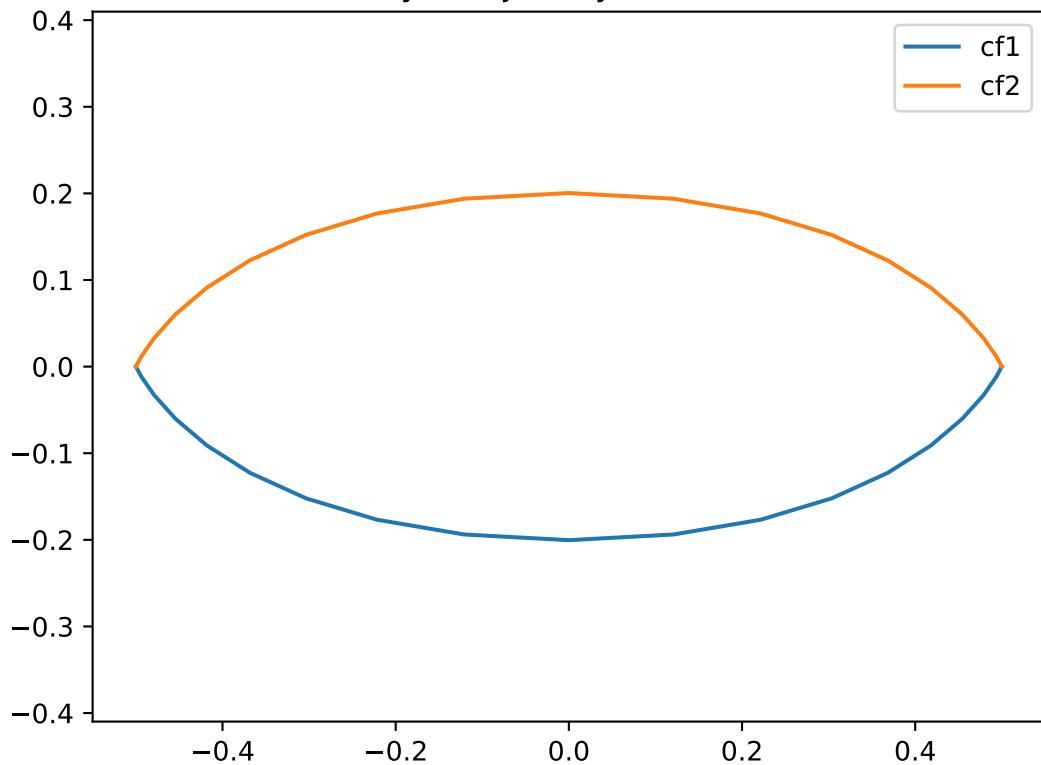
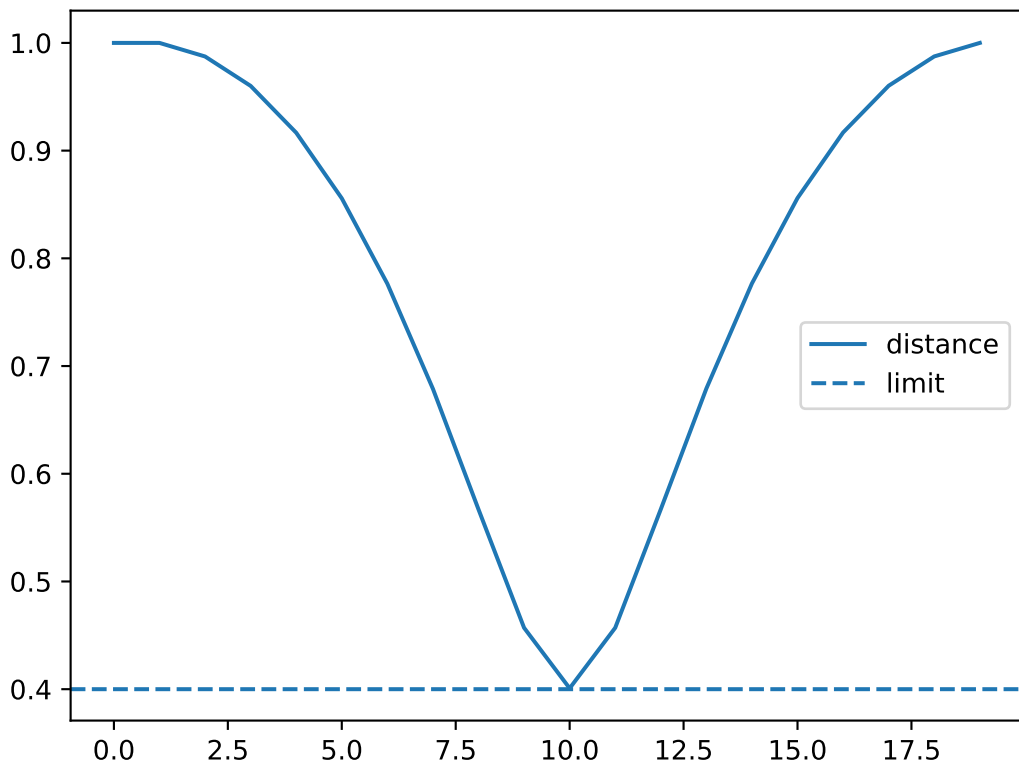


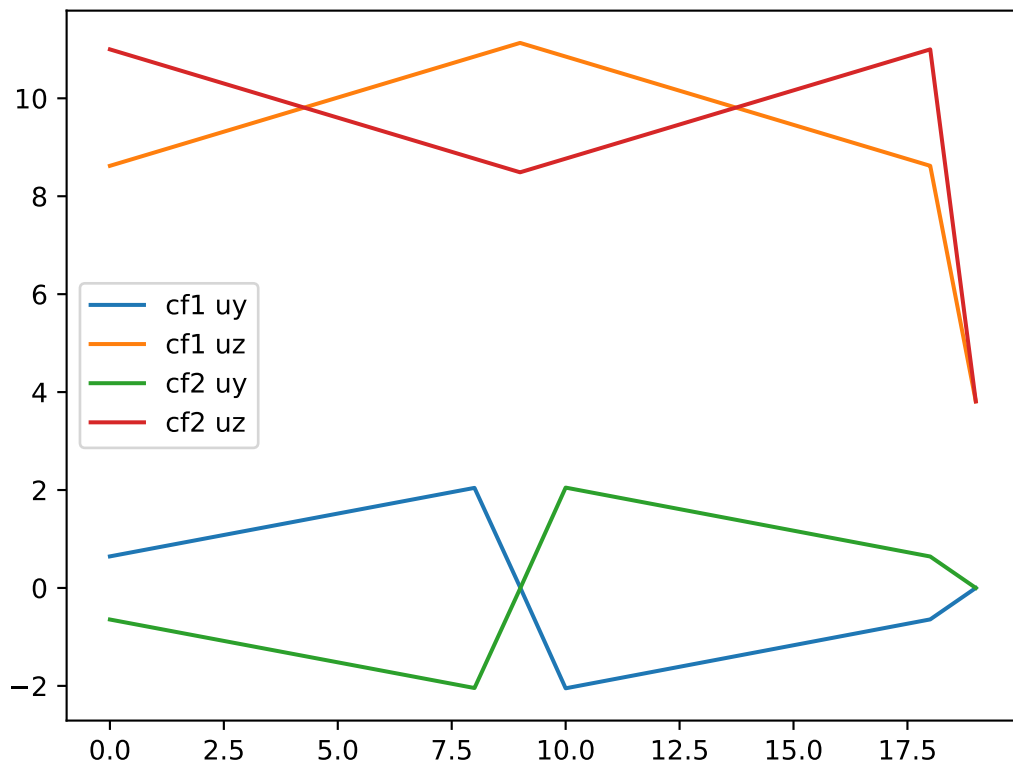
y-z trajectory (initial)



