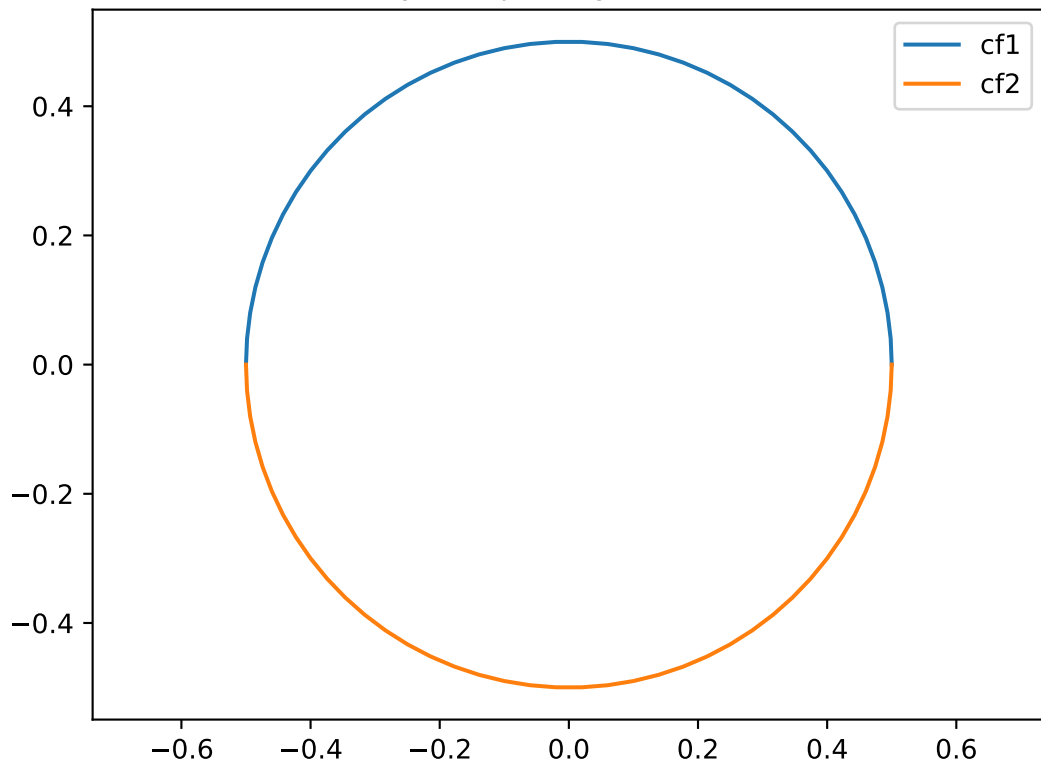
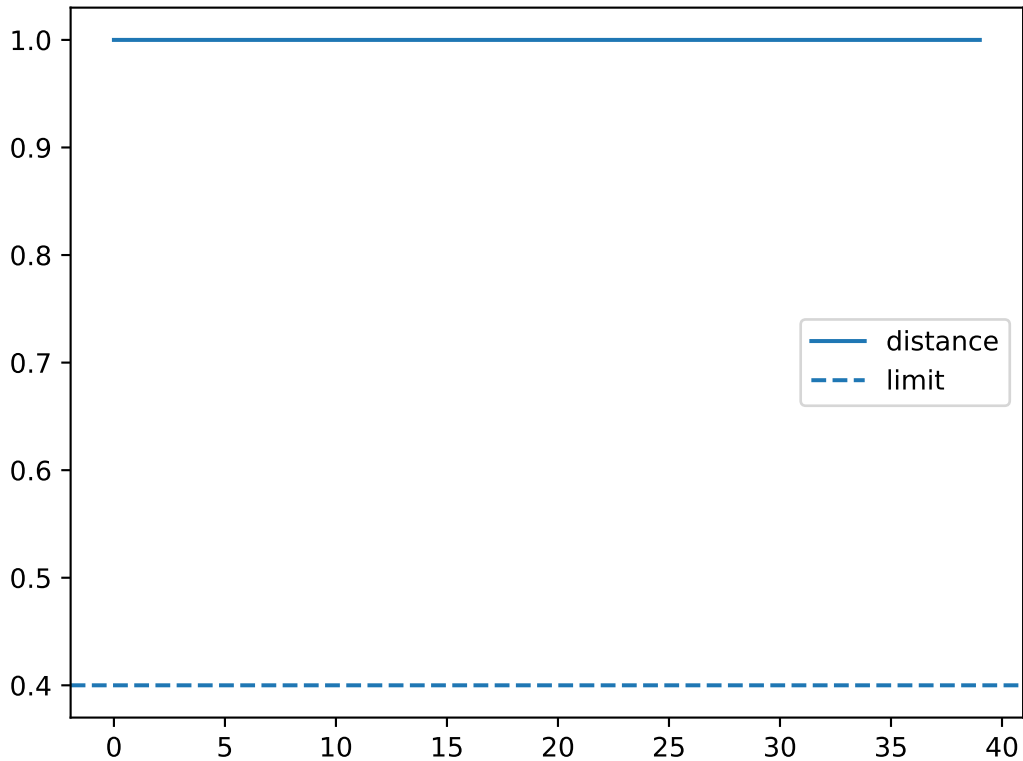


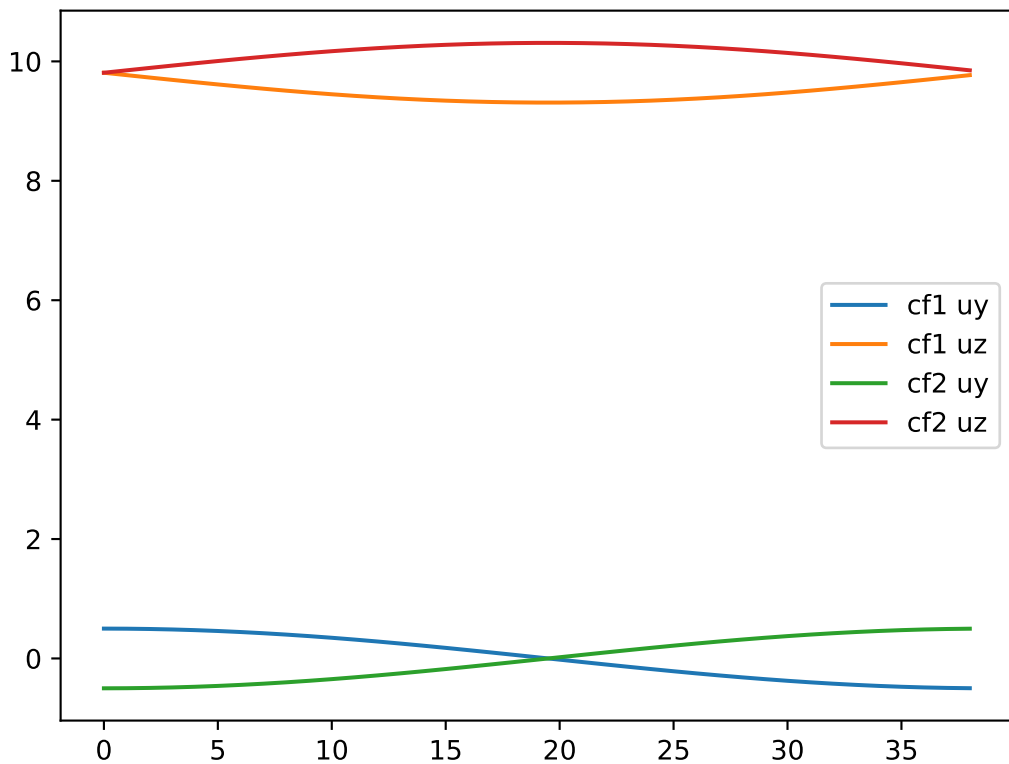
y-z trajectory (initial)



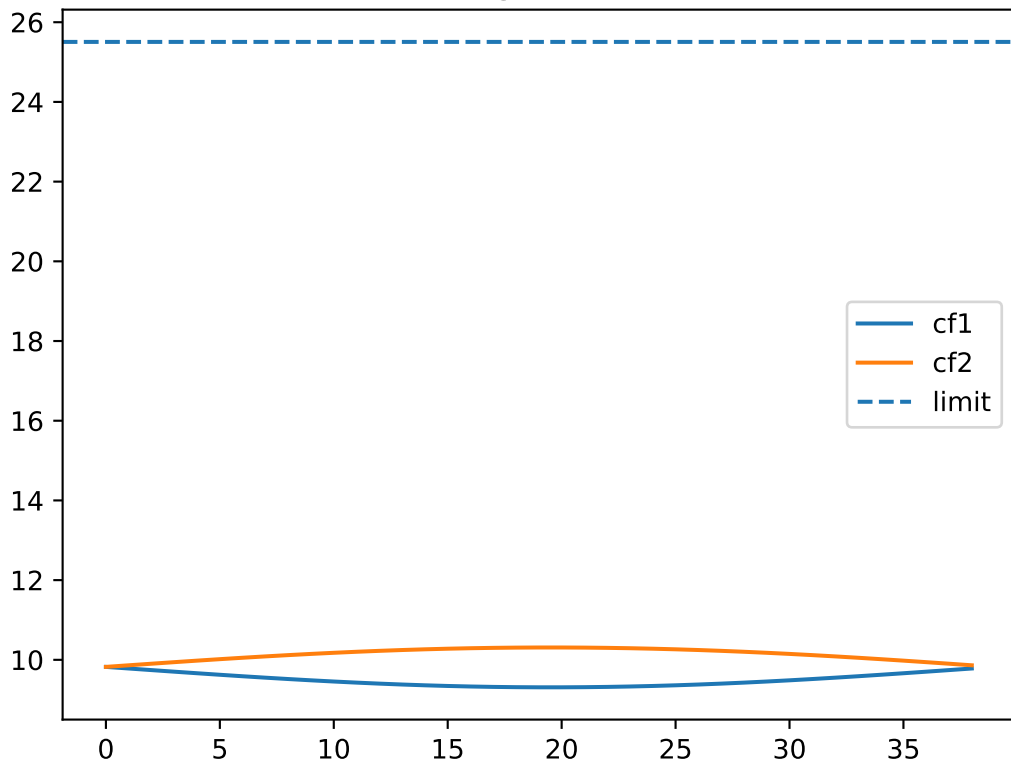
distance (initial)



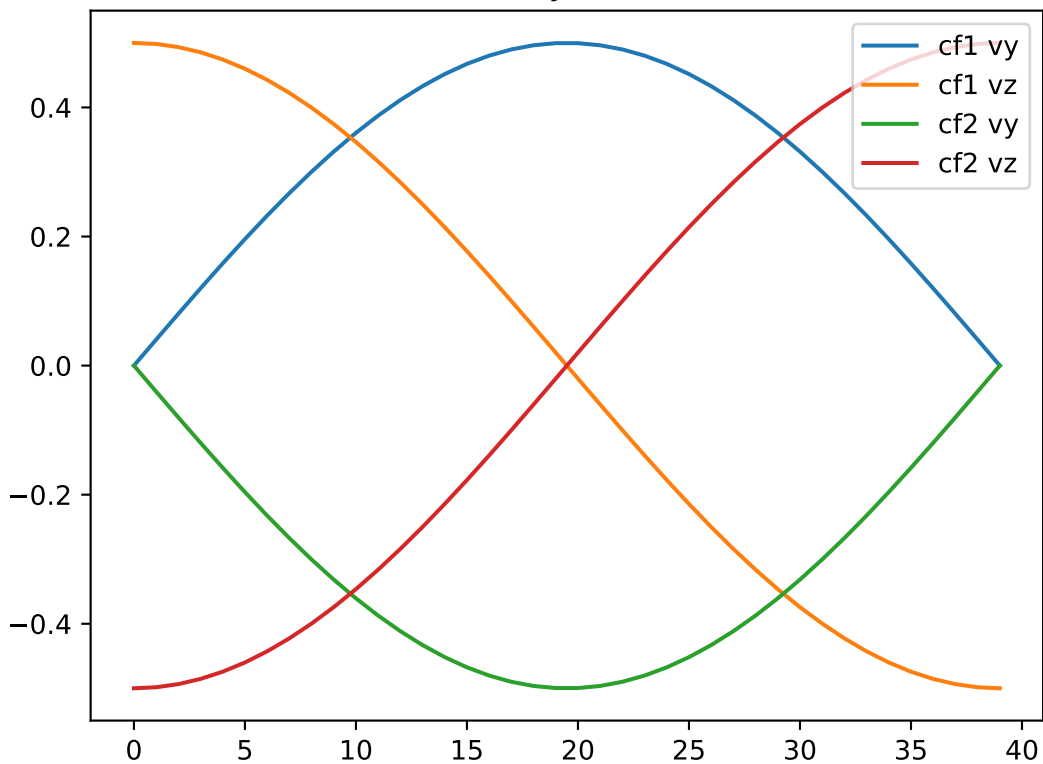
control (initial)



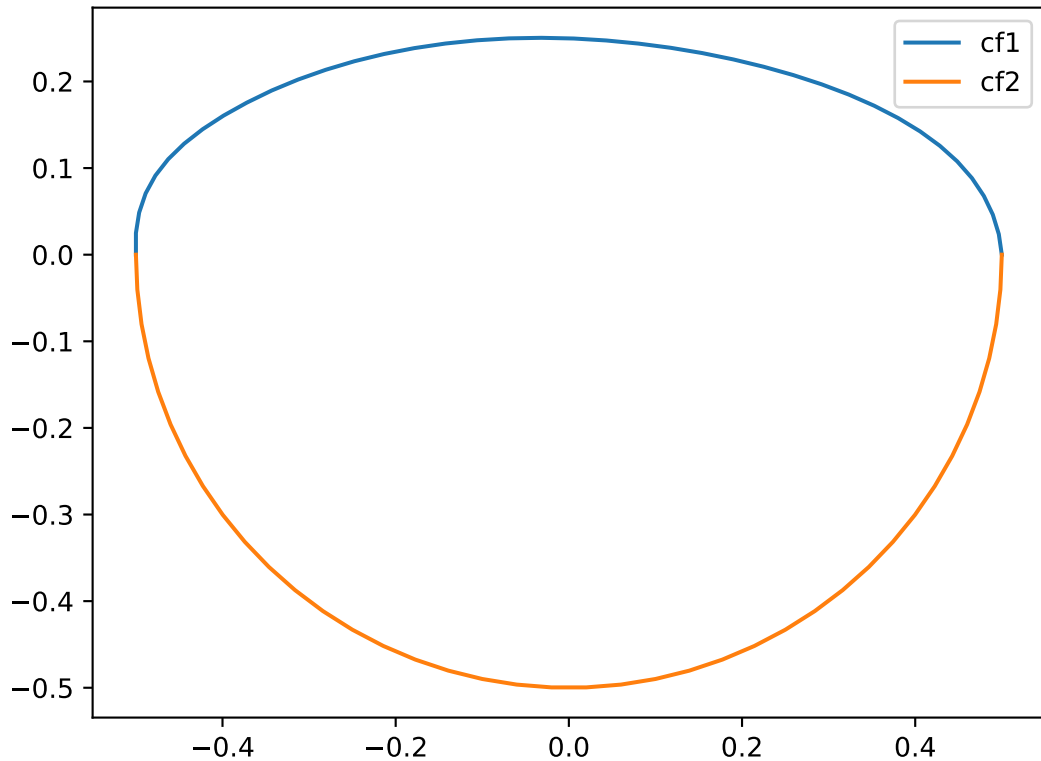
thrust magnitude (initial)



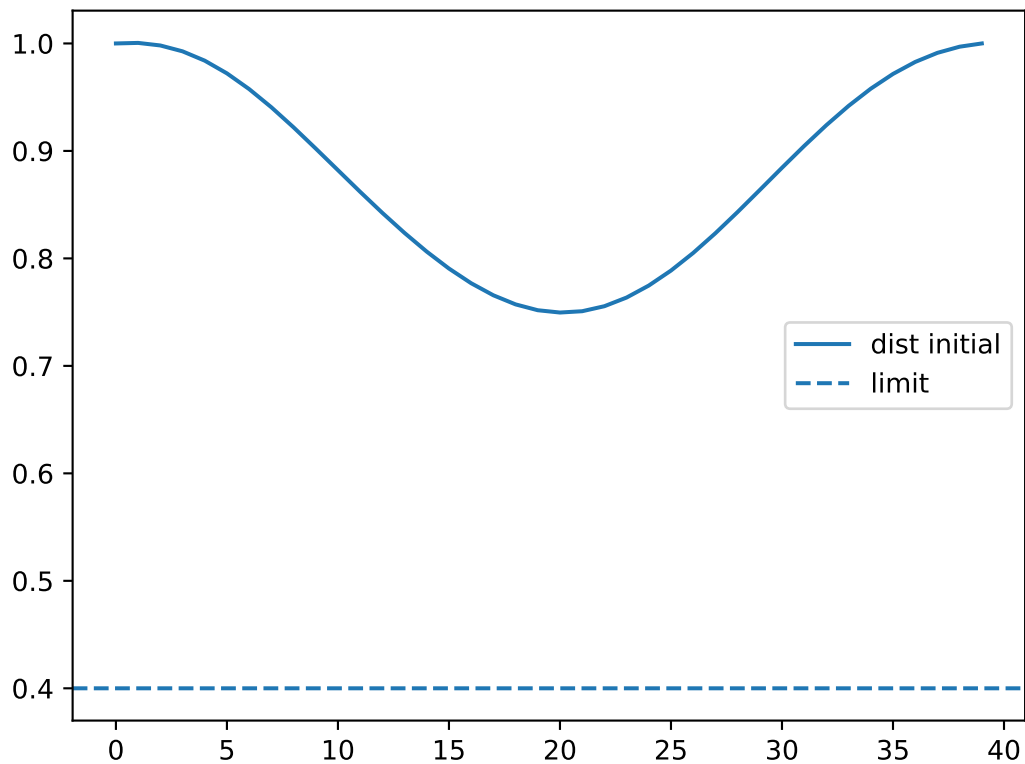
velocity (initial)



