

HK-TN-91: HK LI Fibre Specifications

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Contents

1	Introduction	2
2	HK LI System Overview	2
3	Fibre Lab Measurements	4
3.1	Fibre Test Stand	5
3.2	Preliminary Measurements	5
3.3	Attenuation Measurements	8
3.4	Dispersion Measurements	10
3.5	Fibre Choice	11
4	Fibre Switching Device	12
4.1	Overview	12
4.2	General Comparisons	13
4.3	Cross-talk Measurements	14
4.4	Summary	16
5	Fibre Length Requirements	17
6	Photon Yield Requirements	21
7	Summary	23
A	Additional Cross Talk Plots	27
A.1	Weinert FP400URT	27
A.2	Weinert GIF50C	28

1 Introduction

The Hyper-Kamiokande experiment has a broad physics program, including the aim of making precision measurements of neutrino oscillation parameters. In order to make such precision measurements, a precise understanding of the detector itself is required. To this end an array of different calibration systems are planned, with each playing a crucial role in driving systematic uncertainties down to the percent-level required.

A key component of the calibration program is the light injection (LI) system, which has two primary aims. The first is to measure the optical properties of the water in the tank, and monitor how the measured absorption and scattering parameters evolve with time. The second is to provide light sources with which to calibrate PMT response. In order to illuminate the injectors, lengths of fibre optic cable will be used to carry light from the sources on the top of the tank, all the way to the injectors installed on the PMT support structure.

This technical note focuses on the fibre optic requirements for the LI system, describing the quantities and lengths of cables needed, along with the lab measurements performed to decide on which types of fibre optic cables to use.

2 HK LI System Overview

The HK LI system will be split into two parts, one for the inner detector (ID) and one for the outer detector (OD). The ID system will consist of 33 injector positions, each housing a diffuser and collimator. Full details of the diffuser and collimator designs and requirements can be found in HK-TN-0042 [1] and HK-TN-0065 [2], respectively. Of the ID injectors, 28 will be located in the barrel region, with 7 locations equally spaced in z , each having four positions equally spaced in θ . The bottom end-cap will feature four more injector locations, with the injectors all facing upwards in the $+z$ direction. The top end-cap will feature a single location, where a calibration port will be used, rather than fixing to the PMT support structure. Figure 1 shows the injector locations described. Installing injectors at different heights throughout the detector will allow water parameters to be measured as a function of depth.

The OD system will consist primarily of diffusers, using bare hemispheres coupled to fibres, rather than the housed versions used for the ID system; 122 of these OD diffusers will be installed. The current design features 84 equally spaced around the barrel region. This results in 7 rows of 12 diffusers, with rows alternately offset from one another. This configuration is particularly advantageous as it matches the number of rows in the ID system, simplifying the installation of the fibre optic cables. Each end-cap would then feature 19 diffusers, again equally spaced across the surface. A diagram showing this layout is presented in Figure 2. Finally, 12 collimators will be installed in the OD, in suitable locations to achieve long path lengths such as across the end caps and up the side of the barrel. These collimators will be exactly the same as those installed in the ID.

In order to illuminate the injectors, two separate systems will be employed. The first of these will be a system formed of either five or six picosecond pulsed laser sources, in the wavelength range 337-550 nm. This laser system will be used to illuminate all of the ID injectors, along with the 12 OD collimators. The OD diffusers on the other hand will be illuminated by an LED pulser system, utilising a series of 365 nm wavelength LEDs. Both of these systems will feature

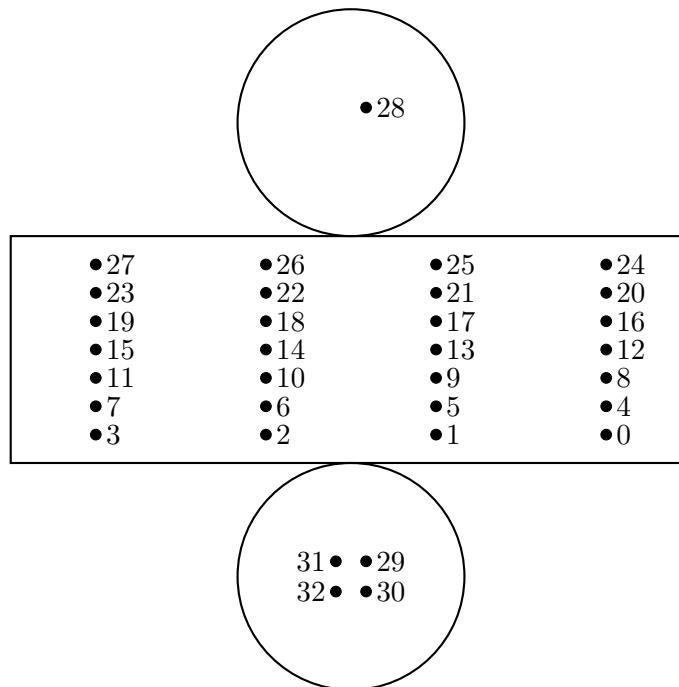


Figure 1: Injector location map for ID positions. Each location will feature a diffuser and collimator.

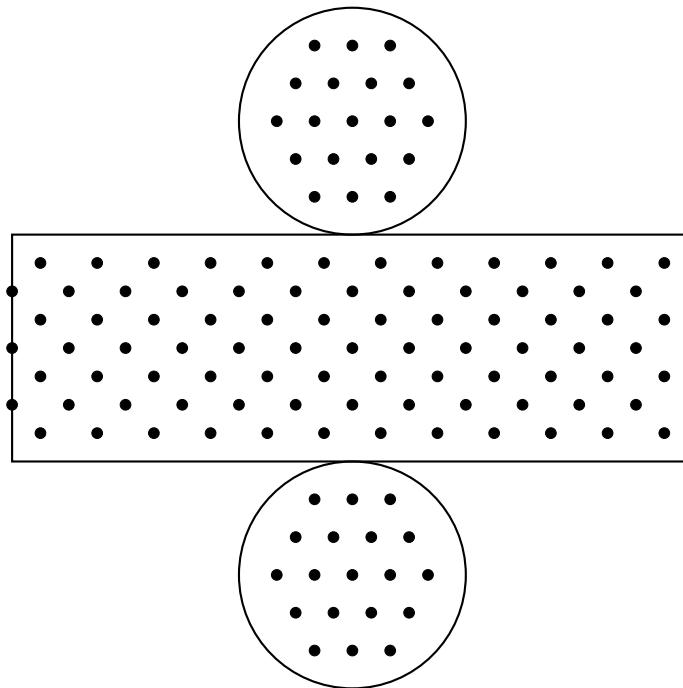


Figure 2: Injector location map for OD diffuser positions. Locations are approximate and dependent on PMT/WLS plate locations.

monitoring devices, so that the stability of the light sources can be monitored prior to convolution with detector parameters.

In total, including a laser diffuser ball and at least one spare channel, the lasers for the ID system will be required to couple to at least 80 channels. To accomplish this, dedicated fibre switching devices are required. A diagram giving an idea of the eventual laser and switch setup that would be used is given in Figure 3. These laser heads will be coupled into a single fibre using

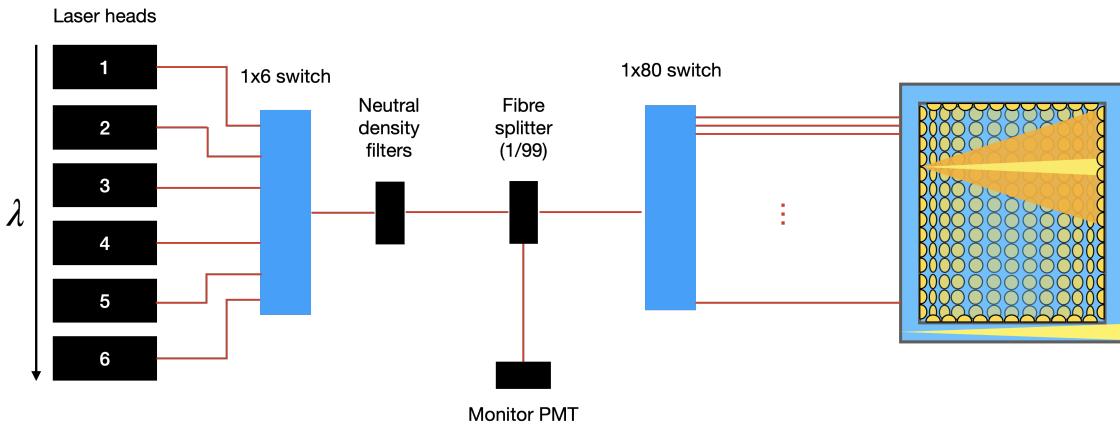


Figure 3: Diagram showing the likely setup for laser heads and fibre switchers.

a 1-to-6 (hereafter denoted as 1x6) switch. This fibre can then be passed through neutral density filters if these are required to reduce laser power, as well as a fibre splitter with a 1/99 splitting. This allows 1% of the laser power to be directed to a nearby monitor PMT, which will monitor laser power before coupling into the long fibres and without entangling water parameters from within the detector. The fibre with the remaining 99% will go into a 1x80 switch, with the output going into the long fibres that extend down to the injectors.

3 Fibre Lab Measurements

In order to make an informed decision on the optimal fibre optic cables to use for the LI system in HK, a series of measurements were made of the properties of the candidate fibres chosen. This section describes the fibre test stand setup at University of Liverpool, along with the measurements made of the candidate fibres, before discussing the decision on which fibres to use.

For the fibres to be suitable for use in the LI system, there are a series of requirements. These are:

- The fibre should be capable of transporting light of wavelengths in the range 337-550 nm.
- The attenuation of the input signal across the full length of fibre should be minimised.
- The dispersion of the input signal across the full length of fibre should be minimised.

Six different fibre types from Thorlabs were considered, to cover a range of options. Four of these were step-index fibres; two wide-core fibres (FP200URT [3] and FP400URT [4]) and two narrow-core fibres (FG050UGA [5] and FG105UCA [6]) were chosen. The remaining two candidates were graded-index fibres (GIF50C [7] and GIF50D [8]). Graded-index fibres were tested as it was expected that they would be required to limit dispersion of input signals across the full fibre length. It was particularly important to test the graded-index fibres as they are primarily for communications applications, and as such are only specified for operation above 800 nm. The main specifications of each fibre type are summarised in Table I. GIF50C and GIF50D have almost the same specifications, with the only difference being the available bandwidth. Preliminary measurements were performed with all six fibre types listed, and these results were used to make an informed choice on which should be investigated more thoroughly.

Fibre	Type	Core ϕ [μm]	NA	Transmission region [nm]
FG050UGA	Step-index	50	0.22	250-1200
FG105UCA	Step-index	105	0.22	250-1200
FP200URT	Step-index	200	0.50	300-1200
FP400URT	Step-index	400	0.50	300-1200
GIF50C	Graded-index	50	0.20	800-1600
GIF50D	Graded-index	50	0.20	800-1600

Table I: Fibre types used for initial testing in lengths of 1 m and 35 m.

