

Model Free Control

Bias Maximization and Double Q-Learning

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Maximization Bias

- ▶ Consider single-state MDP ($|S| = 1$) with 2 actions, and both actions have 0-mean random rewards: $(r \mid a = a_1) = (r \mid a = a_2) = 0$
 - ▶ assume that reward is stochastic (e.g, $\mathcal{N}(0, 1)$)
- ▶ Then $Q(s, a_1) = Q(s, a_2) = 0 = V(s)$
- ▶ Assume there are prior samples of taking action a_1 and a_2

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- ▶ Let $\hat{Q}(s, a_1), \hat{Q}(s, a_2)$ be the **finite** sample estimate of Q
- ▶ Use an unbiased estimator for Q , e.g., $\hat{Q}(s, a_1) = \frac{1}{N(s, a_1)} \sum_{i=1}^{N(s, a_1)} r_i(s, a_1)$

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- ▶ Let $\hat{\pi} \in \arg \max_a \hat{Q}(s, a)$ be the greedy policy wrt the estimated \hat{Q}
- ▶ Even though each estimate of the state-action values is unbiased, the estimate of $\hat{\pi}$'s value $\hat{V}^{\hat{\pi}}$ can be biased:

$$\begin{aligned}\hat{V}^{\hat{\pi}}(s) &= \mathbb{E}[\max \hat{Q}(s, a_1), \hat{Q}(s, a_2)] \\ &\geq \max[\mathbb{E}[\hat{Q}(s, a_1)], \mathbb{E}[\hat{Q}(s, a_2)]] \\ &= \max[0, 0] = V^{\pi}\end{aligned}$$

Double Q-Learning

- ▶ The greedy policy w.r.t. estimated Q values can yield a maximization bias during finite-sample learning
 - ▶ Avoid using max of estimates as estimate of max of true values
 - ▶ Instead split samples and use to create two independent unbiased estimates of $Q_1(s_1, a_i)$ and $Q_2(s_1, a_i). \forall a \in A$
 - ▶ Use one estimate to select max action: $a^* \in \arg \max_{a \in A} Q_1(s_1, a)$
 - ▶ Use other estimate to estimate value of a^* : $Q_2(s, a^*)$
 - ▶ Yields unbiased estimate: $\mathbb{E}(Q_2(s, a^*)) = Q(s, a^*)$
- ↪ Unbiased estimate of the max state-action value because of independent samples to estimate the value

Double Q-Learning for Full MDP

► Initialization:

- $Q_1(s, a)$ and $Q_2(s, a) \forall s \in S, a \in A$
- $t = 0$
- initial state $s_t = s_0$

► Loop

- Select a_t using ϵ -greedy $\pi(s) \in \arg \max_{a \in A} Q_1(s_t, a) + Q_2(s_t, a)$
- Observe (r_t, s_{t+1})
- With 50-50 probability either
 1. $Q_1(s_t, a_t) \leftarrow Q_1(s_t, a_t) + \alpha(r_t + \gamma \max_{a \in A} Q_2(s_{t+1}, a) - Q_1(s_t, a_t))$
or
 2. $Q_2(s_t, a_t) \leftarrow Q_2(s_t, a_t) + \alpha(r_t + \gamma \max_{a \in A} Q_1(s_{t+1}, a) - Q_2(s_t, a_t))$
- $t = t + 1$

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↪ Doubles the memory, same computation requirements, data requirements are subtle – might reduce amount of exploration needed due to lower bias

Double Q-Learning [Sutton & Barto 2018]

