

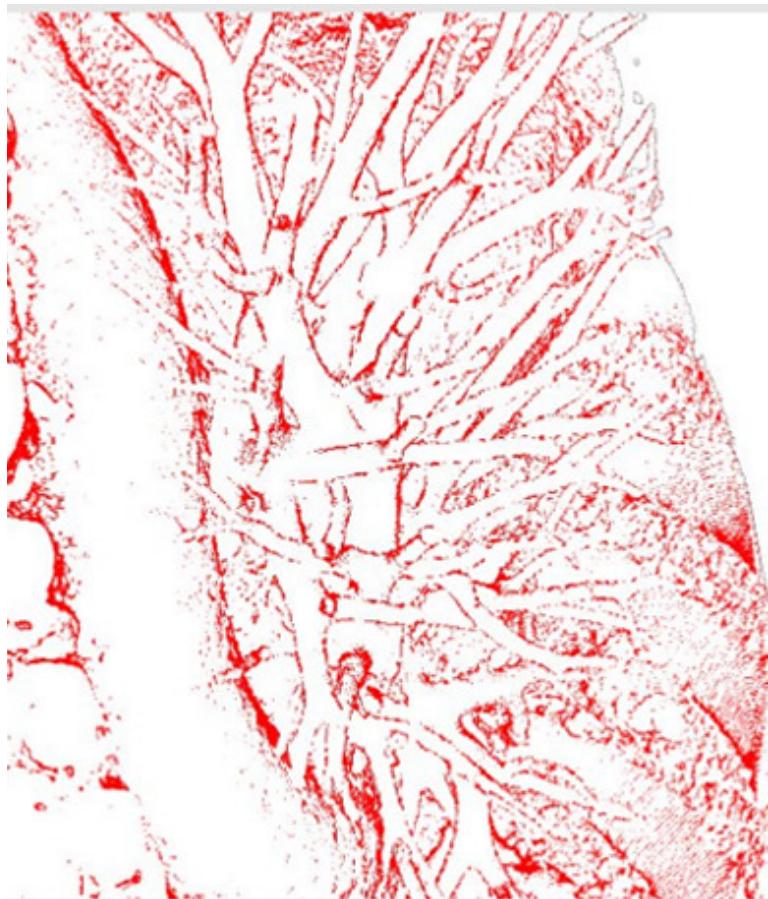
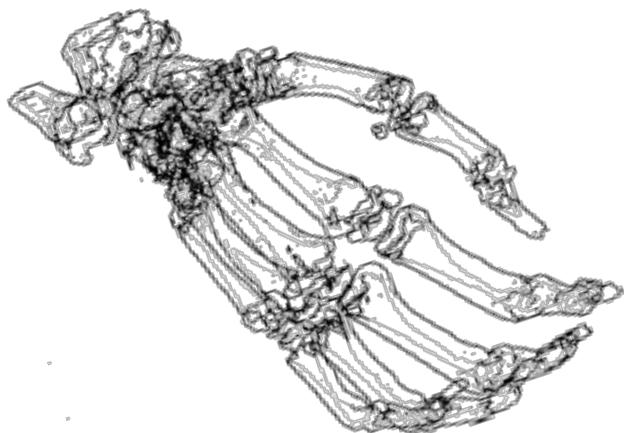


# Module #13b: **Non-Photorealistic Rendering**



# Non-Photorealistic Rendering

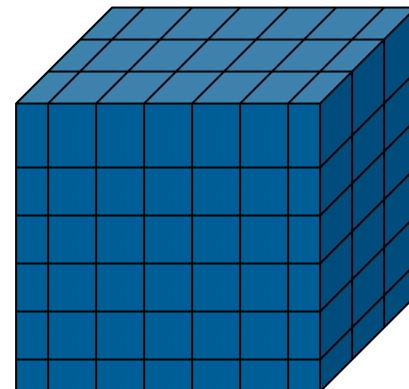
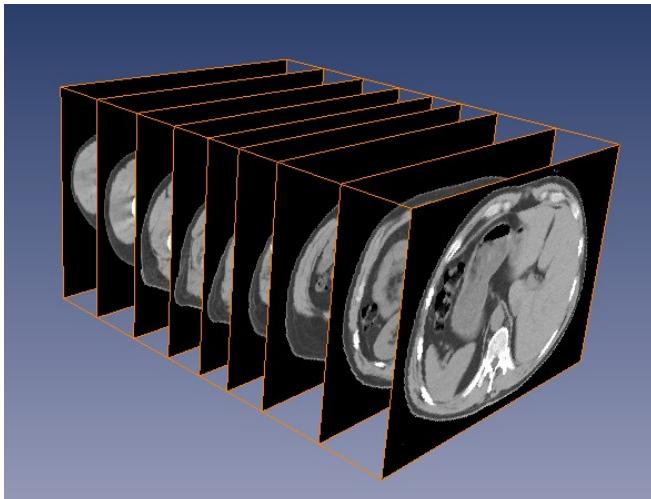
- The use of local image processing to produce artistic and illustrative effects
  - Pen-and-ink drawing
  - Silhouettes
  - Stippling
  - etc





