

How to create Simulink Model

Innova Lee(이상훈)
gcccompil3r@gmail.com

```

8      %
9      eps = 0.000001;
10     i = 0;
11     del = 2*taup/150;
12     for tau = -taup:del:taup
13         i = i + 1;
14         j = 0;
15         fd = linspace(-5/taup,5/taup,151);
16         val1 = 1. - abs(tau) / taup;
17         val2 = pi * taup .* (1.0 - abs(tau) / t
18         x(:,i) = abs( val1 .* sin(val2+eps))./(\
19     end
20

```

명령 창

fx >> simulink



MATLAB®
SIMULINK®



Recent

- zynqRadioFMStereoAD9361AD9364SLX
- marine_gnc.mdl
- demo_waves.mdl
- demo_waves.mdl
- test.mdl
- test2.mdl
- commqpsktxrx.slx
- commrfsatlink.slx

Projects

- Source Control...
- Archive...

New

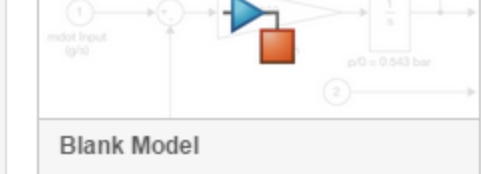
Examples

Search

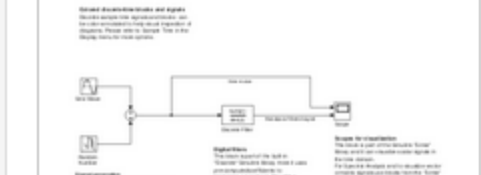
▼ My Templates

You have not created any templates yet.

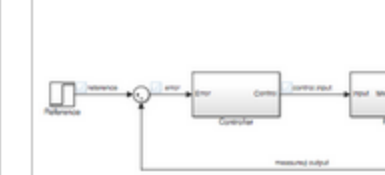
- ▼ Simulink



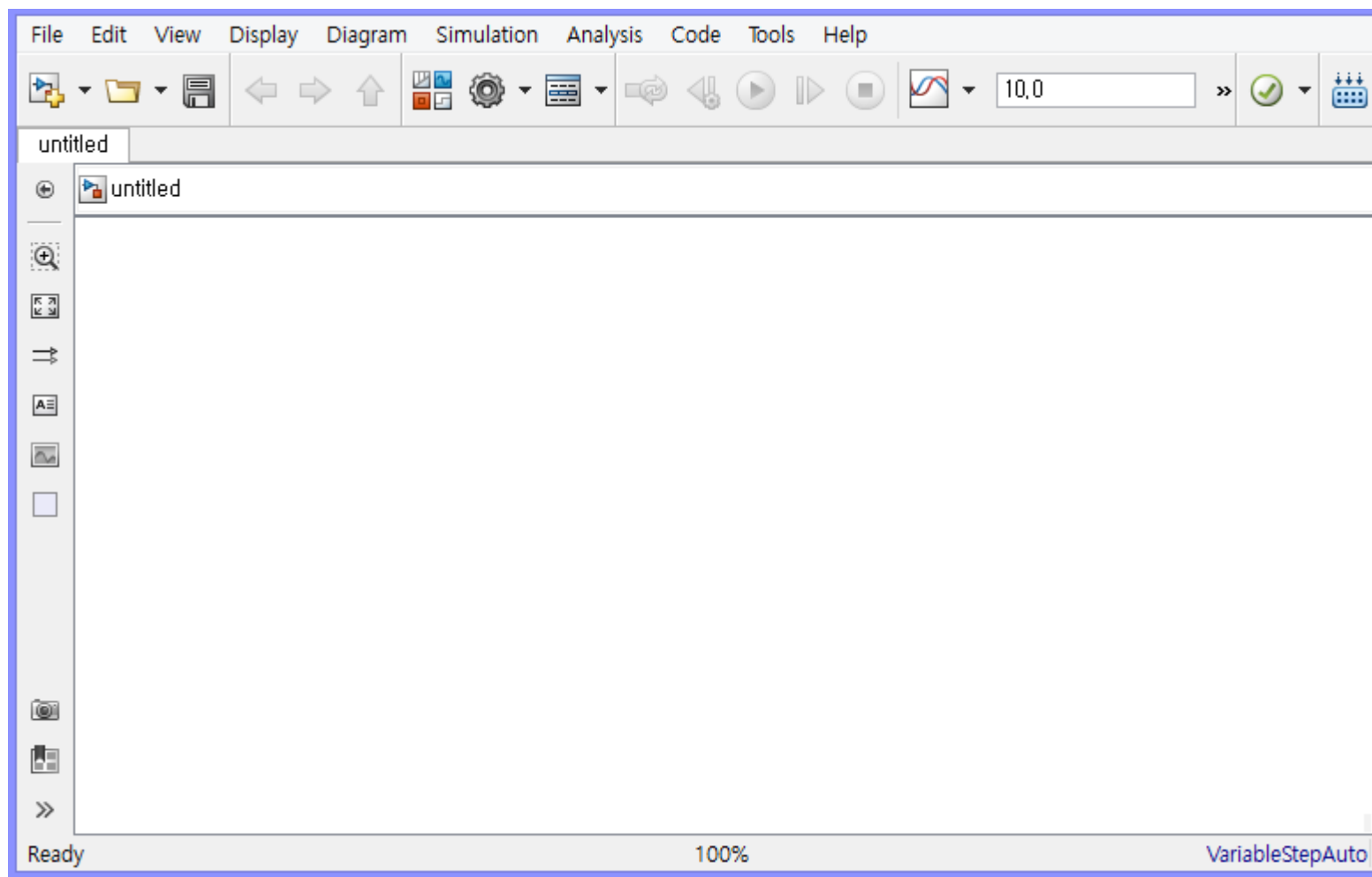


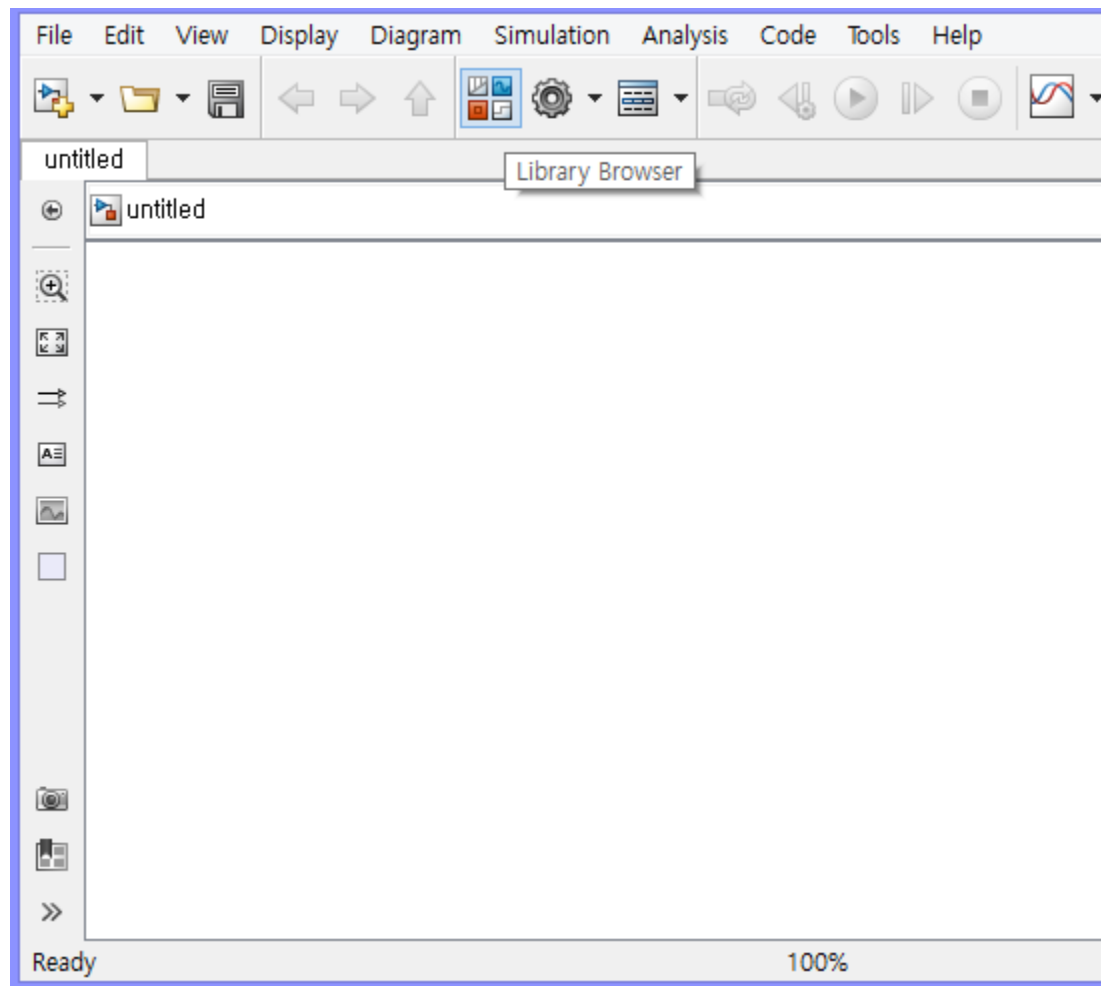


Digital Filter



Feedback Controller





Aerospace Blockset/Flight Instruments

- Simulink
 - Commonly Used Blocks
 - Continuous
 - Dashboard
 - Discontinuities
 - Discrete
 - Logic and Bit Operations
 - Lookup Tables
 - Math Operations
 - Model Verification
 - Model-Wide Utilities
 - Ports & Subsystems
 - Signal Attributes
 - Signal Routing
 - Sinks
 - Sources
 - User-Defined Functions
 - Additional Math & Discrete
- Aerospace Blockset
 - Actuators
 - Aerodynamics
 - Animation
 - Environment
 - Equations of Motion
 - Flight Parameters
 - Flight Instruments
 - GNC
 - Mass Properties
 - Pilot Models
 - Propulsion
 - Utilities
- Audio System Toolbox
 - Dynamic Range Control
 - Effects
 - Filters
 - Sinks
 - Sources
- Communications System Toolbox
 - Channels
 - Comm Filters
 - Comm Sinks
 - Comm Sources
 - Equalizers
 - Error Detection and Correction



