Curriculum Reinforcement Learning

SPaCE

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Automated
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SPaCE [Eimer et al. 2020]

- Most agents estimate the state-value function V in some way
- Common definition of V:

$$V(s) = \exp_\pi \sum_t^T \gamma^t \cdot r_t$$

- Therefore $V(s_0)$ estimates the total discounted reward for the whole episode
- Idea: use this information for curriculum generation

Setting - what makes SPaCE special?

- Designed for deep contextual RL
- No prior knowledge about instance space required, e.g.:
  - size
  - difficulty
  - difficulty regions

Algorithm Outline

- Hyperparameters: threshold η, increment size κ
- Until desired number of steps is reached:
  - Choose the instances on which the evaluation has changed most (according to current instance set size)
  - Train on those instances
  - Evaluate if performance on the training set has changed by at least η. If not, increase instance set size by κ

Results - AntGoal

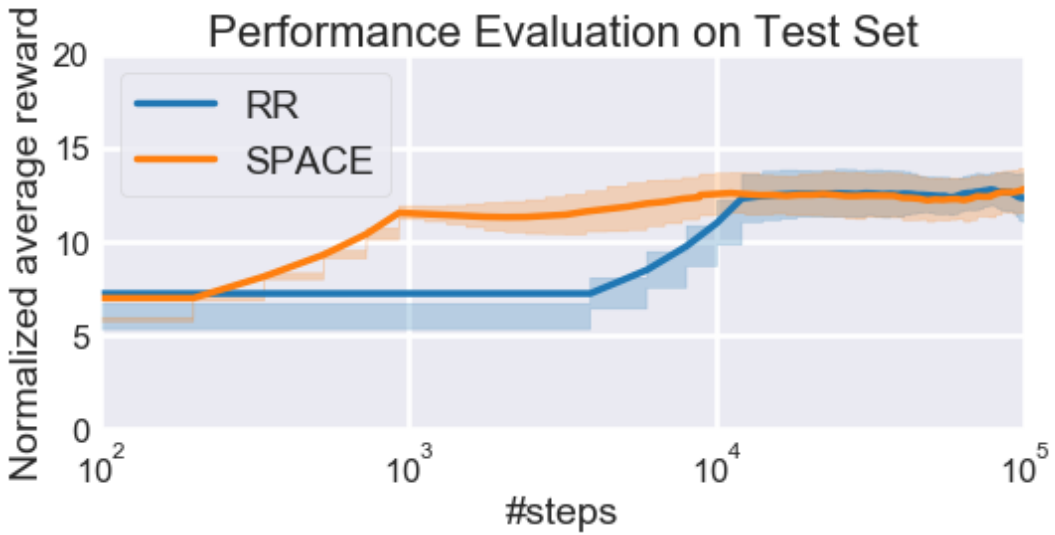

Figure: Comparing SPaCE and round robin on AntGoal with broken limbs.

Results - PointMass

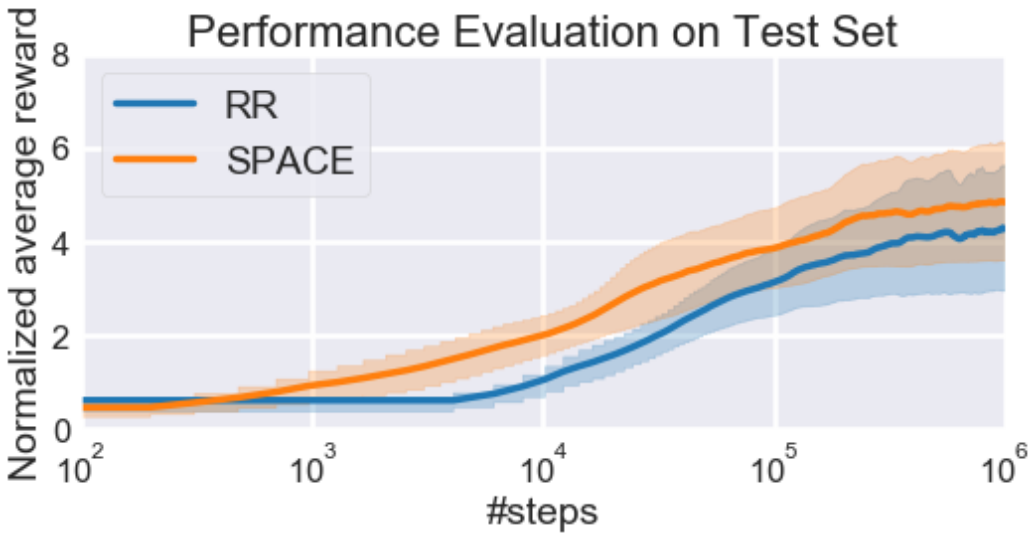

Figure: Comparing SPaCE and round robin on contextual PointMass.