# Variable Ordering

In Constraint Satisfaction Problems (CSPs), variable ordering is a key strategy used to make the search for a solution more efficient. It refers to the order in which variables are selected and assigned values during the search process (such as backtracking search). Choosing the right variable at the right time can significantly reduce the size of the search space and improve performance.

Let's break down variable ordering in detail:



# Key Concepts in CSP Variable Ordering

### 1. Static vs. Dynamic Variable Ordering

Туре	Description	Example
Static	The order is decided before the search begins and does not change.	Assign variables in alphabetical order or input order.
Dynamic	The order can change during search based on the current state of the CSP.	Use heuristics like Minimum Remaining Values (MRV).
Heuristic	Strategy	Goal
MRV	Choose variable with fewest legal values	Fail fast
Degree	Choose variable involved in most constraints	Reduce branching
Static	Predefined order	Simple, but not adaptive
Dynamic	Order changes during search	Adapts to problem state

### **Example in Backtracking Search**

#### **Problem:**

Variables: A, B, C

Domains: A={1,2}, B={1,2}, C={1,2}

Constraints:

A ≠ B

• B ≠ C

A ≠ C

If we use MRV, all variables have equal domain sizes, so we apply degree heuristic:

• Each variable has constraints with two others → choose any.

But after assigning a value to A, if B's domain shrinks more than C's, choose B next using MRV.

### **Impact of Good Variable Ordering**

Good variable ordering:

- Reduces the size of the search tree.
- Decreases the number of backtracks.
- Speeds up solution finding.

Poor variable ordering can:

- Cause a combinatorial explosion.
- Result in unnecessary search paths.

### **Static Variable Ordering**

- Simple to implement.
- May work well for small or easy problems.
- Not adaptive doesn't respond to difficulties encountered during search.

Example:

Variables: X, Y, Z

Static order:  $X \rightarrow Y \rightarrow Z$ 

## **Dynamic Variable Ordering Heuristics**

Dynamic heuristics are often used in backtracking algorithms to speed up solving CSPs. The most common heuristics are:

### 1. Minimum Remaining Values (MRV) / Most Constrained Variable

- Choose the variable with the fewest legal values left.
- Also known as the "fail-first" heuristic try the variable most likely to cause a failure first.

Domain(X) =  $\{1,2,3\}$ 

 $Domain(Y) = \{1\}$ 

Domain(Z) = {1,2}

Choose Y first because it has only 1 value.

Helps detect dead ends early and reduce unnecessary search

## **Degree Heuristic**

- Among variables with same MRV, choose the one involved in the most constraints with unassigned variables.
- A tie-breaker to MRV.
- Prioritizes variables that affect the most others, helping to reduce branching factor early.

### **Example:**

If two variables have 2 remaining values, choose the one that has more constraints with other unassigned variables.

### **Combined Heuristic: MRV + Degree**

- Often, MRV is used first.
- If multiple variables have the same minimum domain size, use the Degree Heuristic to break ties.

# Least Constraining Value (LCV) (Value Ordering, but related)

- Choose the value that rules out the fewest choices for the neighboring variables.
- Though this is value ordering (not variable ordering), it often works in tandem with variable ordering.