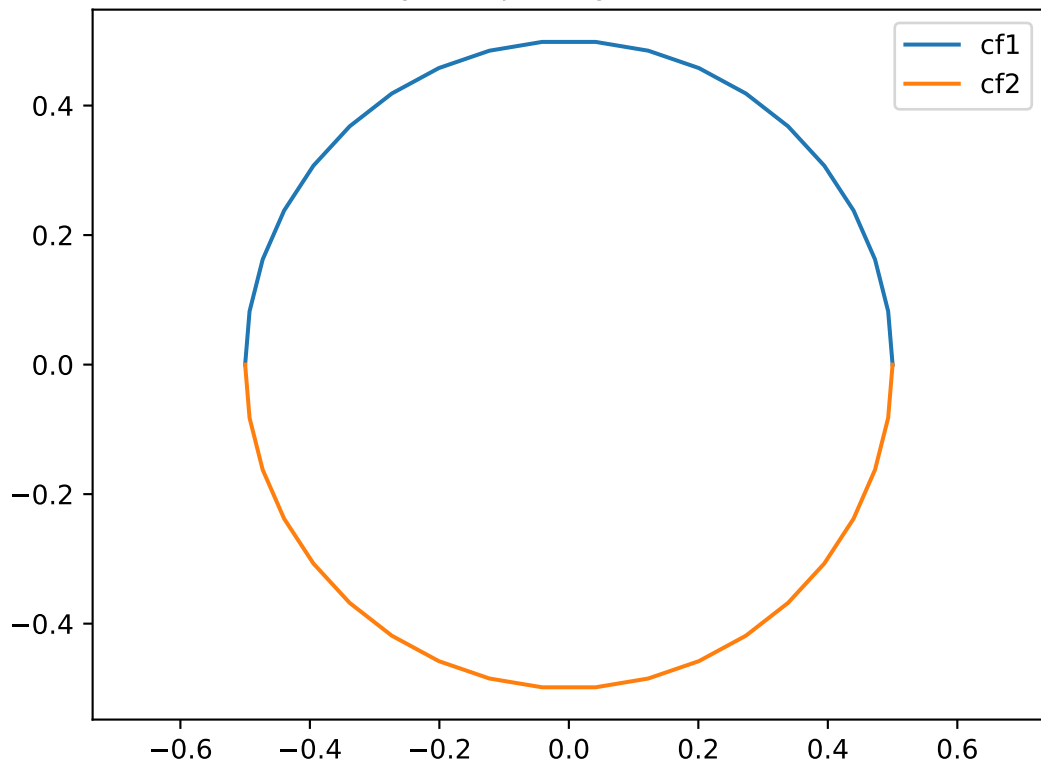
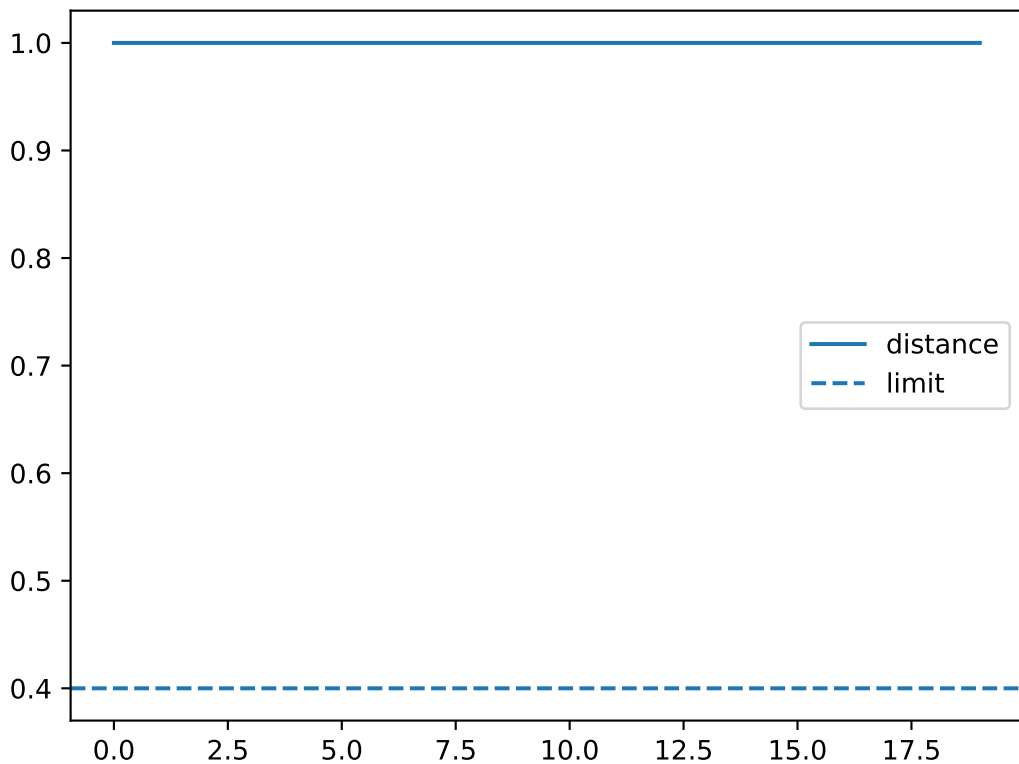


