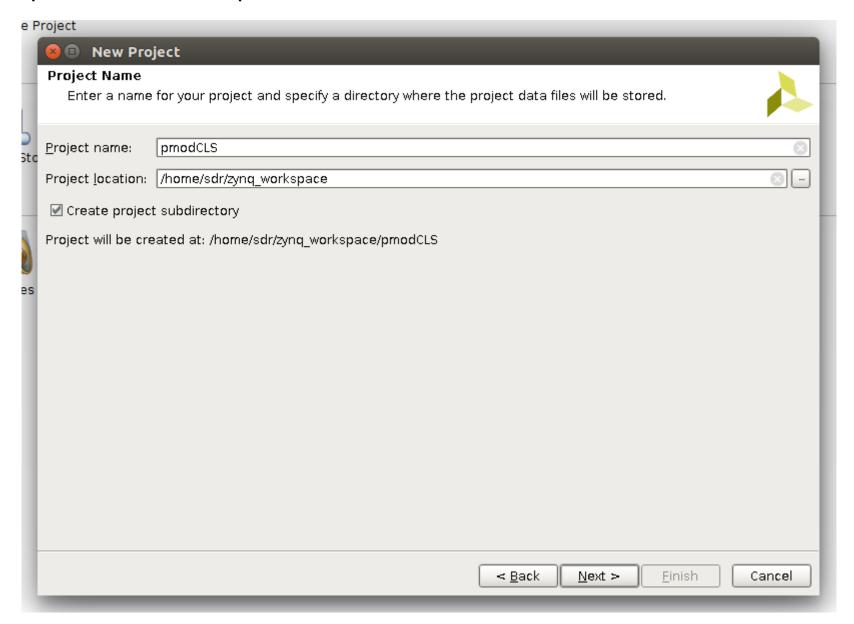
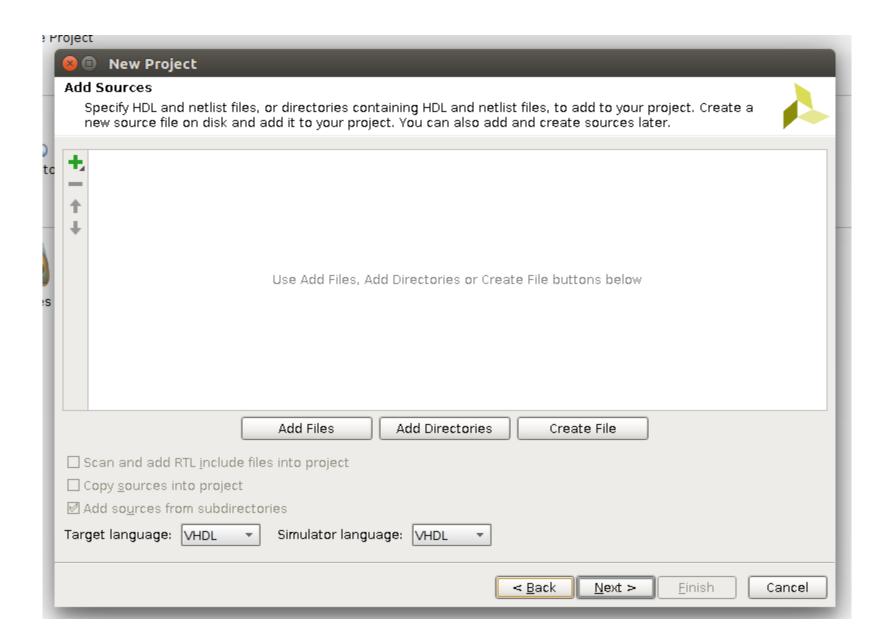
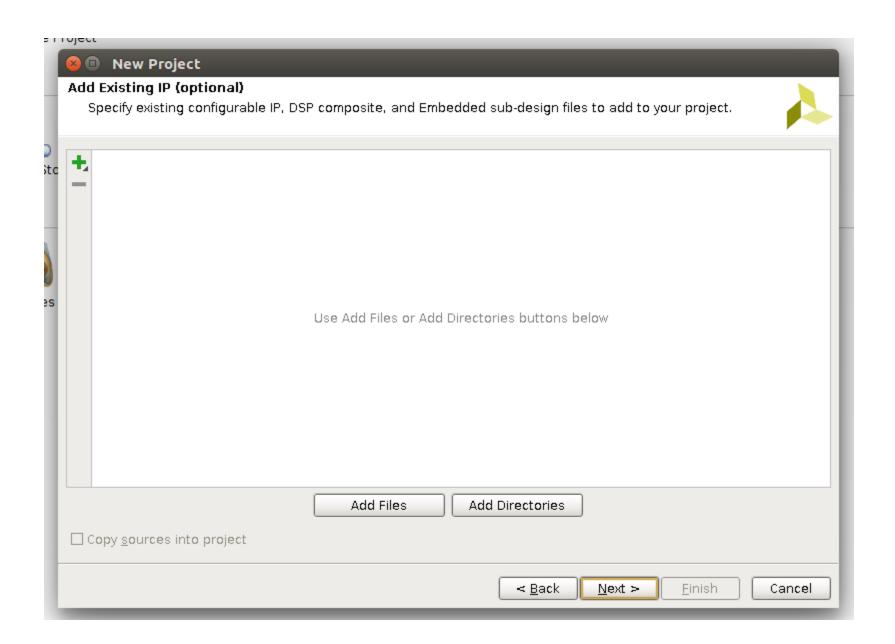
# **Pmod CAN Control with Zybo**

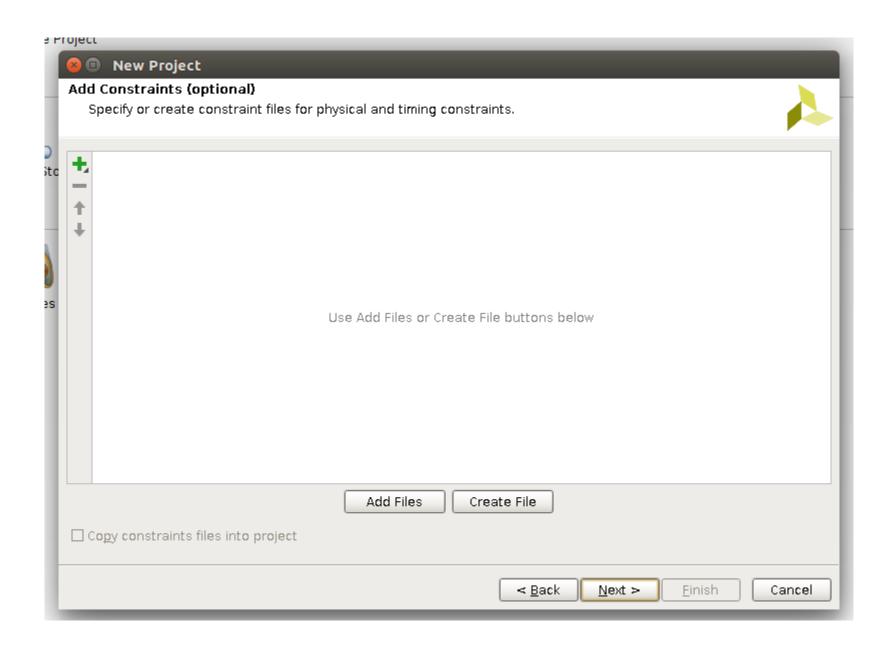
Innova Lee(이상훈) gcccompil3r@gmail.com

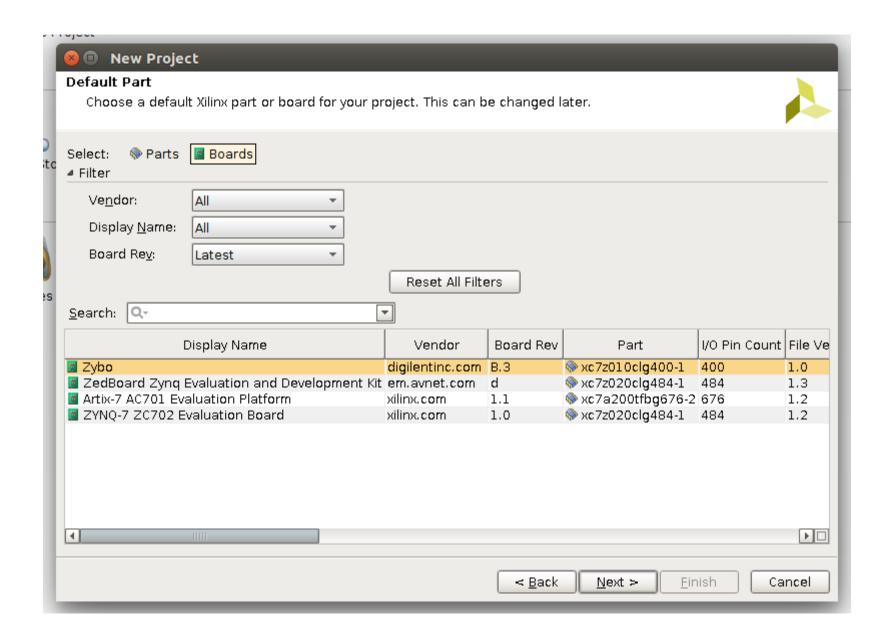
## 이름이 pmodCLS 라고 되어 있는데 pmodCAN 으로 수정하도록 한다.