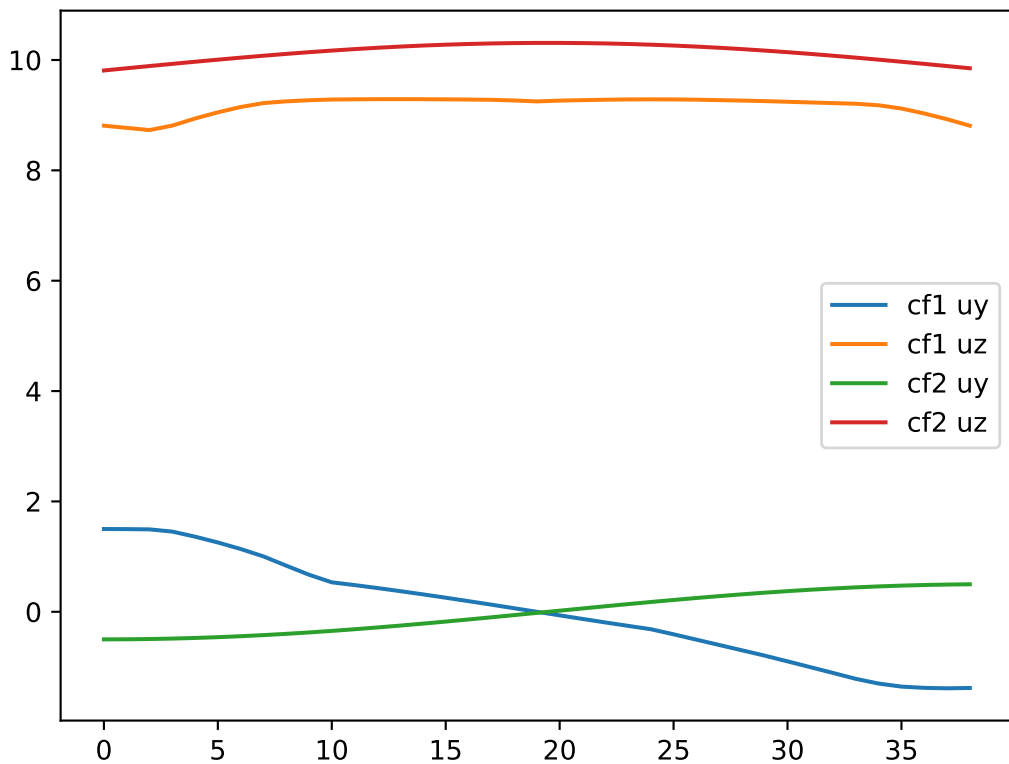
y-z trajectory (iter 0)



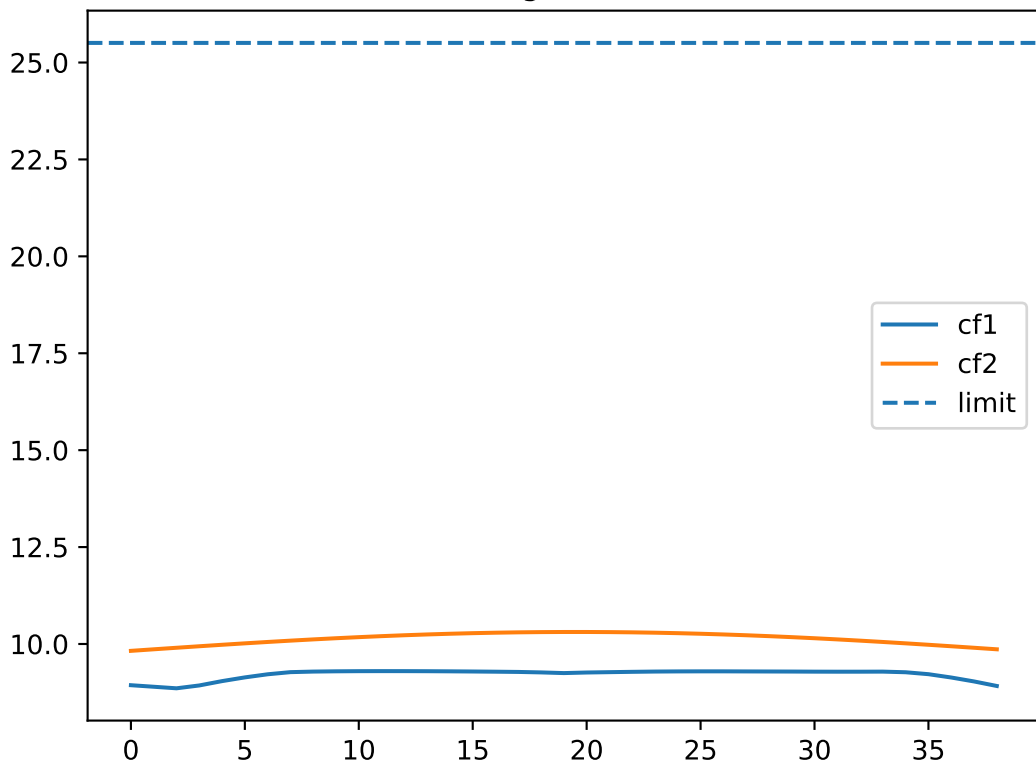
distance (iter 0)



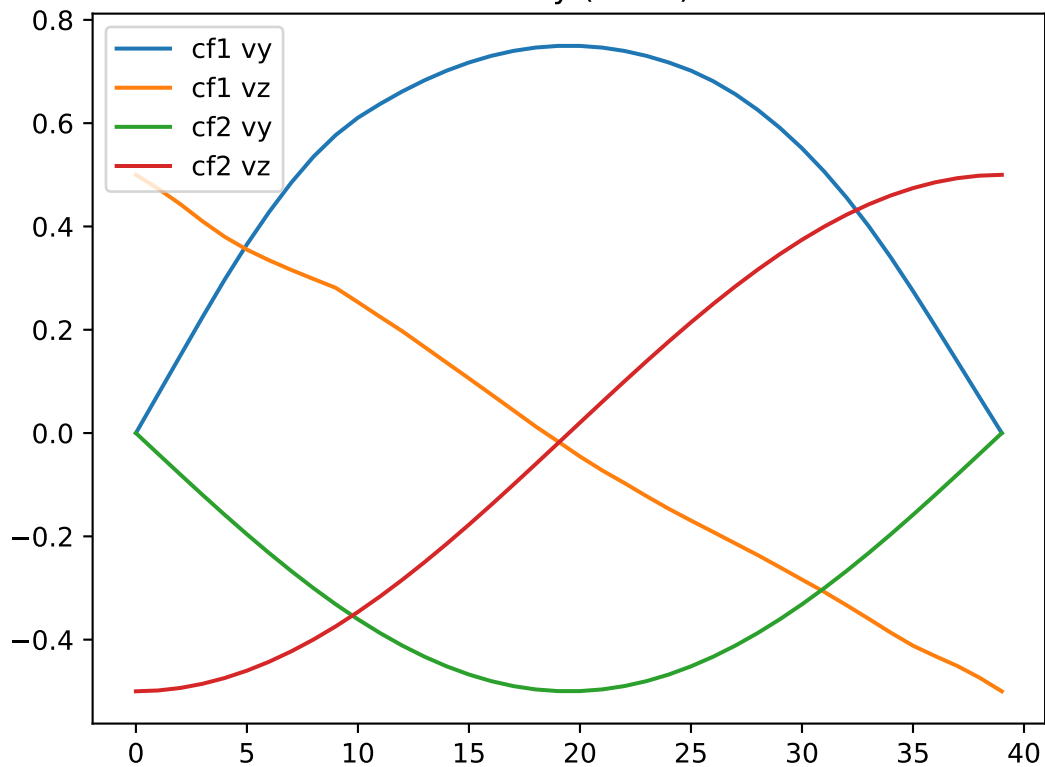
control (iter 0)



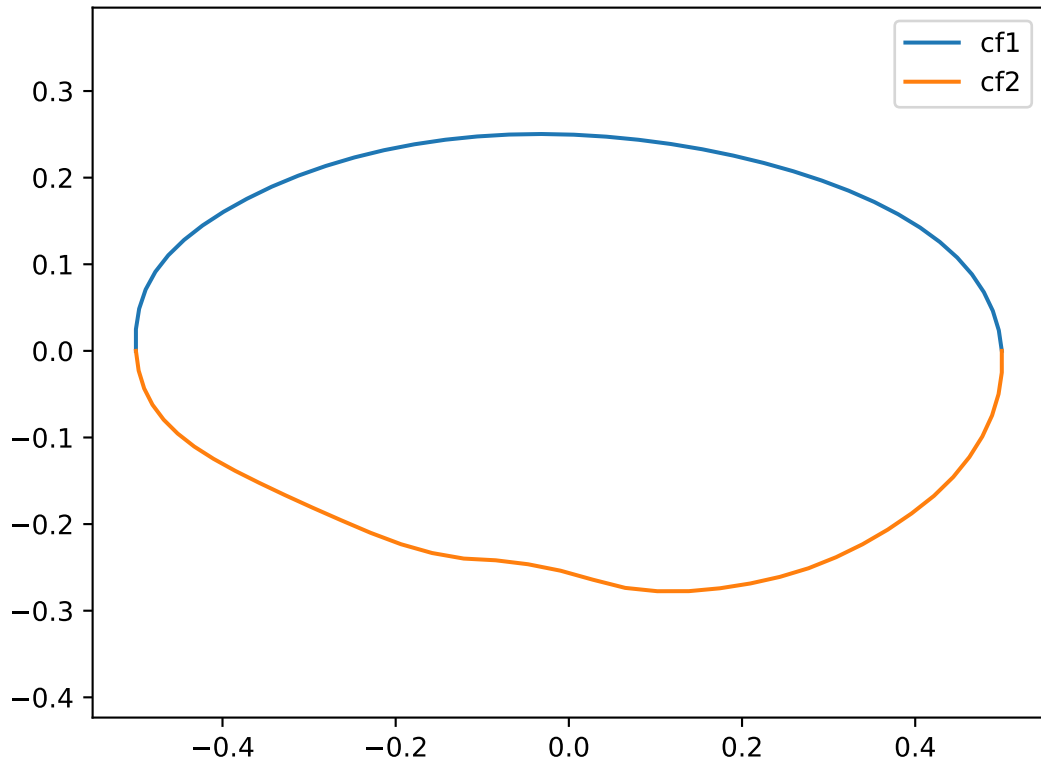
thrust magnitude (iter 0)



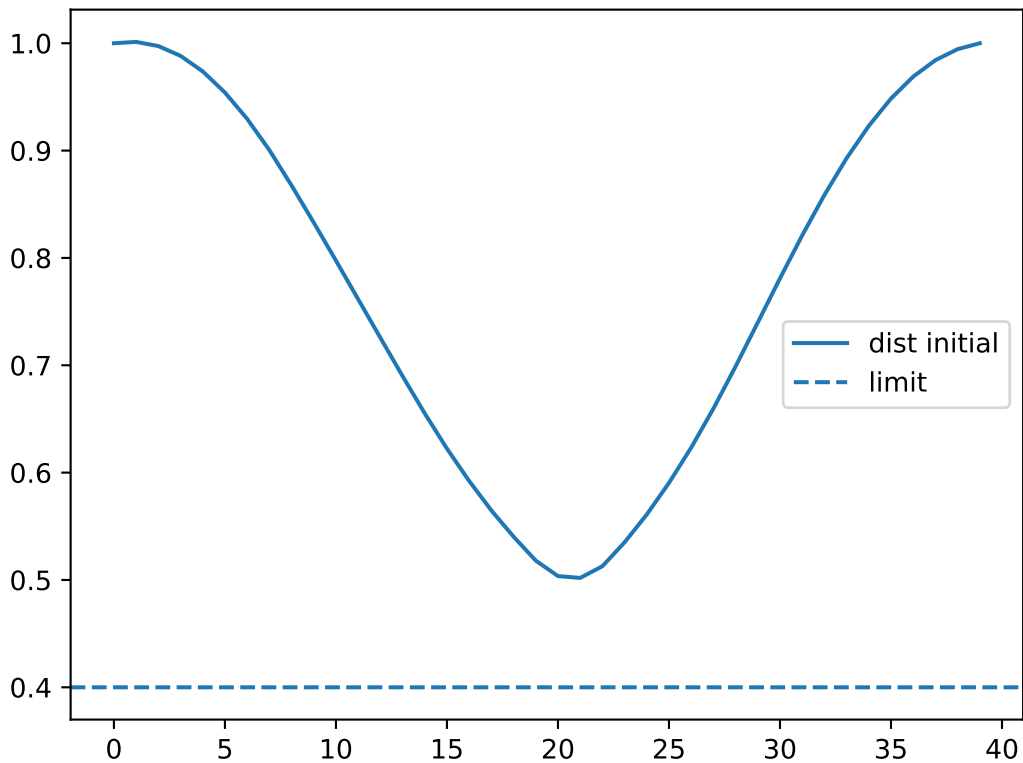
velocity (iter 0)



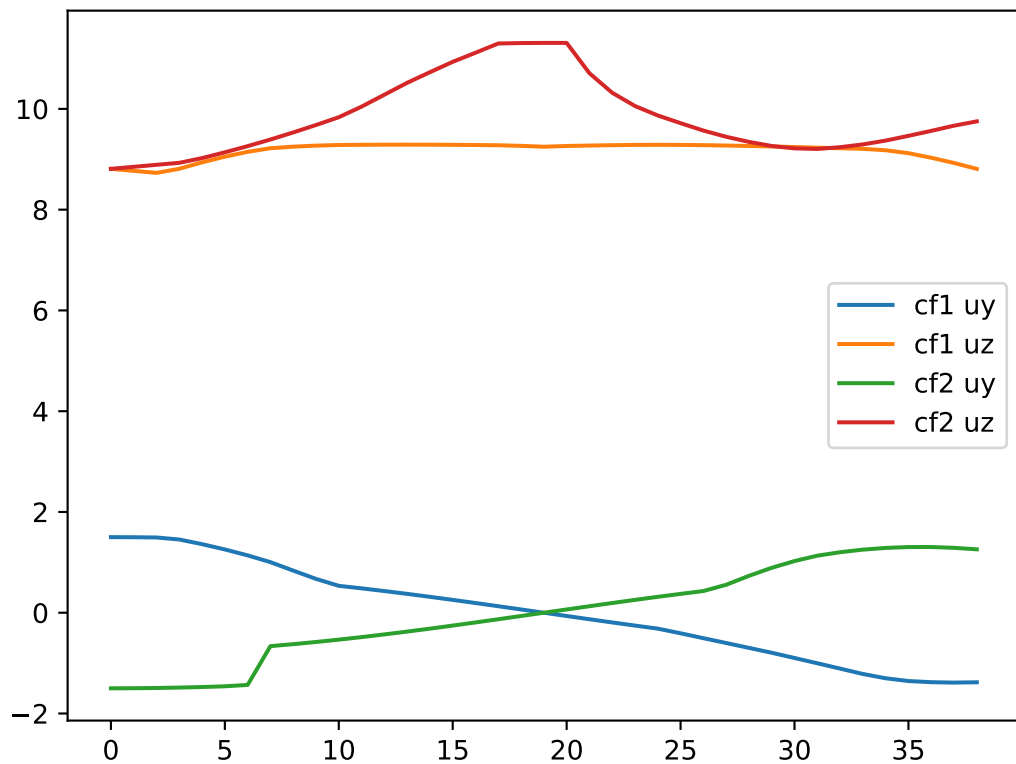
y-z trajectory (iter 1)



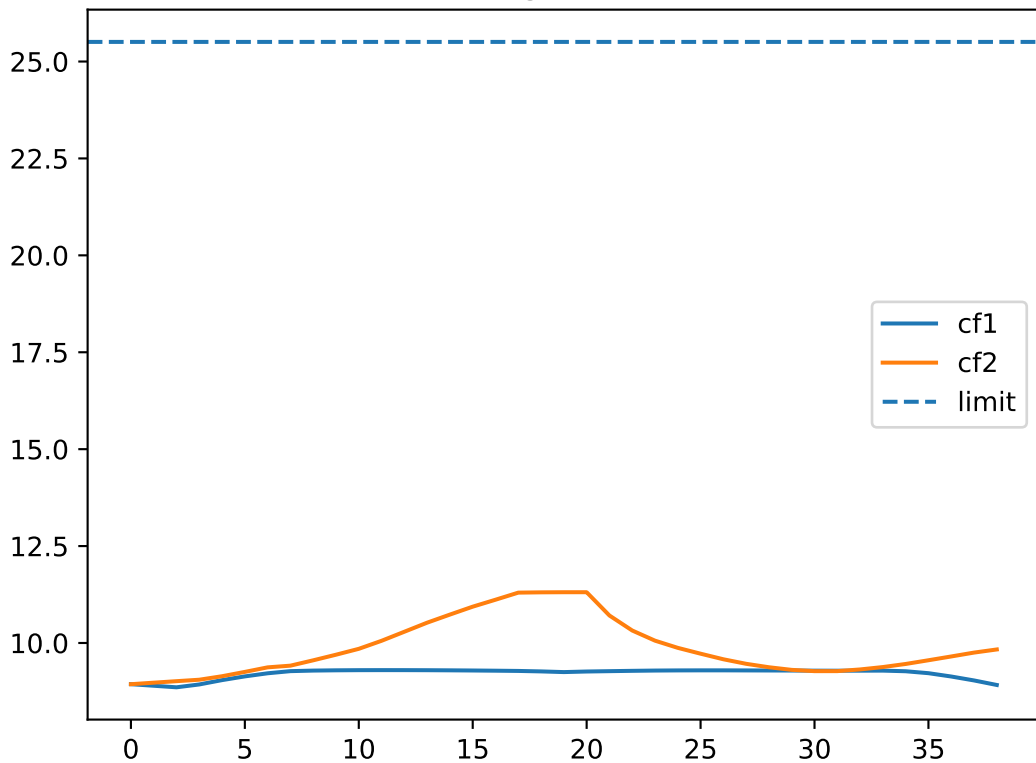
distance (iter 1)



