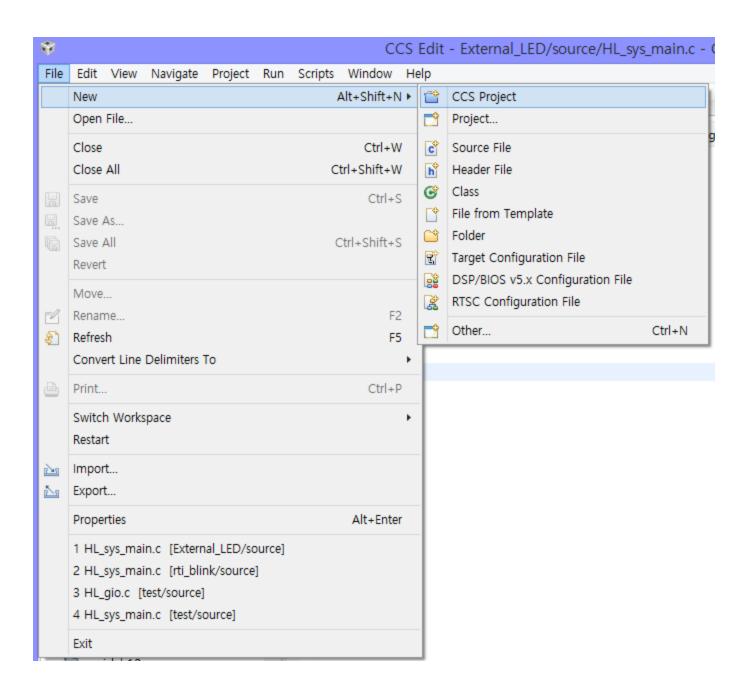
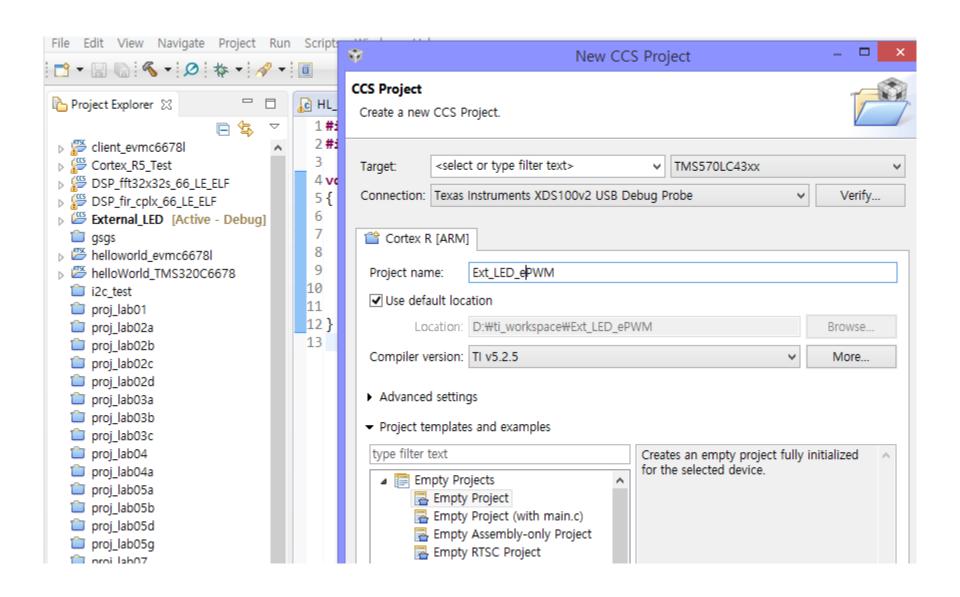
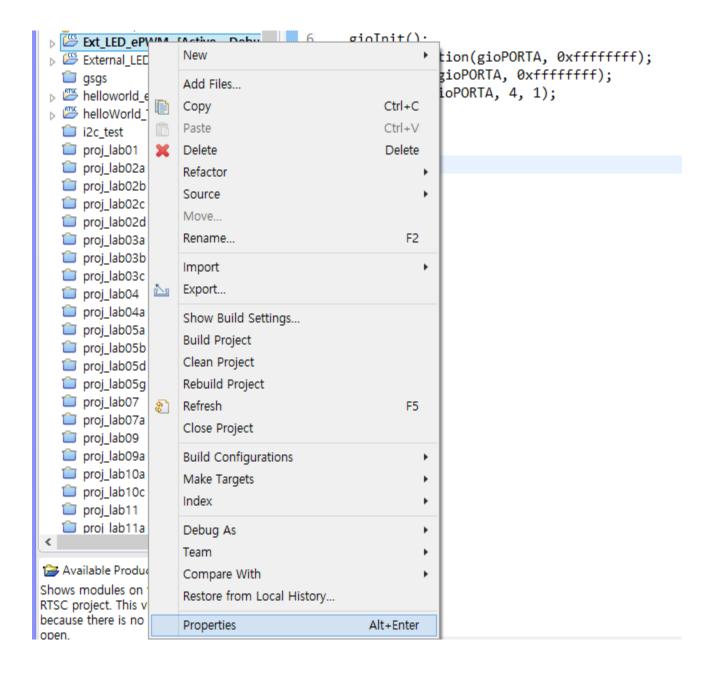
# Xilinx Zynq FPGA, TI DSP, MCU 기반의 회로 설계 및 임베디드 전문가 과정

