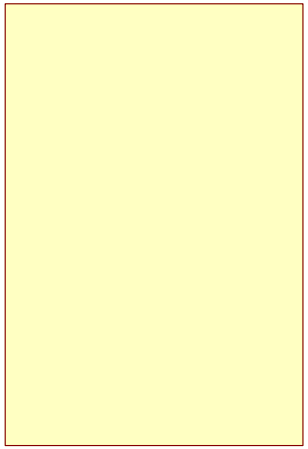
Power

File: power.kicad_sch

User Input

File: user_input.kicad_sch

MCU



File: microcontroller.kicad_sch

Motor Driver

File: motor_driver.kicad_sch

Indicators

File: indicators.kicad_sch

Mounting points

4 x M3 for threaded inserts
1 x M2 for board support

M3 holes	M2 holes
H1 MountingHole	H5 MountingHole
H2 MountingHole	H6 MountingHole
H3 MountingHole	
H4 MountingHole	

Fiducials

- FID1 Fiducial
- FID2 Fiducial
- FID3 Fiducial

SJFOM

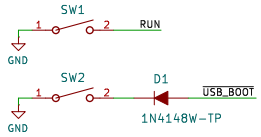
Sheet: /
File: StepUp.kicad_sch

Title: System diagram

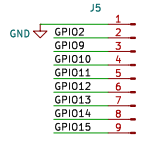
Size: A4	Date: 2024-04-28	**Rev: v0.2**
KiCad E.D.A. 8.0.6		Id: 1/6

MCU reset/prog buttons

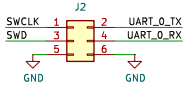
Run – resets MCU
USB_BOOT – hold this and toggle Run to enumerate as USB device for UF2 firmware upload
NOTE: Buttons are SMD and usually hidden from user