# Volume Data Visualization

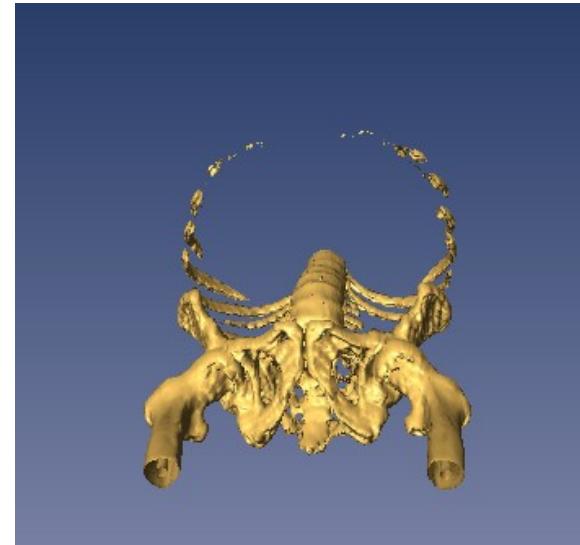
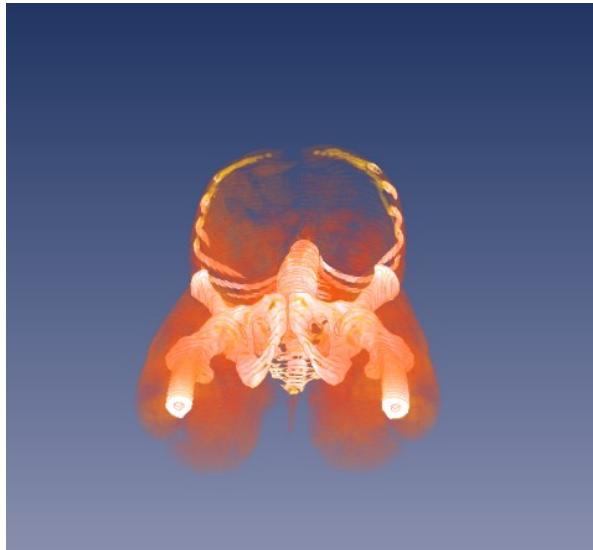
- 3D matrix of data value
- Suitable for densely sampled functions
- Traditionally expensive for storage and rendering





# Volume Visualization

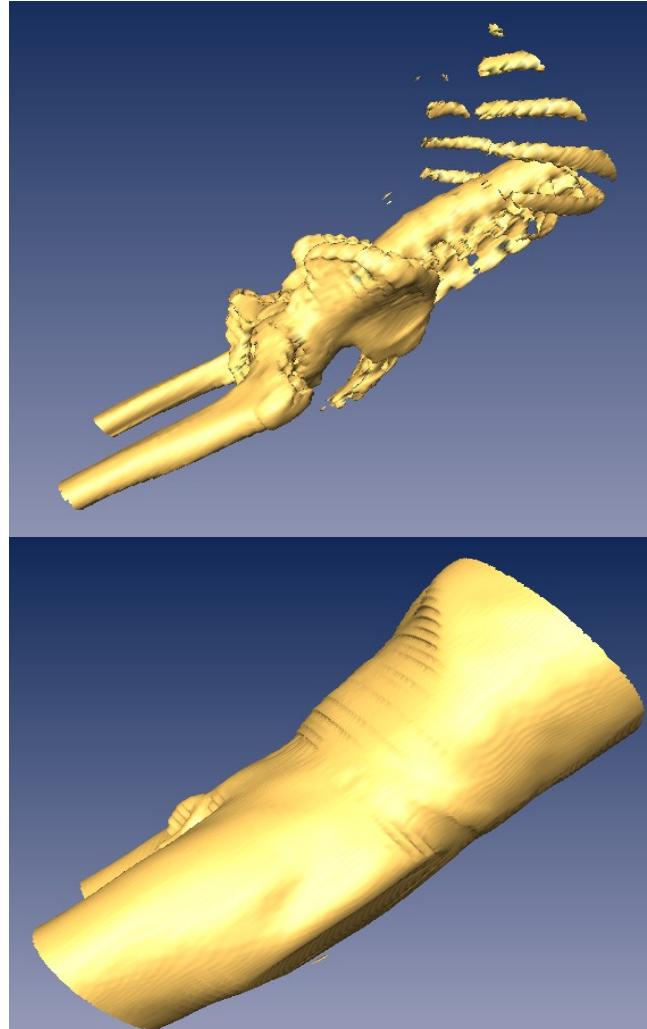
- Direct Volume Rendering
  - Transfer function (color and opacity)
- Isosurface





