view\_frames Result Recorded at time: 1498651249.638 world Broadcaster: /robot\_state\_publisher Broadcaster: /object\_pose Average rate: 50.204 Hz Average rate: 1742.918 Hz Most recent transform: 1498651249.630 ( 0.008 sec old) Most recent transform: 1498651250.133 (-0.496 sec old) Buffer length: 4.980 sec Buffer length: 4.976 sec base\_link object Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /object2camera Average rate: 41.869 Hz Average rate: 50.204 Hz Average rate: 1571.421 Hz Most recent transform: 1498651250.133 (-0.496 sec old) Most recent transform: 1498651249.635 (0.003 sec old) Most recent transform: 1498651249.637 (0.001 sec old) Buffer length: 4.980 sec Buffer length: 4.983 sec Buffer length: 4.968 sec shoulder\_link camera\_in\_object base Broadcaster: /ur\_driver Broadcaster: /robot\_state\_publisher Average rate: 125.203 Hz Average rate: 41.869 Hz Most recent transform: 1498651249.635 ( 0.003 sec old) Most recent transform: 1498651249.635 ( 0.003 sec old) Buffer length: 4.976 sec Buffer length: 4.968 sec upper\_arm\_link tool0\_controller Broadcaster: /robot\_state\_publisher Average rate: 41.869 Hz Most recent transform: 1498651249.635 ( 0.003 sec old) Buffer length: 4.968 sec forearm\_link Broadcaster: /robot\_state\_publisher Average rate: 41.869 Hz Most recent transform: 1498651249.635 ( 0.003 sec old) Buffer length: 4.968 sec wrist\_1\_link Broadcaster: /robot\_state\_publisher Average rate: 41.869 Hz Most recent transform: 1498651249.635 ( 0.003 sec old) Buffer length: 4.968 sec wrist\_2\_link Broadcaster: /robot\_state\_publisher Average rate: 41.869 Hz Most recent transform: 1498651249.635 ( 0.003 sec old) Buffer length: 4.968 sec wrist\_3\_link Broadcaster: /robot state publisher Broadcaster: /robot\_state\_publisher Average rate: 50.204 Hz Average rate: 50.204 Hz Most recent transform: 1498651250.133 (-0.496 sec old) Most recent transform: 1498651250.133 ( -0.496 sec old) Buffer length: 4.980 sec Buffer length: 4.980 sec ee\_link tool0 Broadcaster: /camera\_frame Average rate: 10.141 Hz Most recent transform: 1498651249.558 ( 0.080 sec old) Buffer length: 4.832 sec camera\_frame Broadcaster: /distance\_estimate Average rate: 30.149 Hz Most recent transform: 1498651249.608 ( 0.029 sec old) Buffer length: 4.942 sec

object\_frame