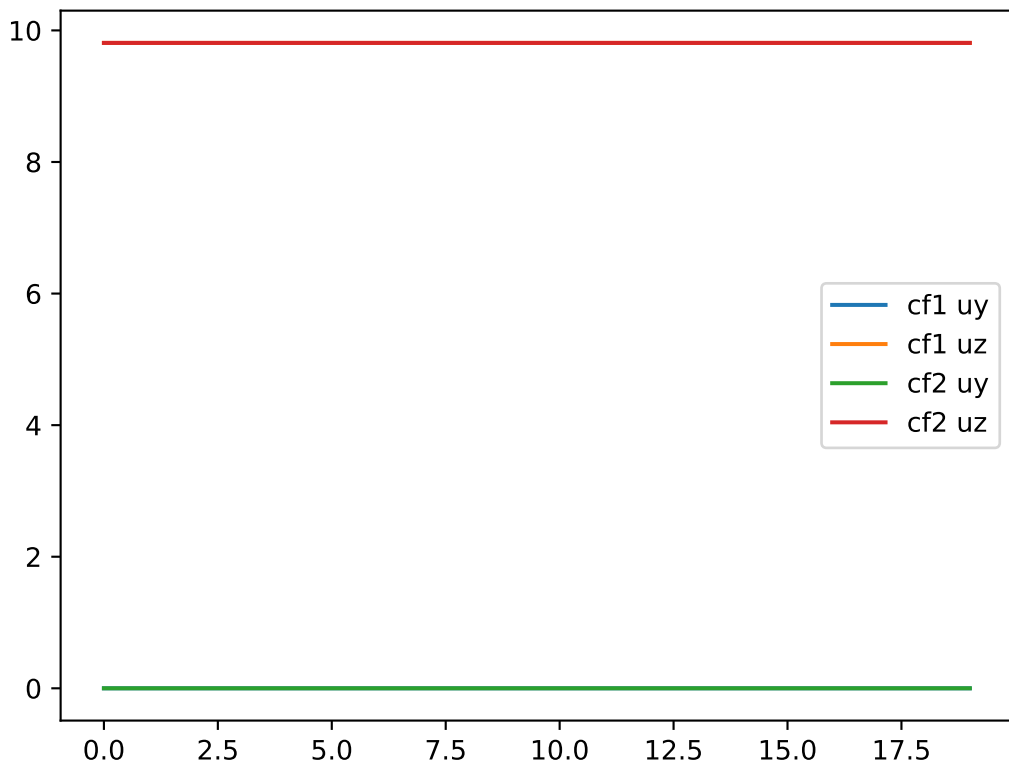
y-z trajectory (initial)



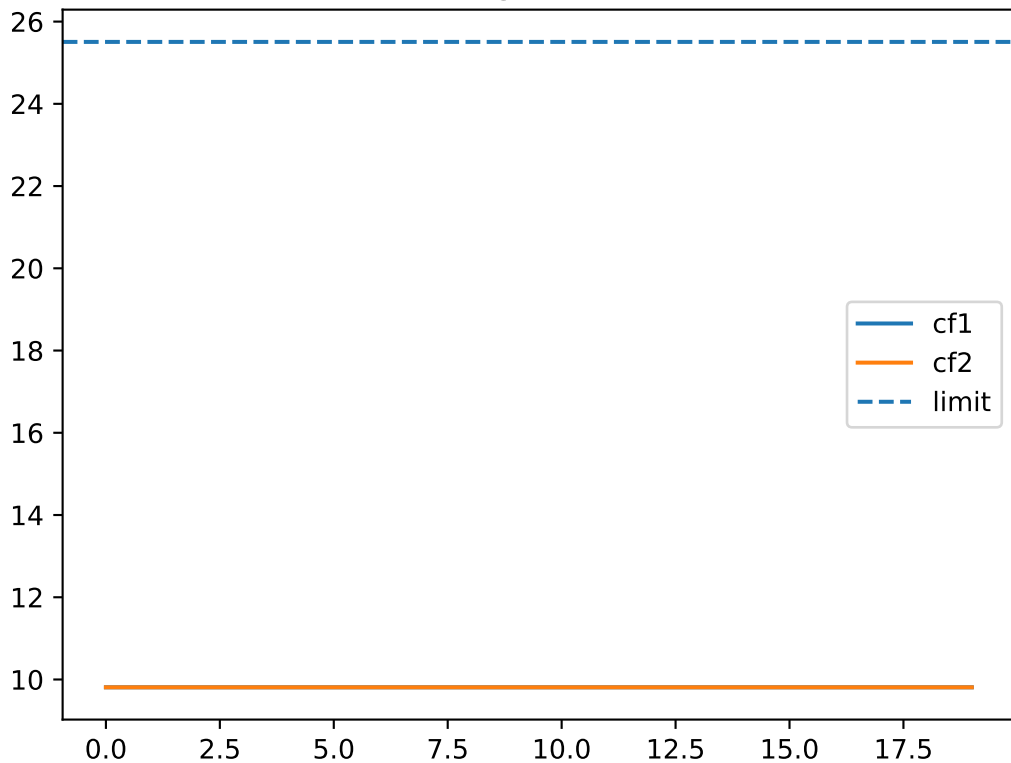
distance (initial)



