Facial Expression Recognition Applications Performance Evaluation

Team 2
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Intro

- Motivation
- Data Collection
- General Approach
- Preprocessing
- Training 3 models
- Ensemble Experience and Result
- Conclusion/ future work

Motivation

- Street crime is always a major concern in big cities
- Criminal behaviour has been connected to a lack of emotion awareness, notably for fear, rage, and other emotions
- Proposed Solution: using the deep Convolutional Neural Network (CNN) technique to detect facial expressions
 3 models: ResNet50V2, Mini-VGG, InceptionV3

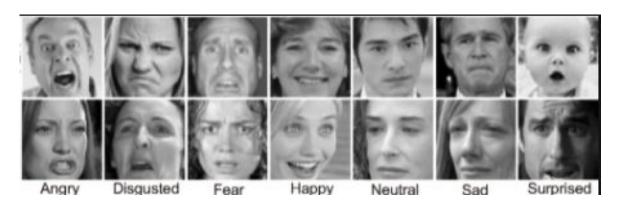




Data Collection

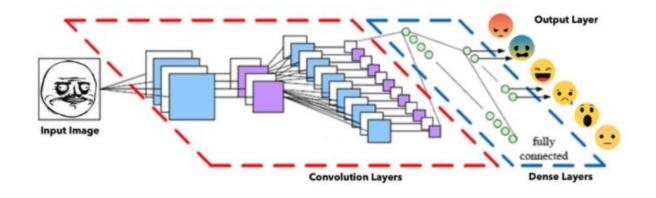
Facial Expression Recognition 2013 Dataset(FER2013)

- Contains 30,000 facial RGB images of different expressions
- The data consists of 48x48 pixel grayscale images of faces
- Seven categories (0=Angry, 1=Disgust, 2=Fear, 3=Happy, 4=Sad, 5=Surprise, 6=Neutral)



General Approach

- Use FER2013 dataset. The training set consists of 28,709 examples and the public test set consists of 3,589 examples.
- Train 3 models: ResNet50V2, Mini-VGG, InceptionV3
- Evaluate the performance of each model



Preprocessing

- Normalization
 - Rescal by 1 / 225.0
- Channel Repetition
 - Pre-trained models support only 3-channel images
 - Repeat the single channel 3 times (gray scale)
- Image Augmentation
 - Augmentation during training (rotation, h/v flip, etc.)

Models

ResNet50V2

Mini-VGG

Ensemble

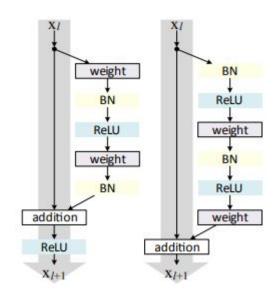
ResNet50V2

Residual Block V1

- Adds the second non-linearity after the addition.
- Performs the convolution before BN and ReLU.

Residual Block V2

- Remove the linearity after addition
- Applies BM and ReLU to the input before the convolution operation



ResNet50V2

- Transfer Learning Using ResNet50V2
 - Freeze ResNet
 - Adding additional FC layer

```
model = tf.keras.Sequential([
    Input(shape=(IMAGE_SIZE[0], IMAGE_SIZE[1], 3)),
    data_augmentation,
    res net v2,
    layers. Global Average Pooling 2D (),
    tf.keras.layers.BatchNormalization(),
    layers. Dropout (0.5),
    layers, Dense (1024, activation="elu", kernel regularizer = tf. keras. regularizers. 12(0.01)),
    tf.keras.layers.BatchNormalization(),
    layers. Dropout (0.4),
    layers. Dense (512, activation="elu"),
    tf.keras.layers.BatchNormalization(),
    layers. Dropout (0.3),
    layers. Dense (128, activation="elu"),
    layers. Dropout (0.2),
    layers. Dense (7, activation="softmax")
```

ResNet50V2

- Freeze and train 50 epoches
- Unfreeze the ResNet 50 epoches
 - Trying a smaller learning rate
- Assign Class Weights -20 epoches
 - Trying even smaller learning rate

```
model.layers[1].trainable = True
```

```
{0: 3196, 1: 349, 2: 3278, 3: 5772, 4: 3972, 5: 3864, 6: 2537}
```