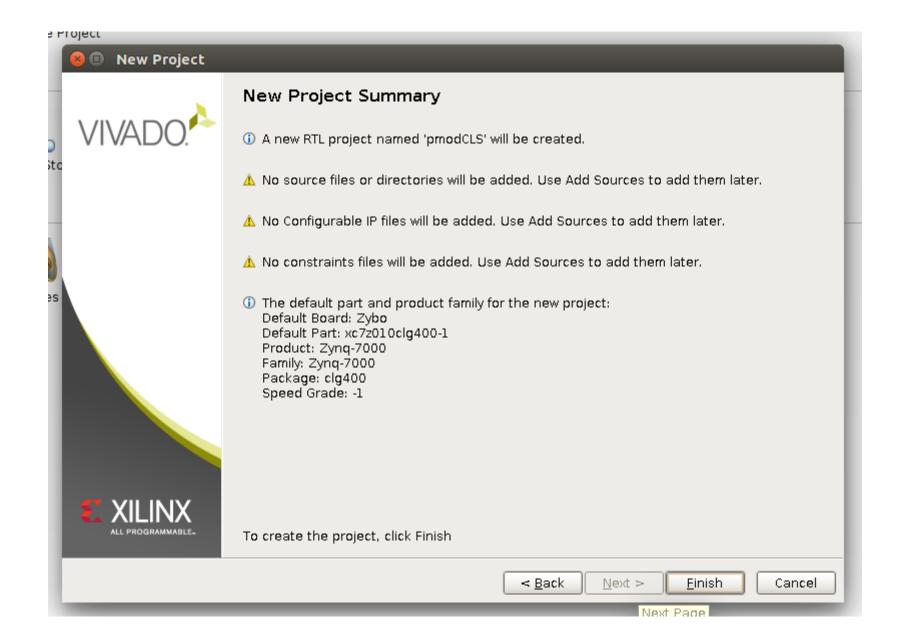




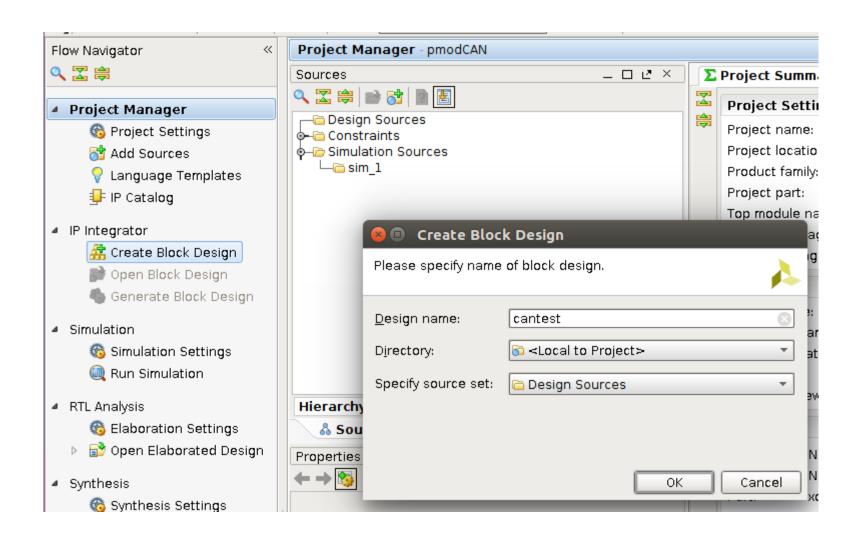


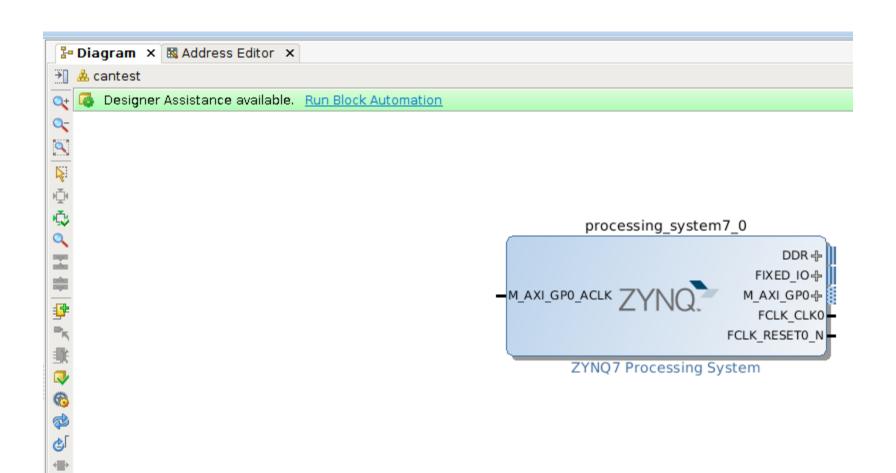


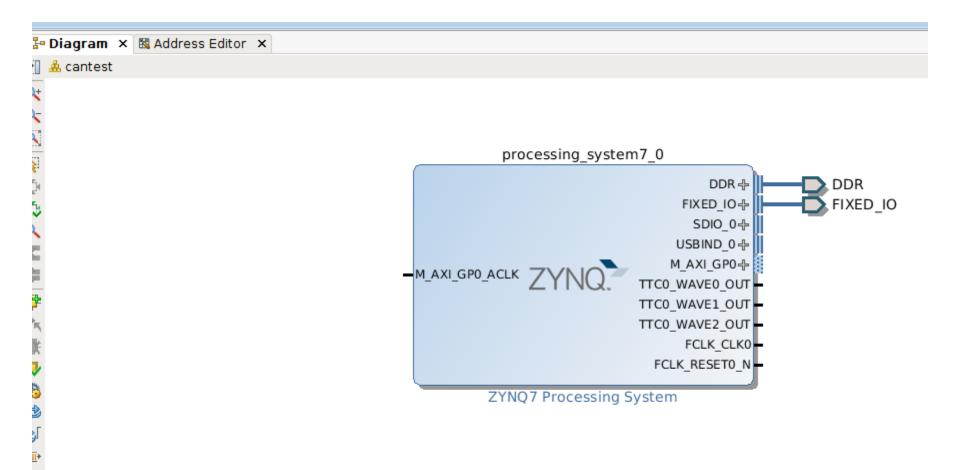


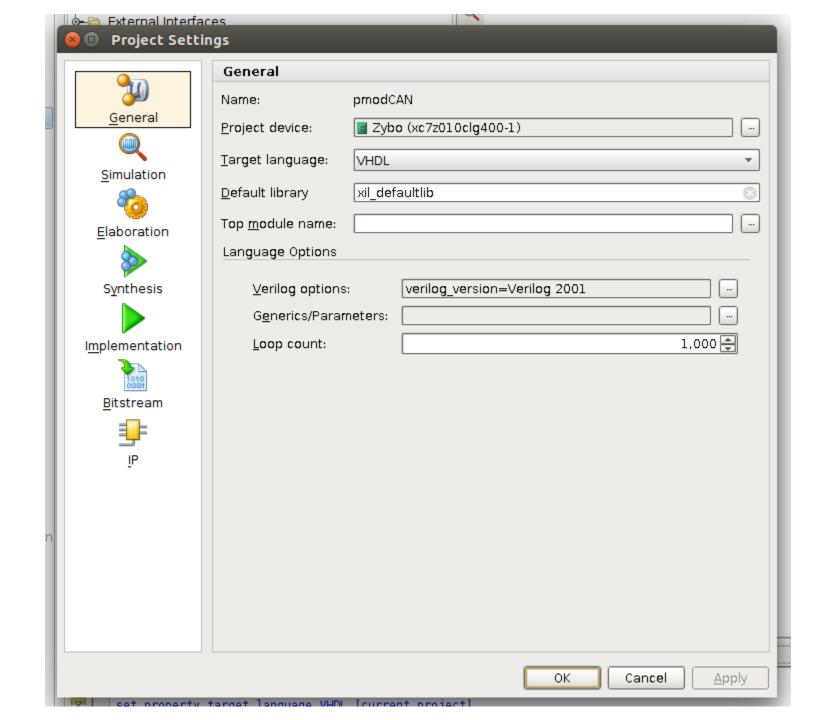


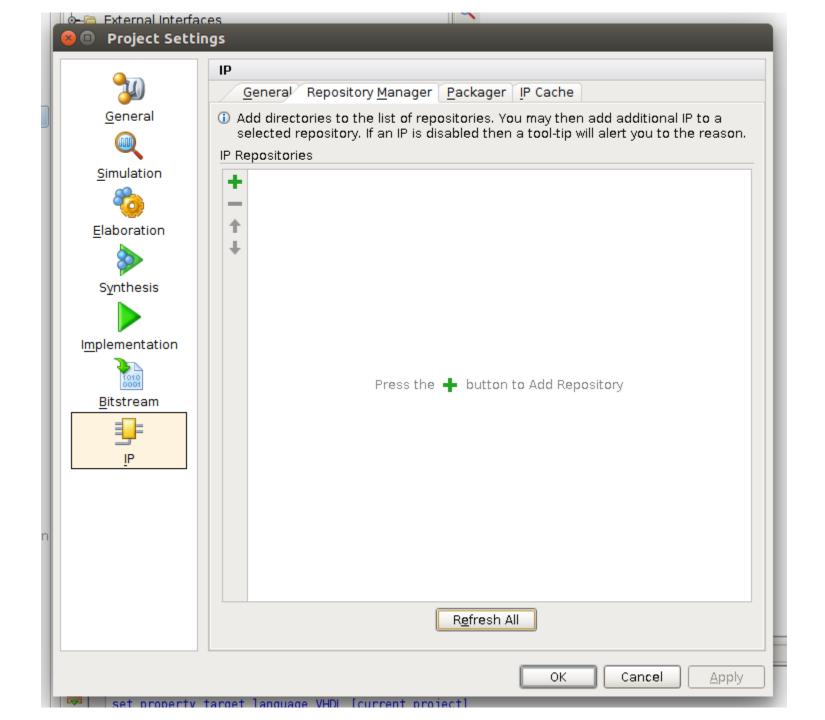
```
tmp fs
fpga
                  Videos
i2c proj
                  vivado.jou
ір геро
                  vivado.log
lab
                  vivado pid3703.str
lab fpga
                  workspace_v8
lecture
Music
                  zynq_test
my proj
                  zyng workspace
ocv
                  zyng zybo
petalinux_zynq
sdr@sdr-Samsung-DeskTop-System:~$ cd zynq_workspace/
sdr@sdr-Samsung-DeskTop-System:~/zyng workspace$ ls
pmodCLS
sdr@sdr-Samsung-DeskTop-System:~/zyng_workspace$ rm -rf pmodCLS/
sdr@sdr-Samsung-DeskTop-System:~/zyng workspace$ mkdir pmod lib
sdr@sdr-Samsung-DeskTop-System:~/zyng workspace$ cd pmod lib/
sdr@sdr-Samsung-DeskTop-System:~/zyng workspace/pmod lib$ git clone https://github
.com/Digilent/vivado-library.git
Cloning into 'vivado-library'...
remote: Counting objects: 7473, done.
remote: Compressing objects: 100% (106/106), done.
Receiving objects: 1% (136/7473), 740.00 KiB | 235.00 KiB/s
```

