Stewart C. Jamieson

GRADUATE STUDENT · AUTONOMOUS ROBOTICS

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A roboticist working to invent autonomous systems that can learn to make decisions using vast quantities of unstructured information.

Education

Woods Hole Oceanographic Institute

Woods Hole, Massachusetts

Ph.D. IN APPLIED OCEAN SCIENCE AND ENGINEERING

June 2018 - Present

- Enrolled in the MIT-WHOI Joint Program, supervised by Dr. Yogesh Girdhar (WHOI) and Prof. Jonathan How (MIT)
- Developing robots and algorithms for autonomous exploration of unknown marine environments

Massachusetts Institute of Technology (MIT)

Cambridge, Massachusetts

S.M. IN AEROSPACE ENGINEERING (4.0/4.0 CGPA)

June 2018 - Present

University of Toronto

Toronto, Canada

B.A.Sc. IN ENGINEERING SCIENCE, ROBOTICS MAJOR (3.83/4.0 CGPA)

Sept. 2013 - Apr. 2018

Skills_

Artificial Intelligence Topic Modelling, Deep Learning for Vision, Neural Networks, Unsupervised Learning

Robotics ROS, Computer Vision, Multi-Agent Path Planning, Controls **Programming** C++14, Python3, OpenCV, Java, MATLAB, Android, Bash, R

Experience _____

Zebra Technologies Inc.

Mississauga, Canada

SOFTWARE ENGINEERING INTERN, ENGINEERING PRODUCT INNOVATION TEAM

May 2016 - Aug. 2017

- Developed software applications and libraries for both mobile devices and high-performance servers
- 16 months of experience with C++14 for networking, data processing, and multithreaded computing
- Helped to research and present business applications for machine learning

Wattpad Inc. Toronto, Canada

ANDROID SOFTWARE DEVELOPER, READER ACQUISITION TEAM

May 2015 - Sept. 2015

- $\bullet \ \ \text{Implemented features to attract new users, as well as A/B tests to validate each features' success}$
- Developed strong teamwork and communication skills by working in a multi-platform feature team

QA Software Developer, Android Core Team

May 2014 - Sept. 2014

- · Searched for, reported, and fixed software bugs in an Android mobile application with over 15 million users
- Managed the translation and localization of the application into 18 languages
- Designed and implemented a virtual doorman to greet company visitors and notify staff

Extracurricular Activity

aUToronto Self-Driving Car Team

Toronto, Canada

June 2017 - June 2018

SOFTWARE TEAM LEAD

- Won 1st place in Year One of the SAE/GM AutoDrive Challenge
- Led a team of 12 graduate and undergraduate students to help make an autonomous Chevrolet Bolt
- Team developed the overall system software architecture, sensor drivers, vehicle control interface, software services

Zebra Technologies Inc.

Mississauga, Canada

EDITOR, EMC INNOVATION NEWSLETTER

May 2016 - Aug. 2017

- Edited bi-monthly department newsletter and distributed it to over 1700 engineers
- · Commissioned, reviewed, and published articles about recent trends and innovations

Corpus Christi Jazz Horns and Concert Band

SAXOPHONIST

• Performed in the Atlantic Music Festival (2013), Toronto Music Festival (2012)

Burlington, Canada Sept. 2009 - June 2013

Honors & Awards

INTERNATIONAL

2018 1st Place, SAE/GM AutoDrive Challenge

Yuma, Arizona

DOMESTIC

2018	Dean's Honour List, University of Toronto	Toronto, Canada
2014-16	Dean's Honour List (x3), University of Toronto	Toronto, Canada
2013	Governor General's Bronze Medal for Academic Excellence, High School Graduation	Burlington, Canada
2013	Regional Champion, ECOO Programming Competition	Halton, Canada
2010-13	School Champion (x4), Waterloo CEMC Math Contest	Burlington, Canada

Presentations

An Introduction to Neural Networks and Machine Learning

Mississauga, Canada

PRESENTER FOR ZEBRA TECHNOLOGIES INC. "LUNCH & LEARN"

Jan. 2017

- Introduced the fundamental concepts of neural networks & machine learning to over 200 engineers
- · Shared results of a research investigation into relevant business applications of neural networks

Should Robots Have Rights?

Toronto, Canada

PRESENTER IN DEBATE AT THE UNIVERSITY OF TORONTO

Dec. 2015

• Participated in a debate to affirm that sufficiently "intelligent" robots should be awarded basic rights

A Customized Graphical Checklist for Efficient Ambulance Inventory

Toronto, Canada

PRESENTER IN "PRAXIS II SHOWCASE" AT THE UNIVERSITY OF TORONTO

Apr. 2014

- Developed a low-cost, computer-generated checklist to improve efficiency for resupplying ambulance inventory
- Presented results of a 3-month engineering team design project to attending professors, paramedics, and CBC Radio

Publications

Girdhar, Y., Cai, L., *Jamieson, S.*, McGuire, N., Flaspohler, G., Suman, S., & Claus, B. (2019). **Enabling Co-Robotic Scientific Exploration of Unknown Environments over a Low Bandwidth Communication Channel.** In IEEE International Conference on Robotics and Automation. Montreal, Canada.

Jamieson, S. (2018). Deep Learning for Robust Vision in Realtime Autonomous Driving. University of Toronto.

Professional Activities

Graduate Student Member

Worldwide

IEEE (INSTITUTE OF ELECTRICAL AND ELECTRONICS ENGINEERS)

Nov. 2013 - Present