SIMs3D

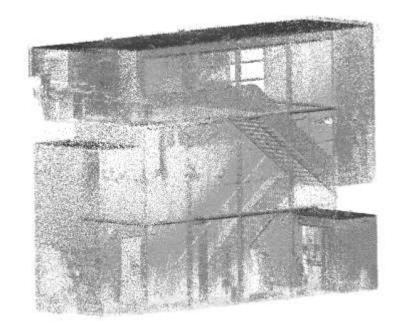
Smart 3D indoor models to support crisis management in large public buildings

Automatic space subdivision for multi-story pathfinding on a 3D point cloud using an octree

F.W. Fichtner, 2016-03-15
MSc Thesis Geomatics







- Acquiring point clouds of indoor spaces became increasingly easy & cheap
 - Unstructured
 - Pathfinding (*Indoor Navigation*) requires additional information





Problem statement

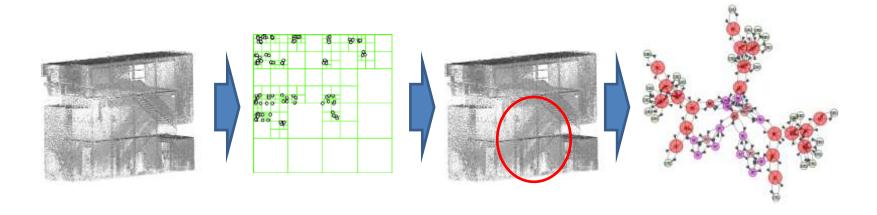
There is no way to automatically derive a subdivided model suitable for pathfinding, while at the same time keep the multi-floor connectivity via stairs.





Research question

To what extent can an **octree data structure** be used to **subdivide 3D space** and to create a **model for multi-story pathfinding**?





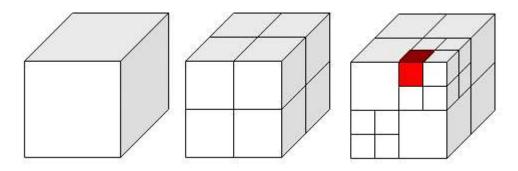


ZEB1 point cloud *Fire Brigade in Berkel* en Rodenrijs

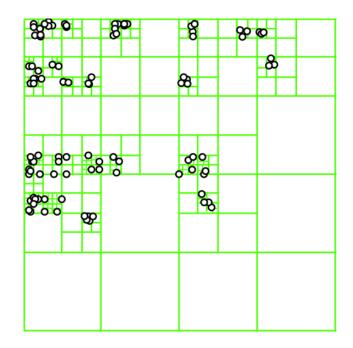




Octree data structure



http://2.bp.blogspot.com/_kvCpVC7wn5s/TOr_DsGqO0I/AAAAAAAAAA4/zYF4UssOk0o/s1600/octree.png