3.1 Fibre Test Stand

All fibre measurements were performed using the fibre test stand in the Particle Physics Optical Laboratory at the University of Liverpool. Two different types of light sources are available for testing; the first of these is a Picoquant Sepia PDL 828-L laser driver [9], powering a LDH-D-C-375M laser head [10], with a peak wavelength of 371 nm. This is a pulsed laser source with a pulse width of \sim 50 ps, and repetition rate up to 80 MHz. The candidate fibres couple directly to the laser head using an FC/PC connector. The second set of light sources was a series of LEDs, covering wavelengths from 365 nm up to 595 nm. These are run in DC mode, and were used primarily to make attenuation measurements over the range of wavelengths relevant for the LI system. In order to connect the FC/PC connector on a candidate fibre to a surface-mounted LED, custom connectors were 3D printed.

Two different detection methods for the fibre transmitted light are available. To measure power output, a Thorlabs PM100USB [11] power meter is used, with an S150C sensor [12] connected. For timing measurements, the fibres are connected to a Hamamatsu H10721-210 PMT [13], which is read out by a Tektronix MSO54 oscilloscope [14]. Fibres are coupled to either read-out method via FC/PC connection such that, in the case of the laser, there are no bare beams in the lab. To ensure light tightness and as an additional safety measure, all light sources and detectors are housed within a dark box, with no connections made outside. Larger fibre reels are kept outside due to their size, with a port used to bring the ends inside for connection. An image of the setup is shown in Figure 4.

3.2 Preliminary Measurements

In order to narrow down the choice of fibre optic cable, all six options listed in Table I were purchased, in lengths of 1 m and 35 m. This is much shorter than the fibres that will be needed for Hyper-K; full length fibres were not used due to supplier issues. The length of cables which could be cut was limited by the size of the building used for production, as cold weather conditions during winter in the US at the time of ordering prevented them from being cut outside. Rather than delay the measurements, the decision was taken to start preliminary measurements of attenuation and dispersion with the lengths that were available.

3.2.1 Testing

Due to the early stage at which these measurements were made, the laser module described in Section 3.1 had not yet been set up. Instead, preliminary measurements of both attenuation and

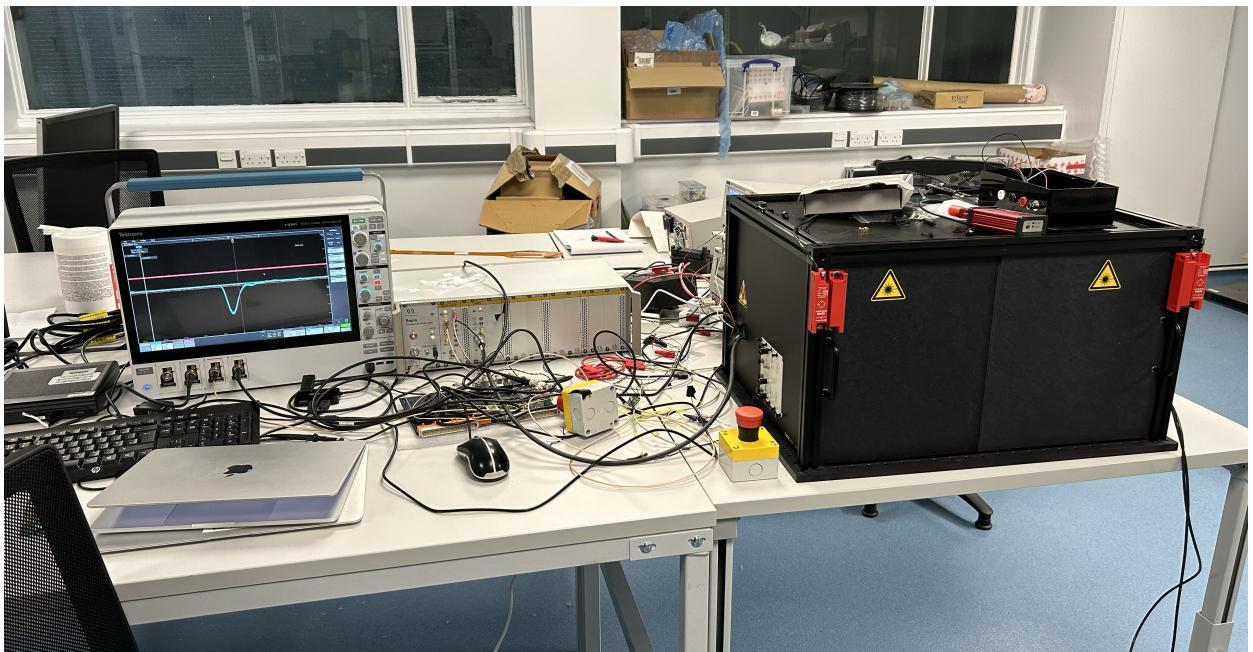


Figure 4: Fibre test stand in the optical lab at University of Liverpool.

dispersion were made using a pulsed 385 nm LED, operated by an early design of the LED pulser board that will be used for the OD LED system.

To calculate dispersion of the signal across the fibre length, the width of the PMT signal pulse was measured for both lengths of each fibre. A total of 20,000 measurements were made for each set to estimate the uncertainty. Subtracting these values in quadrature obtains the amount of dispersion observed. The pulse widths at both lengths and calculated dispersion values for each fibre are presented in Table II. The results shown here are mostly unsurprising. As expected,

Fibre	Pulse width at 1 m [ns]	Pulse width at 35 m [ns]	Dispersion [ns]
FG050UGA	3.486 ± 0.111	4.207 ± 0.305	2.355 ± 0.569
FG105UCA	3.734 ± 0.075	4.841 ± 0.205	3.081 ± 0.335
FP200URT	3.809 ± 0.045	5.117 ± 0.158	3.416 ± 0.242
FP400URT	4.329 ± 0.054	5.252 ± 0.116	2.974 ± 0.219
GIF50C	3.453 ± 0.103	3.867 ± 0.260	1.741 ± 0.613
GIF50D	3.407 ± 0.101	3.899 ± 0.213	1.896 ± 0.509

Table II: Pulse width and dispersion values for initial fibre measurements, using a 385 nm pulsed LED source.

the two graded-index fibres show the smallest amount of dispersion; this is exactly the reason they were added for consideration. For the first three step-index fibres, the dispersion increases with increased core diameter. However, it can be seen that the FP400URT, which has the largest core diameter, actually has a smaller amount of dispersion than the FP200URT. Comparing to the maximum timing resolution of a 50 cm ID PMT, which is quoted to be 3.5 ns [15], all fibres display dispersion smaller than this. When comparing to the typical resolution of 2.7 ns, only the FP200URT fibre dispersion is greater by a significant amount.

The same set-up was also used to make preliminary measurements of attenuation in the fibres. As this was an early version of the fibre test stand, an optical power meter was not used. Instead,

the area under the curve of each recorded pulse was used as a proxy, as this is proportional to the total charge collected by the PMT per pulse. Again, 20,000 measurements for each fibre sample were taken, and the results for this are presented in Table III. Again, the results shown here

Fibre	1 m [nVs]	35 m [nVs]	Transmittance [%]
FG050UGA	1.86 ± 0.23	0.75 ± 0.23	40.3 ± 13.3
FG105UCA	7.16 ± 0.62	4.17 ± 0.28	58.2 ± 6.4
FP200URT	16.53 ± 0.99	9.59 ± 0.74	58.0 ± 5.7
FP400URT	23.56 ± 1.14	19.24 ± 0.94	81.7 ± 5.6
GIF50C	4.61 ± 0.69	4.09 ± 0.59	88.7 ± 18.4
GIF50D	2.39 ± 0.57	0.56 ± 0.24	23.4 ± 11.5

Table III: Area-under-curve measurements from oscilloscope for 1 m and 35 m fibres, with calculated transmittance values.

are unsurprising for the step-index fibres, with the transmittance increasing with increased core diameter. It can also be seen that the recorded values through the 1 m patch cable increase with increasing core diameter; this shows the difficulty of coupling particularly narrow-core fibres to an LED, which generally have a wide opening-angle for the light profile. The results obtained for the two graded-index fibres are seen to be very different, which is potentially related to the different bandwidths they're designed for, and the fact they're not specified for a wavelength range below 800 nm. The amount of charge collected from a 1 m fibre for either of these types is again small due to them having a 50 μm core diameter, and suggests as expected that narrow-core fibres are not suitable for the OD LED pulser system.

3.2.2 Results

The results from these initial tests suggest that different fibre types will need to be employed for the ID laser and OD LED systems. For the OD LED system, where coupling the fibre to the LED and maximising light transmission is important, a wide-core fibre should likely be chosen. The FP400URT fibre showed the best transmission and input light acceptance, so this is the candidate that was favoured. For the laser system timing is more important; the dispersion measurements suggested that the graded-index GIF50C and GIF50D fibres were the best candidates here.

As this was a preliminary version of the fibre test stand, and measurements were carried out with fibre lengths significantly shorter than what will actually be installed into Hyper-K, the decision was initially taken to purchase three candidate fibres for further testing. These were FP400URT, GIF50C and GIF50D. Based on estimates of the length required, reels of 40 m and 105 m length were purchased for each of these fibre types. However, it was later understood that the feed-throughs for the injectors would use an FG105UCA patch cable. In order to not add extra inefficiencies to the system in coupling different fibres to one another, the ideal scenario would be to use this fibre for the laser system. A reel of 105 m for this was also purchased and tested, with results for all four primary candidate fibres described together in the following sections for simplicity.

3.3 Attenuation Measurements

3.3.1 Method

The full laser setup for the HK LI system will feature five or six laser heads, over a range of wavelengths spanning UV to visible. In order to confirm whether attenuation in the candidate fibres is of an acceptable level across multiple wavelengths, LEDs across a series of wavelengths were used for these tests. Those were: 365, 395, 415, 465, 496, 525 and 560 nm. As timing is not relevant to attenuation measurements, and to ensure results were valid by initially getting enough light into the fibres, these LEDs were powered with a DC source.

Measurements were made of the output power from fibres of length 1, 2, 37, 42, 77, 107 and 147 m, where some of these lengths were formed by coupling together multiple fibres of shorter length, and all lengths above 1 m featured two 1 m patch cables in the setup. As a 40 m length of FG105UCA fibre was not ordered, the measurements for this were done at slightly altered lengths. Power measurements were made using an optical power meter, as described in Section 3.1. The longer reels of fibre were purchased without tubing, and it was observed during data taking that there was some level of light leakage into the fibres, causing non-zero readings when the LEDs were not powered. To mitigate this, all measurements were performed with the reels of fibre that were too big to fit inside the dark box wrapped in black sheet.