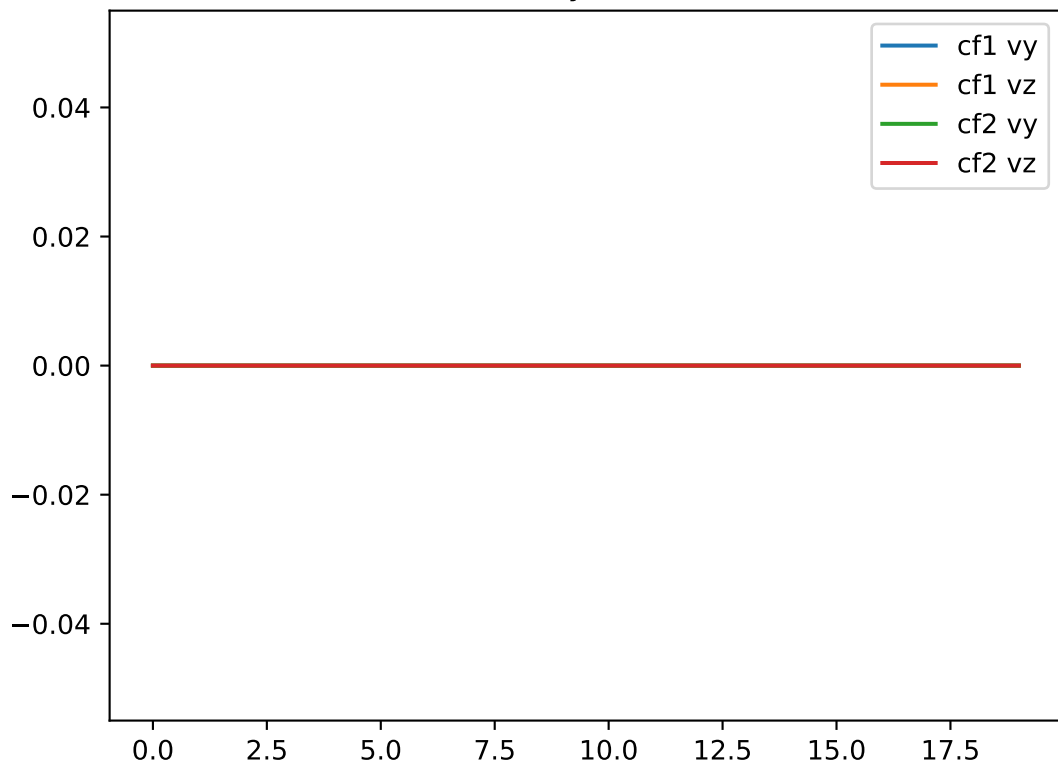
control (initial)



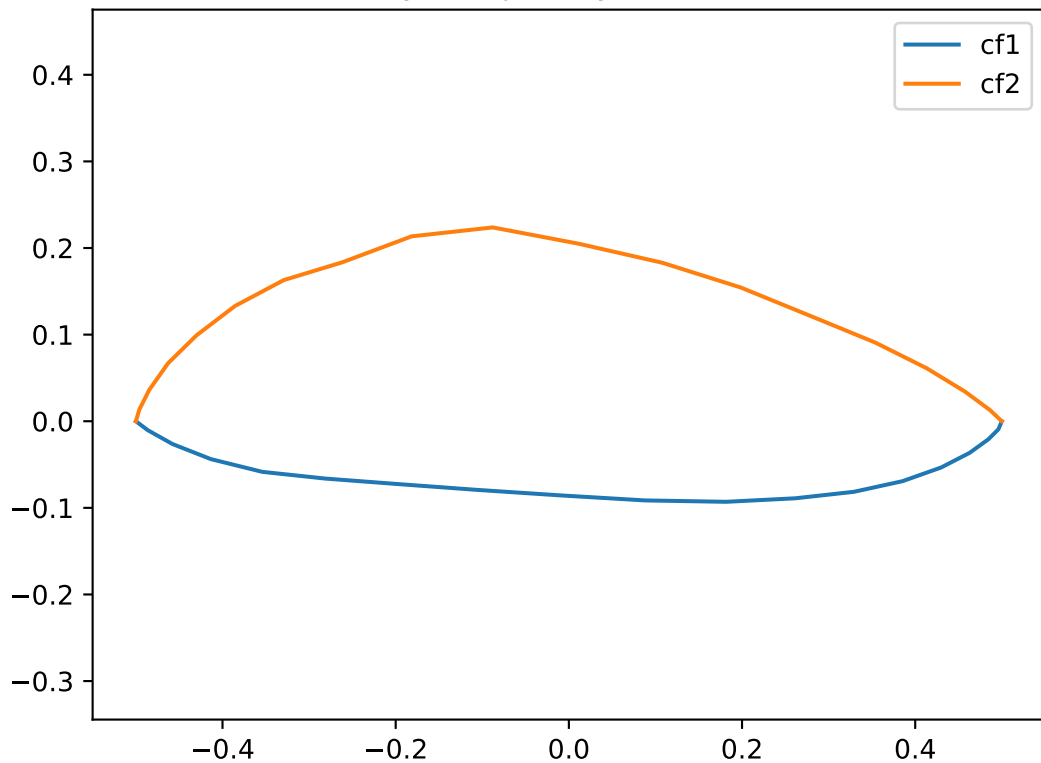
thrust magnitude (initial)



