

Johns Hopkins Engineering

625.464 Computational Statistics

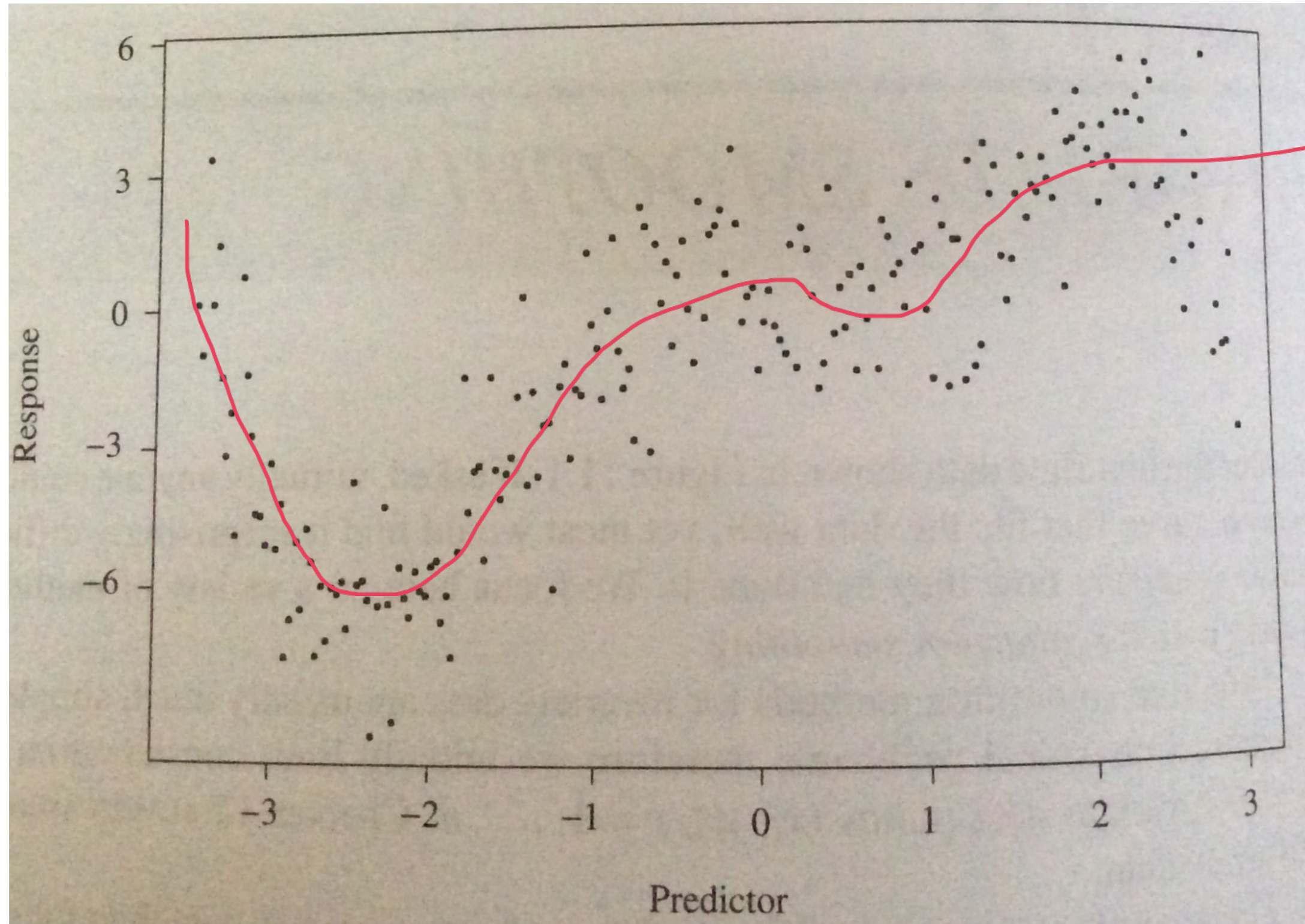
Introduction to Bivariate Smoothers

Module 12 Lecture 12A



JOHNS HOPKINS
WHITING SCHOOL
of ENGINEERING

Introduction to Bivariate Smoothing



Bivariate Smoothing

Suppose we have n bivariate data points

$$(X_i, Y_i) \quad i=1, \dots, n$$

that are predictor-response data

if Y is assumed to be a (stochastic)