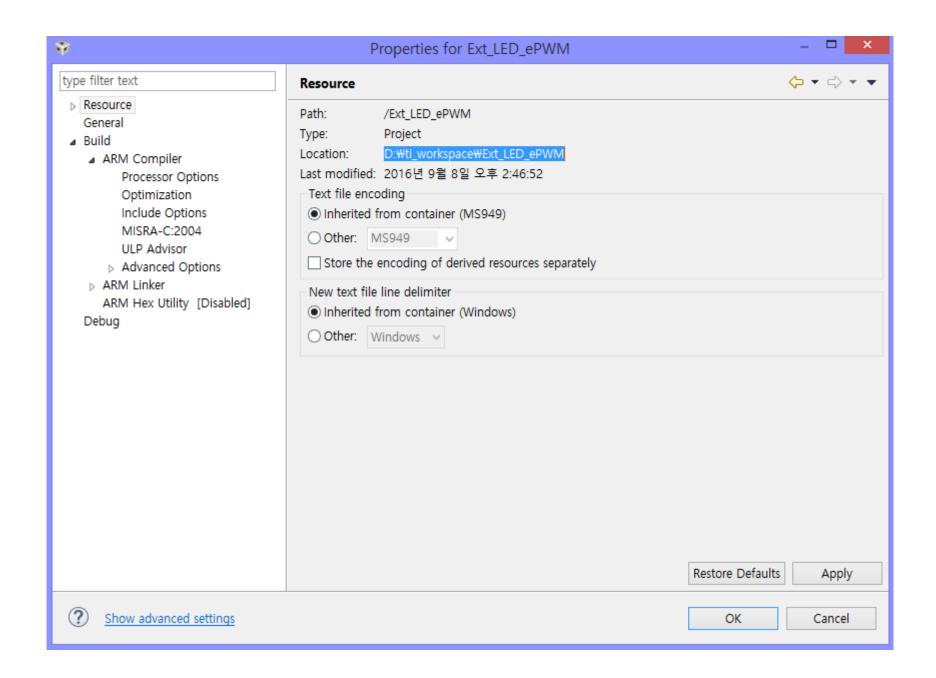
강사 – Innova Lee(이상훈) gcccompil3r@gmail.com