# Isosurface Extraction

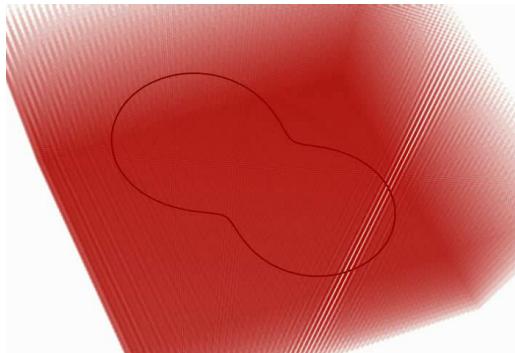
- Implicit surface that represents points of a constant value
  - Density
  - Pressure
  - Temperature
  - Velocity
- Given a threshold  $t$ 
  - Values “inside” greater than  $t$
  - Values “outside” less than  $t$





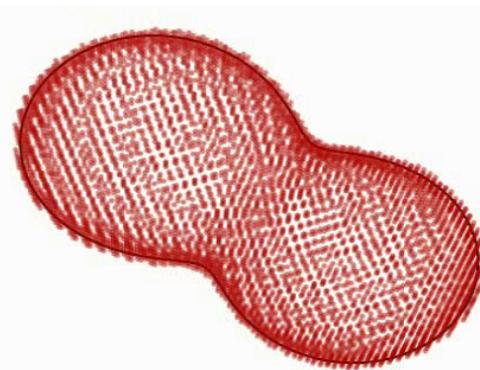
# Key Idea: Lines are Sparse

**Direct Volume  
Rendering**



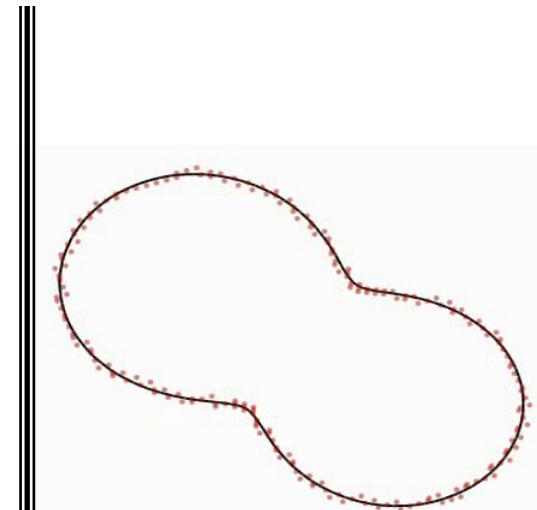