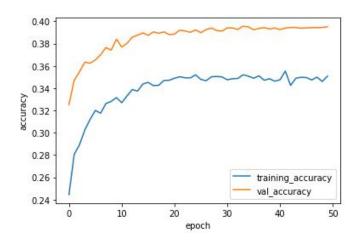
```
{0: 1.0266404434114071,
1: 9.401555464592715,
2: 1.0009587727708533,
3: 0.5684585684585685,
4: 0.826068191627104,
5: 0.8491570541259982,
6: 1.2933160650937552}
```

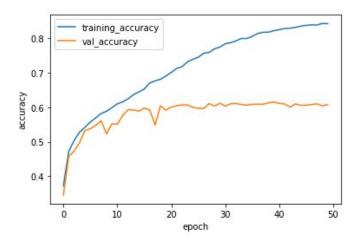
Class Weights

ResNet50V2 Training

Left: Freeze ResNet; Ir = 0.001

Right: Unfreeze ResNet; Ir = 0.0005



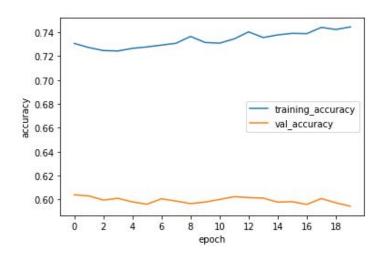


Class Weighting

Assign weights to each class

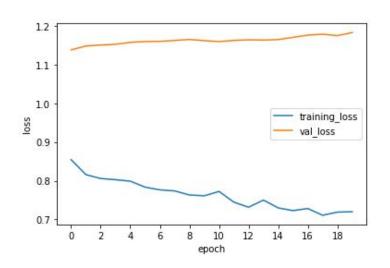
0 {0: 3196, 1: 349, 2: 3278, 3:
5772, 4: 3972, 5: 3864, 6:
2537}

o Ir=0.00005

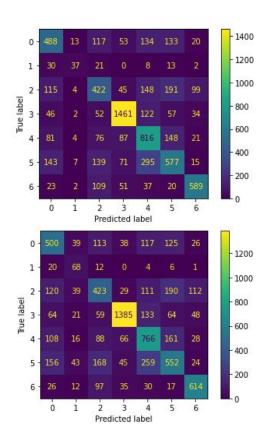


{0: 1.0266404434114071, 1: 9.401555464592715, 2: 1.0009587727708533, 3: 0.5684585684585685, 4: 0.826068191627104, 5: 0.8491570541259982, 6: 1.2933160650937552}

Class Weights



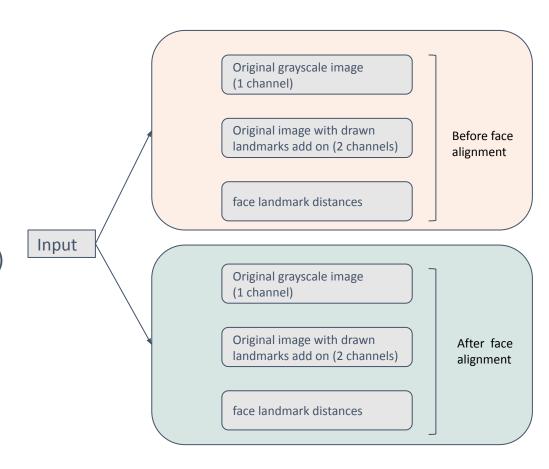
ResNet50V2 Result



	precision	recall	f1-score	support	
0	0.5270	0.5094	0.5180	958	
1	0.5362	0.3333	0.4111	111	
2	0.4509	0.4121	0.4306	1024	
3	0.8264	0.8236	0.8250	1774	
4	0.5231	0.6618	0.5843	1233	
5	0.5066	0.4627	0.4837	1247	
6	0.7551	0.7088	0.7312	831	
accuracy			0.6116	7178	
macro avg	0.5893	0.5588	0.5691	7178	
weighted avg	0.6125	0.6116	0.6099	7178	
I	precision	recall	f1-score	support	
0	0.5030	0.5219	0.5123	958	
1	0.2857	0.6126	0.3897	111	
2	0.4406	0.4131	0.4264	1024	
3	0.8667	0.7807	0.8215	1774	
4	0.5394	0.6212	0.5775	1233	
5	0.4951	0.4427	0.4674	1247	
6	0.7198	0.7389	0.7292	831	
accuracy			0.6002	7178	
macro avg	0.5501	0.5902	0.5606	7178	
weighted avg	0.6106	0.6002	0.6031	7178	