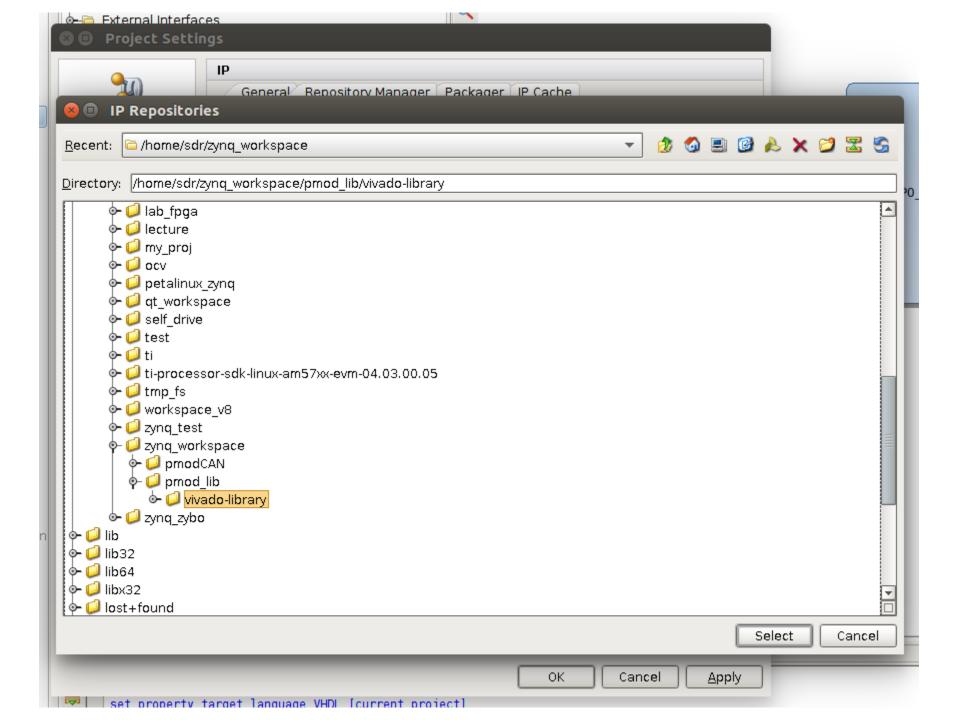


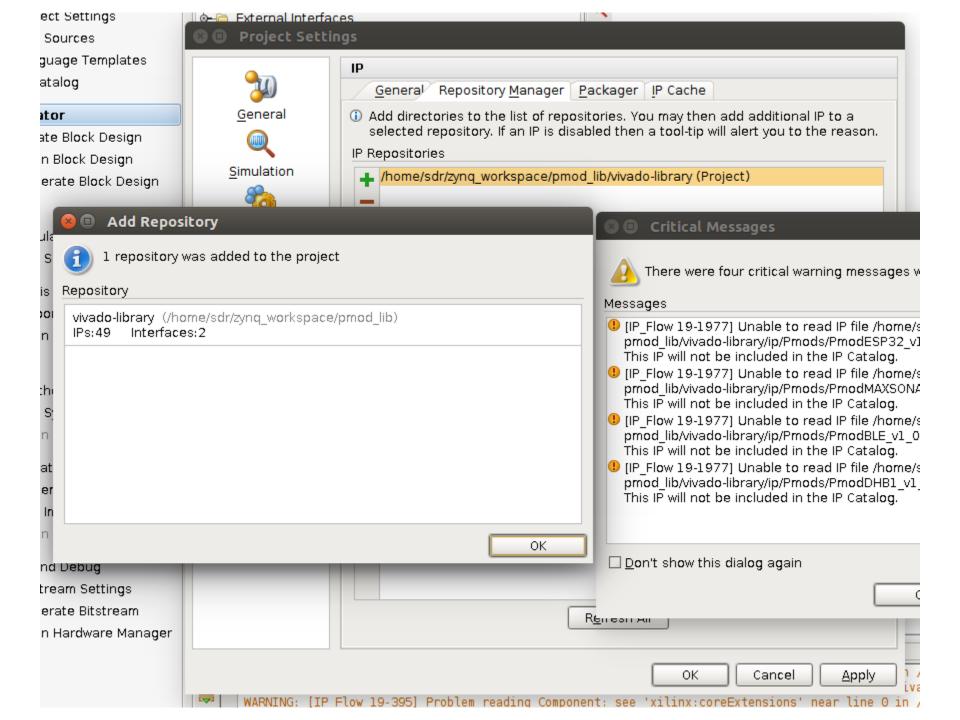


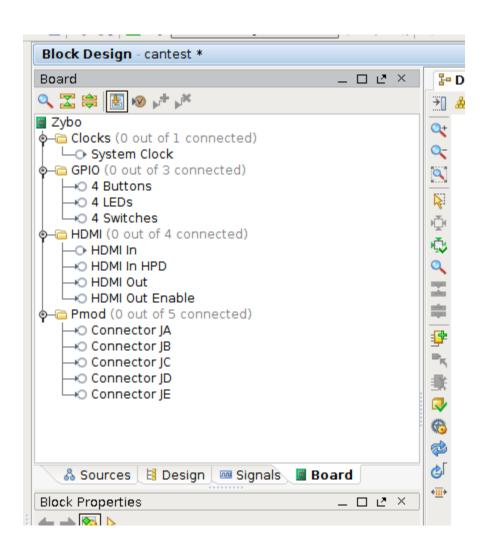


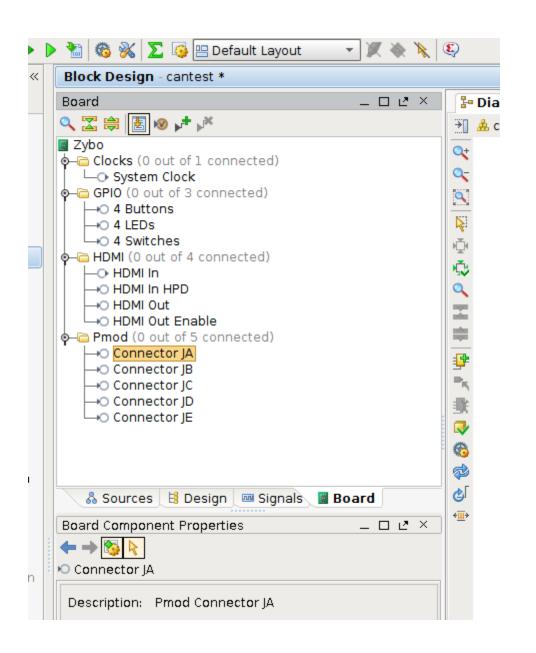


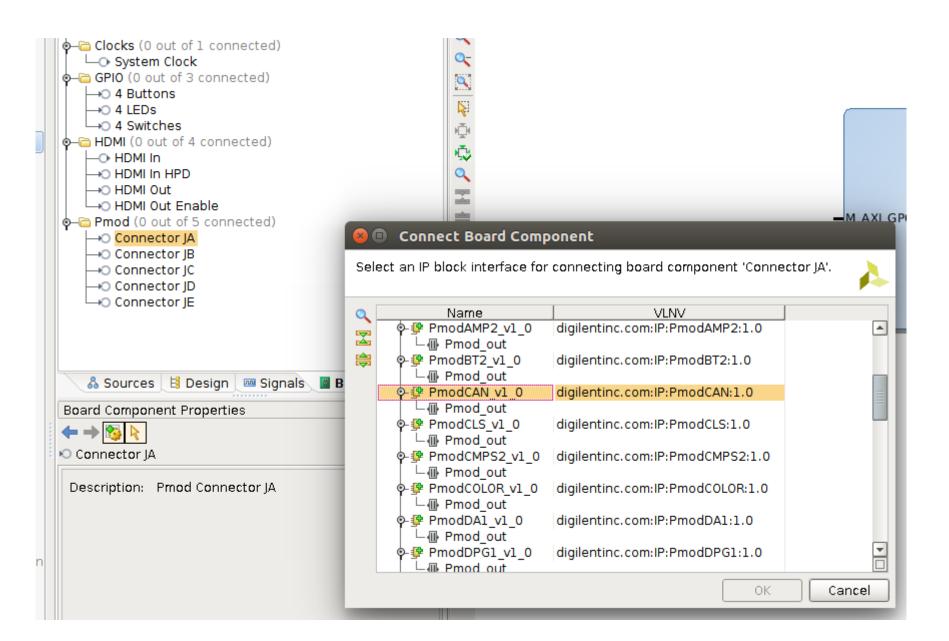


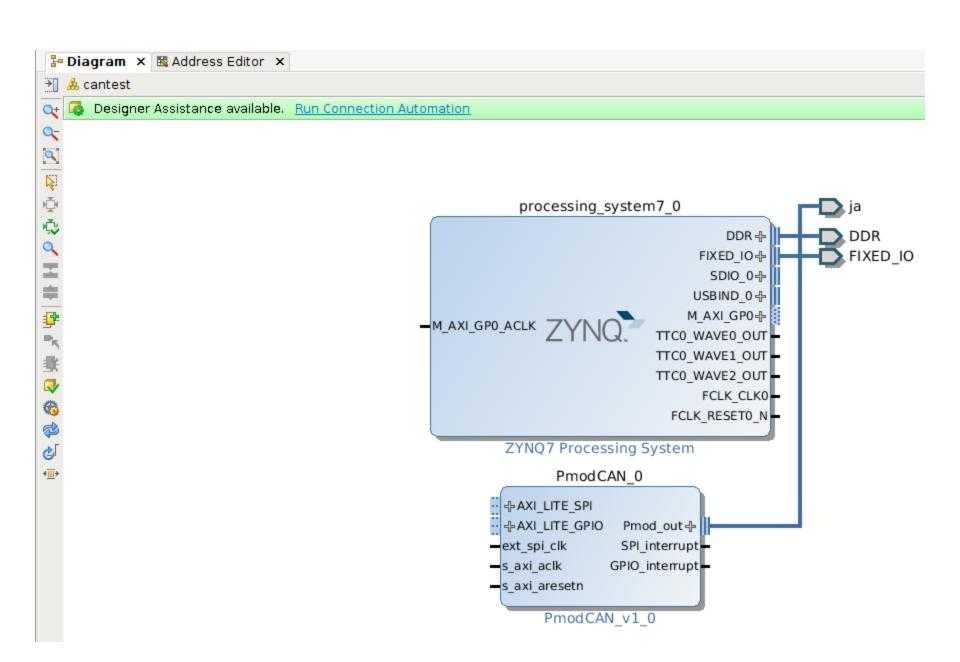










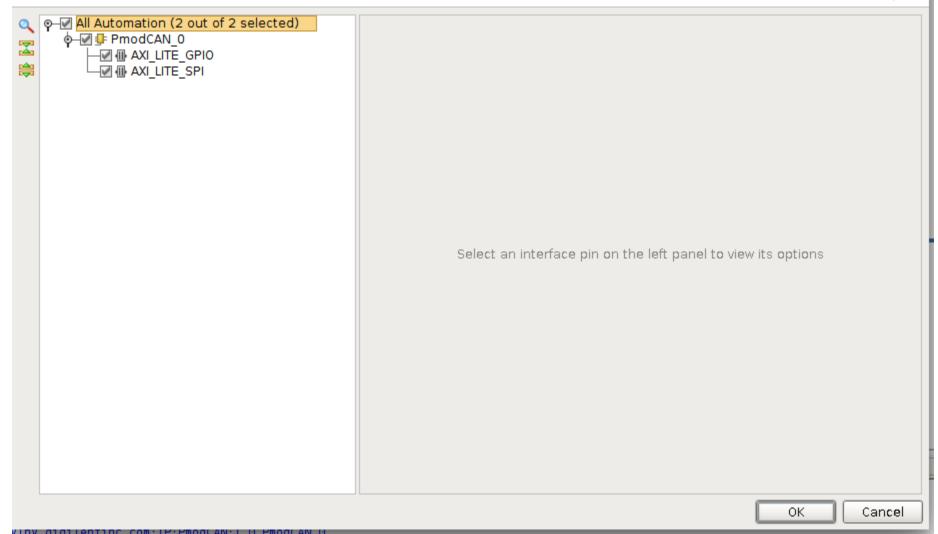


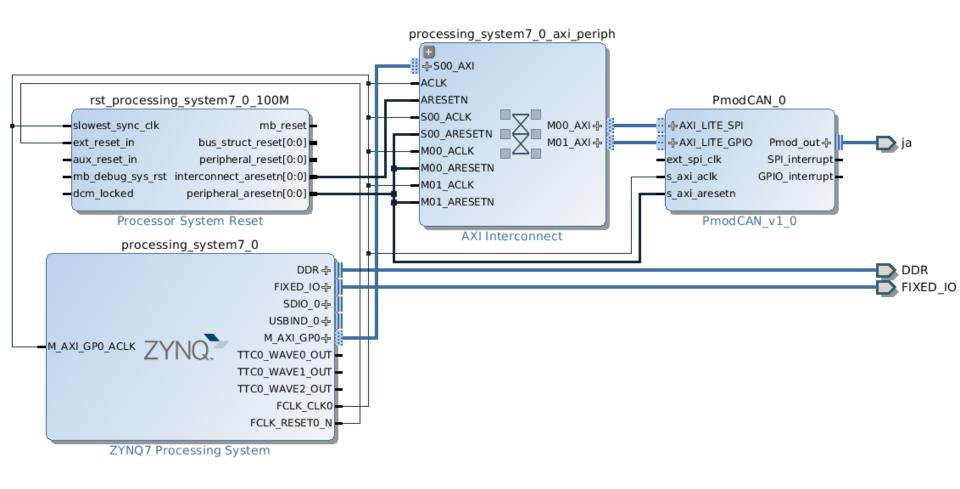
### **8** 🗊

#### **Run Connection Automation**

Automatically make connections in your design by checking the boxes of the interfaces to connect. Select an interface on the left to display its configuration options on the right.







