



Self-Interpretable Graph Learning with Sufficient and Necessary Explanations

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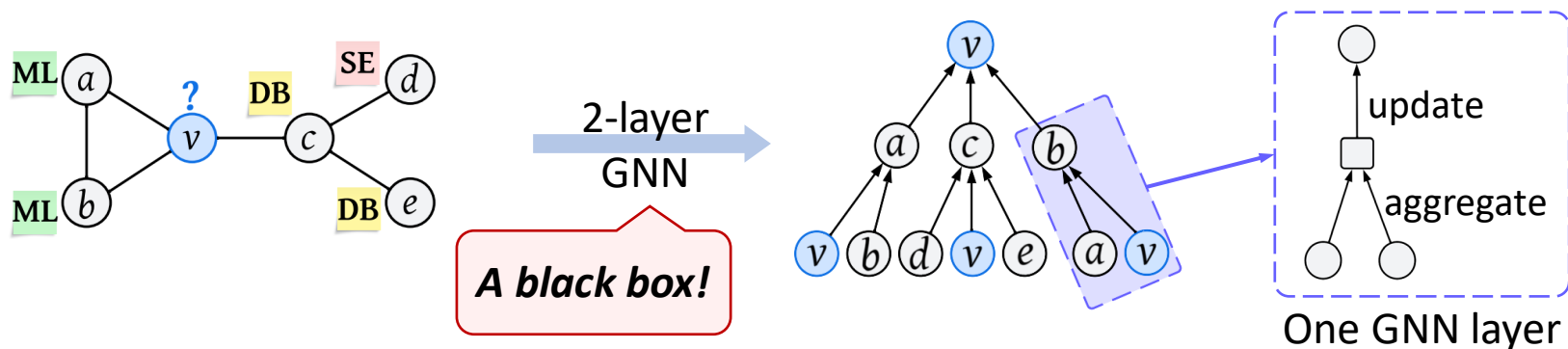
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- Graphs are everywhere
 - Social networks, co-purchase graphs, paper citation networks, ...
- Graph Neural Networks (GNNs) with message passing
 - Strong performance but **lack transparency**;
 - Learning representations by aggregating and updating information from neighbors;
 - An example (predicting the research area of an author node in coauthor network):



- Post-hoc methods
 - Explain a fix GNN by extracting salient substructures from the input graph;
 - Post-hoc explanations can be **biased and inconsistent**^[1].
 - Not directly produced by the GNN model!
- Self-interpretable methods^[2]
 - Simultaneously provide predictions and built-in explanations (**unbiased**);
 - Consist of:
 - An **explanation generator**: extracts explanation from input;
 - A **predictor**: learns the representation from the explanation to make final prediction.

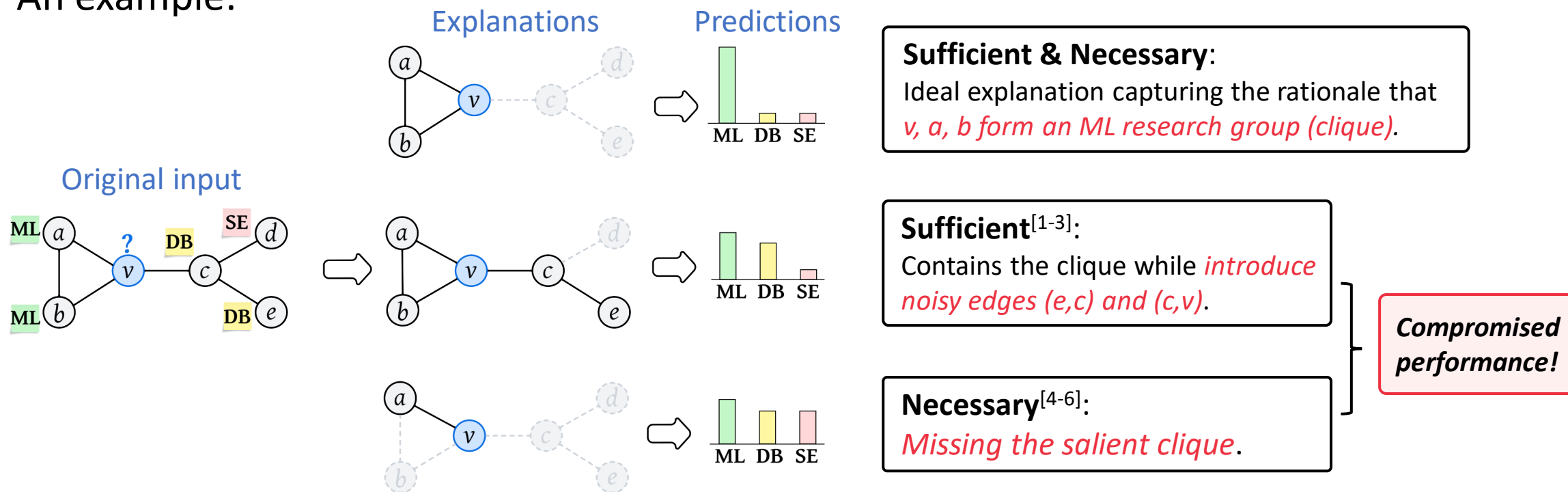
[1] Dai, Enyan, and Suhang Wang. "Towards self-explainable graph neural network." CIKM 2021.