Feature Extraction And Transformation Methods We Tried :

- 1. Extract face landmarks using dlib (48 x 48 features \rightarrow 72 features)
- 2. Extract landmark distances from face landmarks (72 features \rightarrow 8)
- 3. Add an empty image with drawn face landmarks
- 4. Face alignment

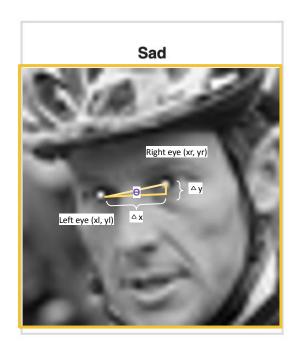


Extract face landmarks using dlib (48 x 48 features \rightarrow 72 features)



```
('chin', [(10, 25), (10, 29), (12, 33), (13, 36), (15, 40), (17, 43), (19, 46), (22, 48), (26, 48), (30, 48), (34, 45), (38, 42), (40, 38), (42, 33), (42, 28), (41, 23), (40, 18)])
('left_eyebrow', [(9, 21), (10, 19), (11, 19), (13, 19), (15, 20)])
('right_eyebrow', [(20, 18), (23, 17), (25, 16), (28, 15), (31, 16)])
('nose_bridge', [(18, 23), (18, 26), (18, 29), (18, 32)])
('nose_tip', [(17, 34), (19, 35), (20, 35), (22, 34), (24, 33)])
('left_eye', [(12, 24), (13, 22), (15, 22), (17, 24), (15, 24), (13, 25)])
('right_eye', [(24, 22), (25, 20), (27, 20), (30, 20), (28, 22), (26, 22)])
('top_lip', [(18, 40), (19, 39), (20, 38), (22, 39), (24, 38), (27, 38), (30, 38), (29, 38), (24, 39), (22, 40), (20, 40), (19, 40)])
('bottom_lip', [(30, 38), (28, 41), (25, 43), (23, 43), (21, 43), (20, 42), (18, 40), (19, 40), (21, 41), (22, 41), (24, 41), (29, 38)])
```

Face alignment



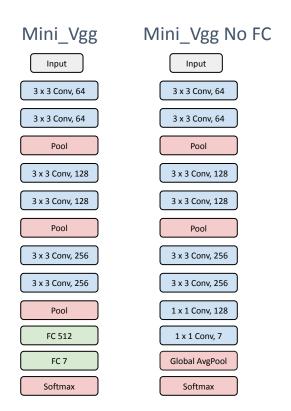
Face Alignment

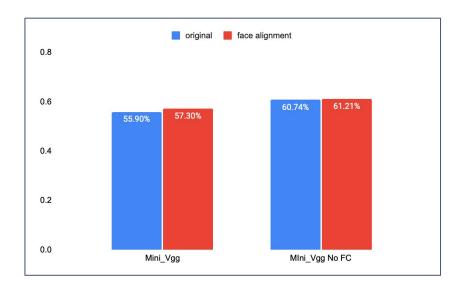
$$\Delta x = x_r - x_l$$

$$\Delta y = y_r - y_l$$

$$\theta = \arctan \frac{\Delta y}{\Delta x}$$







Model variants:

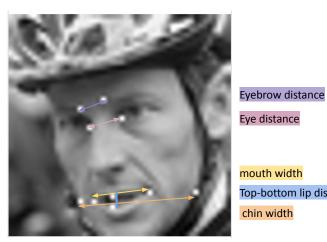
- activation function: Relu
- All convolution layer using strip = 1, padding = 1
- Loss Function: CrossEntropyLoss()
- Optimizer: Adam()
- Batchsize = 100

