

# 학습 목표

그래프의 너비우선탐색(Breath-First Search) 알고리즘을 학습하고 구현한다



# **Data Structures in Python Chapter 9**

- Graph Introduction
- Graph Traversal BFS
- Graph Traversal DFS
- Topological Sort of DAG

# Agenda

- Graph Traversals
  - BFS Breadth First Search
  - DFS Depth First Search
- Reference:
  - Problem Solving with Algorithms and Data Structures
  - Wikipedia: <u>Breadth-first search</u>

# **Graph Traversals**

- Important graph-processing operations include:
  - Finding the shortest path to a given vertex (source) in a graph
  - Finding all the items to which a given item is connected by paths

#### Breadth-First Search (BFS)

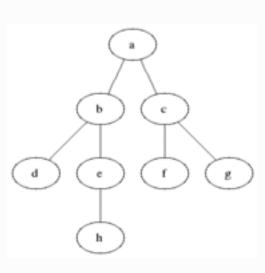
- Idea: Explore from a source in all possible directions, layer by layer.
- It begins at the source vertex and explores its neighbors first.
- Then, it explores their unexplored next neighbors, until it visits the target vertex or all.

#### Depth-First Search (DFS)

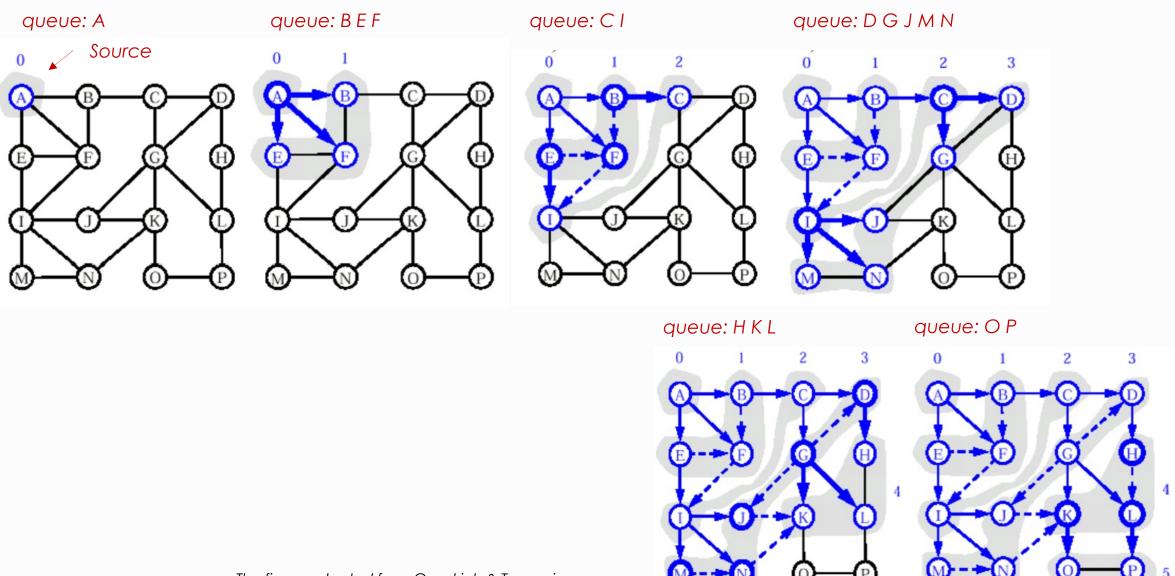
- Idea: Follow the first path you find as far as you can go.
- Then, back up to last unexplored edge when you reach a dead end, then go as far you can.

# **BFS Algorithm**

- It takes the current vertex (the source vertex in the beginning) and then add all its neighbors that we have not visited yet to a queue.
- Continue this with the next vertex in the queue (the "oldest" vertex).
- Set its distance to the distance of the current vertex plus 1 (since all edges are weighted equally), with the distance to the source vertex being 0.
- This is repeated until there are no more vertices in the queue (all vertices are visited).
- It always finds the shortest path if there is more than one path between two vertices.