Airspeed Indicator



Altimeter



Artificial Horizon



Climb Rate Indicator



EGT Indicator



Heading Indicator



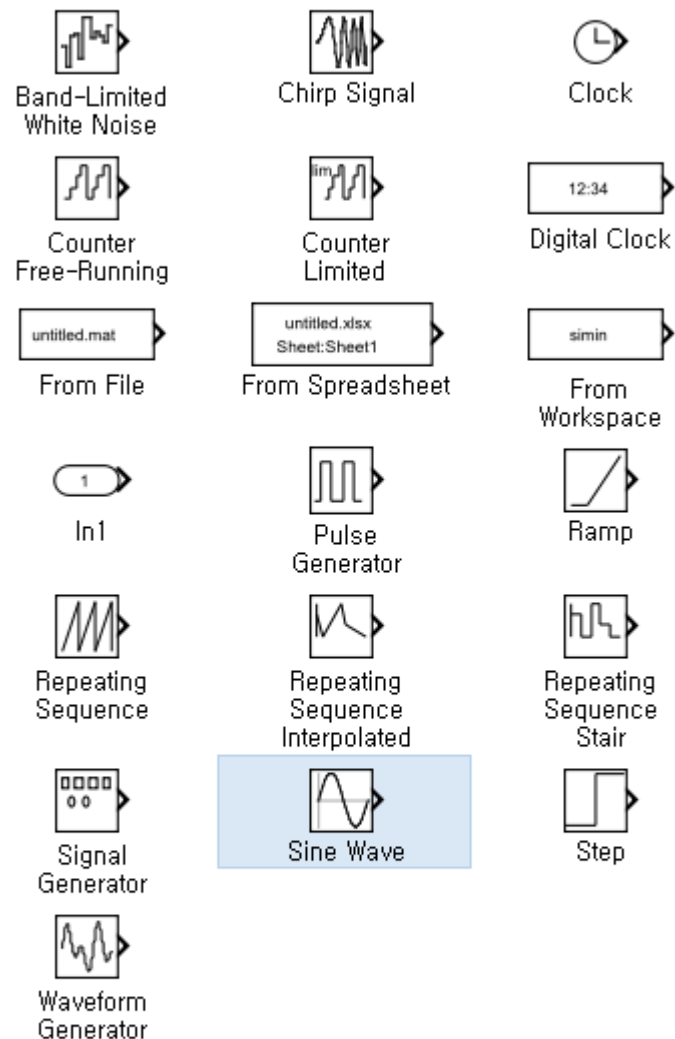
RPM Indicator



Turn Coordinator

Simulink/Sources


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 - Sinks
 - Sources
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 - Channels
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 - Comm Sinks
 - ▷ Comm Sources
 - Equalizers




Workspace

Simulink/Commonly Used Blocks


- Simulink
 - Commonly Used Blocks
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- Audio System Toolbox




