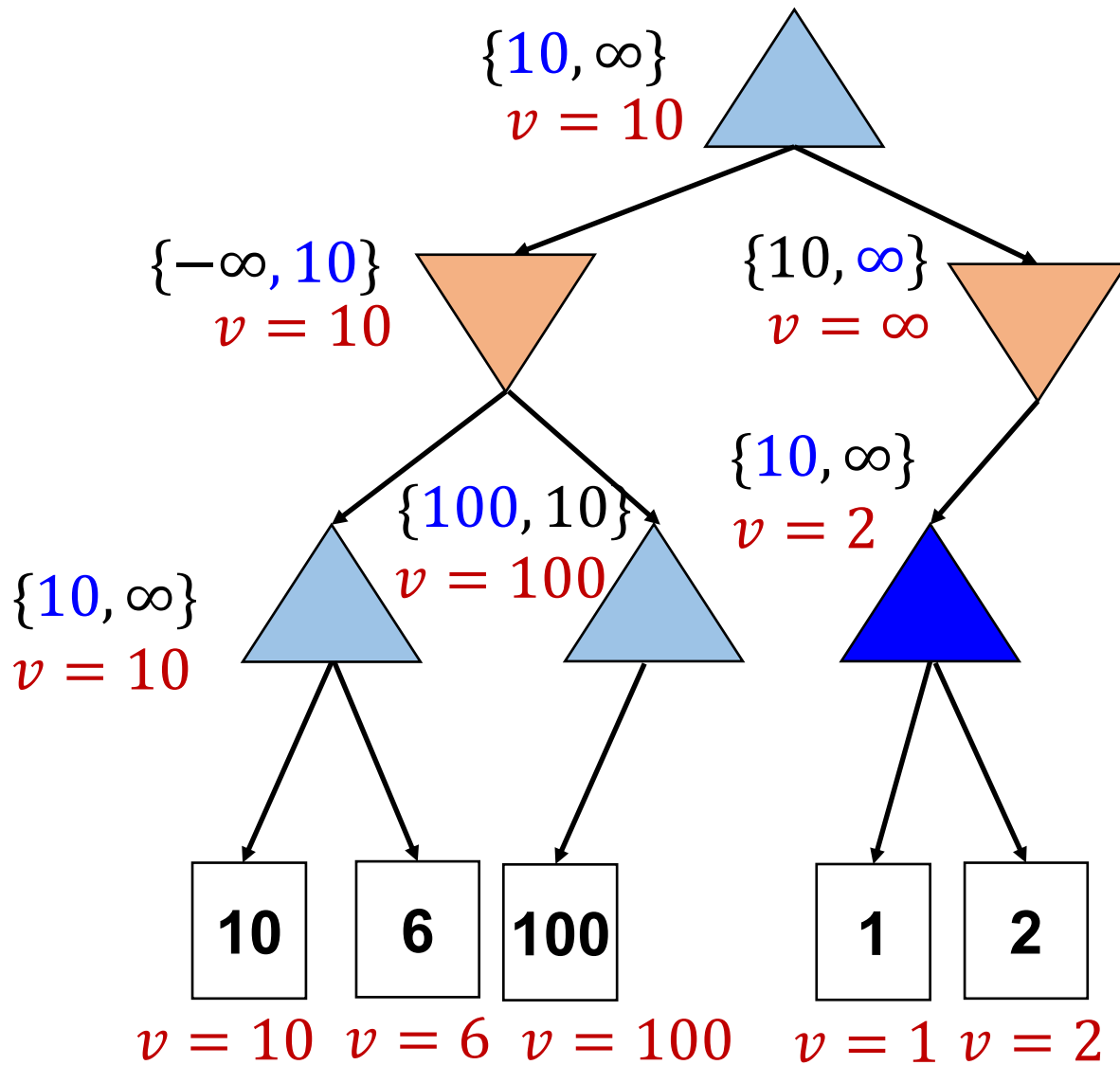


# $\alpha$ - $\beta$ 剪枝: 算法测试



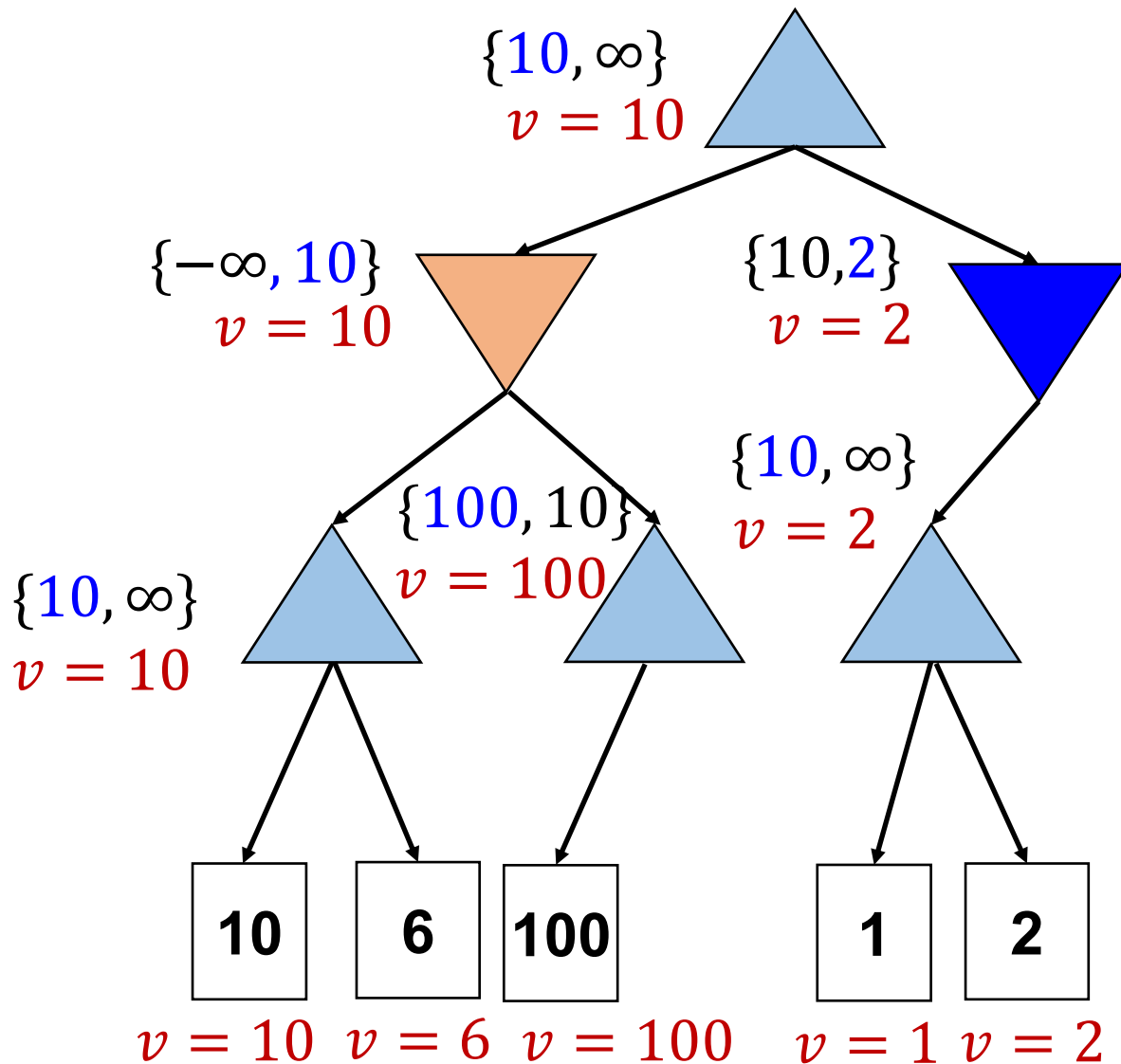


# $\alpha$ - $\beta$ 剪枝：算法测试



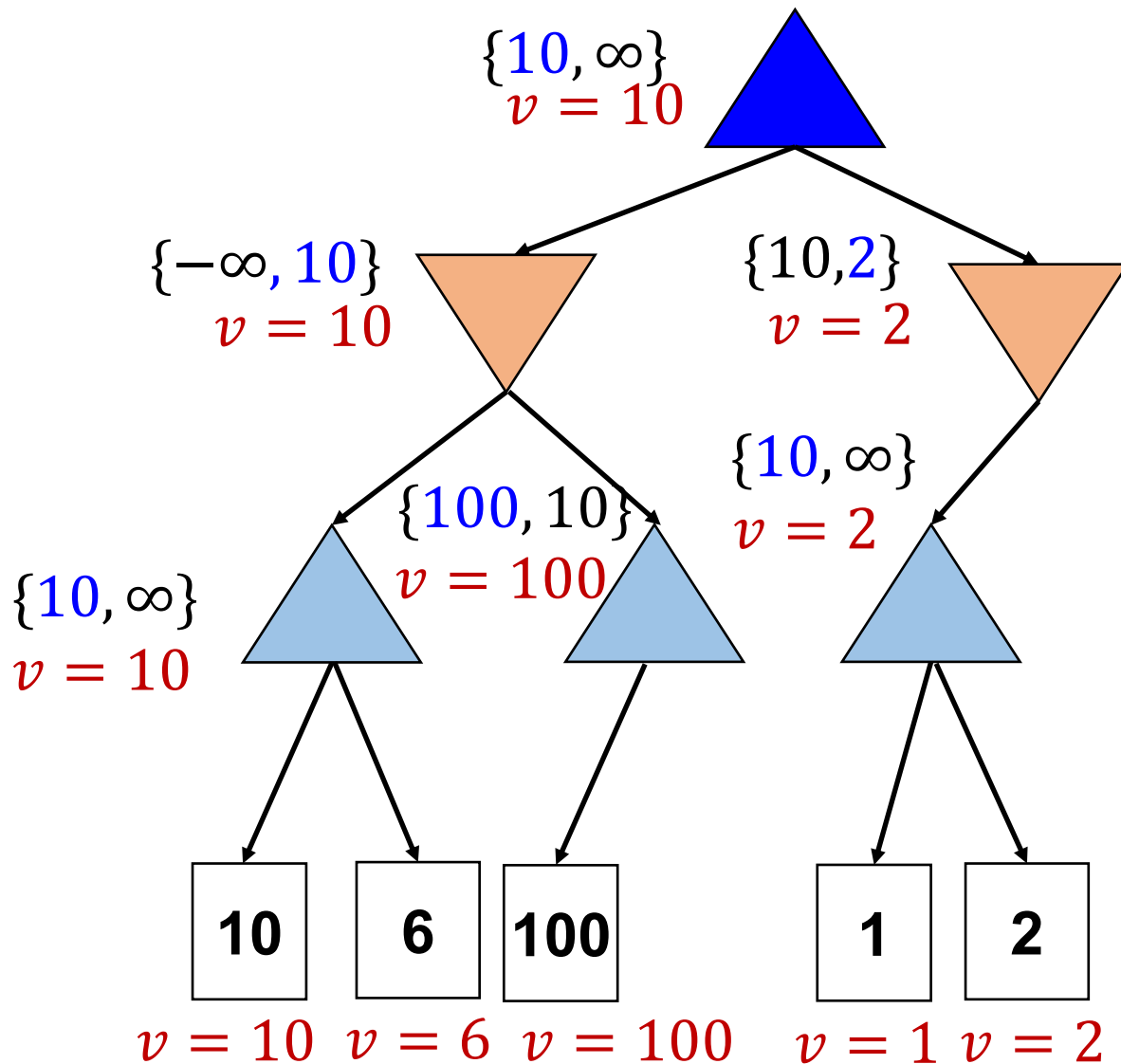


# $\alpha$ - $\beta$ 剪枝：算法测试



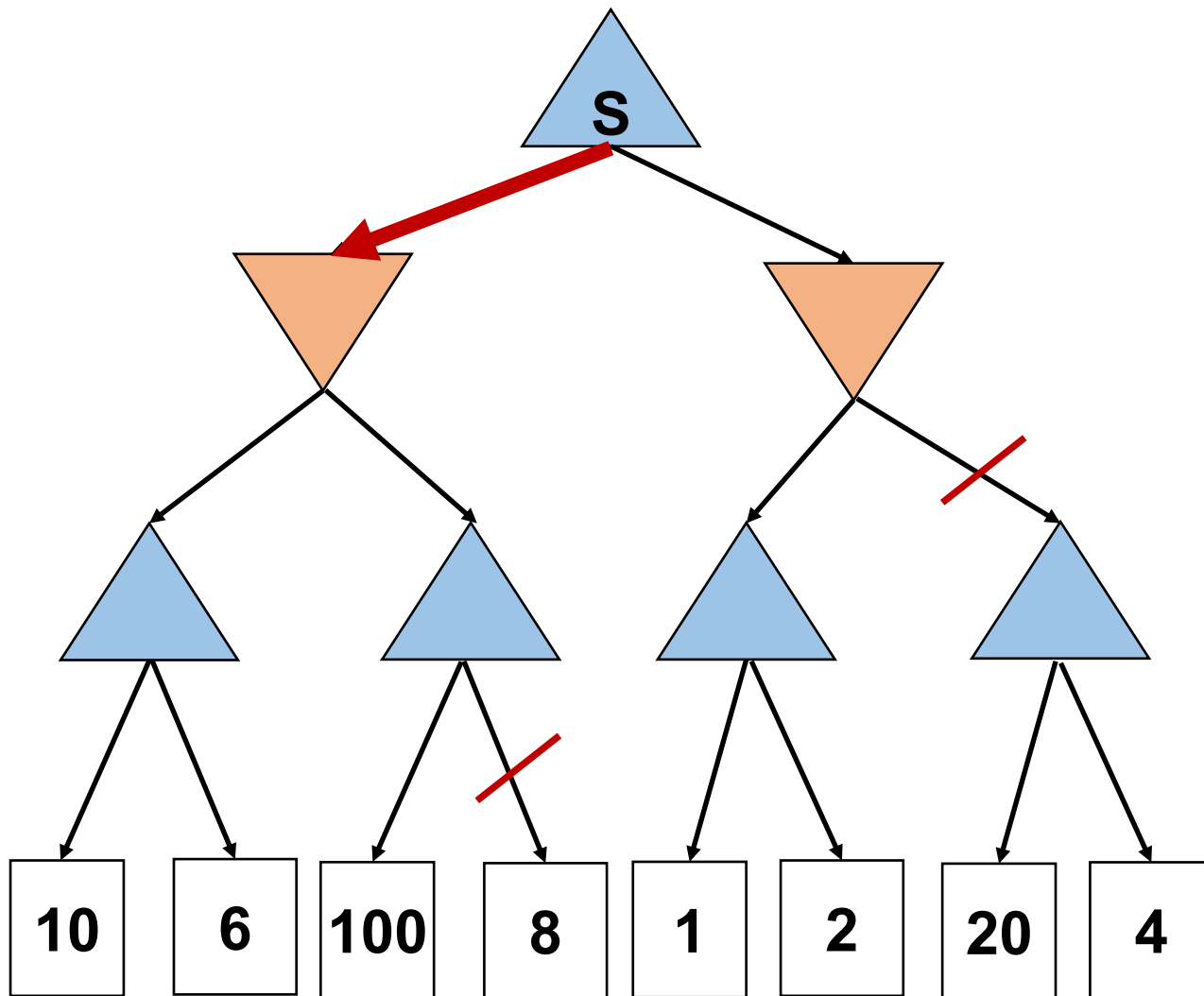