$O(\text{volume})$

**Optimized Isosurface  
Extraction**



$O(\text{surface})$

**Line Extraction**

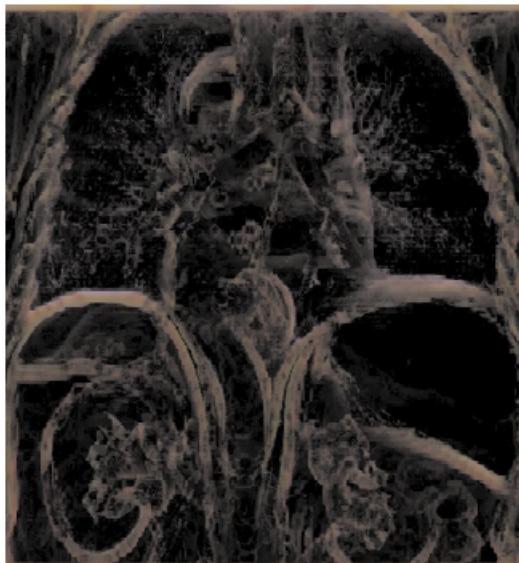


$O(\text{line})$



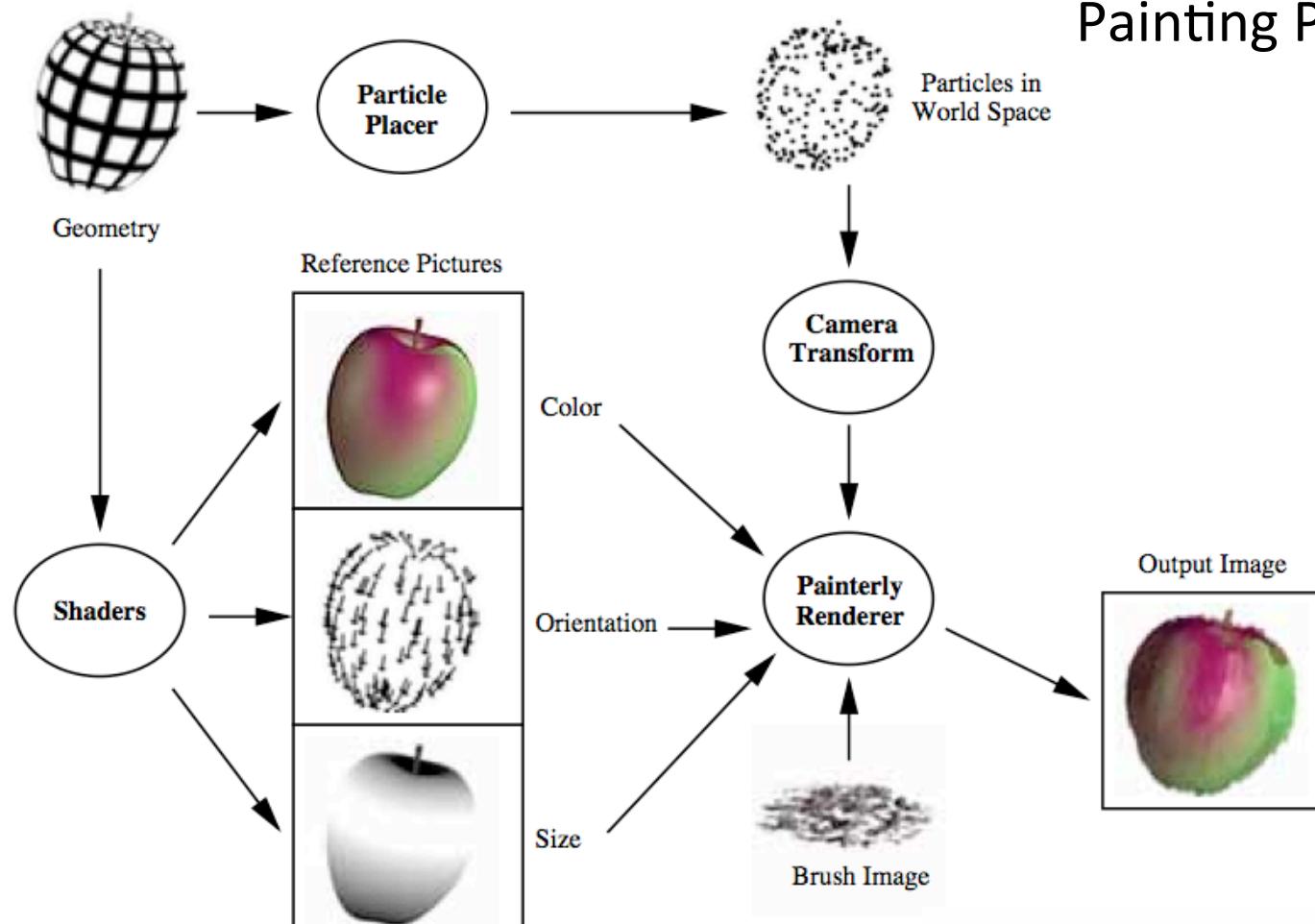
# Background

- Line Drawing from 3D Data





## Painting Pipeline

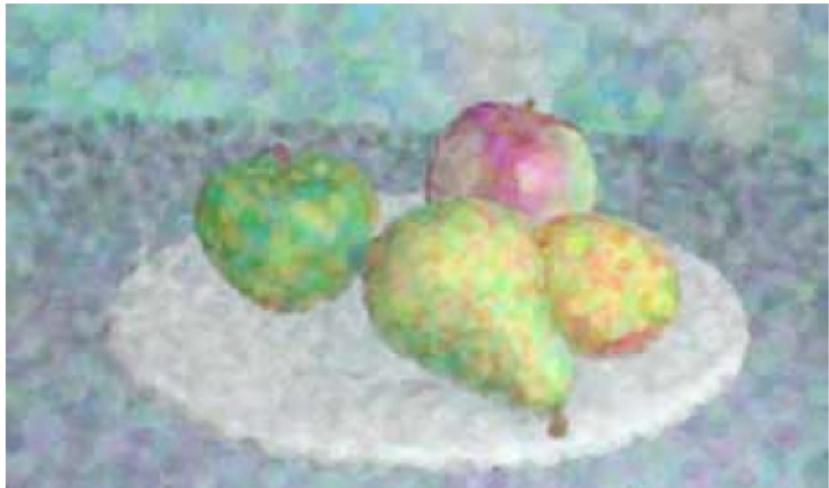


Brushes (color & opacity):





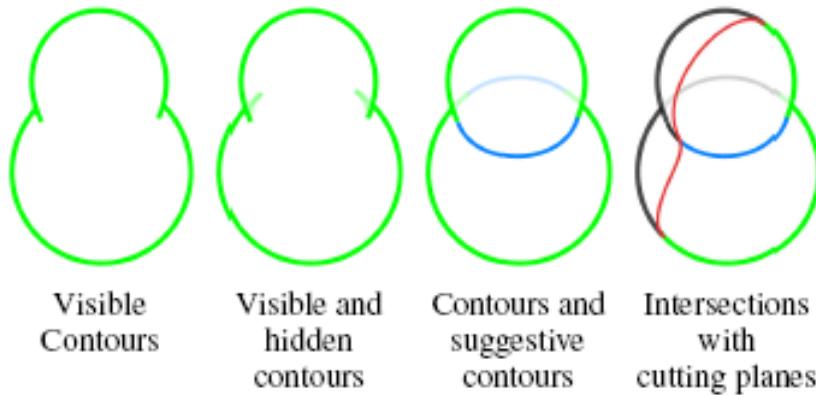
# Different Brushes and Orientation Fields