The power observed after transmission through a fibre of length x can be written as

$$P = P_0 \exp^{-\lambda x}, \quad (1)$$

where P is the observed power after traversing the fibre, P_0 is the initial power, and λ is the coefficient of attenuation, describing how much attenuation occurs per unit length. Taking the natural logarithm of this,

$$\ln P = -\lambda x + \ln P_0, \quad (2)$$

allows a linear fit to be made to data, where the gradient is the coefficient of attenuation, and the y-intercept the log of the input power. The fitted attenuation coefficient can then be used to calculate attenuation in dB for a given fibre length, where in this case a length of 150 m is used:

$$\text{Attenuation (dB/150 m)} = \frac{10}{\ln 10} \times 150 \times \lambda. \quad (3)$$

3.3.2 Results

As a first check of the measurement system, the calculated attenuation values for the FP400URT fibre were compared to those provided in the fibre specifications by Thorlabs. This comparison can be seen in Figure 5, and shows generally good agreement between the two. Values of attenuation stay below 10 dB until just above 400 nm, where the amount of attenuation increases sharply. At the minimum wavelength of 365 nm, attenuation of over 20 dB is observed, suggesting that attenuation values in the UV range will likely be the driving factor for deciding on a fibre type.

The full results for all fibre types are presented in Figure 6, with all values of attenuation again scaled to what would be seen across 150 m of fibre. As was shown for the FP400URT fibre, the amount of attenuation observed in the fibres peaks at the lowest wavelength scanned, 365 nm. At

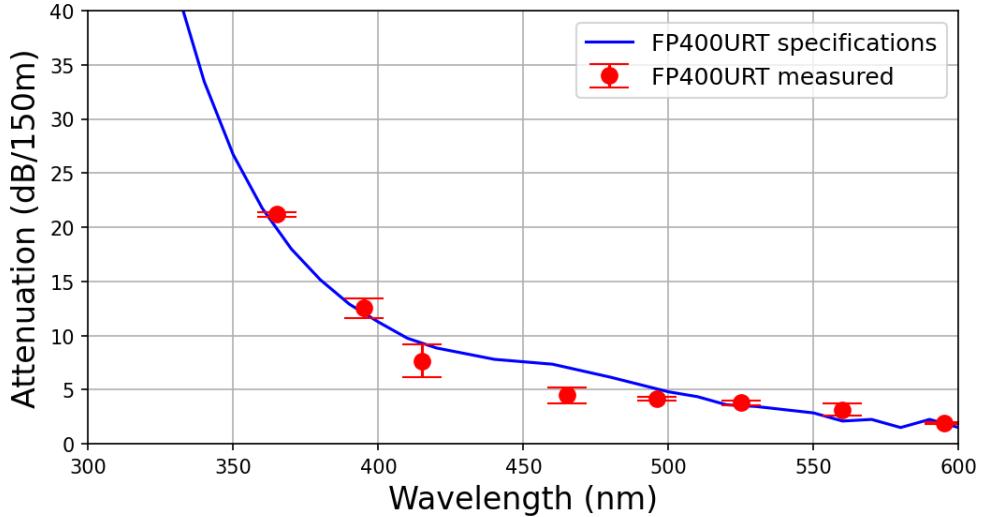


Figure 5: Measured attenuation scaled to 150 m length as a function of wavelength for the FP400URT fibre, compared to specifications from Thorlabs [4].

this value there is a large range of values observed, with the FG105UCA fibre exhibiting the lowest attenuation at under 15 dB. Conversely, the two graded index fibres show much greater attenuation. The spread of values at 395 nm is much reduced, with the two graded-index fibres instead exhibiting lower attenuation here. Above 400 nm, the FG105UCA fibre is seen to consistently exhibit higher attenuation than the other fibres, though in all cases is still below 10 dB. These results suggest that

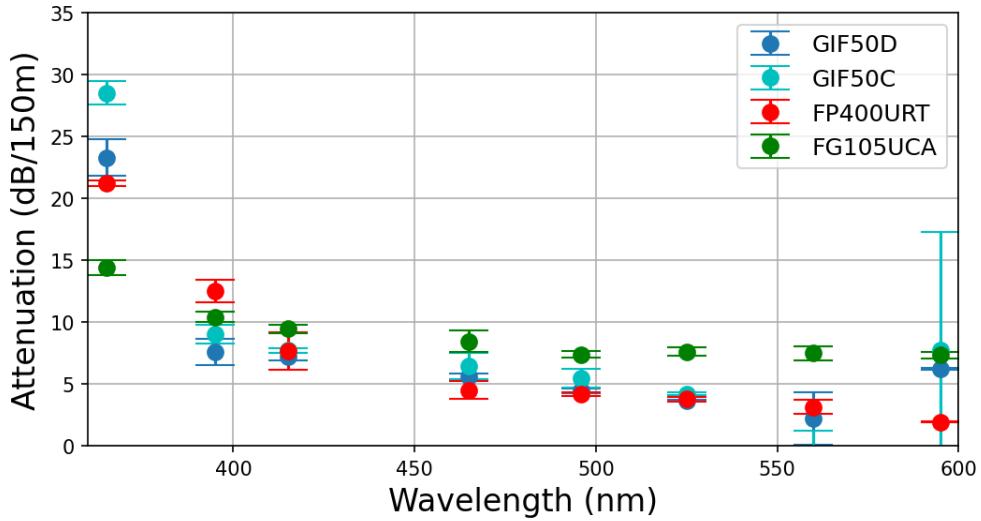


Figure 6: Measured attenuation scaled to 150 m length for all four candidate fibre types, as a function of wavelength.

FG105UCA is the optimal fibre type to use, in terms of attenuation. Although it exhibits higher attenuation in the visible range, there is significantly less observed in the UV range, whereas the other fibre options start to peak sharply in attenuation here. As lower wavelengths of light have been previously observed to be more sensitive to changes in water parameters [16], prioritising lower attenuation in this region should be preferred.

Performing these tests also provided an opportunity to become familiar with handling the fibres.

As was mentioned in Section 3.3.1, the long reels of fibre that were purchased for these tests were done so without tubing, which is generally added in order to protect the fibres. Along with the issues of light leakage previously discussed, during testing it was found that the narrow-core fibres were particularly fragile, with two being broken in the process. The FP400URT fibre however was seen to be far more robust and light-tight. This is attributed to its hard polymer cladding and Tefzel (Teflon-based) coating, as opposed to the clear acrylate used for the graded-index and FG105UCA fibres. Orders of fibre types other than FP400URT will require tubing when ordered for the safety of the system.

3.4 Dispersion Measurements

3.4.1 Method

Similarly to the attenuation measurements described above, by the time the full lengths of fibre had been ordered in, the full fibre test stand had been commissioned. Importantly, this included setup of the laser system described in Section 3.1, which was used as the light source for these measurements. Instead of the $\mathcal{O}(\text{ns})$ input pulse provided by the pulsed LEDs in Section 3.2.1, the laser delivers a pulse of width $\sim 50 \text{ ps}$, meaning measurements would not be limited by this.

Various lengths of each fibre were connected in turn to the laser head, in the same way as in Section 3.3.1. However, due to breakage in the attenuation testing GIF50C was not included in these tests. To make timing measurements, the fibres were connected to the PMT, where the signal was visualised on the oscilloscope. Across 20,000 recorded pulses, measurements were made of the pulse width, negative rise time and negative fall time.

In making these measurements, another limitation of the setup became apparent; it was clear from initial measurements that the measured pulse width and rise time were highly dependent on the amount of light detected by the PMT. This was understood to be a limitation caused by the rise time of the PMT; shorter fibres which would deliver more light due to decreased attenuation exhibited longer pulse widths, as the PMT response was not quick enough. In order to get around this, the measurement approach was modified. For each length of fibre tested, the laser intensity was adjusted such that the output pulse would deliver approximately the same peak voltage each time. This should ensure that the rise time of the PMT had no impact on the timing measurements.

Another issue was encountered with this setup. When making measurements with the 1 m patch cable, large tails in the pulses were observed. An example of this for the FP400URT 1 m cable is shown in Figure 7. Here, negative rise time and negative fall time are labelled as fall time and rise time, respectively, due to the inverted nature of the pulse. It can be seen that the very slowly falling tail results in a negative fall time of $6.53 \pm 0.29 \text{ ns}$, despite a negative rise time of only $0.74 \pm 0.02 \text{ ns}$. This results in a measured pulse width longer than those observed for longer fibre lengths, making dispersion incalculable. As the long tails diminish with increased fibre length, it is thought that they are caused by reflections at the fibre coupling faces. In order to not be affected by this, measurements instead focused on the negative rise time of pulses. Unfortunately this still makes dispersion incalculable, but at least gives a way to compare pulse timing for each fibre type.

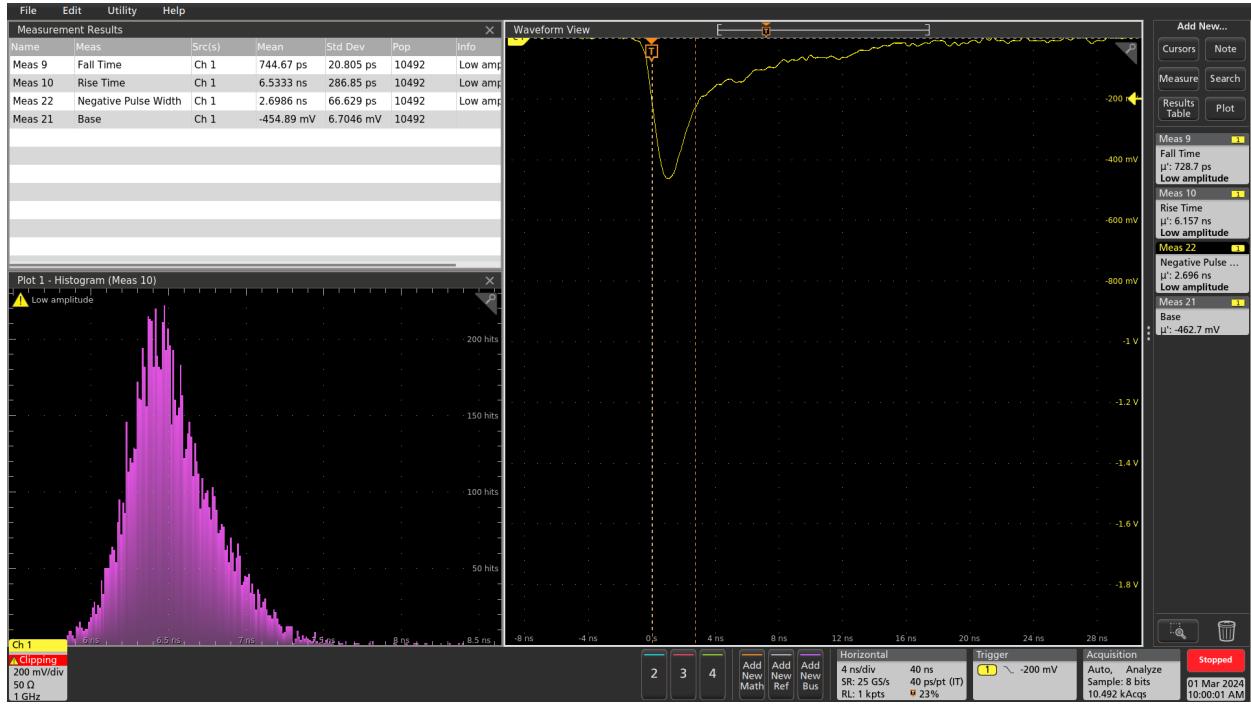


Figure 7: Scope trace and associated measurements for a 1 m FP400URT patch cable, showing the long tail falling tail observed.