# $\alpha$ - $\beta$ 剪枝：算法测试





# $\alpha$ - $\beta$ 剪枝结果



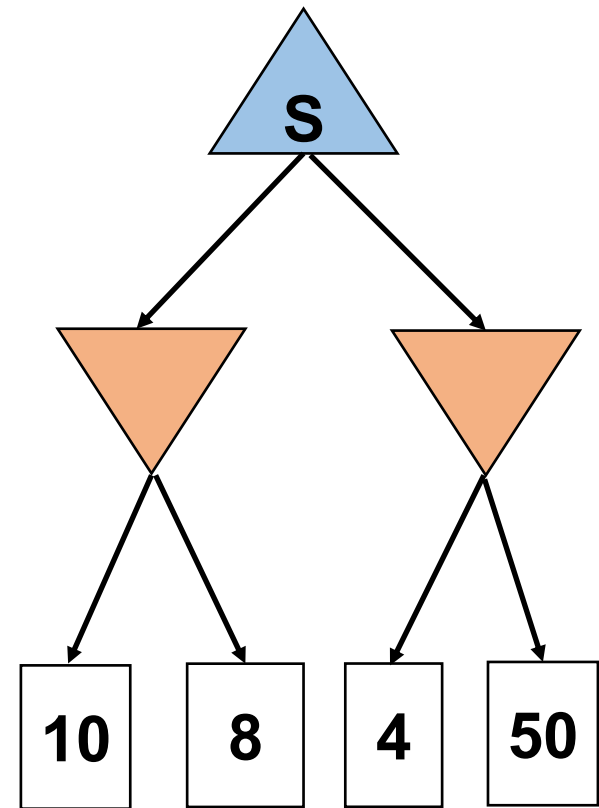




# $\alpha$ - $\beta$ 剪枝: 练习

```
function AlphaBeta(state,  $\alpha$ ,  $\beta$ )  
  If Terminal-Test(state) return Utility(state)  
  If player(state) = MAX {  
