Future Vehicle Education Workshop

Subject: Environment Setting

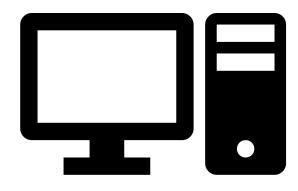
Automation Lab.



■ PC Hardware Environment



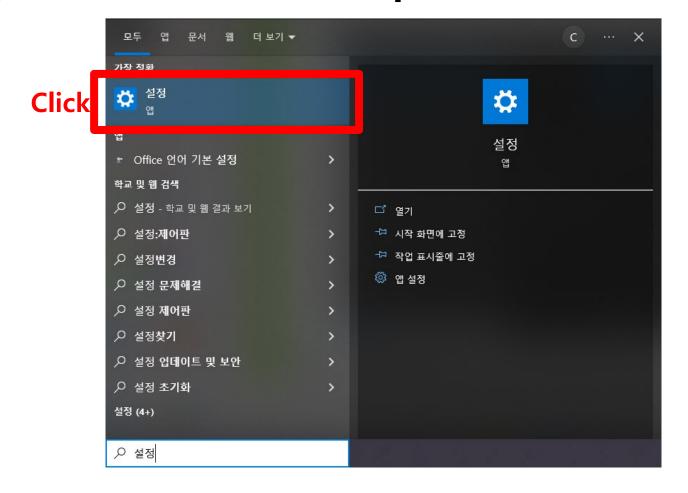
Operating System: Window10



Architecture: x86, x64

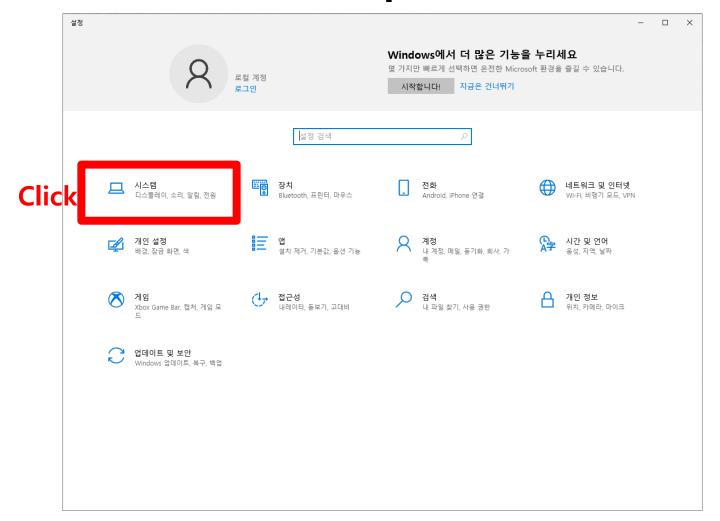


■ Check your PC's hardware specifications



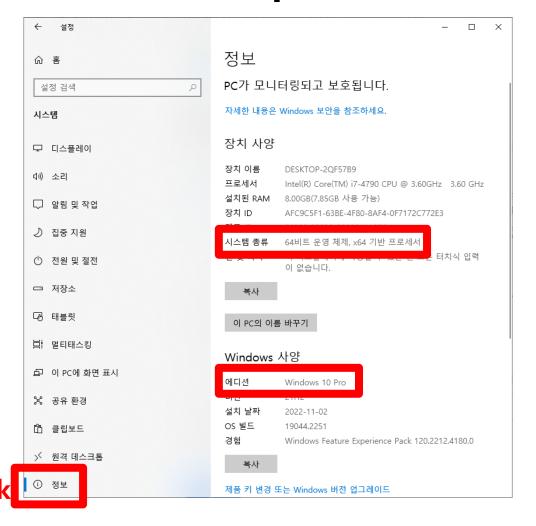


■ Check your PC's hardware specifications





■ Check your PC's hardware specifications





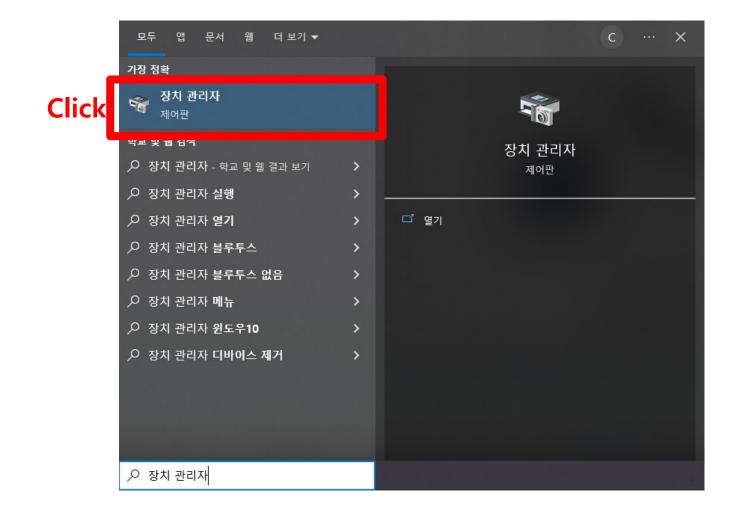
■ LiDAR



Connect the short wire to the PC



■ Verify Lidar Device Connection





■ Verify Lidar Device Connection



Other Device CP2102 USB Recognition Checks

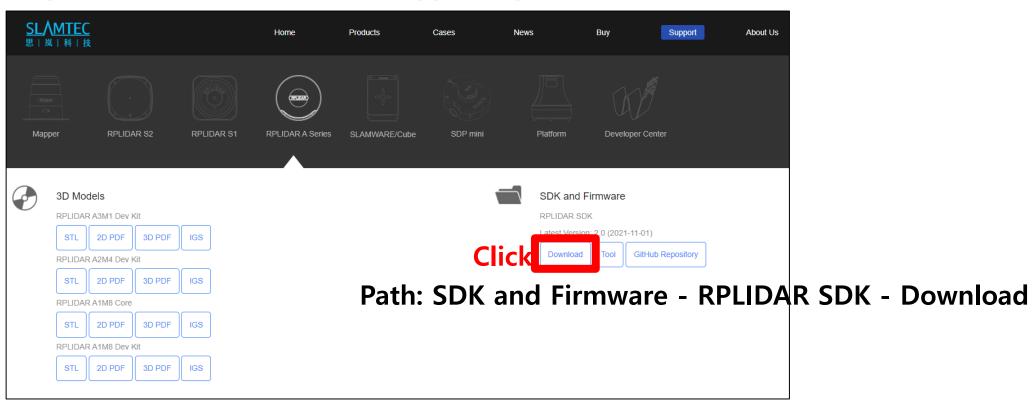
If not recognized, check the lidar USB port connection



■ Install LiDAR Driver

Download page:

https://www.slamtec.com/en/support#rplidar-a-series

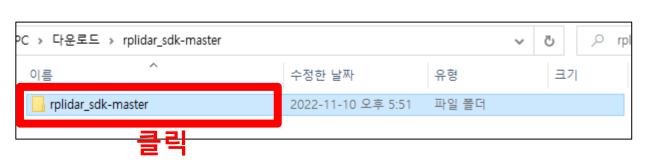


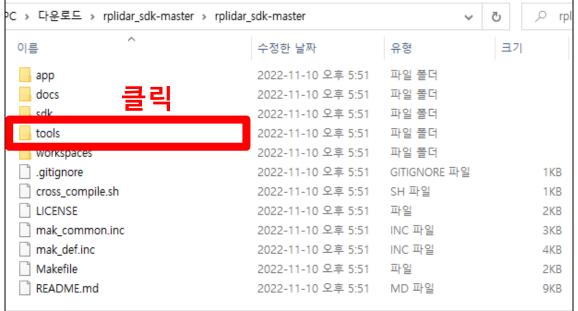




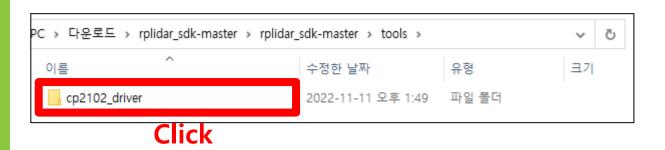


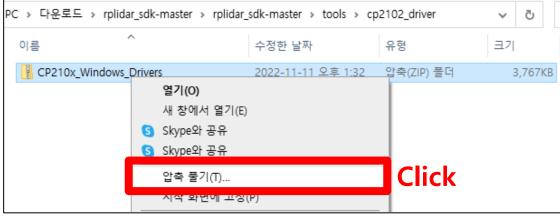






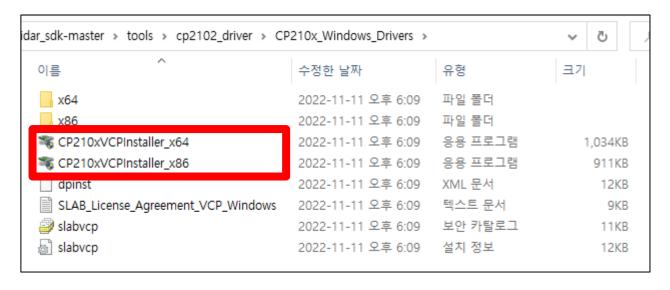








■ Install LiDAR Driver

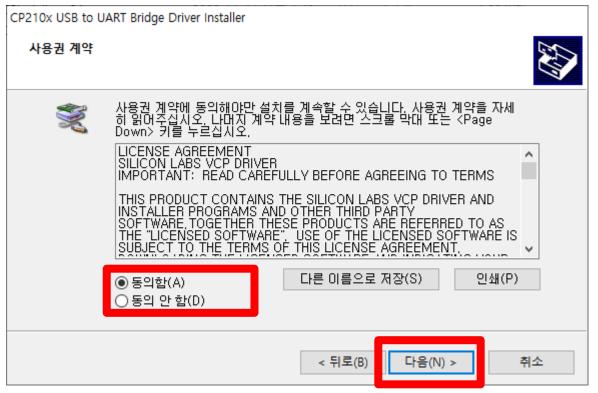


Run programs that meet your PC's specifications



■ Install LiDAR Driver





Click

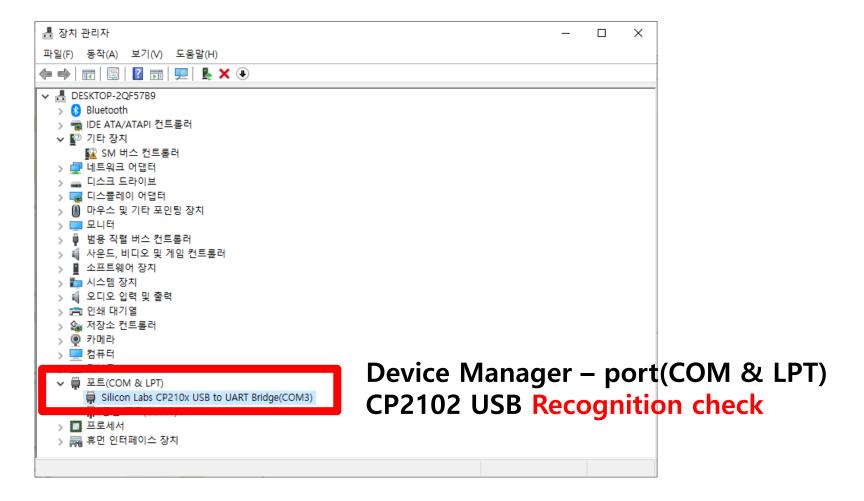
Check Agree, then click Next











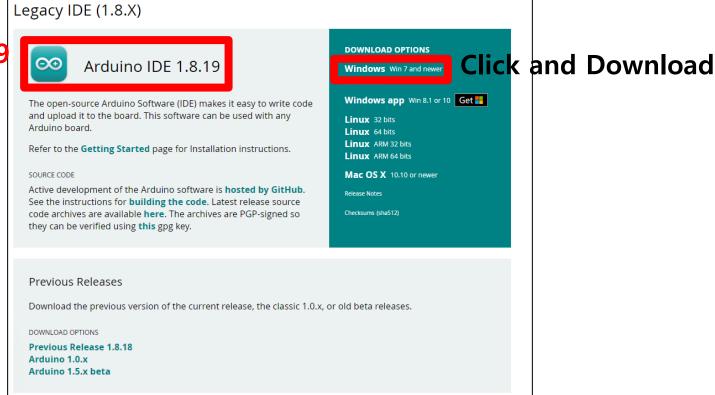


■ Install Arduino IDE

Download page:

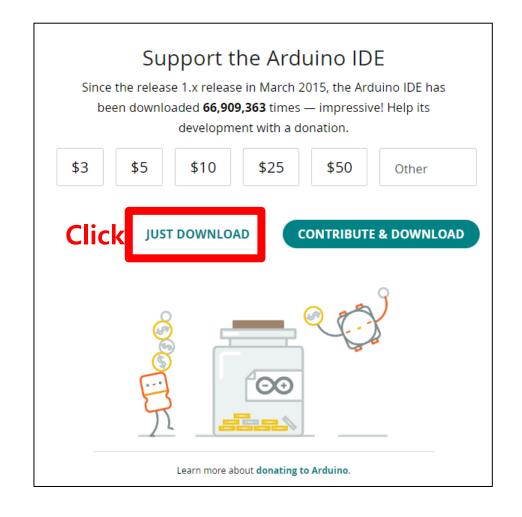
https://www.arduino.cc/en/software

Arduino IDE 1.8.19 Version check



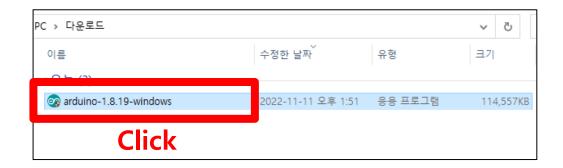


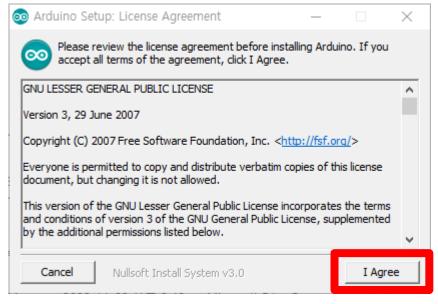
■ Install Arduino IDE





■ Install Arduino IDE

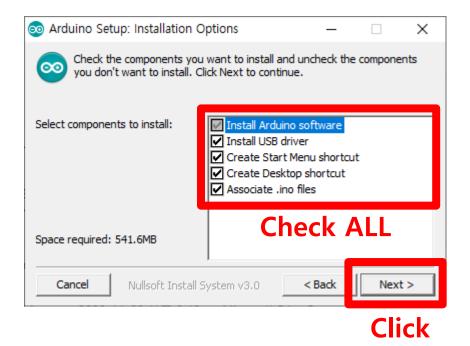


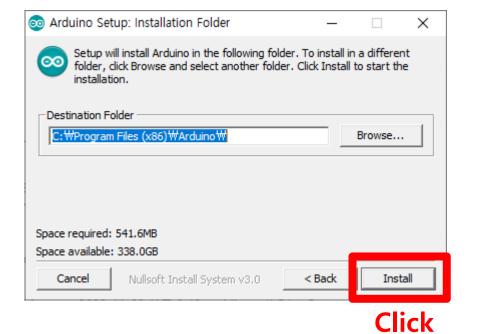


Click



■ Install Arduino IDE







■ Install Arduino IDE

Device Software Installation Notification Appearing, Install All







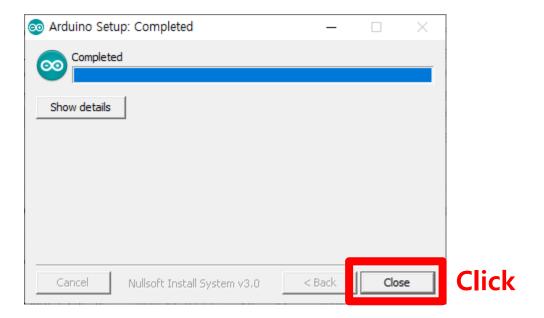
■ Install Arduino IDE

Device Software Installation Notification Appearing, Install All





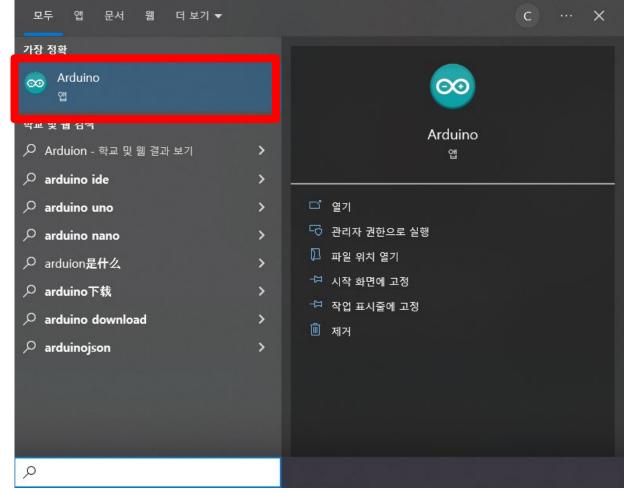
■ Install Arduino IDE





■ Install Arduino IDE

Run Arduino





■ Install Arduino IDE





■ Arduino IDE Initial screen

```
o sketch_nov11a | 아두이노 1.8.19
                                                             Ø
 sketch_nov11a
 // put your setup code here, to run once:
 // put your main code here, to run repeatedly:
```

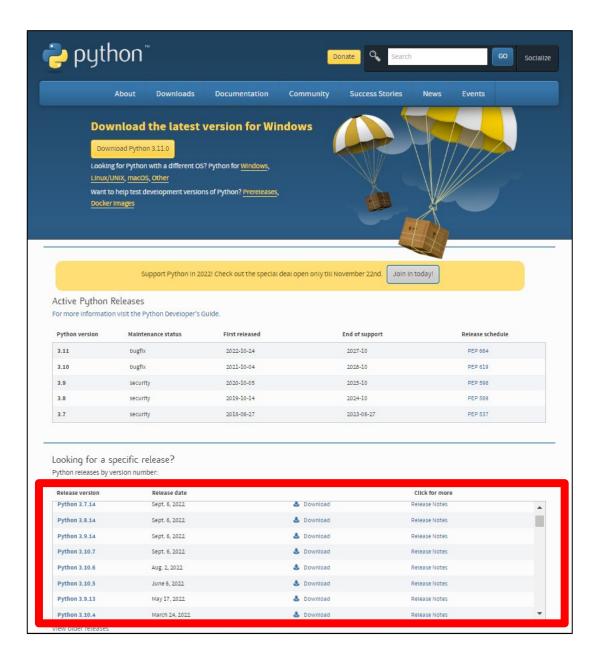


■ Install Python

Download Page:

https://www.python.org/downloads/

Choose version and download





■ Install Python

Download Page:

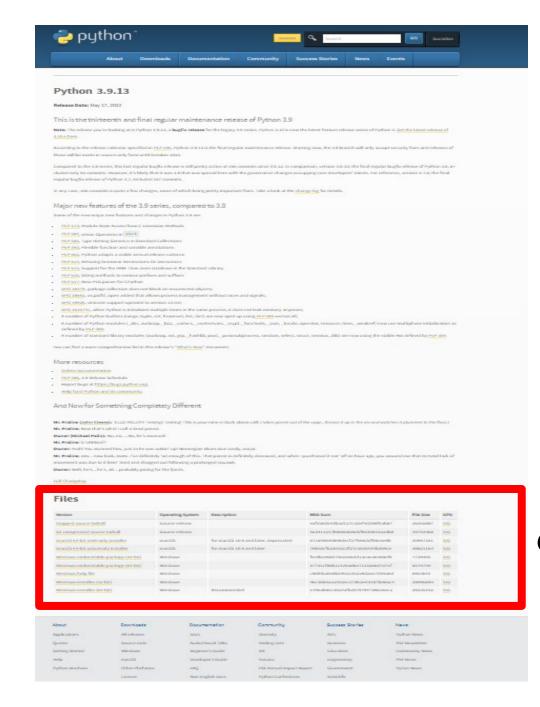
https://www.python.org/downloads/



Version 3.9.13 Click Download



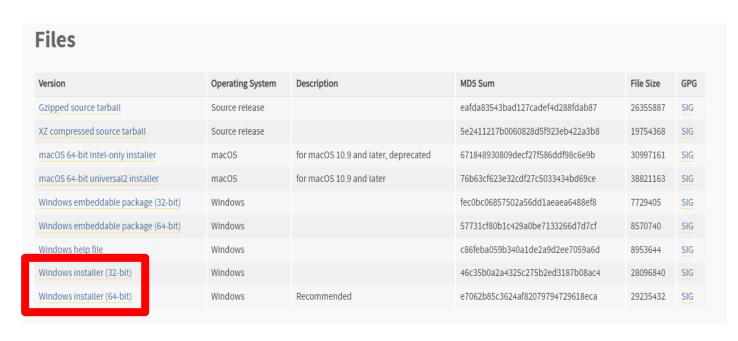
■ Install Python



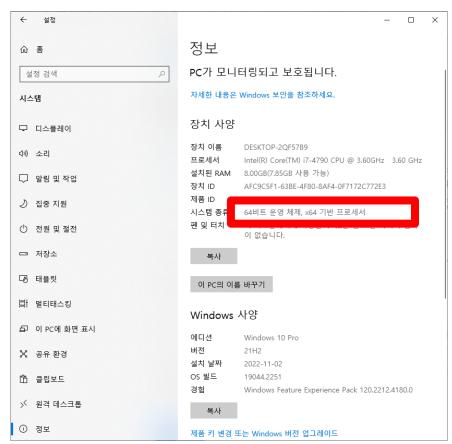
Check the "Files"



■ Install Python



Select your PC hardware specifications (64-bit, 32-bit)

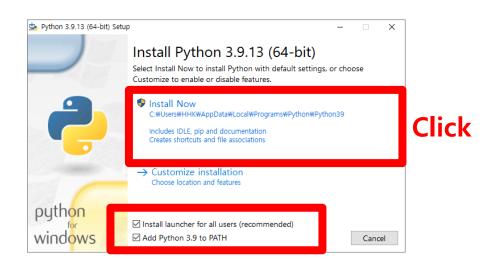


Hardware Specifications
Check out the first part of this document
(page 5)

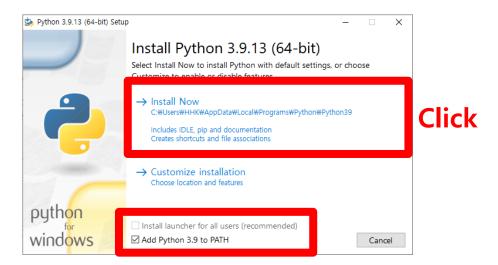


■ Install Python





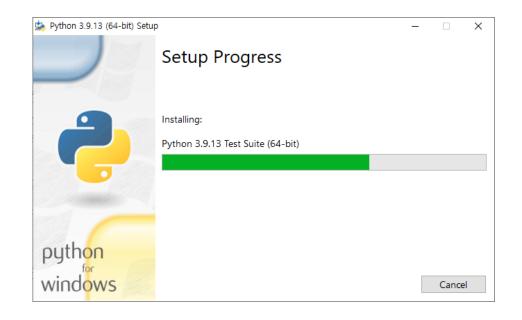
If both checkboxes are enabled Check both