[2] Miao, Siqi, Mia Liu, and Pan Li. "Interpretable and generalizable graph learning via stochastic attention mechanism." ICML 2022.

Issues of Self-Interpretable Methods



- The **quality** of explanations determines the model performance.
- An example:



[1] Yu, Junchi, et al. "Graph Information Bottleneck for Subgraph Recognition." ICLR 2020.

[2] Dai, Enyan, et al. "Towards self-explainable graph neural network." CIKM 2021.

[3] Miao, Siqi, et al. "Interpretable and generalizable graph learning via stochastic attention mechanism." ICML 2022.

[4] Wu, Yingxin, et al. "Discovering Invariant Rationales for Graph Neural Networks." ICLR 2021.

[5] Sui, Yongduo, et al. "Causal attention for interpretable and generalizable graph classification." KDD 2022.

[6] Fan, Shaohua, et al. "Debiasing graph neural networks via learning disentangled causal substructure." NIPS 2022.

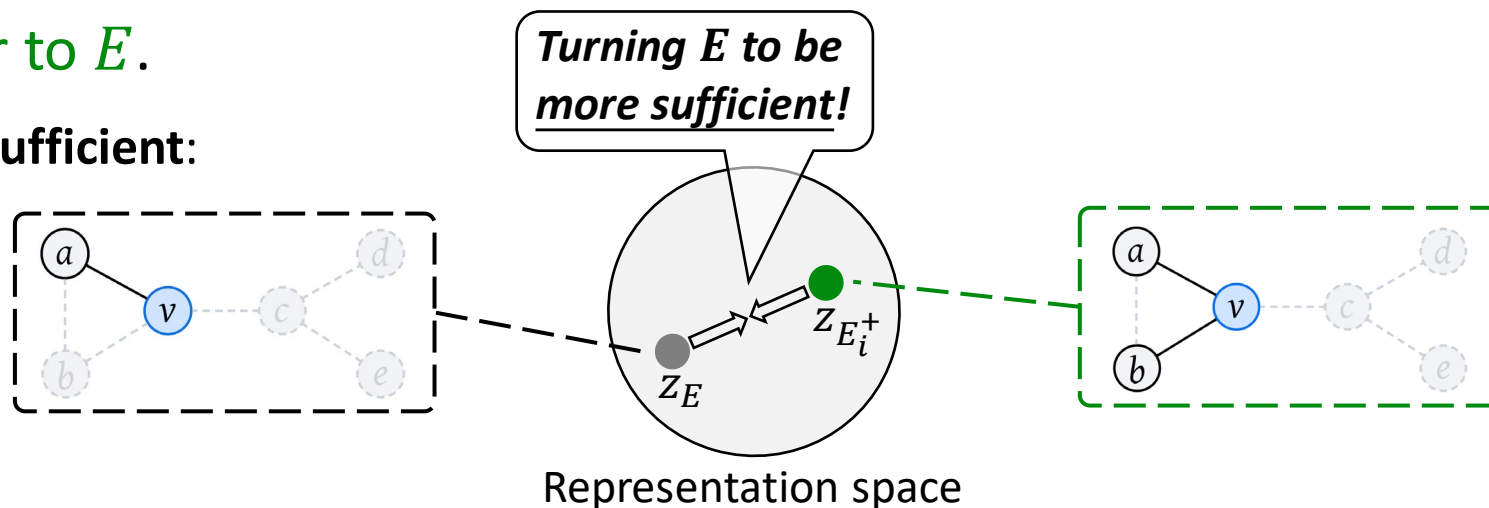