     $v = -\infty$   
    for each child {  
       $v = \max(v, \text{AlphaBeta}(\text{child}, \alpha, \beta))$   
       $\alpha = \max(\alpha, v)$   
      if  $\beta \leq \alpha$  then break // 裁剪 }  
  }  
  else {  
     $v = \infty$   
    for each child {  
       $v = \min(v, \text{AlphaBeta}(\text{child}, \alpha, \beta))$   
       $\beta = \min(\beta, v)$   
      if  $\beta \leq \alpha$  then break // 裁剪 }  
  }  
  return  $v$  //返回值
```

AlphaBeta(S,  $-\infty$ ,  $\infty$ )





# $\alpha$ - $\beta$ 剪枝的特点

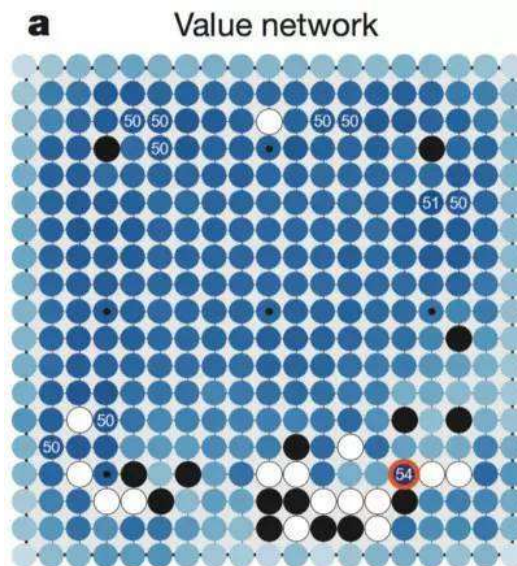
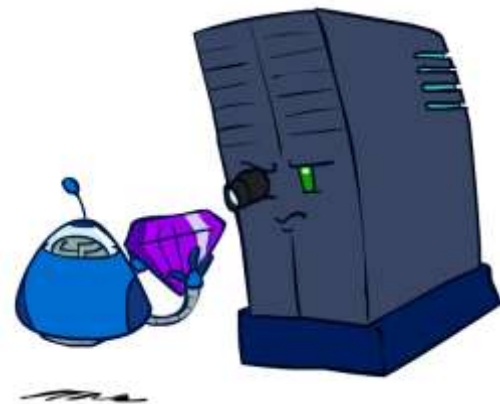
- ❑ 裁剪不影响根节点的MiniMax值，不影响决策的最优性
- ❑ 中间节点的MiniMax值可能不精确
- ❑ 剪枝效率和节点的访问顺序有关
  - 完美顺序下，时间复杂度  $O(b^{m/2})$  —  $\sqrt{b}$ 分支
  - 随机顺序下，时间复杂度  $O(b^{3m/4})$  —  $b^{3/4}$ 分支
- ❑ 对于困难问题，计算复杂度仍然过高