Bus Creator




Bus Selector




Constant




Data Type Conversion




Delay




Demux




Discrete-Time Integrator




Gain




Ground




In1




Integrator




Logical Operator




Mux




Out1




Product




Relational Operator




Saturation




Scope



Subsystem

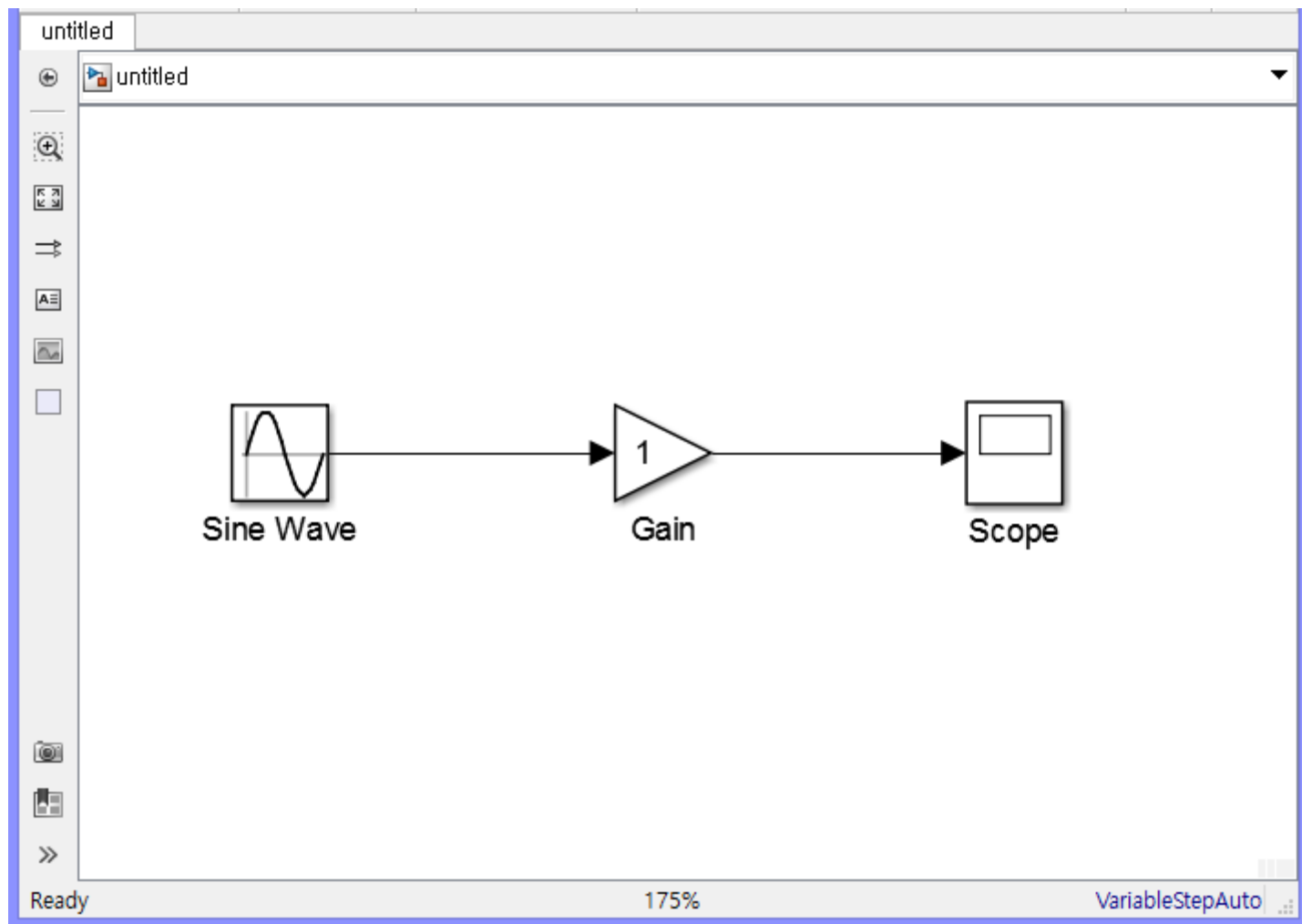


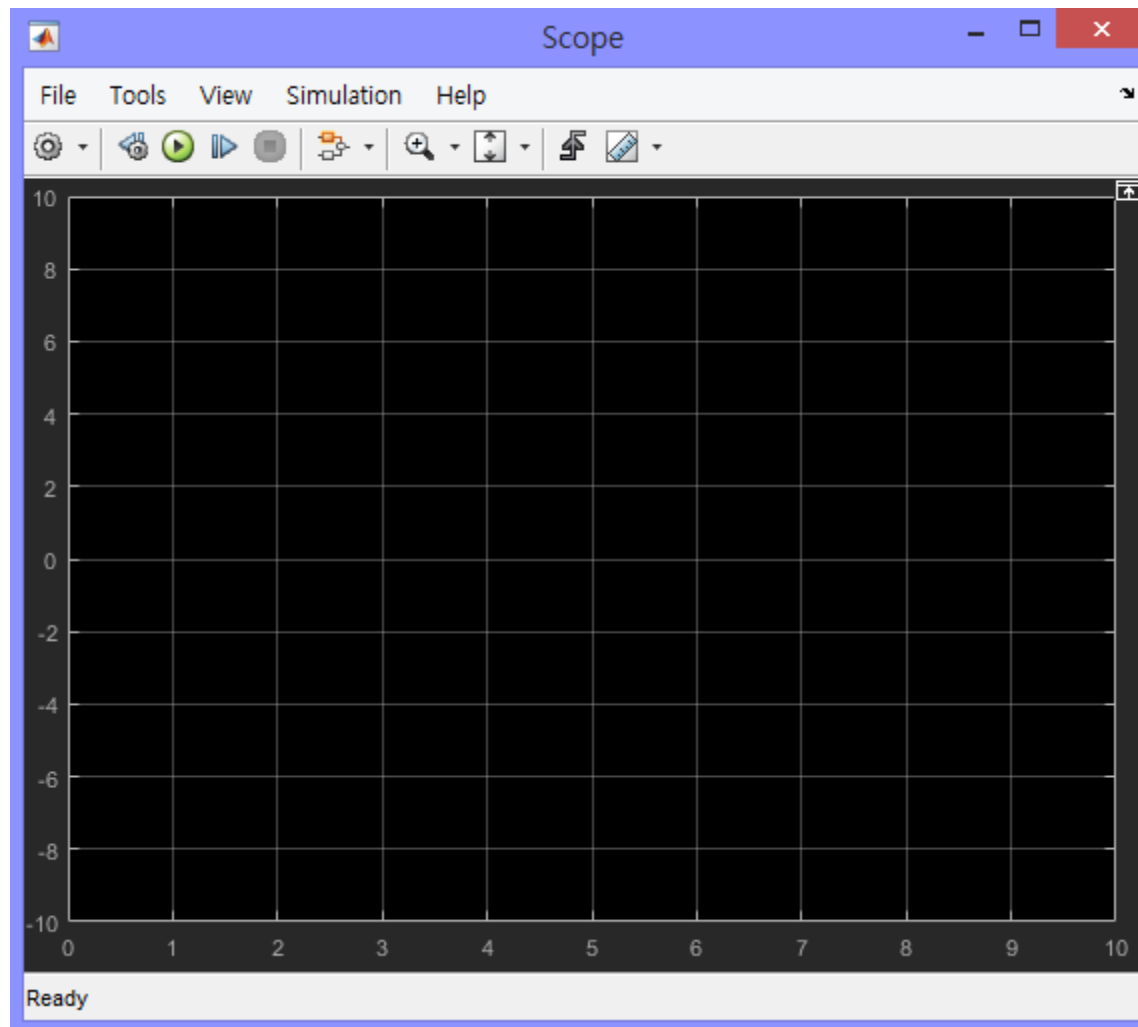
Switch

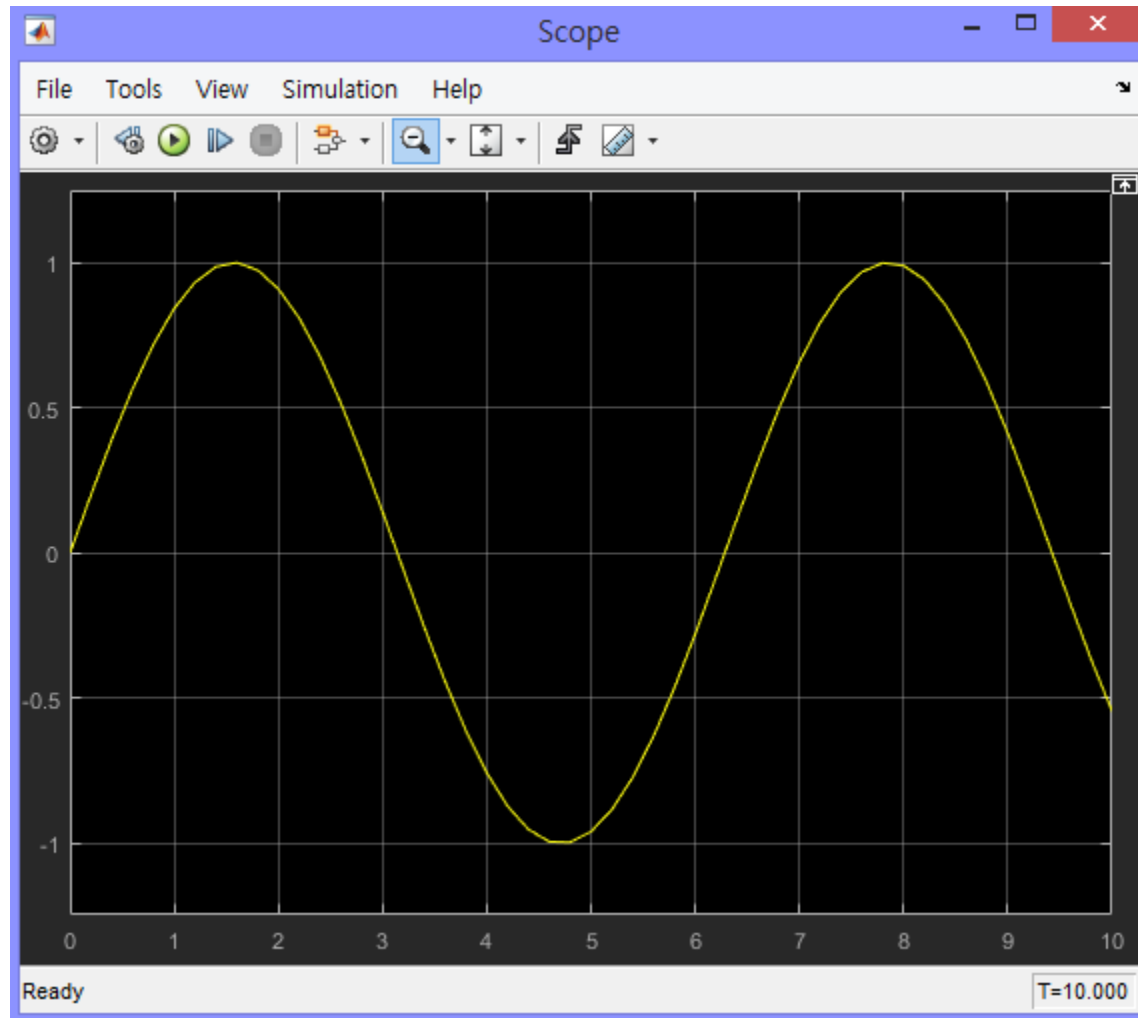


Terminator

simulink/Commonly Used Blocks/Scope:
Displays input signals with respect to simulation time