Extract landmark distances from face landmarks (72 features \rightarrow 8)

Performance is not good

```
[0.4850712500726659,
12.165525060596439.
2.0,
0.0,
-0.24497866312686414.
1.3518824678560455]
```

```
distance feature
O. relative distance between chin width and mouth width
  - chin width : abs(chin[4] - chin[-5])
1. mouth width: ['top_lip'][0], ['bottom_lip'][0]
2. top-bottom lip distance: ['top_lip'][3], ['bottom_lip'][9]
B,4 angle btw mouth corner to top-bottom lip distance mean
5. left eye size: get max min y
6. right eye size: get max min y
7. relative distance between eve and evebrow
    - eye distance: ['left_eye'][3], ['right_eye'][0]
    - evebrow distnace ['left evebrow'][-1], ['right evebrow'][0]
```



mouth width

Top-bottom lip distance chin width

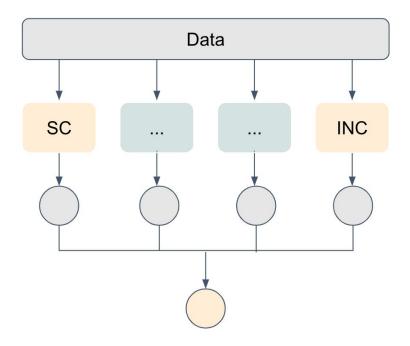
```
('chin', [(10, 25), (10, 29), (12, 33), (13, 36), (15, 40), (17, 43), (19, 46), (22, 48), (26, 48), (30, 48), (34, 45), (38, 42), (40, 38), (42, 33), (42, 28), (41, 23), (40, 18)])
('left_eyebrow', [(9, 21), (10, 19), (11, 19), (13, 19), (15, 20)])
('right_eyebrow', [(20, 18), (23, 17), (25, 16), (28, 15), (31, 16)])
('nose_bridge', [(18, 23), (18, 26), (18, 29), (18, 32)])
('nose_tip', [(17, 34), (19, 35), (20, 35), (22, 34), (24, 33)])
('left_eye', [(12, 24), (13, 22), (15, 22), (17, 24), (15, 24), (13, 25)])
('right eye', [(24, 22), (25, 20), (27, 20), (30, 20), (28, 22), (26, 22)])
('top_lip', [(18, 40), (19, 39), (20, 38), (22, 39), (24, 38), (27, 38), (30, 38), (29, 38), (24, 39), (22, 40), (20, 40), (19, 40)])
('bottom_lip', [(30, 38), (28, 41), (25, 43), (23, 43), (21, 43), (20, 42), (18, 40), (19, 40), (21, 41), (22, 41), (24, 41), (29, 38)])
```

Add an empty image with drawn face landmarks - performance is not good



Ensemble

Mixing models



Soft Vote

Combine the weak classifiers by taking the average of the predicted probability for each class from each classifier.

Vote on Prediction

Simple CNN

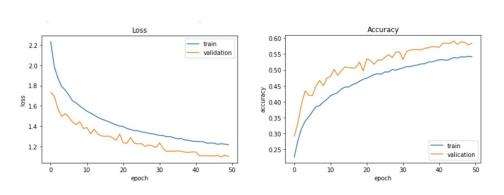
Ensemble

NN = 5 layers with 3 convolutional layers

Accuracy on Testset = 0.54

Total trainable params = 69,223





```
NUM CLASS = 7
lr = 0.0001
opt = Adam(learning rate=lr)
loss = 'categorical crossentropy'
metrics = ['accuracy']
n = 50
def fiveLayerCNN(input shape=(IMG H, IMG W, IMG C),
              num class=NUM CLASS):
  num classes = num class
  input shape = input shape
  model name = 'fiveLayerCNN'
  inputs = keras.Input(shape = input shape)
  x = Conv2D(32, 5, activation='elu')(inputs)
  x = BatchNormalization()(x)
  x = MaxPooling2D(3, strides=2)(x)
  x = Conv2D(32, 4, activation='elu')(x)
  x = BatchNormalization()(x)
  x = MaxPooling2D(3, strides=2)(x)
  x = Conv2D(64, 5, activation='elu')(x)
  x = BatchNormalization()(x)
  x = MaxPooling2D(3, strides=2)(x)
  x = Flatten()(x)
  x = Dense(1024, activation='elu')(x)
  x = Dropout(0.3)(x)
  outputs = Dense(num classes, activation='softmax')(
```