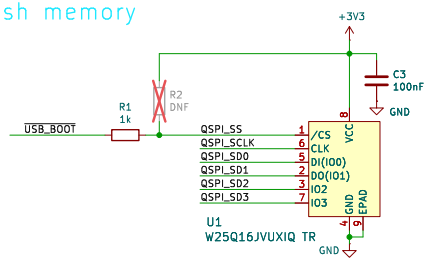
Spare I/O



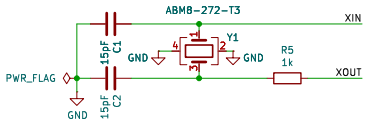
Debug header



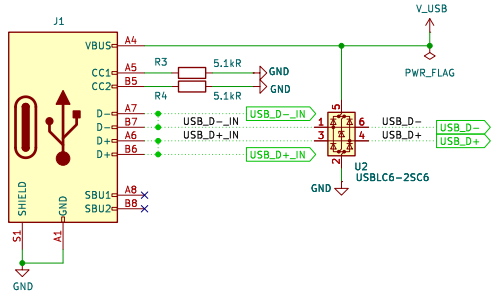
Flash memory

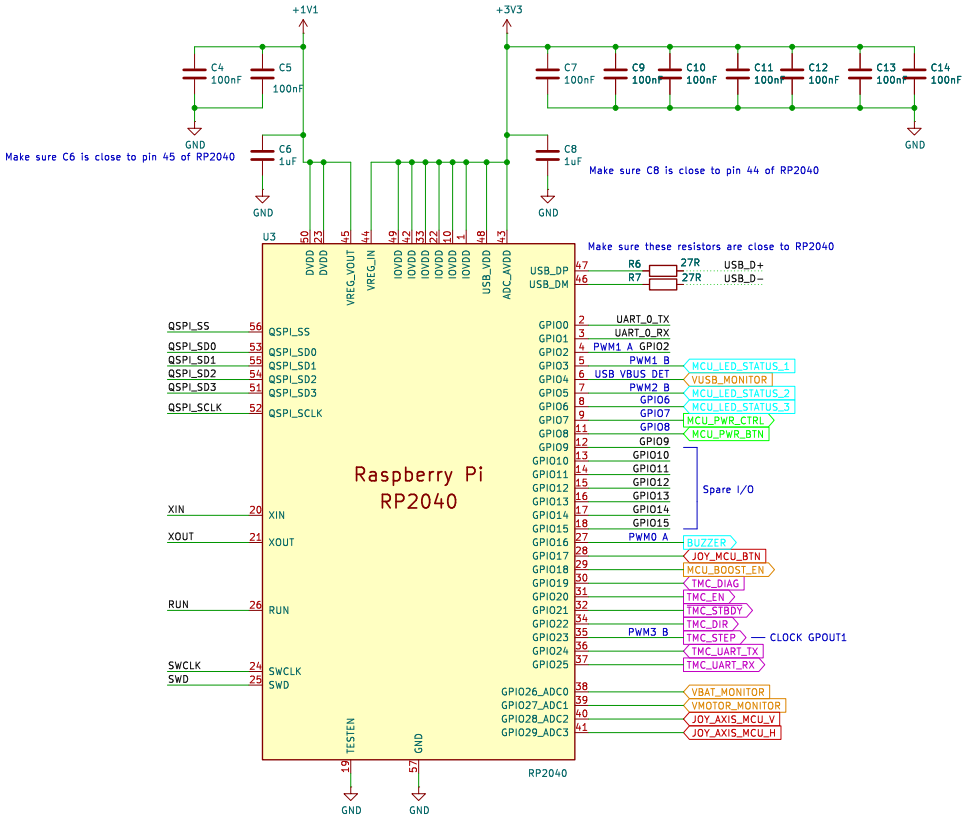


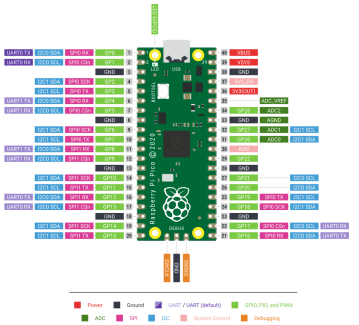
Crystal



USB input



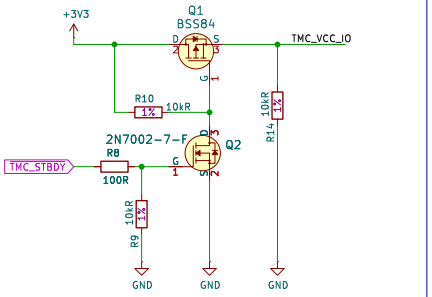




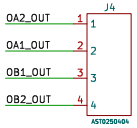
SJFOM		
Sheet: /MCU/		
File: microcontroller.kicad_sch		
Title: Microcontroller		
Size: A3	Date: 2024-04-28	**Rev: v0.2**
KiCad E.D.A. 8.0.6		Id: 2/6

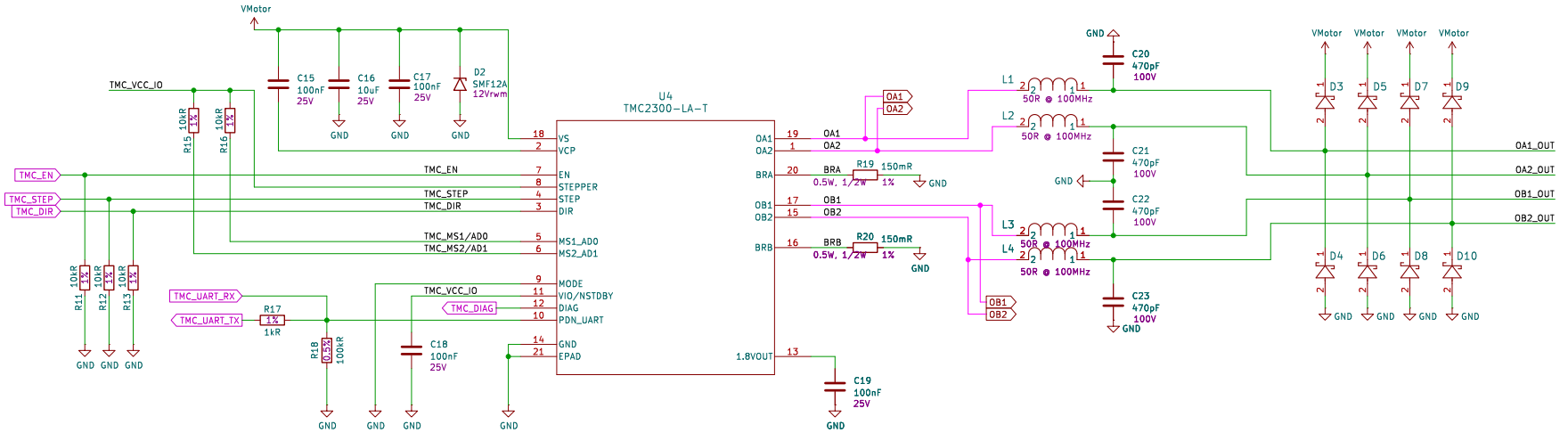
TMC power control

TMC_STDY controls VCC_IO power state



Motor connector

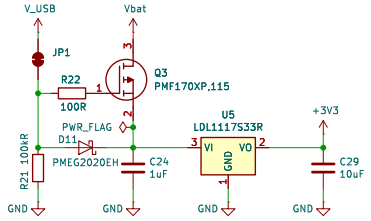




SJFOM		
Sheet: /Motor Driver/		
File: motor_driver.kicad_sch		
Title: Motor Driver		
Size: A3	Date: 2024-04-28	**Rev: v0.2**
KiCad E.D.A. 8.0.6		Id: 3/6

