Post Doc Smart 3D space subdivision for indoor navigation

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TopoBuilding (My PhD Project)

Context & Approach

- Engineers cannot use models from architects to perform simulation...
- Geometric, topological and semantical information needed
- IFC & CityGML: semantic-oriented standards: not always consistent...

Enrich a geometric model with topological and semantic information

BIM



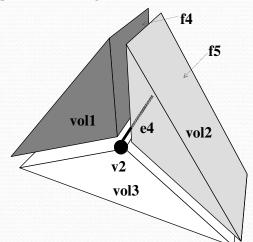


Topological Reconstruction

Combinatorial Maps

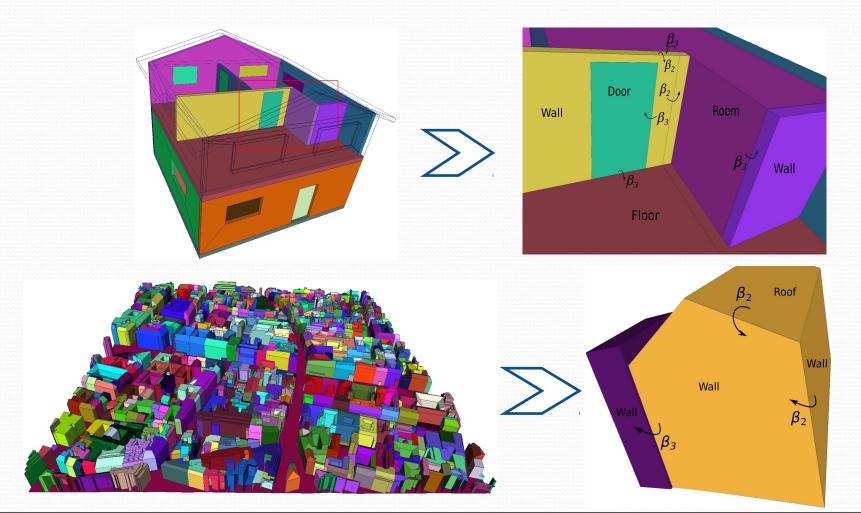
- Edge-centered data structure to represent dD orientable objects subdivided in cells.
- Representation of incidence and adjacency relationships. The i-cells are linked by β_i thanks to the i-sew operations
- Attributes are associated to the cells for information storage (geometry, semantic, etc).