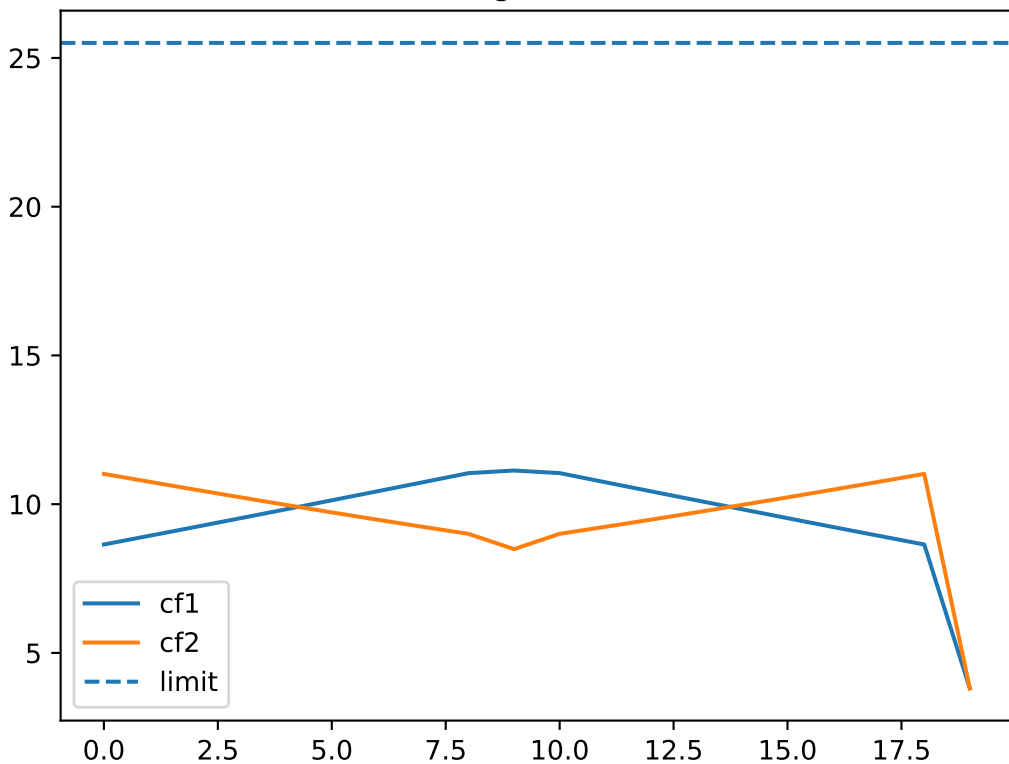
distance (initial)



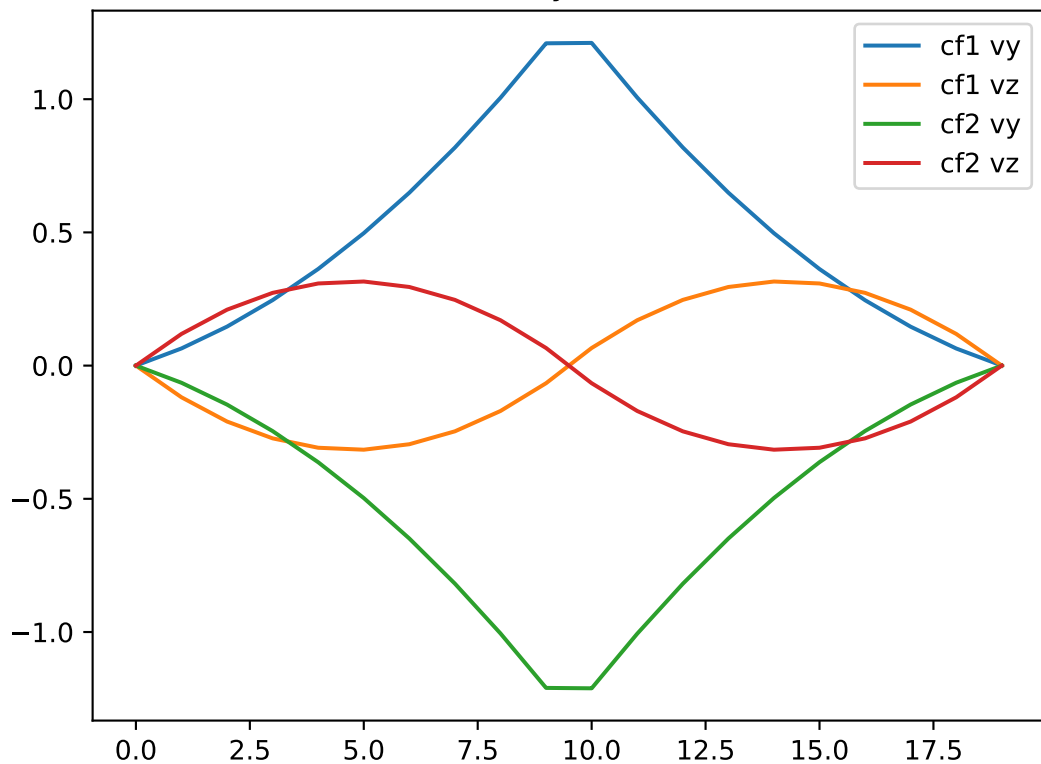
control (initial)



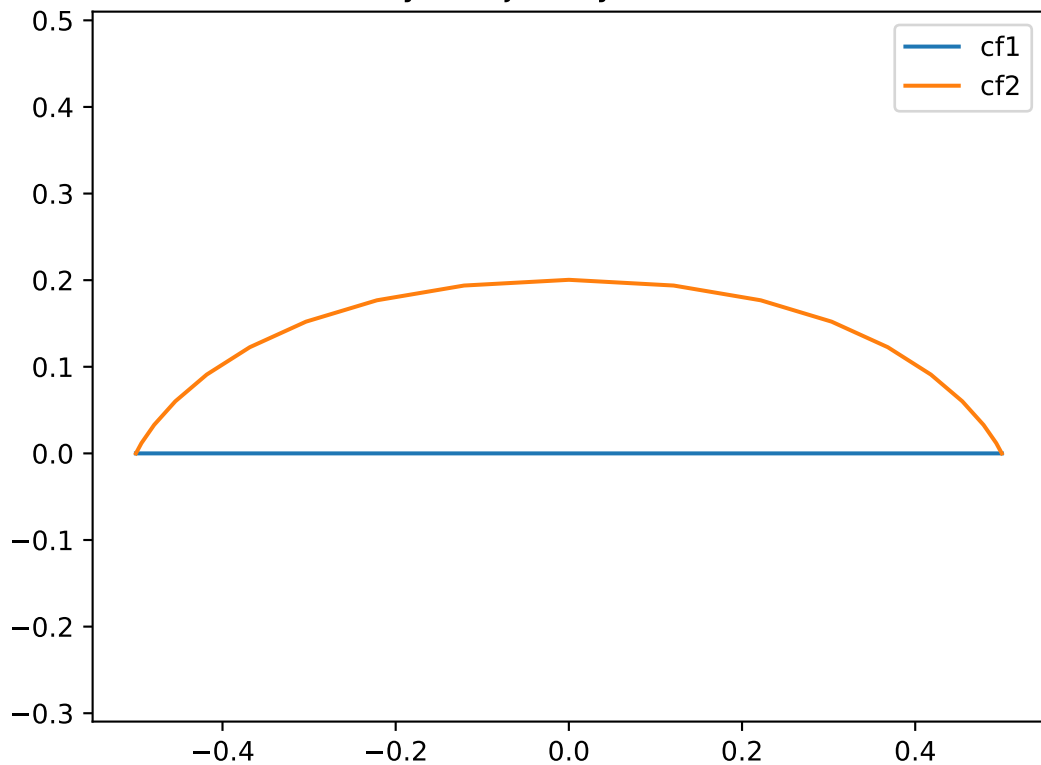
thrust magnitude (initial)



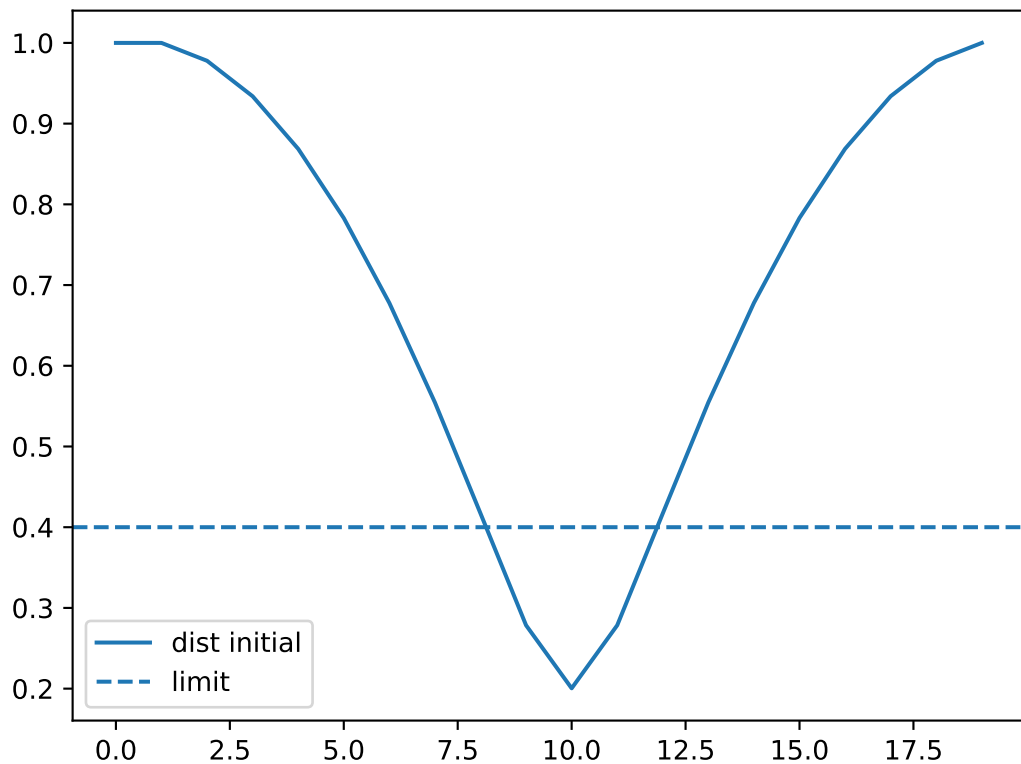
velocity (initial)



