

ASSIGNMENT NO. 8

	Name: Siddheth Dilip khairnar PANNO: 22110398 ROLLIO: 372028 Page Mo. Date
	TP Assignment W 8
- b	
	Aim: Perform object detection from an image of the
	Learning objective: - : newsound soutant (1)
(teams	learn hu concept of object detection, which involves identifying
2)	Localizing object within image or video frames. It are faster familiarize with different object detection models, such as faster
	pariliarize untraggerent object detection models, such as faster R-CNN, YOLO &SSD, and select one that suits your needs.
22.3)	bear about class prediction for detected objects, often using
	softman activation to estimate class probabilities.
	Thony: -> = naisonification > = = 0
to con	Object detection a a computer insion task that involves identifying
doi Hoo	and locating objects within an mage three's a high-level overineur
	of the theory & steps involved in performing object detection from an images:
	7) New Manimum Suppression:
(101)	Data collection: griggatione of stavilgula startinula of
Dipsu jo	Gathor a dataset of image that contain the object you want to detect
	Annotate those images to specify the location of each object with
1 1111	bounding boxes prise may tell (2)
70000	select à Model: 2 aitisen les que le traitemen pritoures
	choose à pre-trained object detection model en design your over.
	popular models includes jaster R-CNN, your and sso (single shot
	Mutti-Box Detector) and Toutoutous (D
io display	Draw tounding loxes and labers or that original image
	नेम वास्ट्रस्त वेपुर्ट्छ.

	Randon Alla Helinbia small 8 8501 Page No. 1999 2002 Page No. 1999 2002 Page No. 1999
	2 av Insmapissa AT
3)	Proprocession:
	prepare your input images by resizing, normalizing and
	prepare your input images by resizing, normalizing and augmenting thin as needed 1991-1991 and
4)	feature extraction:
Bring	The selected model autour convolution layer to extract feature
	from the orpine ortage
Charles Control	2) jamiliarize with different degled notacling medels, such
· · · · · · · · · · · · · · · · · · ·	The model's localization head will predict bounding boxes
0	(woordinates) for each detected object within the image.
	3
6)	Object classification:
pointitach	The classification head of the model will predict the class of
Dominen	each detected orgect. This is often done using a softman actuation
no may n	function to estimate class probabilities.
-7)	Olea Manimum Cuantilian I
	Non Manimum suppression: ->
field at la	To eliminate duplicate on overlapping detection, apply non-maximum suppression (NMS) to retain the most conjudent predicts
	we was a company the brains of each sent.
	Post-processing: -
	Translate the model's output into human - readable result by
	converting coordinates topical positions, associating class lakes,
0000-4	and confidence some with each detected object
19126	pepular minters includes fasta k-ann, you and sen (si
9)	Visualization: - Crecion State Constitution of the Constitution of
	Draw bounding boxes and labers on the original image to display
	the detected objects.

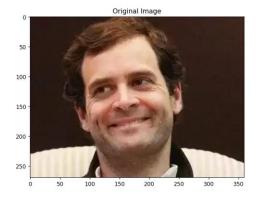
	Page Mo. Date
10)	Evaluation and fine-tuning:— Evaluating the model's performance using metrics like mAP (mean Average precision). fine ture the message model if necessary to improve detection accuracy.
11)	Deployment: - Deploy the object detection model in your application or system, Whether it's for real-time processing or batch processing.
12)	Inference: -> Use the trained model to payorn object detection on new, usurseen images.
	Remember: Conclusion: -> Learn the concept of object detection, which involves identifying and localizing object within image or video frames.
	A A A A A A A A A A A A A A A A A A A

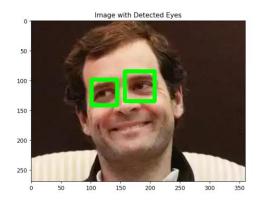
Program Code:

```
import cv2
from matplotlib import pyplot as plt
import os
# Get the full path to the current script
script_path = os.path.dirname(os.path.abspath(__file__))
# Load Haar cascade file for eyes
cascade_path = os.path.join(
    script path, "C:/Users/asus/Downloads/haarcascade eye.xml")
stop_data = cv2.CascadeClassifier(cascade_path)
# Check if the cascade classifier is loaded successfully
if stop data.empty():
    print(f"Error: Unable to load cascade classifier from {cascade_path}")
    exit()
# Opening image
img = cv2.imread("C:/Users/asus/Downloads/Rahul-Gandhi.webp")
# Convert the image to grayscale
img_gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
# Detect eves
found = stop_data.detectMultiScale(img_gray, minSize=(20, 20))
# Display the original image
plt.figure(figsize=(10, 10))
plt.subplot(1, 2, 1)
plt.title('Original Image')
plt.imshow(cv2.cvtColor(img, cv2.COLOR_BGR2RGB))
# Display the image with detected eyes
for (x, y, width, height) in found:
    cv2.rectangle(img, (x, y), (x + width, y + height), (0, 255, 0), 5)
plt.subplot(1, 2, 2)
plt.title('Image with Detected Eyes')
plt.imshow(cv2.cvtColor(img, cv2.COLOR BGR2RGB))
plt.show()
```

XML LINK: <u>haar-cascade-files/haarcascade_eye.xml at master · anaustinbeing/haar-cascade-files</u> (github.com)

% Floure 1 − Ø X





x=272.0 y=207.7
[41, 27, 20]

□