# **BFS - A Graphical Representation**



## **Example Graph Representation:**

DEN PHX ATL ORD

ATL MCO

DEN LAS

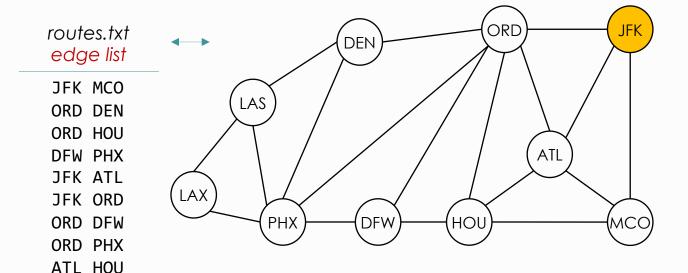
HOU MCO

PHX LAS

LAX PHX

LAX LAS

HOU DFW



```
def addEdge(self, v, w):
    if not self.hasVertex(v): self._adj[v] = list()
    if not self.hasVertex(w): self._adj[w] = list()
        if not self.hasEdge(v, w):
            self._e += 1
            self._adj[v].append(w)
            self._adj[w].append(v)
```

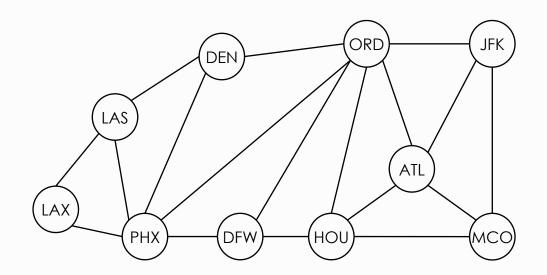
#### Getting each neighbor w of v

```
for w in g.neighbors(v):
```

#### Adjacency list

```
JFK: MCO ATL ORD
MCO: JFK ATL HOU
ORD: DEN HOU JFK DFW PHX ATL
DEN: ORD PHX LAS
HOU: ORD ATL MCO DFW
DFW: PHX ORD HOU
PHX: DFW ORD DEN LAS LAX
ATL: JFK HOU ORD MCO
LAS: DEN PHX LAX
LAX: PHX LAS
```

# Example Graph ADT:



#### Examples of shortest paths in a graph

operation	description
<pre>bfs = BFS(g, s) bfs.distanceTo(v)</pre>	find all shortest paths s in graph g distance between s and v
<pre>bfs.hasPathTo(v) bfs.pathTo(v)</pre>	is there a path between s and v? an iterable for the path from s to v

source	target	distance	<b>a</b> shortest path
JFK LAS	LAX MCO	3 4	JFK-ORD-PHX-LAX LAS-DEN-ORD-HOU-MCO
HOU	JFK	2	HOU-ORD-JFK

# **BFS Algorithm**

#### 1. Initialization

- Initialize the distance to the source vertex s as 0.
- Initialize \_distTo dictionary that stores the distance to s.

  If v exists in \_distTo, it indicates "visited", if not in \_distTo, "unvisited".

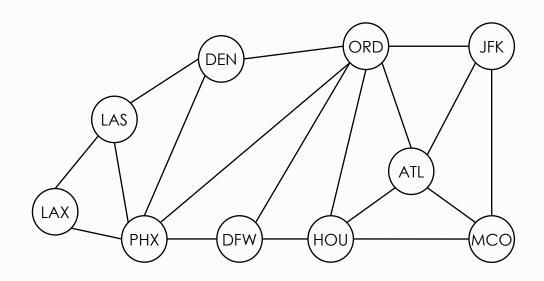
  Initialize \_prevTo dictionary that stores the vertex that one step nearer to the source s.
- 3. Add the first vertex s to the queue.
- 2. While there are vertices in the queue:
  - 1. Take a vertex **v** out of the queue
  - For all vertices w next to it v that we have not visited yet, add them w to the queue, set their distance \_distTo[w] to the distance to the current vertex distTo[v] plus 1 set their \_prevTo[w] to the current vertex v which one step nearer than them w

```
instance variables:
```