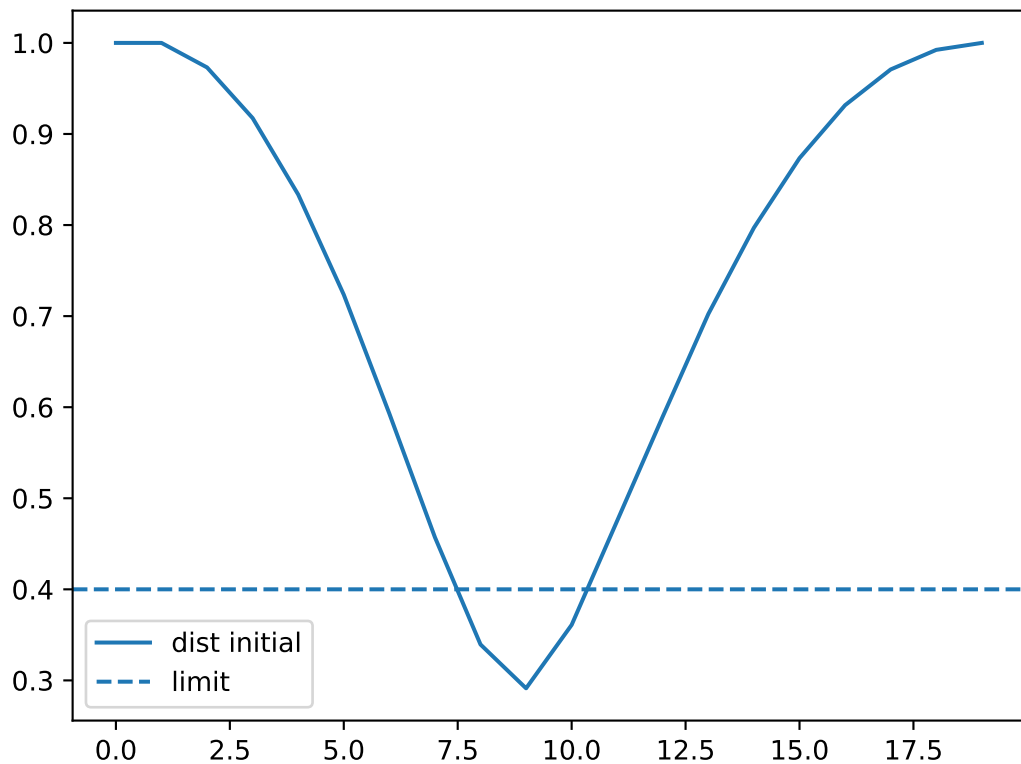
velocity (initial)



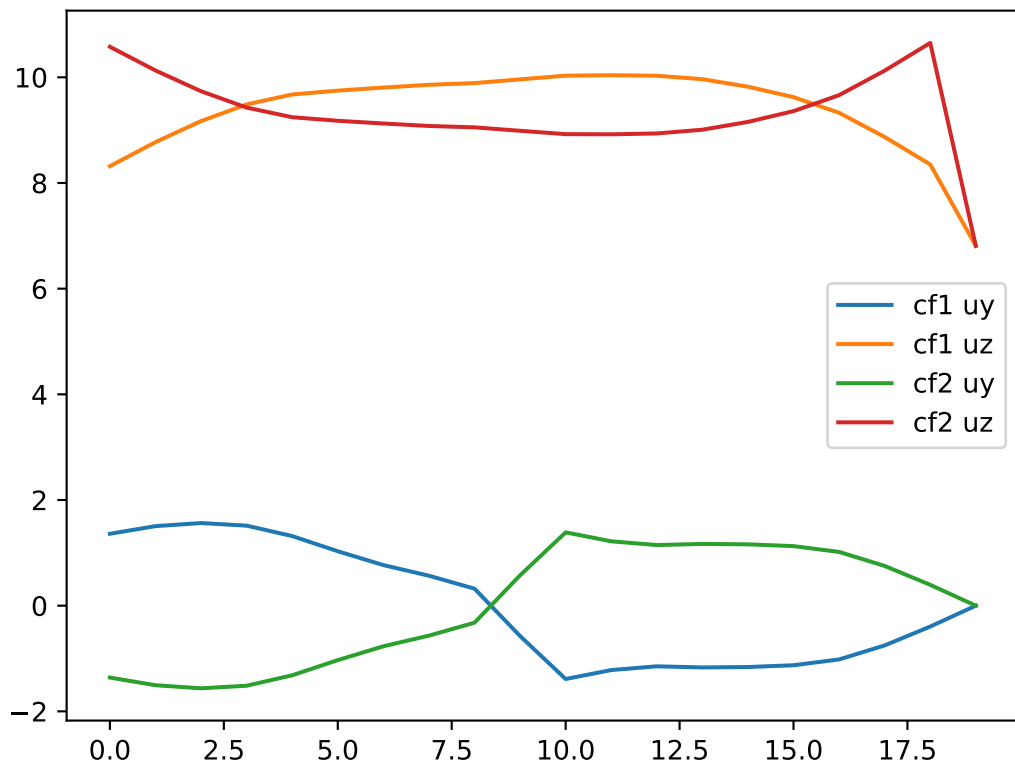
y-z trajectory (iter 0)



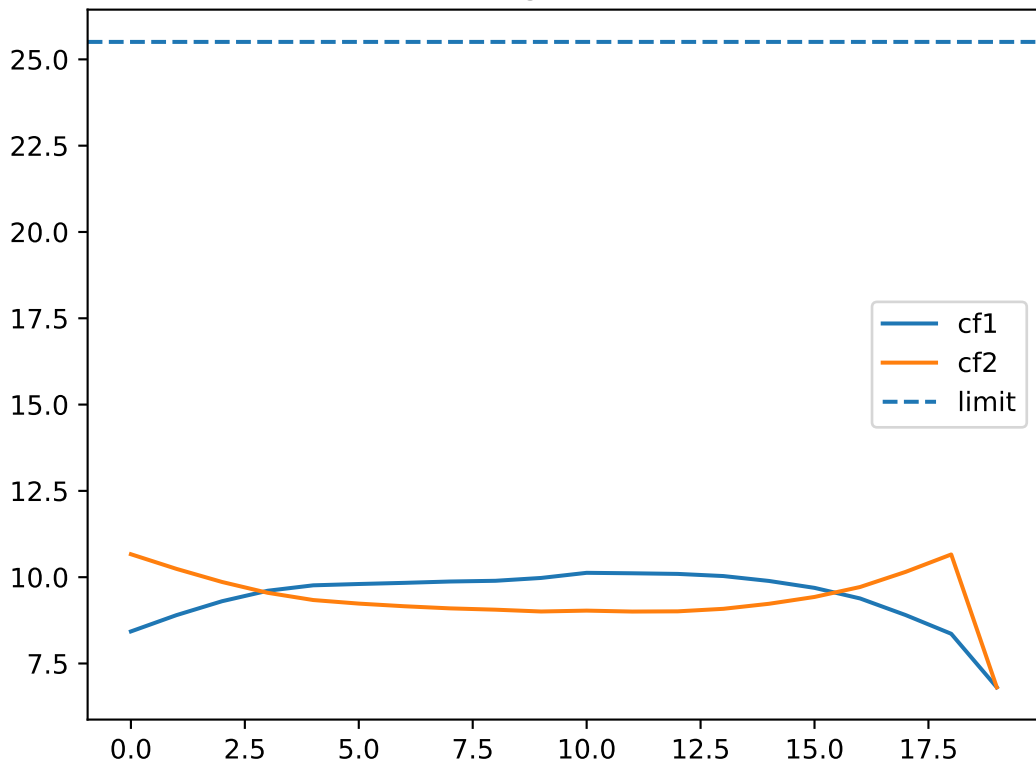
distance (iter 0)