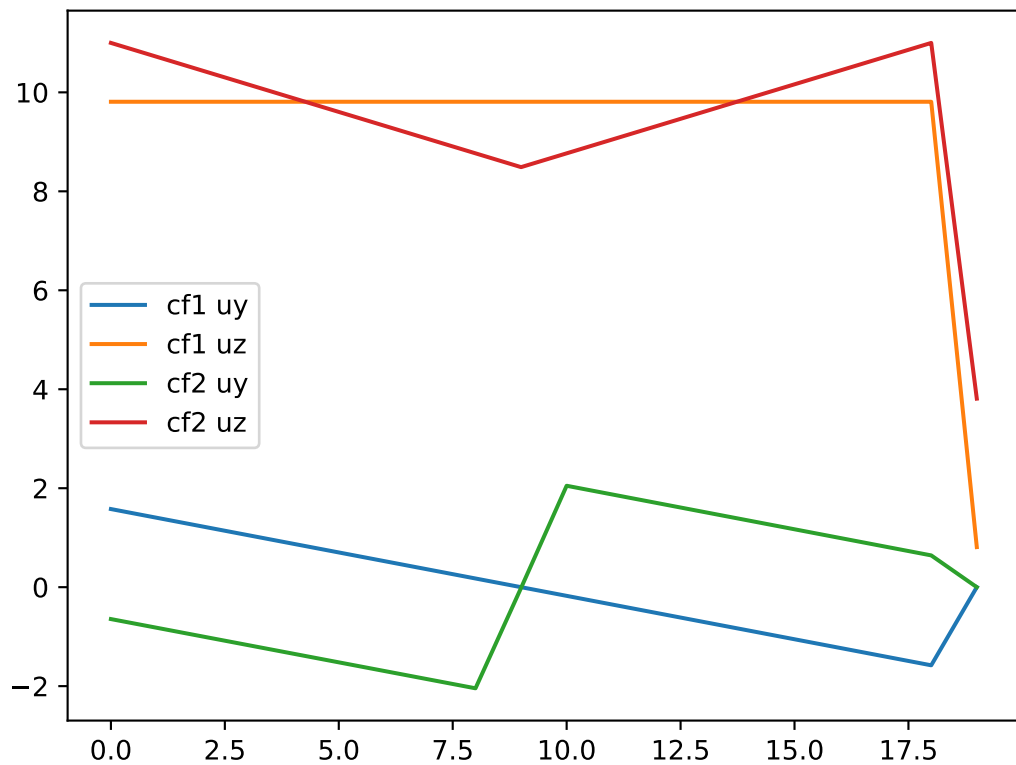
y-z trajectory (iter 0)



distance (iter 0)

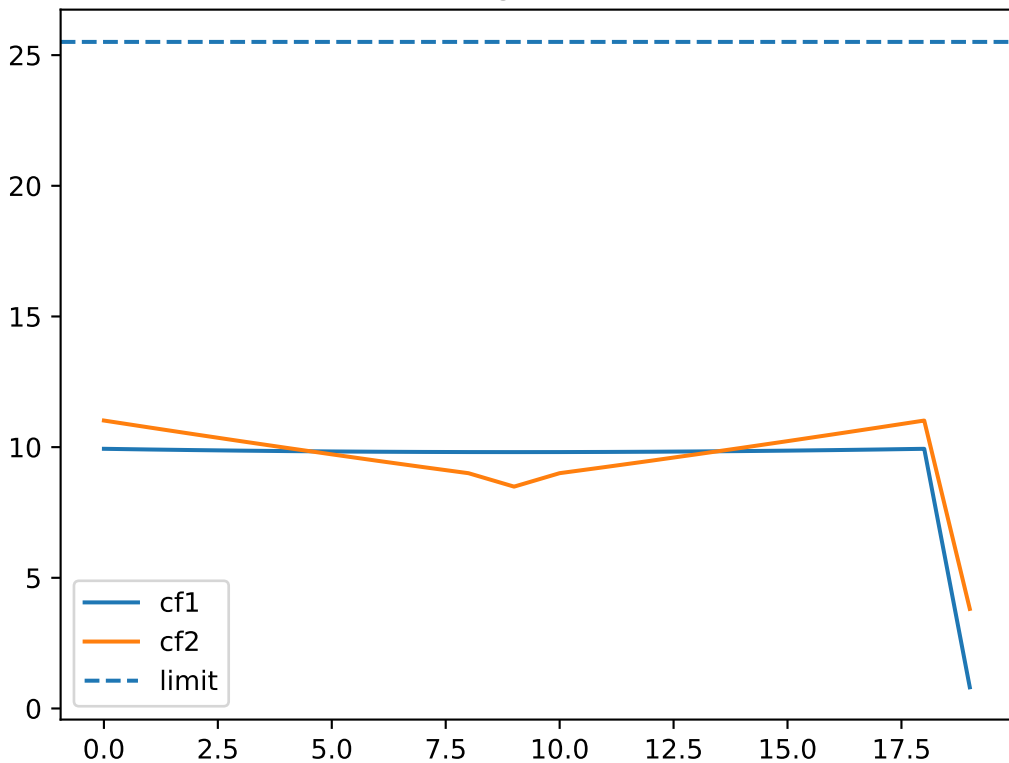


control (iter 0)