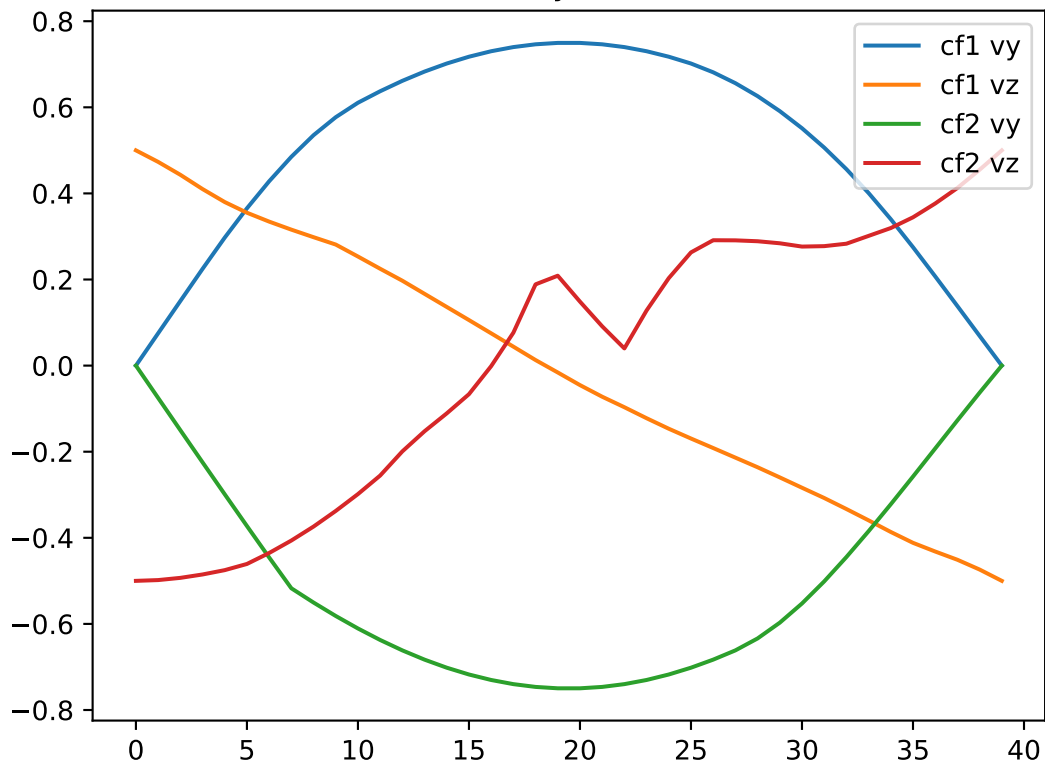
control (iter 1)



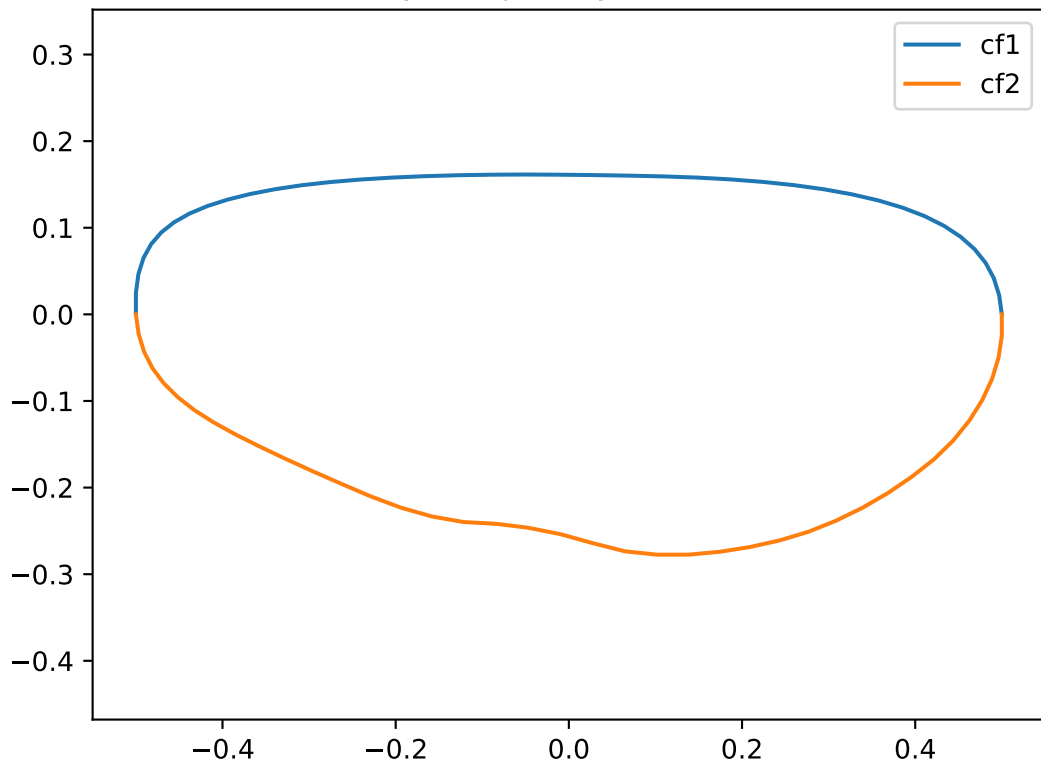
thrust magnitude (iter 1)



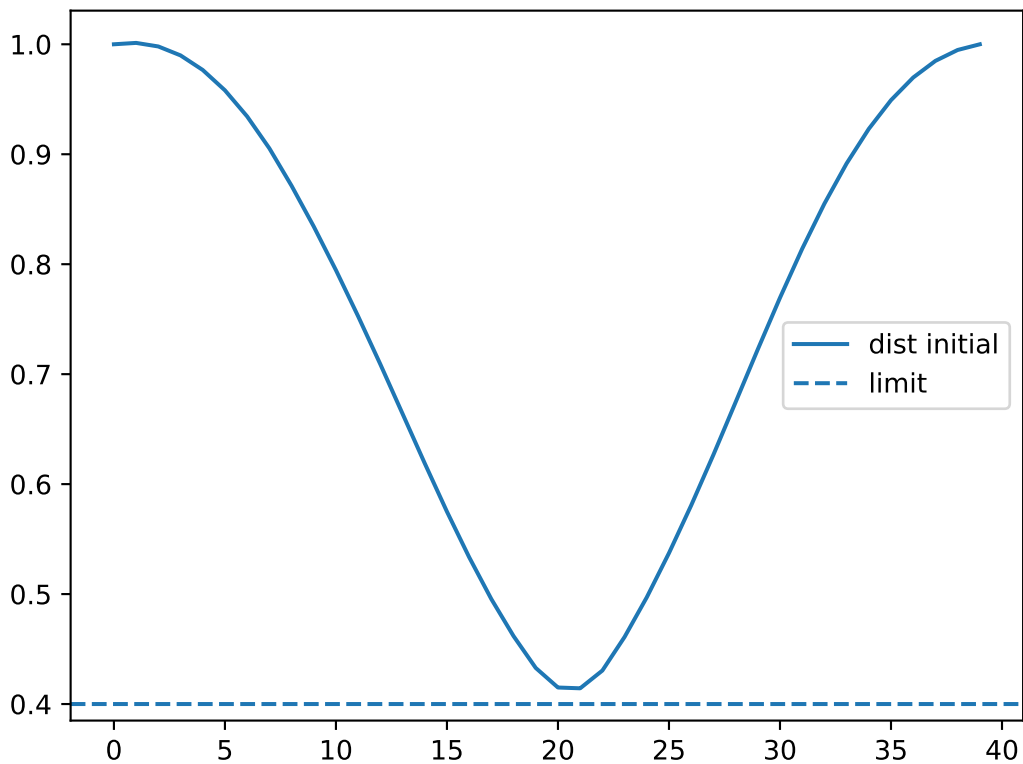
velocity (iter 1)



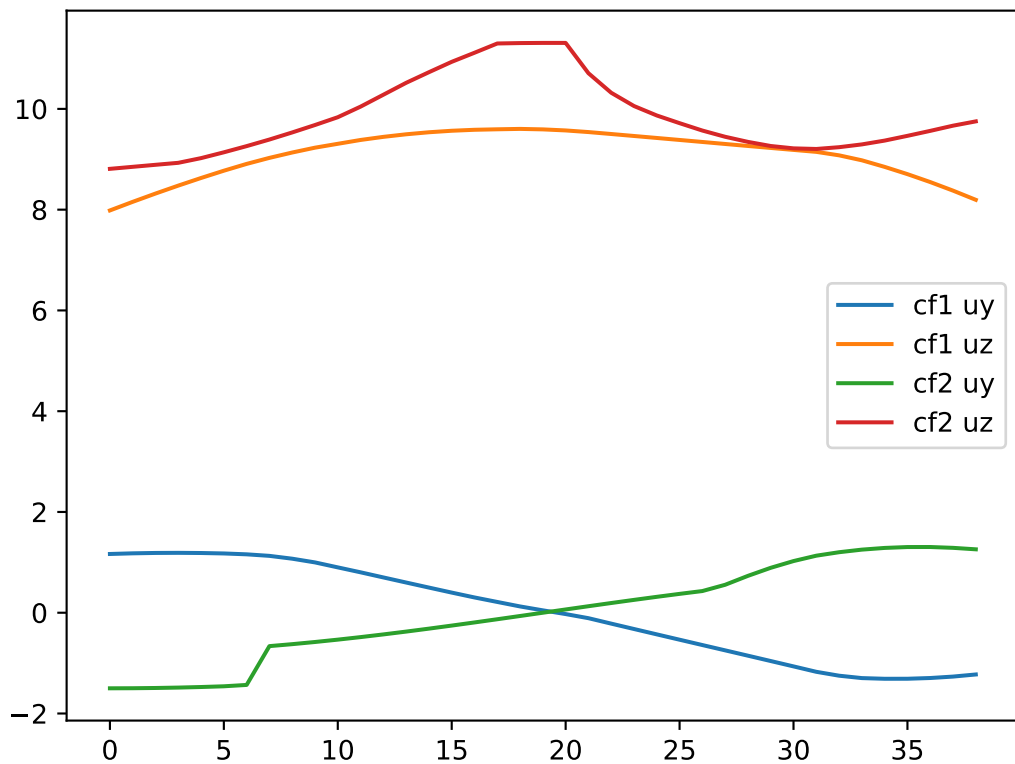
y-z trajectory (iter 2)



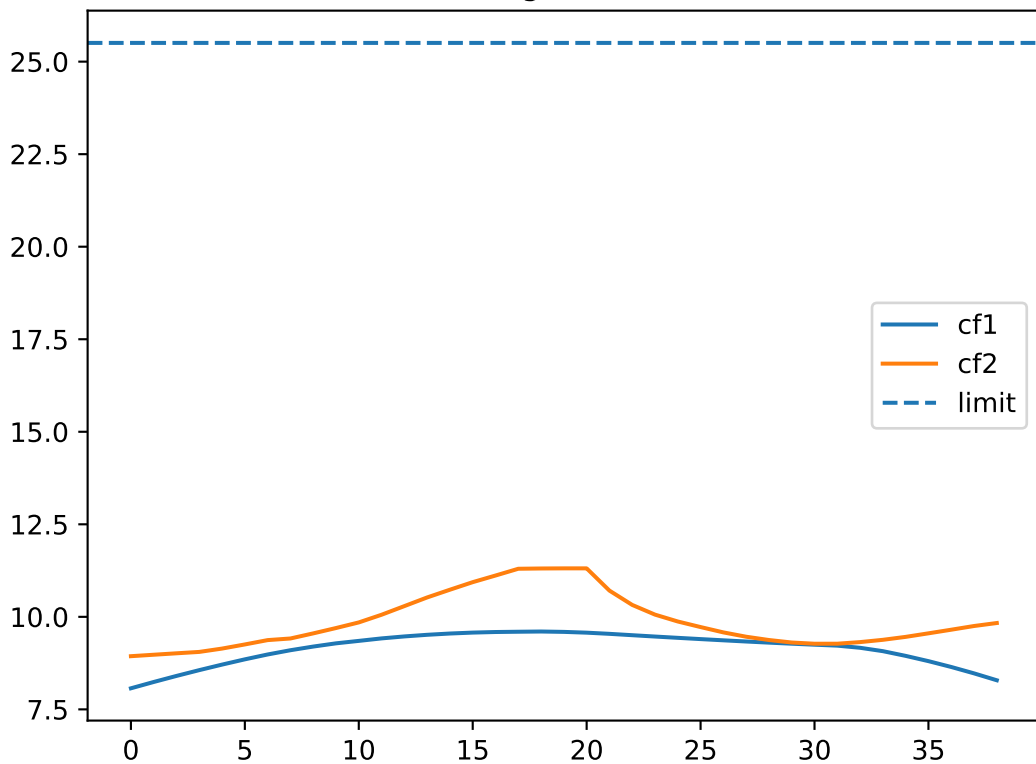
distance (iter 2)



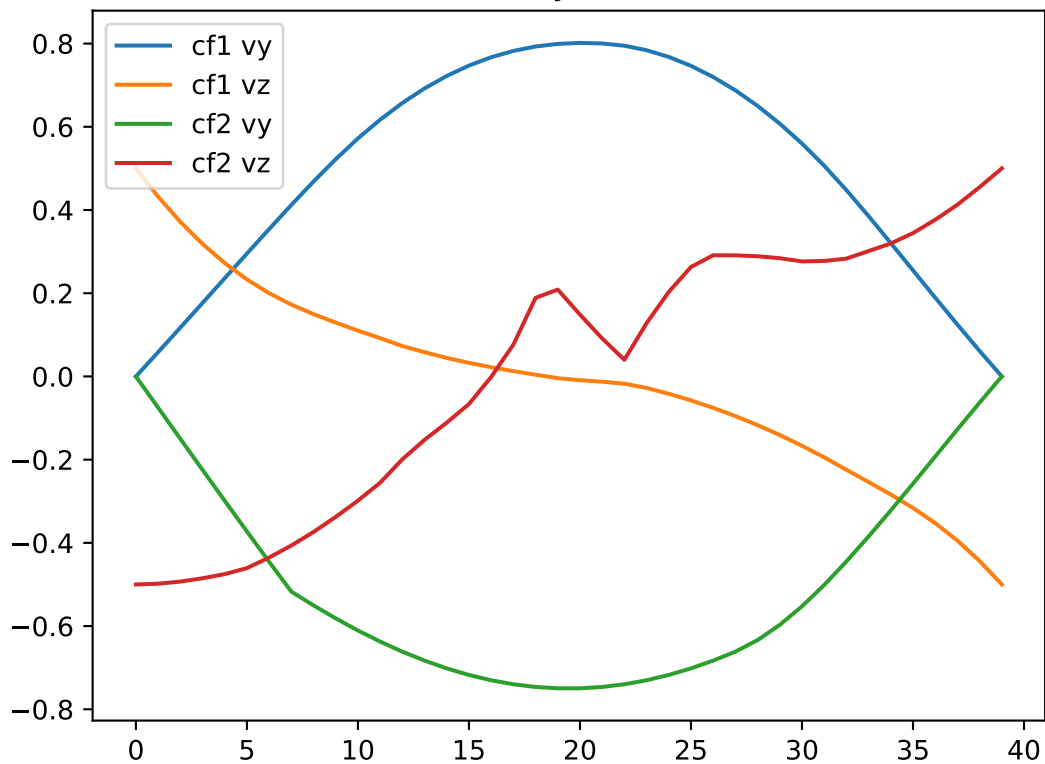
control (iter 2)



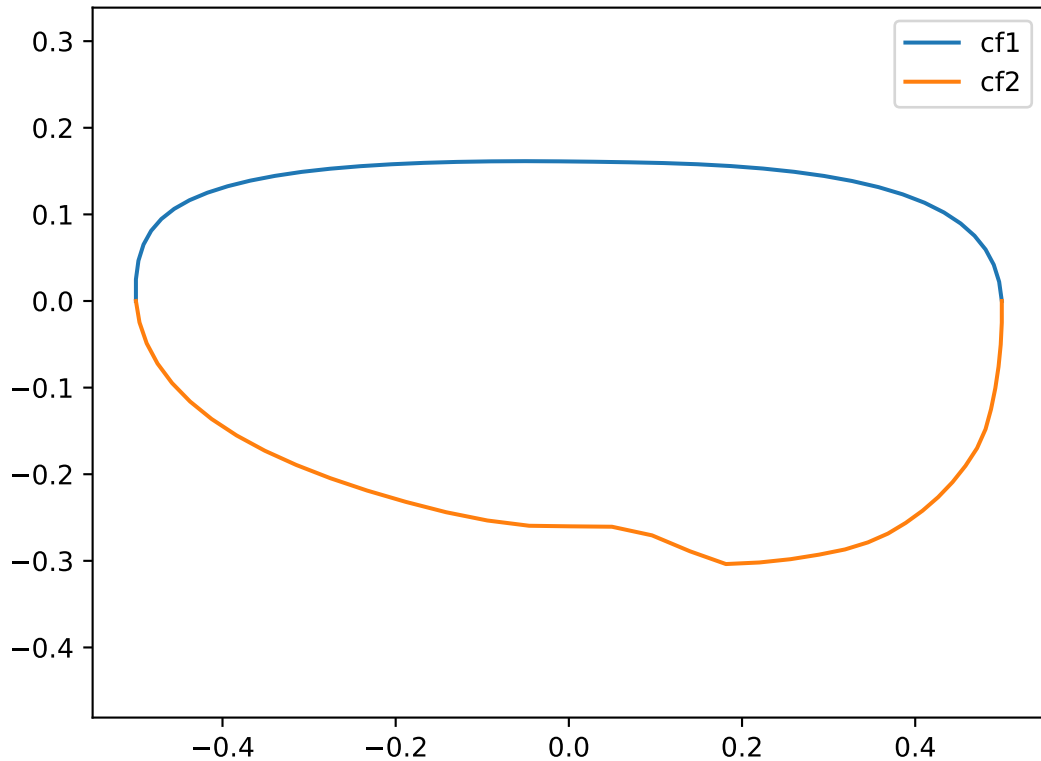
thrust magnitude (iter 2)