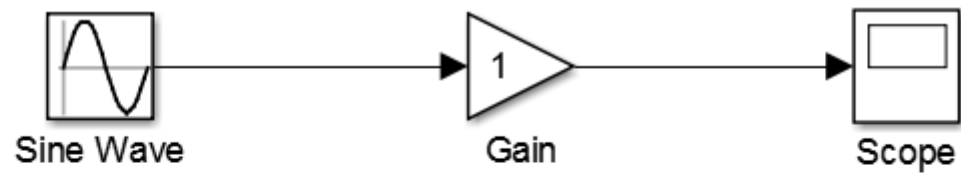
titled

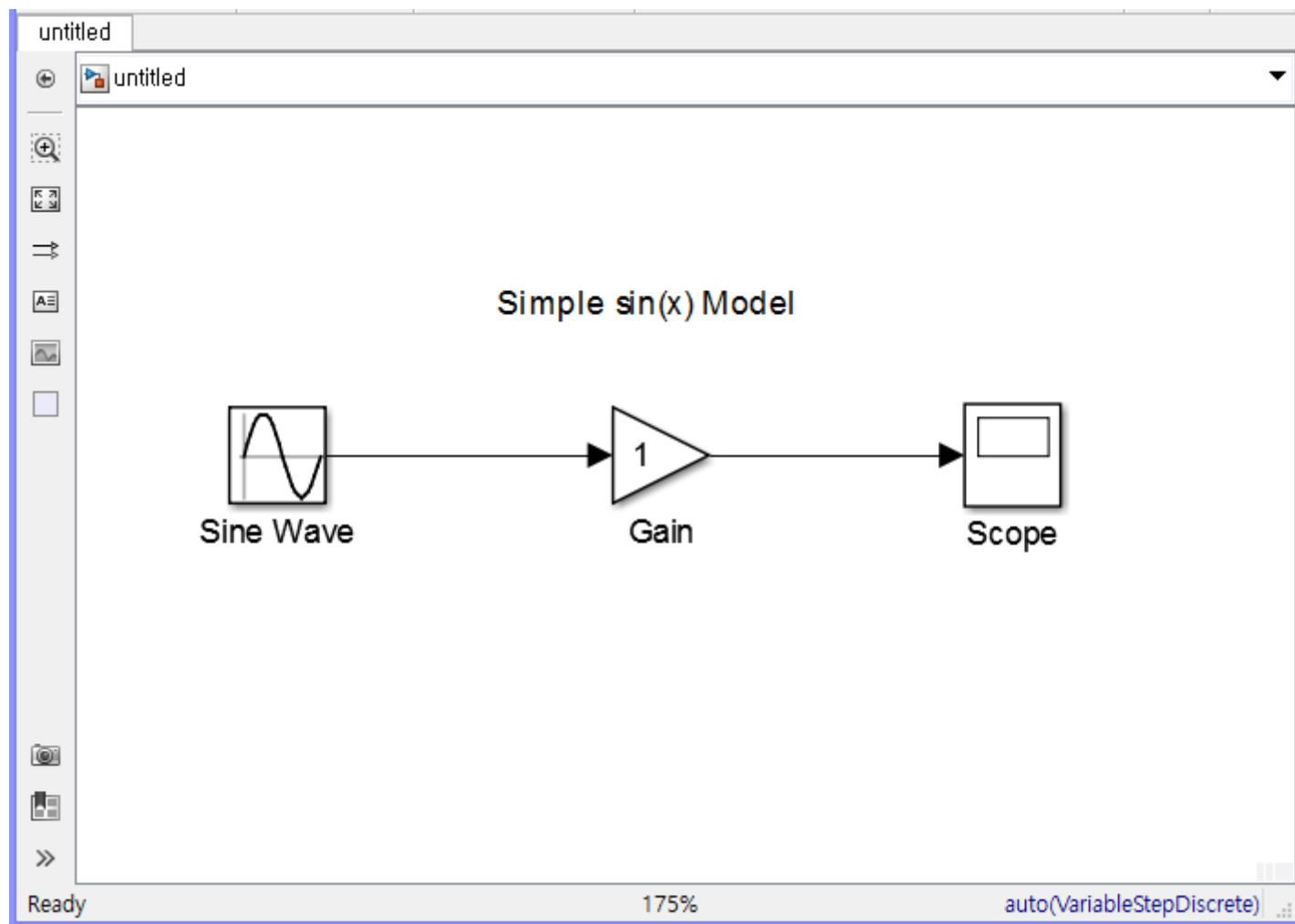
untitled

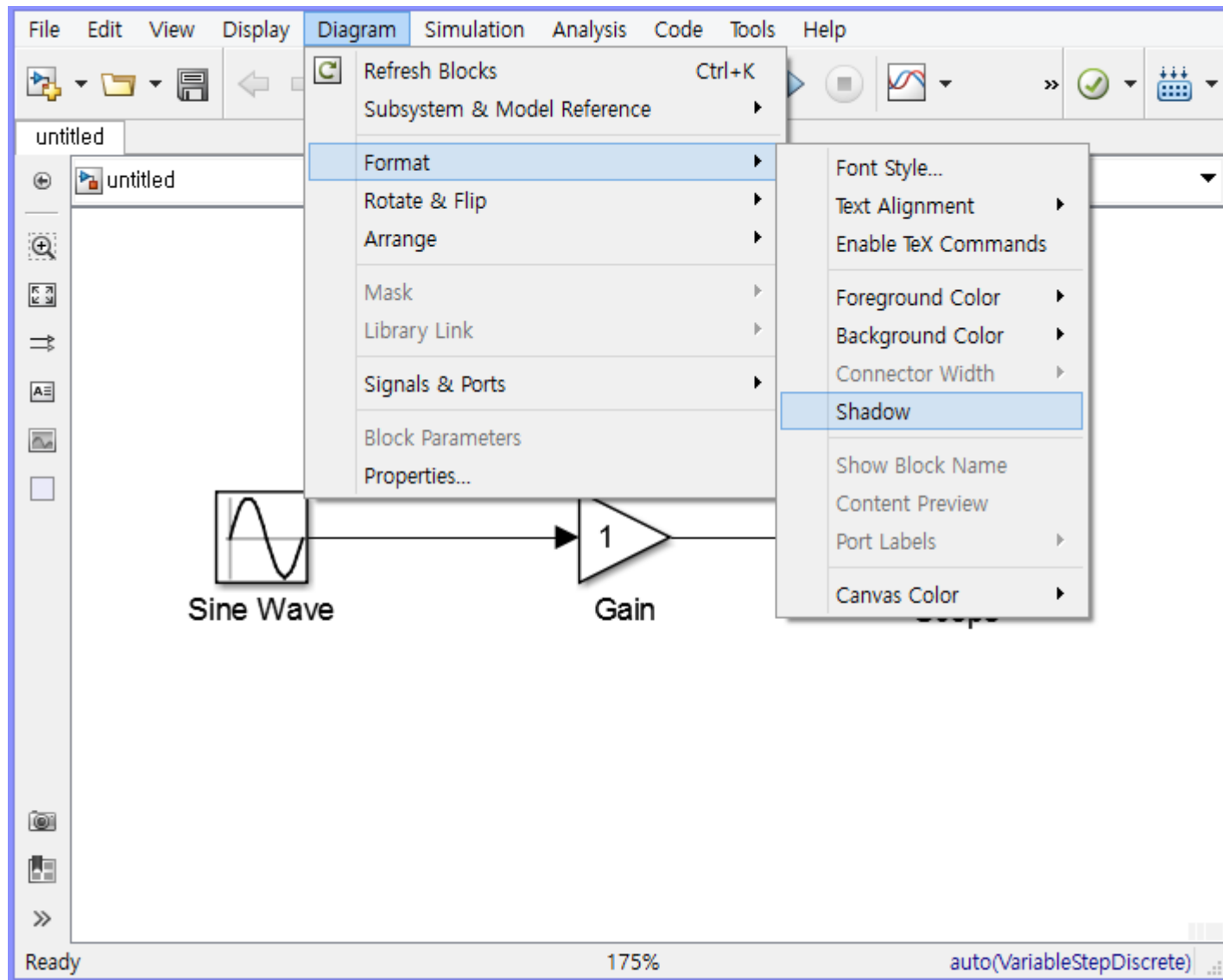
Arial 10

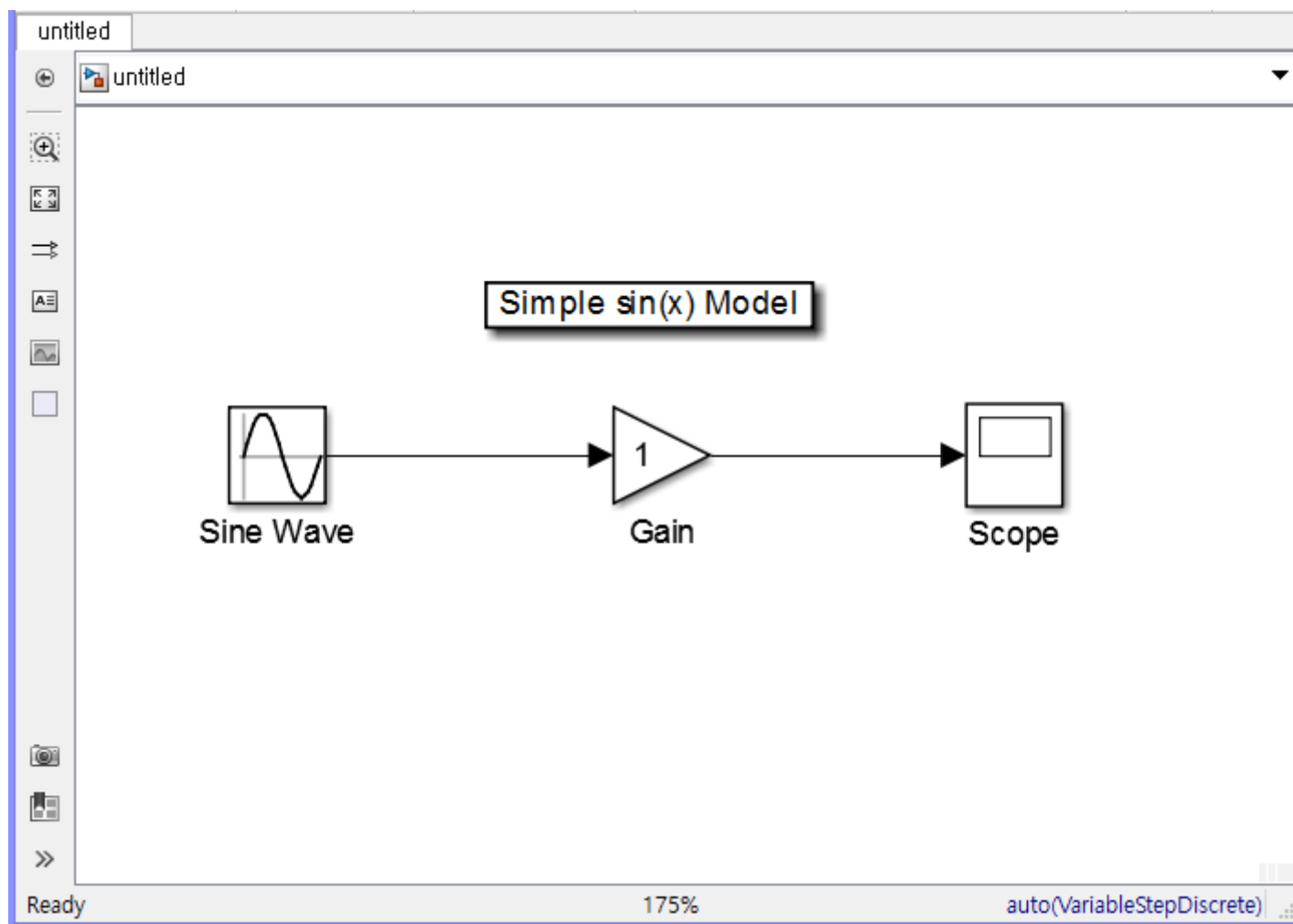
B *I* U A ab ≡ ≡ ↶ ↷ ↶ ↷

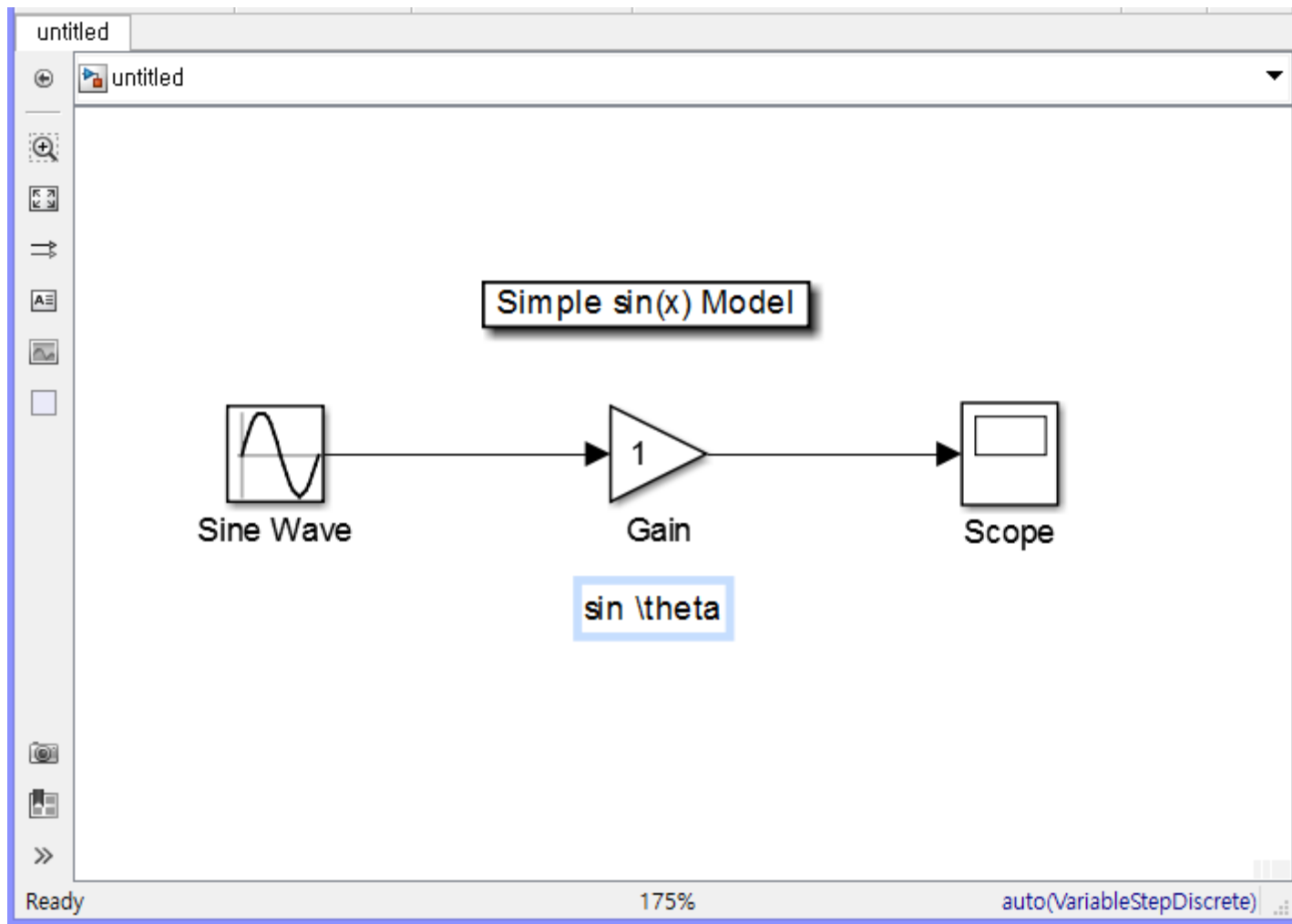
|

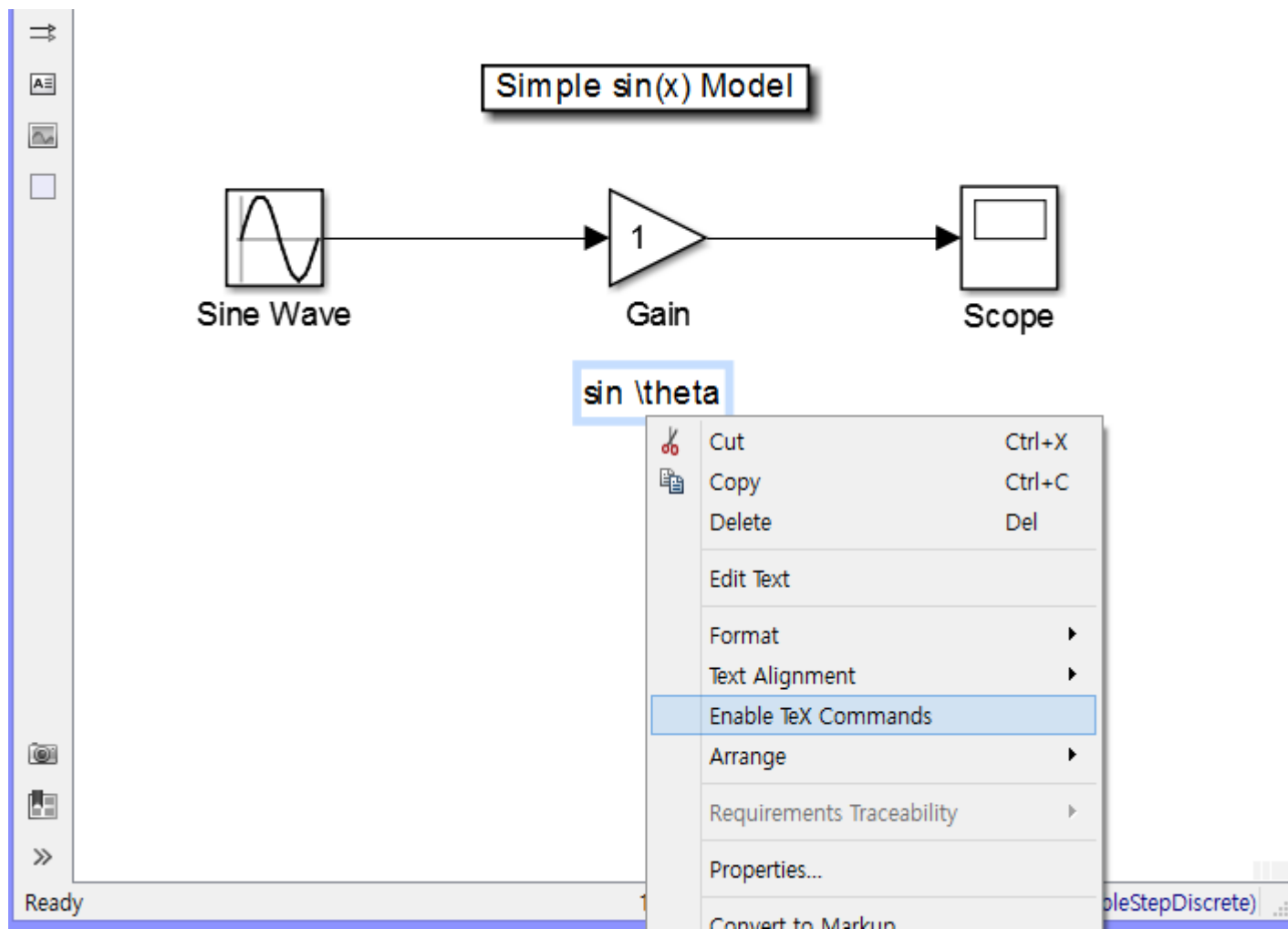


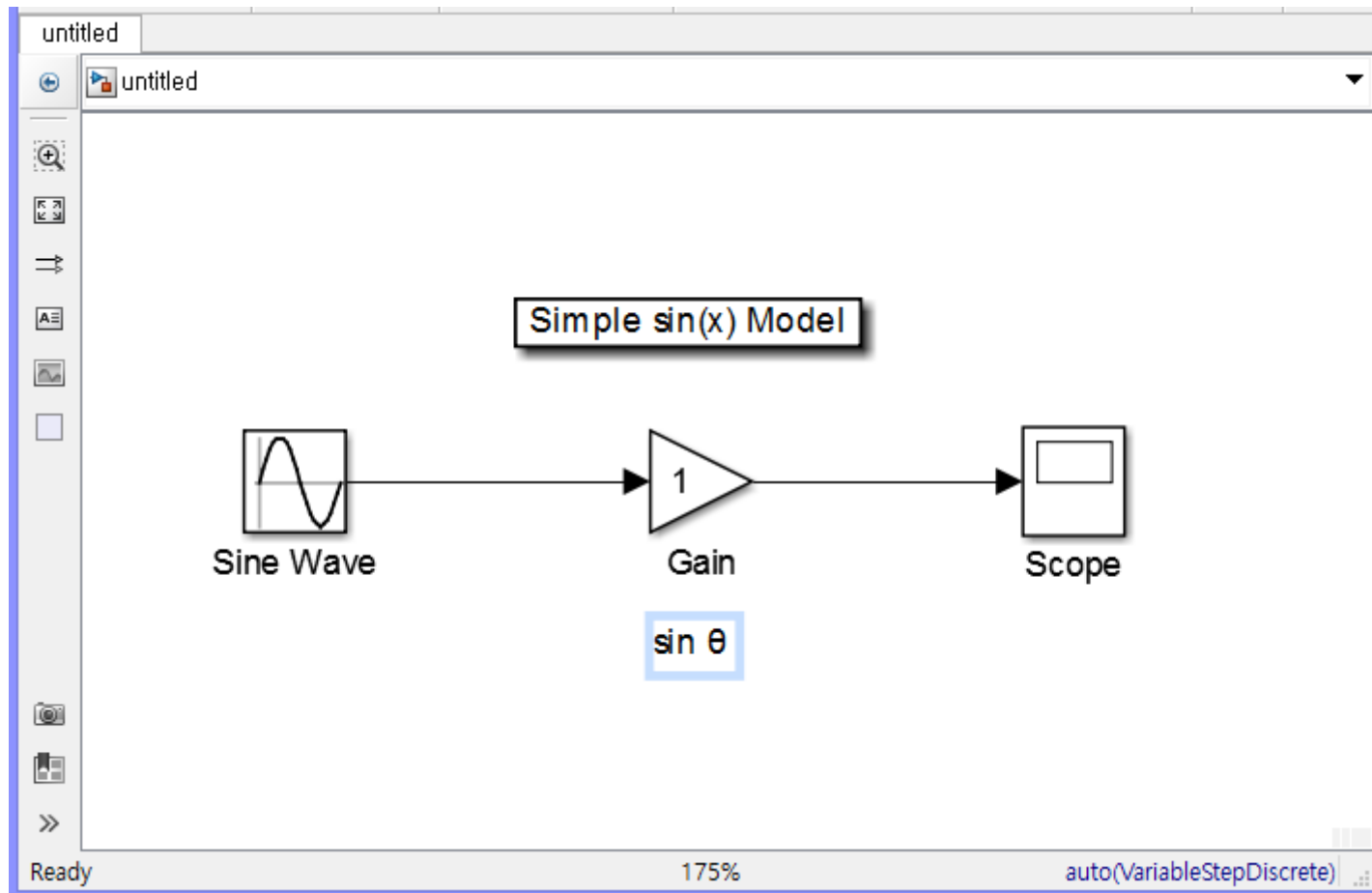


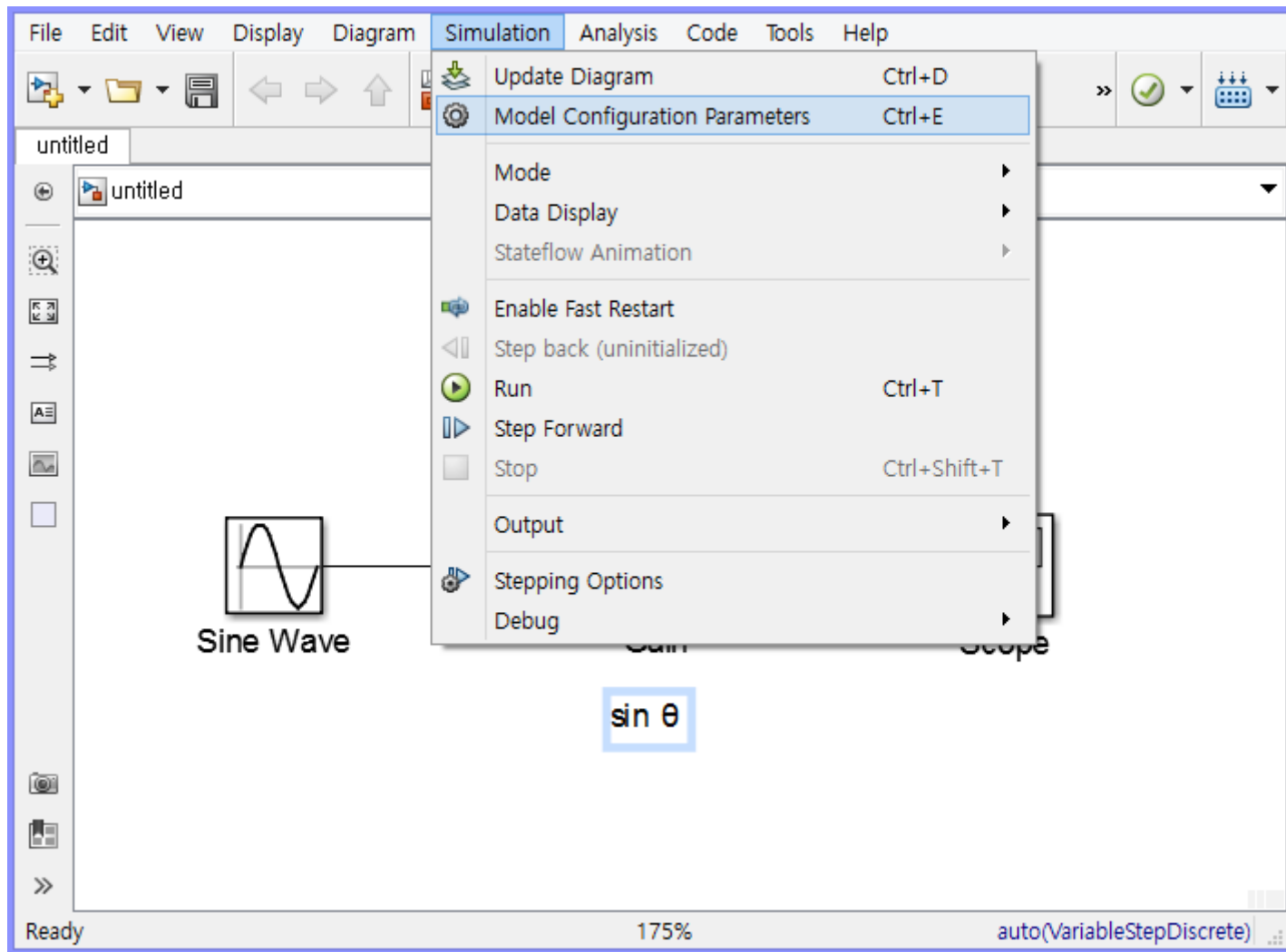












Configuration Parameters: untitled/Configuration (Active)