# **External LED with etPWM Control**



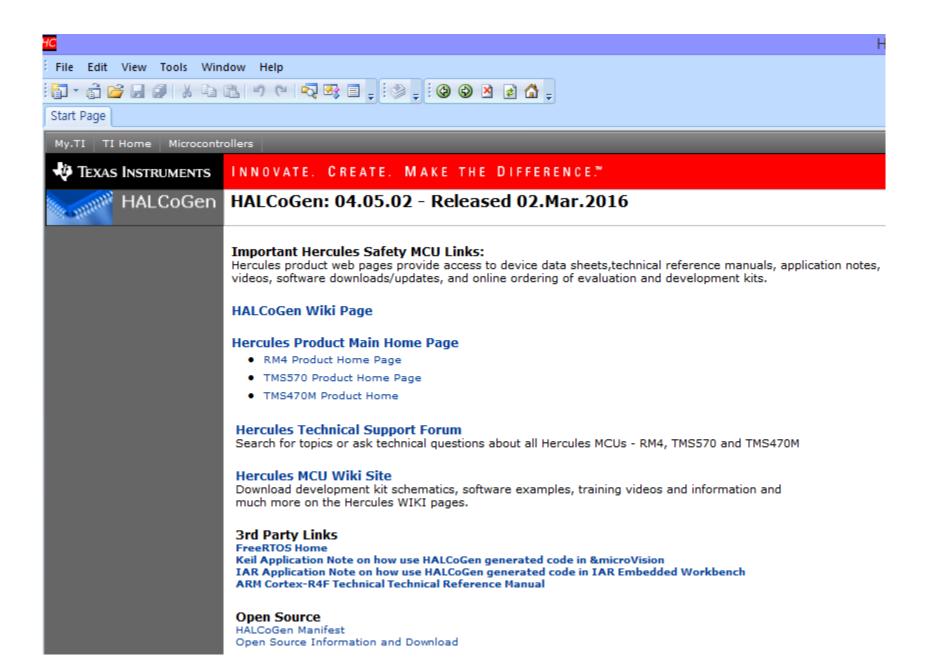


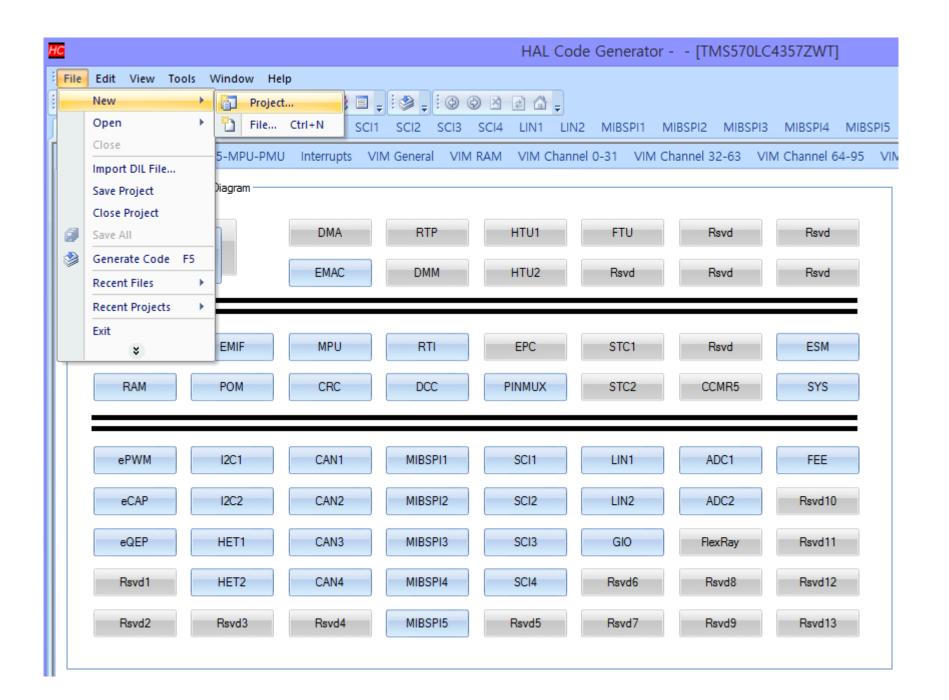


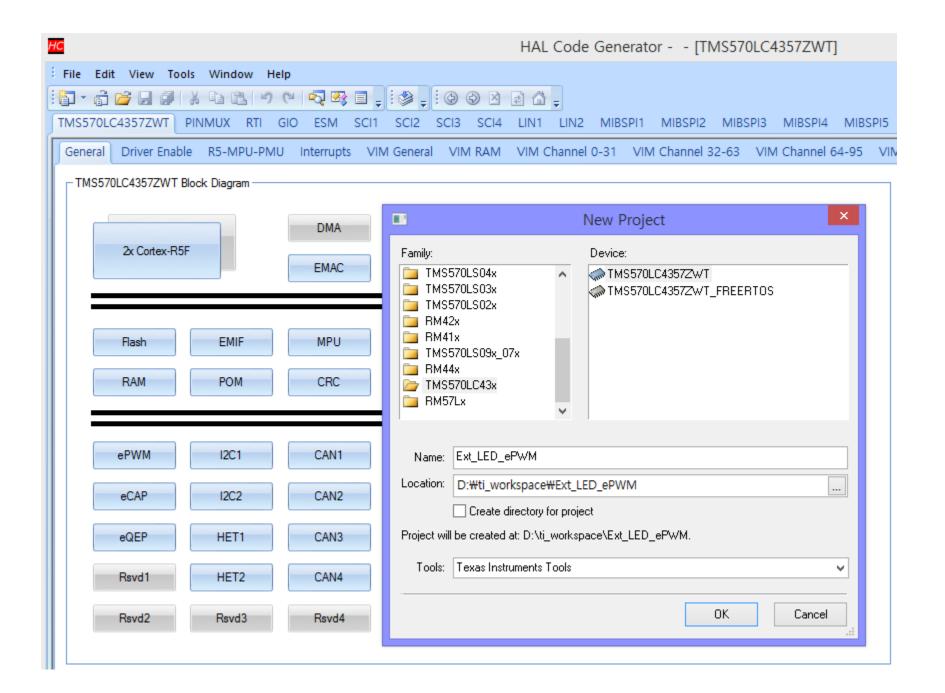


## 복사한 상태로 HALCoGen을 동작시킨다.

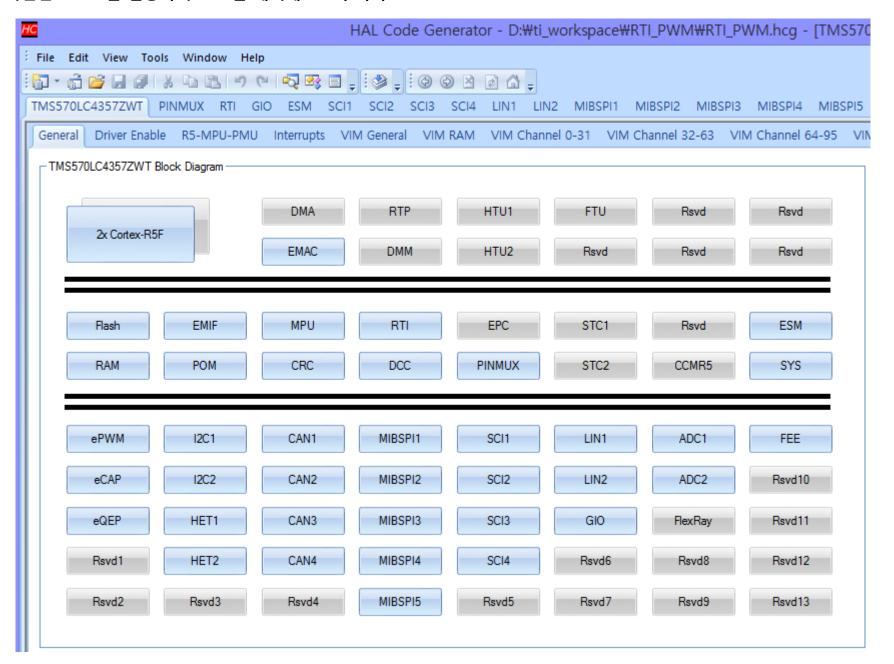
(D:) → ti → Hercules → HALCoGen → v04	1.05.02	
름	수정한 날짜	유
config	2016-04-24 오전	파
Docs	2016-04-24 오전	파
drivers	2016-04-24 오전	파
edit	2016-04-24 오전	파
examples	2016-04-24 오전	파
help	2016-05-03 오전	파
HTML	2016-04-24 오전	파
styles	2016-04-24 오전	파
HALCOGEN.exe	2015-04-07 오후	응
HCG_updater.exe	2015-07-02 오전	응
HCG_updater.ini	2016-04-24 오전	구
mfc100.dll	2013-06-27 오후	00
msvcr100.dll	2013-06-27 오후	응
Production_License_Agreement_SRAS14	2015-02-19 오후	PE
readme.txt	2016-03-02 오후	텍
TICGEN.dll	2015-04-07 오후	응
TIDEVTMP.dll	2015-04-07 오후	응
TIDILIO.dll	2015-04-07 오후	응
TIDRVTMP.dll	2015-04-07 오후	응
TIHCGIO.dll	2015-04-07 오후	응
TIJS32.dll	2015-04-07 오후	응
uninstall.dat	2016-04-24 오전	DA
uninstall.exe	2016-04-24 오전	응