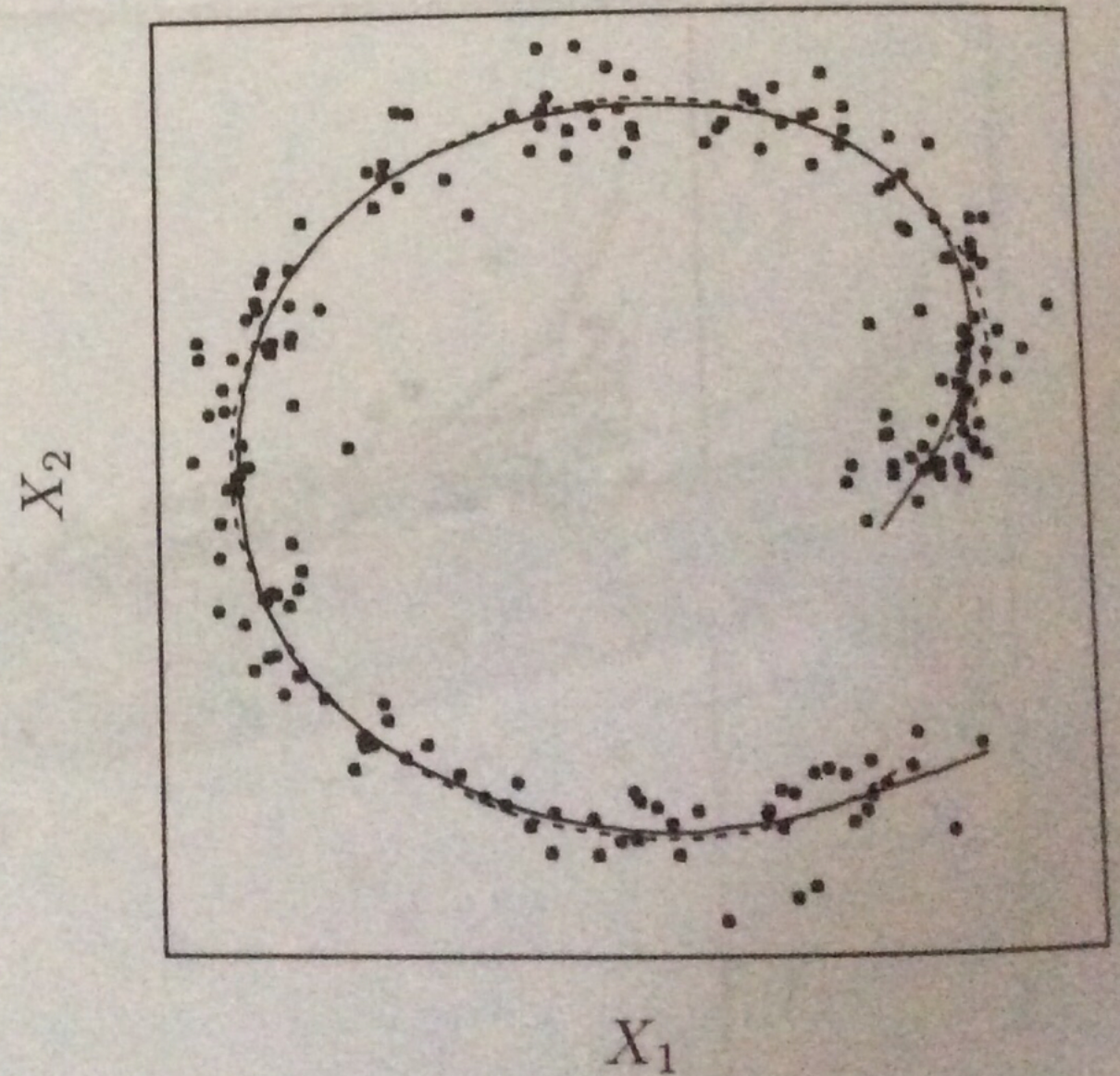
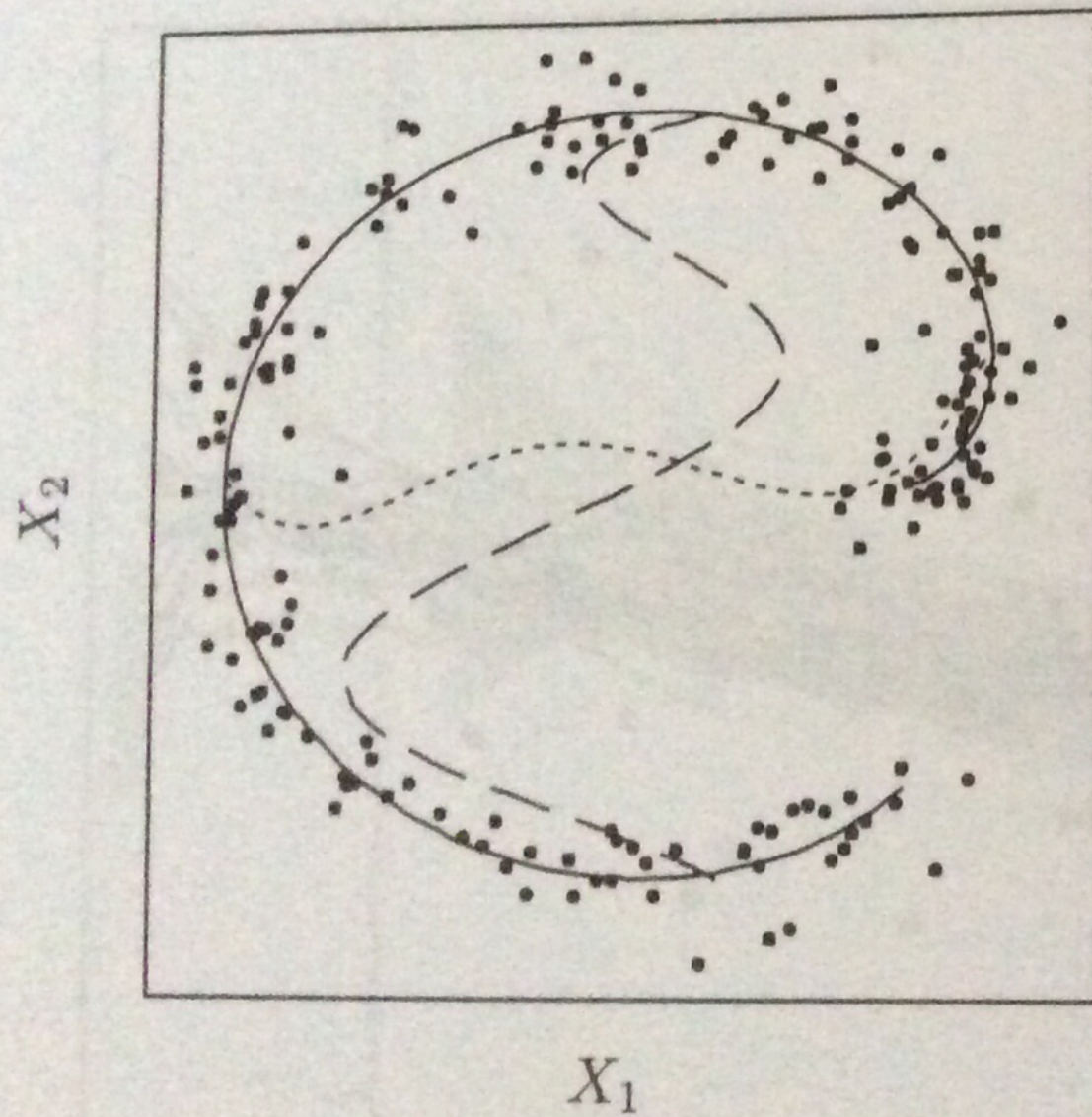
function of X