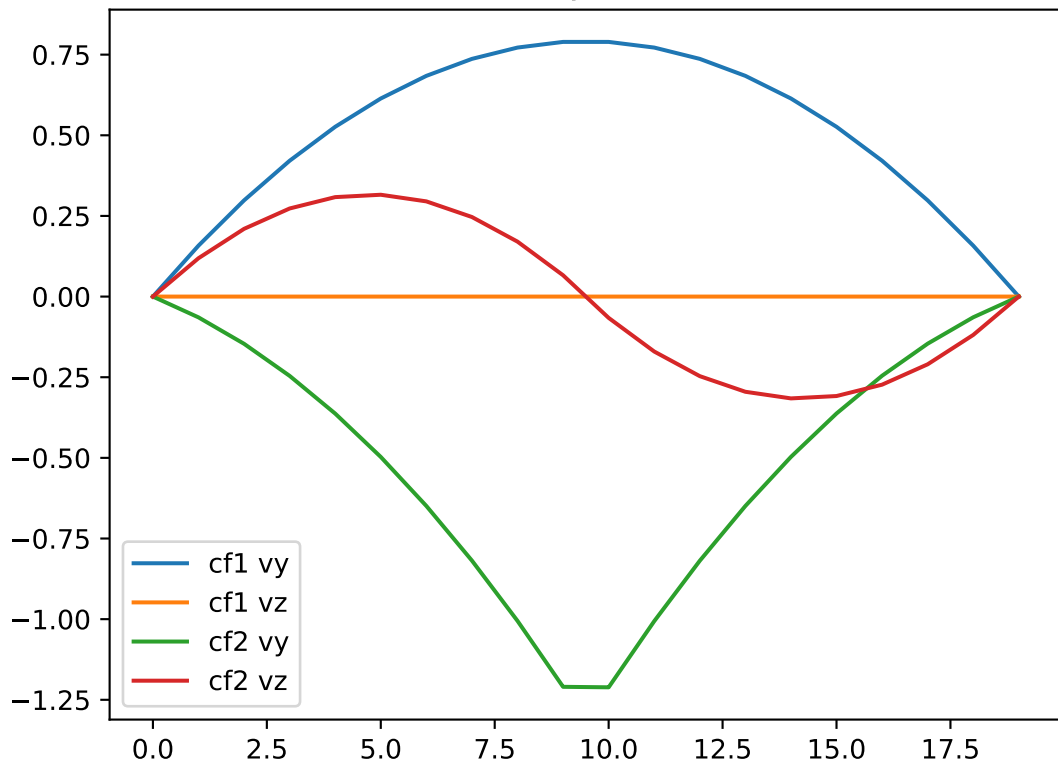




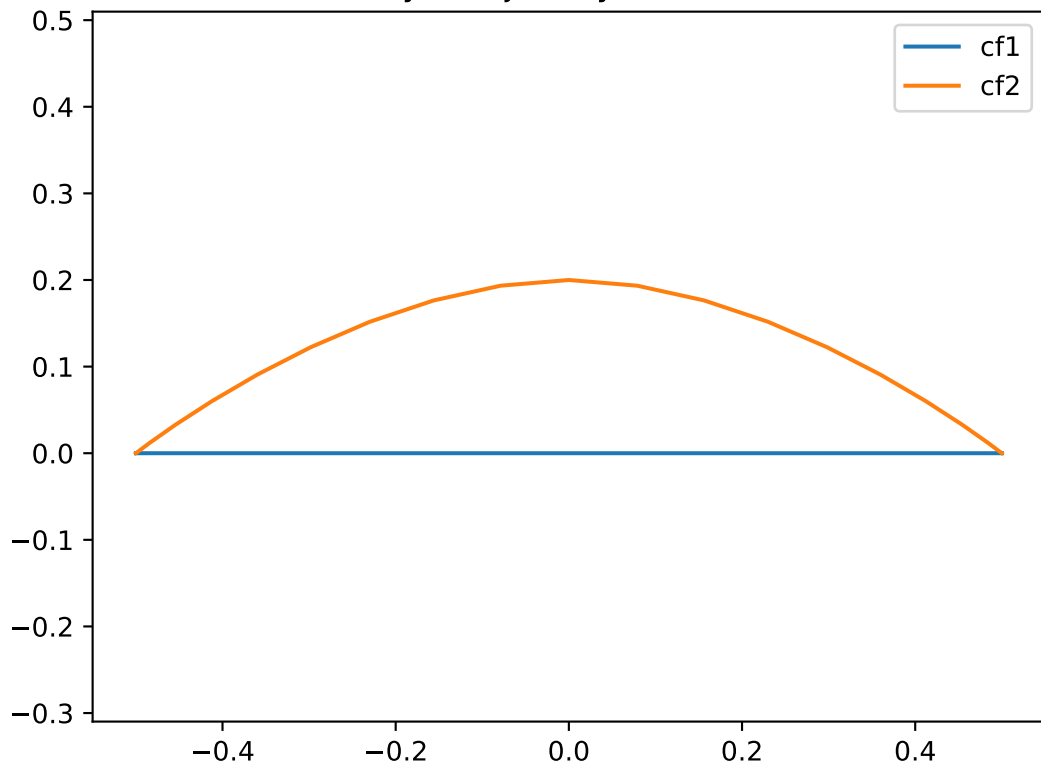
thrust magnitude (iter 0)



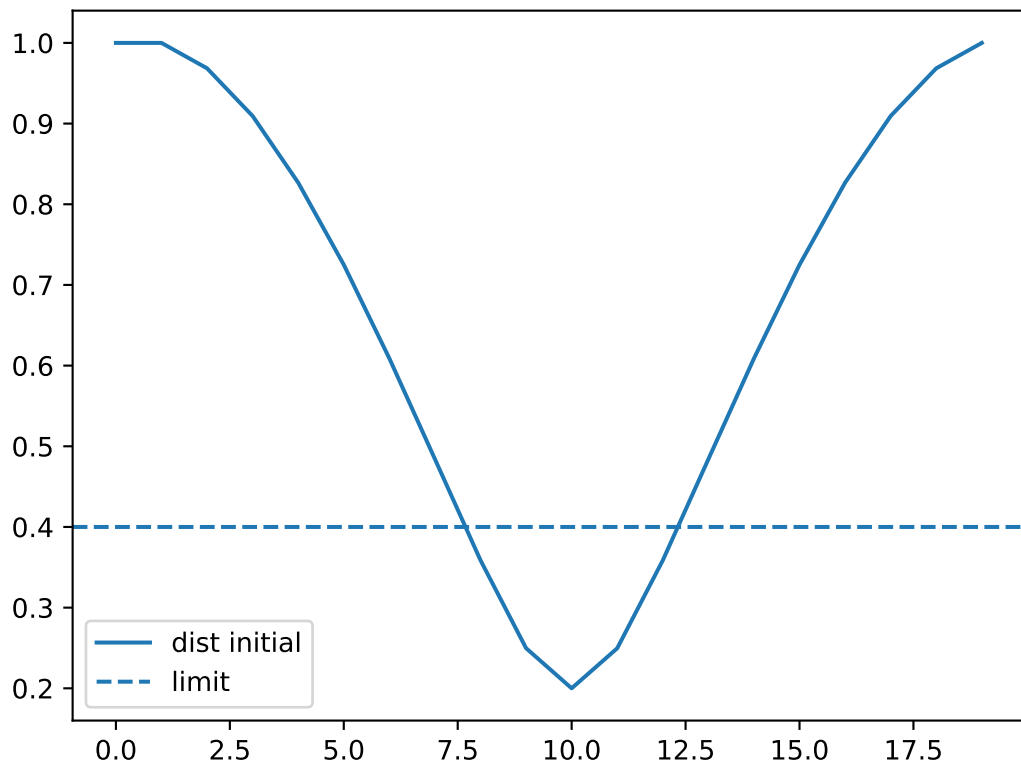
velocity (iter 0)



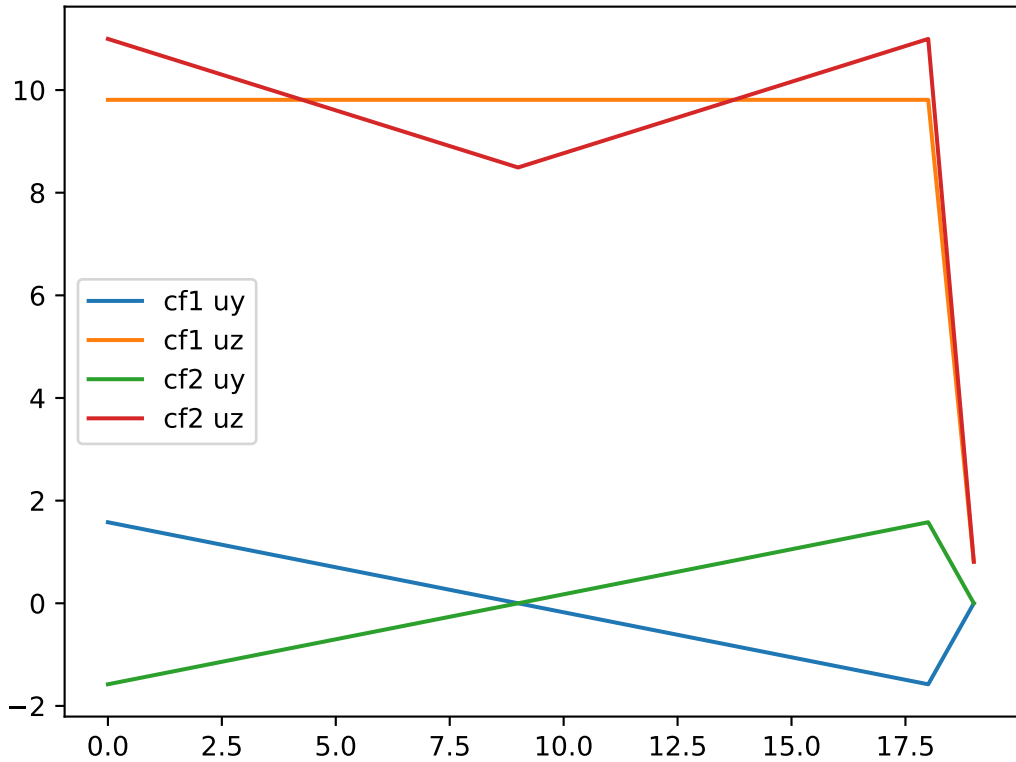
y-z trajectory (iter 1)



