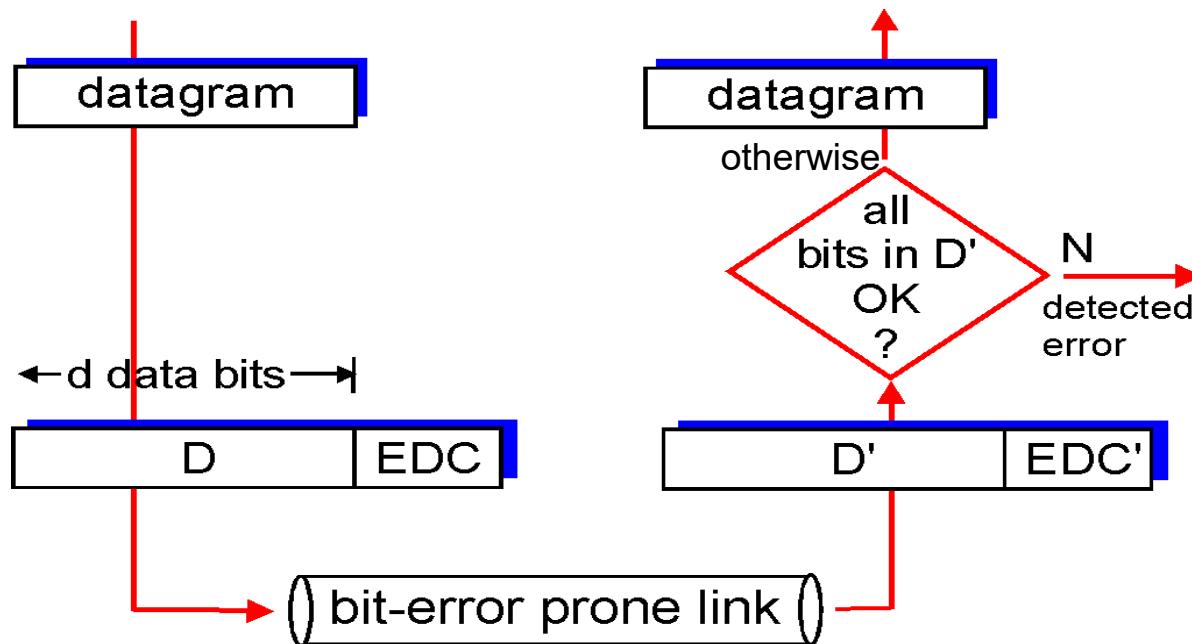


Error detection

EDC= Error Detection and Correction bits (redundancy)

D = Data protected by error checking, may include header fields

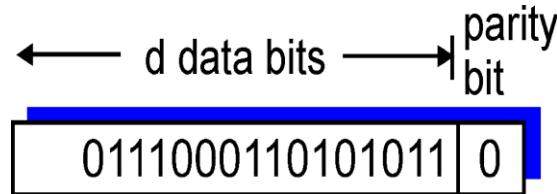
- Error detection not 100% reliable!
 - protocol may miss some errors, but rarely
 - larger EDC field yields better detection and correction



Parity checking

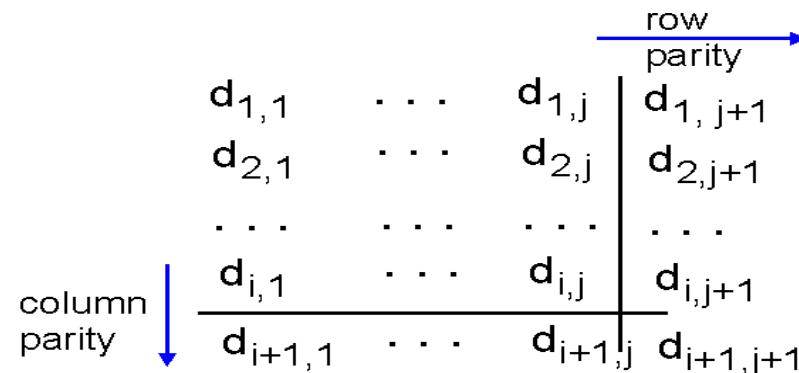
single bit parity:

- ❖ detect single bit errors



two-dimensional bit parity:

- ❖ detect and correct single bit errors



101011
111100
011101
001010
no errors

101011
101100
011101
001010
parity error
parity error
correctable single bit error

P1

1	1	1	0	1
0	1	1	0	0
1	0	0	1	0
1	1	0	1	1
1	1	0	0	0

$4 \times 4 \rightarrow 4 \text{ row parities} + 4 \text{ column parities} + 1 \text{ corner} = 9 \text{ parity bits} \leftarrow \text{fewest}$

Even Parity scheme: Make the total number of 1s in a group of bits (including the parity bit) even.