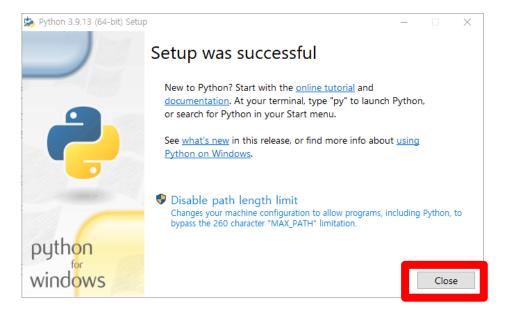


If only one is active Check only the following



■ Install Python

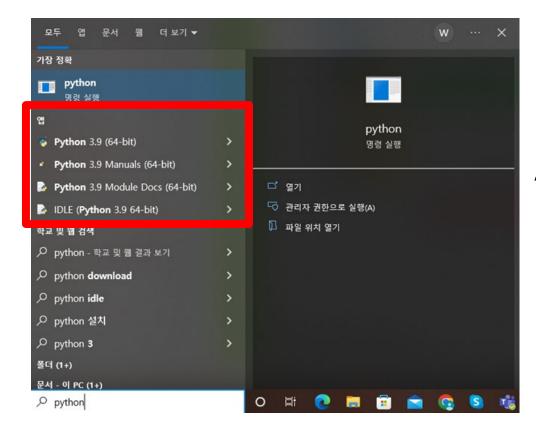








■ Install Python



After searching for Python Make sure the installation is complete

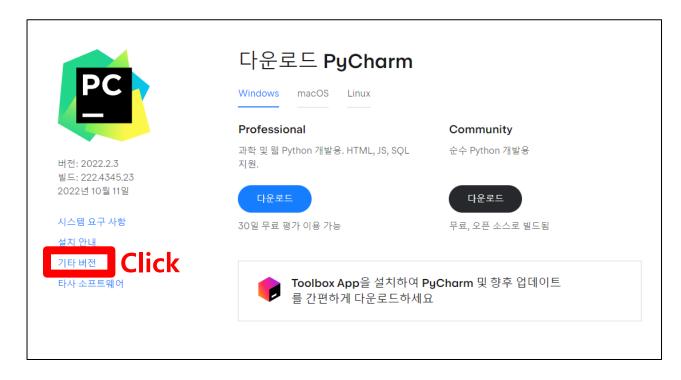


PyCharm

■ Install PyCharm

Download Page:

https://www.jetbrains.com/kokr/pycharm/download/#section=windows

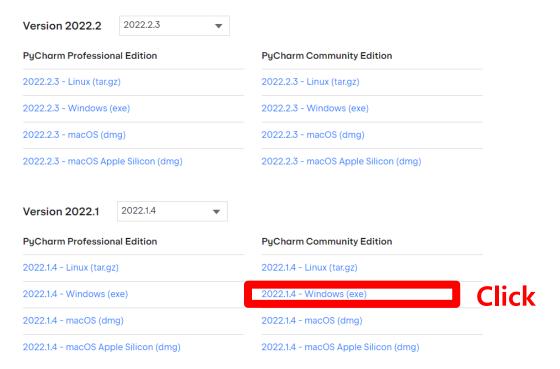




PyCharm

■ Install PyCharm

기타 버전

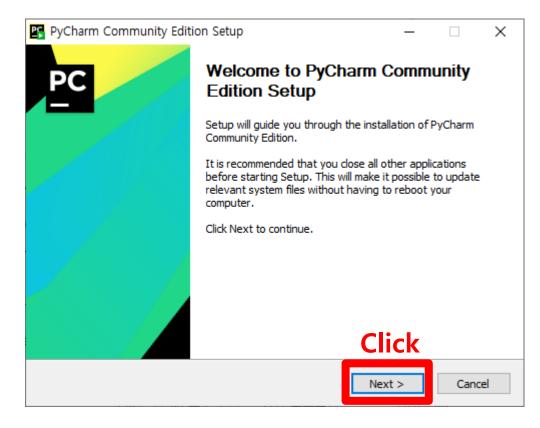




PyCharm

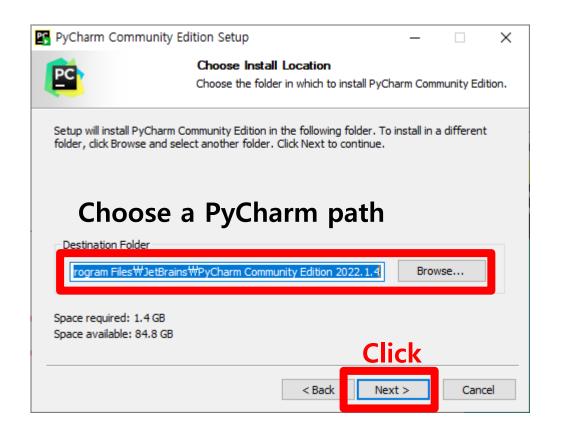
■ Install PyCharm

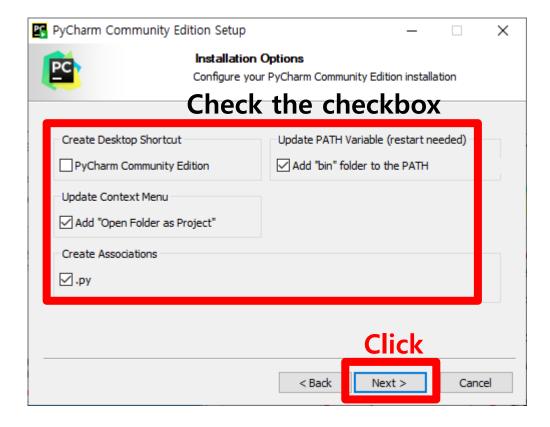






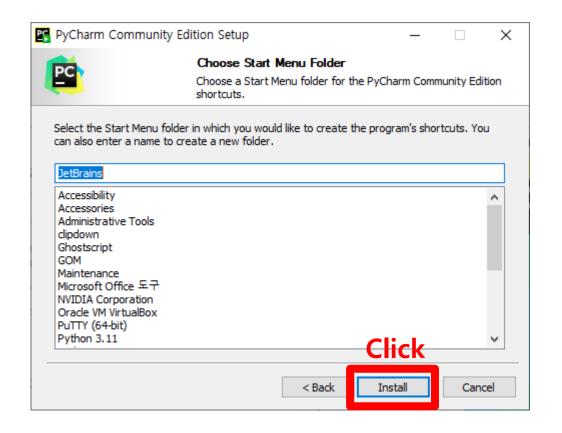
■ Install PyCharm