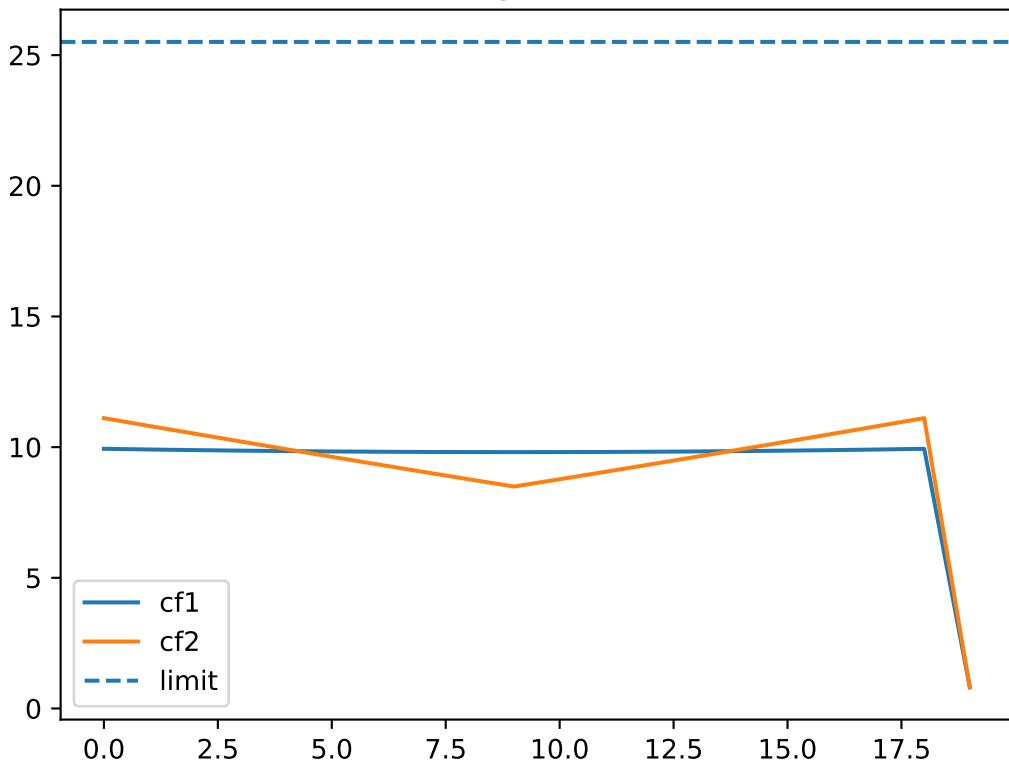
distance (iter 1)



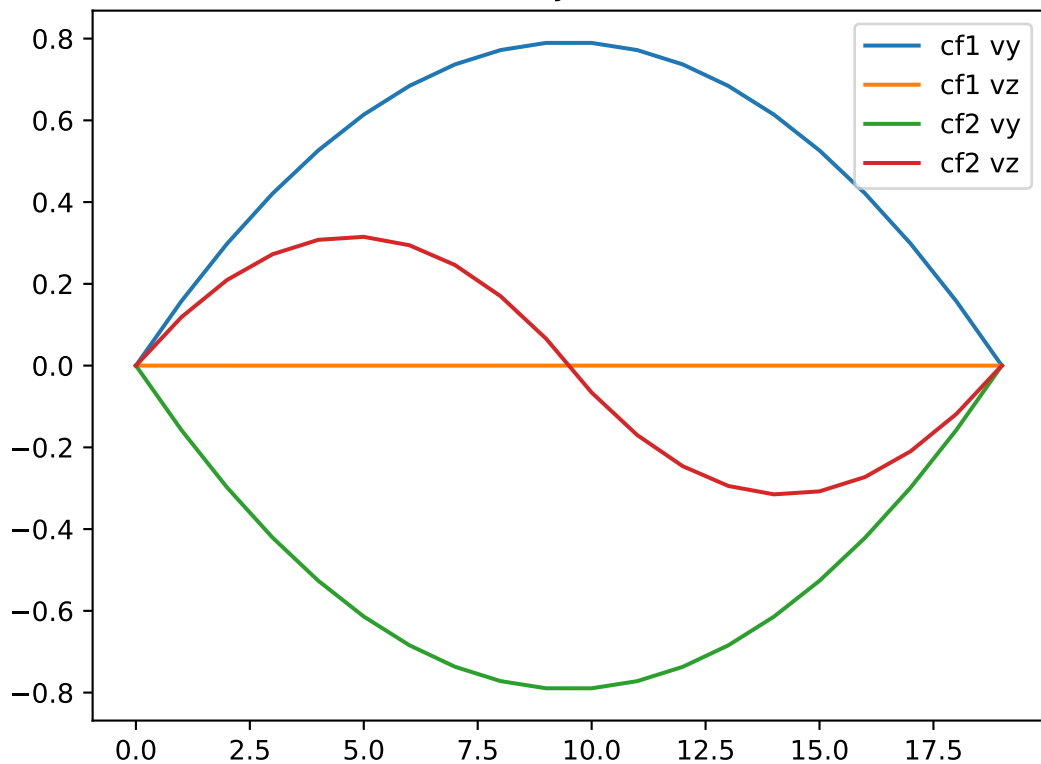
control (iter 1)



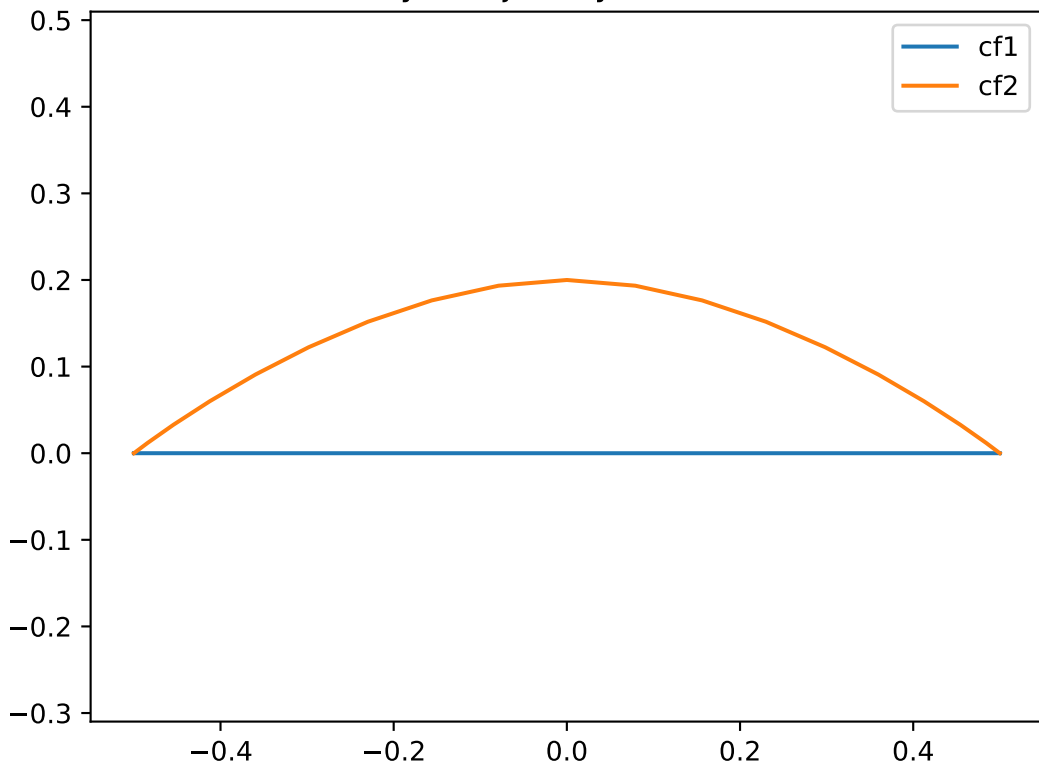
thrust magnitude (iter 1)



velocity (iter 1)