Subdivision & semantic enrichment

walkable space

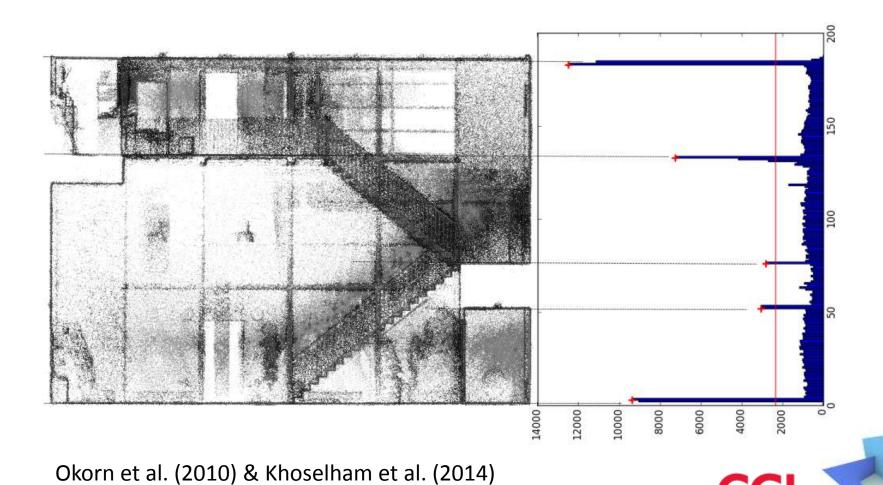
- Floor*
- Stairs*

Empty space

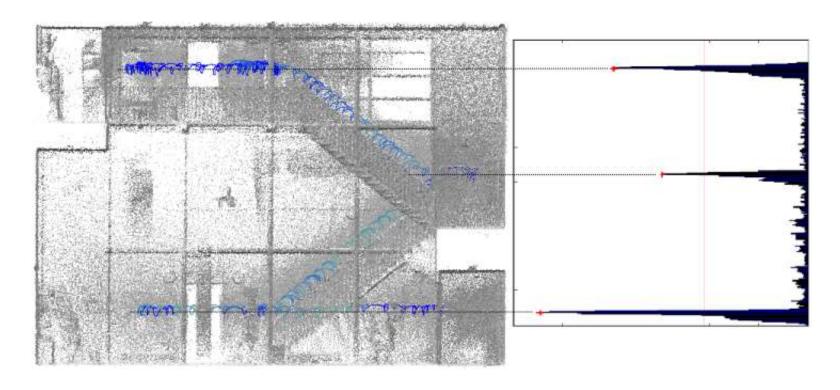
- Walls *
- Obstacles (furniture)*



Subdivision & semantic enrichment

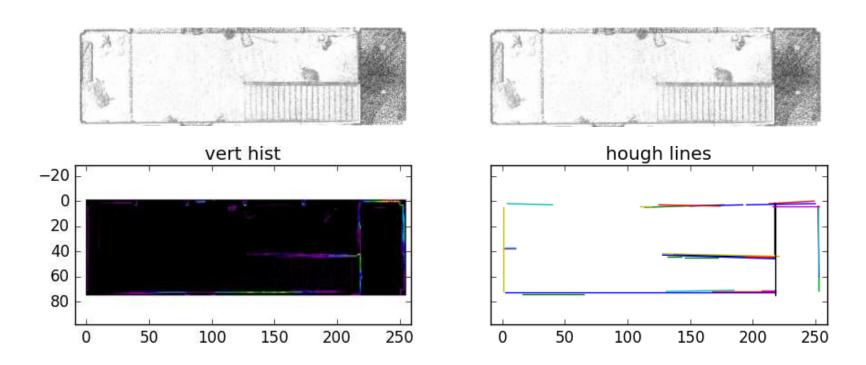


Subdivision & semantic enrichment



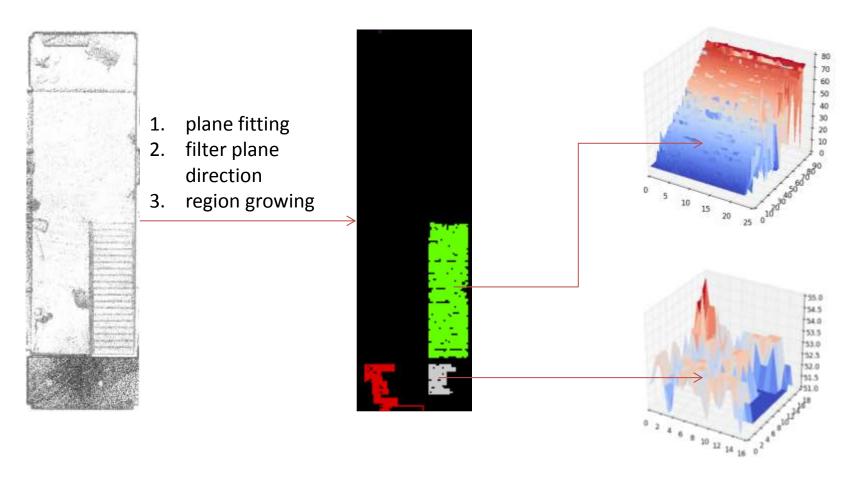


Wall detection



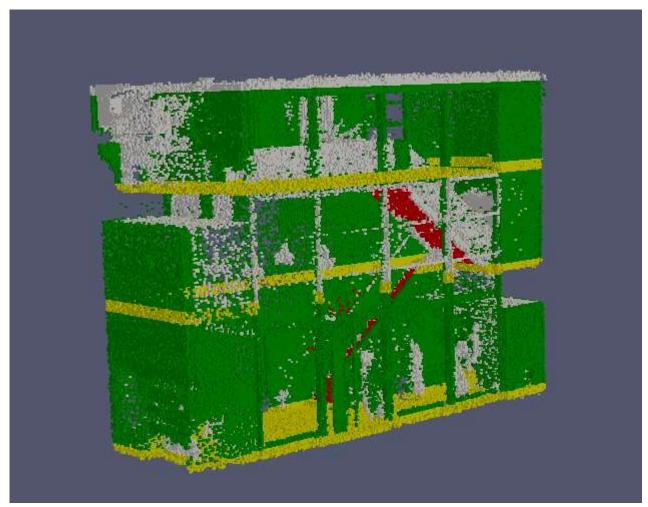