- A self-interpretable graph learning framework with SUFFICIENT aNd NECESSARY explanations (**SUNNY-GNN**).
- Our goal
 - Promote the quality of explanations toward both sufficiency and necessity directions, thus encourage the explanations to improve model performance.
- How to promote?
 - Perform **augmentations** on explanations and employ a **contrastive loss** to supervise the explanation generator for producing sufficient and necessary explanations.

Key Insight: Augmentations and Contrastive Loss



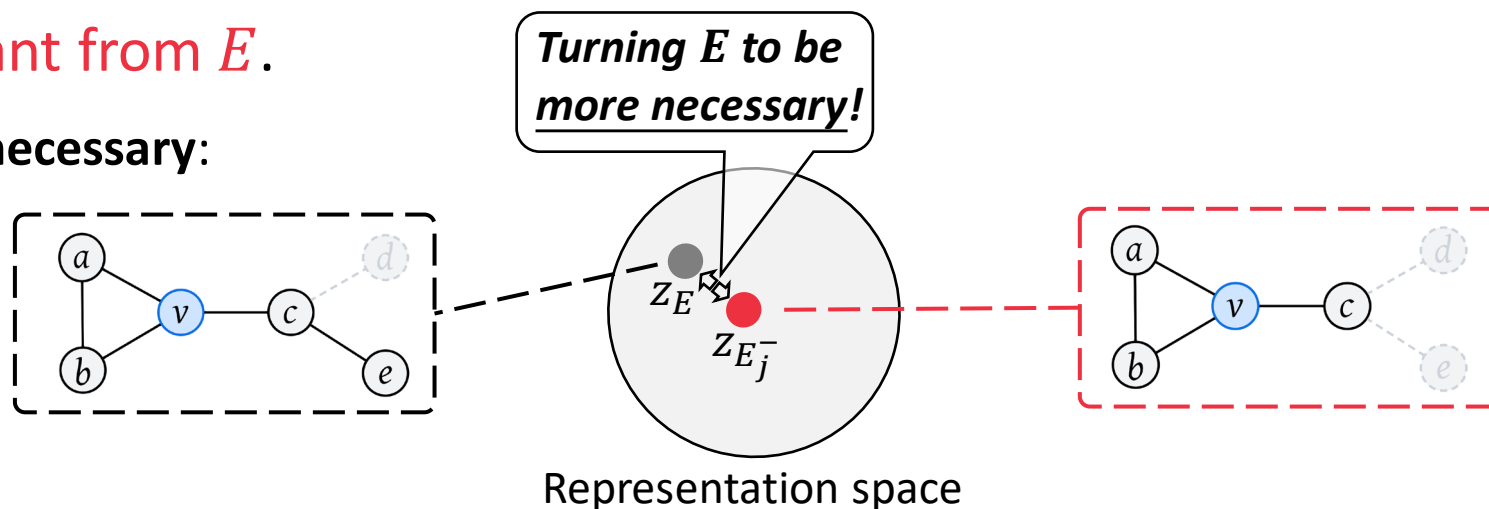
- Augmentations on an explanation E
 - Positive samples E^+ : add information (e.g., edges) to E ;
 - Negative samples E^- : remove information (e.g., edges) from E ;
 - Construct contrastive loss \mathcal{L}_{cts} with E^+ and E^- ;
- Minimizing \mathcal{L}_{cts} means
 - Pulling E^+ closer to E .
 - When E is **not sufficient**:



Key Insight: Augmentations and Contrastive Loss



- Augmentations on an explanation E
 - Positive samples E^+ : add edges to E ;
 - Negative samples E^- : delete edges in E ;
 - Construct Contrastive Loss \mathcal{L}_{cts} with E^+ and E^- ;
- Minimizing \mathcal{L}_{cts} means
 - Pushing E^- distant from E .
 - When E is **not necessary**:



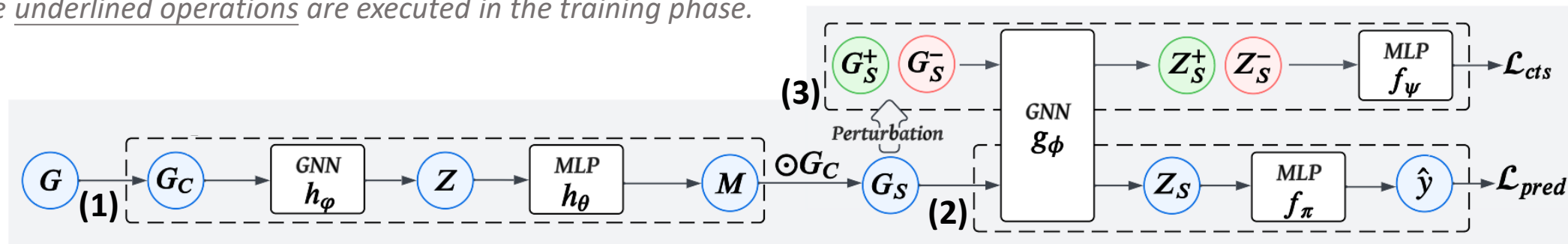
- Workflow of SUNNY-GNN*

- (1) Explanation generation: Extract the explanation G_S from input G ;
- (2) Prediction: Encode G_S and yield the prediction \hat{y} , compute the prediction loss \mathcal{L}_{pred} ;
- (3) Augmentation: Perturb G_S to get a set of positive and negative samples, compute the contrastive loss \mathcal{L}_{cts} .

- SUNNY-GNN is trained in an end-to-end manner

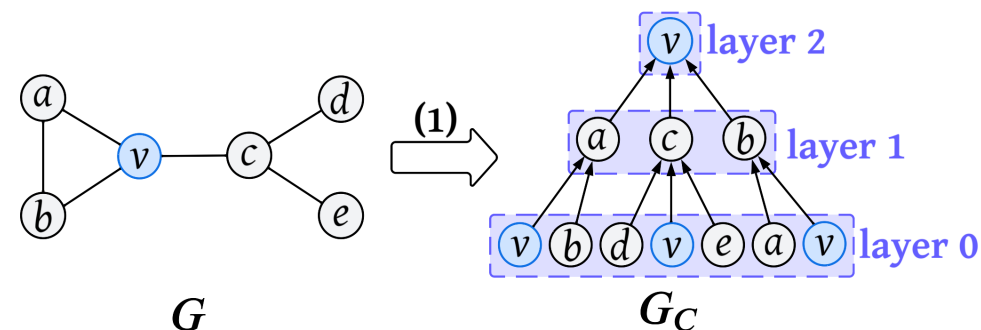
- The update of Parameters $\Theta = \{\varphi, \theta, \phi, \pi, \psi\}$ are supervised by \mathcal{L}_{pred} and \mathcal{L}_{cts} .

* The underlined operations are executed in the training phase.



