Curriculum Reinforcement Learning^a

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^aBased on a blog by Lilian Weng

From Easy to Hard

- ► We humans also learn step by step
 - ► E.g., in math, we learn first basic arithmetics before we later learn complex derivatives and integrals
 - ► E.g., in this lecture, we first talked about simple planning on MDPs, before we talked about complex meta-RL ideas
- ▶ Idea: break down complex concepts into simpler concepts s.t. we can start from the easy ones and build up the complex one
- ► Challenge: How can we design a curriculum starting from simple to hard tasks?
 - ► A poorly designed curriculum might even harm learning.
- ► Challenge: How do we avoid catastrophic forgetting by training on another instance?

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Task-Specific Curriculum Learning [Bengio et al. 2009]

- 1. Cleaner Examples may yield better generalization faster.
- 2. Introducing gradually more difficult examples speeds up online training.
- ▶ Results by [Zaremba and Sutskever. 2014] indicated that one should mix in easy tasks to not forget how to solve these.

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How to Quantify Complexity/Difficulty of an Env?

- Human specification
 - parameterized generator for environments that allow to control the complexity by hand
 - or we can measure meta-features of the different envs, e.g.
 - Size of maze
 - distance between start state and end state
 - Fraction of floor space to walls
 - **.**
 - ▶ Note: We cannot quantify the complexity of the optimal policy for a given MDP, because we have to measure these before actually solving the MDP

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Automatic Curriculum Generation

- ► In contrast to a hand-designed curriculum before training starts, the curriculum is generated on the fly for any instances in the domain
- Criteria for the ordering have to be provided or computed during runtime
- ▶ While criteria need to be computed during runtime, they do not need to be hand-designed

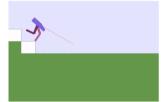
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Example Criterion 1: Manual Difficulty Ratings

1. Idea: define a function to rate env difficulty

2. Example: POET [Wang et al. 2019]¹





¹Image source: Uber Al

Example Criterion 2: External Model

- 1. Minimal loss wrt another policy being pretrained on other tasks as criterion
- 2. Sort the instances s.t. they go from easy to hard wrt this pretrained agent [Weinshall et al. 2018]

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