# Stewart C. Jamieson

PHD STUDENT · AUTONOMOUS ROBOTS & MACHINE LEARNING

A roboticist working to invent autonomous systems that co-operate with humans in uncertain, unstructured, and unknown environments and accomplish their objectives safely and efficiently.

## **Education**

#### Massachusetts Institute of Technology & Woods Hole Oceanographic Institution

Cambridge, MA, USA

Ph.D. IN APPLIED OCEAN SCIENCE AND ENGINEERING — MARINE ROBOTICS

June 2020 - Present

- Co-supervised by Dr. Yogesh Girdhar (WHOI) and Prof. Jonathan P. How (MIT)
- Focus on developing multi-robot systems that robustly achieve mission objectives in remote and unfamiliar environments

#### S.M. IN AERONAUTICS AND ASTRONAUTICS — AUTONOMOUS SYSTEMS (5.0/5.0 CGPA)

June 2018 - May 2020

- Thesis: Enabling Human-Robot Cooperation in Scientific Exploration of Bandwidth-Limited Environments
- Co-supervised by Dr. Yogesh Girdhar (WHOI) and Prof. Jonathan P. How (MIT)
- · Relevant Coursework: Cognitive Robotics, Visual Navigation for Autonomous Vehicles, Bayesian Modelling and Inference

University of Toronto, ON, Canada

B.A.Sc. IN Engineering Science with Honours — Robotics Major (3.83/4.0 CGPA)

Sept. 2013 - Apr. 2018

Thesis: Deep Learning for Robust Vision in Realtime Autonomous Driving, supervised by Prof. Angela Schoellig

# Work & Research Experience

#### WHOI's Autonomous Robotics and Perception Laboratory (WARPLab)

Woods Hole, MA, USA

**GRADUATE RESEARCH ASSISTANT** 

June 2018 - Present

- Developing autonomous exploration algorithms for robot teams operating in the Benthic zone
- Publications focus on enabling robot co-operation with humans over very limited communication channels
- Assisting with the deployment of these novel algorithms into WHOI's world-class deep sea exploration vehicles (e.g. Sentry)

#### aUToronto Self-Driving Car Team

University of Toronto

SOFTWARE TEAM LEAD

June 2017 - June 2018

- · Led a subteam of 12 graduate and undergraduate students working to develop an autonomous Chevrolet Bolt
- My team created the overall system software architecture, sensor drivers, vehicle control interface, and software services
- At the end of my term as lead, aUToronto won 1st place in Year One of the SAE/GM AutoDrive Challenge

#### Zebra Technologies Inc.

Mississauga, ON, Canada

SOFTWARE ENGINEERING INTERN, ENGINEERING PRODUCT INNOVATION TEAM

May 2016 - Aug. 2017

- Contributed to initial development and testing of the novel Zebra SmartSight™ robot designed for retail operations
- Helped to research and present business applications for robotics, machine learning, and neural networks
- 16 months of development experience in C++14 including networking, data processing, and multithreaded computing

# Wattpad Inc.

Toronto, ON, Canada

May 2015 - Sept. 2015

Android Software Developer, Reader Acquisition Team

- Wattpad is a worldwide storytelling platform with a community of over 80 million users
- Implemented features designed to attract new users; also implemented A/B tests to validate each features' success

#### QA SOFTWARE DEVELOPER, ANDROID CORE TEAM

May 2014 - Sept. 2014

- Searched for, reported, and fixed software bugs in the Android mobile application with over 15 million users
- Designed and implemented a virtual doorman to greet company visitors and notify staff of their arrival

## **Professional Activities**

### Zebra Technologies Inc.

Mississauga, ON, Canada

**EDITOR, EMC INNOVATION NEWSLETTER** 

May 2016 - Aug. 2017

- Edited bi-monthly department newsletter and distributed it to over 1700 engineers
- · Commissioned, reviewed, and published articles about recent trends and innovations in electronics, robotics, etc.

#### **Graduate Student Member**

Worldwide

IEEE (INSTITUTE OF ELECTRICAL AND ELECTRONICS ENGINEERS)

Nov. 2013 - Present

## Peer-Reviewed Publications

Jamieson, S., How, J.P., Girdhar, Y. (2020). Active Reward Learning for Co-Robotic Vision Based Exploration in Bandwidth Limited Environments. In IEEE International Conference on Robotics and Automation (ICRA). Paris, France. Finalist for Best Paper Award in Service Robotics.