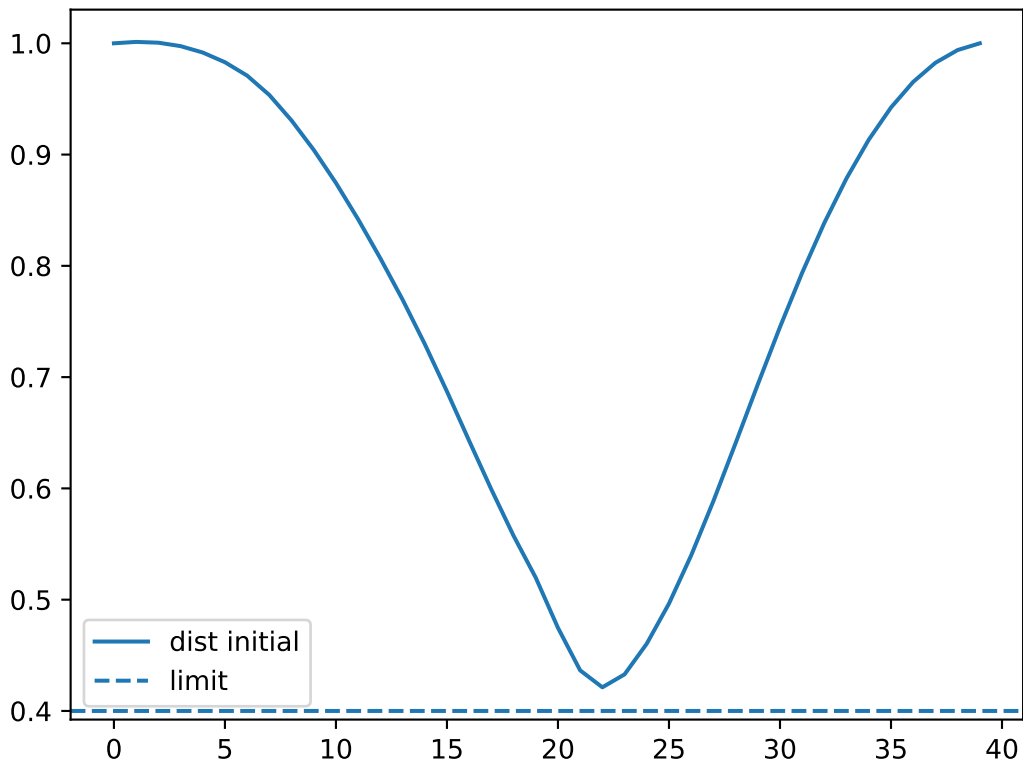
velocity (iter 2)



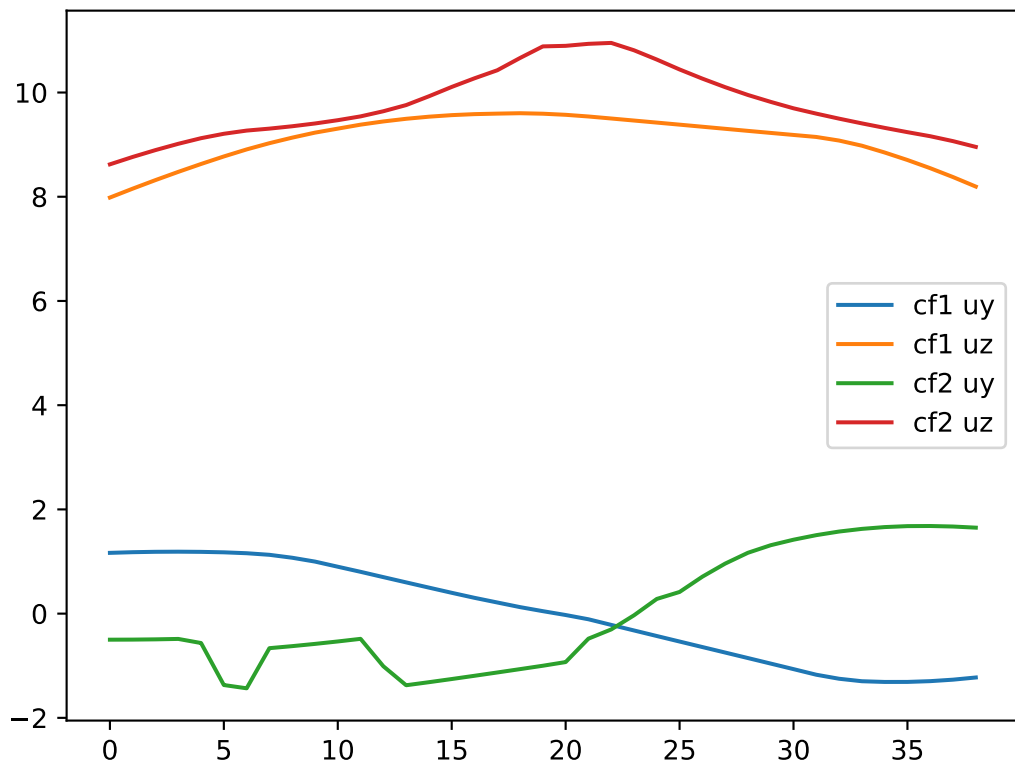
y-z trajectory (iter 3)



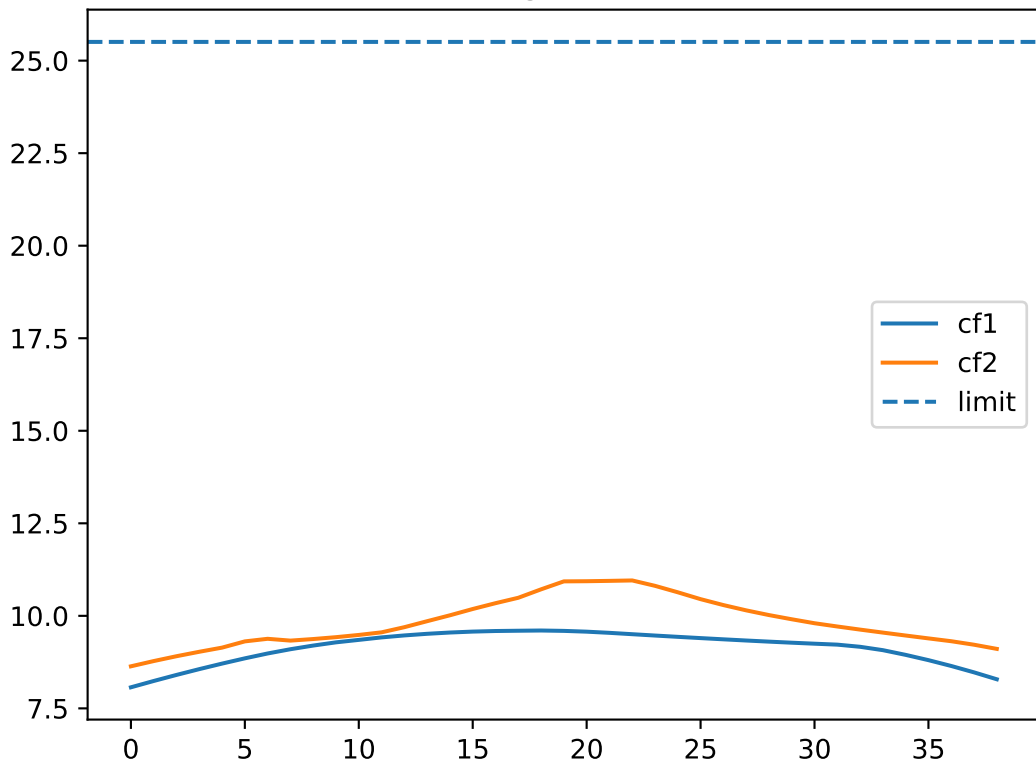
distance (iter 3)



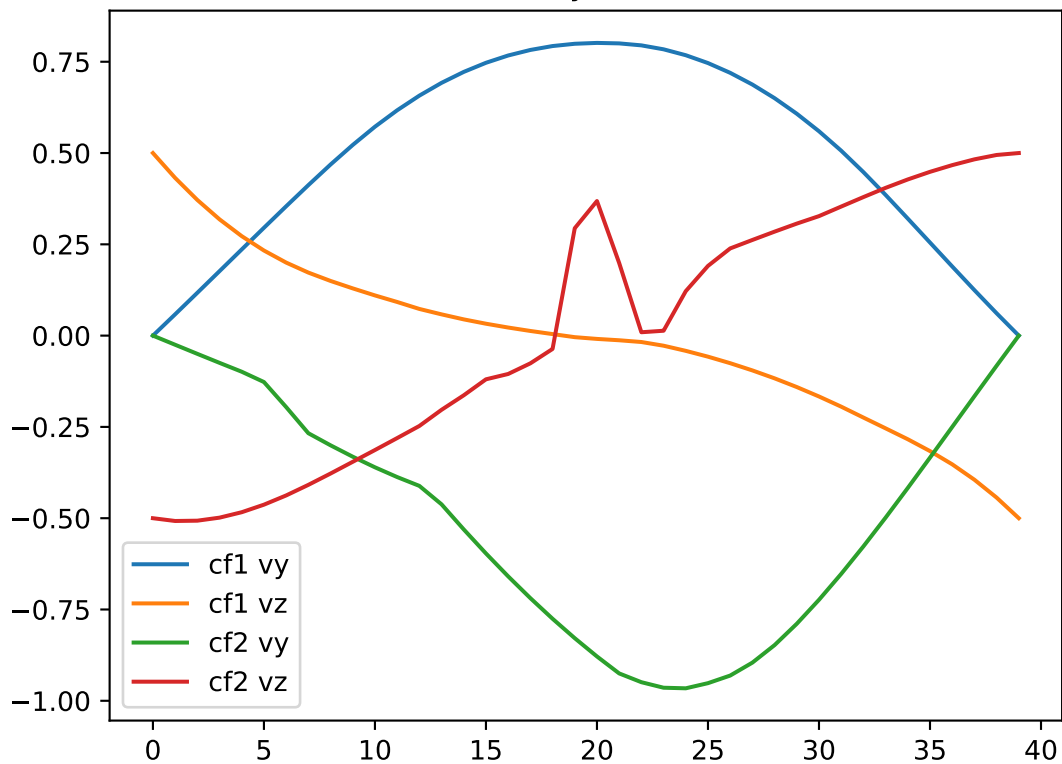
control (iter 3)



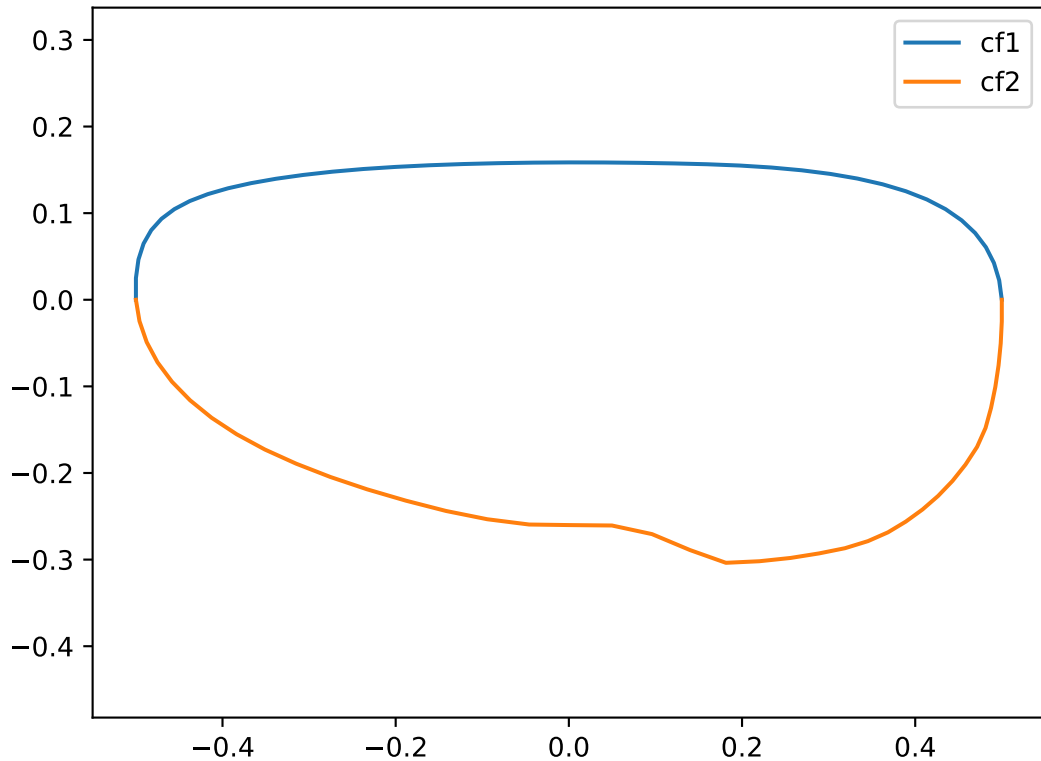
thrust magnitude (iter 3)



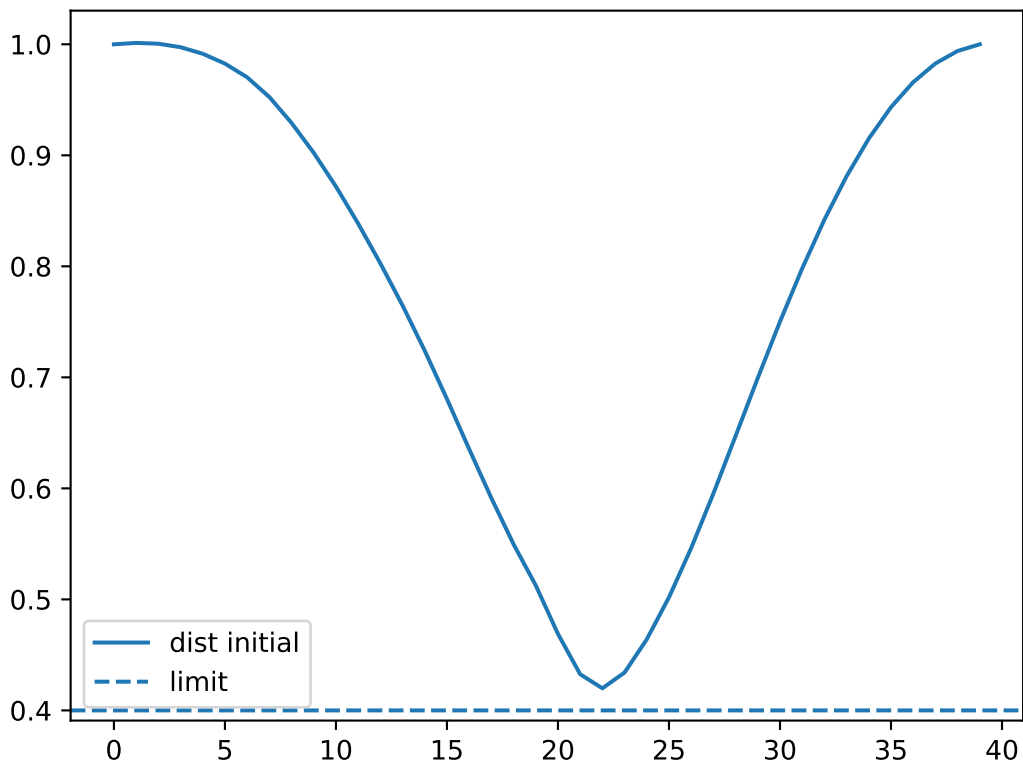
velocity (iter 3)



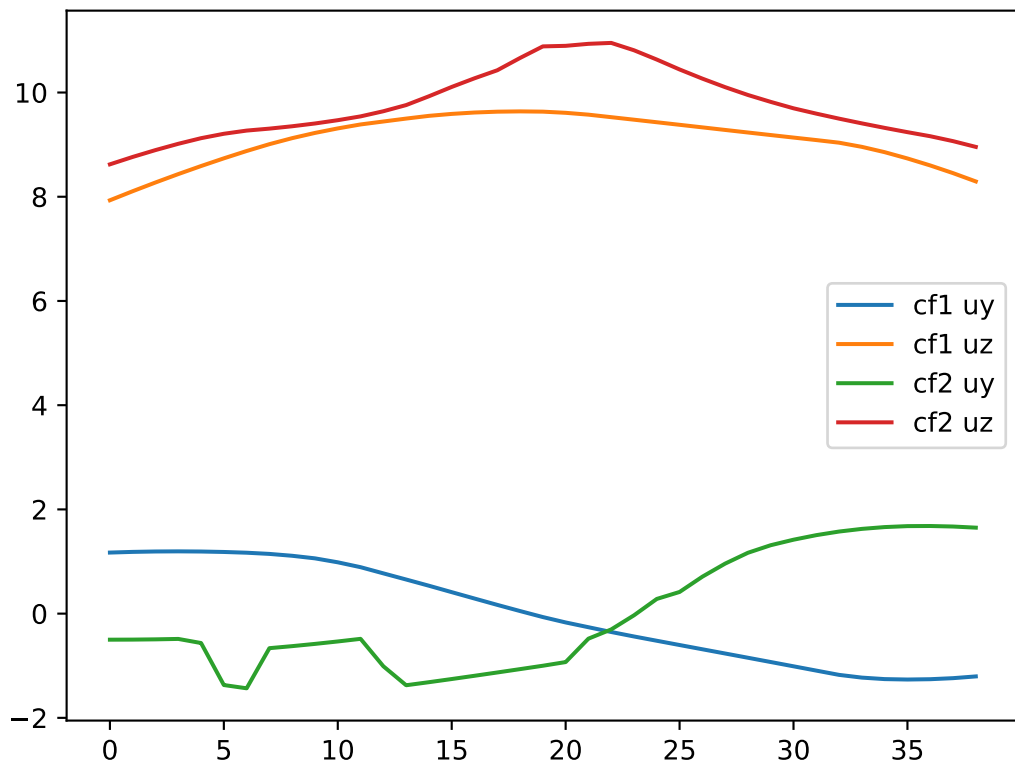
y-z trajectory (iter 4)