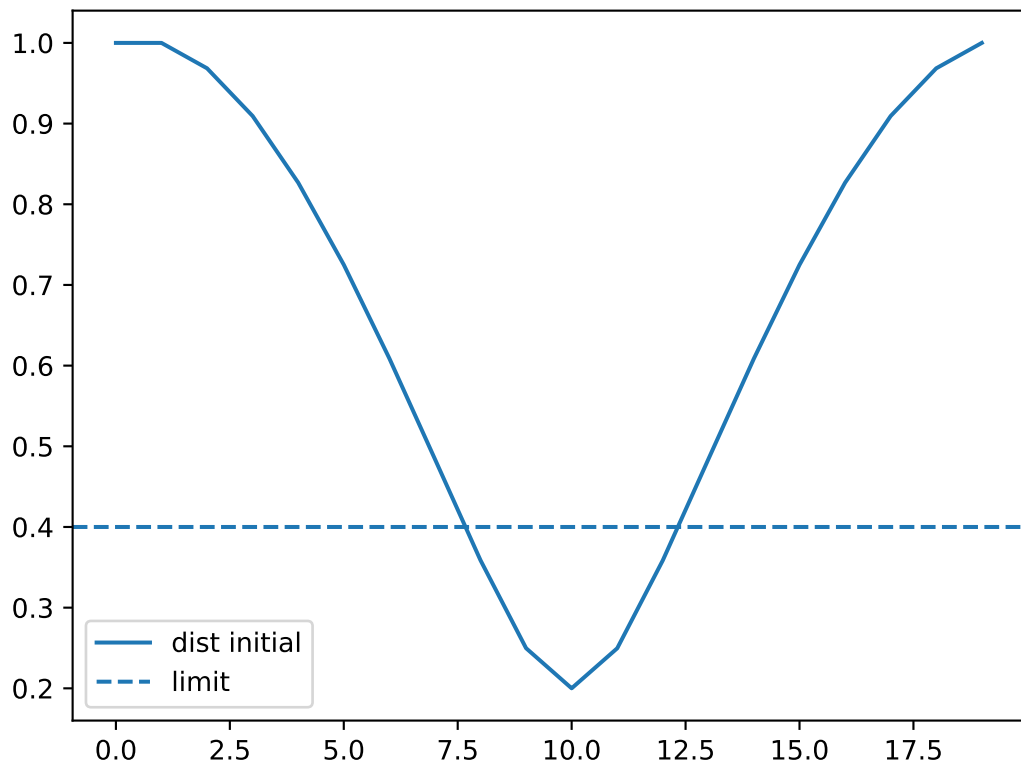


y-z trajectory (iter 2)

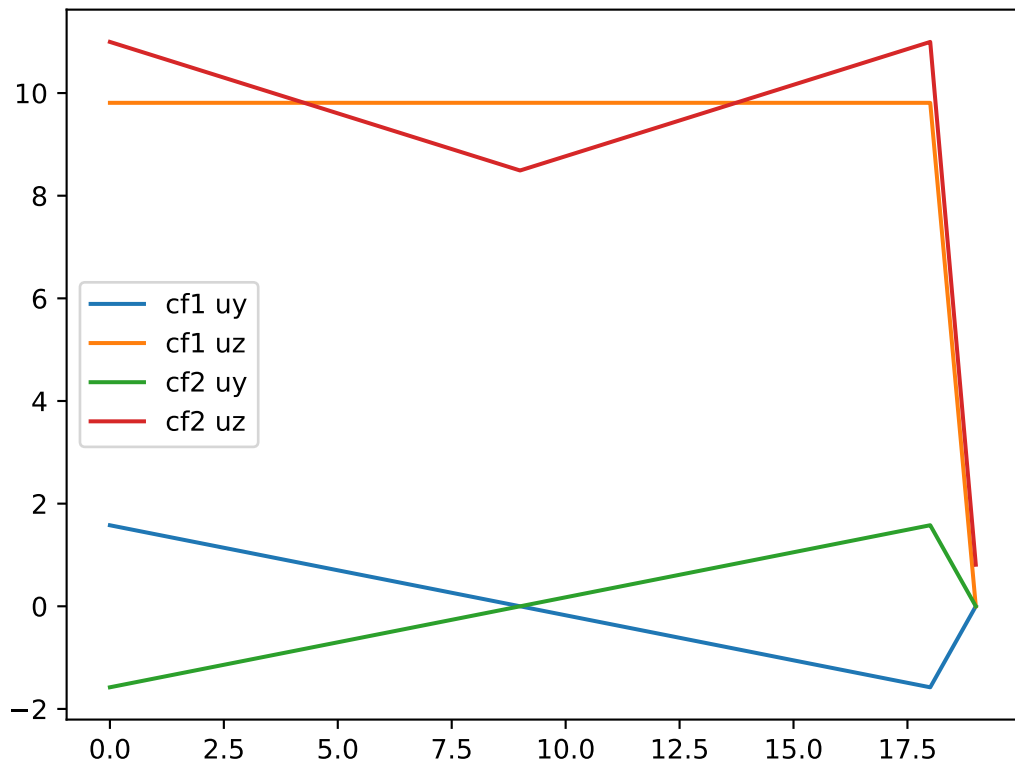




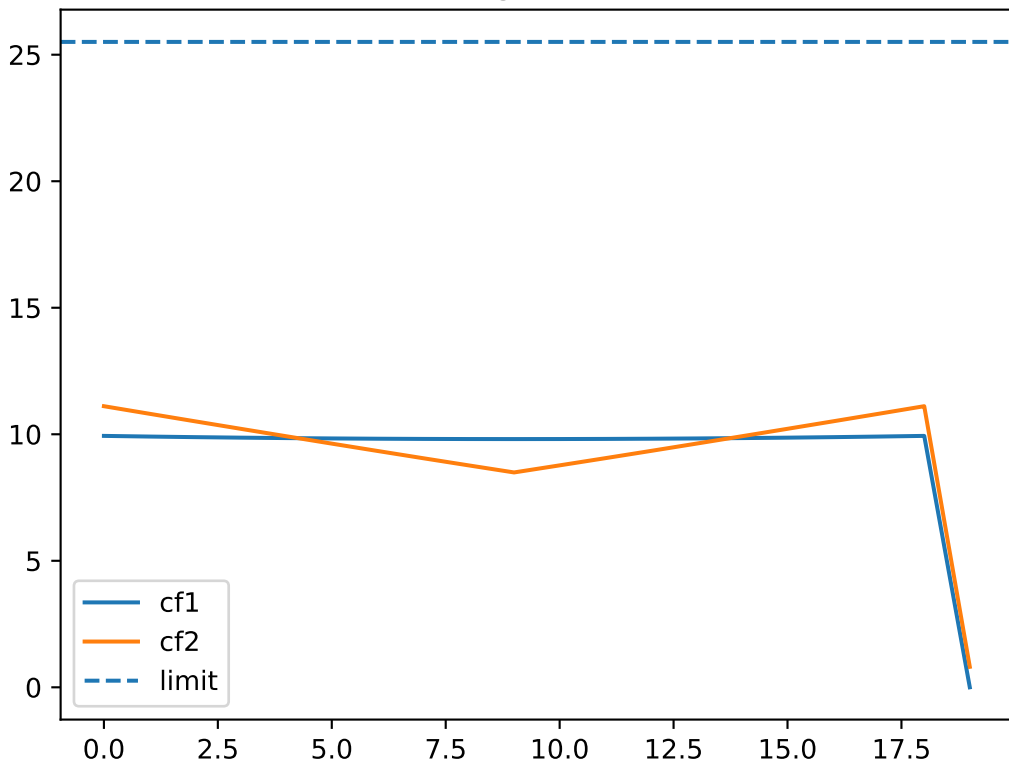
distance (iter 2)



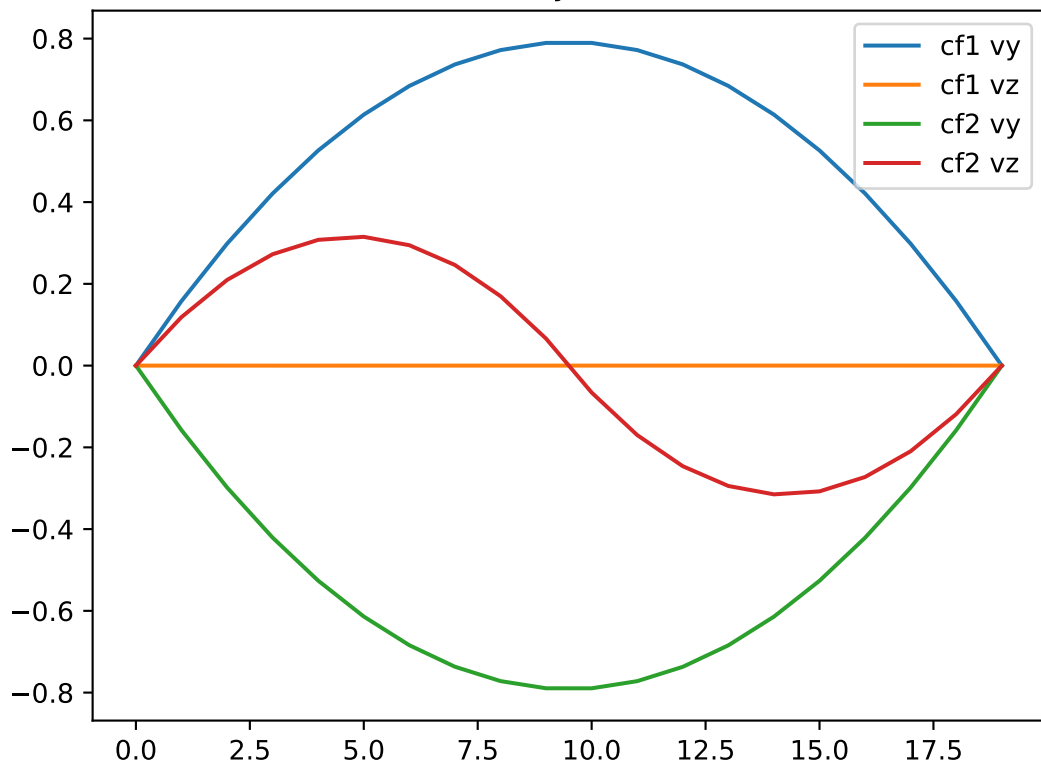
control (iter 2)



