RL: Basics The Markov Process

Marius Lindauer





Leibniz Universität Hannover



Reminder: Markov Assumption

- Information state: sufficient statistic of history
- State s_t is Markov if and only if:

$$p(s_{t+1} \mid s_t, a_t) = p(s_{t+1} \mid h_t, a_t)$$

• with history $h_t = (a_1, s_1, r_1, \dots, a_t, s_t, r_t)$



Markov Process or Markov Chain

- Memoryless random process (/walk)
 - → Sequence of random states with Markov propery
- Definition of Markov Process M = (S, P)
 - S is a (finite) set of states ($s \in S$)
 - ▶ P is dynamics/transition model that specifies $p(s_{t+1} = s' \mid s_t = s)$
- Note: no rewards, no actions
- If finite number (N) of states, can express P as a matrix

$$P_{i,j} = P(s_i \mid s_j)$$



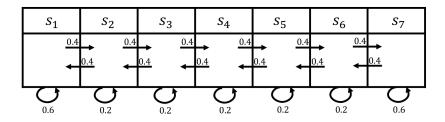
Mars Rover

s_1	s_2	s_3	S_4	S ₅	s ₆	S ₇
			7			

• States: Location of rover (s_1,\ldots,s_7)



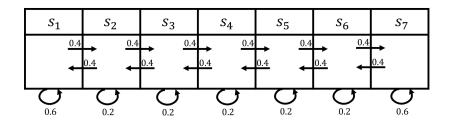
Mars Rover as Markov Process



$$P = \begin{pmatrix} 0.6 & 0.4 & 0 & 0 & 0 & 0 & 0 \\ 0.4 & 0.2 & 0.4 & 0 & 0 & 0 & 0 \\ 0 & 0.4 & 0.2 & 0.4 & 0 & 0 & 0 \\ 0 & 0 & 0.4 & 0.2 & 0.4 & 0 & 0 \\ 0 & 0 & 0 & 0.4 & 0.2 & 0.4 & 0 \\ 0 & 0 & 0 & 0 & 0.4 & 0.2 & 0.4 \\ 0 & 0 & 0 & 0 & 0 & 0.4 & 0.6 \end{pmatrix}$$



Mars Rover as Markov Process (cont'd)



Exemplary episodes:

- \bullet $s_4, s_5, s_6, s_7, s_7, s_7, \dots$
- \bullet $s_4, s_4, s_5, s_4, s_5, s_6, \dots$
- $s_4, s_3, s_2, s_1, \dots$



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 - ► Follow links on homepages
 - Rank websites based on probability to discover this page



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- Used in forecasting of trends, e.g., prices and wind power