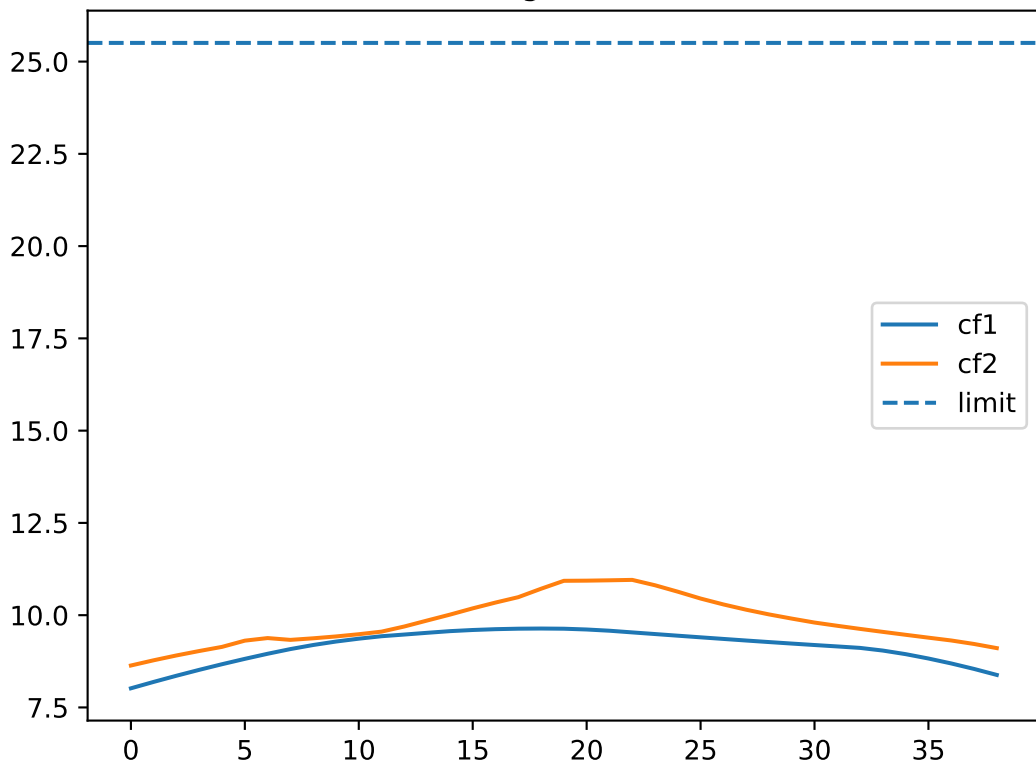
distance (iter 4)



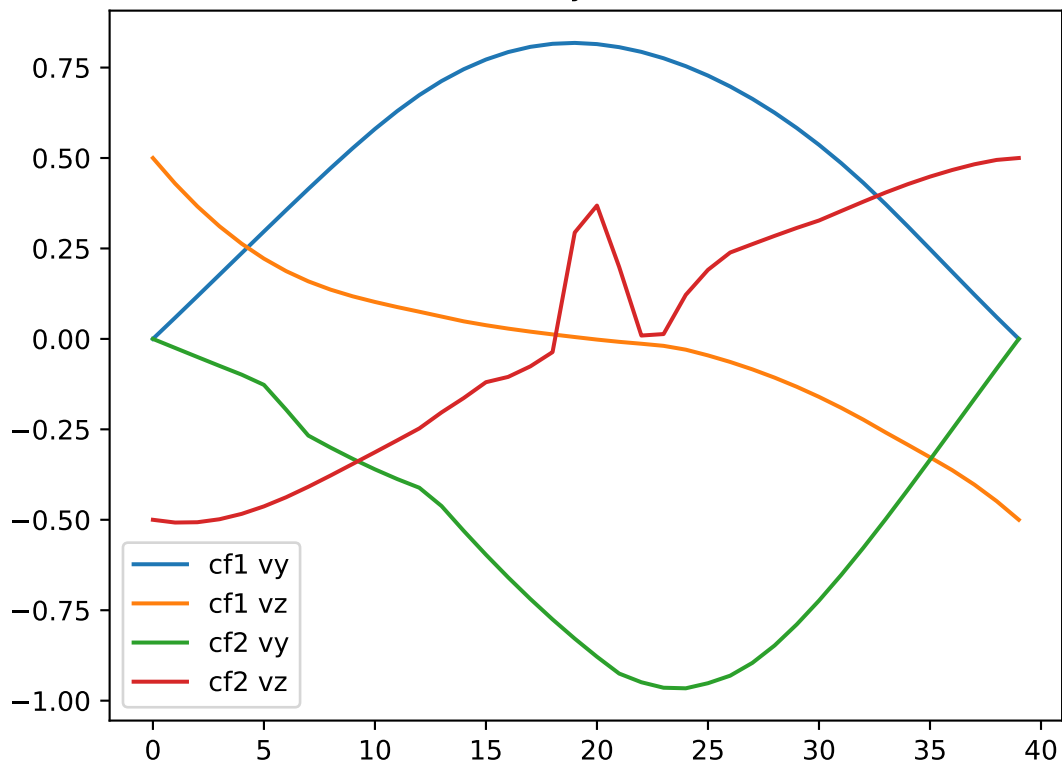
control (iter 4)



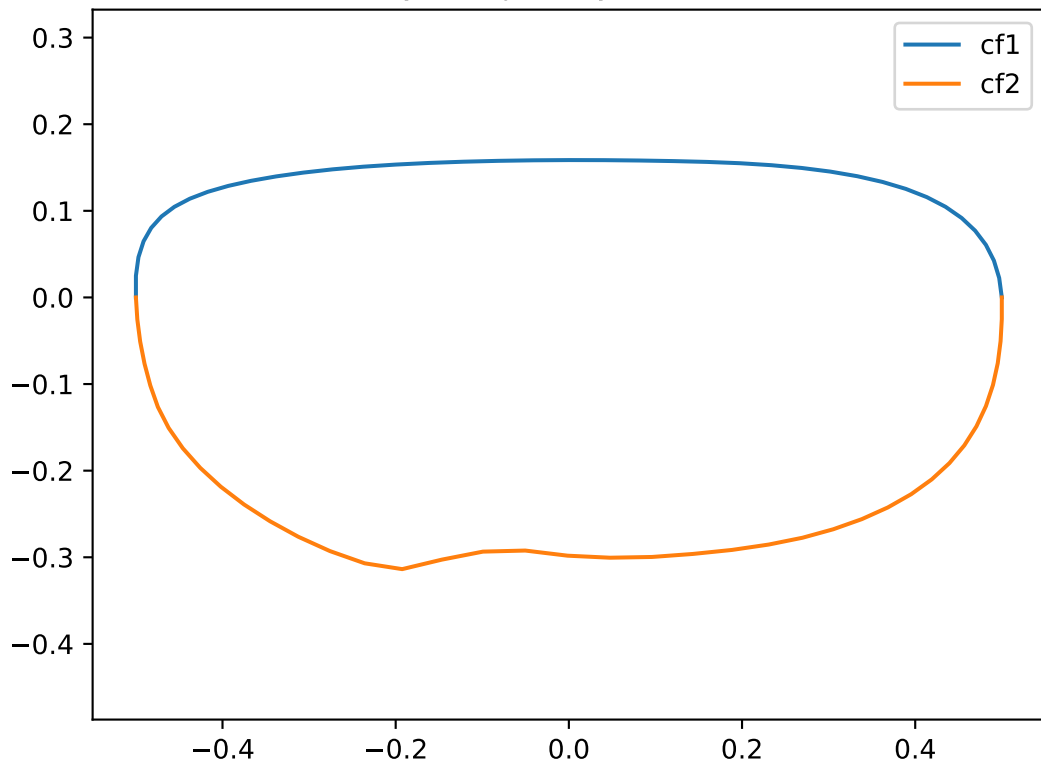
thrust magnitude (iter 4)



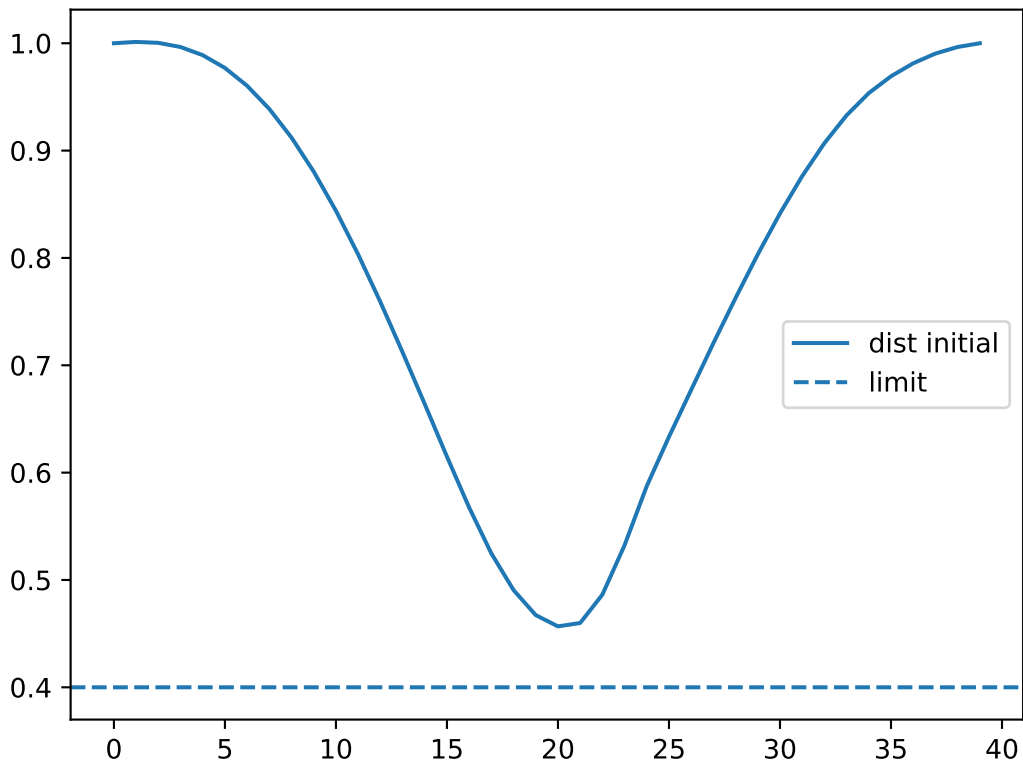
velocity (iter 4)



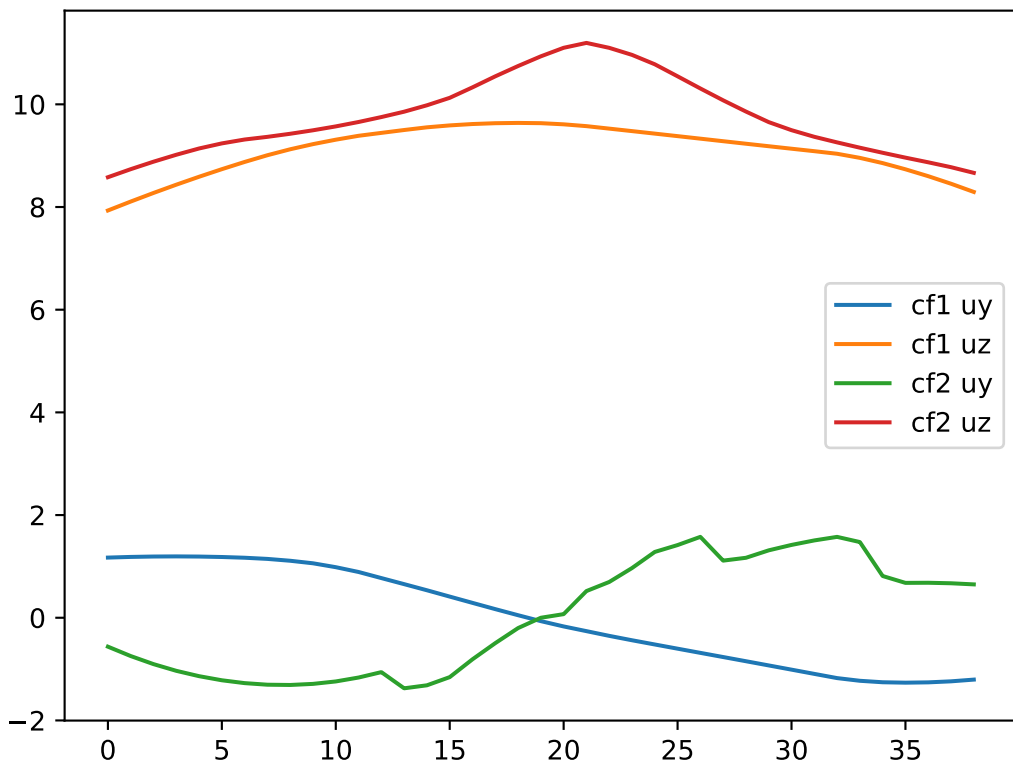
y-z trajectory (iter 5)



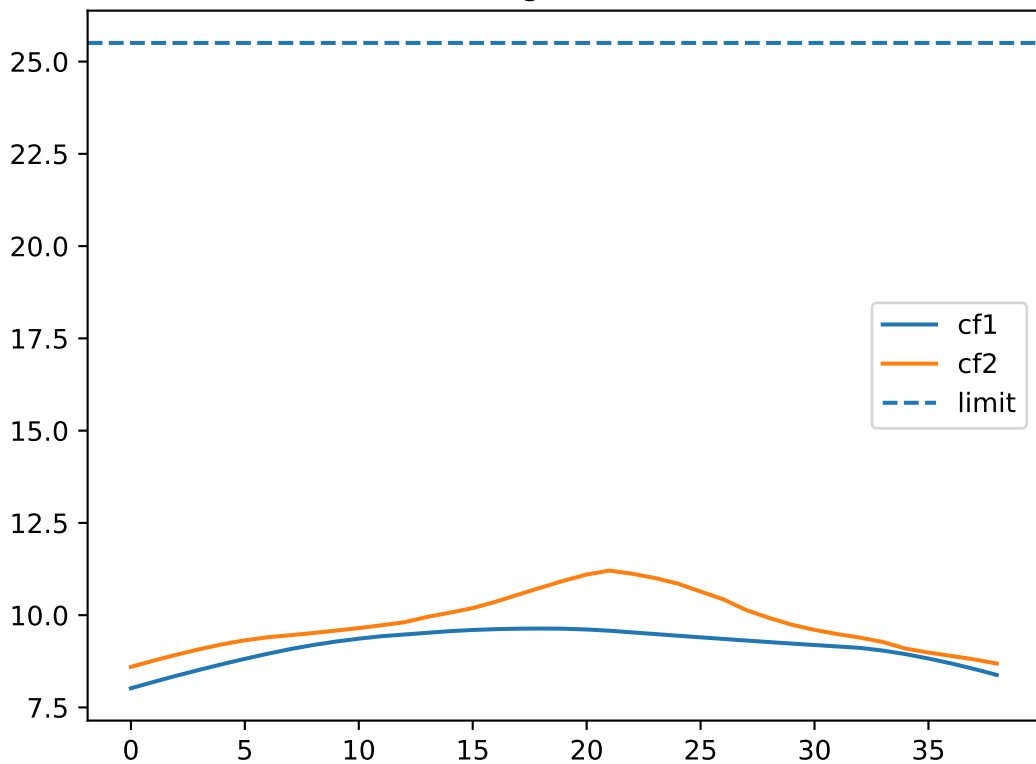
distance (iter 5)



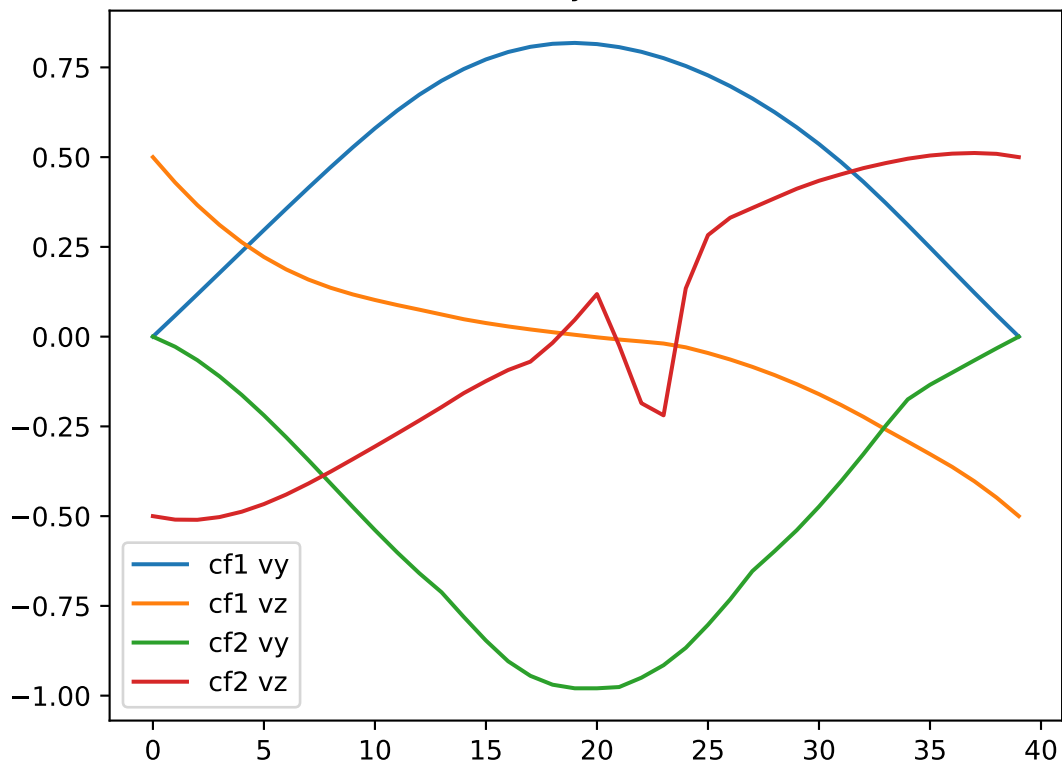
control (iter 5)