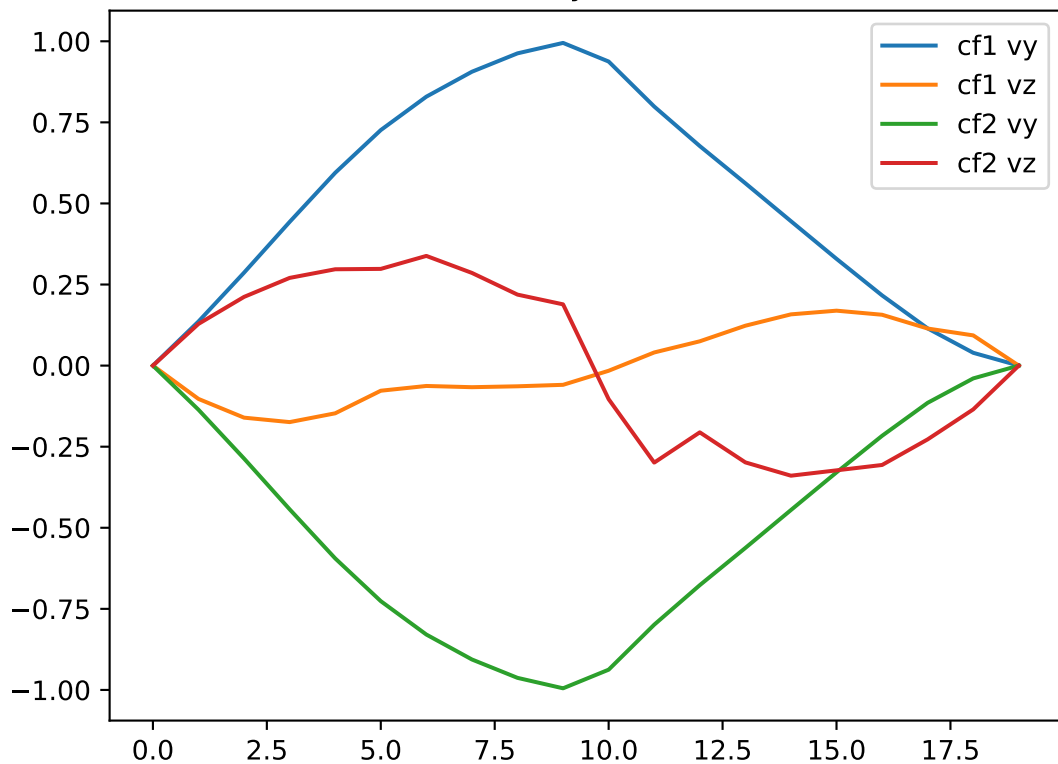
control (iter 0)



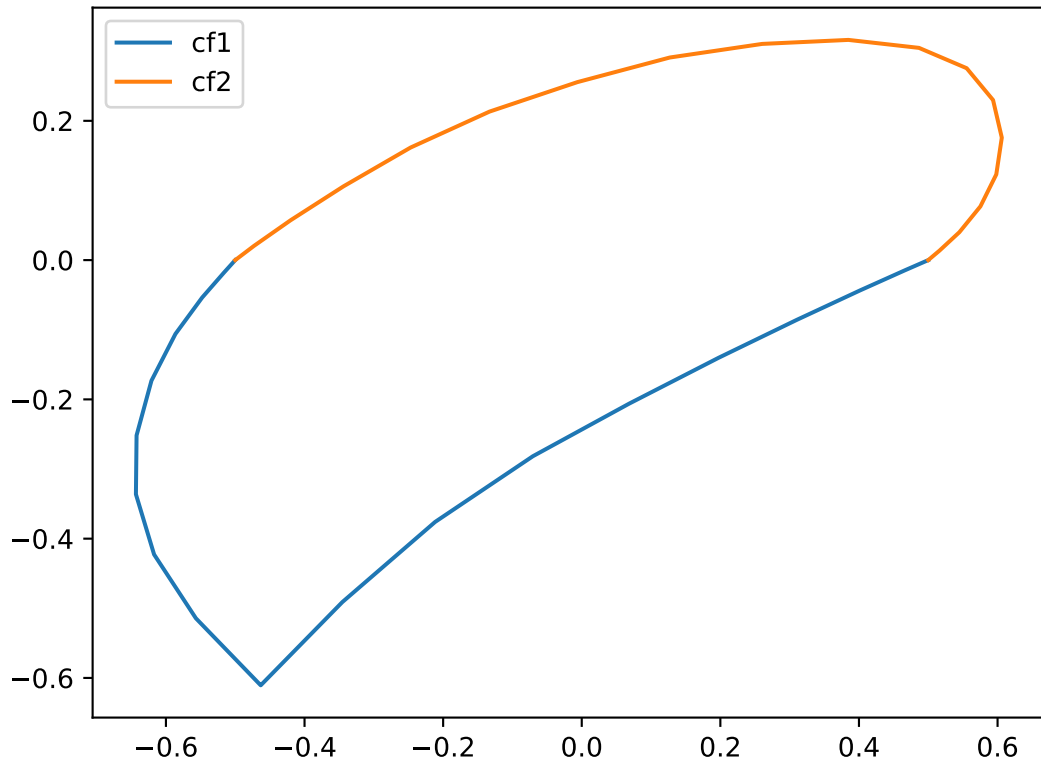
thrust magnitude (iter 0)