# Pmods Supported

CAN

Interface Type

SPI

**Pmod** 

8LD	GPIO	-	-	-	Yes
ACL	SPI	80	ext_spi_clk	-	-
ACL2	SPI	50	ext_spi_clk	-	-
AD1	SPI	-	-	-	-
AD2	IIC	-	-	-	-
AD5	SPI	50	-	-	-
ALS	SPI	50	ext_spi_clk	-	-
AMP2	GPIO	-	-	timer_interrupt	-
BB	GPIO	-	-	-	Yes
BT2	UART	-	-	-	-
BTN	GPIO	-	-	-	Yes

Reference Clock signal name

ext\_spi\_clk

Interrupt pin name/s

SPI\_interrupt, GPIO\_interrupt

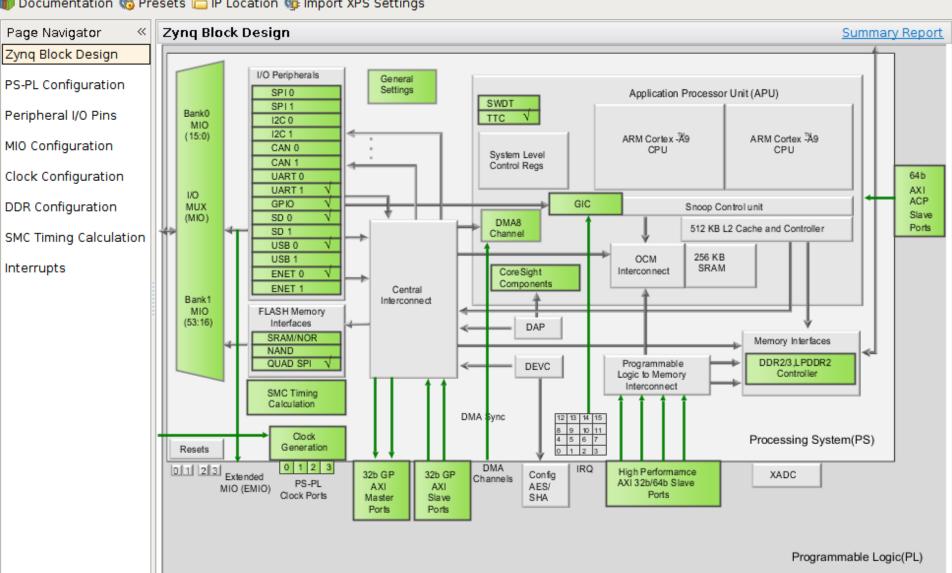
**Uses PmodGPIO** 

Reference clock frequency (MHz)