- Generate edge mask M

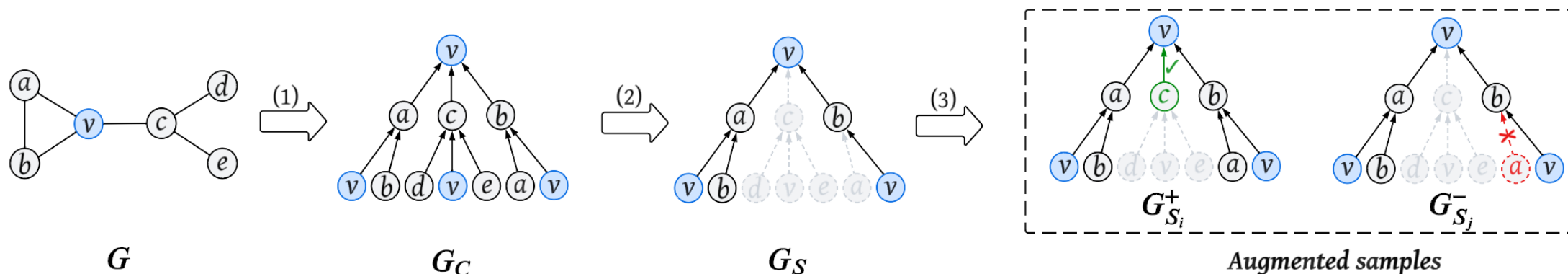
- $m_{ij} = h_{\theta}(z_i^{(0)} || z_j^{(1)} || z_v^{(2)})$ if (i, j) connects nodes between layer 0 and 1, e.g., edge (e, c) ;
- $m_{ij} = h_{\theta}(z_i^{(1)} || z_j^{(2)} || z_v^{(2)})$ if (i, j) connects nodes between layer 1 and 2, e.g., edge (c, v) .



- Get explainable subgraph G_S

- Training phase: $G_{S_{att}} = G_C \odot M$ (*differentiable*)
- Testing phase: $G_S \sim \text{Bern}(G_{S_{att}})$ (*not differentiable*)

- Positive samples
 - Sample edges from $G_C \setminus G_S$ and add them to G_S .
- Negative samples
 - Sample edges from G_S and remove them.



- How to sample?
 - A simple way: by edge mask, but may lead to
 - Trivial samples that impair the self-supervision signals;
 - Unreliable samples that mislead the GNN training.
 - Distance coefficients → Enhance contrastive signal
 - Intuition: *perturbations on edges closer to the target node v tend to have a greater impact to v than those on farther edges.*
 - $\delta^+ = 1 - \alpha \cdot \exp(d) \in \mathbb{R}^{|\mathcal{E}_C|}$
 $\delta^- = \alpha \cdot \exp(d) \in \mathbb{R}^{|\mathcal{E}_C|}$, where $\alpha \in \mathbb{R}^+$ is a positive constant and $d \in \{1, \dots, L\}^{|\mathcal{E}_C|}$.
 - Get positive and negative samples by sampling edges with $M \odot \delta^+$ and $M \odot \delta^-$, respectively.

- How to sample?
 - A simple way: by edge mask, but may lead to
 - Trivial samples that impair the self-supervision signals;
 - Unreliable samples that mislead the GNN training.
 - Confidence coefficients → **Filter out unreliable samples with labels**
 - Intuition: introducing noisy edges and removing irrelevant edges forms *untrustworthy* positive and negative samples, respectively.
 - $\eta^+ = \text{SoftMax}(f_\pi(g_\phi(G_S^+))_{y_{vt}}) \in \mathbb{R}^{n^+}$
 $\eta^- = (1 - \text{SoftMax}(f_\pi(g_\phi(G_S^-))_{y_{vt}})) \in \mathbb{R}^{n^-}$, where $f_\pi(g_\phi(G_S^+))_{y_{vt}}$ the prediction probability of samples in the truth label t of target node v .
 - Reweight the augmented samples in the contrastive loss by η^+ and η^- .

- Prediction: $z_S = g_\phi(G_S)$, $\hat{y} = f_\pi(z_S)$

- Optimization: $\min_{\Theta} \mathcal{L}_{pred} + \gamma \mathcal{L}_{cts}$

- Prediction loss:

$$\mathcal{L}_{pred} = -\frac{1}{|\mathcal{V}_{train}|} \sum_{v \in \mathcal{V}_{train}} \sum_{t=1}^{\tau} \mathcal{Y}_{vt} \log \hat{\mathcal{Y}}_{vt}$$