★ Commonly Used Parameters

≡ All Parameters

Select:

Solver

Data Import/Export

▶ Optimization

▶ Diagnostics

Hardware Implementation

Model Referencing

Simulation Target

▶ Code Generation

Simulation time

Start time: 0.0

Stop time: 10.0

Solver options

Type: Variable-step

Solver: auto (Automatic solver selection)

▼ Additional options

Max step size: auto

Relative tolerance: 1e-3

Min step size: auto

Absolute tolerance: auto

Initial step size: auto

Shape preservation: Disable All

Number of consecutive min steps:

1

Zero-crossing options

Zero-crossing control: Use local settings

Algorithm: Nonadaptive

Time tolerance: 10*128*eps

Signal threshold: auto

Number of consecutive zero crossings:

1000

Tasking and sample time options

Tasking mode for periodic sample times:

Auto

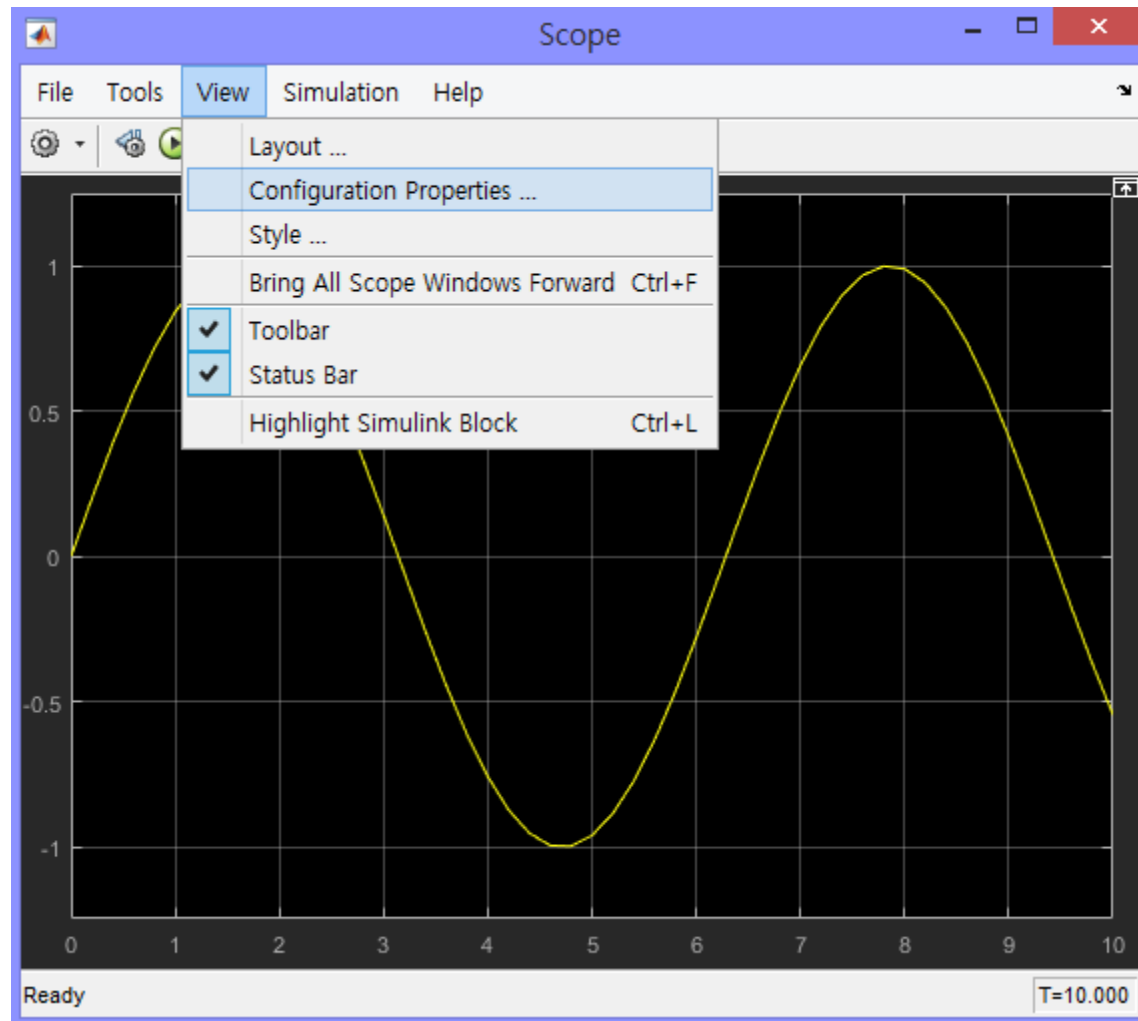
☐ Automatically handle rate transition for data transfer☐ Higher priority value indicates higher task priority