#### variables:

```
queue queue of vertices to visit
g graph
s source
v current vertex
w neighbors of v
```

#### **BFS Class**



#### Adjacency list: g.\_adj

JFK: MCO ATL ORD MCO: JFK ATL HOU

ORD: DEN HOU JFK DFW PHX ATL

DEN: ORD PHX LAS

HOU: ORD ATL MCO DFW

DFW: PHX ORD HOU

PHX: DFW ORD DEN LAS LAX

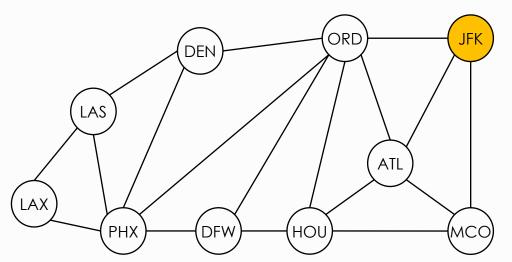
ATL: JFK HOU ORD MCO

LAS: DEN PHX LAX

LAX: PHX LAS

```
class BFS:
   def init (self, graph, s):
        self. distTo = dict()
        self. prevTo = dict()
        self. distTo[s] = 0
        self. prevTo[s] = None
        self. path = []
       queue = deque()
        queue.append(s)
        while queue:
            v = queue.popleft()
           for w in g.neighbors(v):
                if w not in self. distTo:
                    queue.append(w)
                    self. distTo[w] = 1 + self. distTo[v]
                    self. prevTo[w] = v
```

# variables: \_distTo distance to s \_prevTo previous vertex on shortest path from s queue queue of vertices to visit g graph s source v current vertex w neighbors of v



distance 0

```
s = 'JFK'
queue = ['JFK']
_distTo = {'JFK':0}
_prevTo = {None}
```

distance 1

distance 2

Adjacency list: g.\_adj

distance 3

```
JFK: MCO ATL ORD MCO: JFK ATL HOU
```

ORD: DEN HOU JFK DFW PHX ATL

DEN: ORD PHX LAS

HOU: ORD ATL MCO DFW

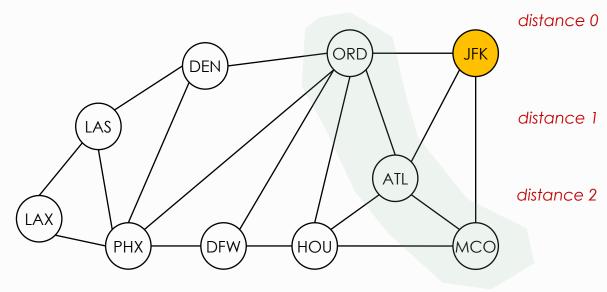
DFW: PHX ORD HOU

PHX: DFW ORD DEN LAS LAX

ATL: JFK HOU ORD MCO

LAS: DEN PHX LAX

LAX: PHX LAS



```
s = 'JFK'
queue = ['JFK']
_distTo = {'JFK':0}
_prevTo = {None}

queue = ['MCO', 'ATL', 'ORD']
_distTo = {'JFK':0, 'MCO':1, 'ATL':1, 'ORD':1}
_prevTo = {'JFK':None, 'MCO':'JFK', 'ATL':'JFK', 'ORD':'JFK'}

Is this order of keys
_in random or fixed?
_prevTo = {'JFK':None, 'MCO':'JFK', 'ATL':'JFK', 'ORD':'JFK'}
```