# What kind of lines?

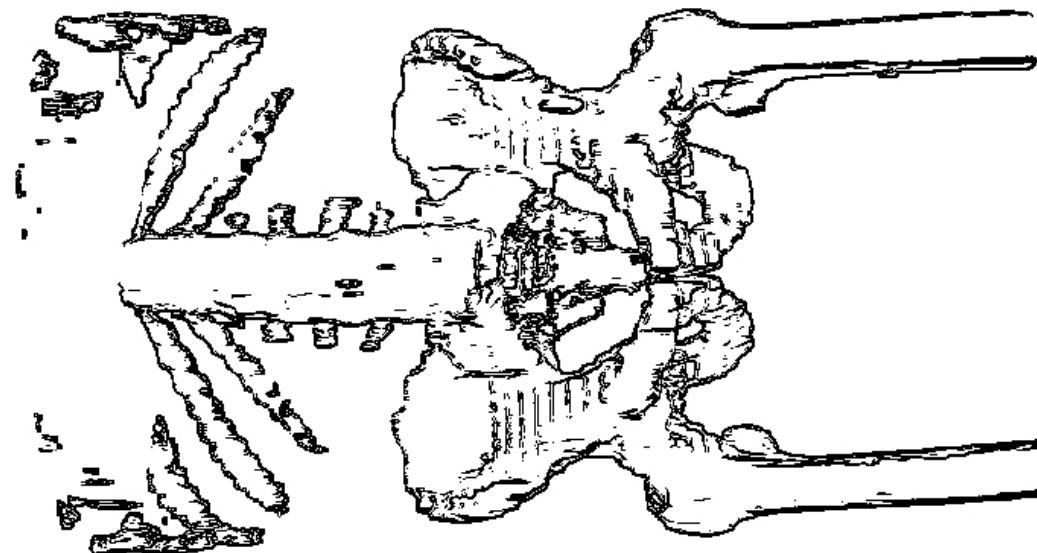
- Contours
- Suggestive Contours
- Cutting Planes





# 1. Contours

- Denote depth discontinuities
- Surface normal perpendicular to view direction
  - Definition:  $n \cdot v = 0$





## 2. Suggestive Contours

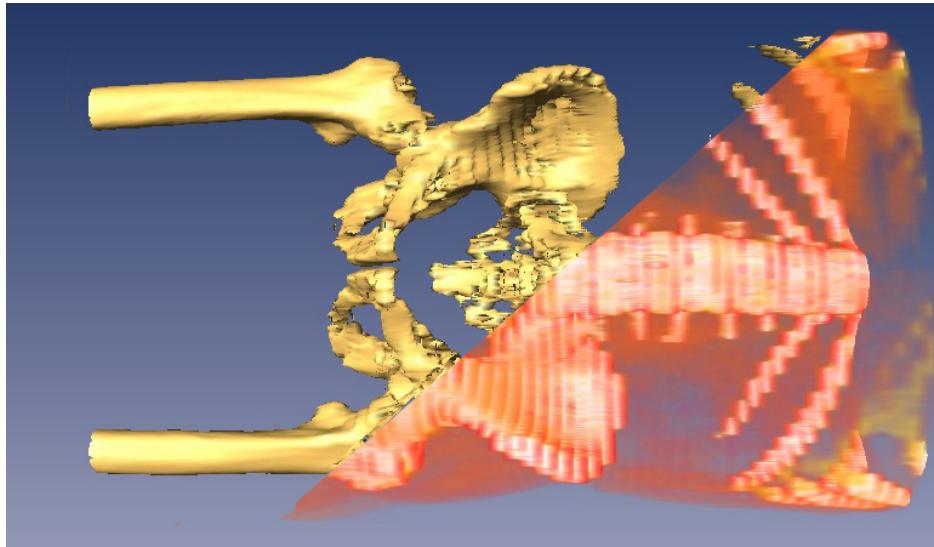
- Complement contours in line drawings to produce more effective rendering of shape.
- Definition:
  - Radial curvature zero
  - Directional derivative to camera positive





## 3. Cutting Plane

- View independent
- Intersection of cutting planes with isosurface.