Count number of 1s
odd \rightarrow parity = 1
even \rightarrow parity = 0

Slotted ALOHA: efficiency

efficiency: long-run fraction of successful slots (many nodes, all with many frames to send)

- ❖ suppose: N nodes with many frames to send, each transmits in slot with probability p
- ❖ prob that given node has success in a slot = $p(1-p)^{N-1}$
- ❖ prob that *any* one of the N nodes has a success = $Np(1-p)^{N-1}$

- ❖ max efficiency: find p^* that maximizes $Np(1-p)^{N-1}$
- ❖ for many nodes, take limit of $Np^*(1-p^*)^{N-1}$ as N goes to infinity, gives:
max efficiency = 1/e = .37

at best: channel used for useful transmissions 37% of time!

!

P2

- a) A's average throughput is given by $p_A(1-p_B)$.

Total efficiency is $p_A(1-p_B) + p_B(1-p_A)$.

- b) A's throughput is $p_A(1-p_B)=2p_B(1-p_B)=2p_B-2(p_B)^2$.

B's throughput is $p_B(1-p_A)=p_B(1-2p_B)=p_B-2(p_B)^2$.

Clearly, A's throughput is not twice as large as B's.

- In order to make $p_A(1-p_B)=2p_B(1-p_A) \Rightarrow p_A - p_A p_B = 2 p_B - 2 p_A p_B$
 - $p_A = 2 p_B - p_A p_B$
 - $p_A + p_A p_B = 2 p_B$
 - $p_A (1 + p_B) = 2 p_B$
 - $p_A = 2 p_B / (1 + p_B)$
- c) A's throughput is $2p(1-p)^{N-1}$, and any other node has throughput $p(1-p)^{N-2}(1-2p)$.

CSMA (carrier sense multiple access)

CSMA: listen before transmit:

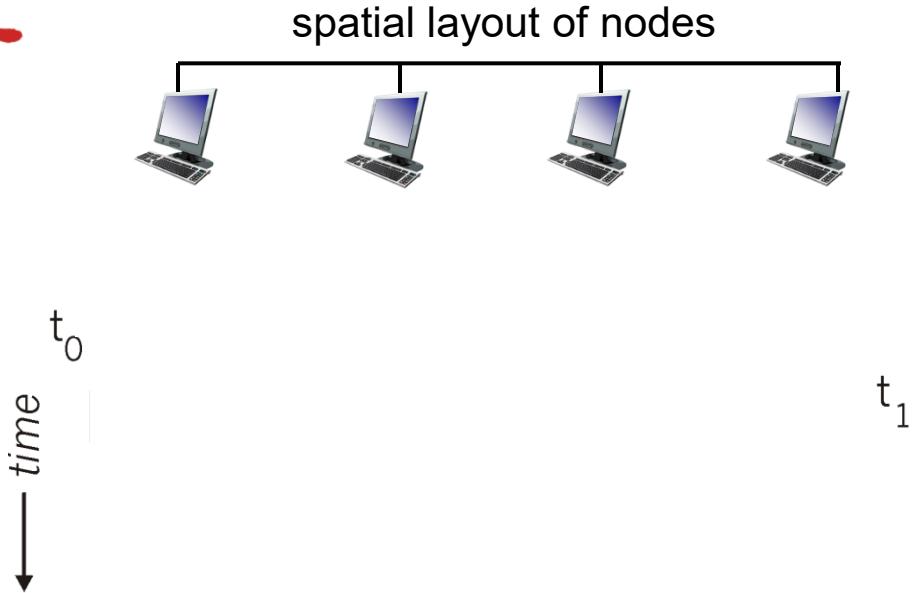
if channel sensed idle: transmit entire frame

❖ if channel sensed busy, defer transmission

❖ human analogy: don't interrupt others!

CSMA collisions

- ❖ **collisions can still occur:** propagation delay means two nodes may not hear each other's transmission
- ❖ **collision:** entire packet transmission time wasted
 - distance & propagation delay play role in determining collision probability