100

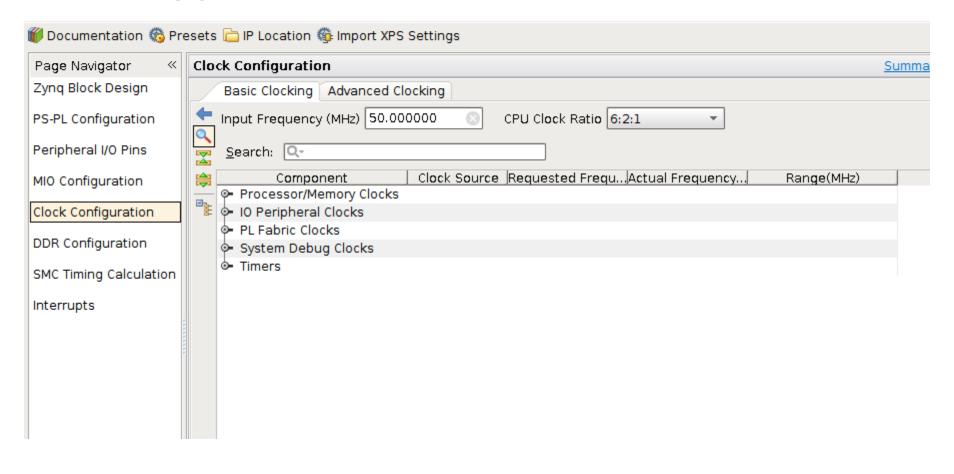


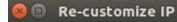


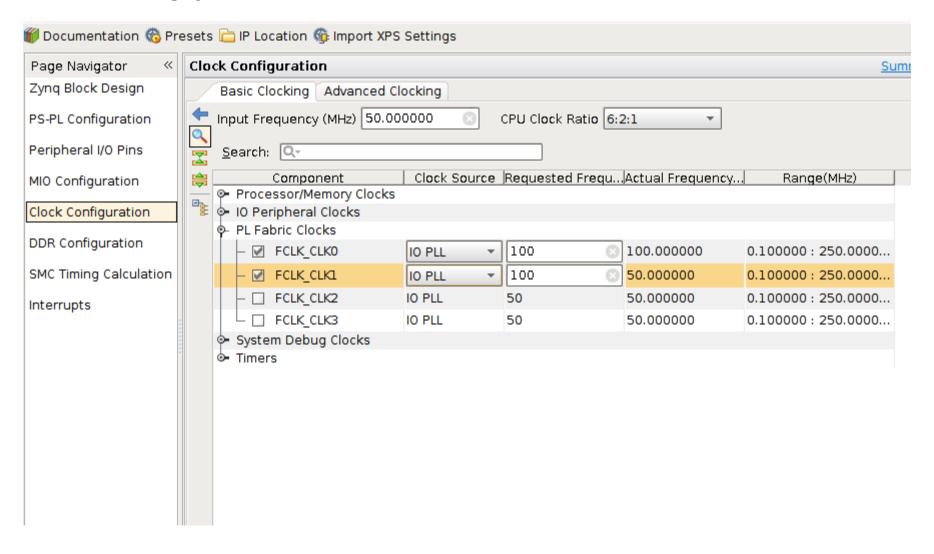


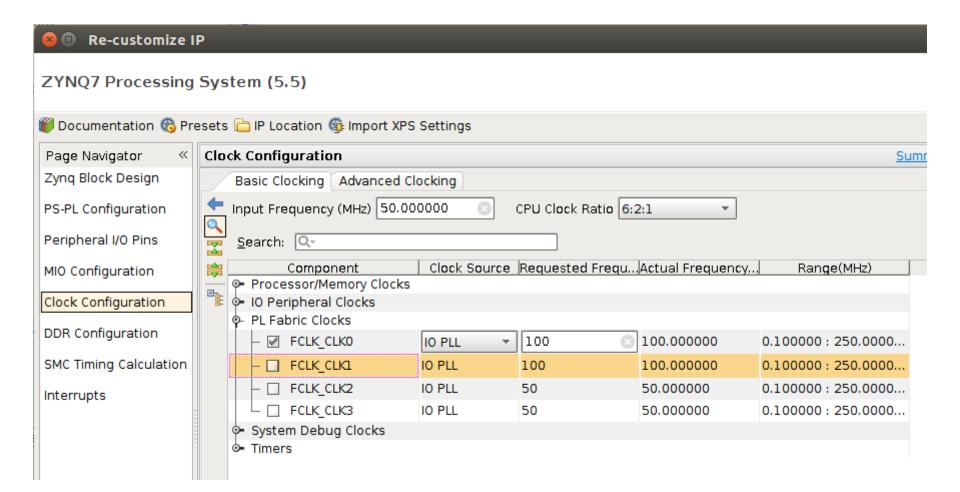
0K Cancel

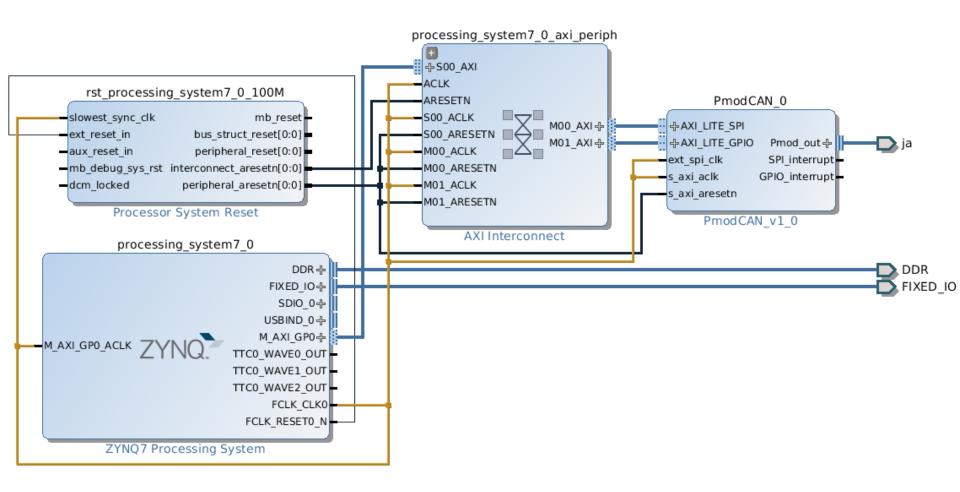
#### 👿 💷 Re-customize IP

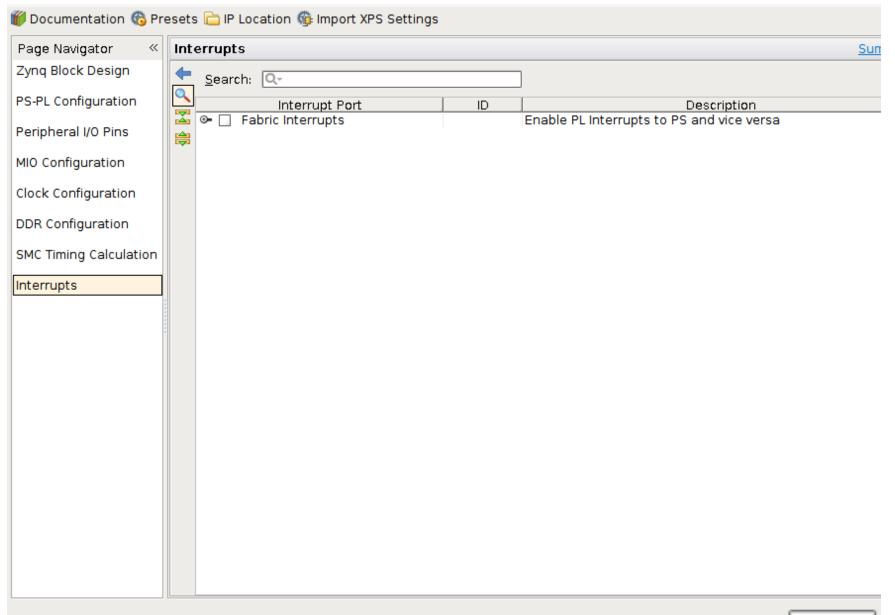


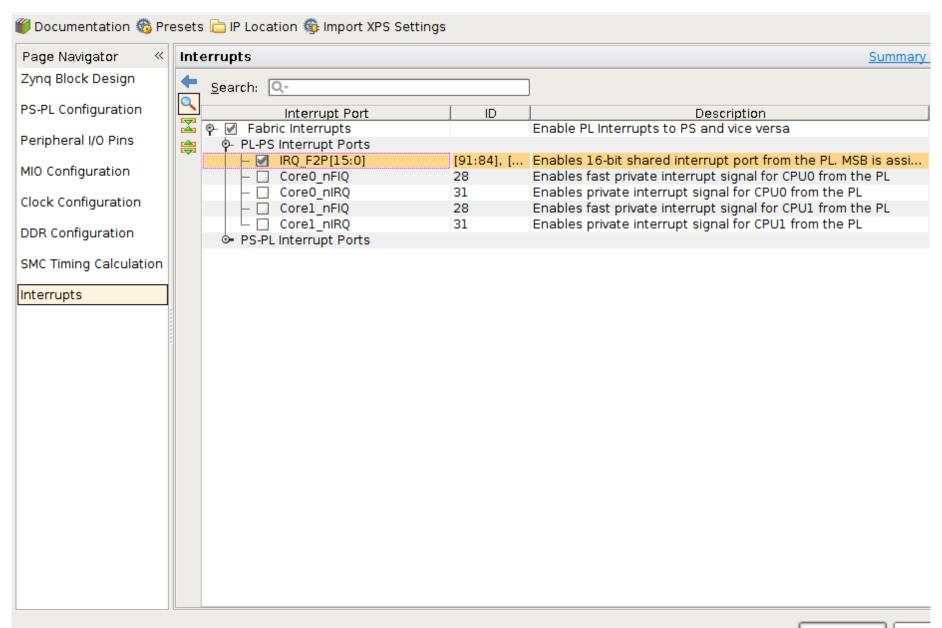


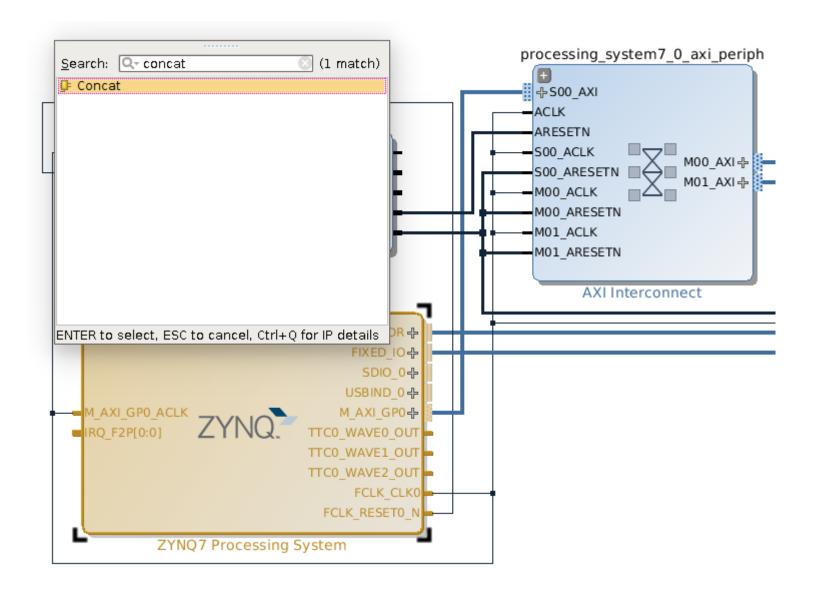


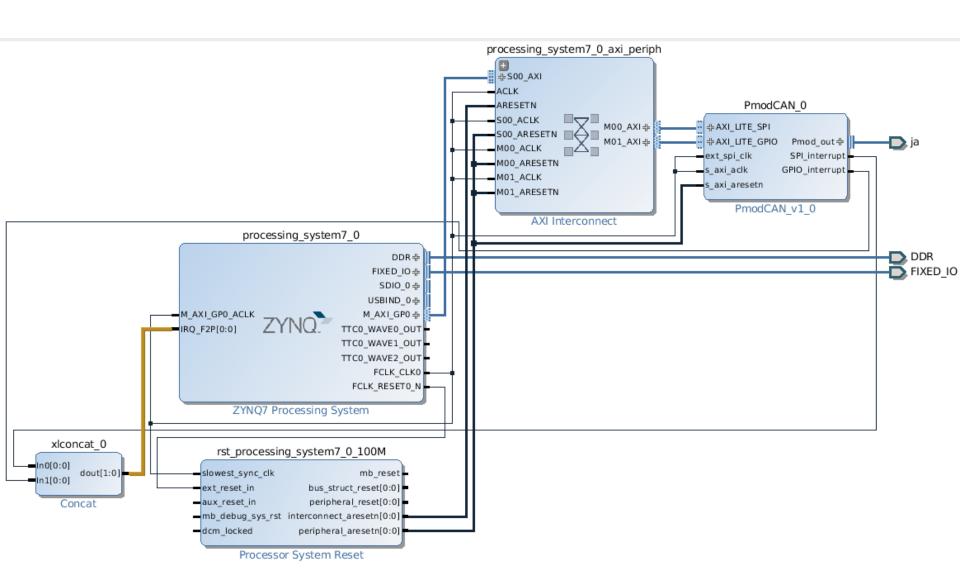


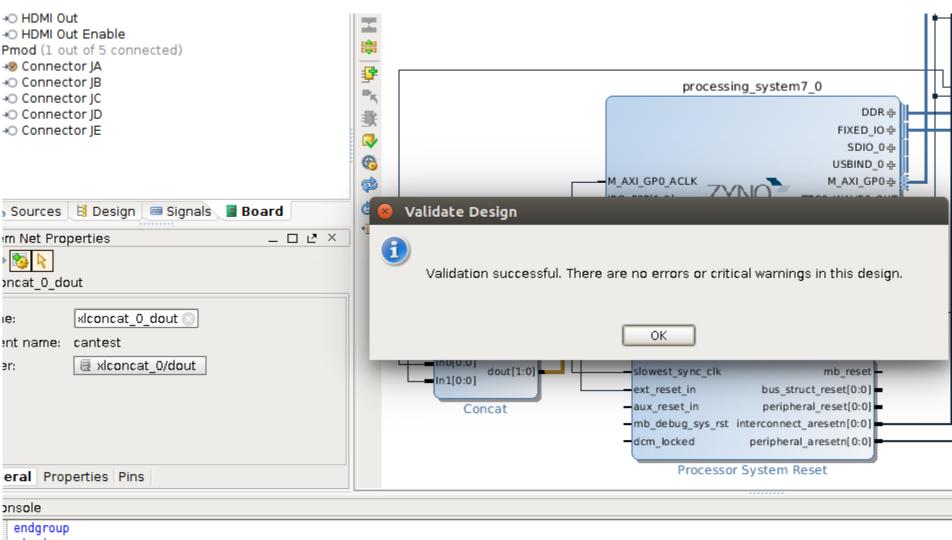




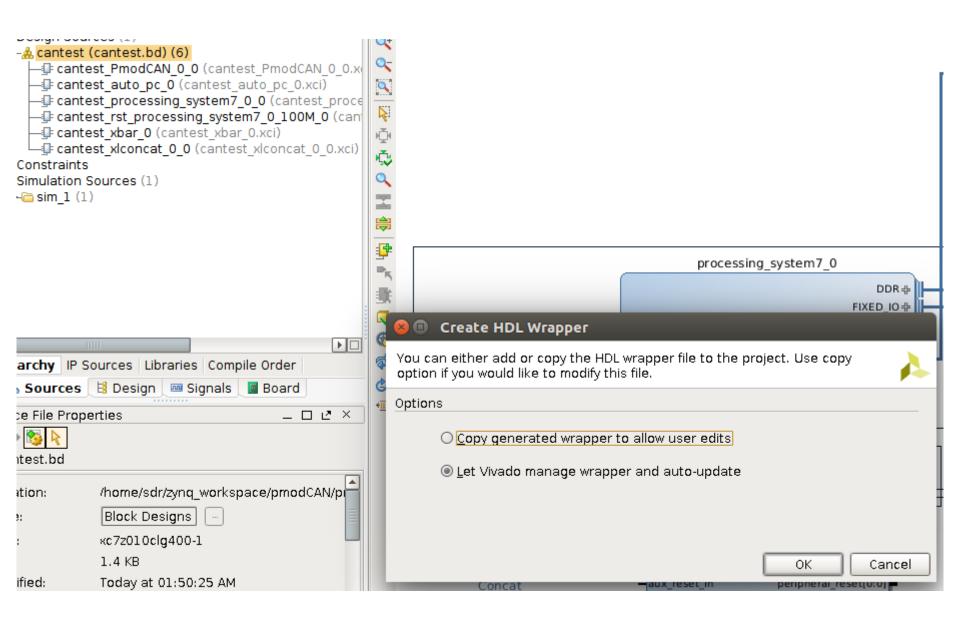


