

Chapter 12

Bayesian Classifier



Chapter List

- Bayes Decision Theory
- Maximum Likelihood Estimation
- Naïve Bayes Classifier
- EM Algorithm

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- **Bayes Decision Theory**
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Bayes Decision Theory

- Bayesian decision theory is a fundamental decision-making approach under the probability framework.
 - When all relevant probabilities were known, Bayesian decision theory makes optimal classification decisions based on the probabilities and costs of misclassifications.

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- Bayesian decision theory is a fundamental decision-making approach under the probability framework.
 - When all relevant probabilities were known, Bayesian decision theory makes optimal classification decisions based on the probabilities and costs of misclassifications.
- Let us assume that there are N distinct class labels, that is, $y = \{c_1, c_2, \dots, c_N\}$. Let λ_{ij} denote the cost of misclassifying a sample of class c_j as class c_i . Then, with the posterior probability $P(c_i | x)$ we can calculate the expected loss of classifying a sample x as class c_i , that is, the conditional risk of the sample x :

$$R(c_i | x) = \sum_{j=1}^N \lambda_{ij} P(c_j | x) \quad (7.1)$$

- Our task is to find a decision rule $h : X \mapsto Y$ that minimizes the overall risk:

$$R(h) = \mathbf{E}_x [R(h(x) | x)] \quad (7.2)$$

Bayes Decision Theory

- The overall risk $R(h)$ is minimized when the conditional risk $R(h(\mathbf{x}) \mid \mathbf{x})$ of each sample \mathbf{x} is minimized.

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- The overall risk $R(h)$ is minimized when the conditional risk $R(h(\mathbf{x}) \mid \mathbf{x})$ of each sample \mathbf{x} is minimized.
- This leads to the Bayes decision rule: to minimize the overall risk, classify each sample as the class that minimizes the conditional risk $R(c \mid \mathbf{x})$

$$h^*(\mathbf{x}) = \operatorname{argmin}_{c \in \mathcal{Y}} R(c \mid \mathbf{x})$$

- where h^* is called the **Bayes optimal classifier**, and its associated overall risk $R(h^*)$ is called the Bayes risk.
- $1 - R(h^*)$ is the best performance that can be achieved by any classifiers, that is, the theoretically achievable upper bound of accuracy for any machine learning models.

Bayes Decision Theory

- To be specific, if the objective is to minimize the misclassification rate, then the misclassification loss λ_{ij} can be written as

$$\lambda_{i,j} = \begin{cases} 0, & \text{if } i = j; \\ 1, & \text{otherwise,} \end{cases}$$

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- Then, the **Bayes optimal classifier** that minimizes the misclassification rate is

$$h^*(x) = \operatorname{argmax}_{c \in \mathcal{Y}} P(c \mid x)$$

- which classifies each sample \mathbf{x} as the class that maximizes its posterior probability $P(c \mid \mathbf{x})$.

Bayes Decision Theory

- We can see that the Bayes decision rule relies on the **posterior probability** $P(c | \mathbf{x})$.
- However, it's often difficult to obtain in practice. The task of machine learning is then to accurately estimate the posterior probability $P(c | \mathbf{x})$ from the training samples.
- Generally speaking, there are two strategies :
 - discriminative models
 - Given \mathbf{X} , predict C by estimating $P(c | \mathbf{x})$ directly.
 - Decision trees, BP neural networks and support vector machines.
 - generative models
 - estimate the joint probability $P(\mathbf{x}, c)$ first and then estimate $P(c | \mathbf{x})$
 - For generative models, we must evaluate:

$$P(c | \mathbf{x}) = \frac{P(\mathbf{x}, c)}{P(\mathbf{x})}$$

Bayes Decision Theory

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the class-conditional probability, also known as the likelihood, of the sample \mathbf{x} with respect to class c

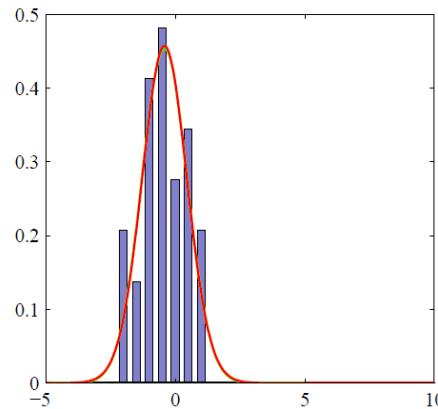
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Maximum Likelihood Estimation

- A general strategy of estimating the class-conditional probability is to hypothesize a fixed form of probability distribution, and then estimate the distribution parameters using the training samples.



- let $P(x | c)$ denote class-condition probability of class c ,
 - suppose $P(x | c)$ has a fixed form determined by a parameter vector θ_c . Then, the task is to estimate θ_c from a training set D .

Maximum Likelihood Estimation

- The training process of probabilistic models is the process of parameter estimation. There are two different ways of thinking about parameters:
 - **(The Frequentist school)** Parameters have unknown but fixed values, and hence they can be determined by some approaches such as optimizing the likelihood function.
 - **(The Bayesian school)** Parameters are unobserved random variables following some distribution, and hence we can assume prior distributions for the parameters and estimate posterior distribution from observed data.

Maximum Likelihood Estimation

- Let D_c denote the set of class c samples in the training set D , and further suppose the samples are *i.i.d.* samples. Then, the likelihood of D_c for a given parameter θ_c is:

$$P(D_c | \theta_c) = \prod_{x \in D_c} P(x | \theta_c)$$

- Applying the MLE to θ_c is about finding a parameter value $\hat{\theta}_c$ that maximizes the likelihood $P(D_c | \theta_c)$. Intuitively, the MLE aims to find a value of θ_c that maximizes the “*likelihood*” that the data will present.

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- Applying the MLE to θ_c is about finding a parameter value $\hat{\theta}_c$ that maximizes the likelihood $P(D_c | \theta_c)$. Intuitively, the MLE aims to find a value of θ_c that maximizes the “likelihood” that the data will present.
- Since the product of a sequence can lead to underflow, we often use the log-likelihood instead:

$$\begin{aligned} LL(\theta_c) &= \log P(D_c | \theta_c) \\ &= \sum_{\mathbf{x} \in D_c} \log P(\mathbf{x} | \theta_c) \end{aligned}$$

- and the MLE of θ_c is $\hat{\theta}_c$:

$$\hat{\theta}_c = \operatorname{argmax}_{\theta_c} LL(\theta_c)$$

Maximum Likelihood Estimation

- For example, suppose the features are continuous and the probability density function follows the Gaussian distribution $p(\mathbf{x} | c) \sim N(\mu_c, \sigma_c^2)$, then the MLE of the parameters μ_c and σ_c^2 are

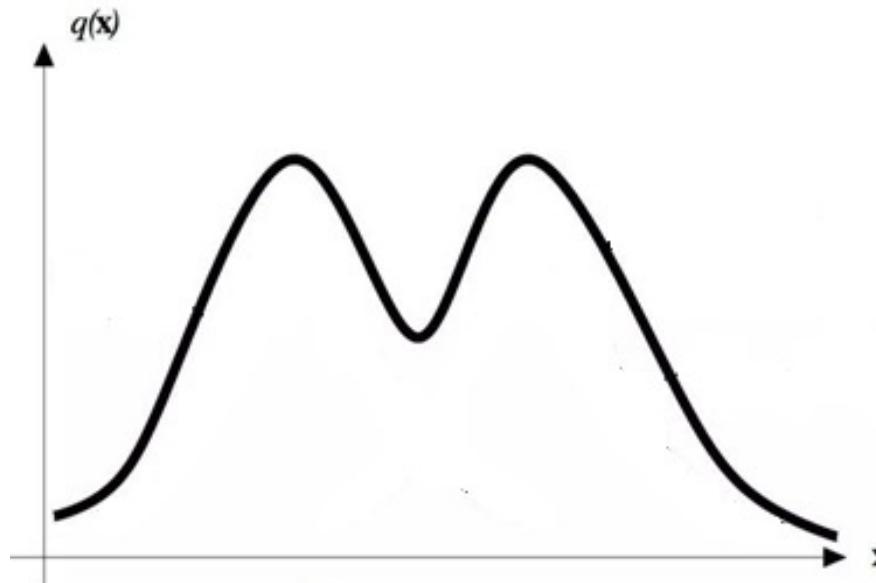
$$\hat{\mu}_c = \frac{1}{|D_c|} \sum_{\mathbf{x} \in D_c} \mathbf{x}$$

$$\hat{\sigma}_c^2 = \frac{1}{|D_c|} \sum_{\mathbf{x} \in D_c} (\mathbf{x} - \hat{\mu}_c)(\mathbf{x} - \hat{\mu}_c)^T$$

- In other words, the estimated mean of Gaussian distribution obtained by the MLE is the sample mean, and the estimated variance is the mean of $(\mathbf{x} - \hat{\mu}_c)(\mathbf{x} - \hat{\mu}_c)^T$.

Maximum Likelihood Estimation

- Such kind of parametric methods simplify the estimation of posterior probabilities, but the accuracy of estimation heavily relies on whether the hypothetical probability distribution matches the unknown ground-truth data distribution. In practice, a “guessed” probability distribution could incur misleading results.



