Stepper Motor :- (Clock-wise)

```c
# include < stdio.h>
# include < reg 51.h>
char xdata port -at -0xe 803;
char xdata port -at 0xe 800;
char xdata acc -at 0x30;

delay () {
    int i;
    for ( i = 0; i < 300 ; i++)
    { }
{

void main ()
{
    port = 0x80;
    while (1) {
        acc = 0x88;
        port a = acc;
        delay ();
        acc = 0x44;
        port a = acc;
        delay ();
        acc = 0x22;
        port a = acc;
        delay ();
        acc = 0x11;
        port a = acc;
        delay ();
    }
}
```