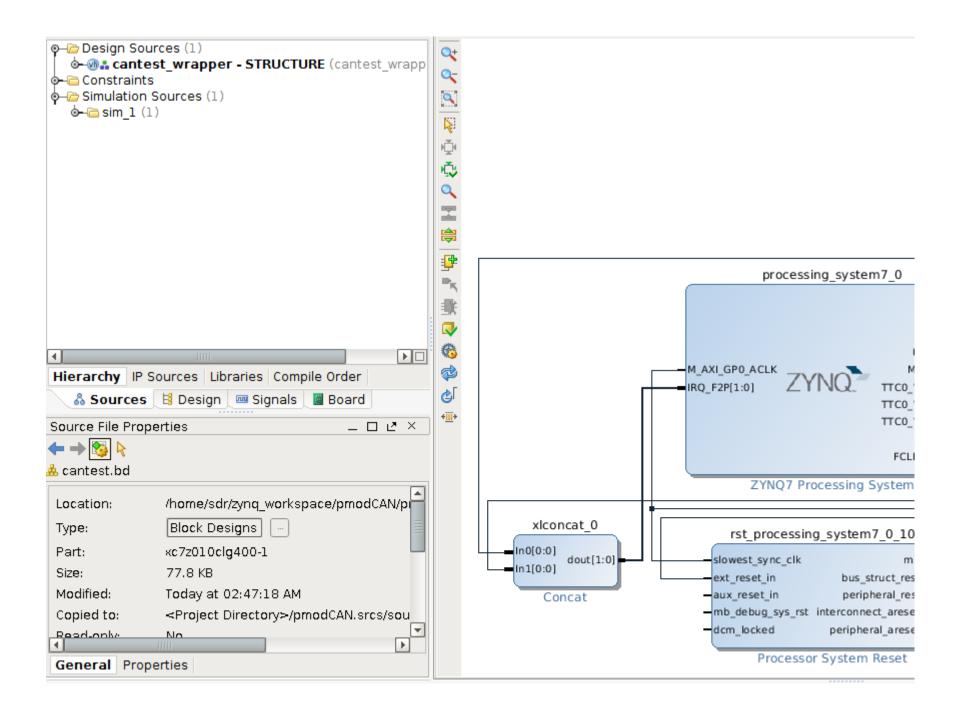


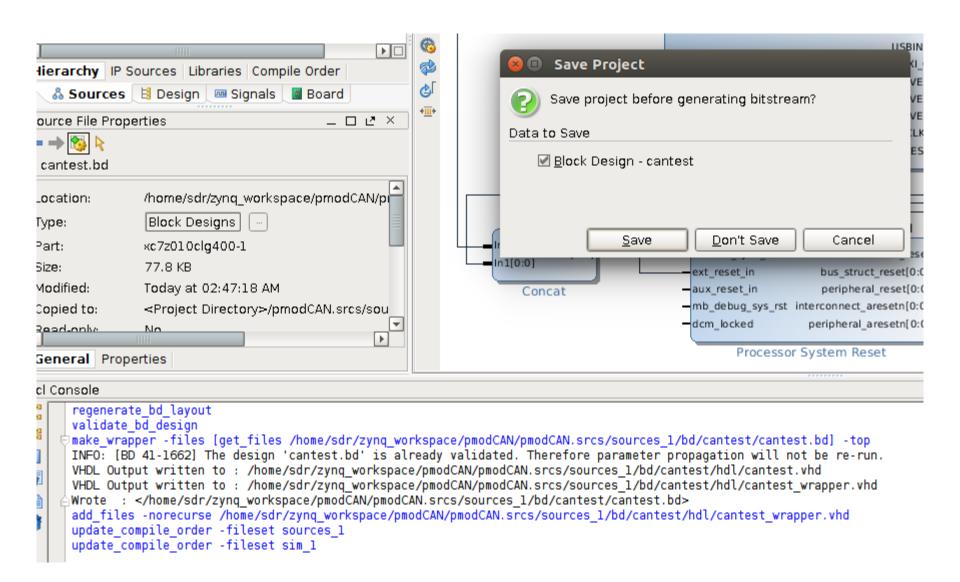


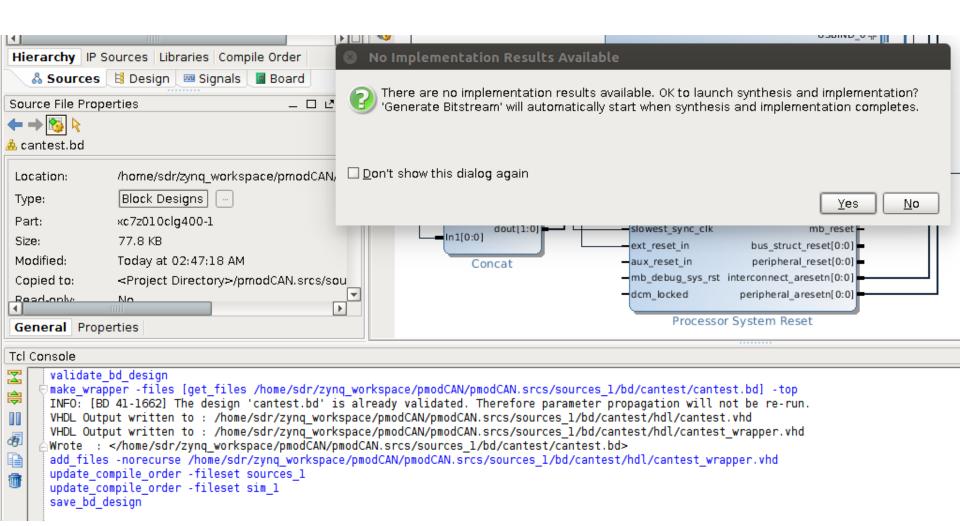


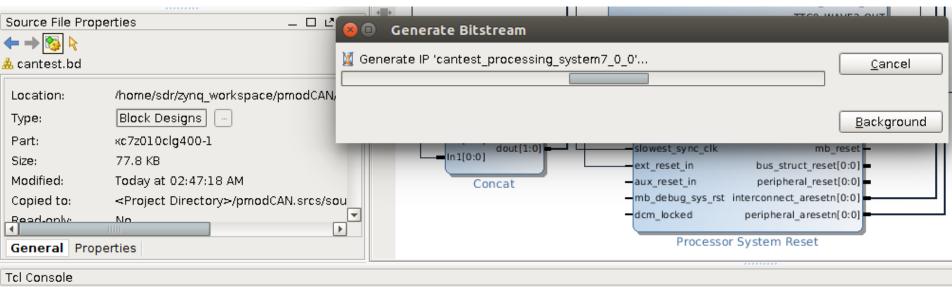
```
startgroup
create_bd_cell -type ip -vlnv xilinx.com:ip:xlconcat:2.1 xlconcat_0
endgroup
connect_bd_net [get_bd_pins PmodCAN_0/SPI_interrupt] [get_bd_pins xlconcat_0/In0]
regenerate_bd_layout
connect_bd_net [get_bd_pins xlconcat_0/In1] [get_bd_pins PmodCAN_0/GPI0_interrupt]