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Naïve Bayes Classifier

- The difficulty of estimating the **posterior probability** $P(c | \mathbf{x})$: it is not easy to calculate the **class-conditional probability** $P(\mathbf{x} | c)$ from the training samples since $P(\mathbf{x} | c)$ is the joint probability on all attributes.
 - For example, d binary attributes $\rightarrow 2^d$ possible values,
 $2^d >>$ the number of samples
- To avoid this, the Naïve Bayes classifier makes the “**attribute conditional independence assumption**”: for any class, assume all attributes are independent of each other.
- With the independence assumption, we have:

$$P(c | \mathbf{x}) = \frac{P(c)P(\mathbf{x} | c)}{P(\mathbf{x})} = \frac{P(c)}{P(\mathbf{x})} \prod_{i=1}^d P(x_i | c)$$

where d is the number of attributes.

Naïve Bayes Classifier

$$P(c \mid \mathbf{x}) = \frac{P(c)P(\mathbf{x} \mid c)}{P(\mathbf{x})} = \frac{P(c)}{P(\mathbf{x})} \prod_{i=1}^d P(x_i \mid c)$$

Naïve Bayes Classifier

$$P(c \mid \mathbf{x}) = \frac{P(c)P(\mathbf{x} \mid c)}{P(\mathbf{x})} = \frac{P(c)}{P(\mathbf{x})} \prod_{i=1}^d P(x_i \mid c)$$

Since $P(x)$ is the same for all classes, from the Bayes decision rule, we have

$$h_{nb}(\mathbf{x}) = \operatorname{argmax}_{c \in \mathcal{Y}} P(c) \prod_{i=1}^d P(x_i \mid c)$$

which is the formulation of the Naïve Bayes classifier.

Naïve Bayes Classifier

- To train a Naïve Bayes classifier, we compute the **prior probability** $P(c)$ from the training set D and then compute the **conditional probability** $P(x_i | c)$ for each attribute.
- Let D_c denote a subset of D containing all samples of class c . Then, The prior probability can be estimated by

$$P(c) = \frac{|D_c|}{|D|}$$

- For discrete attributes, let D_{c,x_i} denote a subset of D_c containing all samples taking the value x_i on the i -th attribute. Then, the conditional probability $P(x_i | c)$ can be estimated by
- For continuous features, suppose $p(x_i | c) \sim N(\mu_{c,i}, \sigma_{c,i}^2)$, where $\mu_{c,i}$ and $\sigma_{c,i}^2$ are, respectively, the mean and variance of the i -th feature of class c . Then, we have

$$P(x_i | c) = \frac{1}{\sqrt{2\pi}\sigma_{c,i}} \exp\left(-\frac{(x_i - \mu_{c,i})^2}{2\sigma_{c,i}^2}\right)$$

Laplace (add-1) Smoothing

- If a feature value has never appeared together with a particular class, it becomes problematic to use the probability.
- For example, given a testing sample with *sound = crisp*, the Naïve Bayes classifier trained on the watermelon data set will predict 0. The classification result will always be *ripe = false* regardless of the values of other features.

$$P_{crisp|true} = \frac{0}{8} = 0$$

ID	color	root	sound	texture	umbilicus	surface	ripe
1	green	curly	muffled	clear	hollow	hard	true
2	dark	curly	dull	clear	hollow	hard	true
3	dark	curly	muffled	clear	hollow	hard	true
4	green	curly	dull	clear	hollow	hard	true
5	light	curly	muffled	clear	hollow	hard	true
6	green	slightly curly	muffled	clear	slightly hollow	soft	true
7	dark	slightly curly	muffled	slightly blurry	slightly hollow	soft	true
8	dark	slightly curly	muffled	clear	slightly hollow	hard	true
9	dark	slightly curly	dull	slightly blurry	slightly hollow	hard	false
10	green	straight	crisp	clear	flat	soft	false
11	light	straight	crisp	blurry	flat	hard	false
12	light	curly	muffled	blurry	flat	soft	false
13	green	slightly curly	muffled	slightly blurry	hollow	hard	false
14	light	slightly curly	dull	slightly blurry	hollow	hard	false
15	dark	slightly curly	muffled	clear	slightly hollow	soft	false
16	light	curly	muffled	blurry	flat	hard	false
17	green	curly	dull	slightly blurry	slightly hollow	hard	false

Laplace (add-1) Smoothing

- To avoid “removing” the information carried by other features, a common choice is the Laplace smoothing.
- Let N denote the number of distinct classes in the training set D , N_i denote the number of distinct values the i -th feature can take. Then, we write smoothed version of prior probability and conditional probability as:

$$\hat{P}(c) = \frac{|D_c| + 1}{|D| + N} ,$$

Why?

$$\hat{P}(x_i | c) = \frac{|D_{c,x_i}| + 1}{|D_c| + N_i}$$

Text Classification

The Bag of Words Representation

I love this movie! It's sweet, but with satirical humor. The dialogue is great and the adventure scenes are fun... It manages to be whimsical and romantic while laughing at the conventions of the fairy tale genre. I would recommend it to just about anyone. I've seen it several times, and I'm always happy to see it again whenever I have a friend who hasn't seen it yet!



it	6
I	5
the	4
to	3
and	3
seen	2
yet	1
would	1
whimsical	1
times	1
sweet	1
satirical	1
adventure	1
genre	1
fairy	1
humor	1
have	1
great	1
...	...

Multinomial Distribution

Suppose one does an experiment of extracting n balls of k different colors from a bag, replacing the extracted balls after each draw. Balls of the same color are equivalent. Denote the variable which is the number of extracted balls of color i ($i = 1, \dots, k$) as X_i , and denote as p_i the probability that a given extraction will be in color i .

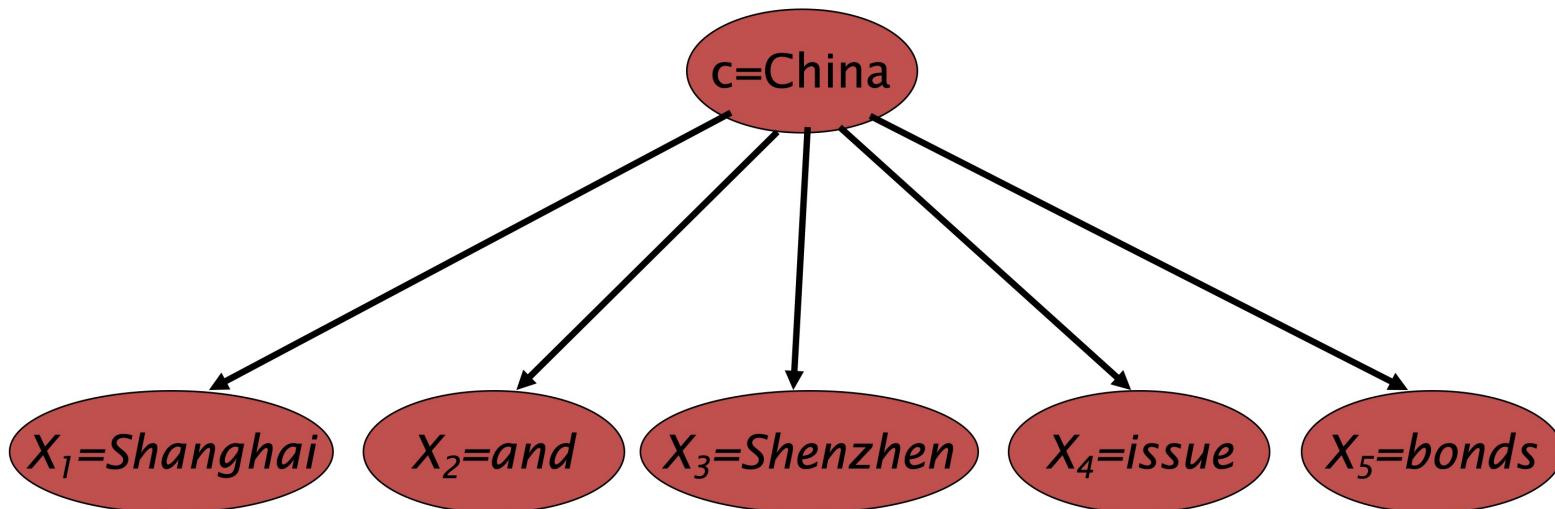
The **probability mass function** of this multinomial distribution is:

$$f(x_1, \dots, x_k; n, p_1, \dots, p_k) = \Pr(X_1 = x_1 \text{ and } \dots \text{ and } X_k = x_k)$$
$$= \begin{cases} \frac{n!}{x_1! \cdots x_k!} p_1^{x_1} \times \cdots \times p_k^{x_k}, & \text{when } \sum_{i=1}^k x_i = n \\ 0 & \text{otherwise,} \end{cases}$$

for non-negative integers x_1, \dots, x_k .

Generative Model for Naive Bayes

$$P(x_i | c)$$



Text Classification

Consider a naive Bayes model with the classes positive (+) and negative (-) and the following model parameters:

w	P(w +)	P(w -)
I	0.1	0.2
love	0.1	0.001
this	0.01	0.01
fun	0.05	0.005
film	0.1	0.1
...

$$P(\text{"I love this fun film"}|+) = 0.1 \times 0.1 \times 0.01 \times 0.05 \times 0.1 = 0.0000005$$

$$P(\text{"I love this fun film"}|-) = 0.2 \times 0.001 \times 0.01 \times 0.005 \times 0.1 = .0000000010$$

Note that this is just the likelihood part of the naive Bayes model.