#### Adjacency list: g.\_adj

JFK: MCO ATL ORD MCO: JFK ATL HOU

ORD: DEN HOU JFK DFW PHX ATL

DEN: ORD PHX LAS

HOU: ORD ATL MCO DFW

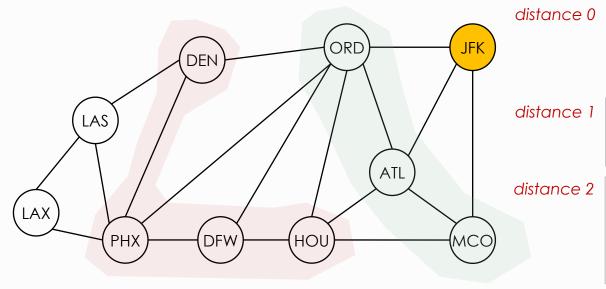
DFW: PHX ORD HOU

PHX: DFW ORD DEN LAS LAX

ATL: JFK HOU ORD MCO

LAS: DEN PHX LAX

LAX: PHX LAS



#### Adjacency list: g.\_adj

JFK: MCO ATL ORD MCO: JFK ATL HOU

ORD: DEN HOU JFK DFW PHX ATL

DEN: ORD PHX LAS

HOU: ORD ATL MCO DFW

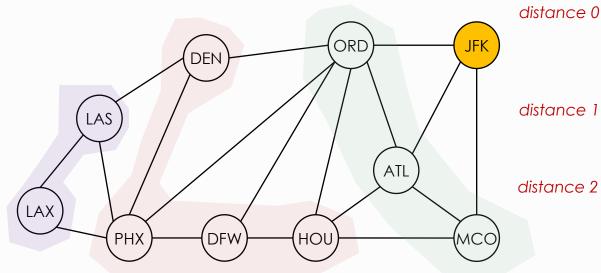
DFW: PHX ORD HOU

PHX: DFW ORD DEN LAS LAX

ATL: JFK HOU ORD MCO

LAS: DEN PHX LAX

LAX: PHX LAS



#### Adjacency list: g. adj

```
JFK: MCO ATL ORD
MCO: JFK ATL HOU
```

ORD: DEN HOU JFK DFW PHX ATL

DEN: ORD PHX LAS

HOU: ORD ATL MCO DFW

DFW: PHX ORD HOU

PHX: DFW ORD DEN LAS LAX

ATL: JFK HOU ORD MCO

LAS: DEN PHX LAX

LAX: PHX LAS

```
distance 0
```

```
s = 'JFK'
queue = ['JFK']
                                   Is the order of queue
distTo = {'JFK':0}
                                   in random or fixed?
prevTo = {None}
```

```
queue = ['MCO', 'ATL', 'ORD']
distTo = {'JFK':0, 'MCO':1, 'ATL':1, 'ORD':1}
prevTo = {'JFK':None, 'MCO':'JFK', 'ATL':'JFK', 'ORD':'JFK'}
```

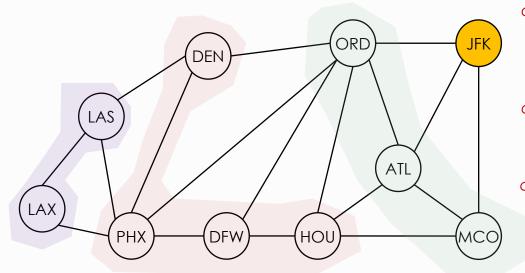
```
distance 2
           queue = ['HOU', 'DEN', 'DFW', 'PHX']
           distTo = {'JFK':0, 'MCO':1, 'ATL':1, 'ORD':1,
                       'HOU':2, 'DEN':2, 'DFW':2, 'PHX':2}
           prevTo = {'JFK':None, 'MCO':'JFK', 'ATL':'JFK', 'ORD':'JFK',
                       'HOU': 'MCO', 'DEN': 'ORD', 'DFW': 'ORD', 'PHX': 'ORD'}
```

#### distance 3

```
queue = ['LAS', 'LAX']
distTo = {'JFK':0, 'ORD':1, 'ATL':1, 'MCO':1,
           'HOU':2, 'DEN':2, 'DFW':2, 'PHX':2,
           'LAS':3, 'LAX':3}
prevTo = {'JFK':None, 'MCO':'JFK', 'ATL':'JFK', 'ORD':'JFK',
           'HOU': 'MCO', 'DEN': 'ORD', 'DFW': 'ORD', 'PHX': 'ORD',
         'LAS':'DEN', 'LAX':'PHX'}
           can it be like the following?
```

**Question:** Explain how it gets the order of airports in the gueue [] at distance 2.

'LAS': 'PHX'