OK

Cancel

Help

Apply



Configuration Properties: Scope

Main Time Display Logging

☐ Limit data points to last: 5000

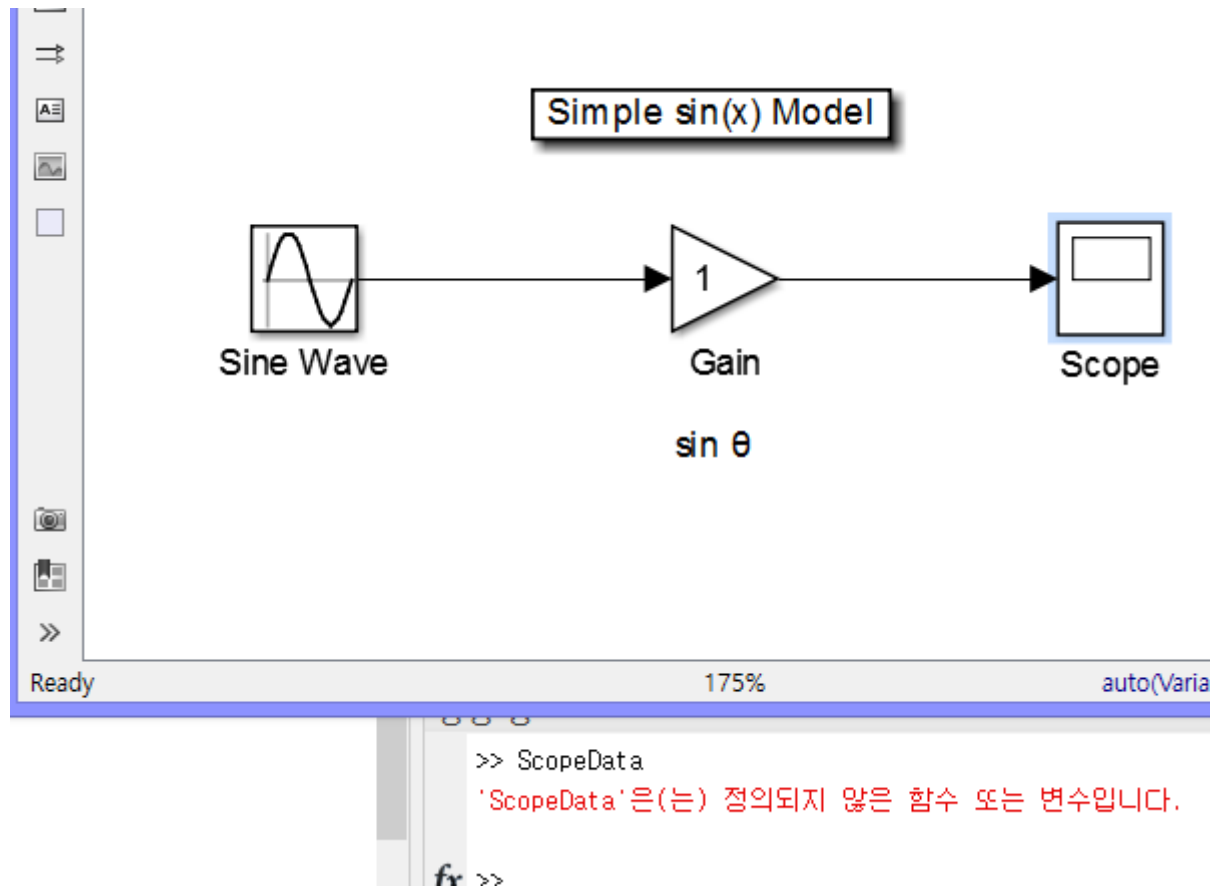
☐ Decimation: 2

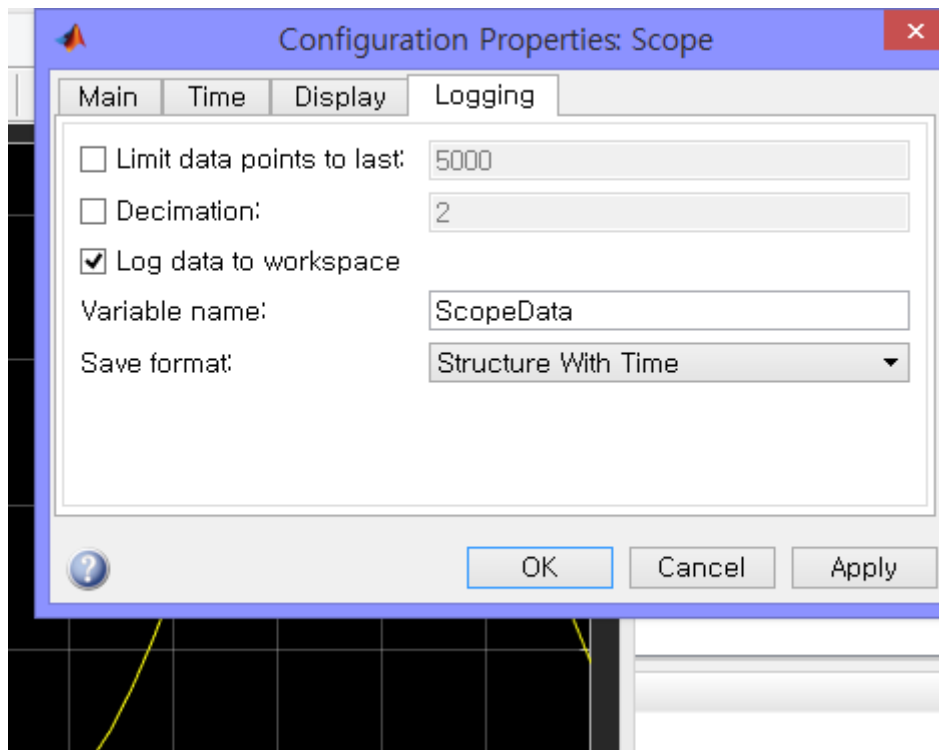
☒ Log data to workspace

Variable name: ScopeData

Save format: Dataset

? OK Cancel Apply





명령 창

```
>> ScopeData
```

```
ScopeData =
```

```
    time: [51x1 double]  
    signals: [1x1 struct]  
    blockName: 'untitled/Scope'
```

```
>> x = ScopeData.time;
```

```
>> ScopeData.signals
```

```
ans =
```

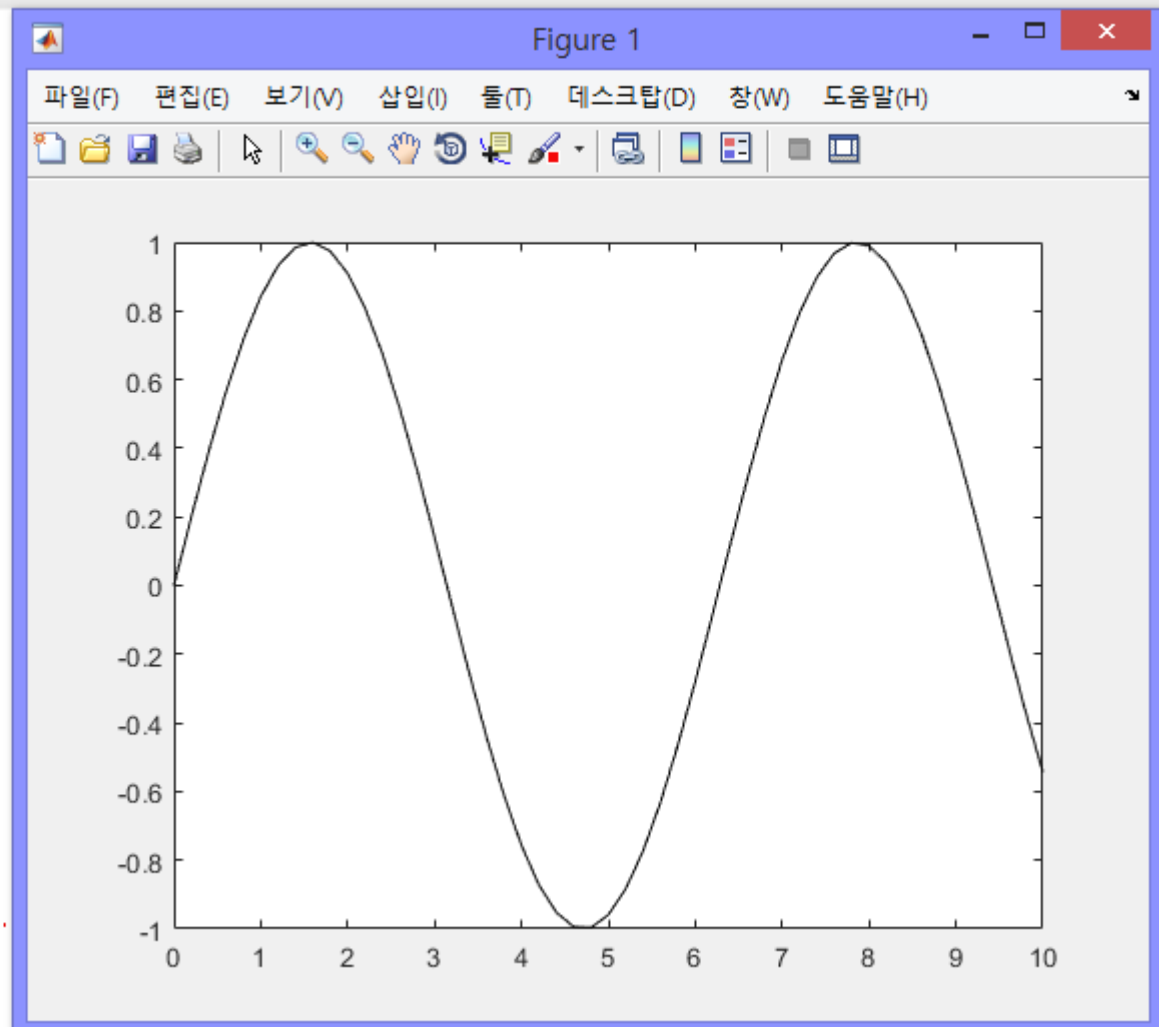
```
    values: [51x1 double]  
    dimensions: 1  
    label: ''  
    title: ''  
    plotStyle: 0
```

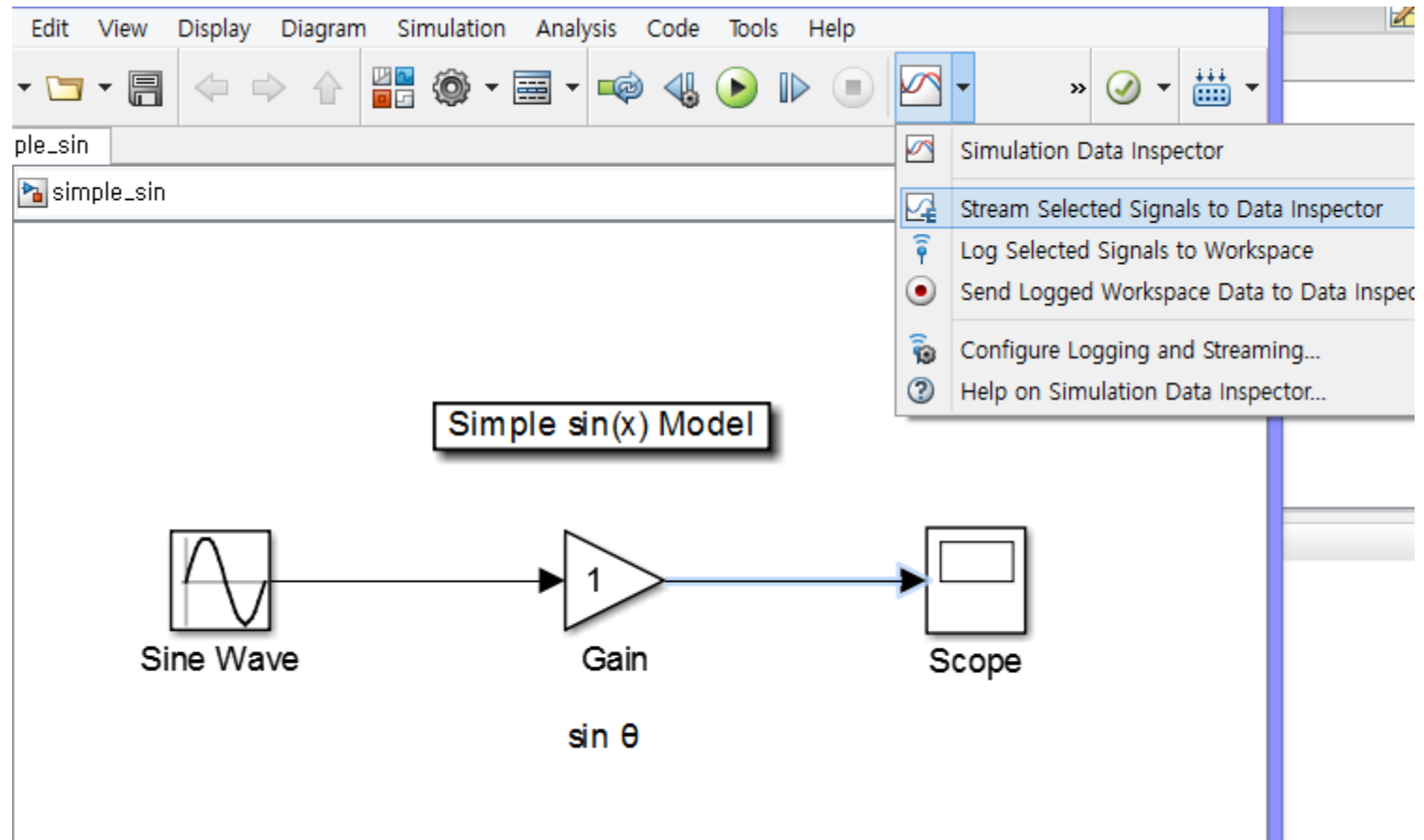
```
>> y = ScopeData.signals.values;
```