- Contrastive loss

- For one node v : $\mathcal{L}_{cts}(v) = \mathbb{E} \left[-\log \frac{\eta_i^+ \exp(z_S^\top z_{S_i}^+ / \tau)}{\sum_j \eta_j^+ \exp(z_S^\top z_{S_j}^+ / \tau) + \sum_k \eta_k^- \exp(z_S^\top z_{S_k}^- / \tau)} \right];$

- Contrastive loss over all training nodes: $\mathcal{L}_{cts} = \frac{1}{|\mathcal{V}_{train}|} \sum_{v \in \mathcal{V}_{train}} \mathcal{L}_{cts}(v)$

	Citeseer	Cora	Pubmed	Amazon	Coauthor-CS	Coauthor-Physics
GCN	69.84±0.7	81.20±0.7	<u>77.68±0.7</u>	<u>90.18±0.3</u>	83.52±0.4	<u>92.46±0.2</u>
+ GSAT	70.90±1.1	<u>81.48±0.7</u>	<u>77.44±0.3</u>	88.36±1.3	<u>83.76±0.6</u>	92.14±0.5
+ CAL	65.60±1.1	75.72±1.2	73.66±0.8	84.32±1.7	82.12±1.2	91.26±0.7
+ SE-GNN	68.90±0.9	80.72±0.1	77.56±0.3	-	83.14±0.8	-
+ ProtGNN	66.30±2.1	77.48±8.7	74.18±3.3	82.46±1.4	79.50±3.7	88.80±3.3
+ SUNNY-GNN	<u>70.72±0.8</u>	81.68±0.9	78.68±0.2	90.43±0.4	85.03±1.1	93.10±0.8
Average impro. (%)	3.6 ↑	3.1 ↑	3.4 ↑	4.8 ↑	3.2 ↑	3.0 ↑
GAT	69.68±1.2	<u>81.22±0.7</u>	<u>77.50±0.4</u>	89.08±1.8	<u>84.42±0.8</u>	<u>92.30±0.5</u>
+ GSAT	69.42±0.8	81.20±0.7	<u>77.04±0.3</u>	<u>89.73±0.4</u>	<u>84.37±0.7</u>	<u>91.90±0.8</u>
+ CAL	67.64±1.5	76.64±1.1	74.74±0.7	84.86±11.5	78.69±3.8	78.24±5.1
+ SE-GNN	68.18±1.1	79.46±0.4	75.88±0.4	-	83.71±0.5	-
+ ProtGNN	<u>69.90±1.5</u>	80.40±0.9	76.84±0.8	86.52±0.3	80.95±1.2	90.42±2.3
+ SUNNY-GNN	71.30±0.7	82.18±1.3	78.14±0.3	90.78±0.4	85.13±0.5	93.06±0.6
Average impro. (%)	3.2 ↑	3.1 ↑	2.3 ↑	3.0 ↑	3.4 ↑	6.0 ↑

Table 2: Classification Acc(%). The best and second-best results are bolded and underlined, respectively.

SUNNY-GNN outperforms all baselines by 3.5% on average and up to 6.0%.

	Citeseer		Cora	
	$fid_+ \uparrow$	$fid_- \downarrow$	$fid_+ \uparrow$	$fid_- \downarrow$
GCN				
+ GNNE explainer	72.27±4.2	9.31±3.4	38.29±4.1	1.08±0.4
+ PGExplainer	82.09±7.2	0.92±2.6	87.47±0.9	1.42±0.3
+ ReFine	83.01±7.1	<u>0.78±0.5</u>	88.19±0.6	0.00±0.0
+ GSAT	<u>86.75±5.7</u>	2.72±1.1	76.11±16.0	1.82±1.0
+ CAL	86.44±4.3	12.25±3.9	82.15±9.1	5.78±0.8
+ SUNNY-GNN	87.29±5.3	0.25±0.4	90.24±0.3	0.00±0.0
GAT				
+ GNNE explainer	52.95±16.9	8.61±10.1	36.44±21.0	1.43±2.2
+ PGExplainer	76.80±0.3	1.71±2.8	88.25±6.1	0.17±0.2
+ ReFine	<u>77.78±2.8</u>	0.32±1.3	<u>88.79±3.2</u>	0.00±0.0
+ GSAT	72.52±8.1	1.55±1.3	77.43±8.7	1.03±0.5
+ CAL	77.78±6.5	11.46±1.4	85.23±9.6	5.34±1.5
+ SUNNY-GNN	79.25±2.4	<u>0.46±0.5</u>	91.79±3.2	0.00±0.0

Table 4: Explainability performance (%). The best and second-best results are bolded and underlined, respectively.