2D histograms & slope to find stairs

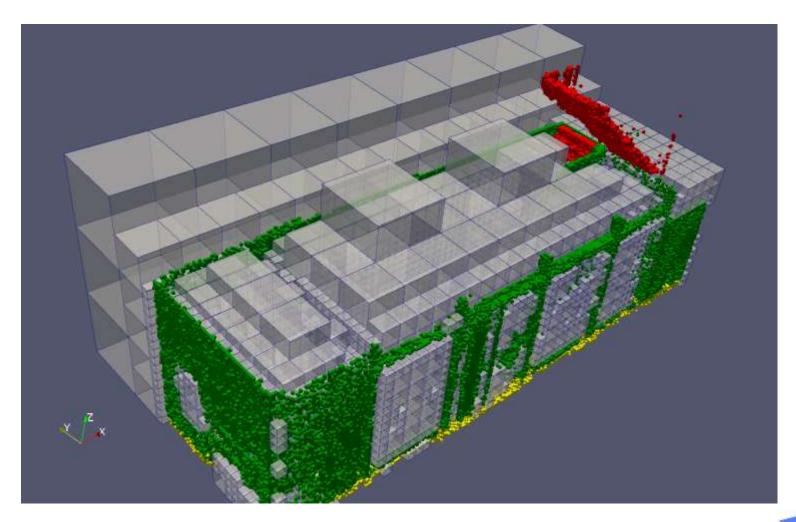


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First results



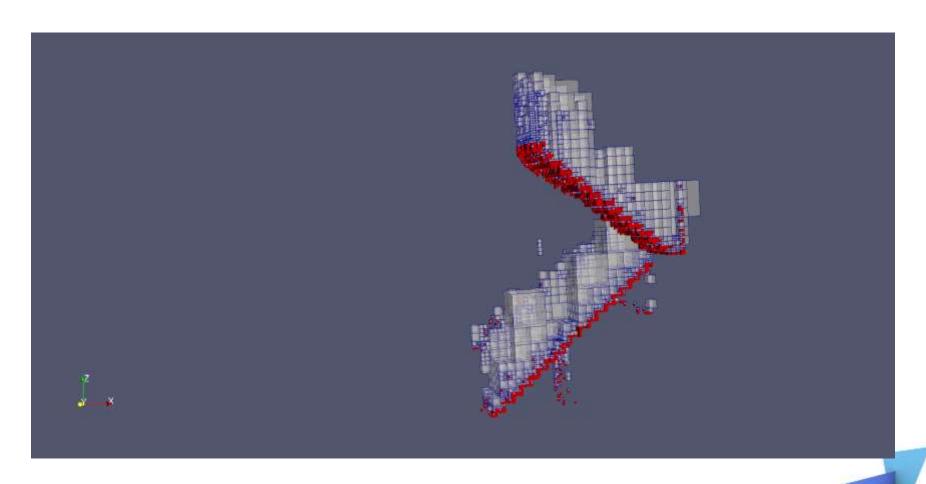
First results



Next: pathfinding

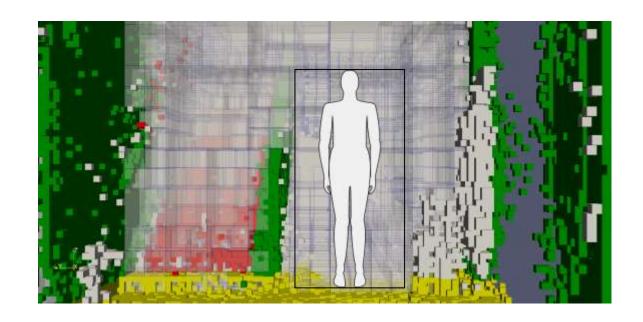


Next: pathfinding



Next: pathfinding

complete subdivision



Derive possible path for humans



References

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Questions?