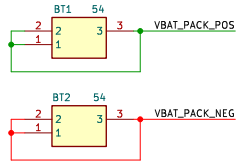
3v3 LDO

Default: 3v3 powered by Vbat & Vusb when USB inserted
Alt: Cut jumper to only power via Vbat



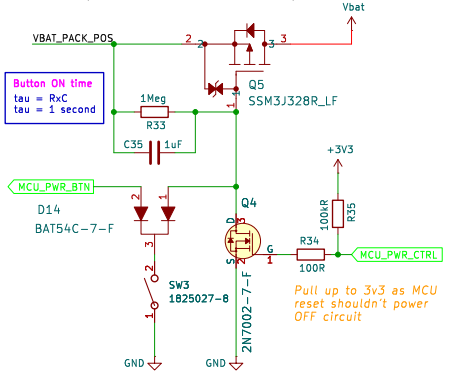
Battery connector

2 battery clip connectors

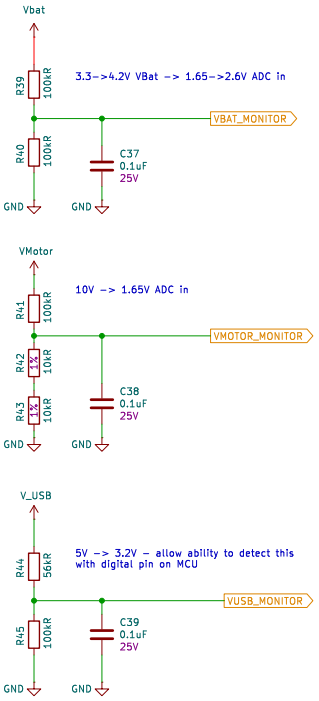


Power switch

Hold button to power circuit on, then NMOS keeps circuit ON

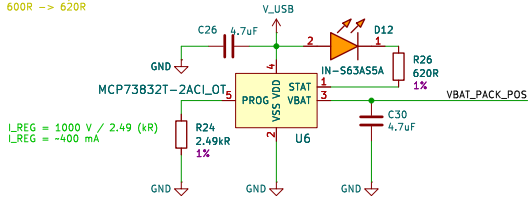


Voltage monitoring



Battery charge IC

LED Vf = 2.0V
5mA = 5-2/R -> R = 600
600R -> 620R



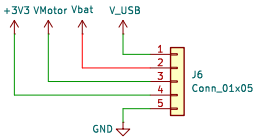
$$I_{REG} = \frac{1000V}{R_{PROG}}$$

Where:

R_{PROG}	=	kOhms
I_{REG}	=	milliampere

Voltage test pads

2 battery clip connectors



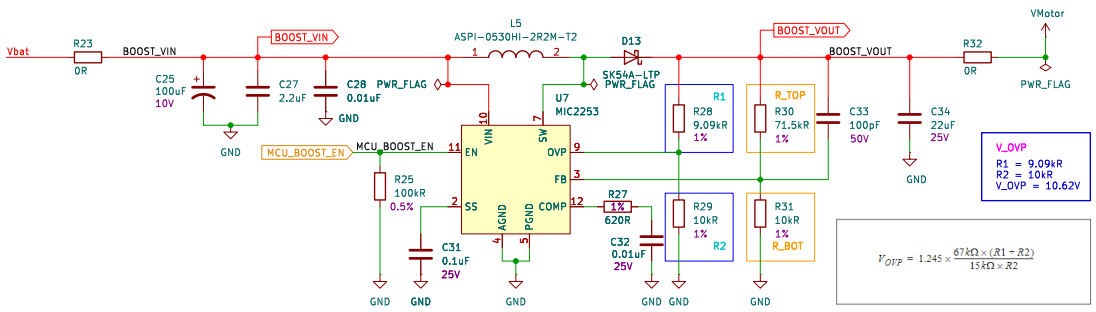
Step up boost converter

Boost from VBat -> 10V
OR jumper resistors can be removed for testing power consumption

