# Stewart C. Jamieson

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A roboticist working to invent autonomous vehicles that can co-operate with humans in uncertain, unstructured, and unknown environments and accomplish their objectives safely and efficiently.

## Education

#### Massachusetts Institute of Technology & Woods Hole Oceanographic Institute

Cambridge, MA, USA

S.M./Ph.D. IN AERONAUTICS AND ASTRONAUTICS (5.0/5.0 CGPA) — MARINE ROBOTICS

June 2018 - Present

- Co-supervised by Dr. Yogesh Girdhar (WHOI) and Prof. Jonathan How (MIT)
- Developing algorithms for robot-based autonomous scientific exploration of highly remote environments (e.g. Mars, oceans)
- Focus on developing robots that can robustly achieve their operator's objectives in unfamiliar and dynamic environments
- Relevant Coursework: Cognitive Robotics, Bayesian Modelling and Inference, Theory of Intelligence

**University of Toronto** Toronto, ON, Canada

B.A.Sc. IN ENGINEERING SCIENCE (3.83/4.0 CGPA) — ROBOTICS MAJOR

Sept. 2013 - Apr. 2018

Thesis: Deep Learning for Robust Vision in Realtime Autonomous Driving, supervised by Prof. Angela Schoellig

# Work & Research Experience \_

#### WHOI's Autonomous Robotics and Perception Laboratory (WARPLab)

Woods Hole, MA, USA

GRADUATE RESEARCH ASSISTANT

June 2018 - Present

- · Developing autonomous exploration algorithms for robot teams operating in the Benthic zone
- · Publications focus on enabling robot co-operation with humans over very limited communication channels
- Assisting with the deployment of these novel algorithms into WHOI's world-class deep sea exploration vehicles (e.g. Sentry)

#### Zebra Technologies Inc.

Mississauga, ON, Canada

SOFTWARE ENGINEERING INTERN, ENGINEERING PRODUCT INNOVATION TEAM

May 2016 - Aug. 2017

- · Helped to research and present business applications for robotics, machine learning, and neural networks
- 16 months of development experience in C++14 including networking, data processing, and multithreaded computing

Wattpad Inc. Toronto, ON, Canada

ANDROID SOFTWARE DEVELOPER, READER ACQUISITION TEAM

May 2015 - Sept. 2015

- Wattpad is a worldwide storytelling platform with a community of over 80 million users
- Implemented features designed to attract new users; also implemented A/B tests to validate each features' success

QA SOFTWARE DEVELOPER, ANDROID CORE TEAM

May 2014 - Sept. 2014

- · Searched for, reported, and fixed software bugs in the Android mobile application with over 15 million users
- · Designed and implemented a virtual doorman to greet company visitors and notify staff of their arrival

## **Professional Activities**

#### **aUToronto Self-Driving Car Team**

University of Toronto, Canada

SOFTWARE TEAM LEAD

June 2017 - June 2018

- Led a subteam of 12 graduate and undergraduate students working to develop an autonomous Chevrolet Bolt
- · My team created the overall system software architecture, sensor drivers, vehicle control interface, and software services
- At the end of my term, aUToronto won 1st place in Year One of the SAE/GM AutoDrive Challenge

#### Zebra Technologies Inc.

Mississauga, ON, Canada

May 2016 - Aug. 2017

• Edited bi-monthly department newsletter and distributed it to over 1700 engineers

· Commissioned, reviewed, and published articles about recent trends and innovations in electronics, robotics, etc.

#### **Graduate Student Member**

**EDITOR, EMC INNOVATION NEWSLETTER** 

Worldwide

IEEE (INSTITUTE OF ELECTRICAL AND ELECTRONICS ENGINEERS)

Nov. 2013 - Present

### Peer-Reviewed Publications

[In Review] **Jamieson, S.**, How, J.P., Girdhar, Y. (2020). *Active Reward Learning for Co-Robotic Vision Based Exploration in Bandwidth Limited Environments*. Submitted to IEEE International Conference on Robotics and Automation.