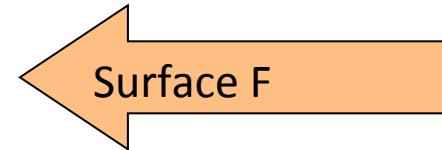
# Outline

- Background
- **Line Extraction**
- Hidden-Line Removal
- Stylization
- Conclusion



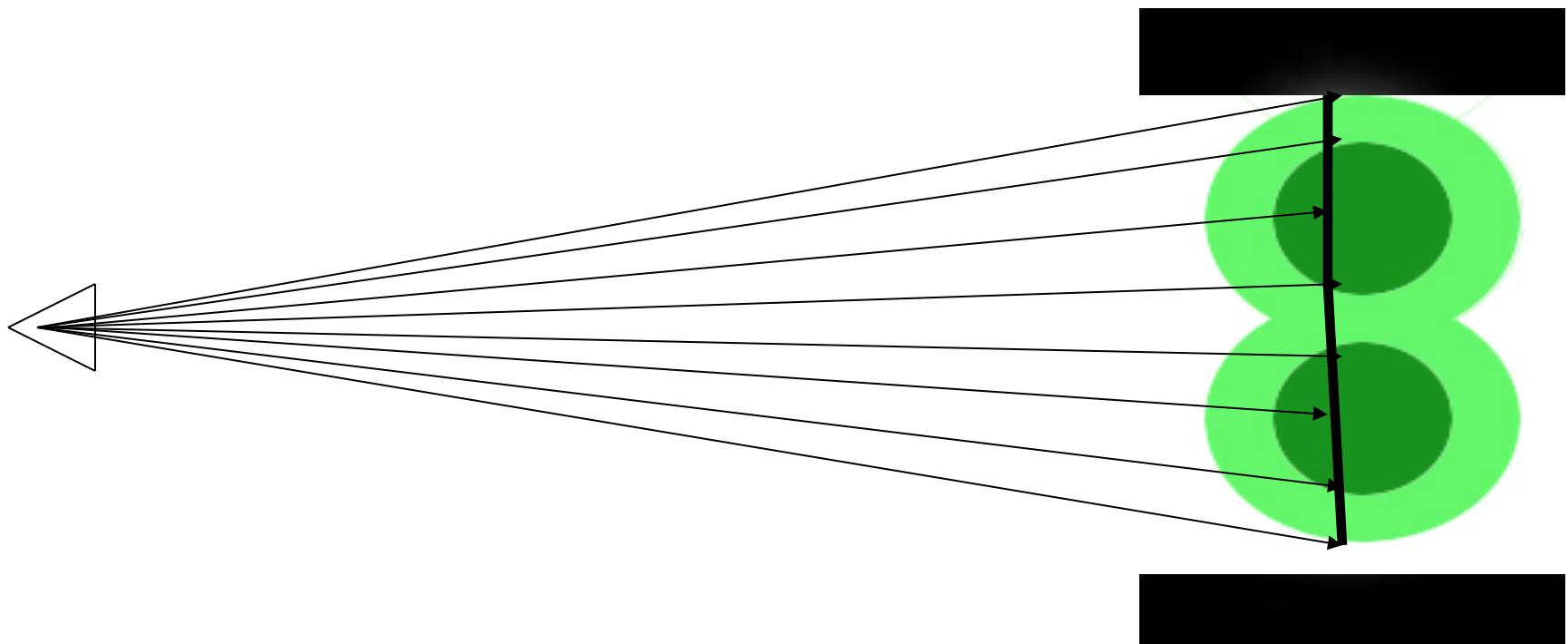
# Extracting Contours

- At surface contours:  $n \circ v = 0$
- Let  $\alpha(i,j,k)$  is a volume (3D matrix)
  - Isosurface at threshold  $t$ :
    - $f(i, j, k) = \alpha(i,j,k) - t$
  - Isosurface *normal* at point  $p$ :
    - $N(p) = \Delta f(p)$
  - Surface containing contours at all isovalues
    - $N(p) \circ v(p) = 0$