- Metrics of explanation quality:

$$fid_- = \frac{1}{N} \sum_{i=1}^N |\mathbb{1}(\hat{y}_i = y_i) - \mathbb{1}(\hat{y}_i^{G_S} = y_i)|,$$

$$fid_+ = \frac{1}{N} \sum_{i=1}^N |\mathbb{1}(\hat{y}_i = y_i) - \mathbb{1}(\hat{y}_i^{G_C \setminus G_S} = y_i)|$$

- Smaller fid_- indicates better sufficiency;
- Larger fid_+ means better necessity.
- SUNNY-GNN generates explanations satisfying both good sufficiency and necessity. It outperforms the baselines by 13.1% on average and up to 33.5%.

- Case Studies:

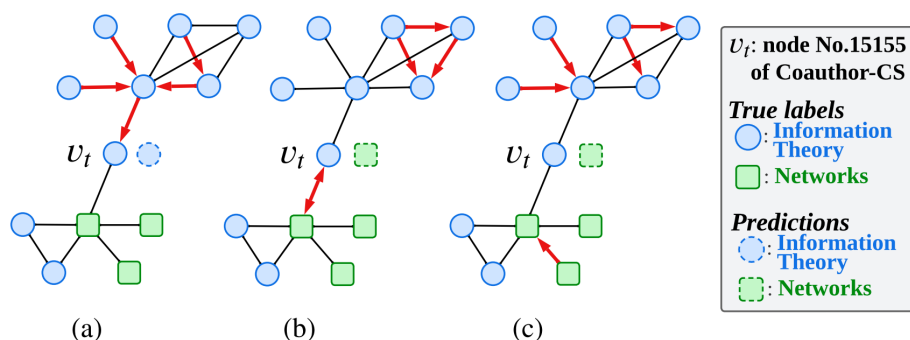


Figure 5: The visualization of explanations generated by (a) SUNNY-GNN, (b) GSAT and (c) CAL in Coauthor-CS.

- SUNNY-GNN highlights the most salient input information, while other baselines fail to.

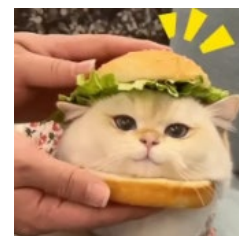
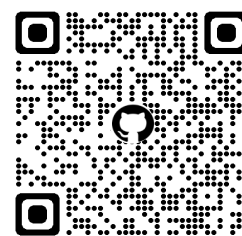
- Ablation Studies:

	Acc \uparrow	fid_+ \uparrow	fid_- \downarrow
SUNNY-GNN	71.26 \pm 0.7	79.25 \pm 2.4	0.46 \pm 0.5
w/o \mathcal{L}_{cts}	69.01 \pm 1.2	76.50 \pm 1.4	1.78 \pm 0.4
w/o δ	70.78 \pm 0.7	79.13 \pm 1.8	0.47 \pm 0.5
w/o η	70.48 \pm 0.8	77.83 \pm 1.9	1.28 \pm 1.0

Table 5: Individual contributions of proposed modules.

- The contrastive training paradigm plays a key role in improving the prediction and explainability performance of SUNNY-GNN.

- We illustrate the importance of generating **sufficient** and **necessary** explanations for improving the performance of self-interpretable graph learning methods;
- We propose **SUNNY-GNN**, to generate such explanations while improving prediction performance empowered by **contrastive loss**;
- Future work: More complex graph mining scenarios such as heterogenous settings or multimodal settings.
- Code: <https://github.com/SJTU-Quant/SUNNY-GNN>
- Contact us: jialedeng@sjtu.edu.cn



Thanks!