connect_bd_net [get_bd_pins xlconcat_0/dout] [get_bd_pins processing_system7_0/IRQ_F2P]
regenerate_bd_layout
validate_bd_design
```







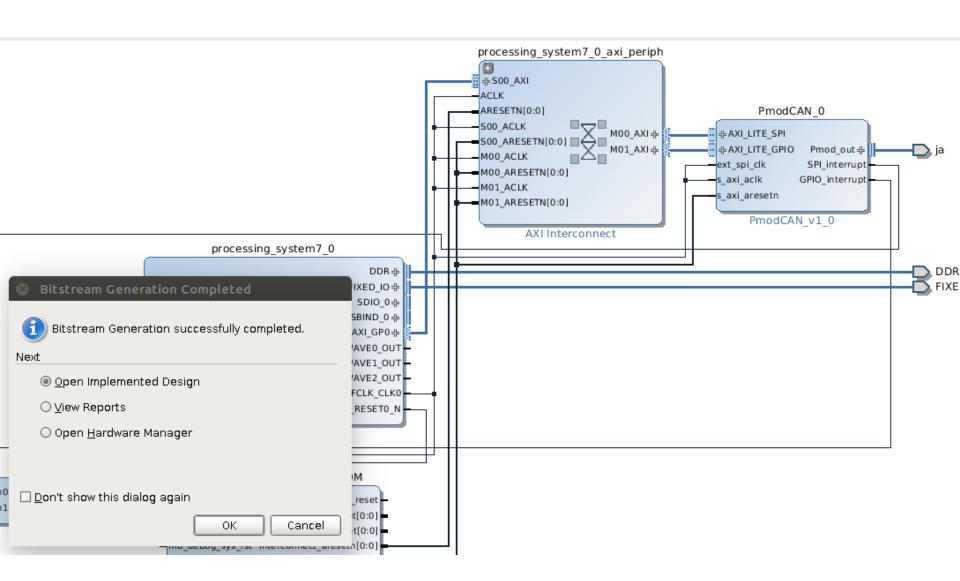


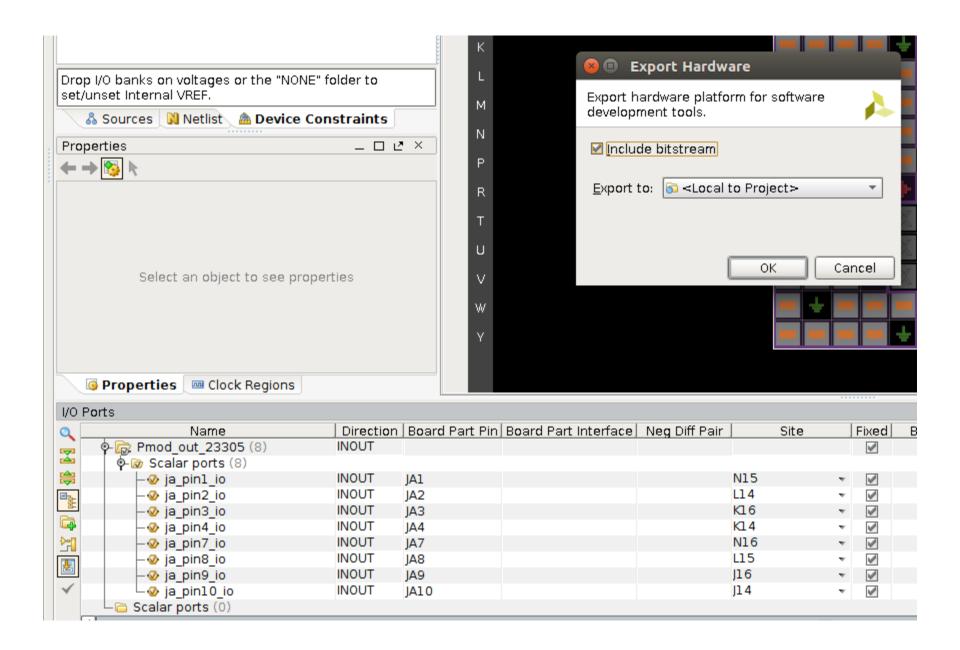


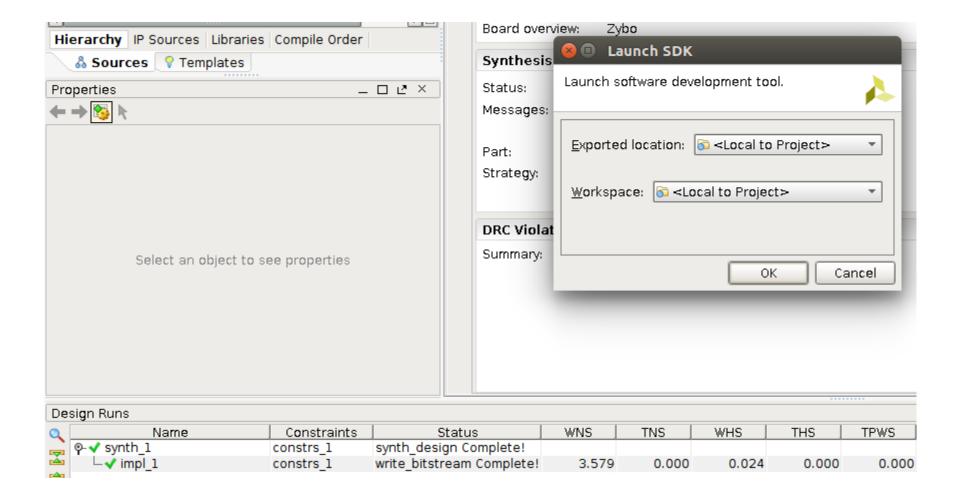
add\_files -norecurse /home/sdr/zynq\_workspace/pmodCAN/pmodCAN.srcs/sources\_1/bd/cantest/hdl/cantest\_wrapper.vhd update\_compile\_order -fileset sources\_1 update\_compile\_order -fileset sim\_1 save\_bd\_design ⇒ launch runs impl 1 -to step write bitstream