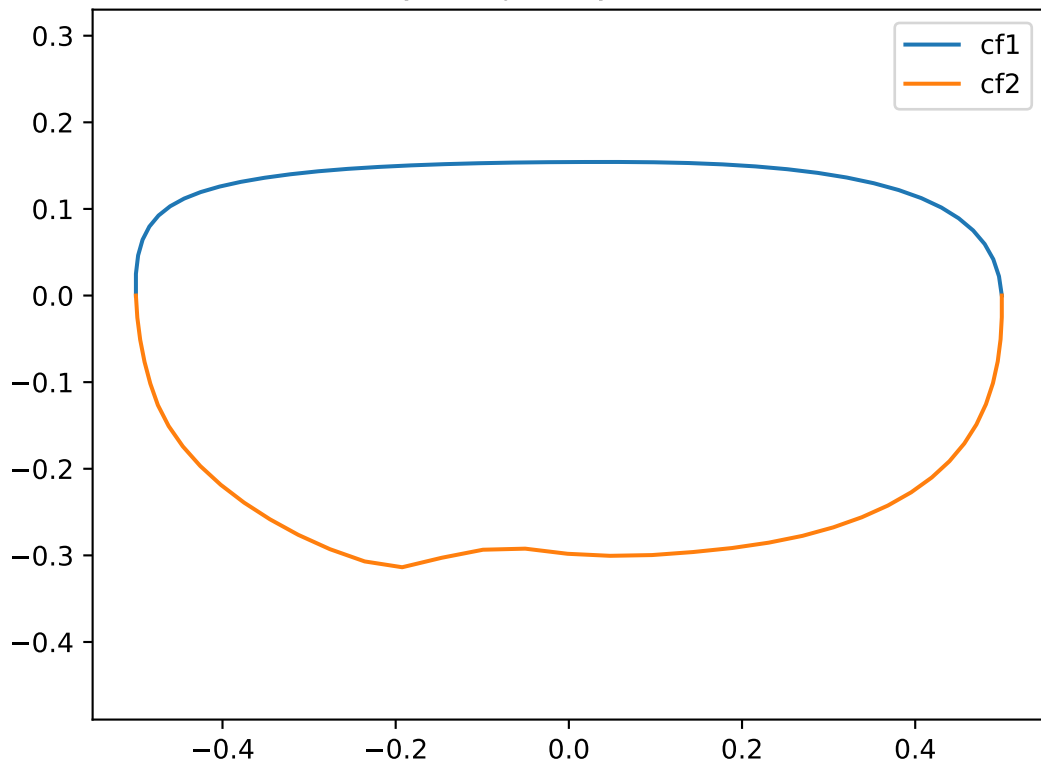
thrust magnitude (iter 5)



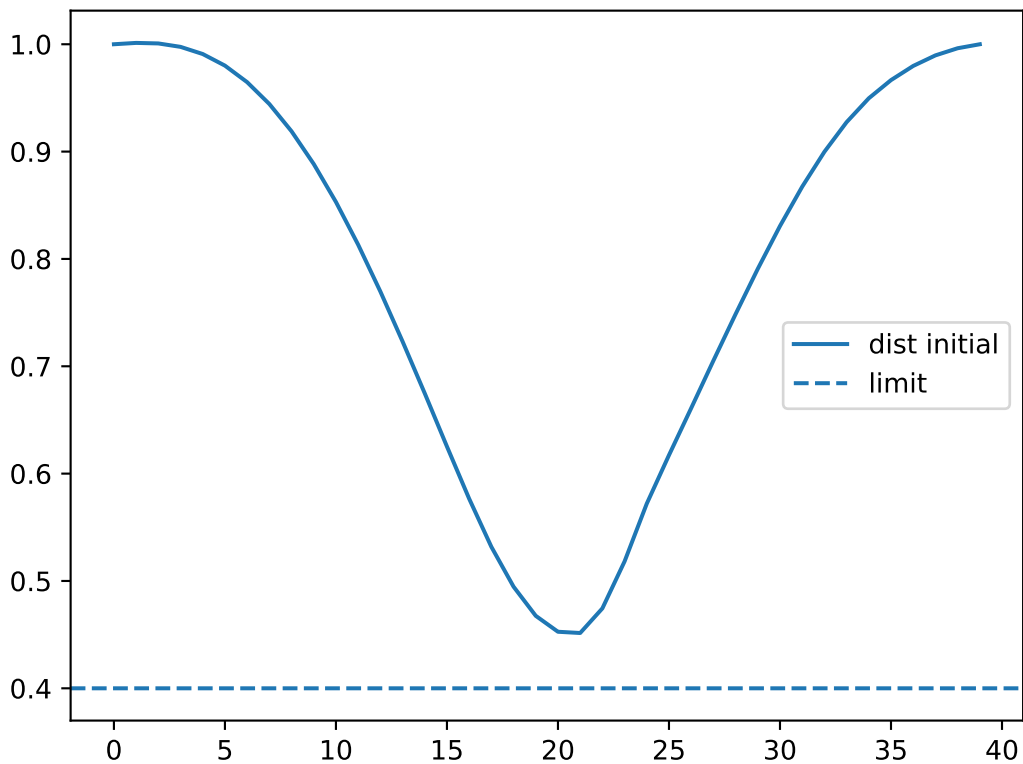
velocity (iter 5)



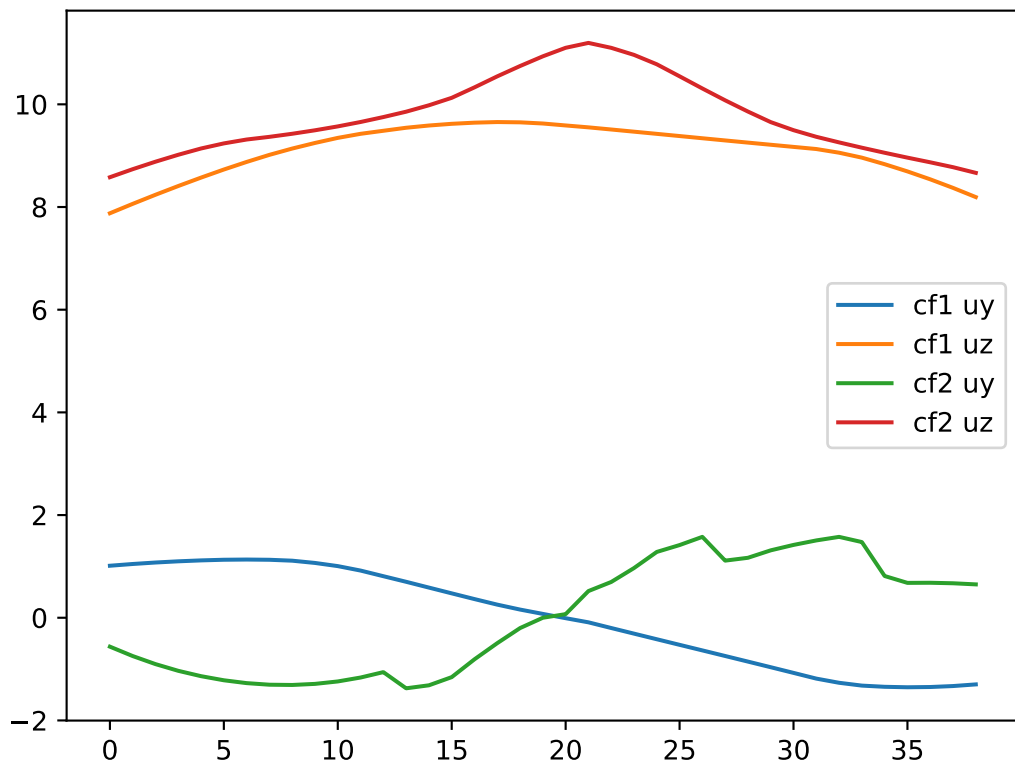
y-z trajectory (iter 6)



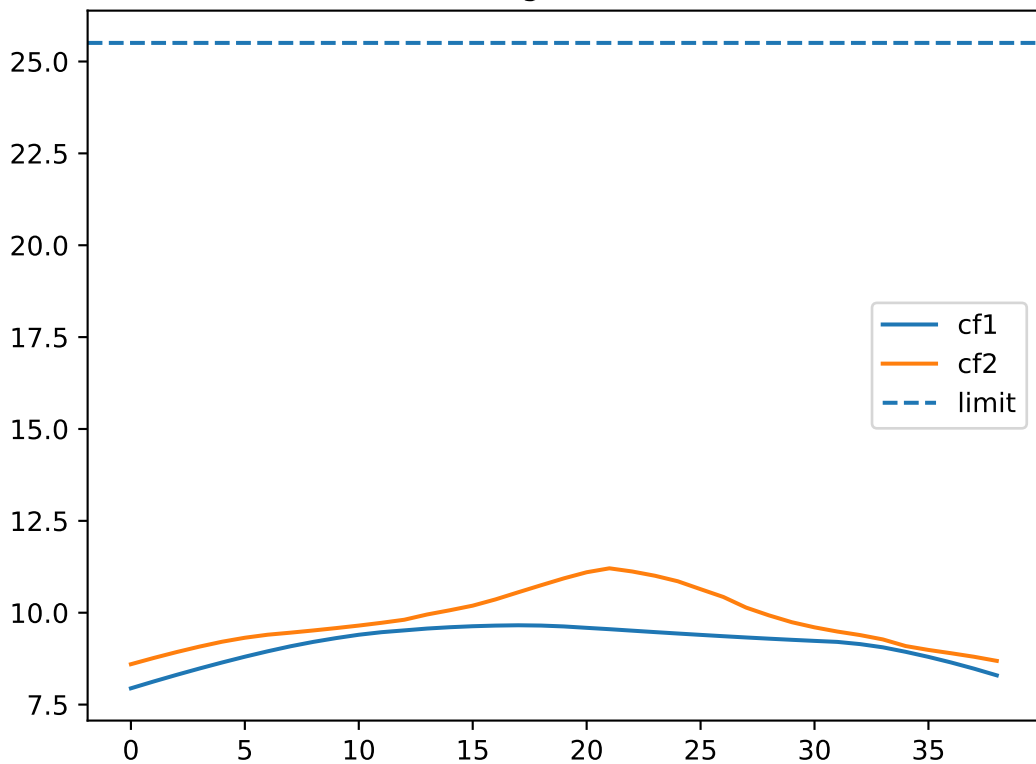
distance (iter 6)



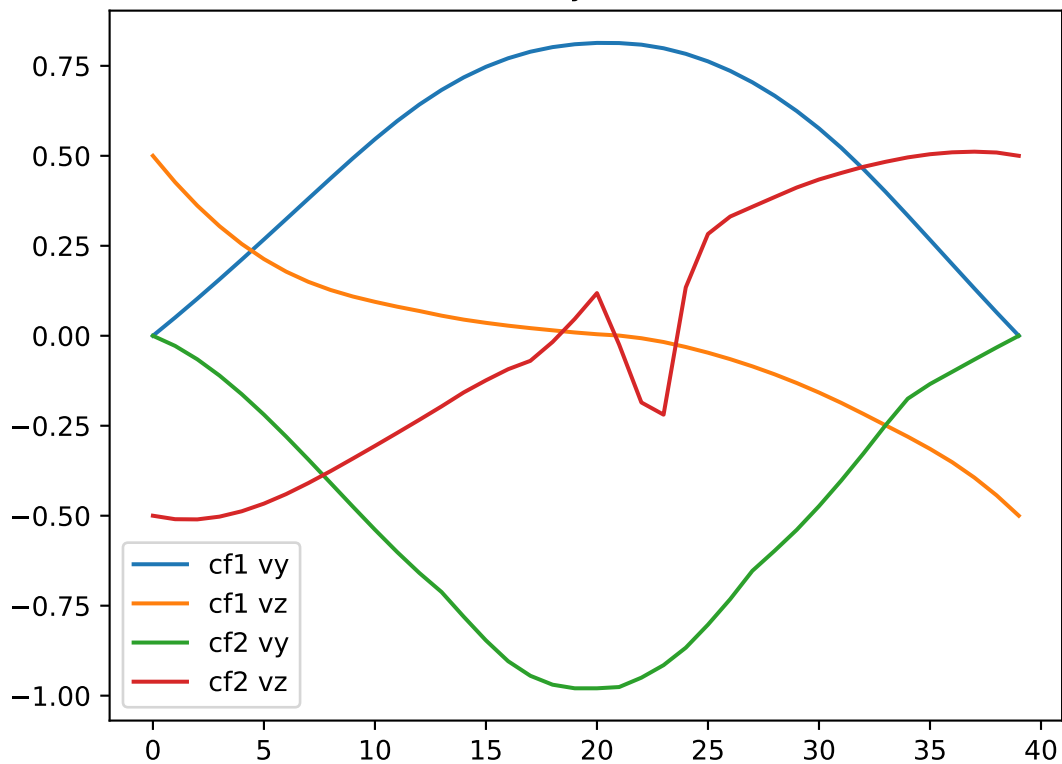
control (iter 6)



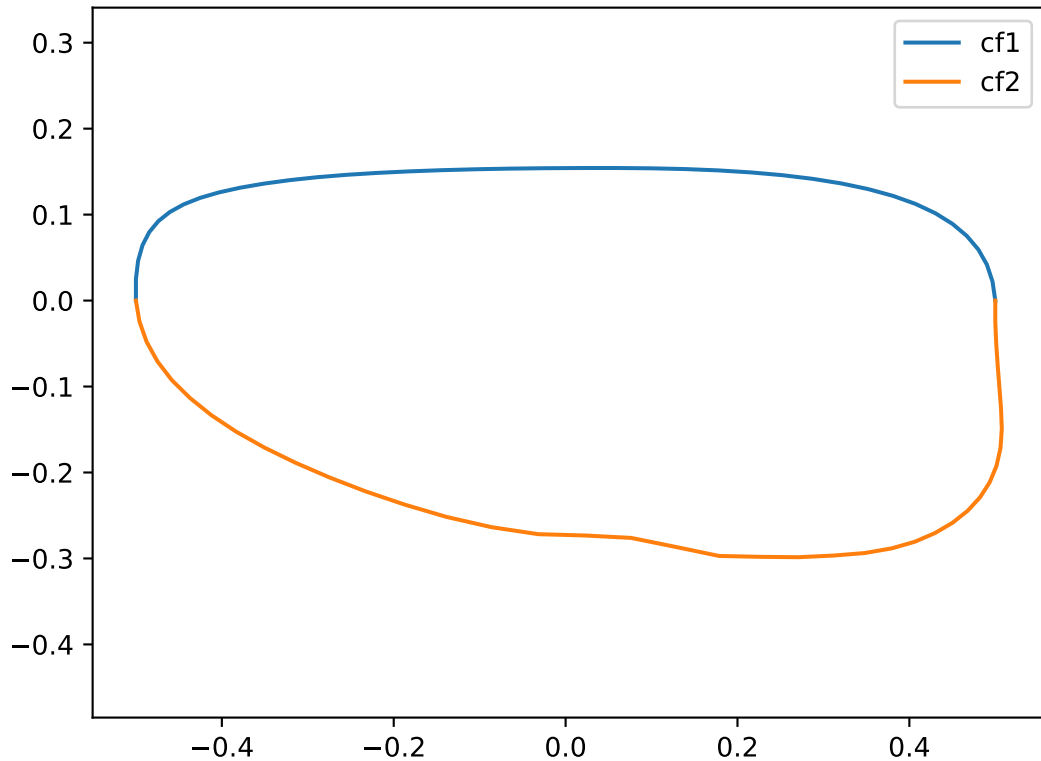
thrust magnitude (iter 6)



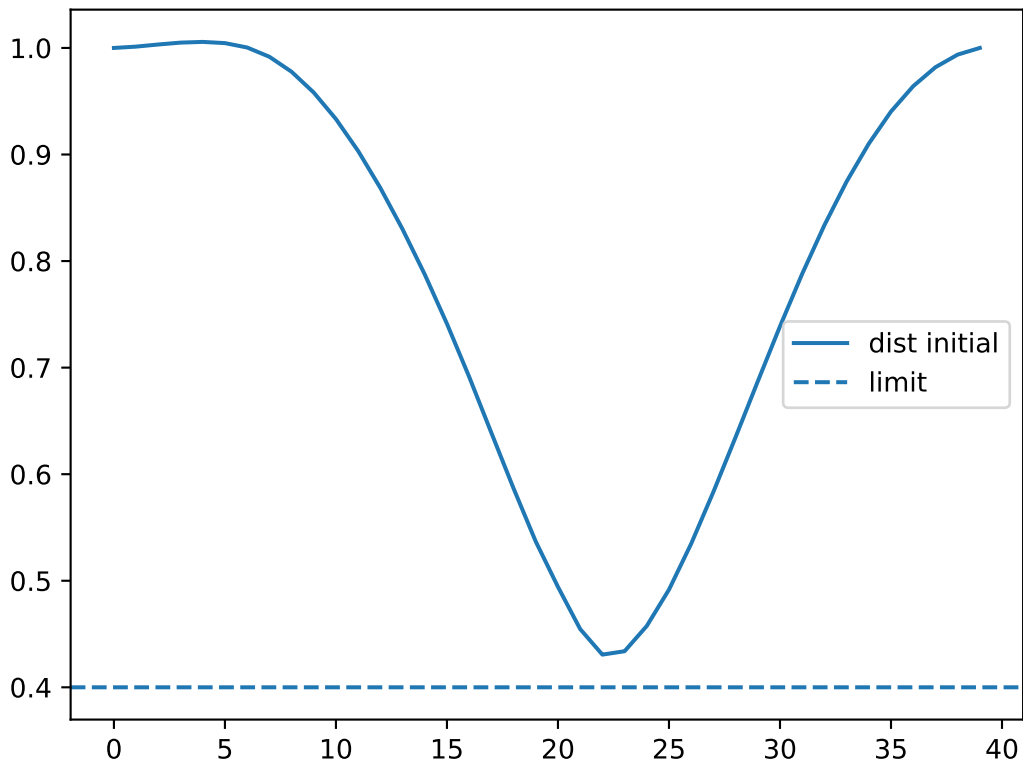
velocity (iter 6)