Ex/ $Y_i = S(X_i) + \epsilon_i$

\nearrow smooth function \nearrow stochastic noise mean 0

Then cond dist $Y|X$ describes how Y depends on $X=x$ and is a possible choice for smoother.

Why we use Predictor Response Dats



$$(x(t), y(t)) = ((1 - \cos t) \cdot \cos t, (1 - \cos t) \cdot \sin t)$$

Predictor Response Data

Suppose we have P-R data (x_i, y_i) and $E[Y|X] = S(X)$ for a smooth function S .

The Goal: Estimate $S(\cdot)$

smoother $\hat{S}(x)$.

↳ based on data (x_i, y_i) and also a user specified smoothing parameter λ .

$$\hat{S}_\lambda(x)$$

Two Metrics for Predictor Response Data

For a given point x , let an estimate of $S(x)$ be $\hat{S}_\lambda(x)$. How do we know if $\hat{S}_\lambda(x)$ is good?

$$\textcircled{1} \text{MSE}_\lambda(\hat{S}_\lambda(x)) = E[(\hat{S}_\lambda(x) - S(x))^2] = \\ = (\text{bias}(\hat{S}_\lambda(x)))^2 + \text{var}(\hat{S}_\lambda(x)) \quad \text{pointwise}$$

consider a new point x^* for which we predict $\hat{S}_\lambda(x^*)$

$$\textcircled{2} \text{MSPE}_\lambda(\hat{S}_\lambda(x)) = E[(Y - \hat{S}_\lambda(x^*))^2 | x = x^*] \\ = \text{var}[Y | x = x^*] + \text{MSE}_\lambda(\hat{S}_\lambda(x^*)) \quad \text{pointwise}$$

How do we construct good smoothers?

Basic idea: Want the smoother to summarize the cond dist of y_i given $x_i = x_i$ by some measure of location. //

- want $\hat{\eta}(x)$ to go through the 'center'.
- in general they rely on local averaging

smooth at $x \rightarrow$ use y_i whose

x_i are close to x .

generically: $\hat{S}_\eta(x) = \text{ave} [y_i \mid x_i \in N(x)]$

neighborhood of x

Comments on Lambda

generic smoother

$$\hat{S}_\lambda(x) = \text{ave} \{ y_i \mid x_i \in N(x) \}$$

λ will represent the span of the neighborhood $N(x)$

small $\lambda \rightarrow$ local \rightarrow higher variance

large $\lambda \rightarrow$ distant points \rightarrow introduce bias