Text Classification

To apply the naive Bayes classifier to text, we need to consider word positions, by simply walking an index through every word position in the document:

positions \leftarrow all word positions in test document

$$c_{NB} = \operatorname{argmax}_{c \in C} P(c) \prod_{i \in \text{positions}} P(w_i | c)$$

Naive Bayes calculations are done in log space, to avoid underflow and increase speed

$$c_{NB} = \operatorname{argmax}_{c \in C} \log P(c) + \sum_{i \in \text{positions}} \log P(w_i | c)$$

Naive Bayes is a **linear classifiers**.

Training the Naive Bayes Classifier

Let N_c be the number of documents in our training data with class c and N_{doc} be the total number of documents. Then:

$$\hat{P}(c) = \frac{N_c}{N_{doc}}$$

$$\hat{P}(w_i|c) = \frac{\text{count}(w_i, c)}{\sum_{w \in V} \text{count}(w, c)}$$

$$\hat{P}(w_i|c) = \frac{\text{count}(w_i, c) + 1}{\sum_{w \in V} (\text{count}(w, c) + 1)} = \frac{\text{count}(w_i, c) + 1}{(\sum_{w \in V} \text{count}(w, c)) + |V|}$$

Text Classification

	Doc	Words	Class
Training	1	Chinese Beijing Chinese	c
	2	Chinese Chinese Shanghai	c
	3	Chinese Macao	c
	4	Tokyo Japan Chinese	j
Test	5	Chinese Chinese Chinese Tokyo Japan	?

Priors:

$$P(c) = ?$$

$$P(j) = ?$$

Conditional Probabilities:

$$P(\text{Chinese}|c) = ?$$

$$P(\text{Tokyo}|c) = ?$$

$$P(\text{Japan}|c) = ?$$

$$P(\text{Chinese}|j) = ?$$

$$P(\text{Tokyo}|j) = ?$$

$$P(\text{Japan}|j) = ?$$

Choosing a class:

$$P(c|d5) = ?$$

$$P(j|d5) = ?$$

$$\hat{P}(w|c) = \frac{\text{count}(w,c)+1}{\text{count}(c)+|V|}$$

Text Classification

Priors:

$$P(c) = \frac{3 + 1}{4 + 2} = \frac{2}{3}$$

$$P(j) = \frac{1 + 1}{4 + 2} = \frac{1}{3}$$

Text Classification

Conditional Probabilities:

$$P(\text{Chinese}|c) = (5+1) / (8+6) = 6/14 = 3/7$$

$$P(\text{Tokyo}|c) = (0+1) / (8+6) = 1/14$$

$$P(\text{Japan}|c) = (0+1) / (8+6) = 1/14$$

$$P(\text{Chinese}|j) = (1+1) / (3+6) = 2/9$$

$$P(\text{Tokyo}|j) = (1+1) / (3+6) = 2/9$$

$$P(\text{Japan}|j) = (1+1) / (3+6) = 2/9$$

Text Classification

Choosing a class:

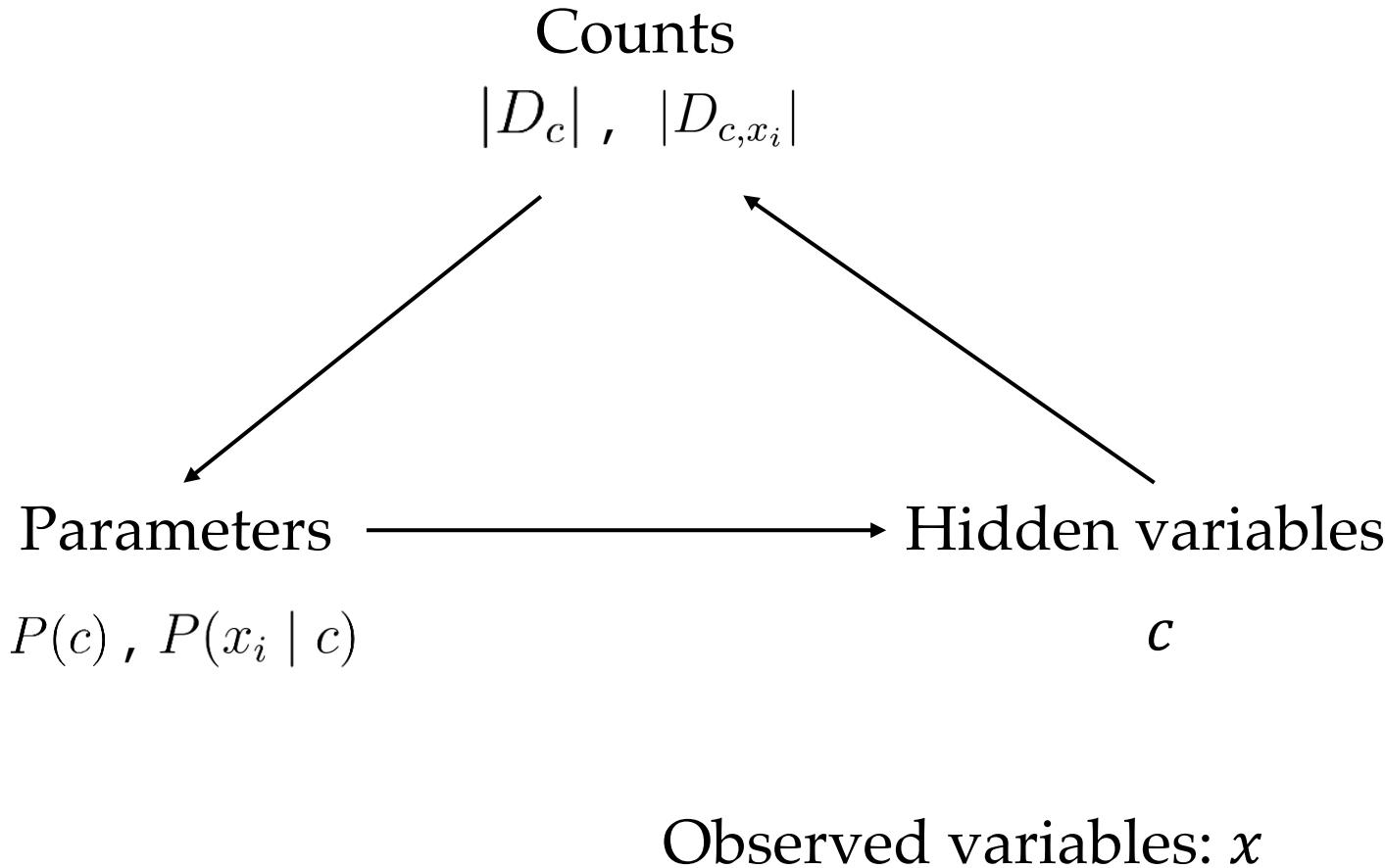
$$P(c|d5) \propto \frac{2}{3} * \left(\frac{3}{7}\right)^3 * \frac{1}{14} * \frac{1}{14} \approx 0.00027$$

$$P(j|d5) \propto \frac{1}{3} * \left(\frac{2}{9}\right)^3 * \frac{2}{9} * \frac{2}{9} \approx 0.00018$$