V_OUT
R_TOP = 71.5kR
R_BOT = 10kR
V_OUT = 10.15V

$$V_{OUT} = V_{REF} \times \left(\frac{R_{TOP}}{R_{BOT}} + 1\right)$$

Where:
V_{REF} = 1.245V

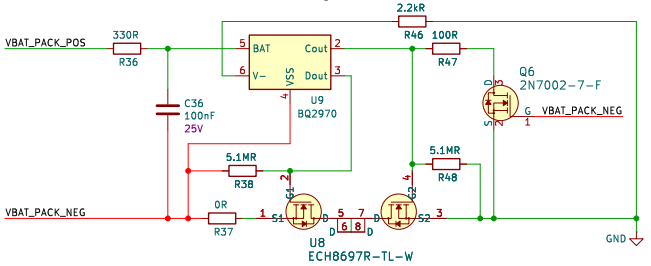


V_OVP
R1 = 9.09kR
R2 = 10kR
V_OVP = 10.62V

$$V_{OVP} = 1.245 \times \frac{67k\Omega \times (R1 + R2)}{15k\Omega \times R2}$$

Battery Protection circuit

Default: ~4.3Amp MAX discharge current
Alternative: Increase OR resistor to lower MAX discharge current



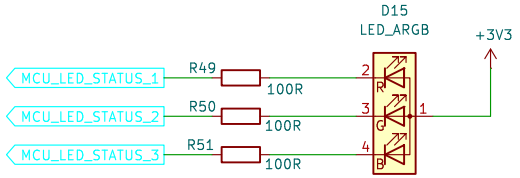
SJFOM

Sheet: /Power/		
File: power.kicad_sch		
Title: Power		
Size: A3	Date: 2024-04-28	**Rev: v0.2**
KiCad E.D.A. 8.0.6		Id: 4/6

Status LED's

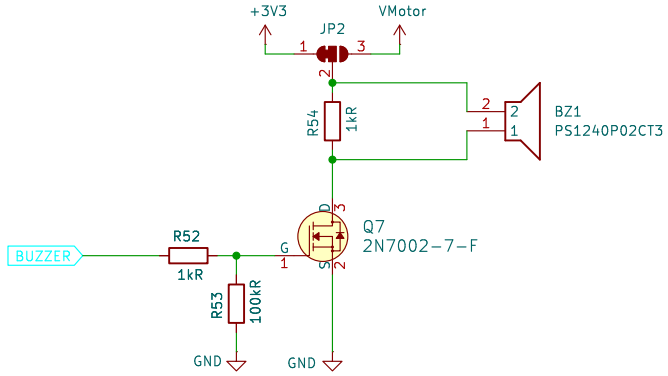
Status LEDs, surface-mount, side-entry, clear

LED power calculations (TBD)
Vf_red = ...V
Vf_green = ...V
Vf_blue = ...V



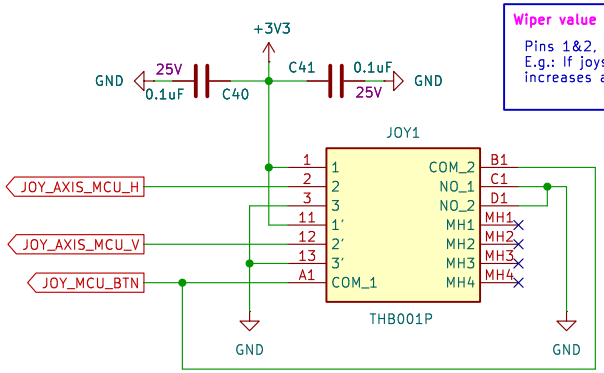
Buzzer

To indicate device states, f = 4kHz
User selectable voltage, 3v3 or 10V for motor (default = 3v3)



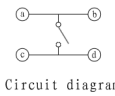
SJFOM	
Sheet: /Indicators/	
File: indicators.kicad_sch	
Title: User Input	
Size: A4	Date: 2024-04-28
KiCad E.D.A. 8.0.6	Id: 5/6
	Rev: v0.2

Joystick

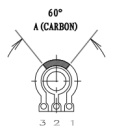


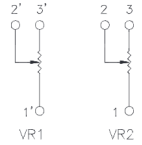
Wiper value

Pins 1&2, resistance goes down as wiper moved in that direction
E.g.: If joystick has pin 1 = 3v3 and pin 3 = GND, pin 2 voltage increases as josytick moved to pin 1, decreases as moved to pin 3



Circuit diagram





SJFOM		
Sheet: /User Input/		
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Title: User Input		
Size: A4	Date: 2024-04-28	**Rev: v0.2**
KiCad E.D.A. 8.0.6		Id: 6/6