3.4.2 Results

The obtained rise time measurements for the three fibre types tested are given in Figure 8. As expected from the preliminary measurements, the fibre which exhibited the least increase in rise time was the graded-index, GIF50D, with an increase of 0.24 ± 0.03 ns. This is closely followed by FP400URT, which shows an overall increase of 0.34 ± 0.03 ns. A comparably higher increase is then observed for the FG105UCA fibre of 0.60 ± 0.05 ns. An interesting observation in these measurements is that the rise time increase is relatively sharp over the first ~ 50 m, but then plateaus toward the longest distances measured. This suggests that, should fibres be required to be longer than those tested, there should not be a substantial increase in rise time over what has already been observed.

While these measurements give a good estimate of how timing will increase over large lengths for each fibre type, it will be important to confirm exact dispersion measurements for the chosen fibre type. As such, a high frequency readout system is currently in development, so that these measurements can be made at a later time.

3.5 Fibre Choice

Unfortunately, the results from both the attenuation and dispersion tests are diametrically opposed; while the graded index fibres performed best in terms of dispersion and pulse rise time increase, they exhibited the greatest amount of attenuation. The opposite is true for the FG105UCA fibre, with FP400URT performance in the middle for both tests, meaning there is not a single fibre type that is clearly preferred. Specific aspects and requirements of the two separate LI systems should be taken into account to make this choice.

Firstly, it is important to remember that the decibel scale is logarithmic, meaning that the

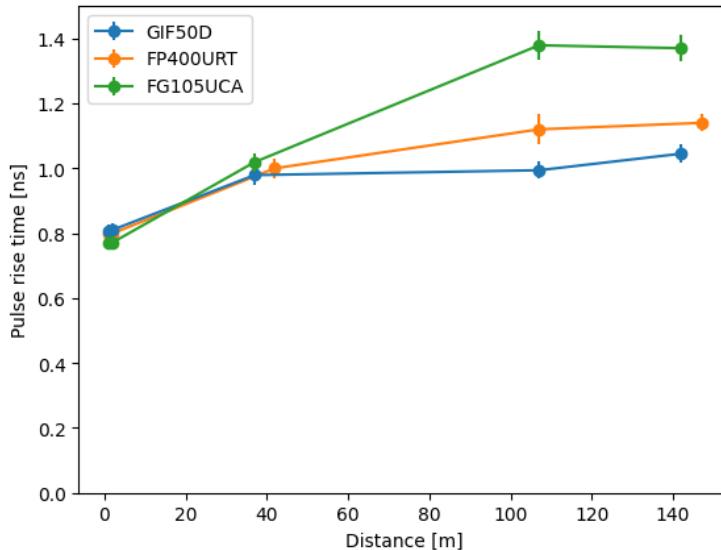


Figure 8: Pulse rise time measurements for three candidate fibres, across a range of lengths.

~ 10 dB difference between the FG105UCA and FP400URT/GIF50D fibres observed at 365 nm represents an additional $\mathcal{O}(10)$ times power loss. Therefore, the differences observed in attenuation are much greater than for the pulse width measurement, and as such the former should be prioritised as a basis for fibre decisions. While the GIF50D fibre showed the best results in terms of rise time increase, it showed significantly worse attenuation. Secondly, the ID injectors (and OD collimators) already have an internal patch fibre of FG105UCA. Coupling a wide-core fibre such as FP400URT into this narrow-core fibre will result in significant light loss at the connection point, and so should be avoided. Therefore, on balance, the FG105UCA narrow-core step-index fibre is judged to be the optimal choice for the laser system. However, the initial results for the 1 m patch cables given in Table III make it clear that coupling an LED to such a small core diameter fibre is difficult. As such, the choice for the OD LED system is the FP400URT fibre, which has a four times wider core and the next best attenuation results.

4 Fibre Switching Device

4.1 Overview

As was mentioned in Section 2, the ID laser system will require dedicated fibre switching devices in order to couple all lasers to all possible channels. To that end, two potential companies that manufacture fibre switching devices were identified, and test devices in a 1x4 configuration were purchased for evaluation. From the first company, Agiltron [17], a single 1x4 device was purchased with FP400URT as the internal fibre. A second company, Weinert Industries [18] supplied two 1x4 devices; one of these contained FP400URT fibre, while the other used GIF50C. All three devices are controlled via USB. It should be noted that only two companies could be found that could supply these kinds of specialist devices.

4.2 General Comparisons

To understand the performance of the three test switches, power measurements were made comparing the output power from each of the four ports to a reference fibre of the same type. For the reference fibre measurements, two 1 m patch cables were coupled together to make a 2 m cable, with the total cable length of each of the switches being around this length.

Measurements were made using the 371 nm laser as the light source. The power meter was used to make measurements across 20,000 readings, where each of the four fibre outputs on a switch were selected and coupled to in turn. Power readings and calculated transmission percentages for the Agiltron FP400URT switch are given in Table IV. The results obtained show generally

	Agiltron FP400URT		Weinert FP400URT		Weinert GIF50C	
	Power (μW)	% of ref.	Power (μW)	% of ref.	Power (μW)	% of ref.
Reference	9.58 ± 0.01	100	9.67 ± 0.01	100	9.69 ± 0.01	100
Port 1	8.93 ± 0.01	93.11 ± 0.14	7.41 ± 0.01	76.64 ± 0.13	9.49 ± 0.01	98.09 ± 0.20
Port 2	8.67 ± 0.01	90.55 ± 0.14	7.41 ± 0.01	76.64 ± 0.13	9.59 ± 0.01	98.83 ± 0.20
Port 3	8.71 ± 0.01	91.06 ± 0.14	7.27 ± 0.01	75.18 ± 0.13	9.36 ± 0.01	96.70 ± 0.20
Port 4	8.66 ± 0.01	90.50 ± 0.14	7.00 ± 0.01	72.39 ± 0.13	9.23 ± 0.01	95.30 ± 0.20

Table IV: Power transmission across the 1x4 switching devices, with comparison to a reference cable of the same type as the device internal fibre.

good power transmission for all three devices tested, albeit with clearly better transmission for the Agiltron FP400URT and Weinert GIF50C than for the Weinert FP400URT. This may be in part due to the fact the fibre on the Weinert FP400URT is longer than the others (and the 2 m reference), measuring approximately 2.3 m in total. It should be noted here that, at least for the Weinert switches, any switch with more than four outputs is formed by daisy-chaining together 1x4 switches. For example, a 1x16 switch would be constructed by connecting the four output channels of a single 1x4 switch into the inputs of four additional 1x4 switches. Therefore for the required 1x6 and 1x80 switches, these losses will be experienced up to six times in total. It is unclear whether the Agiltron switch is constructed in the same manner.

The variation in output power between ports is also generally low across the devices, with a difference of 2.61% for the Agiltron FP400URT, 4.25% for the the Weinert FP400URT and 3.53% for the Weinert GIF50C. These results suggest that the Agiltron device minorly outperforms the Weinert devices in terms of power variation across ports, whilst the Weinert GIF50C was best for transmission.

During ordering, setup and testing of these devices, we experienced very different degrees of assistance from the two companies. While this is not a quantifiable metric, it is none the less very important to keep in mind when making a decision for the full fibre system. The Agiltron switch arrived with no documentation on how to set up and run the device. The correct way of doing this was eventually understood out after several emails to the supplier. The Weinert switches on the other hand arrived with full documentation, along with a simple software package for operation. All email communication with them throughout the ordering and testing process has been very helpful, if somewhat slow at times.

The LI system is a critical component of the HK calibration programme, and will need to run for many years. It is crucial that support is available from the manufacturer of significant

components such as the fibre optic switch, should anything go wrong during its lifetime. The experience of working with Weinert was significantly better, and this should be kept in mind when selecting which device to proceed with. In particular, should issues arise with hardware in the future, it would be significantly easier to deal directly with the manufacturer, rather than going through a third-party distributor as with Agiltron.

4.3 Cross-talk Measurements

While making the transmittance measurements shown in Table IV for the Agiltron device, it was noted that small non-zero readings were being made by the power meter whilst connected to ports that were not currently being illuminated. These persisted after turning off the laser and re-zeroing the power meter, and suggested some crosstalk between fibres. This is of course something that should be avoided, as only one injector should be illuminated within the tank at a time.

In order to confirm this was the case and measure the level of crosstalk for these devices, four power meters were set up, with one connected to each of the four ports on a switch, and all re-zeroed at the same time. A simple python script was used to loop through the four ports 1000 times, before stopping at each port in turn and taking readings for ~ 10 s. This was repeated for runs of approximately 18 hours per fibre switching device. Data was analysed by stripping out data points from the rapidly varying periods, as well as the first and last point of each sustained period where the device may still have been switching and thus not illuminating the port for the entire time taken for one reading.

Data from this test is shown in Figures 9, 10 and 11 for the Agiltron FP400URT, Weinert FP400URT and Weinert GIF50C switches, respectively. Each of these shows data taken by the power meters when the port was a) illuminated and b) not illuminated. These plots show a subset of the full data-taking runs in order to better show the observed structure. Figures 9a, 10a and 11a, which show the readings from illuminated ports, show a similar level of variation to the data presented in Table IV. The most interesting result is seen in Figure 9b, which shows clear

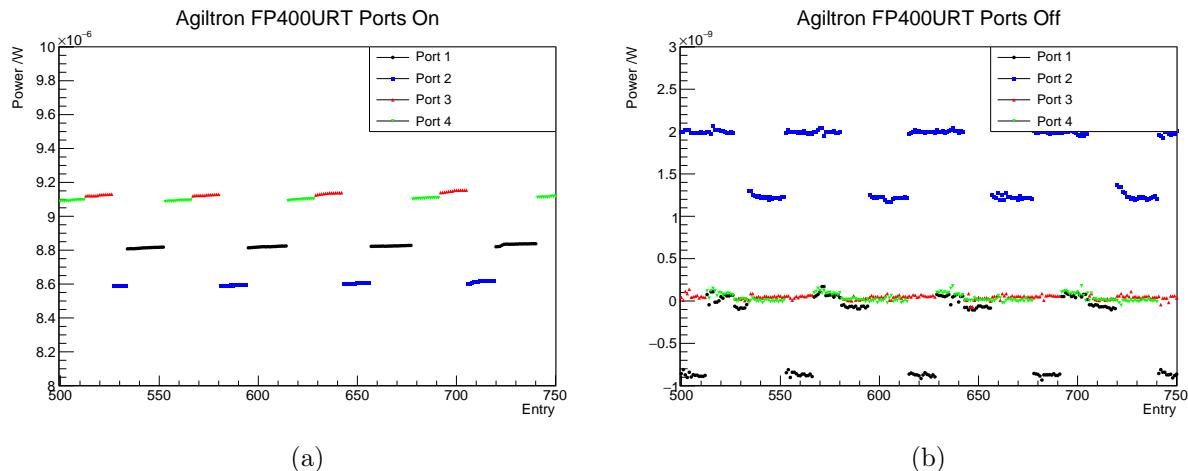


Figure 9: Power meter readings from all four ports for the Agiltron FP400URT device, zoomed into a shorter period of data to better show structure. Data is shown for when ports are a) illuminated and b) not illuminated. Note the different y-axis scales.

changes in the power readings recorded on ports 1 and 2, when these ports are not illuminated.