# Adjacency list: g. adj

```
JFK: MCO ATL ORD MCO: JFK ATL HOU
```

ORD: DEN HOU JFK DFW PHX ATL

DEN: ORD PHX LAS

HOU: ORD ATL MCO DFW

DFW: PHX ORD HOU

PHX: DFW ORD DEN LAS LAX

ATL: JFK HOU ORD MCO

LAS: DEN PHX LAX

LAX: PHX LAS

#### distance 0

```
s = 'JFK'
queue = ['JFK']
_distTo = {'JFK':0}
_prevTo = {None}
```

#### distance 1

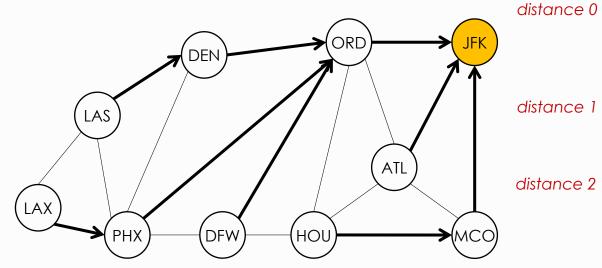
```
queue = ['MCO', 'ATL', 'ORD']
_distTo = {'JFK':0, 'MCO':1, 'ATL':1, 'ORD':1}
_prevTo = {'JFK':None, 'MCO':'JFK', 'ATL':'JFK', 'ORD':'JFK'}
```

#### distance 2

```
• Find the distance to LAX: g._distTo['LAX'] → 3
```

```
    Find the shortest path to LAX: g._prevTo['LAX'] → 'PHX'
        g._prevTo['PHX'] → 'ORD'
        g._prevTo['ORD'] → 'JFK'
        g. prevTo['JFK'] → None
```

# BFS Class Example: JFK shortest paths tree



shortest paths tree

```
distance 0
```

```
s = 'JFK'
queue = ['JFK']
distTo = {'JFK':0}
prevTo = {None}
```

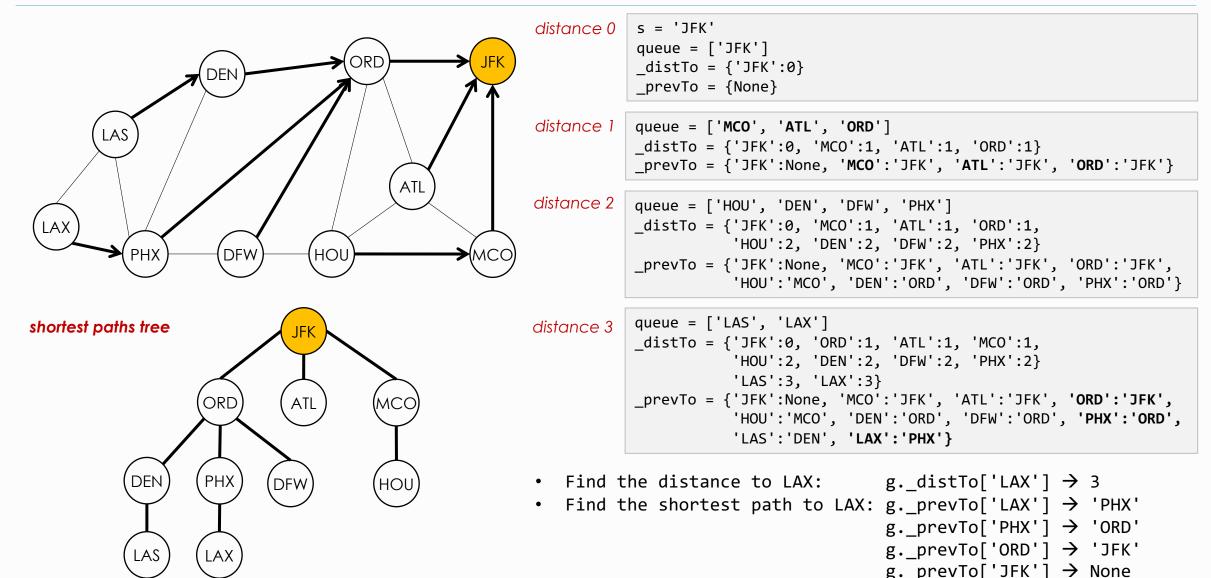
queue = ['MCO', 'ATL', 'ORD'] distTo = {'JFK':0, 'MCO':1, 'ATL':1, 'ORD':1} prevTo = {'JFK':None, 'MCO':'JFK', 'ATL':'JFK', 'ORD':'JFK'}

```
queue = ['HOU', 'DEN', 'DFW', 'PHX']
distTo = {'JFK':0, 'MCO':1, 'ATL':1, 'ORD':1,
           'HOU':2, 'DEN':2, 'DFW':2, 'PHX':2}
prevTo = {'JFK':None, 'MCO':'JFK', 'ATL':'JFK', 'ORD':'JFK',
           'HOU':'MCO', 'DEN':'ORD', 'DFW':'ORD', 'PHX':'ORD'}
```