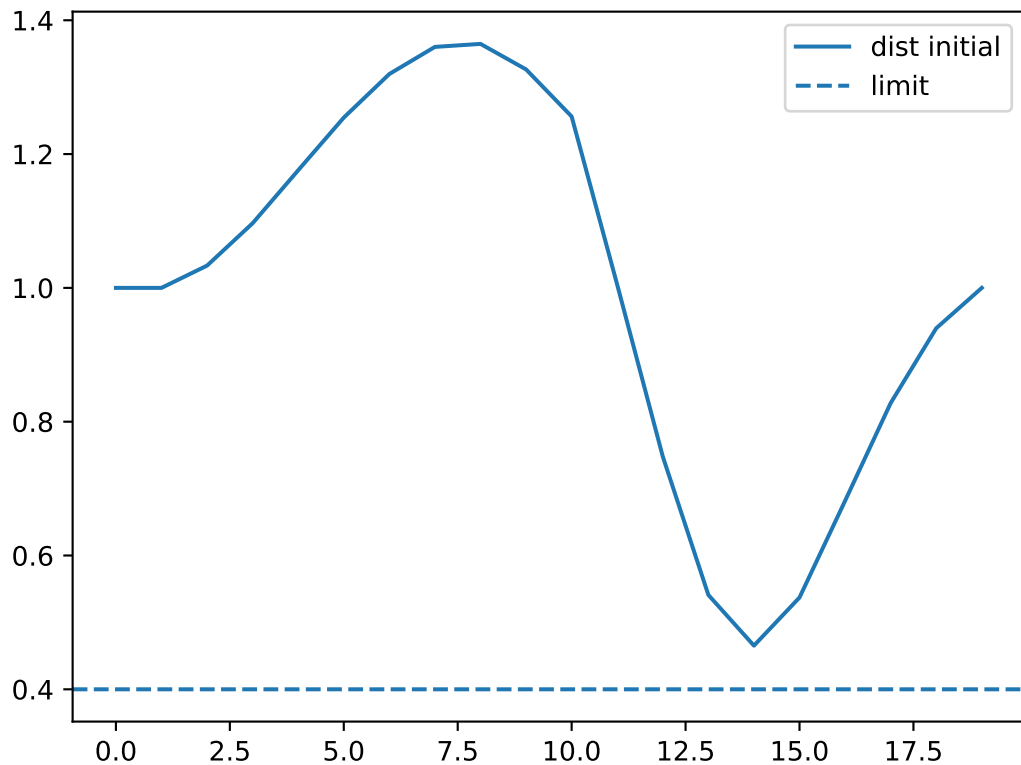
velocity (iter 0)



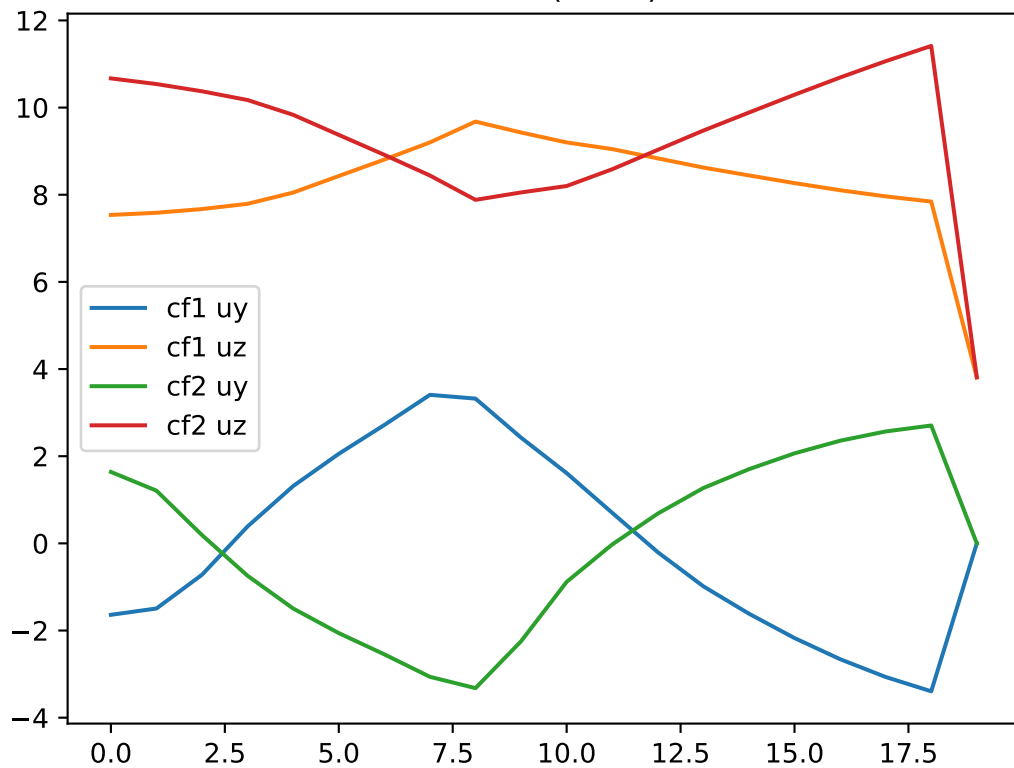
y-z trajectory (iter 1)