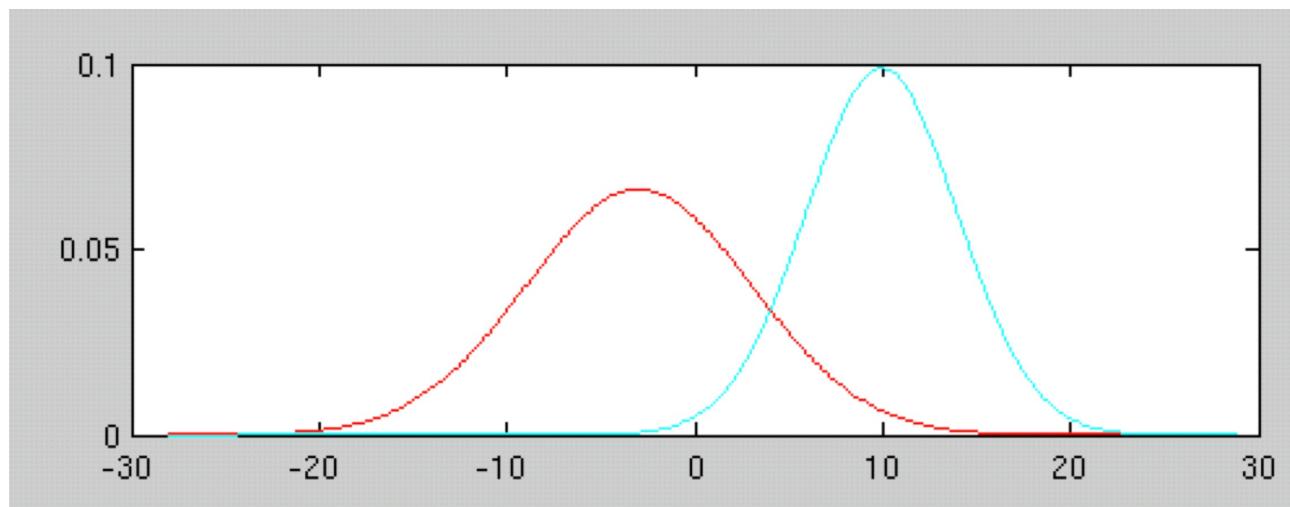
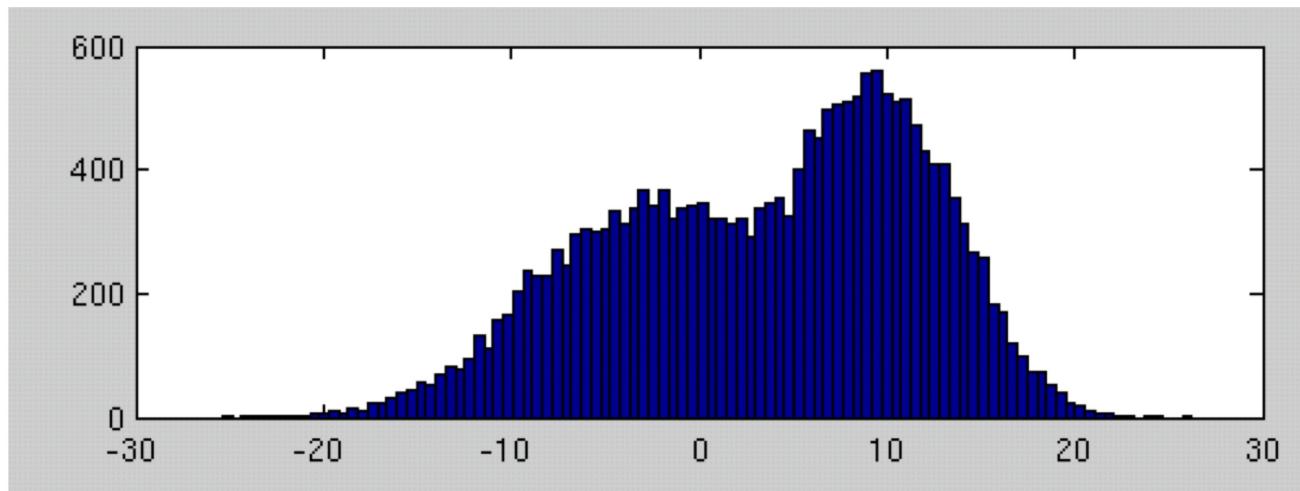
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Dealing with Hidden Variables



Gaussian Mixture-Model



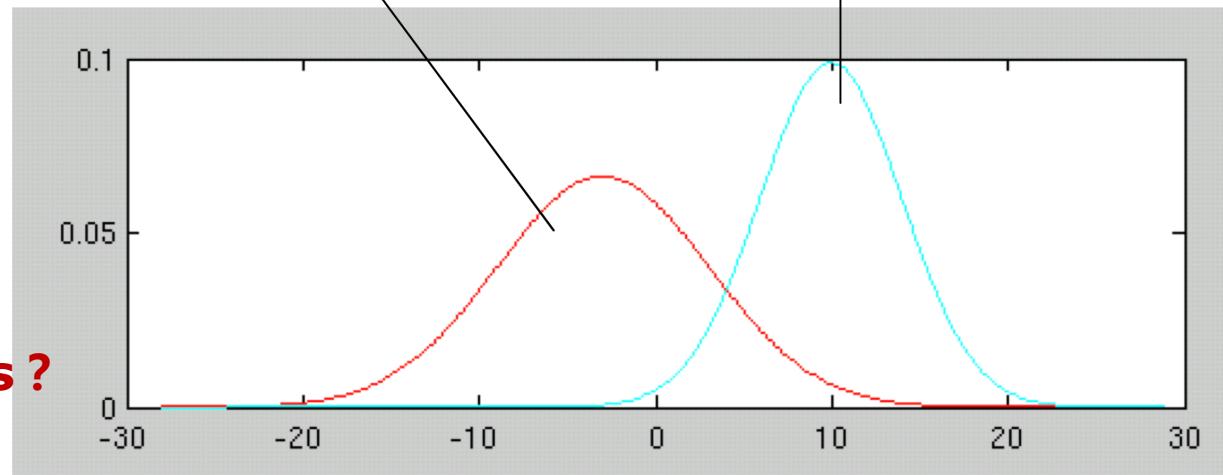
Gaussian Mixture-Model

$$P(x) = \pi \mathcal{N}(x|\mu_1, \Sigma_1) + (1 - \pi) \mathcal{N}(x|\mu_2, \Sigma_2)$$

GMM with 2 gaussians

Hidden Variable ?

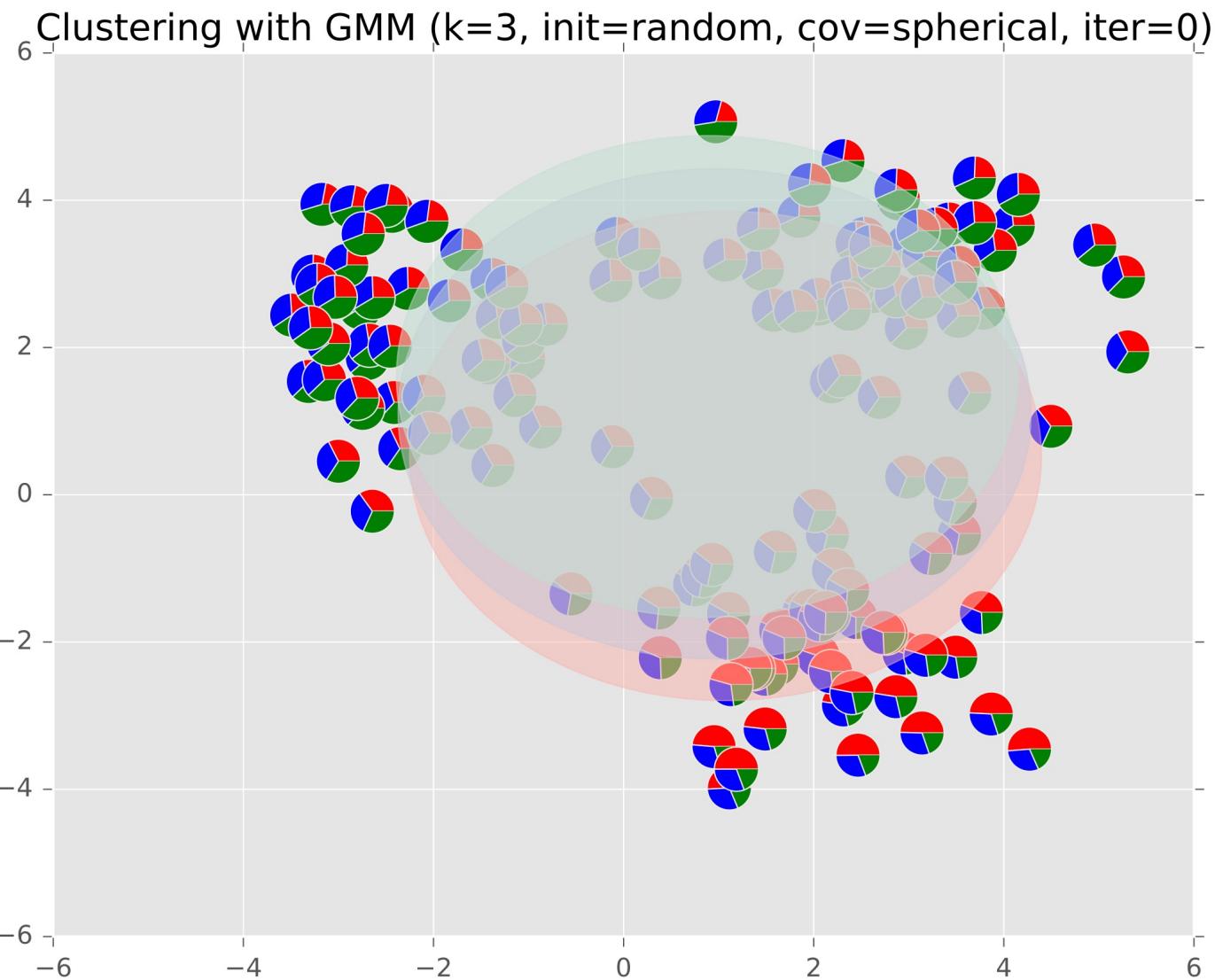
Model Parameters ?