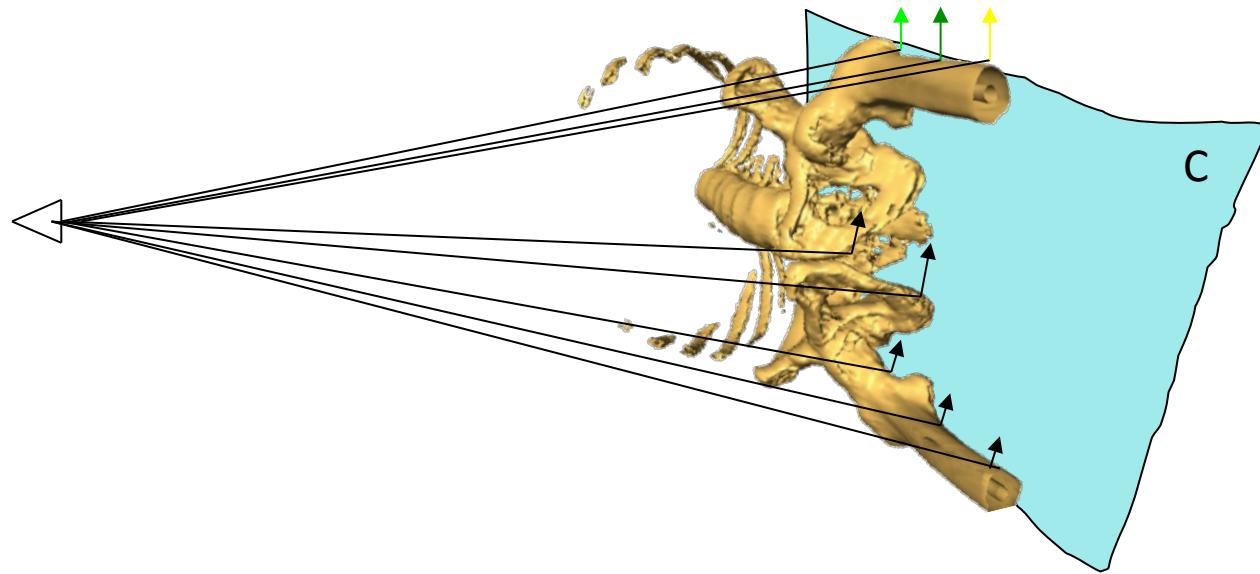


# Extracting Contours





# Extracting Contours

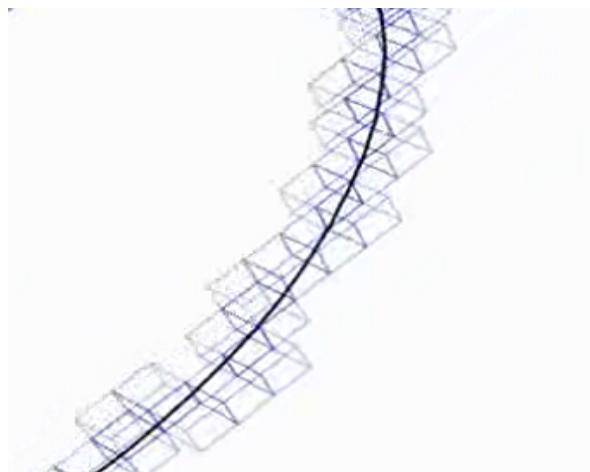
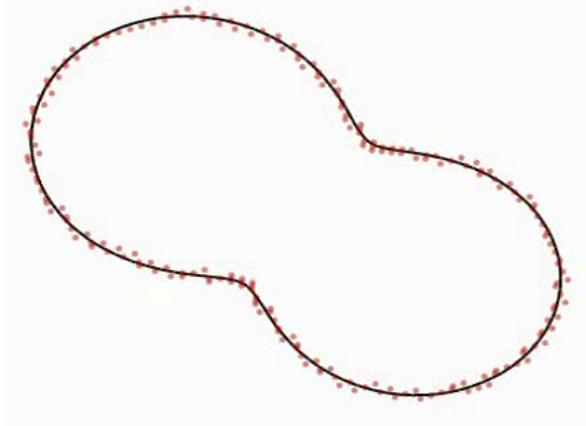


- Contours at intersection between **F** and **C**
- Lines
  - Surface intersection between this isosurface and contours surface.



# Extra Lines

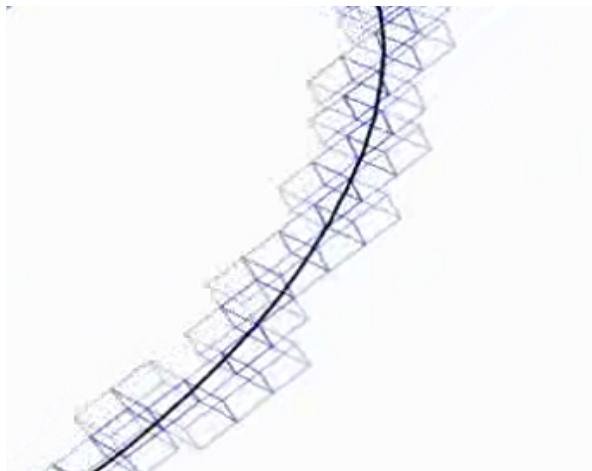
- Brute force  $O(n^3)$
- Optimization
  - Locate seed cells
  - Proceeding to neighbor cells by extending end points of the line segment at seed cell.





# Search for seeds

- Probe random cells
- Gradient Descent
  1. From voxel P, take steps proportional to the *negative* of the **gradient**
  2. From voxel P', find descent using  $\mathbf{n} \circ \mathbf{v}$





# Other Line Types

- Suggestive contours
  - Recall: Radial curvature zero
  - Intersect isosurface  $S$  with  $K_r = 0$
- Cutting plane intersections
  - Intersect isosurface  $S$  with  $Ax + By + Cz - D = 0$





# Outline

- Background
- Lines Extraction
- **Hidden-Line Removal**
- **Stylization**
- Results
- Conclusion



# Hidden-Line Removal

- Large number of lines
  - Hard to distinguish which surfaces are closer to the camera
- Solution
  - Detecting surfaces occluded by isosurfaces closer to the camera
  - Remove them