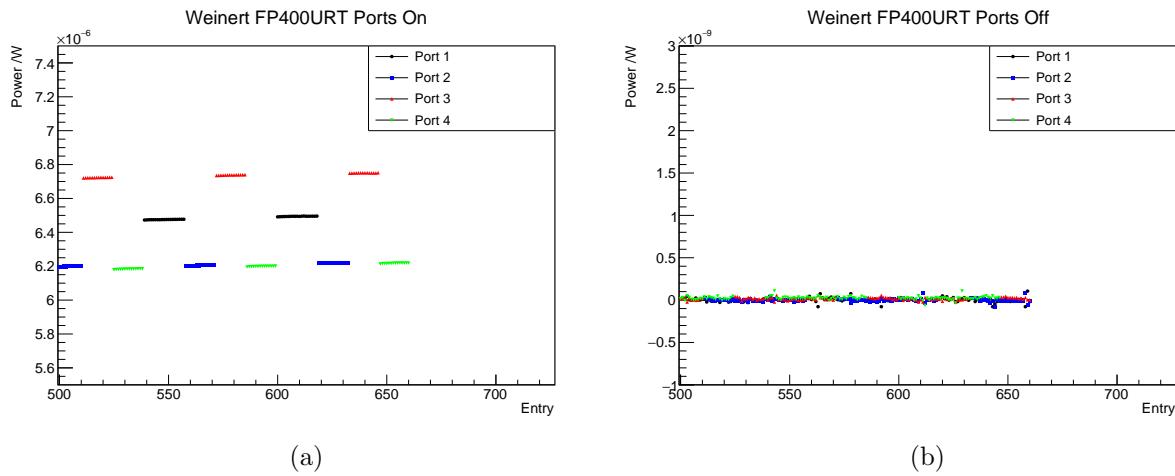


Figure 10: Power meter readings from all four ports for the Weinert FP400URT device, zoomed into a shorter period of data to better show structure. Data is shown for when ports are a) illuminated and b) not illuminated. Note the different y-axis scales.

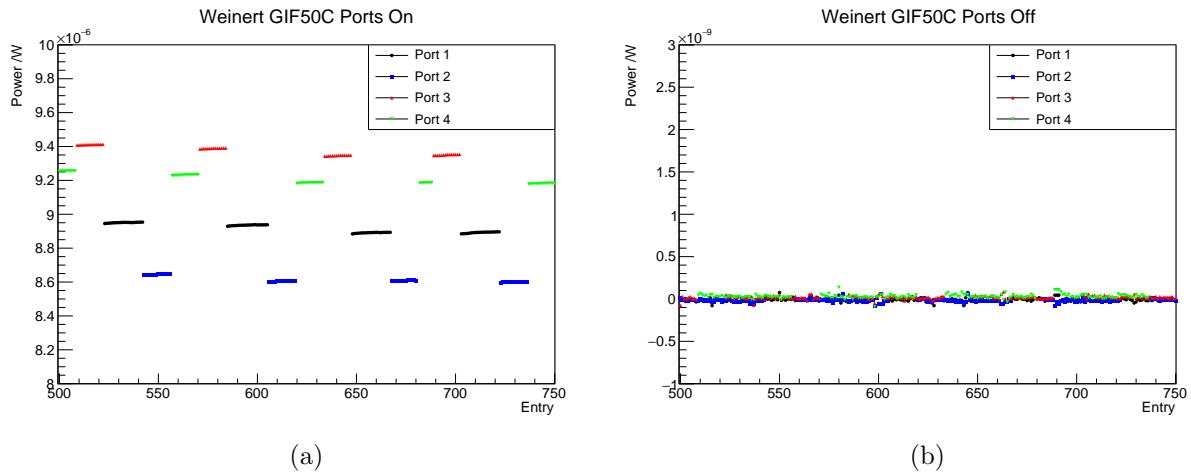


Figure 11: Power meter readings from all four ports for the Weinert GIF50C device, zoomed into a shorter period of data to better show structure. Data is shown for when ports are a) illuminated and b) not illuminated. Note the different y-axis scales.

There is also a repeating structure to the data from port 4 suggesting a lower level of crosstalk to that channel. This suggests varying levels of crosstalk between different ports. Figures 10b and 11b on the other hand show no measurable cross talk between any of the channels.

To further investigate this, the way the data is plotted was inverted. The four plots in Figure 12 show the power recorded on a specific port, each separated by which of the other three ports was illuminated at the time. While the absolute value of the power is not expected to be exactly zero due to global drift caused by temperature changes in the lab over the course of data taking, all four power meters were calibrated at the same time, so should show the same level of power when not illuminated. This is clearly not the case for ports 1 and 2 (Figures 12a and 12b), with the former showing higher power readings when port 2 or port 3 were illuminated, and the latter showing the same when port 3 or port 4 were illuminated. There is also a small offset observed for port 4 in Figure 12d, when port 3 is being illuminated. Interestingly, no obvious cross talk was observed to

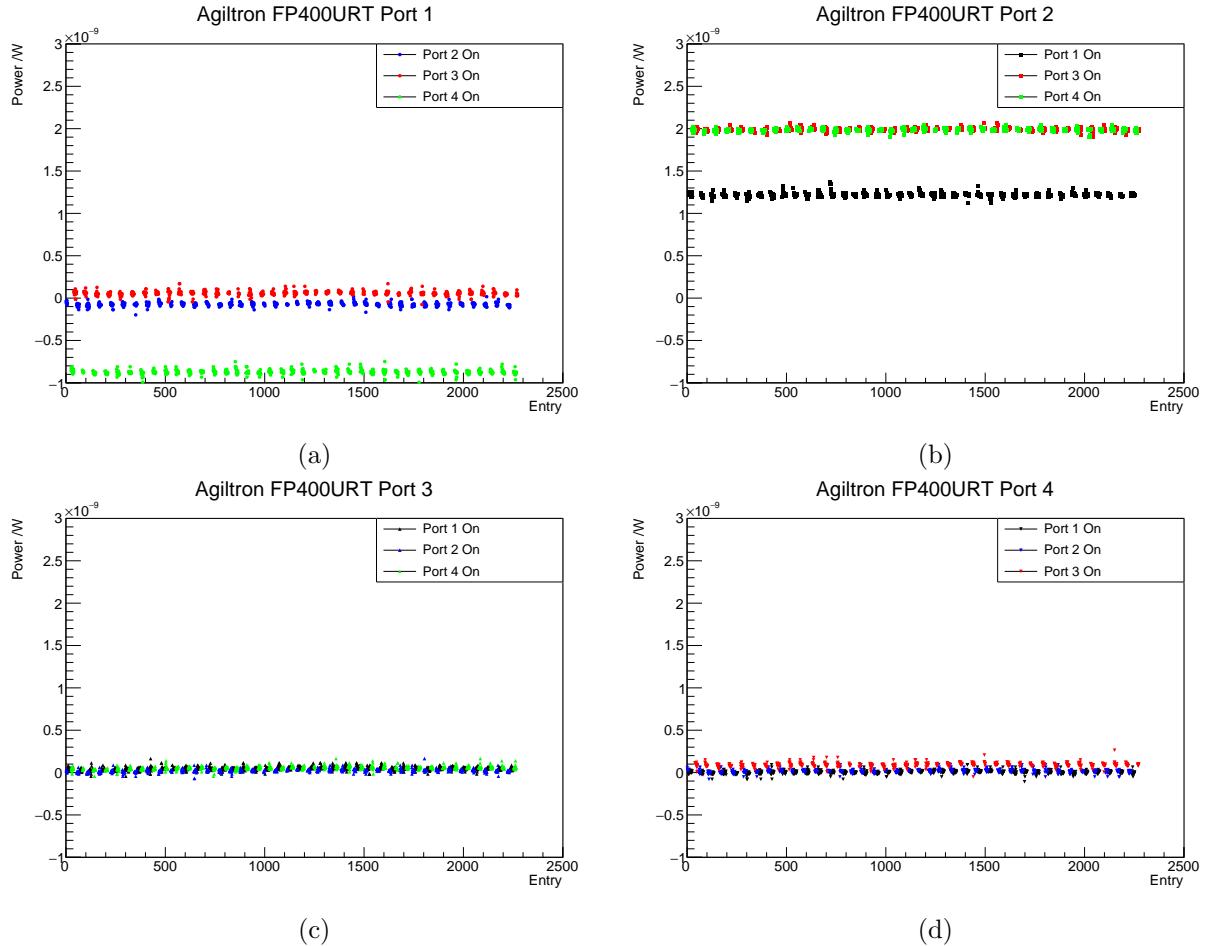


Figure 12: Power recorded on a) port 1, b) port 2, c) port 3 and d) port 4 of the Agiltron FP400URT switch, when one of the other three ports was illuminated.

port 3, from any of the other ports being illuminated.

As no cross talk was observed for either of the Weinert devices, the corresponding plots are not shown here, but are given in Figures 19 and 20 in Appendix A for completeness.

4.4 Summary

Testing of the three different fibre switching devices finds different devices come out best based on different factors. The Weinert GIF50C device showed best power transmission, with at most 4.7% loss compared to the reference fibre, while the Weinert FP400URT device showed up to 27.6% loss. This is with the caveat that the device package was different, and the latter had a greater length of fibre than both the other devices and the reference fibre used. All devices exhibited under 5% variation in output power across the four ports, with the Agiltron switch showing the least variation at a difference of 2.61%.

A clear preference for the Weinert devices comes from the cross talk measurements, which show measurable cross talk between certain channels on the Agiltron device. While this is at the level of $\mathcal{O}(0.1\%)$, the lack of any measurable cross talk from either of the Weinert devices is clearly preferable. Coupled with the superior support from Weinert which will make setup and potential servicing of the hardware easier, this is the device that is preferred. The internal fibre will of course

be chosen to match what is used for the rest of the laser system, so will be Thorlabs FG105UCA or equivalent.

5 Fibre Length Requirements

With the large number of injectors being employed for the light injection system, an even larger number of fibre optic cables will be required. This section details the quantity and lengths of cables required to connect the full HK LI system.