PDF of Guassian:

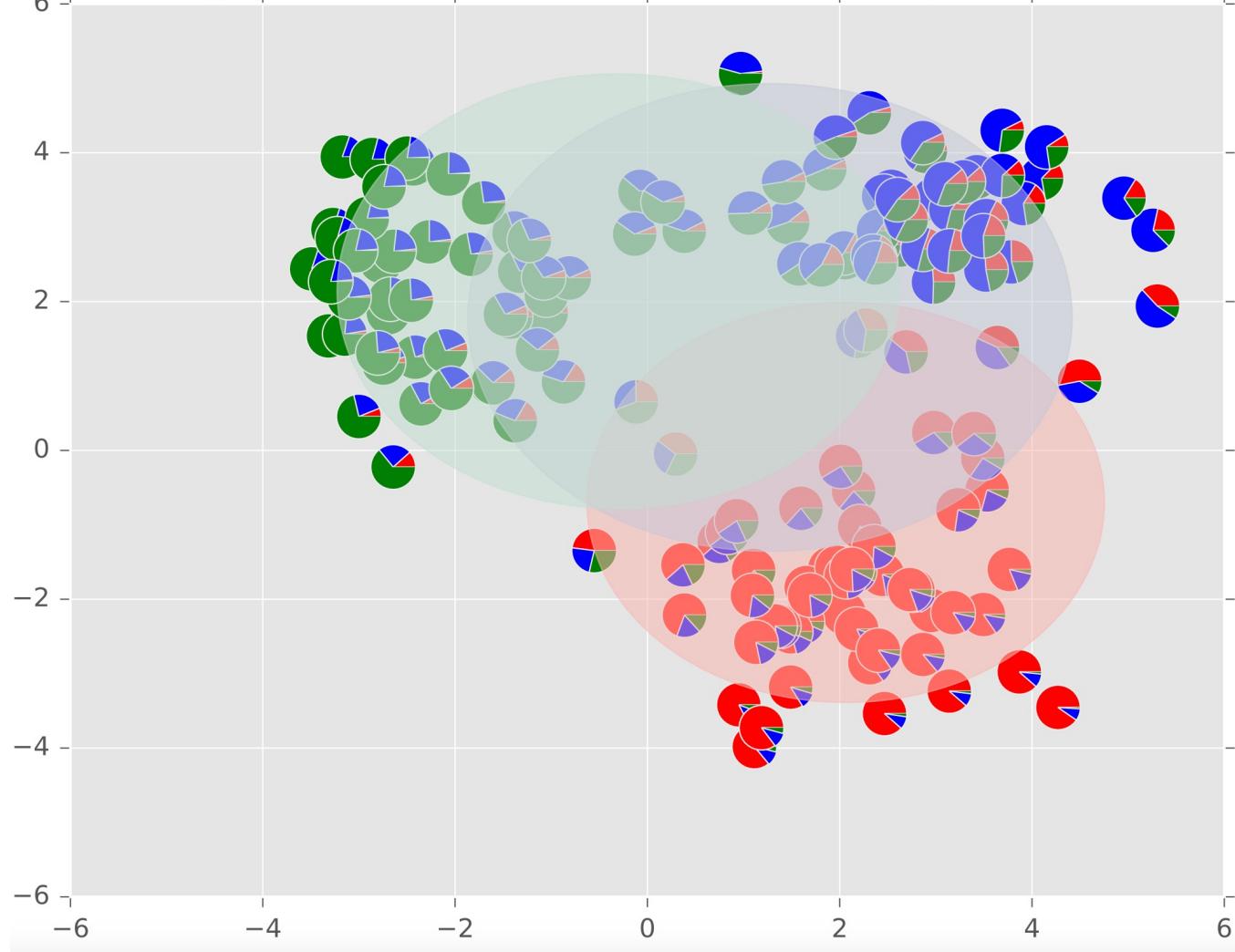
$$\frac{1}{(2\pi)^{d/2} |\Sigma_j|^{1/2}} e^{-\frac{1}{2}(x-\mu_j)^T \Sigma_j^{-1} (x-\mu_j)}$$

Example: GMM



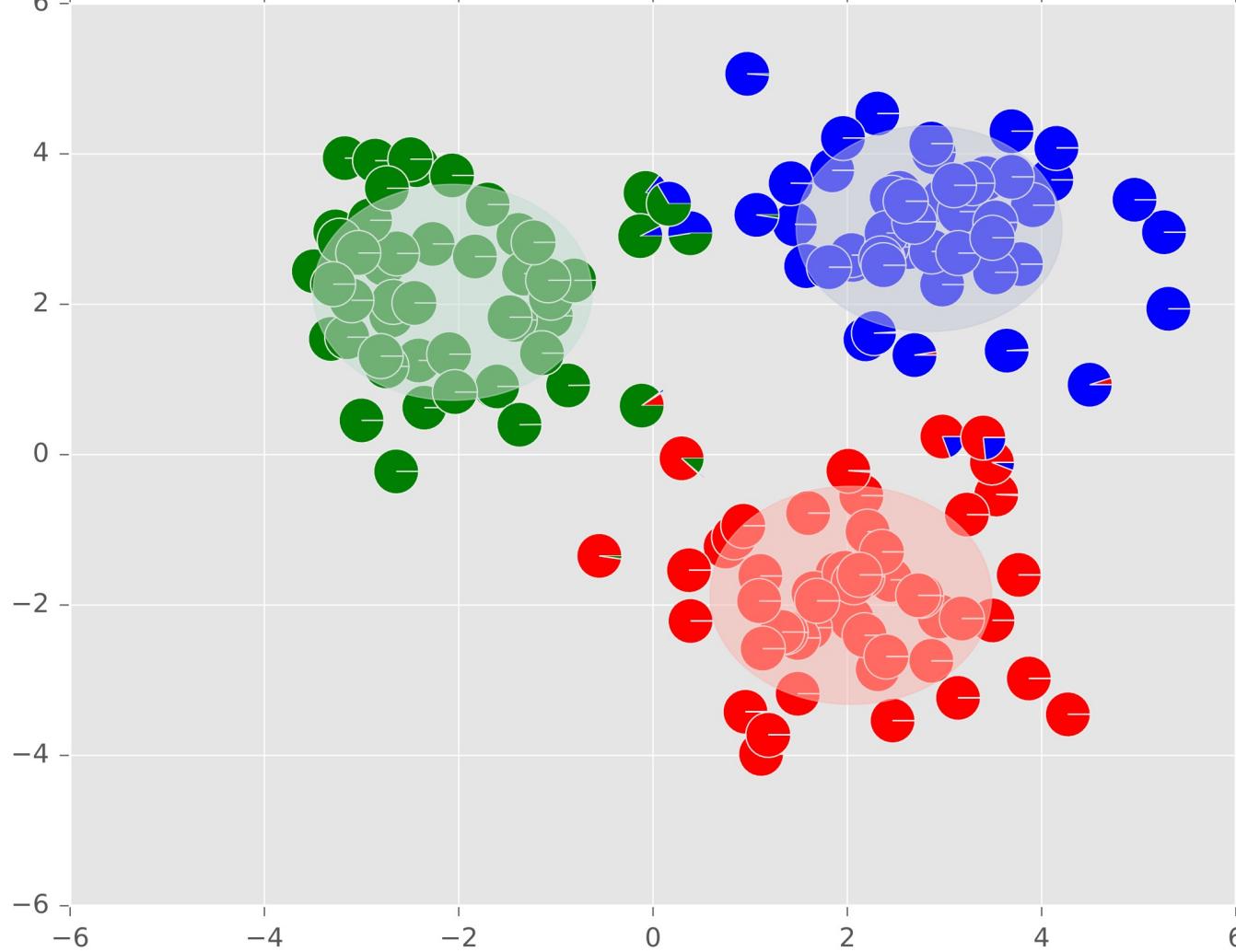
Example: GMM

Clustering with GMM (k=3, init=random, cov=spherical, iter=10)



Example: GMM

Clustering with GMM ($k=3$, init=random, cov=spherical, iter=19)



(Soft) EM Algorithm

The EM algorithm seeks to find the maximum likelihood estimate of the marginal likelihood by iteratively applying these two steps:

- **E-step (Expectation):** infer the current conditional distribution $P(\mathbf{Z} | \mathbf{X}, \Theta^t)$ based on Θ^t , and compute the expectation of the log-likelihood function with respect to \mathbf{Z} :

$$Q(\Theta | \Theta^t) = \mathbb{E}_{\mathbf{Z}|\mathbf{X},\Theta^t} LL(\Theta | \mathbf{X}, \mathbf{Z})$$

- **M-step (Maximization):** find the parameters that maximize the expected log-likelihood, that is,

$$\Theta^{t+1} = \operatorname{argmax}_{\Theta} Q(\Theta | \Theta^t)$$

Relationships between MLE and Q-function

When the outputs are hidden variables, and if z is known, we can turn EM algorithm to MLE in supervised settings.

- supposed that each \mathbf{x}_i has a supervised label y_i
- defining

$$P(z \mid \mathbf{x}_i, \Theta^t) = \begin{cases} 1 & \text{if } z = y_i \\ 0 & \text{otherwise} \end{cases}$$

$$\begin{aligned} Q(\Theta \mid \Theta^t) &= \sum_{i=1}^N \sum_{\mathbf{z} \in Z} P(\mathbf{z} \mid \mathbf{x}_i, \Theta^t) \log P(\mathbf{x}_i, \mathbf{z} \mid \Theta) \\ &= \sum_{i=1}^N \log P(\mathbf{x}_i, y_i \mid \Theta) \end{aligned}$$

which is exactly the maximum log-likelihood training objective.