# Hidden-Line Removal

- Solution #1:
  - For each line segment:
    - Trace a ray through the cells towards the camera
    - Test for isosurface intersection
  - Complexity  $O(n^2)$
- Solution #2:
  - Approximate visibility every  $k^{\text{th}}$  voxels



# Approximate Visibility



Stride = 1 (590 msec./frame)

Stride = 2 (370 msec./frame)



Stride = 4 (280 msec./frame)

Stride = 8 (244 msec./frame)

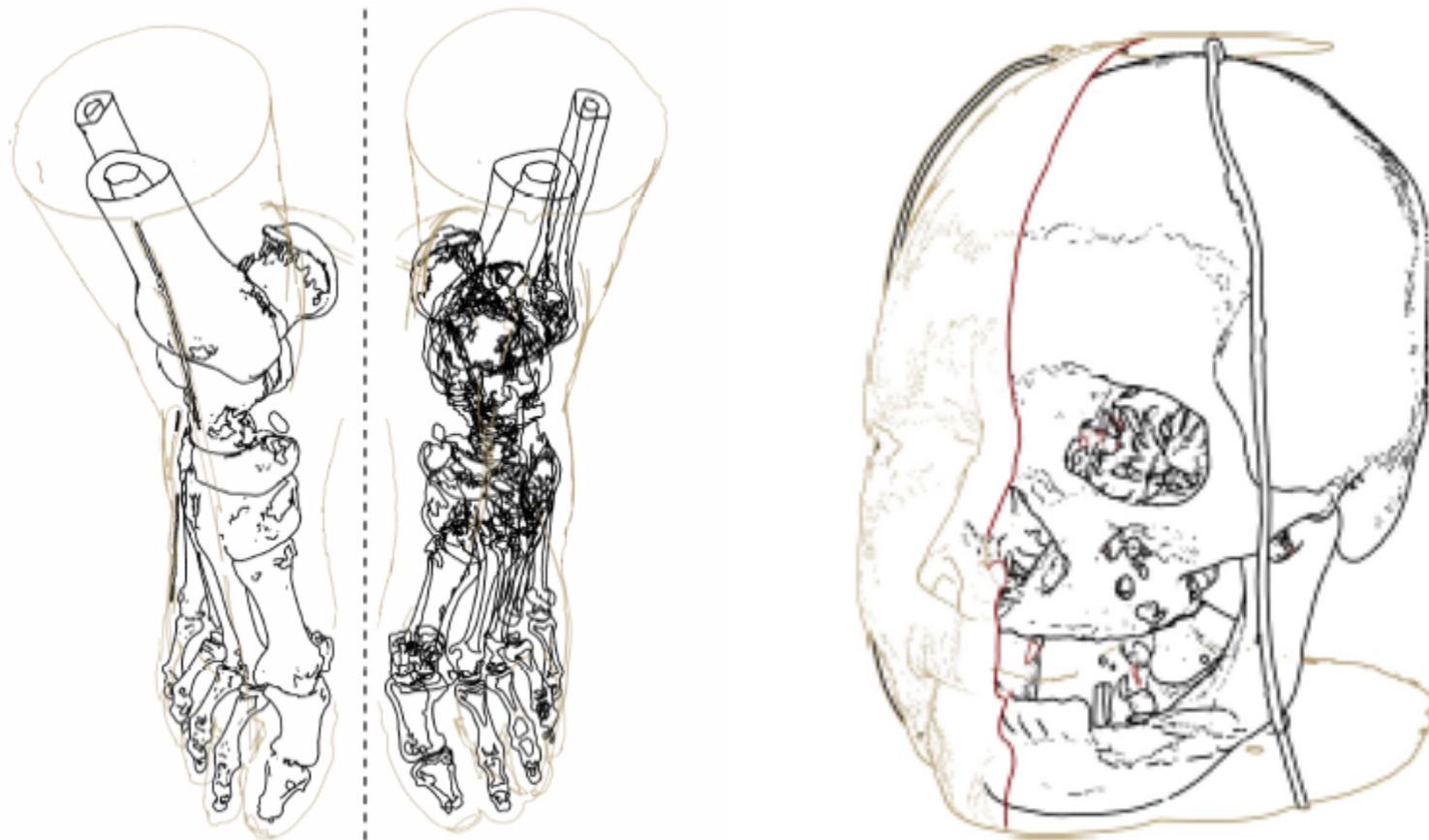


# Stylization

- Color, width, opacity, modulated by:
  - Line type
    - Contour
    - suggestive contours
    - cutting plane
  - Isovalue
  - Occlusion test
  - Cutting plane test
  - Back-facing test



# Multiple Isovalues





# Bonsai



Silhouettes



Suggestive Contours



Different  
isovalue

Michael Burns, Janek Klawe, Szymon Rusinkiewicz, Adam Finkelstein, Doug DeCarlo  
ACM Transactions on Graphics (Proc. SIGGRAPH), August 2005



# Non-photorealistic Volume Rendering