# 状态评估

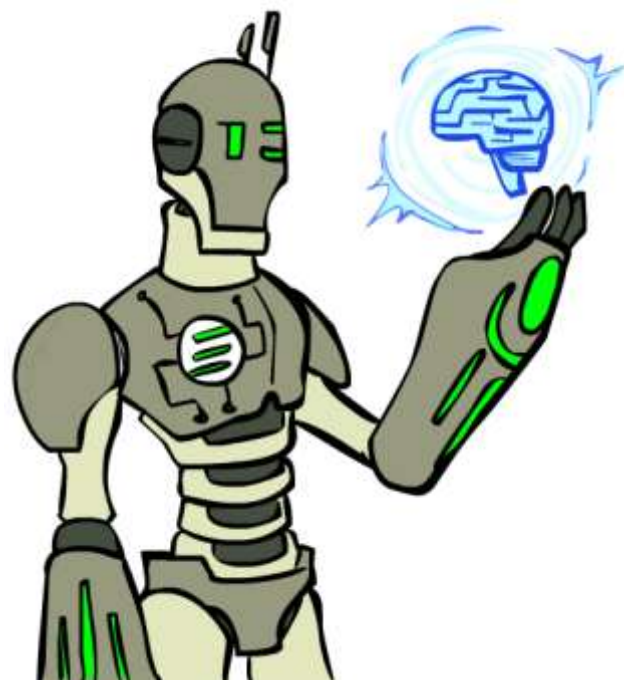
- 设计评估函数 (evaluation function) , 估计非终端节点的得分 (utilities)
- 理想: 得到实际的MiniMax值
- 现实: 估计每个状态的获胜概率
  - Alpha Go: 机器学习





# 本节课安排

- 博弈搜索问题  
Game Search Problem  
Adversarial Search Problem
- 极小极大搜索  
Minimax Search
- $\alpha$ - $\beta$  剪枝
- 练习





- 
- ```

graph TD
    Root[ ] --- L1L[ ]
    Root --- L1R[ ]
    L1L --- L2L1[ ]
    L1L --- L2L2[ ]
    L1R --- L2R1[ ]
    L1R --- L2R2[ ]
    L2L1 --- L3L11[3]
    L2L1 --- L3L12[11]
    L2L2 --- L3L21[2]
    L2L2 --- L3L22[13]
    L2L2 --- L3L23[7]
    L2L2 --- L3L24[8]
    L2L2 --- L3L25[6]
    L2R1 --- L3R11[0]
    L2R1 --- L3R12[4]
    L2R1 --- L3R13[5]
    L2R2 --- L3R21[1]
    L2R2 --- L3R22[15]
  
```



# 练习：答案

1. 考虑下图所示的零和博弈树，假设博弈树都是从MAX层出发，MAX-MIN层交替进行。如果采用 $\alpha - \beta$ 剪枝操作，请在需要剪除的分支上打 $\times$ （本小题共6分）。