Graphical interpretation

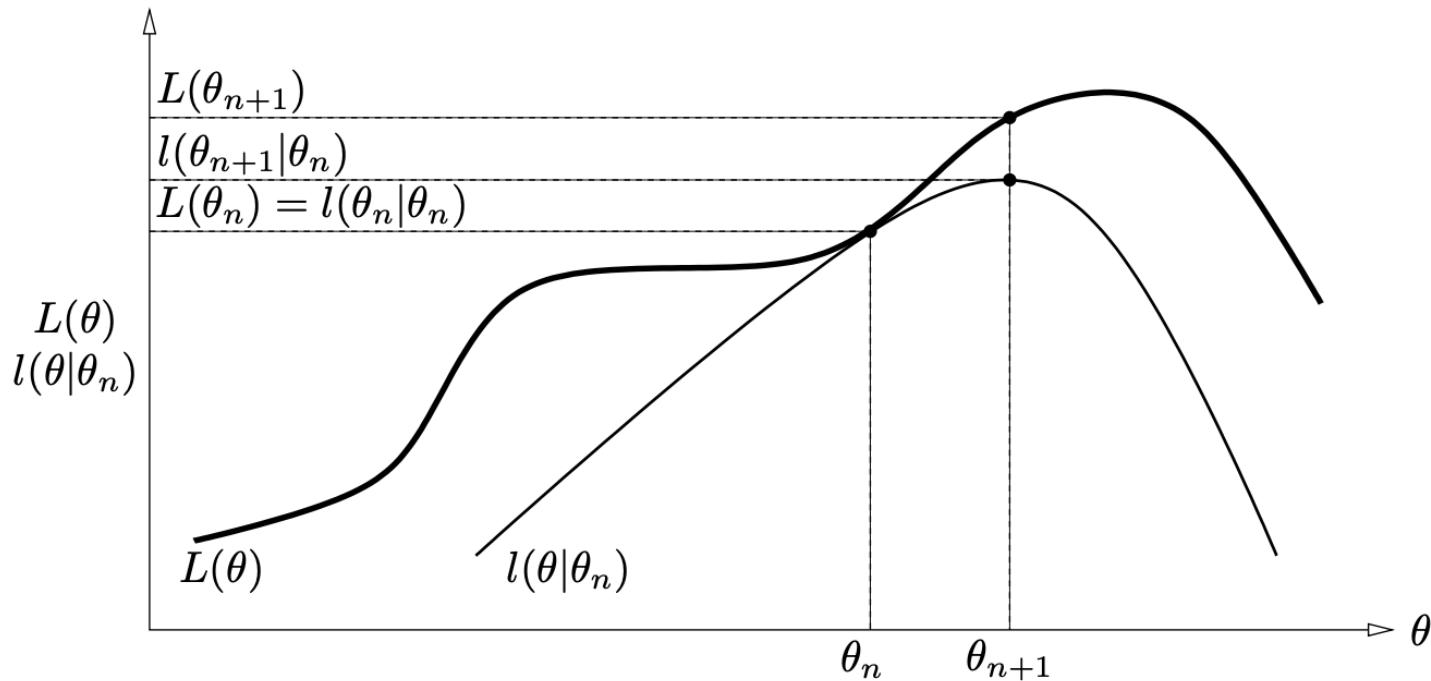


Figure 2: Graphical interpretation of a single iteration of the EM algorithm: The function $l(\theta|\theta_n)$ is upper-bounded by the likelihood function $L(\theta)$. The functions are equal at $\theta = \theta_n$. The EM algorithm chooses θ_{n+1} as the value of θ for which $l(\theta|\theta_n)$ is a maximum. Since $L(\theta) \geq l(\theta|\theta_n)$ increasing $l(\theta|\theta_n)$ ensures that the value of the likelihood function $L(\theta)$ is increased at each step.

Convergence

EM is guaranteed to converge to a point with **zero gradient**.

$$\begin{aligned} L(\theta) - L(\theta_n) &= \ln \sum_{\mathbf{z}} \mathcal{P}(\mathbf{X}|\mathbf{z}, \theta) \mathcal{P}(\mathbf{z}|\theta) - \ln \mathcal{P}(\mathbf{X}|\theta_n) \\ &= \ln \sum_{\mathbf{z}} \mathcal{P}(\mathbf{X}|\mathbf{z}, \theta) \mathcal{P}(\mathbf{z}|\theta) \cdot \frac{\mathcal{P}(\mathbf{z}|\mathbf{X}, \theta_n)}{\mathcal{P}(\mathbf{z}|\mathbf{X}, \theta_n)} - \ln \mathcal{P}(\mathbf{X}|\theta_n) \\ &= \ln \sum_{\mathbf{z}} \mathcal{P}(\mathbf{z}|\mathbf{X}, \theta_n) \left(\frac{\mathcal{P}(\mathbf{X}|\mathbf{z}, \theta) \mathcal{P}(\mathbf{z}|\theta)}{\mathcal{P}(\mathbf{z}|\mathbf{X}, \theta_n)} \right) - \ln \mathcal{P}(\mathbf{X}|\theta_n) \\ \text{WHY? } \rightarrow &\geq \sum_{\mathbf{z}} \mathcal{P}(\mathbf{z}|\mathbf{X}, \theta_n) \ln \left(\frac{\mathcal{P}(\mathbf{X}|\mathbf{z}, \theta) \mathcal{P}(\mathbf{z}|\theta)}{\mathcal{P}(\mathbf{z}|\mathbf{X}, \theta_n)} \right) - \ln \mathcal{P}(\mathbf{X}|\theta_n) \\ &= \sum_{\mathbf{z}} \mathcal{P}(\mathbf{z}|\mathbf{X}, \theta_n) \ln \left(\frac{\mathcal{P}(\mathbf{X}|\mathbf{z}, \theta) \mathcal{P}(\mathbf{z}|\theta)}{\mathcal{P}(\mathbf{z}|\mathbf{X}, \theta_n) \mathcal{P}(\mathbf{X}|\theta_n)} \right) \\ &\triangleq \Delta(\theta|\theta_n) \end{aligned}$$

Convergence

Theorem 2 (Jensen's inequality) Let f be a convex function defined on an interval I . If $x_1, x_2, \dots, x_n \in I$ and $\lambda_1, \lambda_2, \dots, \lambda_n \geq 0$ with $\sum_{i=1}^n \lambda_i = 1$,

$$f\left(\sum_{i=1}^n \lambda_i x_i\right) \leq \sum_{i=1}^n \lambda_i f(x_i)$$

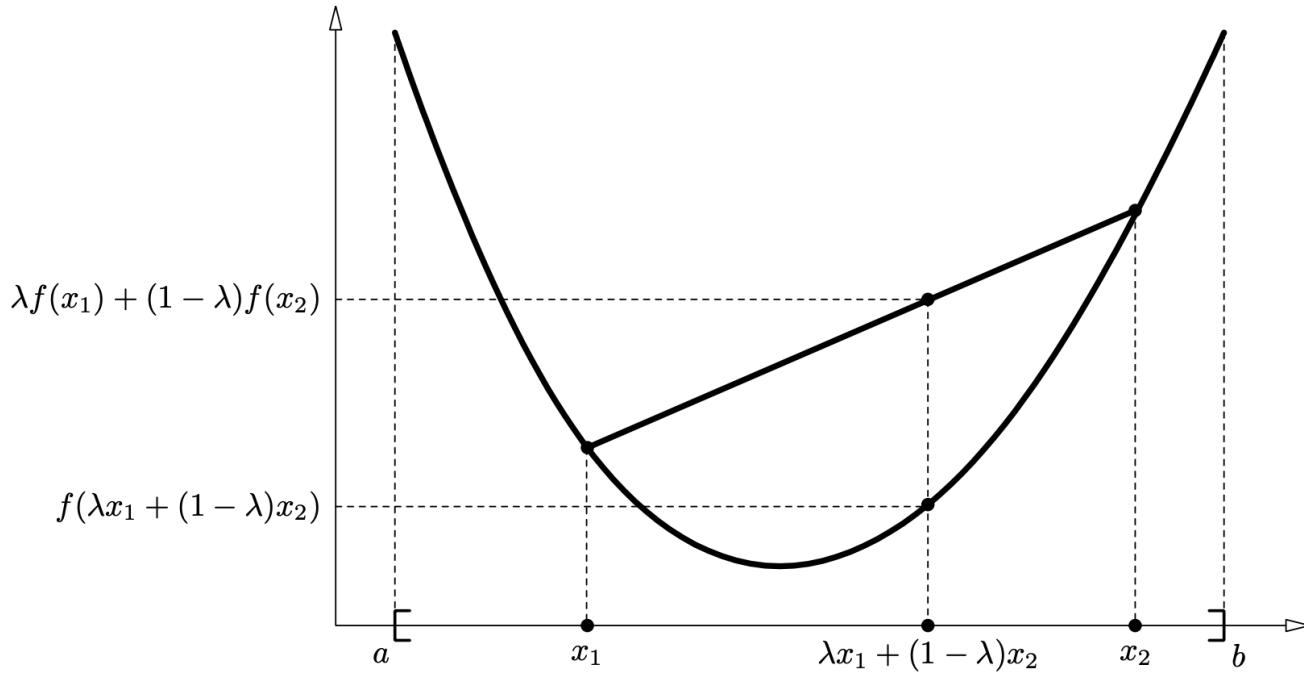


Figure 1: f is convex on $[a, b]$ if $f(\lambda x_1 + (1 - \lambda)x_2) \leq \lambda f(x_1) + (1 - \lambda)f(x_2)$ $\forall x_1, x_2 \in [a, b], \lambda \in [0, 1]$.