The overall design of the HK water tank and PMT support structure is given in Figure 13. Fibre optics will run through specifically installed fibre ports around the edge of the dome floor into the OD, then down to each injector location. 16 of these fibre ports are distributed roughly evenly

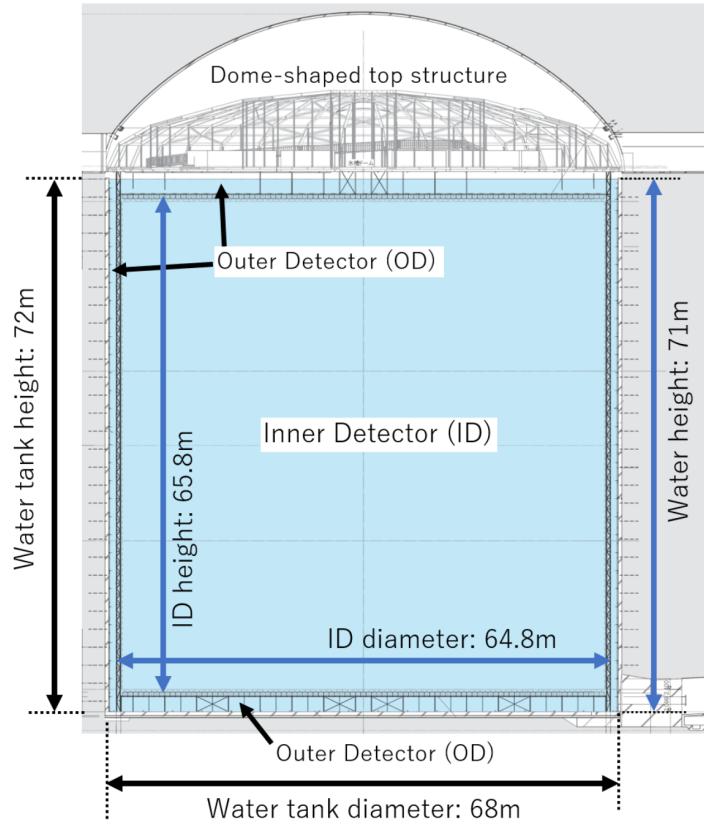


Figure 13: Schematic of the HK water tank and PMT support structure.
[19]

around the outer edge of the dome. The full schematic of the dome showing all calibration and fibre ports is given in Figure 14. The OD fibre ports in question are those marked with magenta dots and labelled “odf” (OD(ファイバー用)).

Although the injector layout described in Section 2 equates to a large range of required lengths, all fibre optic cables will be kept the same length, such that there is no offset in injection timing between injector locations due to the fibre path lengths. As a result, the required length of fibre optic cable is dictated by that needed to reach the injector located at the centre of the bottom end-cap. In order to be most accessible from all fibre ports, the electronics racks for the LI system will be located near the centre of the dome, next to the ID fibre port (labelled “Bidf”, light pink,

in Figure 14). This is the calibration port used to deploy an ID diffuser and collimator to the top end-cap, mentioned in Section 2. Rather than run single lengths of fibre optic cable from injectors to the electronics rack, each required length will be split in two, with patch panels to connect the two parts near the OD fibre ports. The reason for doing this is to allow for replacement of fibres in case of breakage. The parts on top of the dome (out of the water) are more at risk of being damaged by people passing by or nearby work being done, no matter how much care is taken around them. If a single fibre running all the way to an injector in the tank were to break, it would be impossible to replace. However if the fibre outside of the tank is separate, the damaged part can be easily replaced, without having to touch the part that extends into the tank.

Assuming the fibre optic cable runs along the outer side of the PMT support structure, and can only run in orthogonal directions along the bottom end-cap, a total length of 116.8 m is required to reach from the middle of the bottom end-cap to one of the OD fibre ports. In reality, the number and position of the OD fibre ports means it is unlikely that a fibre would have to take the longest possible orthogonal path to the centre, and thus this number is treated as the maximum possible length required. In order to allow additional contingency and for the fibre to reach out of the port to a patch panel, this can be rounded to 120 m. The fibres of this length used to connect to ID injectors (and OD collimators) will require FC/PC connectors on both ends. For the OD diffusers however, the fibre is to be connected to the diffuser simply by pushing into the housing, so these will require one end to have no connector. The end without the connector will still require cleaving and polishing to minimise reflections at the surface.

The second part of this fibre is that which runs across the top of the tank to the electronics rack. As mentioned previously, the rack will be positioned near the ID fibre port, which is approximately 3 m from the centre of the dome. In order to estimate the required fibre length, it again has to be assumed that the fibre cannot take the shortest radial path to the centre, and rather has to travel orthogonally to navigate obstacles. Using a water tank radius of 33 m, this gives an orthogonal distance of 46.68 m. An addition of 5 m **maybe don't need this much** to reach the electronics rack can be added, and the final requirement of 51.68 m rounded to 55 m to again ensure contingency and not require the fibre to be completely taught. In order to connect to both the patch panel and the electronics rack, these fibres will require FC/PC connectors on both ends.

To connect to the ID injectors, an additional patch fibre is also required. ID injectors will be installed on the PMT support structure during construction, while the fibre installation will be carried out after construction of the structure has been completed, by utilising the OD gondola. In order to avoid workers having to reach far out of the gondola, through the support structure, to attach fibres to the injector housing, short patch fibres will be attached to the injectors at the time of their installation. These will span the dead region and be fixed to the outer side of the structure, so that the long fibres can be connected directly to the patch fibres. As part of this a fibre guide will be used, to ensure that the end of the fibre will be pointing vertically upwards for connection, without the fibre being pushed past its bending radius. **Work is ongoing to establish the exact design of this fibre guide, but with a dead region depth of 0.6 m it is expected that a patch cable of 1 m length will be sufficient. These again will require FC/PC connectors on both ends.** Finally, four additional patch cables will be required for connections between the two fibre switchers. The lengths of these are estimated at 30 cm. Exact specifications of chosen fibre splitters and neutral density filters will dictate the connections needed, but as a standard connector type FC/PC is

assumed for now.

A series of short patch fibres will also be required for the LED system. Each LED pulser board will feature a connector sitting atop the surface mounted LED, with space for two fibres to be inserted. One of these will be directly above the LED to collect as much light as possible, and this will be used for illuminating the OD diffusers. The second will be offset, collecting some of the remaining light to be used as a signal for monitoring purposes. As the monitor system will sit at the electronics rack, much less fibre will be used and therefore less initial light input is required. **The design for the the fibre connector is currently ongoing, and will be used to confirm the required length of the patch fibres within the pulser board crates.** Initial measurements of the required lengths, which are different due to the topology of the connector, give 21.1 ± 1.4 cm and 18.4 ± 0.6 cm, where the uncertainties here are the measured tolerances on the length. Any shorter than this and the cable will not reach. If the cables are longer, they would be required to bend at a greater angle than their specified bending radius, which will cause degradation over the lifetime of the system. As the connector for the LED pulser board will hold the fibres simply by friction, each of these patch cables will require FC/PC connectors on one end, with the other cleaved and polished.

The final set of patch cables for the LED pulser system is that used to connect to the monitor PMTs. The internal patch cable from the LED connector will go into a patch panel on the front of the electronics rack. These patch cables will carry light from that patch panel to a system of several monitor PMTs in the same electronics rack. These will be 1 m long, with an FC/PC connector on the patch panel end, and polished bare fibre at the PMT-facing end.

Table V summaries all the required fibres, detailing the chosen type, length, connectors and quantities needed.

Fibre type	Length (m)	Connector A	Connector B	Quantity	Use
FG105UCA	120	FC/PC	FC/PC	80	Laser underwater cable
FG105UCA	55	FC/PC	FC/PC	80	Laser above water cable
FG105UCA	1	FC/PC	FC/PC	66(?)	Dead region patch cable
FG105UCA	0.3	FC/PC	FC/PC	4	Switch system patch cables
FP400URT	120	FC/PC	Bare	122	LED underwater cable
FP400URT	55	FC/PC	FC/PC	122	LED above water cable
FP400URT	1	FC/PC	Bare	122	Patch cables to monitor PMTs
FP400URT	0.211	FC/PC	Bare	122	LED rack patch cable 1
FP400URT	0.184	FC/PC	Bare	122	LED rack patch cable 2

Table V: List of all required fibres with necessary lengths, connector configurations, quantities and uses.

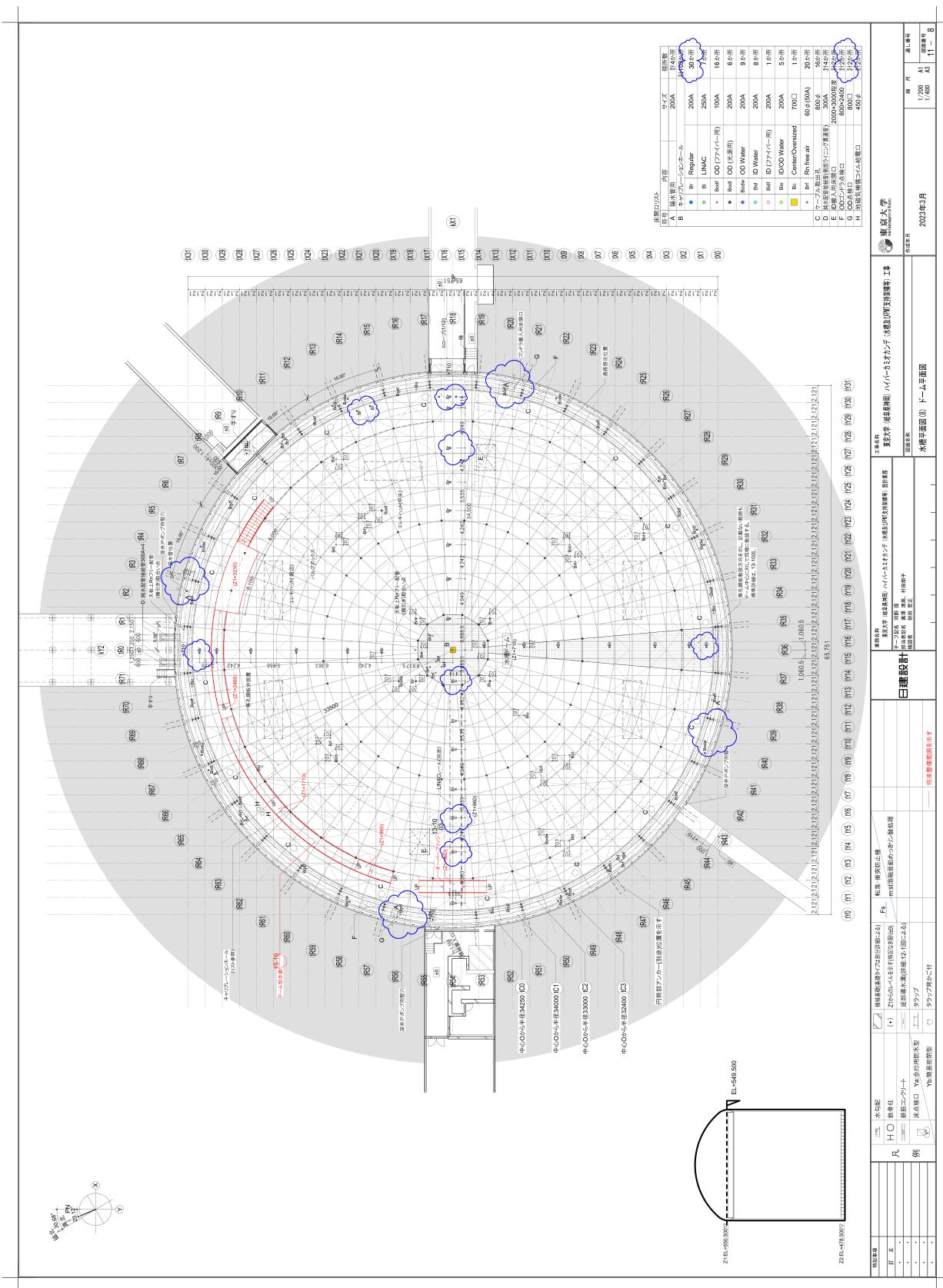


Figure 14: Top down view of the HK experimental area on top of the tank, showing locations of various calibration and fibre ports.