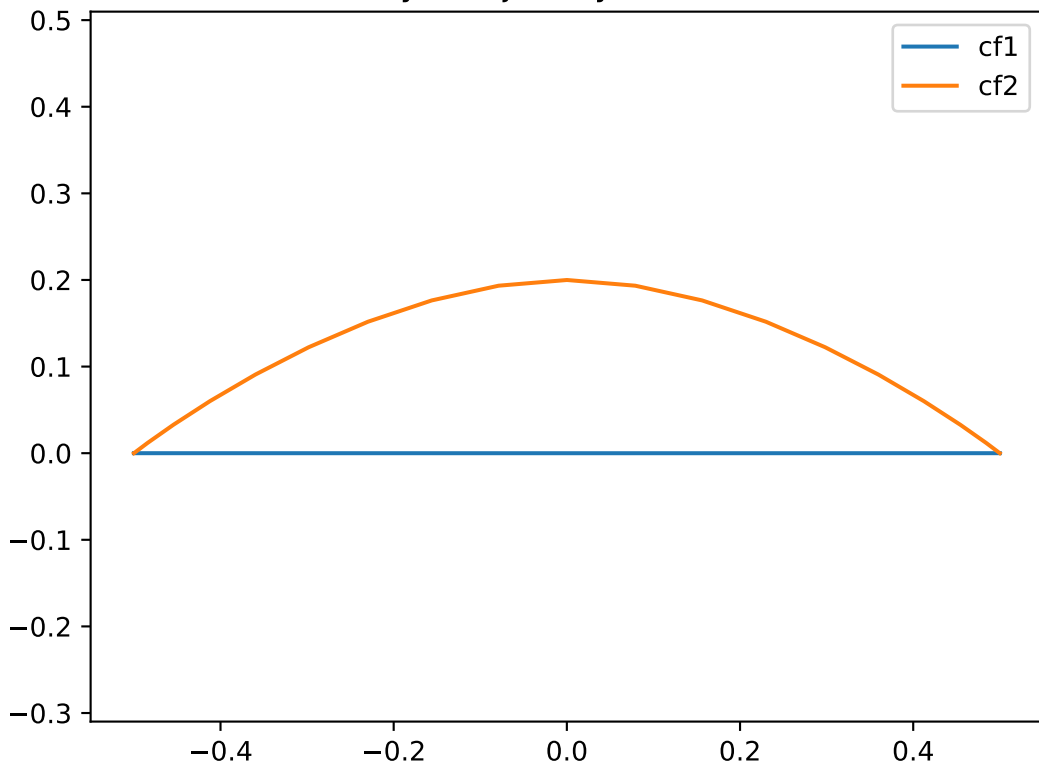
thrust magnitude (iter 2)



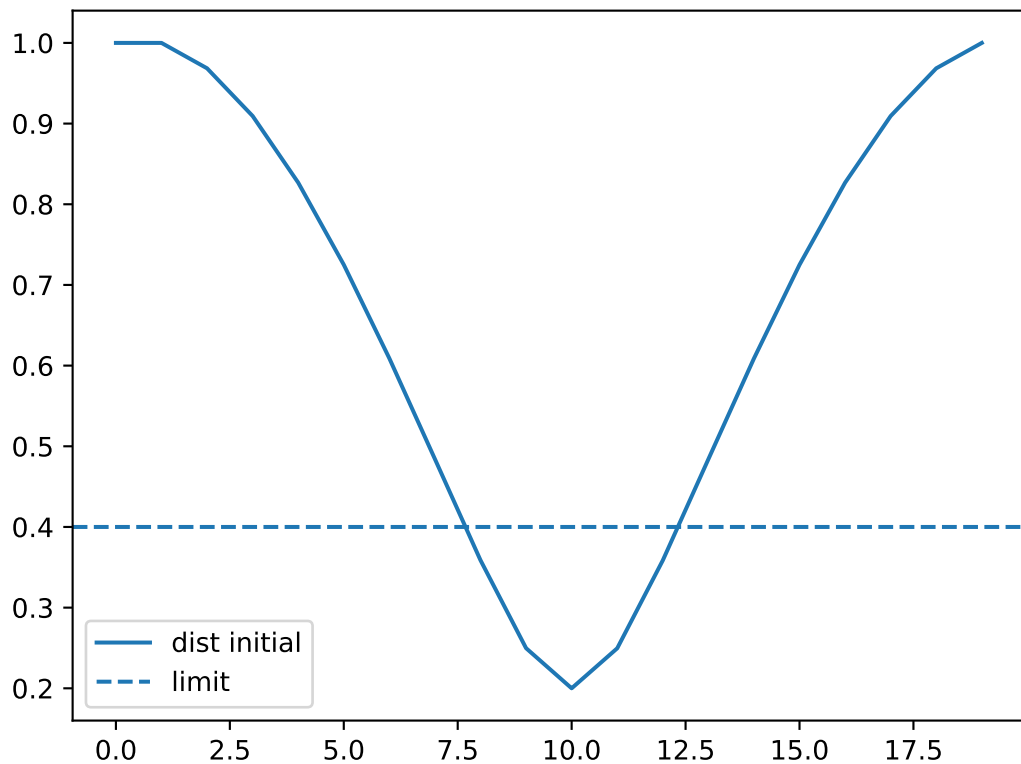
velocity (iter 2)



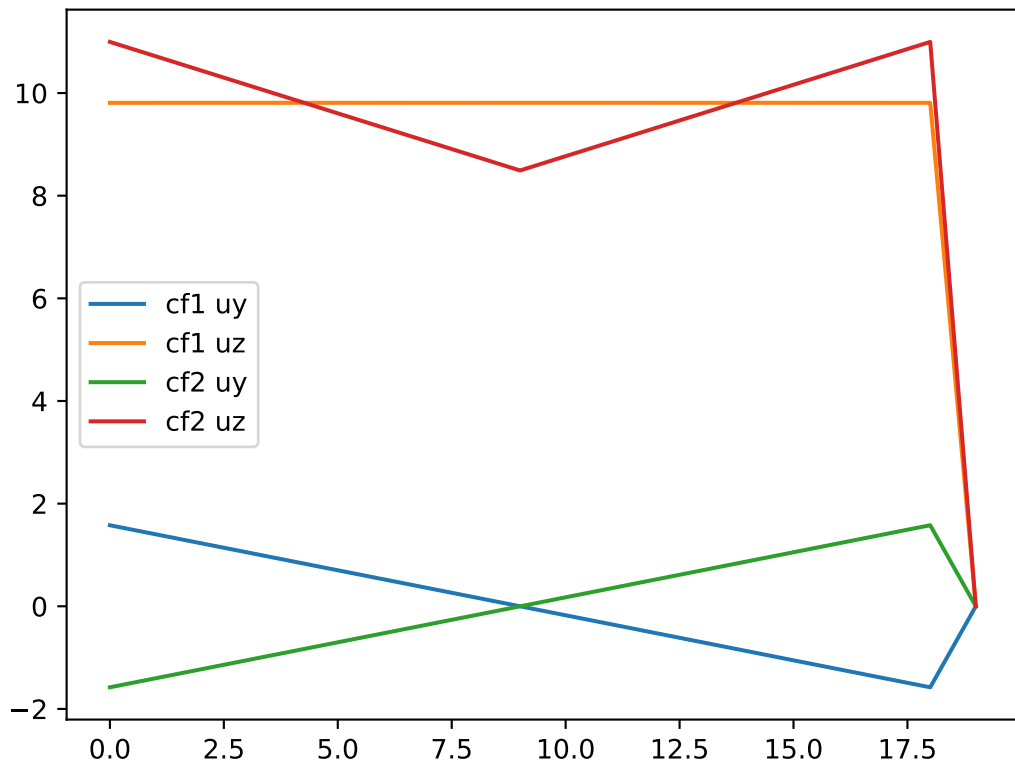
y-z trajectory (iter 3)