Convergence

Equivalently we may write,

$$L(\theta) \geq L(\theta_n) + \Delta(\theta|\theta_n)$$

and for convenience define,

$$l(\theta|\theta_n) \triangleq L(\theta_n) + \Delta(\theta|\theta_n)$$

so that

$$L(\theta) \geq l(\theta|\theta_n).$$

Additionally, observe that,

$$\begin{aligned} l(\theta_n|\theta_n) &= L(\theta_n) + \Delta(\theta_n|\theta_n) \\ &= L(\theta_n) + \sum_{\mathbf{z}} \mathcal{P}(\mathbf{z}|\mathbf{X}, \theta_n) \ln \frac{\mathcal{P}(\mathbf{X}|\mathbf{z}, \theta_n) \mathcal{P}(\mathbf{z}|\theta_n)}{\mathcal{P}(\mathbf{z}|\mathbf{X}, \theta_n) \mathcal{P}(\mathbf{X}|\theta_n)} \\ &= L(\theta_n) + \sum_{\mathbf{z}} \mathcal{P}(\mathbf{z}|\mathbf{X}, \theta_n) \ln \frac{\mathcal{P}(\mathbf{X}, \mathbf{z}|\theta_n)}{\mathcal{P}(\mathbf{X}, \mathbf{z}|\theta_n)} \\ &= L(\theta_n) + \sum_{\mathbf{z}} \mathcal{P}(\mathbf{z}|\mathbf{X}, \theta_n) \ln 1 \\ &= L(\theta_n), \end{aligned}$$

Convergence

$$\begin{aligned}\theta_{n+1} &= \arg \max_{\theta} \{l(\theta|\theta_n)\} \\ &= \arg \max_{\theta} \left\{ L(\theta_n) + \sum_{\mathbf{z}} \mathcal{P}(\mathbf{z}|\mathbf{X}, \theta_n) \ln \frac{\mathcal{P}(\mathbf{X}|\mathbf{z}, \theta) \mathcal{P}(\mathbf{z}|\theta)}{\mathcal{P}(\mathbf{X}|\theta_n) \mathcal{P}(\mathbf{z}|\mathbf{X}, \theta_n)} \right\}\end{aligned}$$

Now drop terms which are constant w.r.t. θ

$$\begin{aligned}&= \arg \max_{\theta} \left\{ \sum_{\mathbf{z}} \mathcal{P}(\mathbf{z}|\mathbf{X}, \theta_n) \ln \mathcal{P}(\mathbf{X}|\mathbf{z}, \theta) \mathcal{P}(\mathbf{z}|\theta) \right\} \\ &= \arg \max_{\theta} \left\{ \sum_{\mathbf{z}} \mathcal{P}(\mathbf{z}|\mathbf{X}, \theta_n) \ln \mathcal{P}(\mathbf{X}, \mathbf{z}|\theta) \right\} \\ &= \arg \max_{\theta} \left\{ \mathbb{E}_{\mathbf{Z}|\mathbf{X}, \theta_n} \{ \ln \mathcal{P}(\mathbf{X}, \mathbf{z}|\theta) \} \right\}\end{aligned}$$

$$Q(\Theta \mid \Theta^t) = \mathbb{E}_{\mathbf{Z}|\mathbf{X}, \Theta^t} LL(\Theta \mid \mathbf{X}, \mathbf{Z})$$

Graphical interpretation

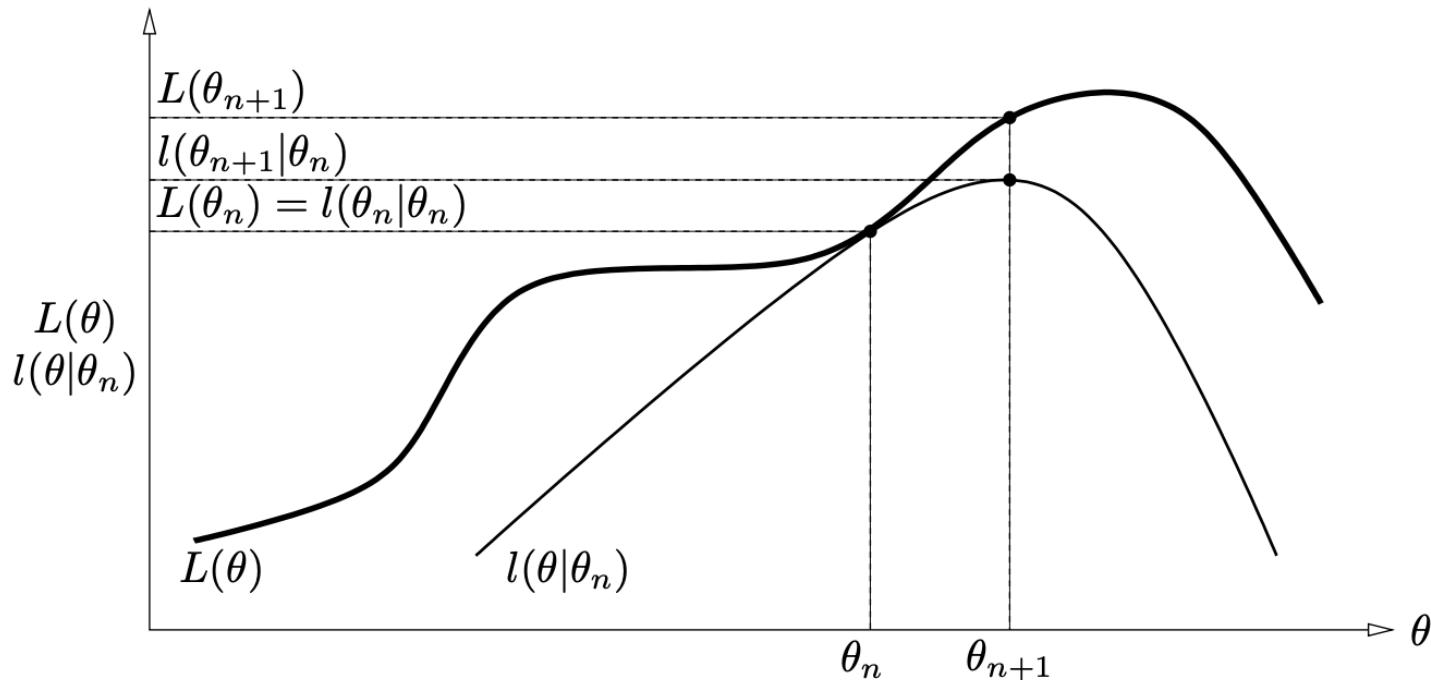
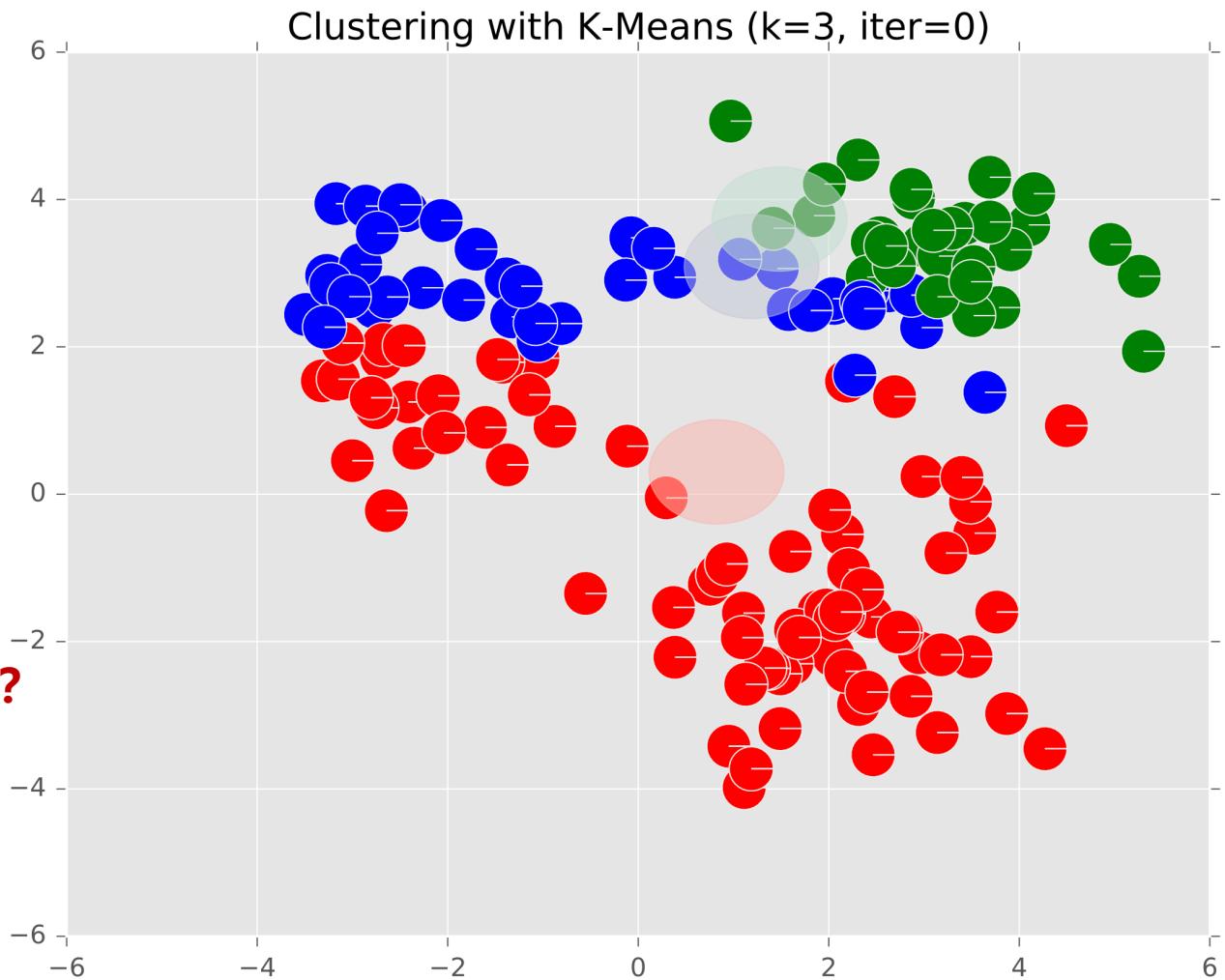


Figure 2: Graphical interpretation of a single iteration of the EM algorithm: The function $l(\theta|\theta_n)$ is upper-bounded by the likelihood function $L(\theta)$. The functions are equal at $\theta = \theta_n$. The EM algorithm chooses θ_{n+1} as the value of θ for which $l(\theta|\theta_n)$ is a maximum. Since $L(\theta) \geq l(\theta|\theta_n)$ increasing $l(\theta|\theta_n)$ ensures that the value of the likelihood function $L(\theta)$ is increased at each step.