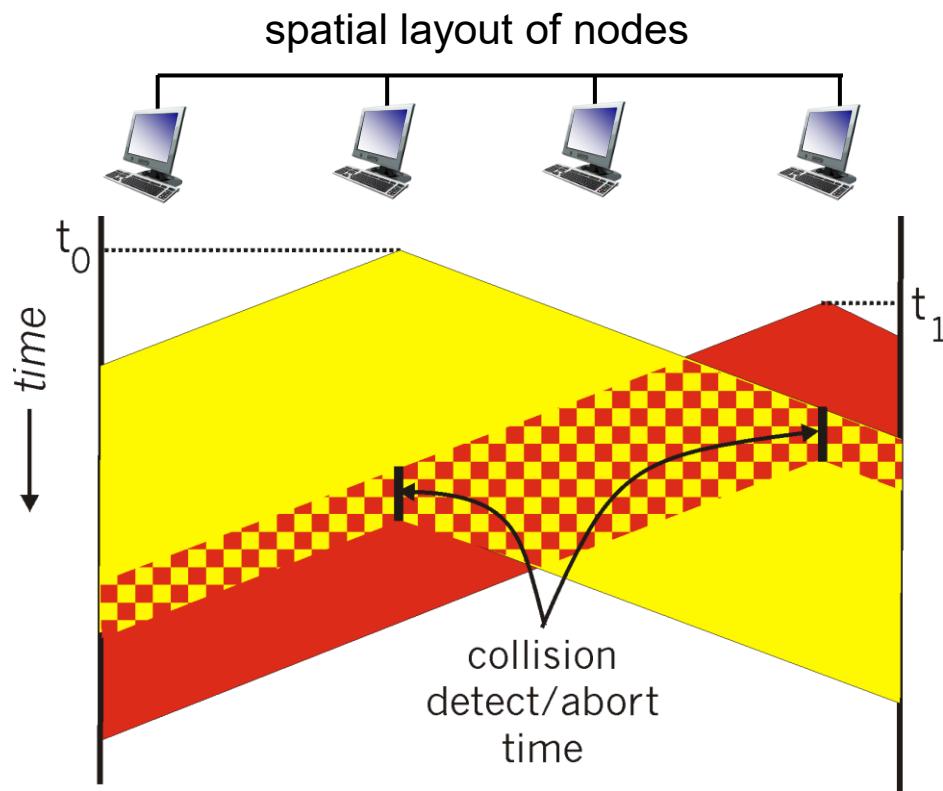


CSMA/CD (collision detection)

CSMA/CD: carrier sensing, deferral as in CSMA

- collisions detected within short time
- colliding transmissions aborted, reducing channel wastage
- ❖ collision detection:
 - easy in wired LANs: measure signal strengths, compare transmitted, received signals
 - difficult in wireless LANs: received signal strength overwhelmed by local transmission strength
- ❖ human analogy: the polite conversationalist

CSMA/CD (collision detection)

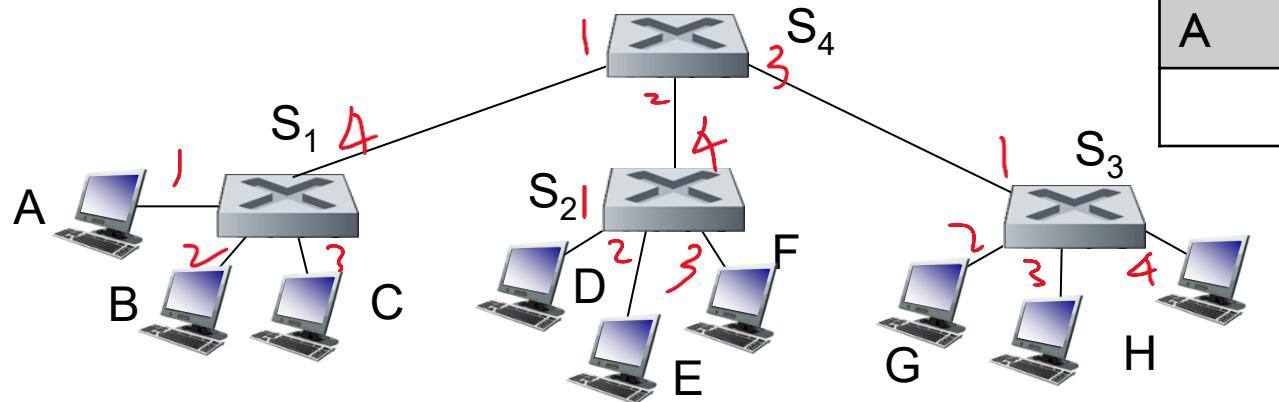


P3

- When the bits transmitted by a node A have yet to reach another node B, the latter senses the channel idle and in accordance with the CSMA protocol begins transmitting its frame. A short time later, B's transmission begins to interfere with A's transmission.

P4: Self-learning multi-switch example

- ❖ A sends frame to G: Flooding through S_1 , S_4 , S_3
- ❖ G responds to A: Selectively send through S_3 , S_4 , S_1



S_2	
MAC address	Interface
A	4

S_1

MAC address	Interface
A	I
G	4

S_4

MAC address	Interface
A	I
G	3

S_3

MAC address	Interface
A	I
G	2