Girdhar, Y., Cai, L., **Jamieson, S.**, McGuire, N., Flaspohler, G., Suman, S., & Claus, B. (2019). *Enabling Co-Robotic Scientific Exploration of Unknown Environments over a Low Bandwidth Communication Channel*. In IEEE International Conference on Robotics and Automation (ICRA). Montréal, Canada.

**Jamieson, S.** (2019). The Pervasiveness of Deep Learning in Robotics Research Does Not Impede Scientific Insights into Robotics Problems. "Debates on the Future of Robotics Research" Workshop at ICRA 2019. Montréal, Canada.

## Other Publications\_

Jamieson, S. (2018). Deep Learning for Robust Vision in Realtime Autonomous Driving. B.A.Sc. Thesis, University of Toronto.

## **Presentations**

Videos and other materials used in some of the following presentations are available at www.stewartjamieson.com

#### Deep Learning Does Not Impede Scientific Insights into Robotics Problems

Montréal, QC, Canada

PRESENTER AT THE DEBATES ON THE FUTURE OF ROBOTICS RESEARCH, ICRA 2019

May 201

• Presented an accepted talk arguing that deep learning is a tool, rather than an obstacle, for making scientific insights into robotics problems and their solutions. See the IEEE RA-M Paper: https://ieeexplore.ieee.org/document/8825887

#### **Multi-Robot Adaptive Sampling**

Cambridge, MA, USA

CO-PRESENTER IN LECTURE AT MASSACHUSETTS INSTITUTE OF TECHNOLOGY

Apr. 2019

• Co-presented a lecture on multi-robot adaptive sampling techniques and robotics applications

#### An Introduction to Neural Networks and Machine Learning

Mississauga, ON, Canada

CO-PRESENTER FOR ZEBRA TECHNOLOGIES INC. "LUNCH & LEARN"

Jan. 2017

- Introduced the fundamental concepts of neural networks & machine learning to over 200 engineers
- Shared results of a research investigation into relevant business applications of neural networks

#### **Should Robots Have Rights?**

Toronto, ON, Canada

CO-PRESENTER IN DEBATE AT THE UNIVERSITY OF TORONTO

Dec. 2015

• Participated in a debate to affirm that sufficiently "intelligent" robots should be awarded basic rights

## A Customized Graphical Checklist for Efficient Ambulance Inventory

Toronto, ON, Canada

Co-Presenter in "Praxis II Showcase" at the University of Toronto

Apr. 2014

- Developed a low-cost, computer-generated checklist to improve efficiency for resupplying ambulance inventory
- Presented results of a 3-month engineering team design project to attending professors, paramedics, and CBC Radio

## **Honors & Awards**

#### INTERNATIONAL

2018 1st Place Team, SAE/GM AutoDrive Challenge

Yuma, AZ, USA

#### **DOMESTIC**

2018	Dean's Honour List, University of Toronto	Toronto, ON, Canada
2014-16	Dean's Honour List (x3), University of Toronto	Toronto, ON, Canada
2013	Governor General's Bronze Medal for Academic Excellence, High School Graduation	Burlington, ON, Canada
2013	Regional Champion, ECOO Programming Competition	Halton, ON, Canada
2010-13	School Champion (x4), Waterloo CEMC Math Contest	Burlington, ON, Canada

## Research Interests & Skills

Artificial Intelligence Topic Modelling, Deep Learning for Robust Vision, Active Learning, Unsupervised Learning, Al Ethics

**Robotics** Autonomous Scientific Exploration, Human-Robot Interaction, Informative Path Planning

**Programming** C++14, Python, ROS, OpenCV, Java, MATLAB, Pandas, Android

# Personal Interests\_

## **Corpus Christi Jazz Horns and Concert Band**

SAXOPHONIST

• Performed in the Atlantic Music Festival (2013), Toronto Music Festival (2012)

Burlington, ON, Canada Sept. 2009 - June 2013