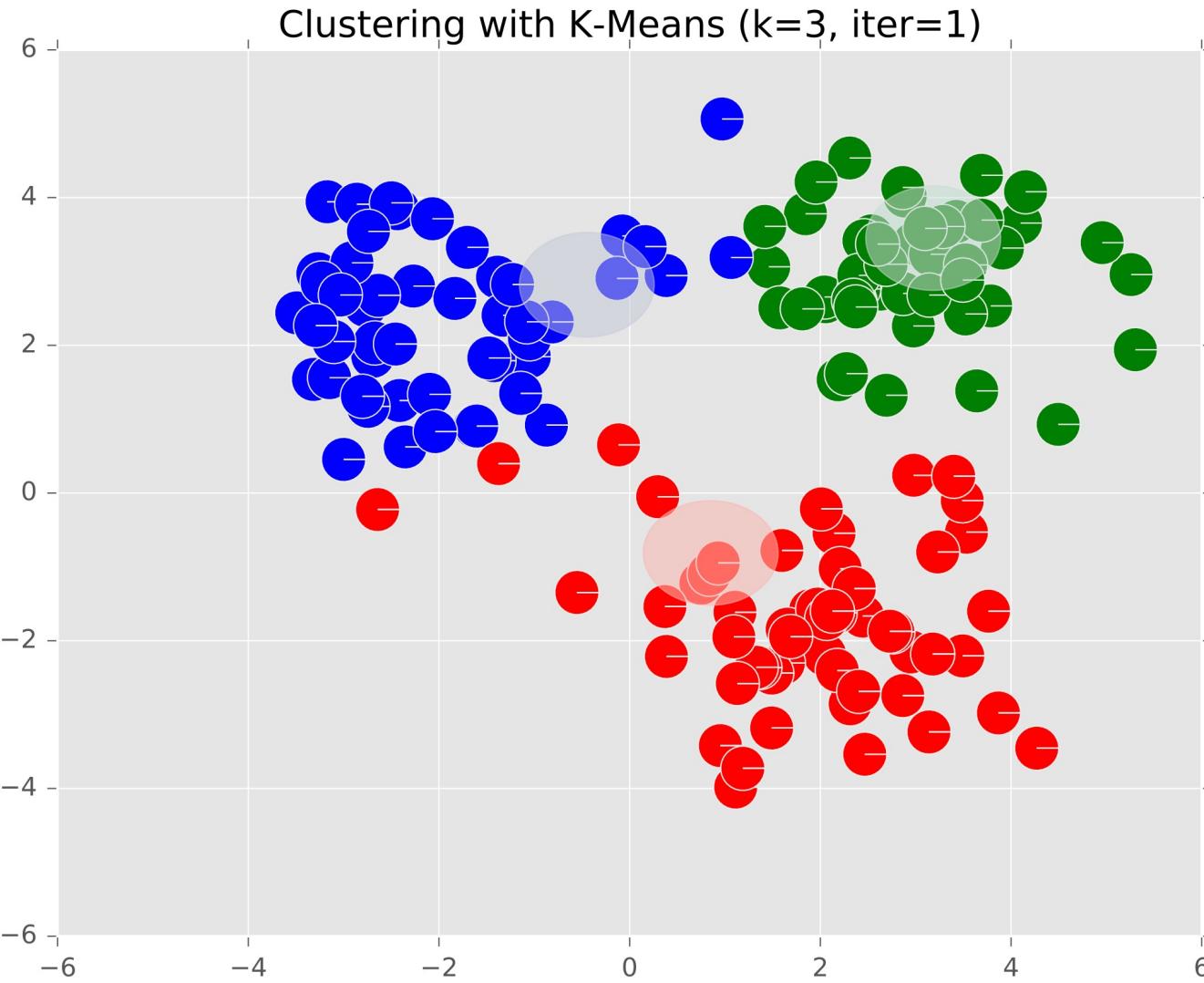
Example: K-Means

Hidden Variable ?

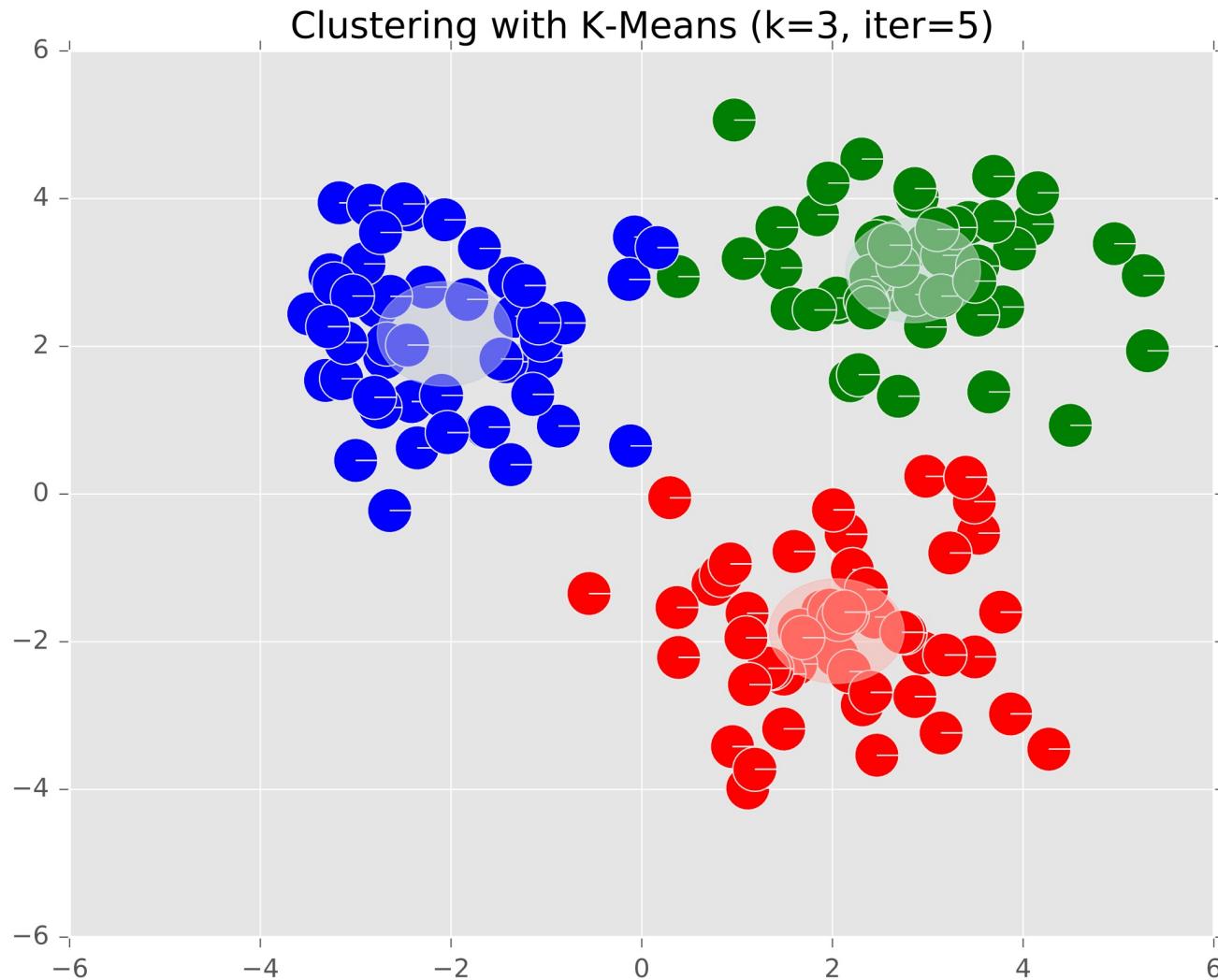
Model Parameters ?



Example: K-Means



Example: K-Means



(Hard) EM Algorithm

repeat

Expectation step:

$$\mathbf{Z}^t \leftarrow \arg \max_{\mathbf{Z}} \log P(\mathbf{X}, \mathbf{Z} | \Theta^t);$$

Maximisation step:

$$\Theta^{t+1} \leftarrow \arg \max_{\Theta} \log P(\mathbf{X}, \mathbf{Z}^t | \Theta);$$

$$t \leftarrow t + 1;$$

until CONVERGE(\mathbf{Z}, Θ);