6 Photon Yield Requirements

With a series of points in the system where light can be lost, it is important to verify the number of photons required to be injected into the tank for calibration, and the initial laser power required to achieve this. This section describes the study performed to calculate these required numbers.

A series of simulations were run using the Monte Carlo generation package for Hyper-K, WCSim [20], using diffusers at each vertical depth level (injector indices 0, 4, 8, 12, 16, 20, 24), along with one on the top end cap (28) and one on the bottom (32). For each injector, sets of simulations were run with injected light at wavelengths of 365 nm, 395 nm, 415 nm, 465 nm, 496 nm, 525 nm and 560 nm. These are the wavelengths used for attenuation measurements in Section 3.3.1 and, although not necessarily the exact wavelengths that will be used in the system, allow for explicit calculation of loss factors due to attenuation without interpolating between measurements. Within each of these sets, a number of simulations were run at differing values of injected photons, initially increasing in steps of 200, before moving to larger steps for the higher wavelengths which required greater numbers. For all simulations, 1000 events are run, using nominal water parameters. The injector is treated as an ideal diffuser, with a 40°opening half-angle, and dark noise was disabled.

The aim for general running of the diffusers is 1% occupancy within the diffuser spot, and so this is used as the target for these studies. For each of the 1000 events in a simulation, the number of hit PMTs within the diffuser spot is calculated and histogrammed. This is fit with a Gaussian distribution, and the mean of that taken to be the number of hit PMTs within the spot. An example of this distribution is shown in Figure 15. The obtained mean can then be compared

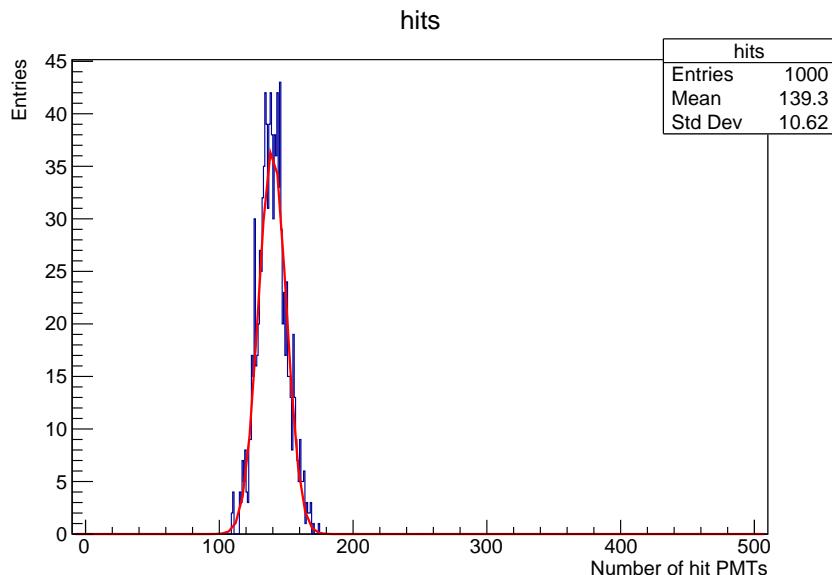


Figure 15: Number of hit PMTs in the spot of diffuser 0, for 1000 injected photons at a wavelength of 365 nm.

to the total number of PMTs within the diffuser spot, to calculate the percentage coverage. This is repeated for all simulations, and compared to the 1% requirement for all injectors to obtain the minimum number of injected photons required.

The coverage percentages for all nine injectors for the 365 nm wavelength are given in Figure 16. The shape of these plots can be understood by thinking about the geometry of the detector. Injectors 0 and 24 are the barrel injectors closest to the bottom and top endcaps respectively, so

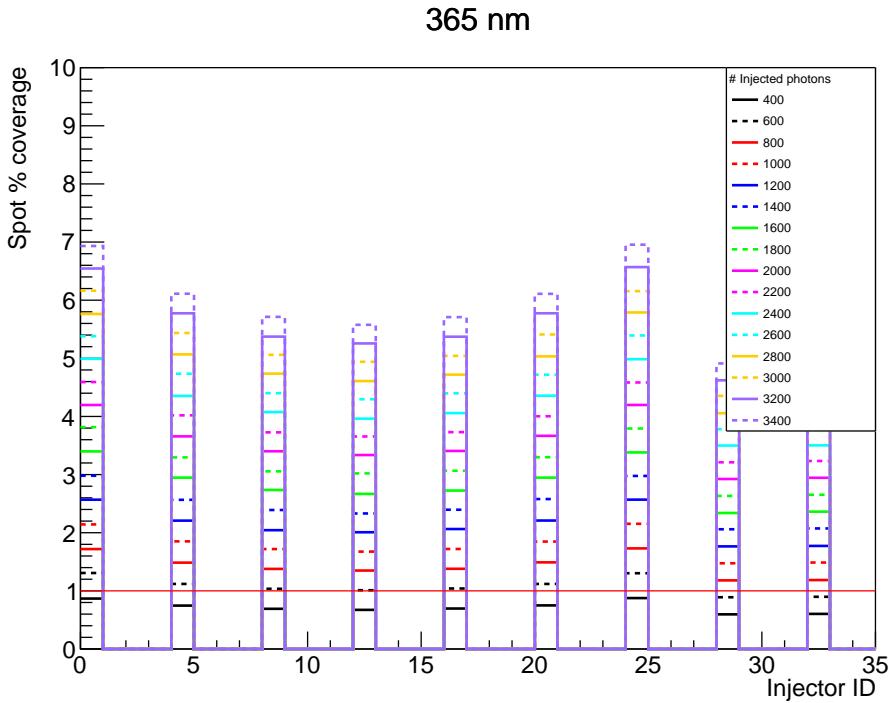


Figure 16: Coverage percentages as a function of diffuser position, for differing numbers of injected photons of 365 nm wavelength. The 1% level is shown by the red line.

those diffusers illuminate a large part of the respective end caps. The shorter path lengths between these injectors and the endcaps results in a greater amount of the initial photons causing hits, and therefore less required for 1% coverage. As the injector positions move towards the middle, there is less to no overlap with the end caps, increasing the average path length to PMTs. The final two injectors, those on the top and bottom end caps, have the greatest distance to the opposite side of the tank. There are therefore more PMTs in the spot, and with the greater distance photons are required to travel, means a greater number of injected photons are needed for 1% coverage. At this wavelength, 800 injected photons are required to obtain at least 1% coverage in all injectors. The behaviour described repeats for all wavelengths checked, making the top and bottom injectors the limiting cases for each.

The approximate number of photons required to achieve 1% spot coverage per wavelength is given in Table VI. These numbers can then be used to calculate the required laser power per wavelength, accounting for loss due to attenuation in the fibres and other points of inefficiency within the system. The attenuation coefficients calculated in Section 3.3.1 for the above wavelengths are used to obtain the attenuation factors for the fibres, assuming the 175 m calculated in Section 5. The fibre is assumed to be the Thorlabs FG105UCA favoured in Section 3.5.

Additional light loss factors are also added into the calculations. An 80% loss is included for the efficiency of the ID diffuser. **Rough value based on conversations with Katharina, this still needs confirming. Update this and calculations when we have a number.** To account for losses in the fibre switch, we use the worst case scenario from the Weinert FP400URT measurements, and assume a 25% loss at each stage of the switch. As any larger switch is formed by daisy-chaining 1x4 switches, this 25% loss can be experienced up to 6 times (twice for a 1x6 switch plus four times for

Wavelength (nm)	N photons for 1% coverage
365	800
395	800
415	1400
465	2400
496	5000
525	19000
560	100000

Table VI: Approximate number of injected photons required for 1% diffuser spot coverage, per wavelength.

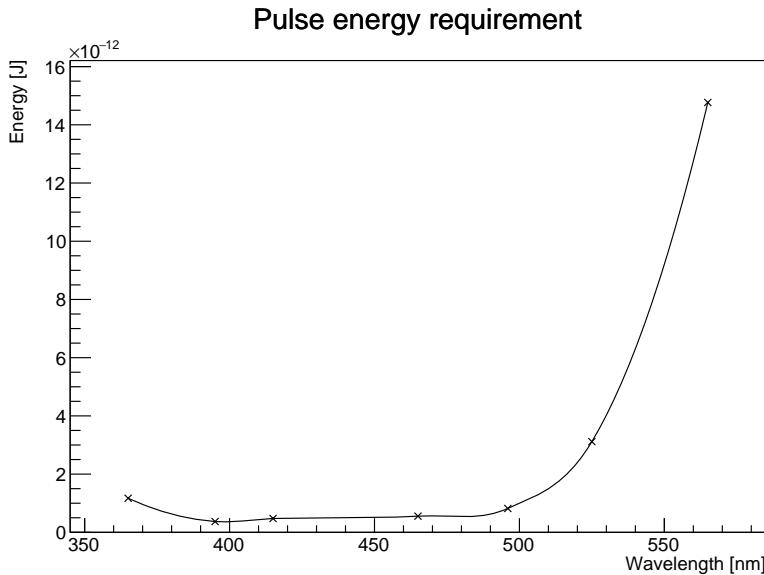


Figure 17: Laser pulse energy as a function of wavelength required to achieve 1% diffuser spot coverage.

a 1x80 switch), resulting in an efficiency of $0.75^6 \simeq 0.18$. As the Weinert GIF50C results showed much greater transmission these numbers are considered conservative, and the final efficiency of the device will depend on the internal fibre used. Finally, a factor of 50% is included to account for any losses in coupling fibres together across the system.

Applying these scaling factors to the requirements in Table VI yields the required number of photons per pulse from the laser, which goes up to at most 4.5×10^7 at 560 nm. This can easily be translated to the required energy per pulse, which is given in Figure 17. Finally, assuming a 1 kHz pulse frequency for occasional intensive calibration runs, the average power required of the lasers at each wavelength is given in Figure 18.