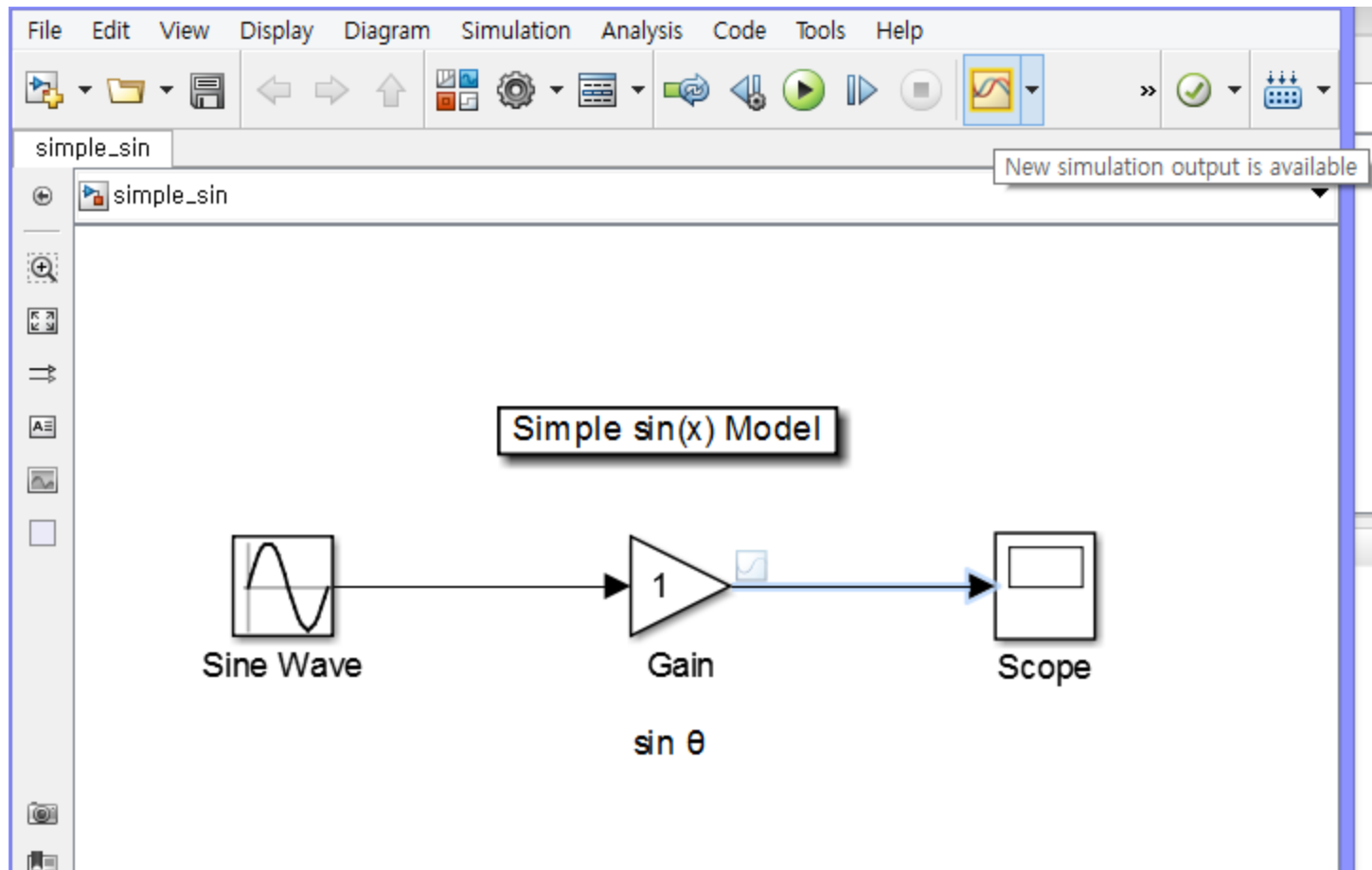
```
>> plot(x, y, 'test')
```

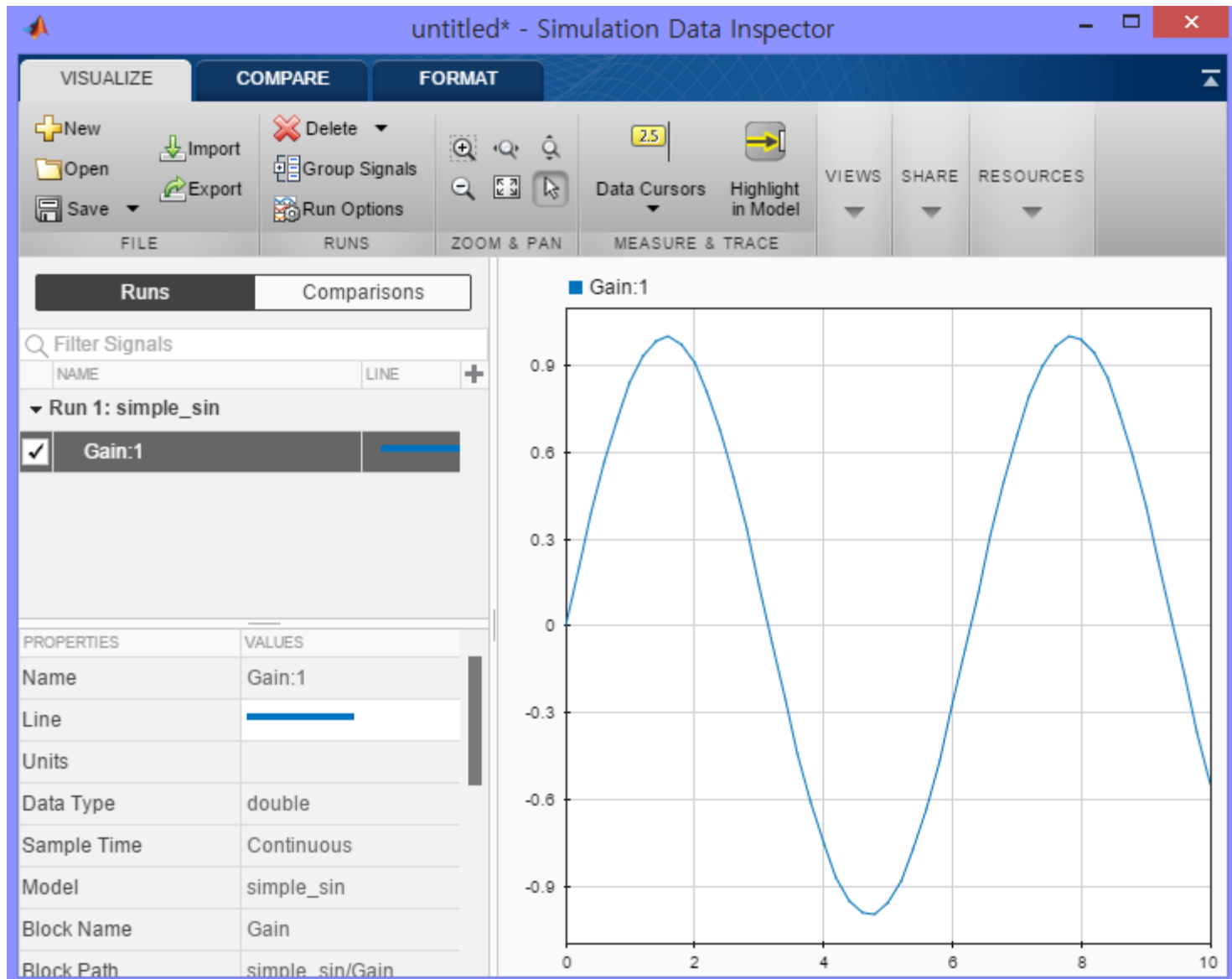
다음 사용 중 오류가 발생함: **plot**
색/선 유형 인수에서 오류가 발생했습니다.

```
>> plot(x, y, 'k')
```

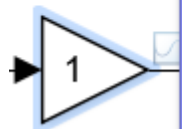








e sin(x) Mo



Gain

sin θ

175%

Block Parameters: Gain

Gain
Element-wise gain ($y = K.*u$) or matrix gain ($y = K*u$ or $y = u*K$).

Main | Signal Attributes | Parameter Attributes

Gain:

Multiplication:

? OK Cancel Help Apply