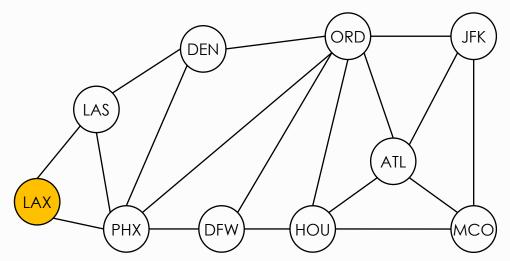
```
queue = ['LAS', 'LAX']
distTo = {'JFK':0, 'ORD':1, 'ATL':1, 'MCO':1,
           'HOU':2, 'DEN':2, 'DFW':2, 'PHX':2}
           'LAS':3, 'LAX':3}
prevTo = {'JFK':None, 'MCO':'JFK', 'ATL':'JFK', 'ORD':'JFK',
           'HOU': 'MCO', 'DEN': 'ORD', 'DFW': 'ORD', 'PHX': 'ORD',
           'LAS': 'DEN', 'LAX': 'PHX'}
```

```
• Find the distance to LAX: g. distTo['LAX'] → 3
• Find the shortest path to LAX: g._prevTo['LAX'] → 'PHX'
                                g. prevTo['PHX'] → 'ORD'
                                g._prevTo['ORD'] → 'JFK'
                                g. prevTo['JFK'] → None
```

# BFS Class Example: JFK shortest paths tree



#### BFS Class Exercise: LAX



```
distance 0
```

```
s = 'LAX'
queue = ['LAX']
_distTo = {'LAX':0}
_prevTo = {None}
```

distance 1

```
queue = ['LAS', 'PHX']
_distTo =
_prevTo =
```

distance 2

#### Adjacency list: g.\_adj

JFK: MCO ATL ORD MCO: JFK ATL HOU

ORD: DEN HOU JFK DFW PHX ATL

DEN: ORD PHX LAS

HOU: ORD ATL MCO DFW

DFW: PHX ORD HOU

PHX: DFW ORD DEN LAS LAX

ATL: JFK HOU ORD MCO

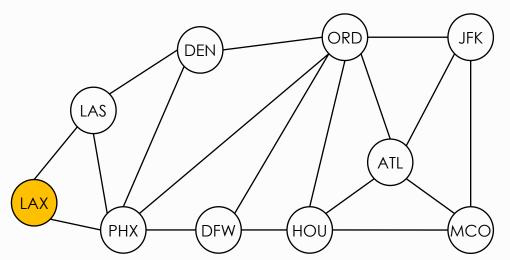
LAS: DEN PHX LAX

LAX: PHX LAS

#### distance 3

- Find the distance to MCO: g.\_distTo['MCO']  $\rightarrow$
- Find the shortest path to MCO: g.\_prevTo['MCO'] →

# BFS Class Exercise: LAX shortest paths tree



```
distance 0
```

```
s = 'LAX'
queue = ['LAX']
_distTo = {'LAX':0}
_prevTo = {None}
```

distance 1

```
queue = ['LAS', 'PHX']
_distTo =
_prevTo =
```

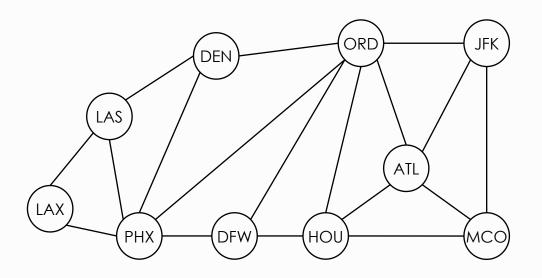
distance 2

shortest paths tree

distance 3

- Find the distance to MCO: g.\_distTo['MCO'] →
- Find the shortest path to MCO: g.\_prevTo['MCO'] →

