

[RightHand Labs](#)[ReFlex Documentation](#)[Contact](#)

Mounting Plates

[Introducing the ReFlex Hand](#) » [Reflex Documentation](#) » Mounting Plates

The ReFlex back shell is secured using M6 countersunk bolts - x3.
The three holes are evenly spaced on diameter 65mm.

A number of interface plates are provided below:

Baxter - [reflex_baxter_interfaceplate.stl](#) (tested)

UR5 - [reflex_ur5_interfaceplate.stl](#) (tested)

Please send us a note if you have another plate developed and we will add it to the list.

Mounting Steps:

- 1) Remove the back shell from ReFlex by opening the screw on the palm of the hand.
- 2) Attach the interface plate to the mounting plate on the robot.
- 3) Attach the back shell to the interface plate using three M6 screws.
- 4) Slide the hand into the back shall and secure the screw on the palm.

page revision: 13, last edited: 29 Dec 2014, 17:01 (534 days ago)

[Stop watching site docs.righthandrobotics.com](#) [?]

[Edit](#) [Rate \(0\)](#) [Tags](#) [History](#) [Files](#) [Print](#) [Site tools](#) [+ Options](#)

Powered by [Wikidot.com](#)

[Help](#) | [Terms of Service](#) | [Privacy](#) | [Report a bug](#) | [Flag as objectionable](#)

RightHand Robotics Inc (c) 2014