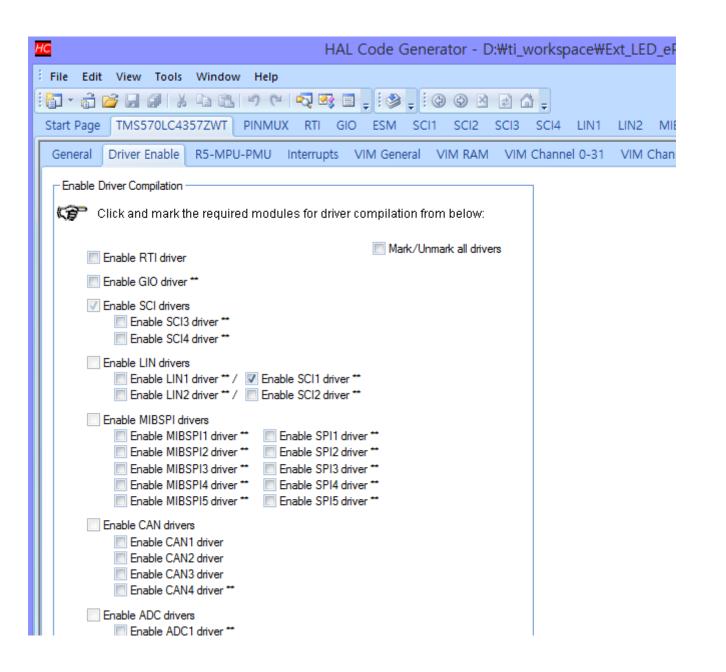


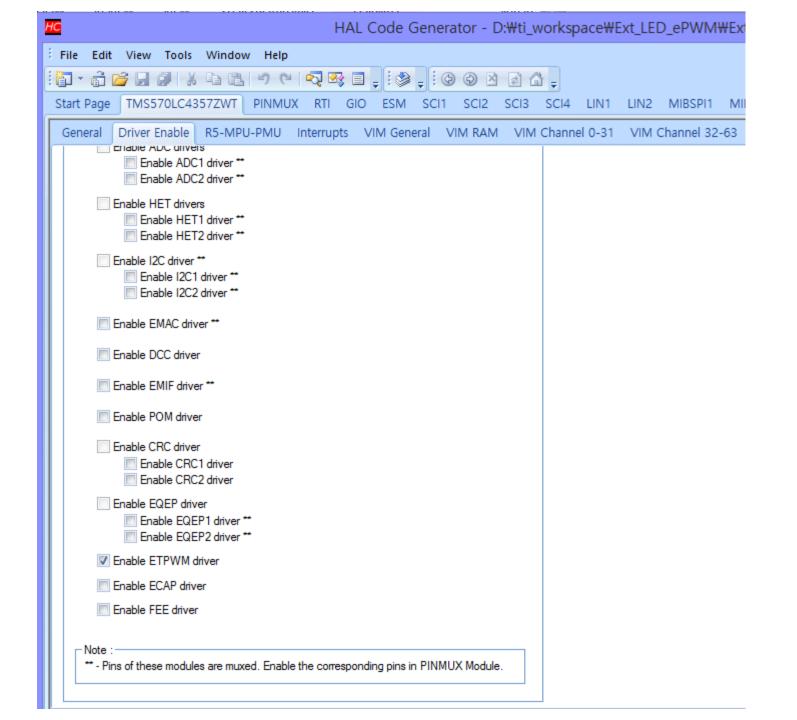


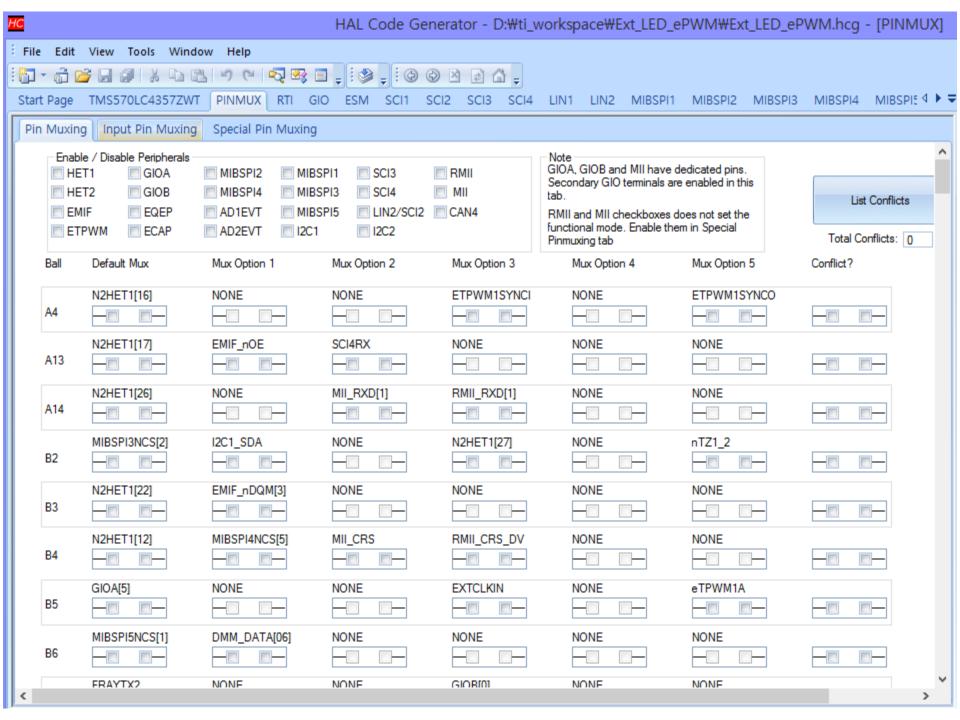


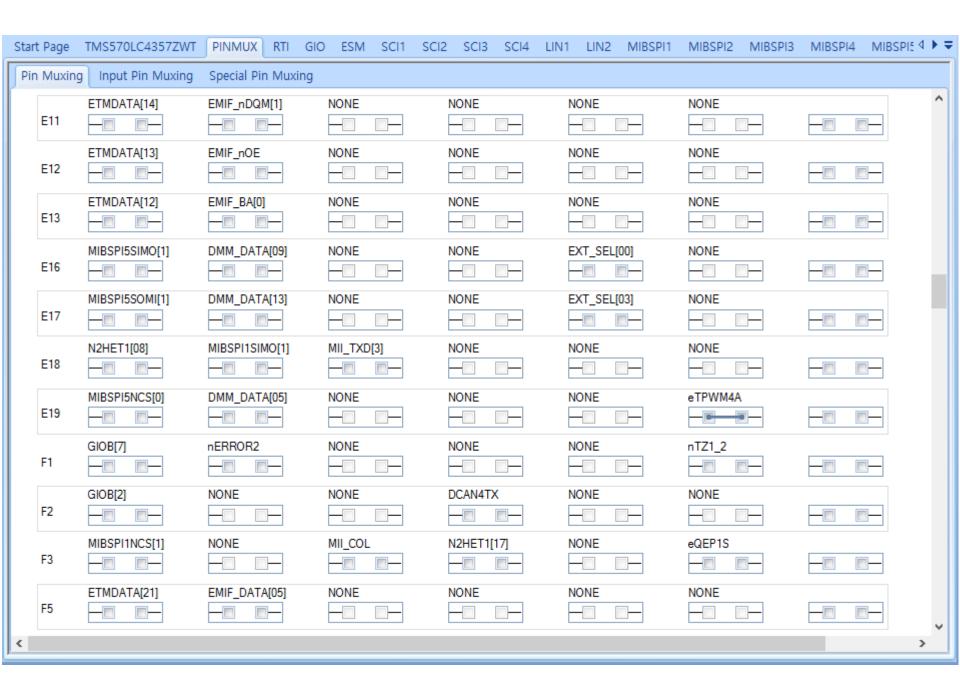
### 이번엔 PWM 을 활용하여 LED 를 제어해보도록 하자!