InceptionV3

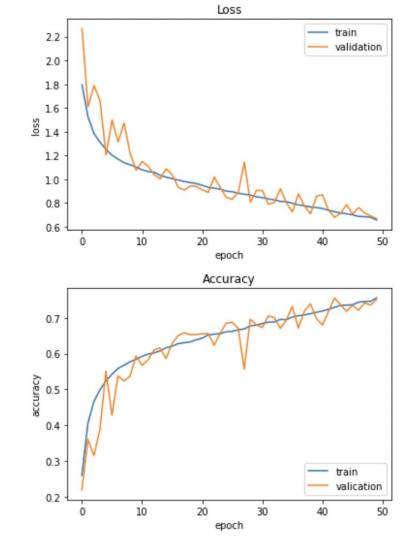
Ensemble

NN = pre-trained on 'imagenet'

Total trainable **params** = 21,786,797 (x315)

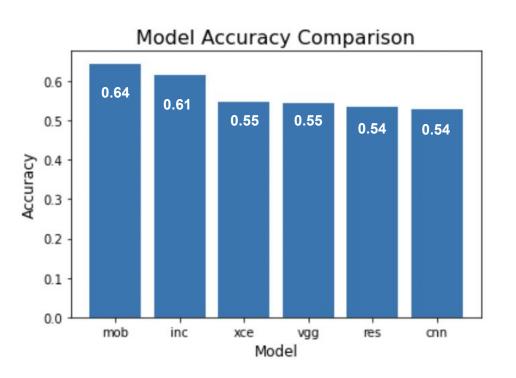
Accuracy on Testset = 0.61 (+0.9)

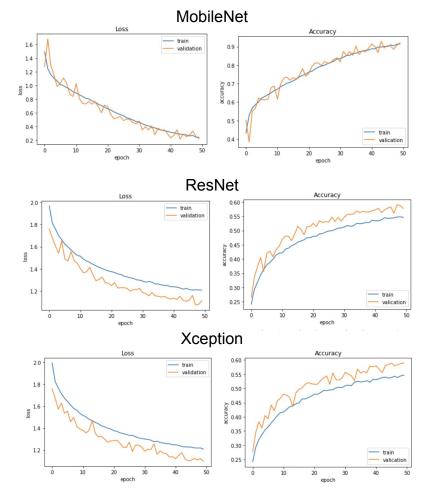
org_img (InputLayer)	[(None, 48, 48, 1)]	0
<pre>img_augment (Sequential)</pre>	(None, 224, 224, 3)	6
inception_v3 (Functional)	(None, 5, 5, 2048)	21802784
batch_normalization_1420 (B atchNormalization)	(None, 5, 5, 2048)	8192
<pre>max_pooling2d_163 (MaxPooli ng2D)</pre>	(None, 2, 2, 2048)	0
global_average_pooling2d_41 (GlobalAveragePooling2D)	(None, 2048)	0
dropout_35 (Dropout)	(None, 2048)	0
dense_46 (Dense)	(None, 7)	14343



