

RL: MDP

The Markov Reward Process

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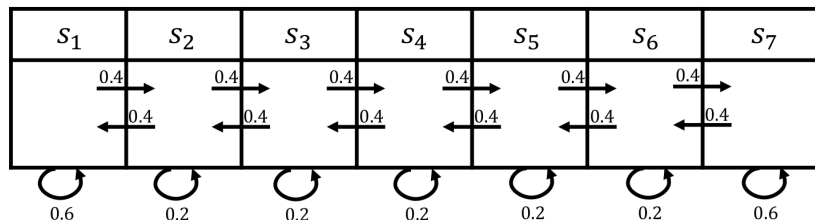


Automated
Machine Learning
Hannover

Markov Reward Process (MRP)

- Extend Markov Process by rewards
- Definition of Markov Reward Process (MRP) $M = (S, P, R, \gamma)$
 - ▶ S is a (finite)
 - ▶ P is dynamics/transition model that specifies $P(s_{t+1} = s' \mid s_t = s)$
 - ▶ R is a reward function $R(s_t = s) = \mathbb{E}[r_t \mid s_t = s]$
 - ▶ Discount factor $\gamma \in [0, 1]$
- Note: no actions
- If finite number (N) of states, we can express R as a vector

Mars Rover as MRP



Rewards:

- +1 in s_1 ,
- +10 in s_7 ,
- 0 in all other states

- Definition of Horizon

- ▶ Number of time steps in each episode
- ▶ Can be infinite
- ▶ Otherwise called finite Markov reward process

Return & Value Function

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- Definition of Return: G_t (for a MRP)
 - ▶ Discounted sum of rewards from time step t to horizon

$$G_t = r_t + \gamma r_{t+1} + \gamma^2 r_{t+2} + \gamma^3 r_{t+3} + \dots$$

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- Definition of State Value Function: $V(s)$ for a MRP

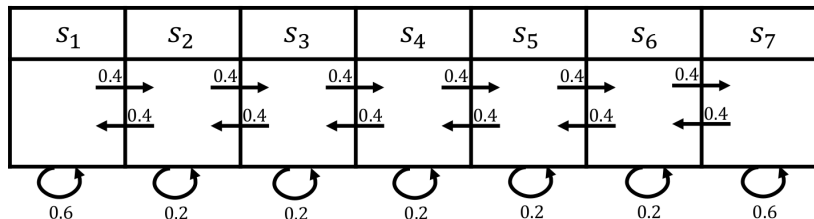
- ▶ Expected return from starting in state s

$$V(s) = \mathbb{E}[G_t \mid s_t = s] = \mathbb{E}[r_t + \gamma r_{t+1} + \gamma^2 r_{t+2} + \gamma^3 r_{t+3} + \dots \mid s_t = s]$$

$$V(s) = \mathbb{E}[G_t \mid s_t = s] == \mathbb{E}[r_t + \gamma r_{t+1} + \gamma^2 r_{t+2} + \gamma^3 r_{t+3} + \dots \mid s_t = s]$$

- Mathematically convenient (avoid infinite returns and values)
- Humans often act as if there's a discount factor $\gamma < 1$
- $\gamma = 0$: Only care about immediate reward
- $\gamma = 1$: Future reward is as beneficial as immediate reward
- If episode lengths are always finite, can use $\gamma = 1$ (but don't have to)

Mars Rover as MRP



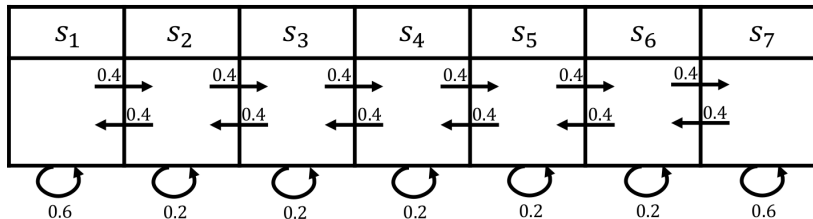
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Sample returns for 4-step episodes, $\gamma = 1/2$

- $s_4, s_5, s_6, s_7 : 0 + \frac{1}{2} \cdot 0 + \frac{1}{4} \cdot 0 + \frac{1}{8} \cdot 10 = 1.25$

Mars Rover as MRP



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$$V(s) = \mathbb{E}[G_t \mid s_t = s] = \mathbb{E}[r_t + \gamma r_{t+1} + \gamma^2 r_{t+2} + \gamma^3 r_{t+3} + \dots \mid s_t = s]$$

$$\rightsquigarrow V(s_1) = 1.53, V(s_2) = 0.37, \dots, V(s_7) = 15.31$$

Computing the Value of a Markov Reward Process

- Could estimate by simulation:
 - 1 Generate a large number of episodes
 - 2 Average returns
- Requires no assumption of Markov structure

Computing the Value of a Markov Reward Process

- Could estimate by simulation:
- Markov property yields additional structure
- MRP value function satisfies

$$V(s) = R(s) + \gamma \sum_{s' \in S} P(s' | s) V(s')$$

Matrix Form of Bellman Equation for MRP

$$\begin{pmatrix} V(s_1) \\ \vdots \\ V(s_n) \end{pmatrix} = \begin{pmatrix} R(s_1) \\ \vdots \\ R(s_n) \end{pmatrix} + \gamma \begin{pmatrix} P(s_1|s_1) & \dots & P(s_n | s_1) \\ \vdots & & \vdots \\ P(s_1|s_n) & \dots & P(s_n | s_n) \end{pmatrix} \begin{pmatrix} V(s_1) \\ \vdots \\ V(s_n) \end{pmatrix}$$

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$$V = R + \gamma PV \quad (1)$$

$$V - \gamma PV = R \quad (2)$$

$$(1 - \gamma P)V = R \quad (3)$$

$$V = (1 - \gamma P)^{-1} R \quad (4)$$

$$(5)$$

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\rightsquigarrow Solving directly requires taking a matrix inverse $O(n^3)$

Iterative Algorithm for Computing Value of a MRP

- Dynamic Programming :
 - ▶ Initialize $V_0(s) = 0$ for all s
 - ▶ For $k = 1$ until convergence
 - ★ For all s in S

$$V_k(s) = R(s) + \gamma \sum_{s' \in S} P(s' | s) V_{k-1}(s')$$

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- Computational complexity: $O(|S|^2)$ for each iteration ($|S| = n$)