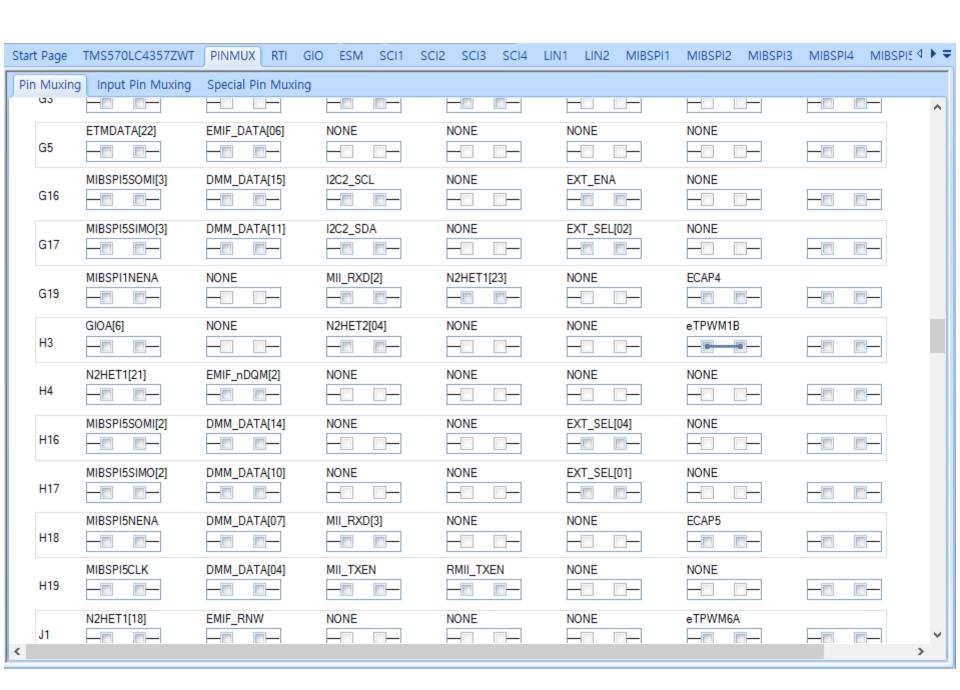


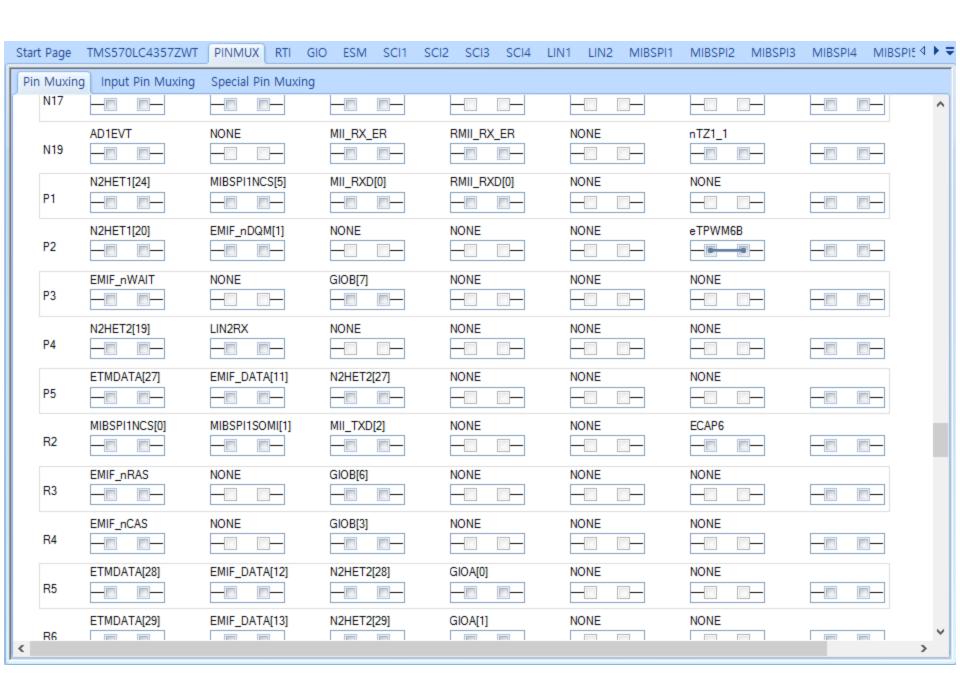


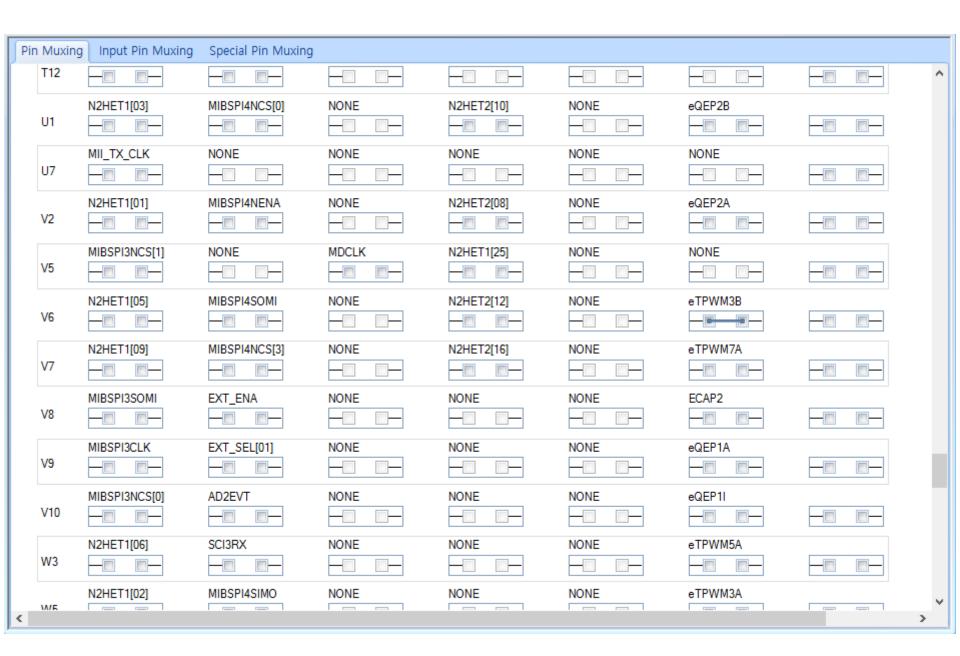


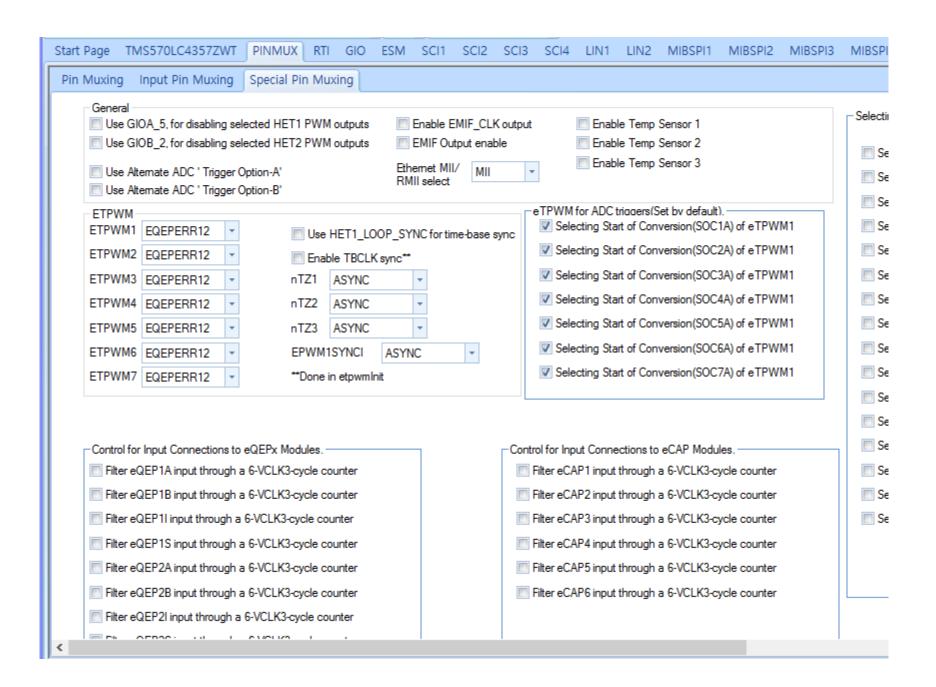


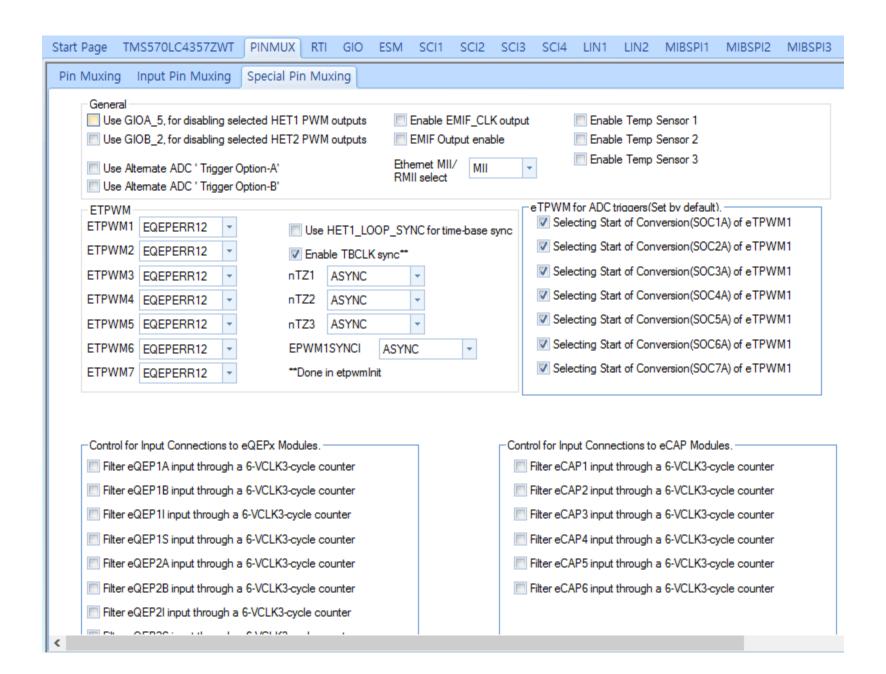


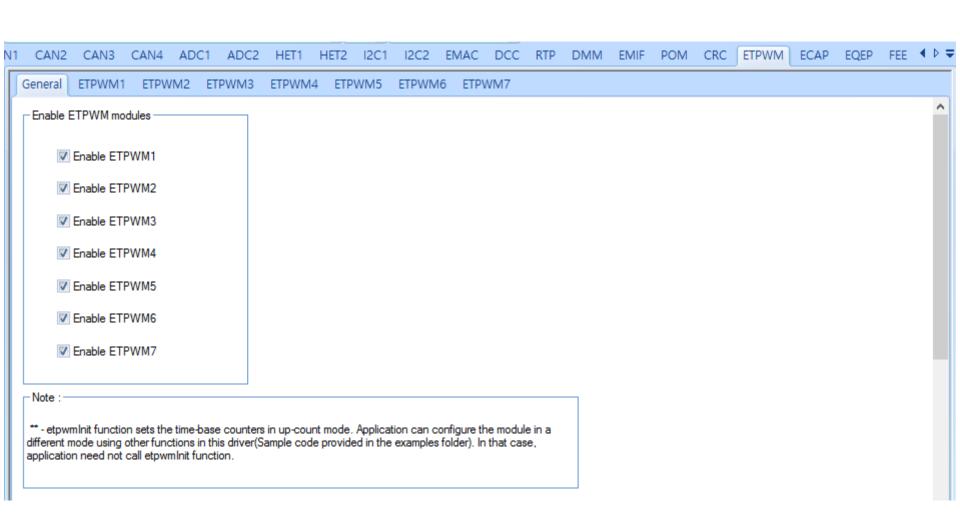


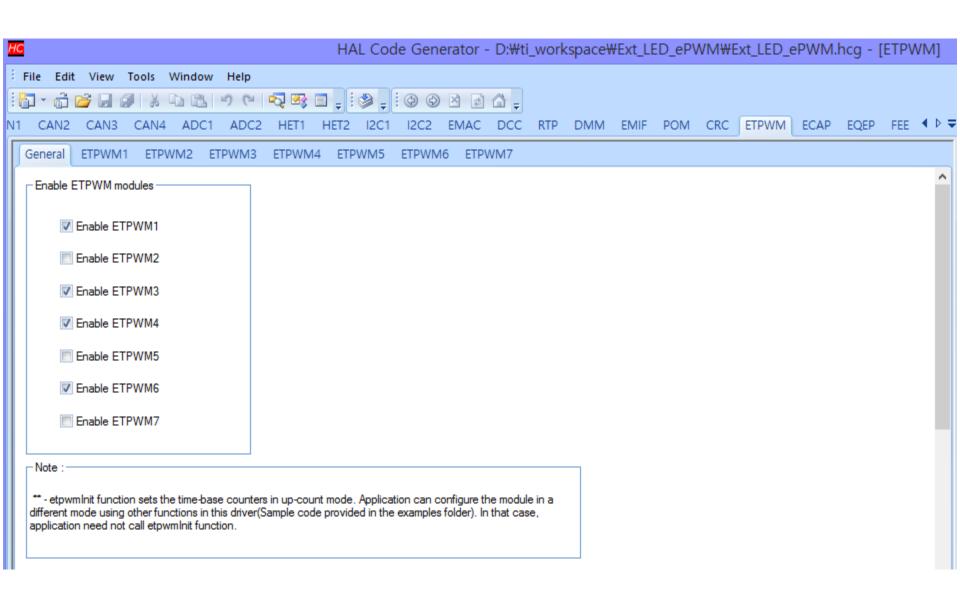


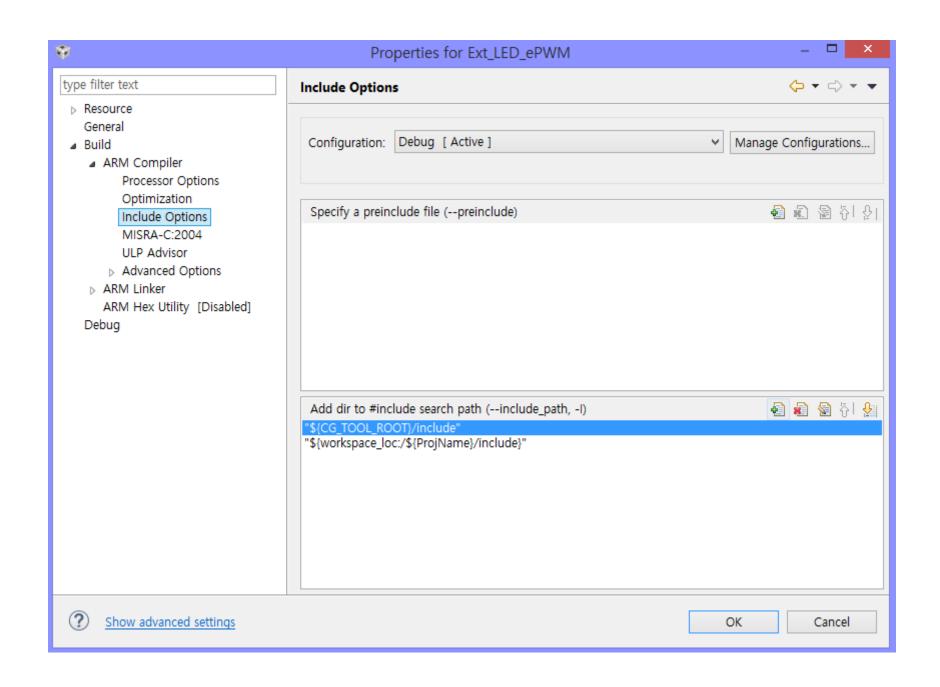








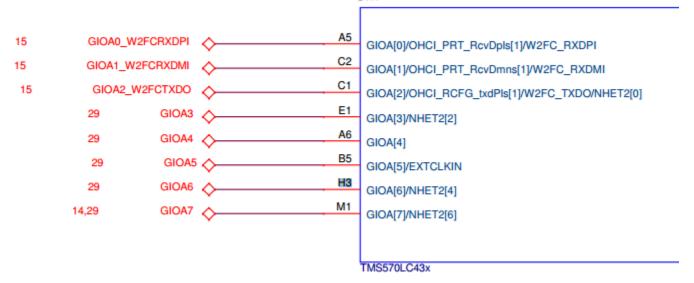




#### U1D

F18 R2 F3 G3 J3 G19	MIBSPI1CLK  MIBSPI1NCS[0]/MIBSPI1SOMI[1]/MII_TXD[2]/OHCI_PRT_RcvData[0]  MIBSPI1NCS[1]/NHET1[17]/MII_COL/OHCI_RCFG_suspend[0]  MIBSPI1NCS[2]/NHET1[19]/MDIO  MIBSPI1NCS[3]/NHET1[21]  MIBSPI1NCS[3]/NHET1[21]  MIBSPI1NCS[3]/MHET1[23]/MII_RXD[2]/OHCI_PRT_RcvDpls[0]	D2 D1 D3 N3 E2
F19 G18	MIBSPI1SIMO MIBSPI1SOMI  DMM_CLK	F17 F16
	DMM_nENA DMM_SYNC  DMM_DATA0 DMM_DATA1 MIBSPI5NCS[2]/DMM_DATA[2]	L19 L18 W6 T12
	MIBSPI5NCS[3]/DMM_DATA[3]  MIBSPI5CLK/DMM_DATA[4]/MII_TXEN/RMII_TXEN  MIBSPI5NCS[0]/DMM_DATA[5]  MIBSPI5NCS[1]/DMM_DATA[6]  MIBSPI5NENA/DMM_DATA[7]/MII_RXD[3]/OHCI_PRT_RcvDmns[0]	H19 E19 B6 H18
V9 V10 V5 B2 C3 W9 W8 V8	MIBSPI3CLK MIBSPI3NCS[0]/AD2EVT/GIOB[2] MIBSPI3NCS[1]/NHET1[25]/MDCLK MIBSPI3NCS[2]/I2C_SDA/NHET1[27] MIBSPI3NCS[3]/I2C_SCL/NHET1[29] MIBSPI3NCS[3]/I2C_SCL/NHET1[29] MIBSPI3NCS[3]/I2C_SCL/NHET1[31] MIBSPI3NCS[3]/I2C_SCL/NHET1[31] MIBSPI3NCS[3]/I2C_SCL/NHET1[31] MIBSPI3NCS[3]/I2C_SCL/NHET1[31] MIBSPI3SIMO MIBSPI3SOMI MIBSPI5SOMI[1]/DMM_DATA[13] MIBSPI5SOMI[2]/DMM_DATA[14] MIBSPI3SOMI MIBSPI5SOMI[3]/DMM_DATA[15]	J19 E16 H17 G17 J18 E17 H16 G16





```
In It is a second of the last of the l
Getting Started
                                                                                                                                                                   TI Resource...
                                                                                                                                                                                                                        CCS App Center
