



## **Robotics**

Documentation	SJSU-IB2023
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#### **Features**

USB-C MPU-6050 CAN, I2C, AD0 Jumpers

#### **Applications**

Breakout board used to send power and data to the MPU-6050 and CAN Bus for motors. The boards have an input and output USB-C connector so it can either connect to the Universal Controller Board or to another Arm Breakout board.

At most 4 MPU-6050s can be used at a time by utilizing 2 I2C channels.

#### **USB-C Stubby**

12-Pin USB-C comes in SMD form.

#### MPU-6050

The MPU-6050 receives 3.3V through VCC. The device communicates bi-directionally using I2C SCL, SDA pins. The MPU-6050 has two possible addresses 0x68, 0x69 which are selected by driving the AD0 pin either LOW or HIGH respectively. This can be selected with the AD0 jumper solder pad.

#### CAN

CAN transceiver sends signal through USB-C and is received in the arm breakout. This line is broken into high and low onto a solder pad that also contains a pad for the voltage line for arm motors. The board contains two sets of pads for ease of use for connecting to motors.

#### I2C

The two I2C lines are sent over USB-C and are received in the arm breakout. These lines are sent to a set of jumper solder pads one for SDA and the other for SCL. This allows for selection of which line will go to the MPU.

#### **Arm Breakout Board**

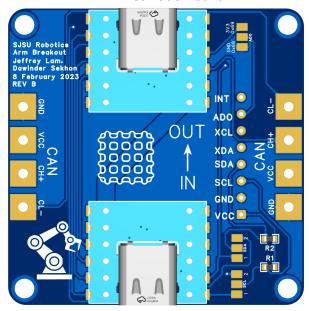


Figure 1: Top-view

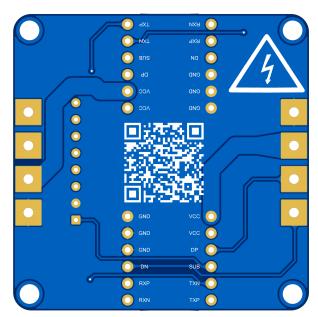


Figure 2: Bottom-view

### **AD0 Jumpers**

AD0 from the MPU is sent to a jumper solder pad. This allows the AD0 to be set high or low as the solder pads have a VCC pad and a ground pad.

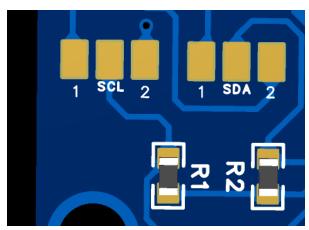


Figure 3: Solder Pads for 12C SCL and SDA Jumpers

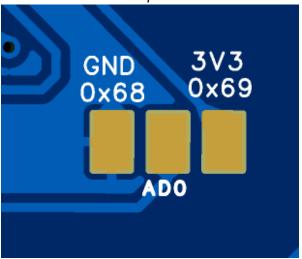


Figure 4: Solder Pads for AD0 jumper.

## **Block Diagram**

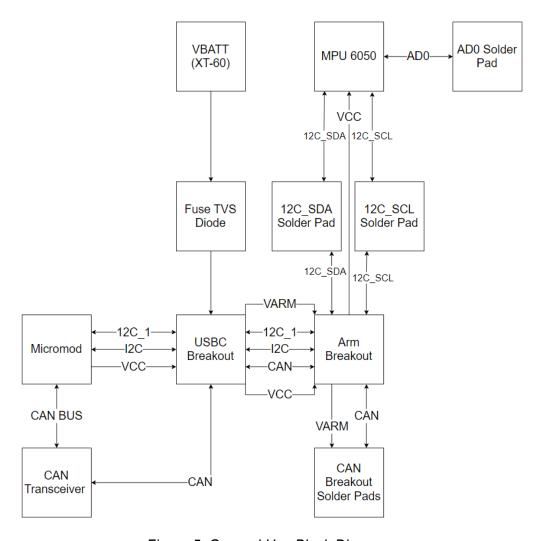


Figure 5: General Use Block Diagram

#### **USB C Breakout**

TXP pins are shorted together. RXP pins are shorted together.

TXN pins are shorted together. RXN pins are shorted together.

SUB pins are shorted together.

USB-C is broken out with the intention of using a USB 3.X C to C cable to make connections to different parts of the rover.

TX and RX pins are not connected for drive

VBUS	D+	D-	TXP	TXN
VBATT	CANH	CANL	I2C_SDA	I2C_SCL

GND	RXP	RXN	SUB DRIVE	SUB ARM
GND	I2C_SDA1	I2C_SCL1	HOME_X	3V3

Table 1: USB C Breakout Connections

\*\* USE ONLY 240W USB 3.X C TO C CABLES FOR CONNECTIONS OTHERWISE RISK OF BURNING CABLE \*\*

USB C 3.X Stubby Breakout Board seen below in figure 6.

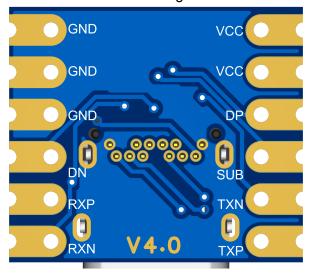


Figure 6: USB-C Stubby Breakout

<sup>\*\*</sup> USB C CABLE CROSSES TX > RX and RX > TX (KEEP IN MIND FOR UPSTREAM CONNECTIONS) \*\*

# Specifications

## **Designed Ratings**

Parameter	Rating
USB C Breakout Current	5A
Buck Converter Current	1A

Table 2: Designed Ratings