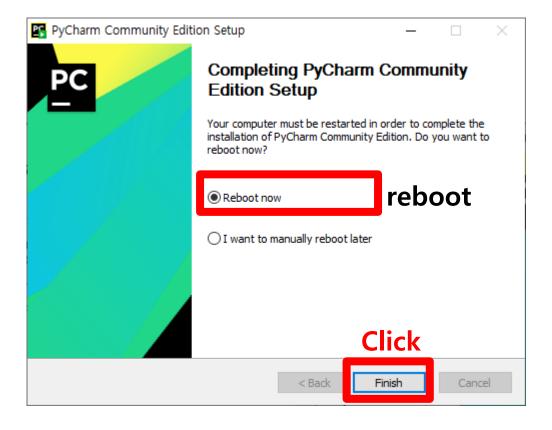






■ Install PyCharm

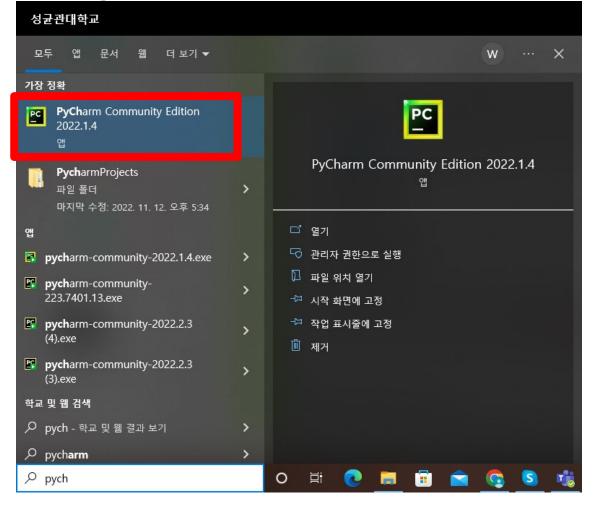




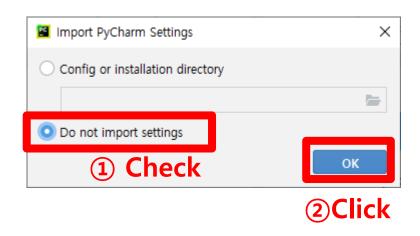


■ Interpreter setting

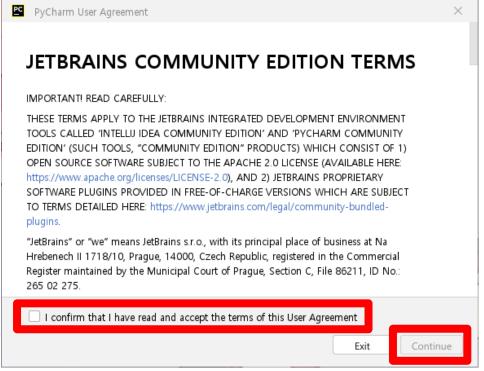
Run PyCharm





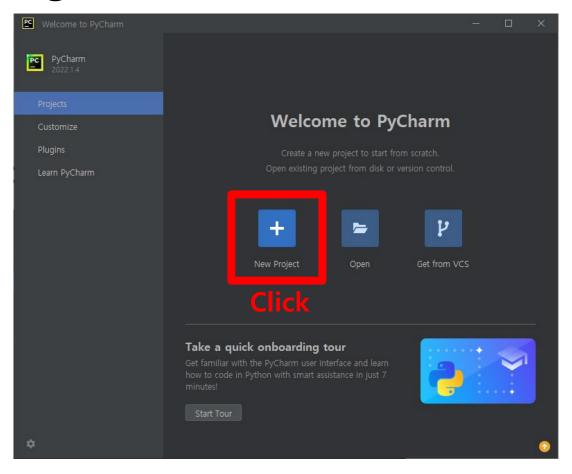




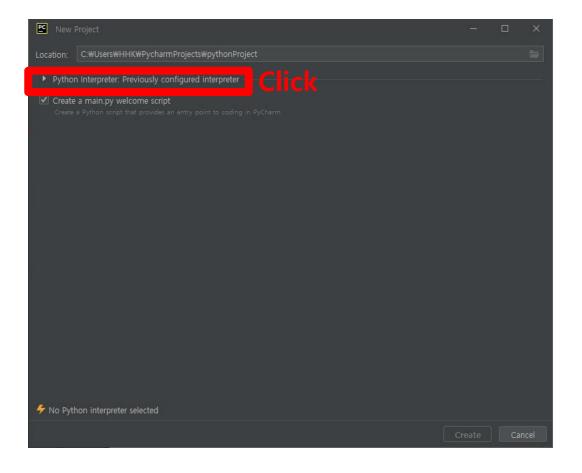






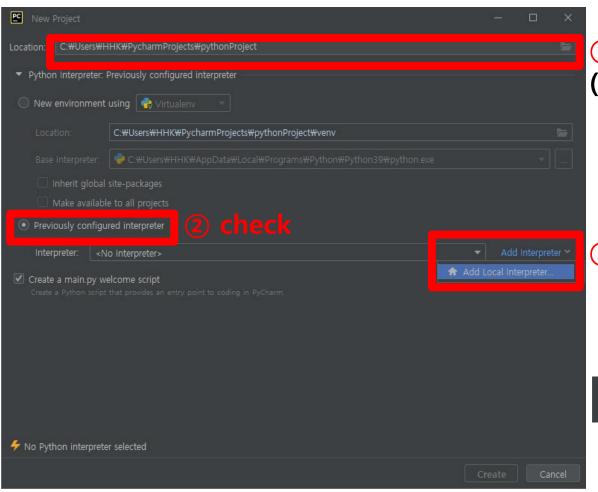








■ Interpreter setting