                                                                                                                     1 #include "HL sys common.h"
                                                                                                                     2 #include "HL system.h"
  3 #include "HL etpwm.h"
  4#include "HL sci.h"
  DSP_fft32x32s_66_LE_ELF
                                                                                                                     5 #include <string.h>
  DSP_fir_cplx_66_LE_ELF
  Ext_LED_ePWM [Active - Debu
                                                                                                                     7 #define UART
                                                                                                                                                                                 sciREG1
          8 #define MAX
                                                                                                                                                                                 50
          ▶ 🚮 Includes
          Debug
                                                                                                                 10 volatile int delay;
          include
                                                                                                                 11 unsigned int ePWM4A = 0, ePWM6B = 0, ePWM3B = 0, ePWM1B = 0;
          Source
                                                                                                                 12
                  13 uint32 receiveData = 0;
                  ▶ Ic HL_errata.c
                  15 void catchCommand(void)
                  16 {
                   17
                                                                                                                                       while((UART->FLR & 0x4) == 4)
                  18
                   19
                  receiveData = sciReceiveByte(UART);
                                                                                                                  20
                  21 }
                  22
```

```
23 void main(void)
24 {
25
      int flag = 0;
26
      int temp = MAX;
27
28
      sciInit();
29
      etpwmInit();
30
      for(;;)
31
32
33
           etpwmStartTBCLK();
34
35
           if((UART->FLR & 0x200) == 0 && flag == 0)
36
37
               for(delay = 0; delay < 100000; delay++)</pre>
38
                   ;
39
40
               if(ePWM4A >= (temp + 50))
41
                   ePWM4A = 0;
42
               else
43
                   ePWM4A++;
44
45
               etpwmSetCmpA(etpwmREG4, ePWM4A);
46
47
               for(delay = 0; delay < 100000; delay++)</pre>
48
49
50
               if(ePWM6B >= (temp + 30))
51
                   ePWM6B = 0;
52
               else
53
                   ePWM6B++;
```

```
54
55
               etpwmSetCmpB(etpwmREG6, ePWM6B);
56
57
               for(delay = 0; delay < 100000; delay++)</pre>
58
                   j
59
60
               if(ePWM3B >= (temp - 10))
61
                   ePWM3B = 0;
62
               else
                   ePWM3B++;
63
64
65
               etpwmSetCmpB(etpwmREG3, ePWM3B);
66
67
               for(delay = 0; delay < 100000; delay++)</pre>
68
69
70
               if(ePWM1B >= (temp + 60))
71
72
                   for(delay = 0; delay < 100000; delay++)</pre>
73
74
75
                   ePWM1B = 0;
76
77
               else
78
                   ePWM1B++;
79
               etpwmSetCmpB(etpwmREG1, ePWM1B);
80
81
```

```
82