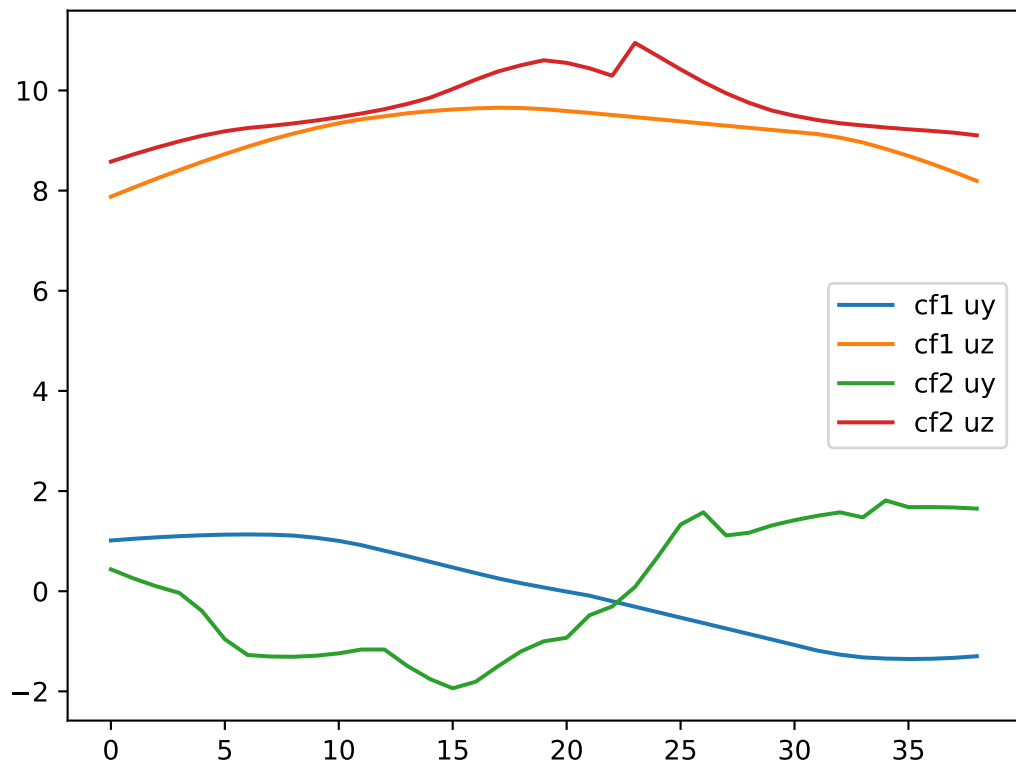
y-z trajectory (iter 7)



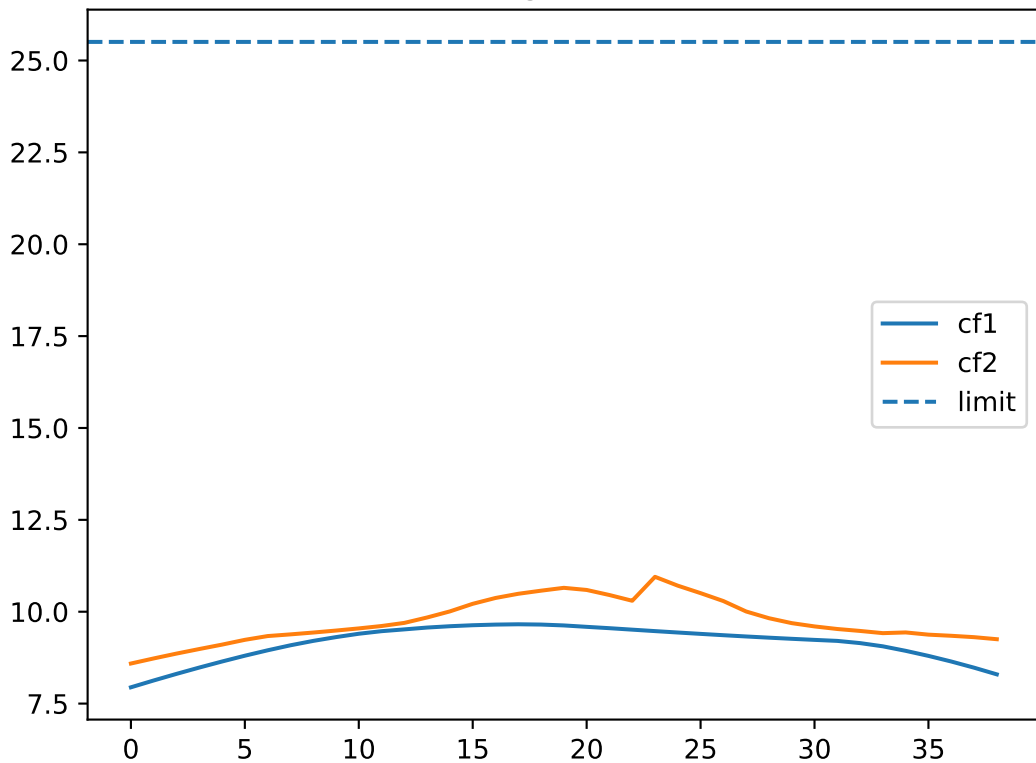
distance (iter 7)



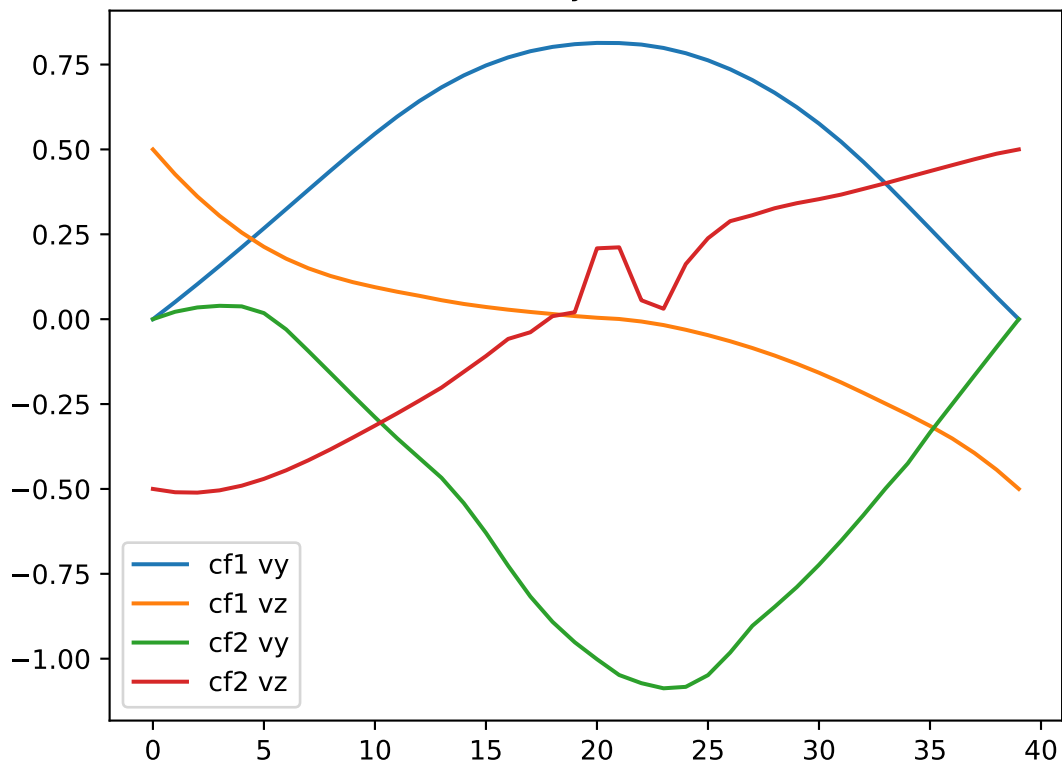
control (iter 7)



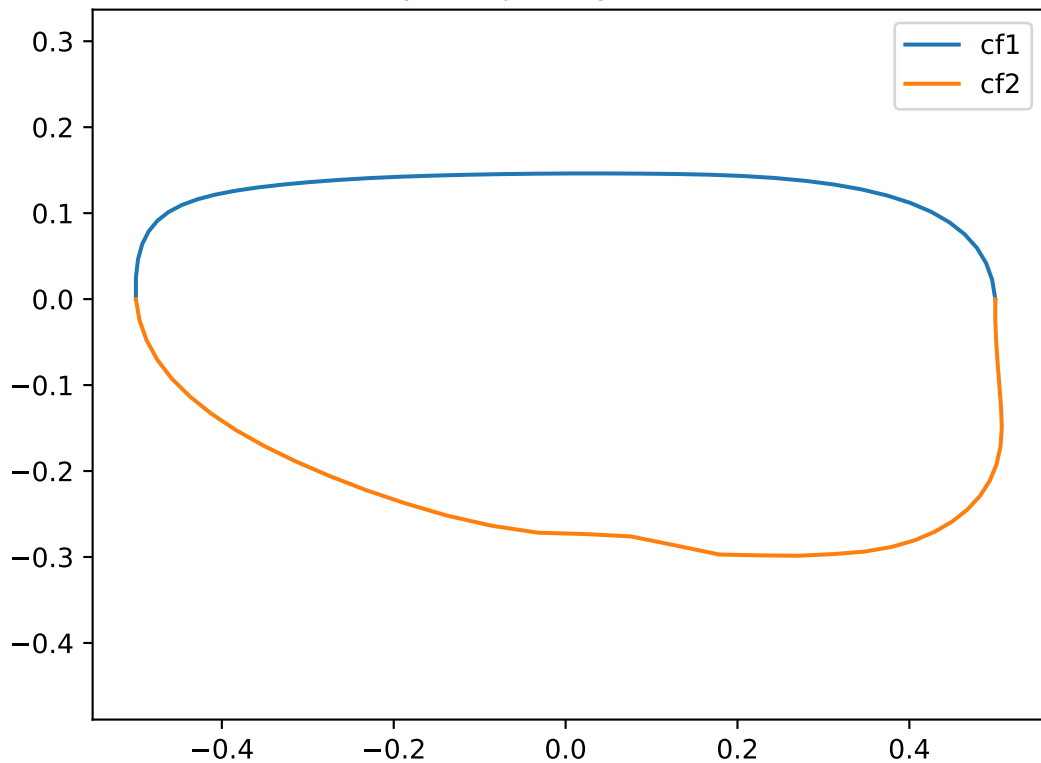
thrust magnitude (iter 7)



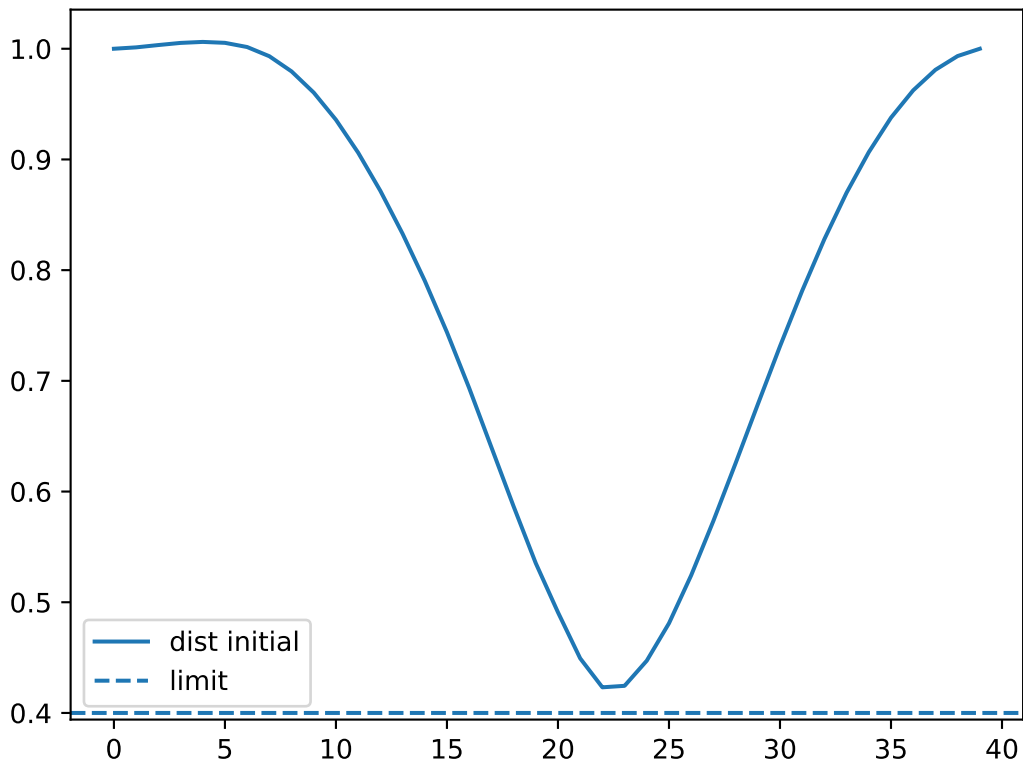
velocity (iter 7)



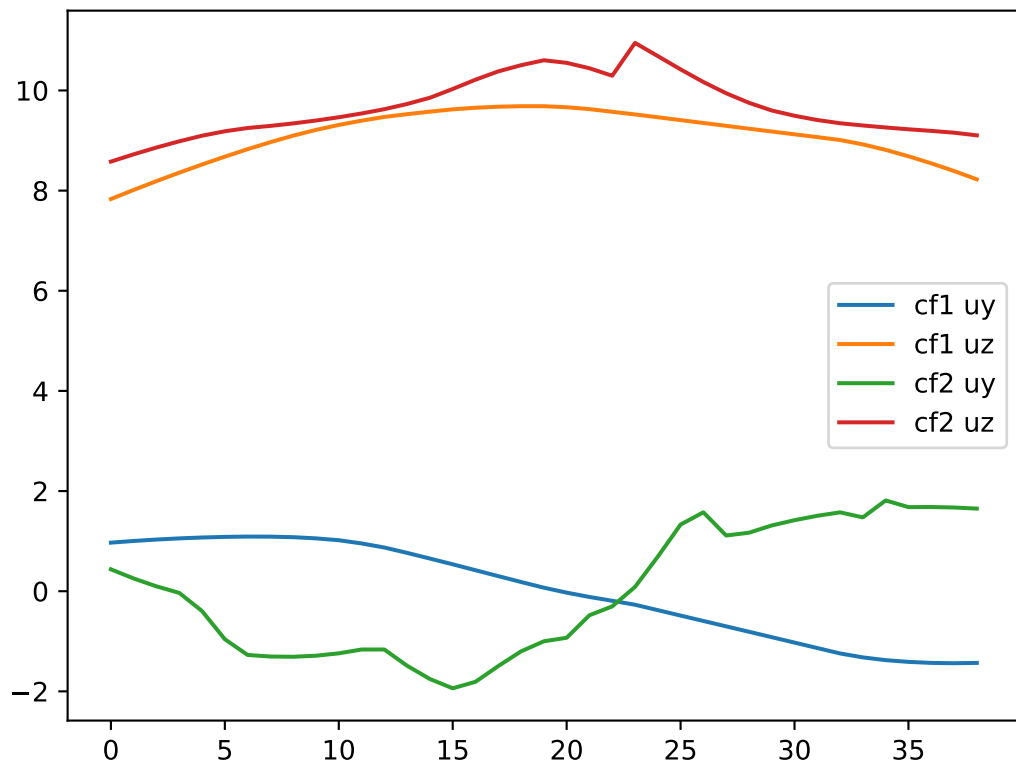
y-z trajectory (iter 8)



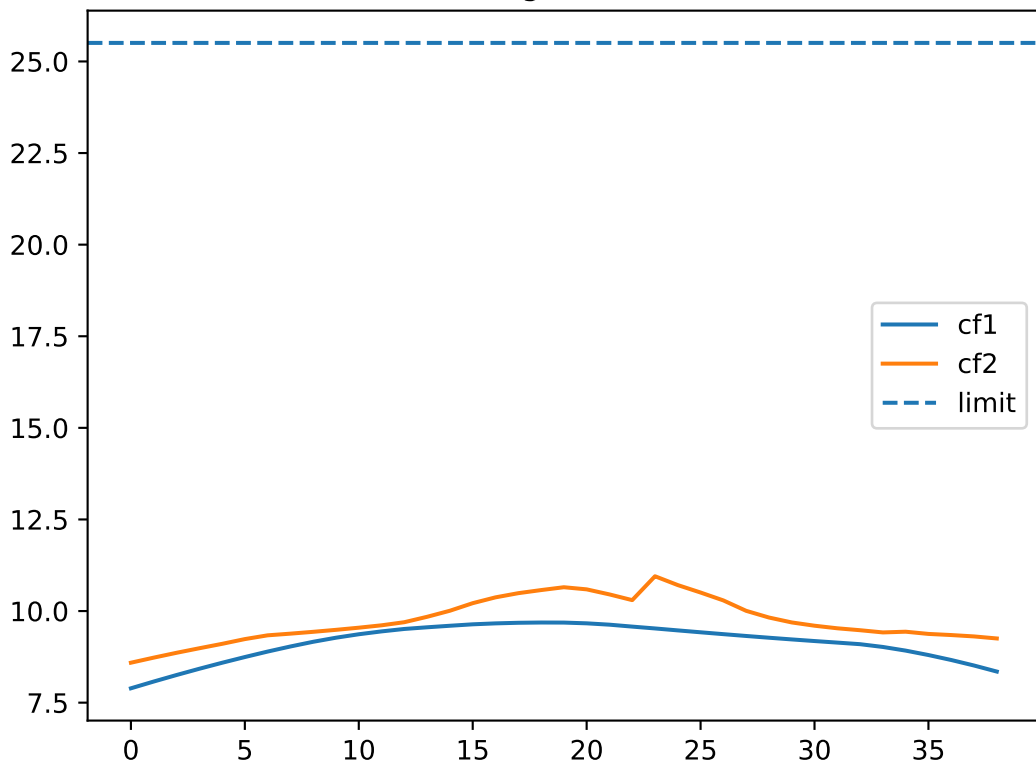
distance (iter 8)