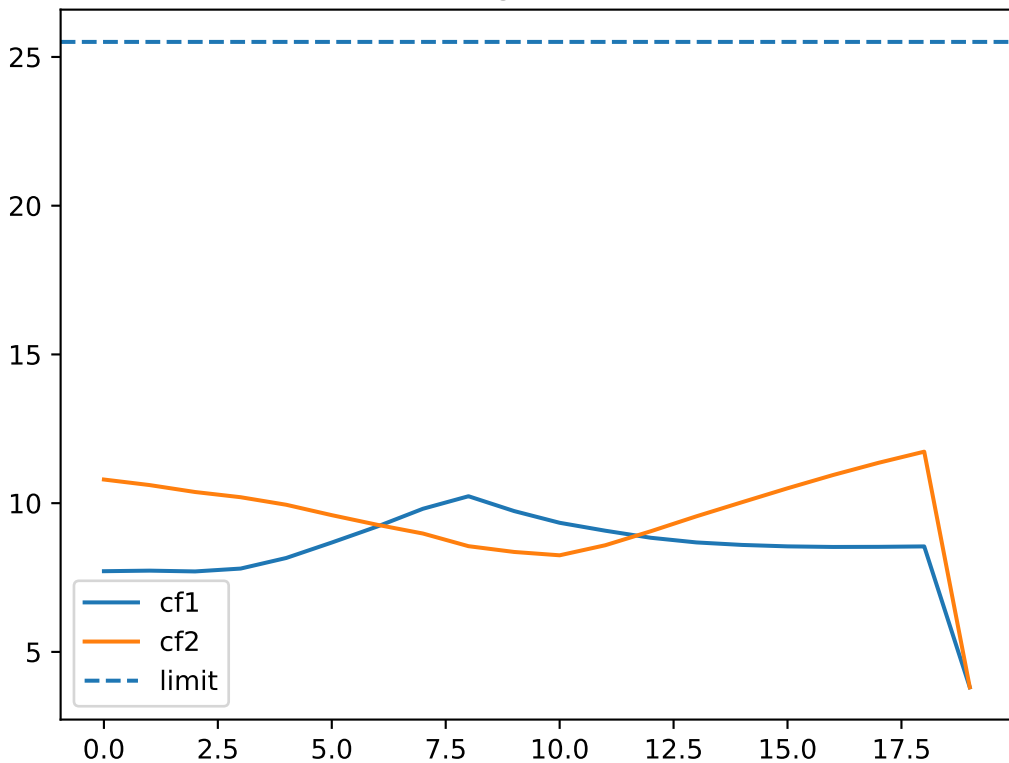
distance (iter 1)



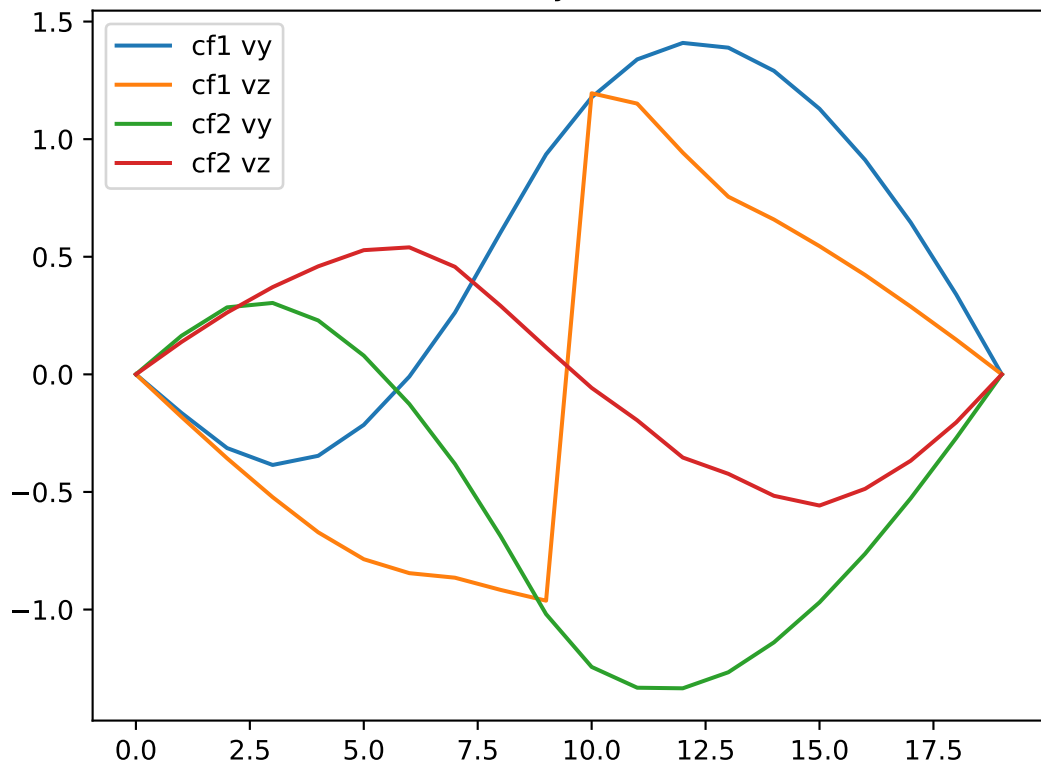
control (iter 1)