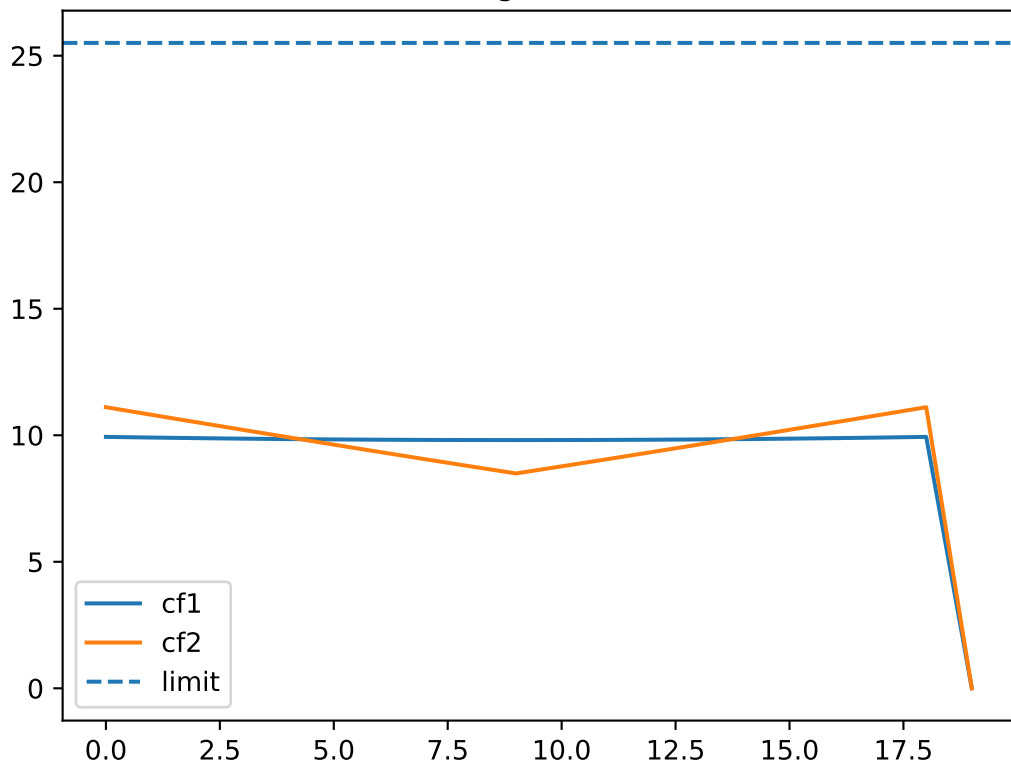
distance (iter 3)



control (iter 3)

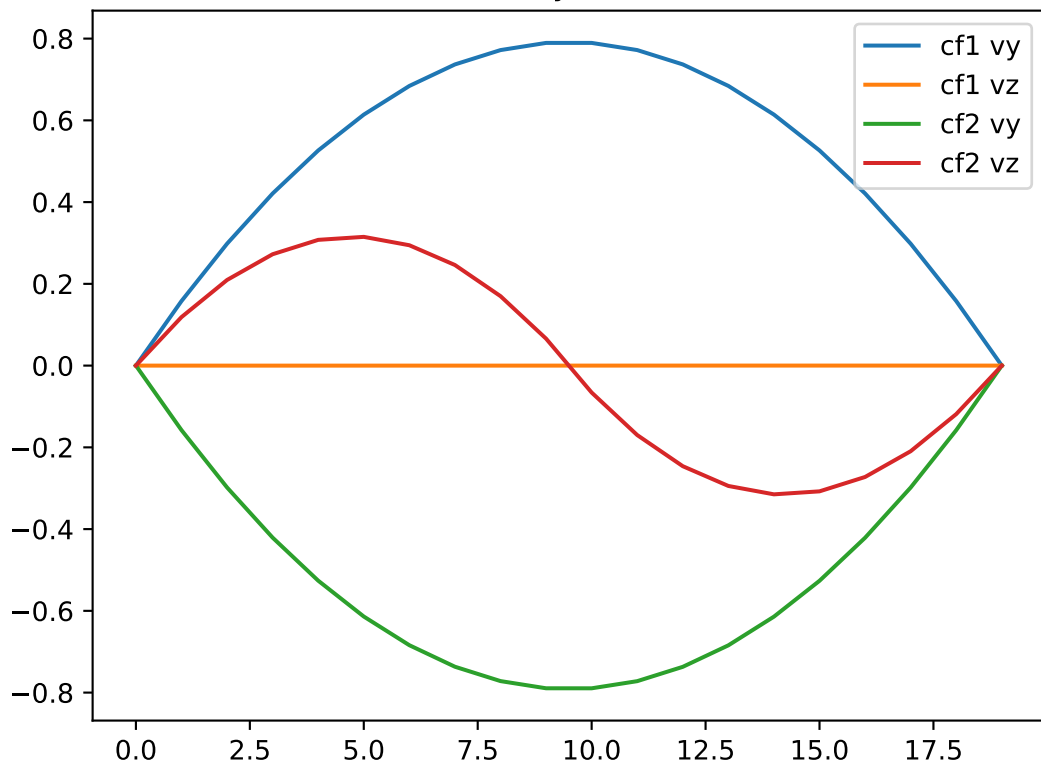


thrust magnitude (iter 3)

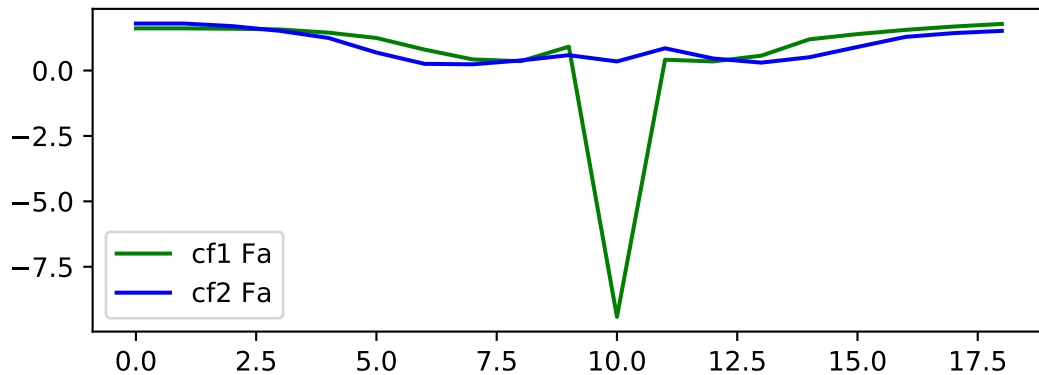
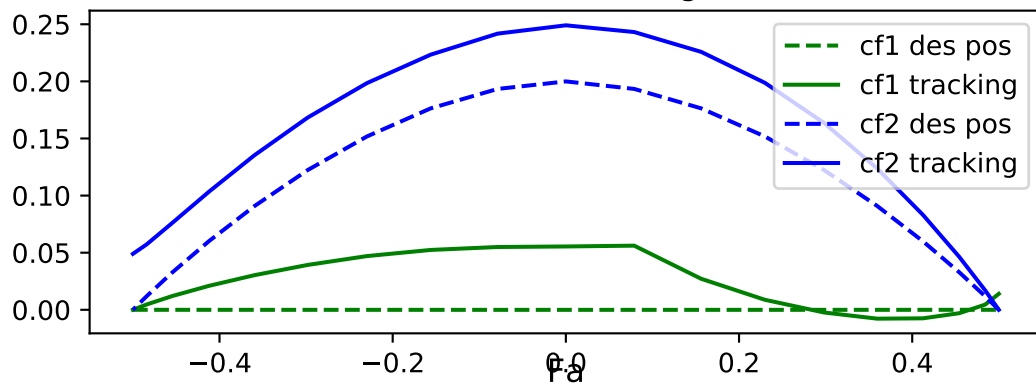




velocity (iter 3)



Position tracking



Velocity tracking