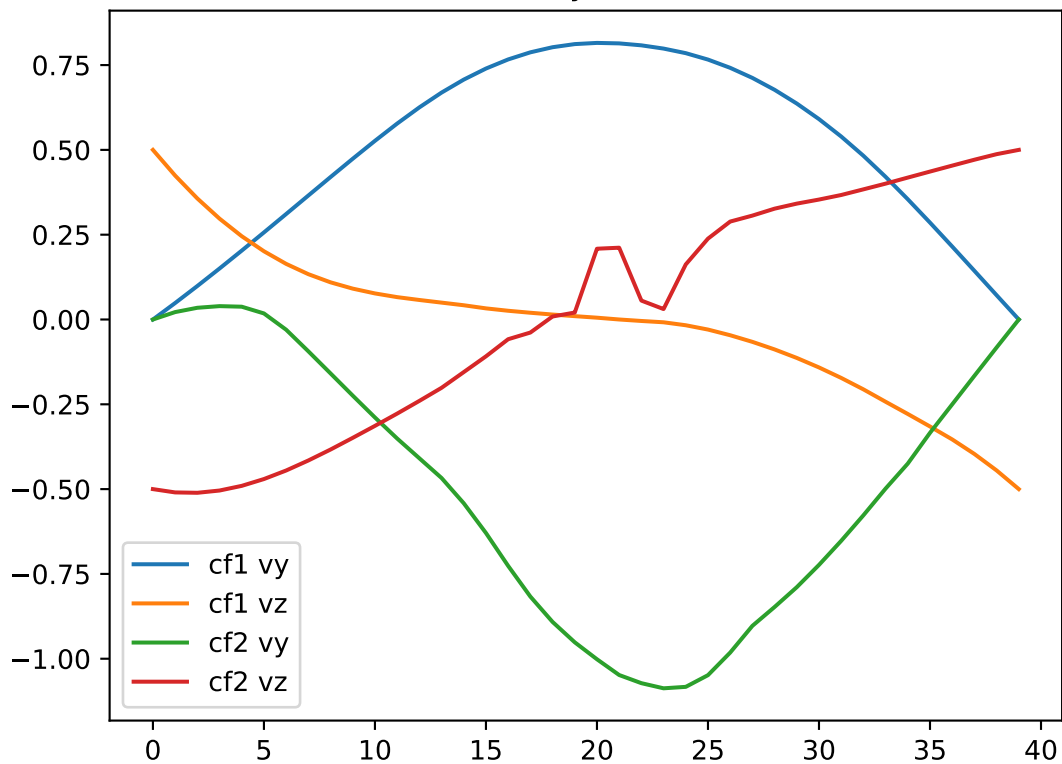
control (iter 8)



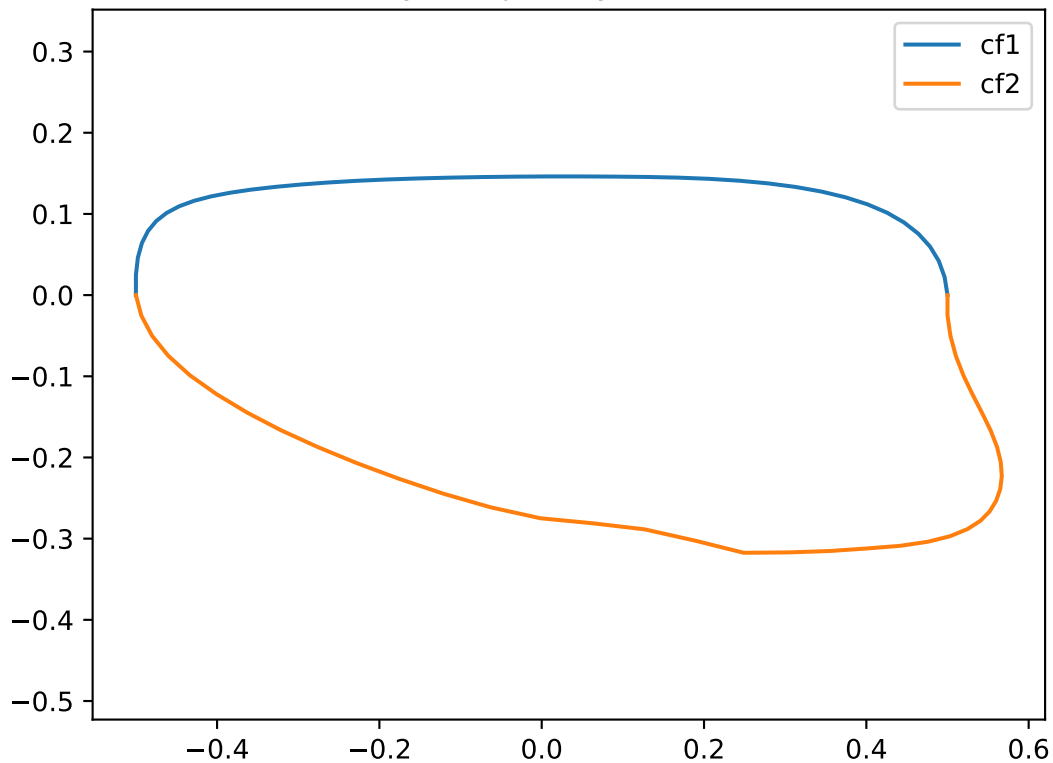
thrust magnitude (iter 8)



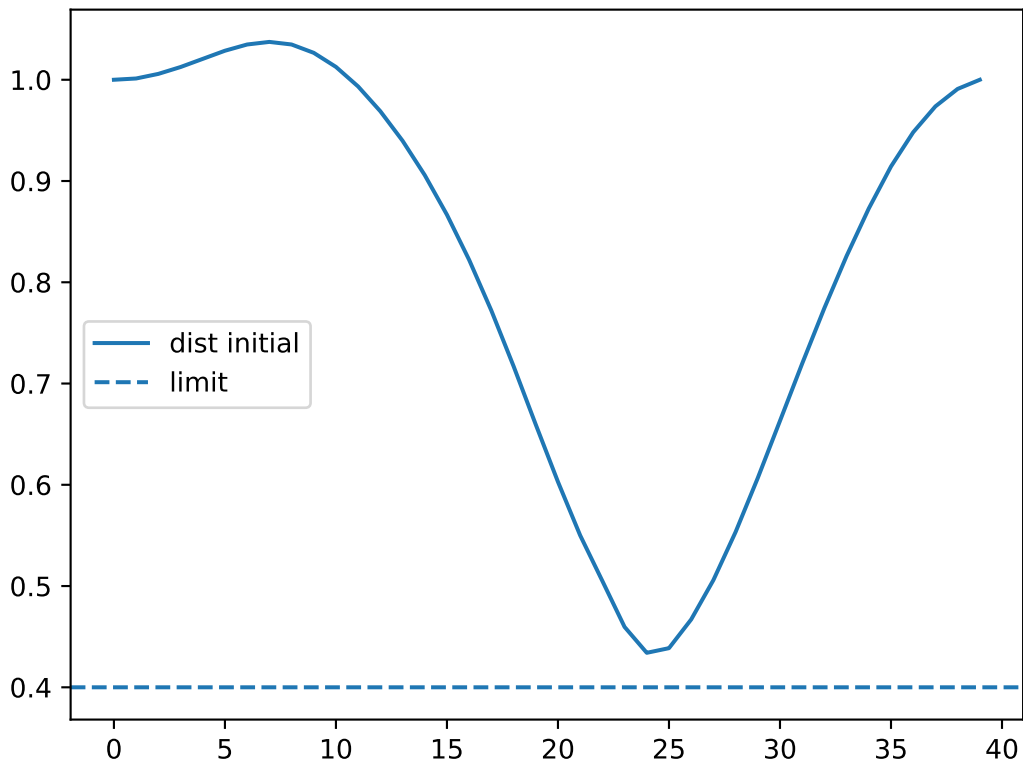
velocity (iter 8)



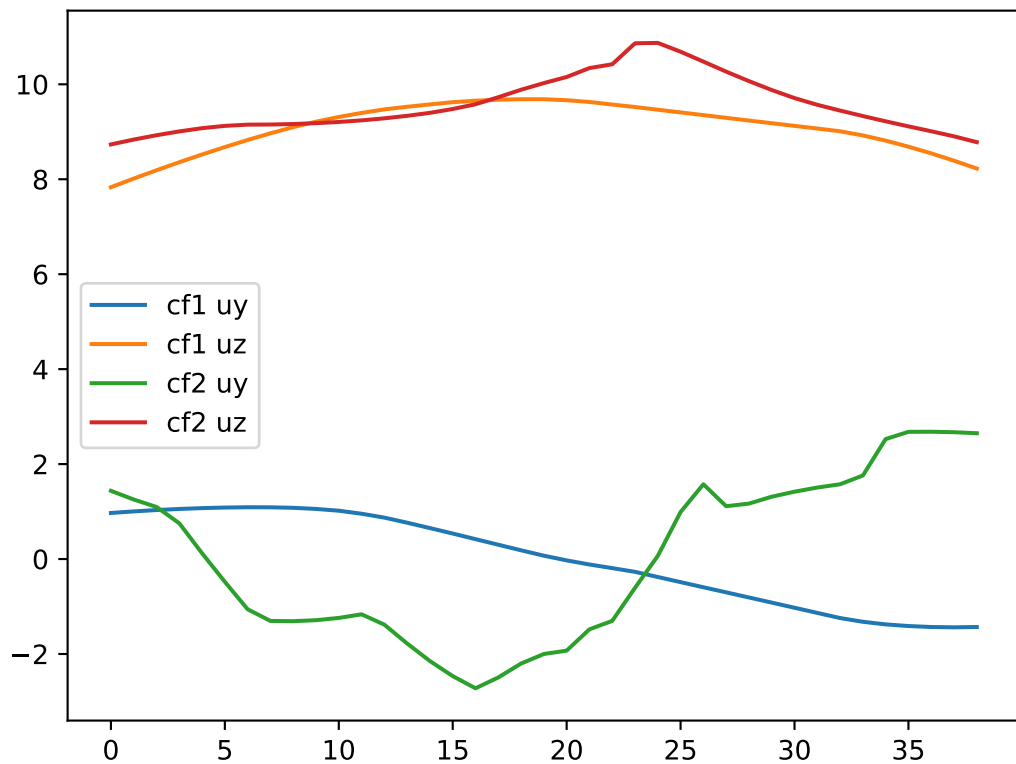
y-z trajectory (iter 9)



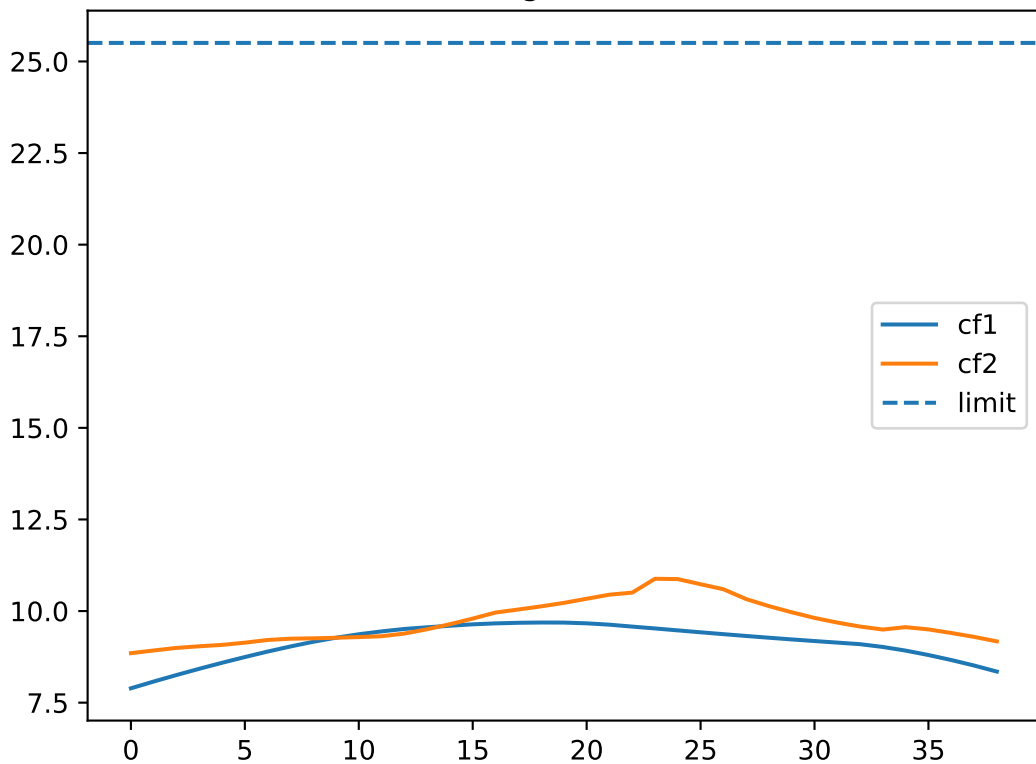
distance (iter 9)



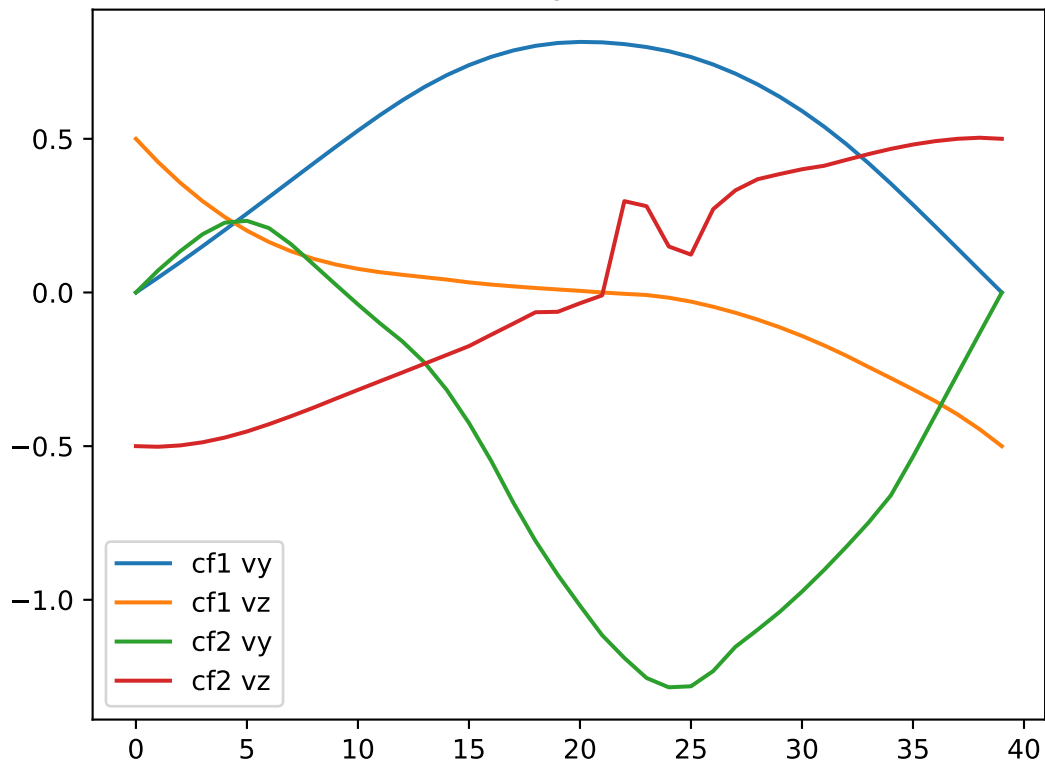
control (iter 9)



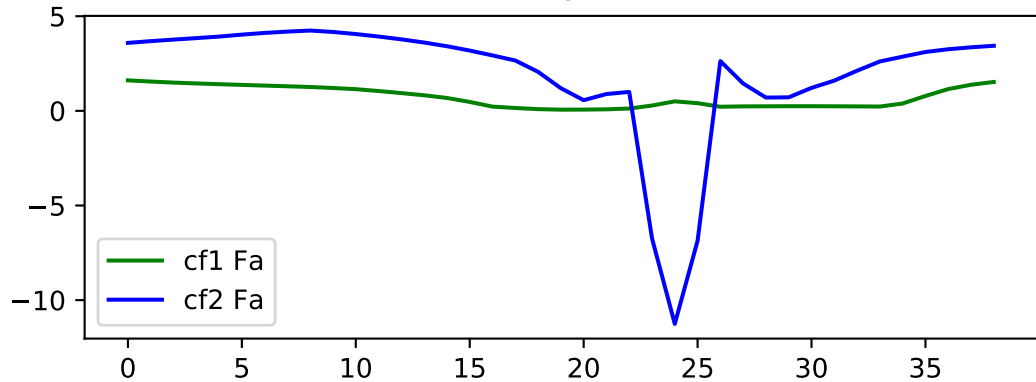
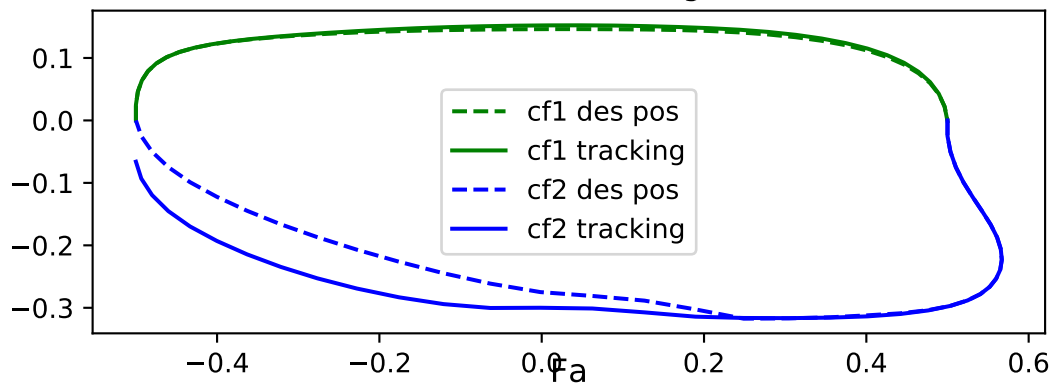
thrust magnitude (iter 9)



velocity (iter 9)



Position tracking



Velocity tracking