B3



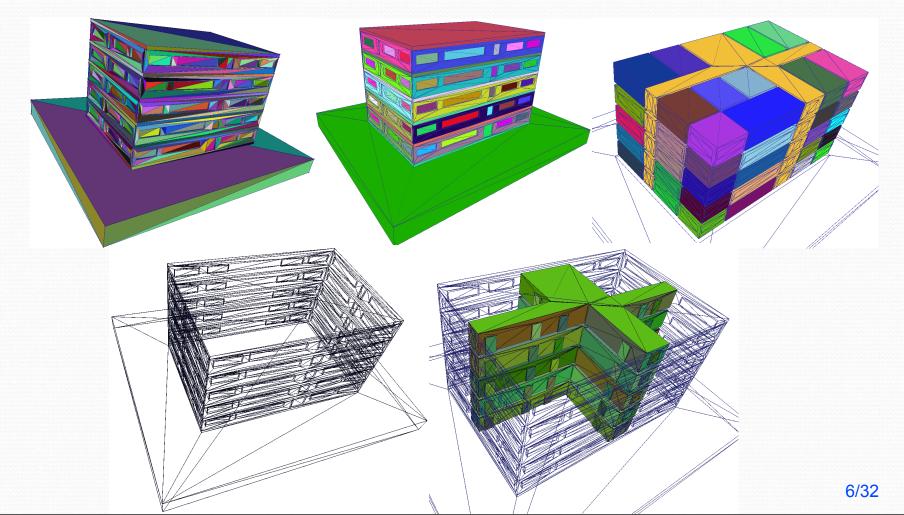
Topological Reconstruction

Proper Formalism for BIM and GIS



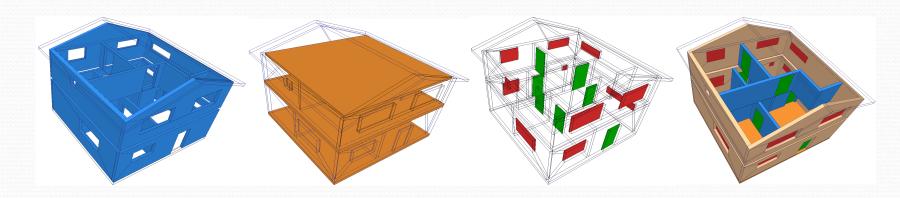
Topological Reconstruction

Creation of the β_2 and β_3 Links

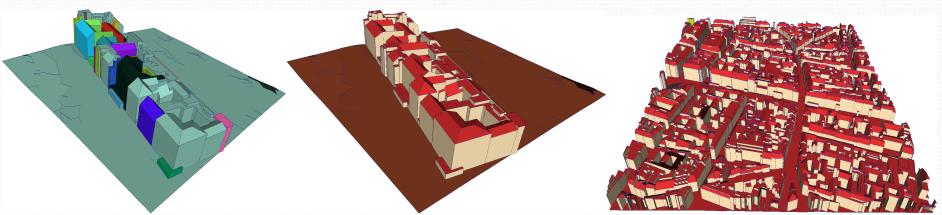


Automatic Semantic Labelling

On BIM



On GIS



The SIMs3D Project

Conceptual framework for indoor navigation

The approach fits well to the framework proposed in Zlatanova et al. (2013)

3-Cells

- Space
- Sub-spaces
- Partitions

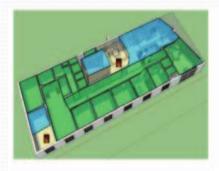
- Activities
- Resources
- Modifiers
- States
- Other ...



And navigation graph can be directly derived from the topology!

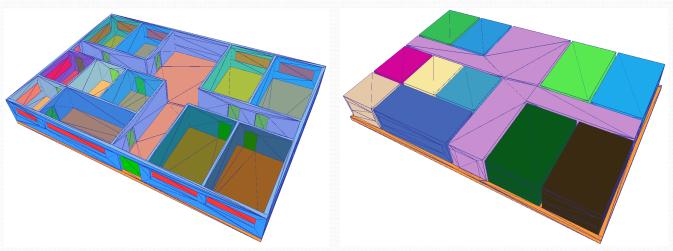
Conceptual framework for indoor navigation

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If the initial partition is proper → attributes can be used to label spaces as safe, navigable, etc or not.





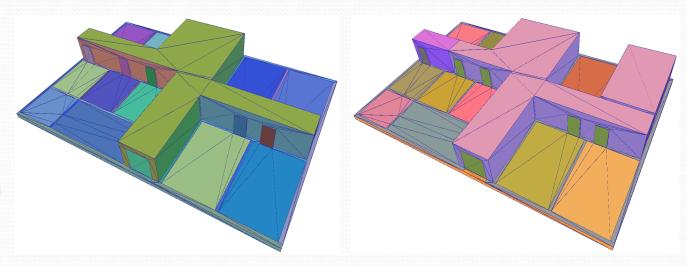
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Resource-Related Partition

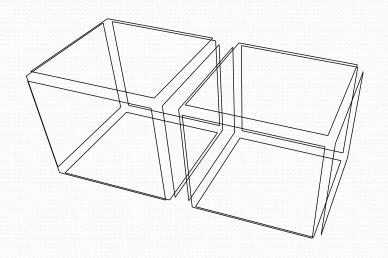
If the initial partition is not proper → change the subdivision by splitting / merging cells to define adequate spaces.



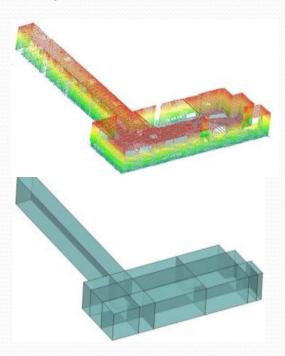
What if we want to work on point cloud?

3-maps can also fit to the method proposed by Khoshelham et al. (2014)

Define a 3-cell as the unit cube: starting shape



Proposed Grammar Rules can be applied to the 3-cells



Thanks!