Model Comparisons

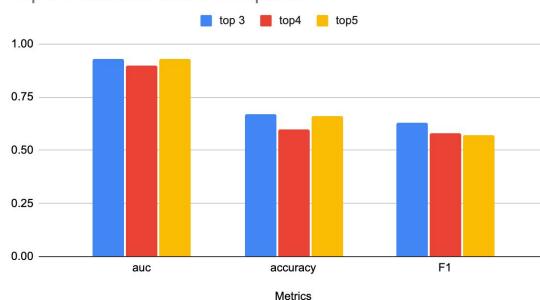
Ensemble





Top-N Ensembling Ensemble

Top-N Ensemble Model Comparison



```
res = load model(path + 'models/ResNet101V2.h5')
INP SIZE = (48, 48)
NUM CLASS = 7
lr = 0.0001
opt = Adam(learning rate=lr)
act = 'elu'
loss = 'categorical crossentropy'
metrics = ['accuracy']
def top3(input_shape=(INP_SIZE[0],INP_SIZE[1],1),
    n classes = n class
    model name = 'top3'
    inputs = keras.Input(shape=input shape)
    y1 = mob(inputs)
    y2 = inc(inputs)
    y3 = xce(inputs)
    outputs = layers.average([y1, y2, y3])
    model = keras.Model(inputs=inputs, outputs=out
    model.compile(loss=loss, optimizer = opt, metr
```

simpleCnn = load model(path +'models/simpleCnn.h5'

mob = load_model(path +'models/Pre_MobileNetV2.h5'
inc = load model(path +'models/features InceptionV

xce = load_model(path +'models/Pre_Xception.h5')
vgg = load model(path +'models/Pre VGG19.h5')

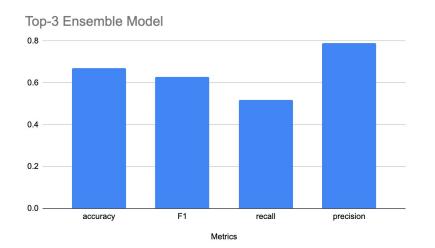
top models

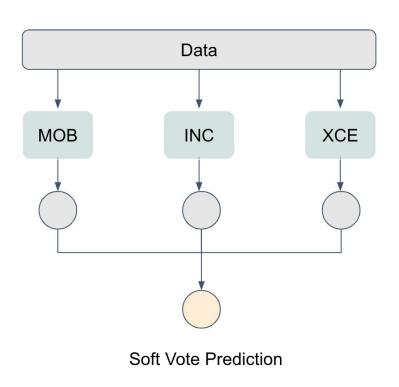
Top-3 Ensembling

Ensemble Result

NN = ensemble MobileNet, Inception, and Xception Total trainable **params** = 25,100,129

Accuracy on Testset = 0.67 (+0.13)





Conclusion

- Issue:Bad data quality
- Improvement:
 Fine tune, add more epochs, test real images
- Future work:Mobile App

Reference

- A. Ng, "With facial recognition, shoplifting may get you banned in places you've never been," CNET, 20-Mar-2019. [Online]. Available: https://www.cnet.com/tech/services-and-software/with-facial-recognition-shoplifting-may-get -you-banned-in-places-youve-never-been/. [Accessed: 04-Dec-2021]
- 2. H. K. Sharma *et al.*, "CNN based facial expression recognition system using deep learning approach," in *Cyber Intelligence and Information Retrieval*, Singapore: Springer Singapore, 2022, pp. 391–405.
- 3. A. Khanzada, C. Bai, and F. T. Celepcikay, "Facial expression recognition with deep learning," *arXiv* [cs.CV], 2020.
- 4. C. Pramerdorfer and M. Kampel, "Facial expression recognition using Convolutional Neural Networks: State of the art," *arXiv* [cs.CV], 2016.
- 5. J. Tang, X. Zhou, and J. Zheng, "Design of Intelligent classroom facial recognition based on Deep Learning," J. Phys. Conf. Ser., vol. 1168, p. 022043, 2019

Contribution

Team 2: Mavis Wang, Xiaocen Xie, Coco Yu, Yan Tang, Zuojun Zheng

Facial Expression Recognition Classification on FER2013

Tasks	Intro	Data Collection	Data Preparation	Modeling	ResNet50- V2	mini VGG	Ensembling	Conclusion
Presentation	Xiaocen Xie	Xiaocen Xie	Zuojun Zheng	>	Zuojun Zheng	Yan Tang	Mavis Wang	Coco Yu
Project	Xiaocen Xie	Zuojun Zheng	Mavis Wang, Zuojun Zheng	>	Zuojun Zheng	Yan Tang	Mavis Wang	Coco Yu
IEEE Paper	Xiaocen Xie	Yan Tang	Mavis Wang, Zuojun Zheng	All	Zuojun Zheng	Yan Tang	Mavis Wang	Coco Yu