### **BFS Class**



#### operation

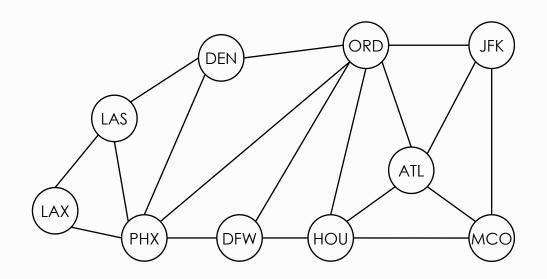
# bfs = BFS(g, s) bfs.distanceTo(v) bfs.hasPathTo(v) bfs.pathTo(v)

#### description

```
find all shortest paths s in graph g distance between s and v is there a path between s and v? an iterable for the path from s to v
```

```
from collections import deque
from graph import Graph
class BFS:
    def __init__(self, graph, s):
    def distanceTo(self, v):
        return self._distTo[v]
    def hasPathTo(self, v):
        return v in self._distTo
   def pathTo(self, v):
        path = []
        while v is not None:
            path += [v]
            v = self. prevTo[v]
        return reversed(path)
```

#### **BFS Class Exercise**



#### operation

#### description

```
bfs = BFS(g, s) find all shortest paths s in graph g
bfs.distanceTo(v) distance between s and v
bfs.hasPathTo(v) is there a path between s and v?
bfs.pathTo(v) an iterable for the path from s to v

bfs.source() return the source vertex
bfs.shortestPaths() print all shortest paths from source
```

```
from collections import deque
from graph import Graph
class BFS:
   def __init__(self, graph, s):
  Shortest Paths from: JFK
  ['JFK']
                      Do it for LAX
  ['JFK', 'MCO']
  ['JFK', 'ATL']
  ['JFK', 'ORD']
  ['JFK', 'MCO', 'HOU']
  ['JFK', 'ORD', 'DEN']
  ['JFK', 'ORD', 'DFW']
  ['JFK', 'ORD', 'PHX']
  ['JFK', 'ORD', 'DEN', 'LAS']
  ['JFK', 'ORD', 'PHX', 'LAX']
   def source(self):
       pass
   def shortestPaths(self):
       pass
```

# **Time Complexity**

- We can obtain the time complexity by counting the number to visit the vertices.
  - The repeats in the while-loop become V in the worst case. The repeats will be the sum of the vertices at most because we only add the vertices not visited.
  - The repeats in the for-loop become 2E in the worst case. The repeats in the only one for-loop will be the degree. So, the repeats in all for-loop will be the sum of the degrees or 2E.
  - Therefore, we get the time complexity of the breadth-first search as O(V + E).

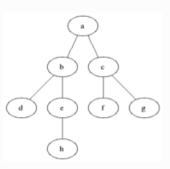
#### Handshaking lemma:

The sum of all the degrees always doubles as the sum of all edges for undirected graph.

$$\sum_{v \in V} deg(v) = 2|E|$$

# **Summary**

- BFS(Breadth-First Search) traverses by adding any each one of the graph's vertices at the back of a queue, starting from the source vertex.
- BFS always finds the shortest path if there is more than one path between two vertices.
- The time complexity of BFS is linear, O(V + E).



# 학습 정리

- 1) 그래프의 너비우선탐색(Breadth-First Search)은
  - Step 1: 탐색 시작 노드 v를 큐에 삽입하고 방문 처리를 한다
  - Step 2: 큐에서 노드 v를 꺼내 그 노드의 인접 노드 중에서 방문하지 않은 노드를 모두 큐에 삽입하고 방문 처리한다
  - Step 3: Step 2의 과정을 더 이상 수행할 수 없을 때까지 반복한다
- 2) BFS로 최단 거리 경로를 찾을 수 있다
- 3) BFS의 시간 복잡도는 O(V + E)이다



# BFS Class Example: JFK shortest paths tree

```
_prevTo = {
'JFK':None,
'MCO':'JFK', 'ATL':'JFK', 'ORD':'JFK',
'HOU':'MCO', 'DEN':'ORD', 'DFW':'ORD',
'PHX':'ORD', 'LAS':'DEN', 'LAX':'PHX'}
```

# DEN ORD JFK LAS PHX DFW HOU MCO

#### shortest paths tree