            else if((UART->FLR & 0x200) == 0 && flag == 1)
 83
            {
 84
                for(delay = 0; delay < 100000; delay++)</pre>
 85
 86
 87
                if(ePWM4A >= temp)
 88
                     ePWM4A = 0;
 89
                else
 90
                     ePWM4A++;
 91
 92
                etpwmSetCmpA(etpwmREG4, ePWM4A);
 93
 94
                for(delay = 0; delay < 100000; delay++)</pre>
 95
 96
 97
                if(ePWM6B >= temp)
 98
                     ePWM6B = 0;
 99
                else
100
                     ePWM6B++;
101
102
                etpwmSetCmpB(etpwmREG6, ePWM6B);
103
104
                for(delay = 0; delay < 100000; delay++)</pre>
105
106
107
                if(ePWM3B >= temp)
108
                     ePWM3B = 0;
109
                else
110
                     ePWM3B++;
111
112
                etpwmSetCmpB(etpwmREG3, ePWM3B);
```

```
113
114
              for(delay = 0; delay < 100000; delay++)</pre>
115
                  ;
116
117
               if(ePWM1B >= temp)
118
                  ePWM1B = 0;
119
               else
120
                  ePWM1B++;
121
122
               etpwmSetCmpB(etpwmREG1, ePWM1B);
123
124
           else
                      테라텀이나 하이퍼터미널을 활용해서 UART 통신을 수행할 수 있다.
125
126
               catchCommand();
127
               if (receiveData == 53) 숫자 5에 해당하는 부분
128
129
130
                  flag = 1;
131
                  ePWM4A = temp-20;
132
                  ePWM6B = temp-20;
133
                  ePWM3B = temp-20;
134
                  ePWM1B = temp-20;
135
136
               else if (receiveData == 48) 숫자 0에 해당하는 부분
137
138
                  flag = 0;
139
                  ePWM4A = 0;
140
                  ePWM6B = 0;
141
                  ePWM3B = 0;
142
                  ePWM1B = 0;
143
144
           }
145
146
           etpwmStopTBCLK();
147
148 }
```