Girdhar, Y., Cai, L., Jamieson, S., McGuire, N., Flaspohler, G., Suman, S., & Claus, B. (2019). Enabling Co-Robotic Scientific Exploration of Unknown Environments over a Low Bandwidth Communication Channel. In IEEE International Conference on Robotics and Automation (ICRA). Montréal, Canada.

Jamieson, S. (2019). The Pervasiveness of Deep Learning in Robotics Research Does Not Impede Scientific Insights into Robotics Problems. "Debates on the Future of Robotics Research" Workshop at ICRA 2019. Montréal, Canada.

## Other Publications

Jamieson, S. (2020). Enabling Human-Robot Cooperation in Scientific Exploration of Bandwidth-Limited Environments. Master's Thesis, Massachusetts Institute of Technology & Woods Hole Oceanographic Institution.

Jamieson, S. (2018). Deep Learning for Robust Vision in Realtime Autonomous Driving. B.A.Sc. Thesis, University of Toronto.

## Presentations

Videos and other materials used in some of the following presentations are available at www.stewartjamieson.com

#### Deep Learning Does Not Impede Scientific Insights into Robotics Problems

Montréal, QC, Canada

SOLO PRESENTER AT THE DEBATES ON THE FUTURE OF ROBOTICS RESEARCH, ICRA 2019

May 2019

· Presented an accepted talk arguing that deep learning is a tool, rather than an obstacle, for making scientific insights into robotics problems and their solutions. See IEEE RA-M Paper of the event: https://ieeexplore.ieee.org/document/8825887

## **Multi-Robot Adaptive Sampling**

Cambridge, MA, USA

CO-PRESENTER IN LECTURE AT MASSACHUSETTS INSTITUTE OF TECHNOLOGY

Apr. 2019

· Co-presented a lecture on multi-robot adaptive sampling techniques and robotics applications

## **An Introduction to Neural Networks and Machine Learning**

Mississauga, ON, Canada

CO-Presenter for Zebra Technologies Inc. "Lunch & Learn"

Jan. 2017

- Introduced the fundamental concepts of neural networks & machine learning to over 200 engineers
- Shared results of a research investigation into relevant business applications of neural networks

## **Should Robots Have Rights?**

Toronto, ON, Canada

CO-PRESENTER IN DEBATE AT THE UNIVERSITY OF TORONTO

Dec. 2015

• Participated in a debate to affirm that sufficiently "intelligent" robots should be awarded basic rights

### A Customized Graphical Checklist for Efficient Ambulance Inventory

Toronto, ON, Canada

CO-PRESENTER IN "PRAXIS II SHOWCASE" AT THE UNIVERSITY OF TORONTO

Apr. 2014

· Developed a low-cost, computer-generated checklist to improve efficiency for resupplying ambulance inventory

Presented results of a 3-month engineering team design project to attending professors, paramedics, and CBC Radio

## Honors & Awards

#### INTERNATIONAL

2020 Finalist for Best Paper Award in Service Robotics, ICRA 2020 Paris, France

1st Place Team, SAE/GM AutoDrive Challenge

Yuma, AZ, USA

#### DOMESTIC

2018	Dean's Honour List, University of Toronto	Toronto, ON, Canada
2014-16	Dean's Honour List (x3), University of Toronto	Toronto, ON, Canada
2013	Governor General's Bronze Medal for Academic Excellence, High School Graduation	Burlington, ON, Canada
2013	Regional Champion, ECOO Programming Competition	Halton, ON, Canada
2010-13	School Champion (x4), Waterloo CEMC Math Contest	Burlington, ON, Canada

## Research Interests & Skills\_

Artificial Intelligence Topic Modelling, Deep Learning for Robust Vision, Active Learning, Unsupervised Learning, Al Ethics

**Robotics** Autonomous Scientific Exploration, Human-Robot Interaction, Informative Path Planning

**Programming** C++14, Python, ROS, OpenCV, Java, MATLAB, Pandas, Android

## **Service Activities**

Professional ServiceWorldwideEDITORIAL ROLESNov. 2019 - Present

• Reviewed Conference Submissions for:

- International Conference on Machine Learning (ICML)

- International Conference on Robotics and Automation (ICRA)
- International Conference on Intelligent Robots and Systems (IROS)
- Reviewed Journal Submissions for:
  - Journal of Aerospace Information Systems (JAIS)

## Personal Interests \_\_\_

## **Corpus Christi Jazz Horns and Concert Band**

SAXOPHONIST

• Performed in the Atlantic Music Festival (2013), Toronto Music Festival (2012)

Burlington, ON, Canada Sept. 2009 - June 2013