7 Summary

This technical note describes the tests performed on candidate fibre optic cables, which are used to justify the choices made for optimal fibres to use for the ID and OD systems. For the ID system, along with the OD collimators, Thorlabs FG105UCA is chosen. This fibre showed the least attenuation of the four types tested, in the UV wavelength range which is of most interest, and also matches the fibre type that has already been chosen as the internal feed-through for the

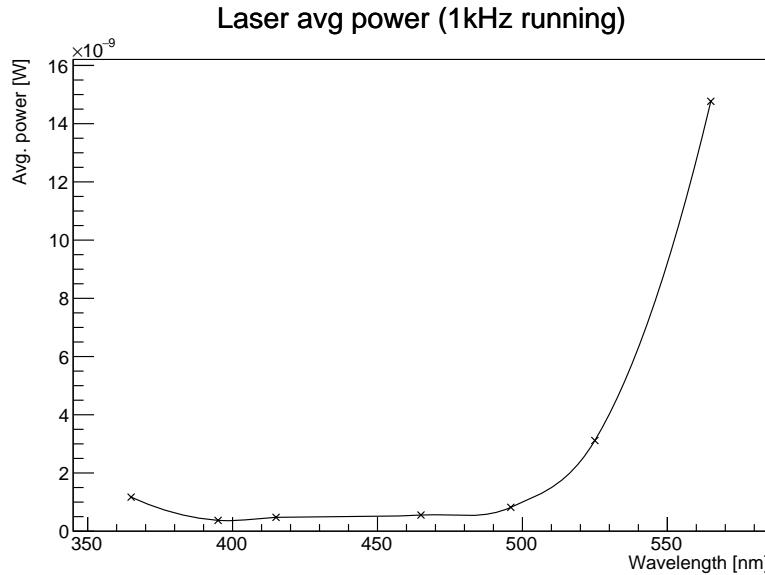


Figure 18: Laser average power as a function of wavelength required to achieve 1% diffuser spot coverage, for 1 kHz running.

optics themselves. This reduces losses that would otherwise be obtained when coupling fibres of different types together. This is the reason for choosing this fibre, despite the fact it exhibits a greater increase in pulse rise time than the other candidates. A high frequency read-out system is currently in development in order to make complete measurements of the dispersion from the full lengths of this fibre, as this is still an important property to understand.

For the OD diffuser system, the fibre of choice is instead Thorlabs FP400URT. While this showed increased attenuation at lower wavelengths when compared to FG105UCA, the advantage of the former fibre type is the diameter being four times greater. This makes coupling an LED to the fibre considerably easier, and ensures a greater amount of light is directed into the fibre in the first place.

A series of measurements of 1x4 fibre switching devices have also been presented, manufactured by two different companies. The results for power transmission found the Weinert device with GIF50C internal fibre to be the best, while for power variation the Agiltron FP400URT device performed slightly better than the others. However, when making power measurements, non-zero power measurements were observed on channels of the Agiltron device that were not being illuminated. Dedicated measurements of this showed cross talk between several different channels on the Agiltron device, whereas no measurable cross talk was found for either of the Weinert devices. Coupled with the fact the support from Weinert was vastly superior, which will be incredibly important for maintaining the device over the lifetime of the experiment, the favoured company is Weinert. The internal fibre will be the same as that used for the ID laser system, and as such should be FG105UCA, as discussed already.

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A Additional Cross Talk Plots

A.1 Weinert FP400URT

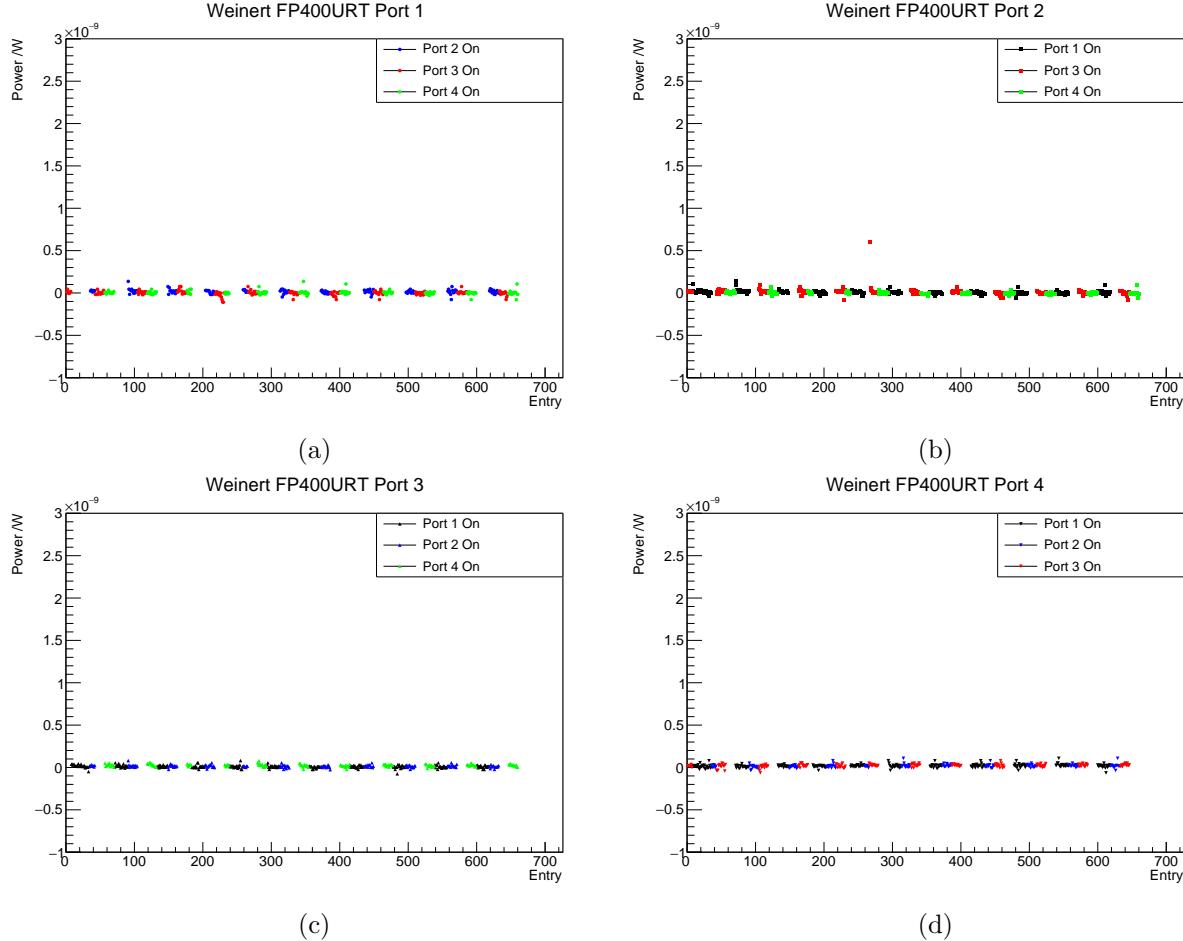


Figure 19: Power recorded on a) port 1, b) port 2, c) port 3 and d) port 4 of the Weinert FP400URT switch, when one of the other three ports was illuminated.

A.2 Weinert GIF50C

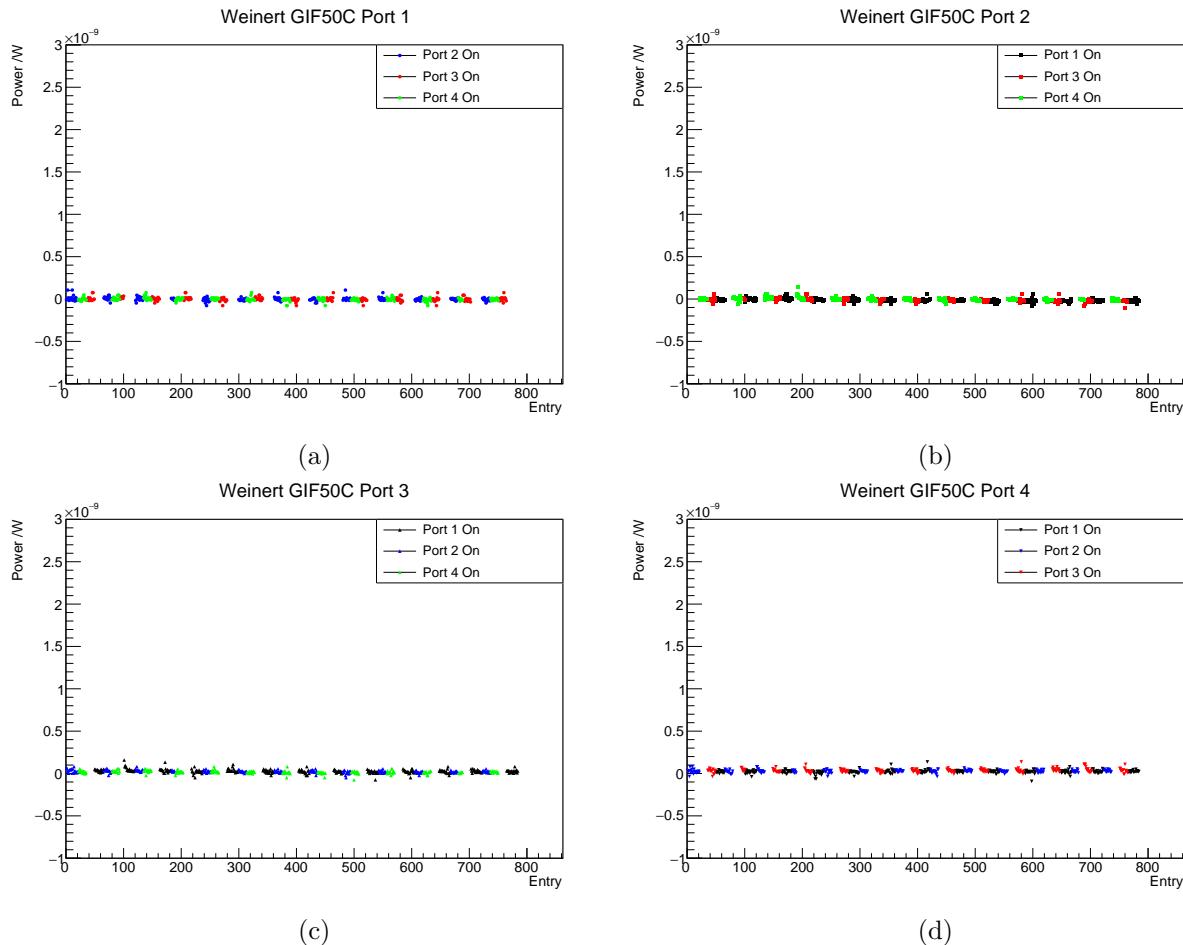


Figure 20: Power recorded on a) port 1, b) port 2, c) port 3 and d) port 4 of the Weinert GIF50C switch, when one of the other three ports was illuminated.