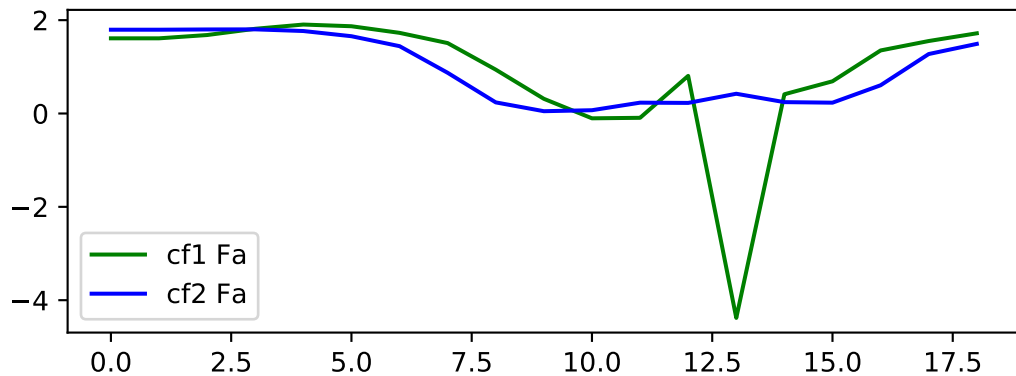
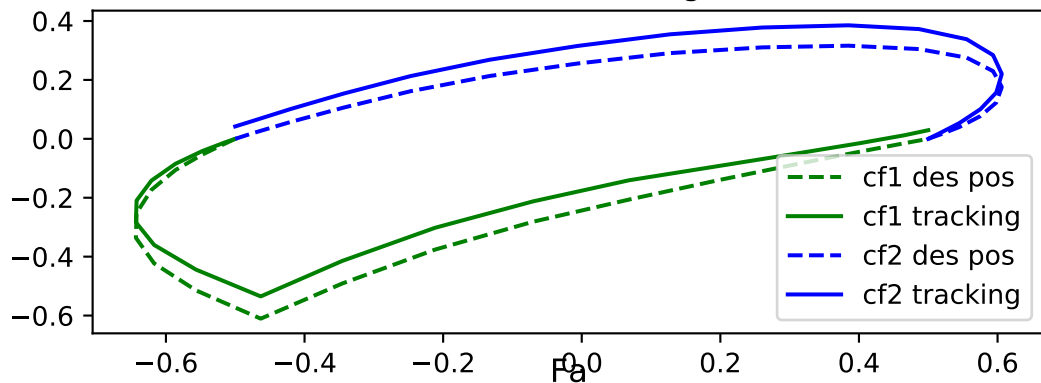
thrust magnitude (iter 1)



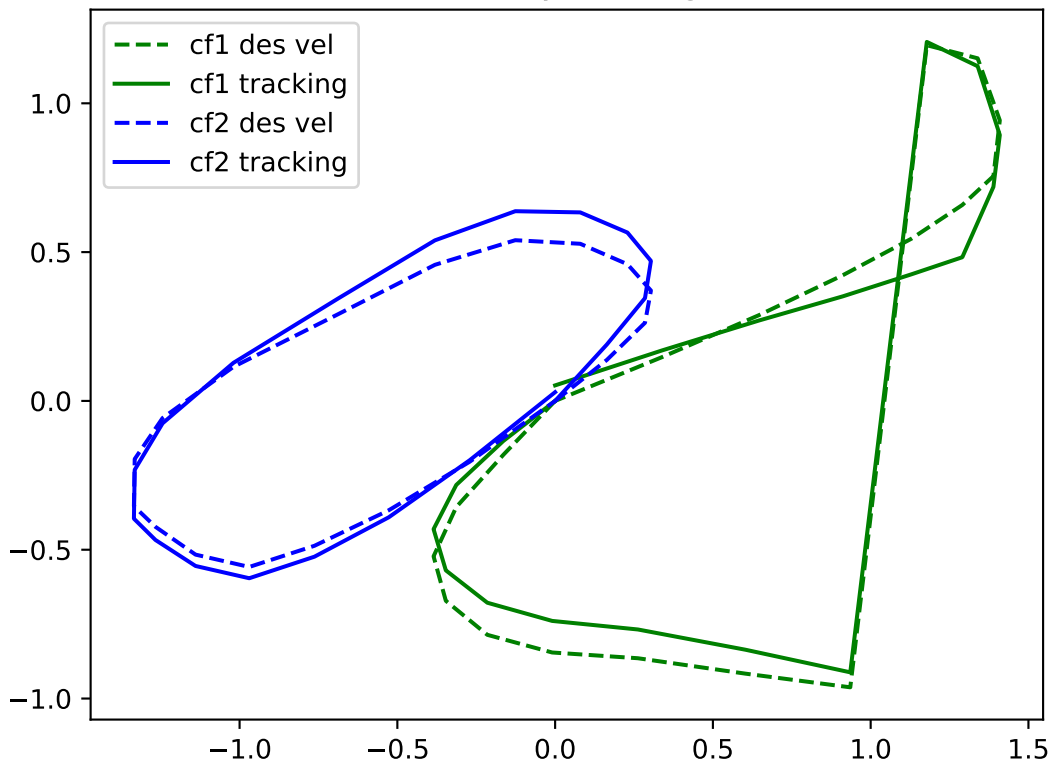
velocity (iter 1)



Position tracking



Velocity tracking



Control and thrust