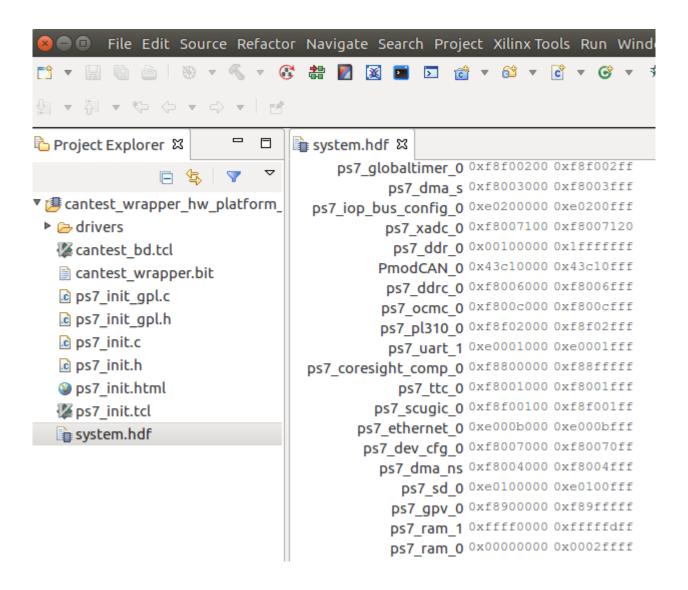
INFO: [BD 41-1662] The design 'cantest.bd' is already validated. Therefore parameter propagation will not be re-run. VHDL Output written to : /home/sdr/zynq\_workspace/pmodCAN/pmodCAN.srcs/sources\_1/bd/cantest/hdl/cantest.vhd VHDL Output written to : /home/sdr/zynq\_workspace/pmodCAN/pmodCAN.srcs/sources\_1/bd/cantest/hdl/cantest\_wrapper.vhd INFO: [IP Flow 19-1686] Generating 'Instantiation Template' target for IP 'cantest processing system7 0 0'...

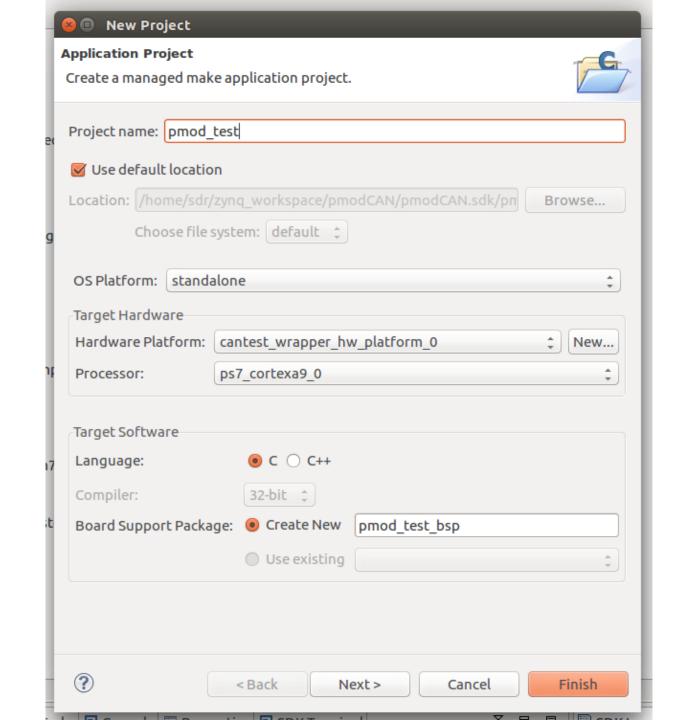
INFO: [IP\_Flow 19-1686] Generating 'Synthesis' target for IP 'cantest\_processing\_system7\_0\_0'...

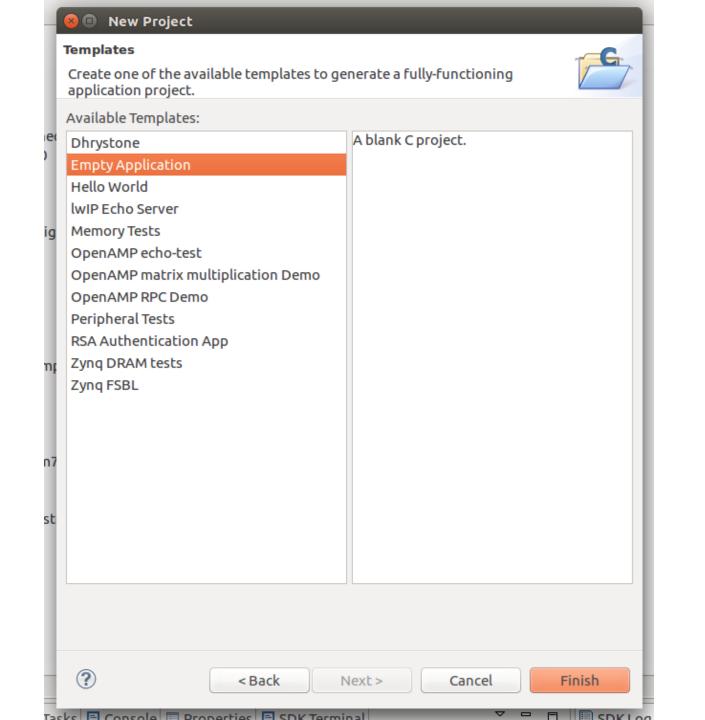


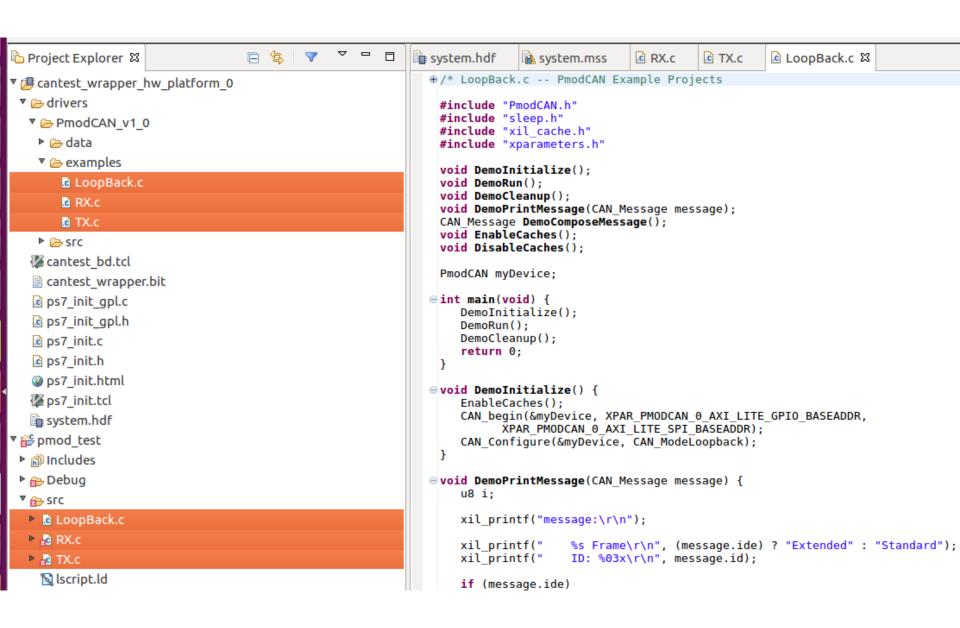












```
📂 cancesc_wrapper_nw_ptacronii_u
▼ B PmodCAN v1 0
  data
  examples
     LoopBack.c
     RX.c
     c TX.c
  ▶ Brc
 E cantest bd.tcl
 cantest wrapper.bit
 ps7 init gpl.c
 ps7 init gpl.h
 ps7 init.c
 ps7 init.h
 ps7 init.html
 ps7 init.tcl
 system.hdf
pmod test
▶ ₩ Binaries
▶ 🔊 Includes
Debug
▼ BSCC
 ▶ LoopBack.c
 ▶ [c] TX.c
  🛐 lscript.ld
  README.txt
pmod test bsp
```

```
#include "PmodCAN.h"
 #include "sleep.h"
 #include "xil cache.h"
 #include "xparameters.h"
 void DemoInitialize();
 void DemoRun();
 void DemoCleanup();
 void DemoPrintMessage(CAN_Message message);
 CAN Message DemoComposeMessage();
 void EnableCaches():
 void DisableCaches():
 PmodCAN myDevice;
⊝int main(void) {
    DemoInitialize():
    DemoRun():
    DemoCleanup();
    return 0;
 }
ovoid DemoInitialize() {
    EnableCaches():
    CAN begin(&myDevice, XPAR PMODCAN 0 AXI LITE G
          XPAR PMODCAN 0 AXI LITE SPI BASEADDR);
    CAN Configure(&myDevice, CAN ModeNormalOperati
void DemoPrintMessage(CAN_Message message) {
    u8 i:
    xil_printf("message:\r\n");
    xil printf("
                    %s Frame\r\n", (message.ide) ?
    xil_printf("
                    ID: %03x\r\n", message.id);
    if (message.ide)
       xil printf("
                       EID: %05x\r\n", message.eid
    if (message.rtr)
       xil_printf("
                       Remote Transmit Request\r\n
```