1 Locate Project Files Folders (Keep Initial Value)

③ Add Interpreter->Add Local Interpreter클릭

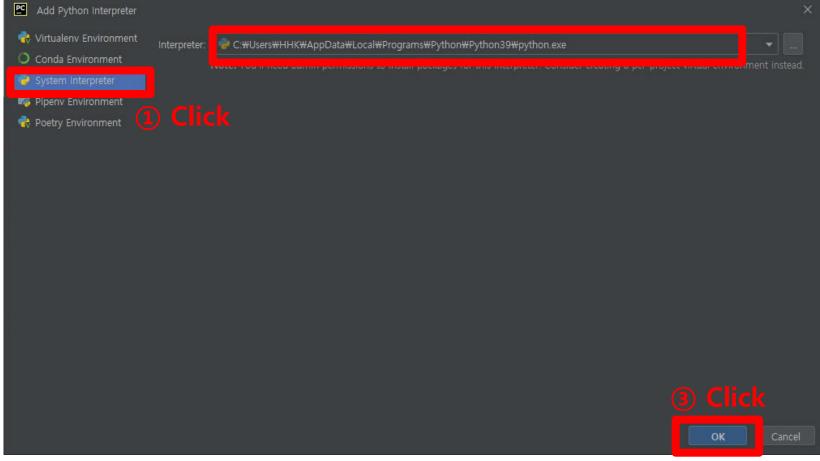
- Previously configured interpreter

 Interpreter: <No interpreter>
- **3-1** If it pops up like this Click the ... to proceed



■ Interpreter setting

2 Interpreter check



If you don't have an Interpreter,
Python not installed Requires Python reinstallation



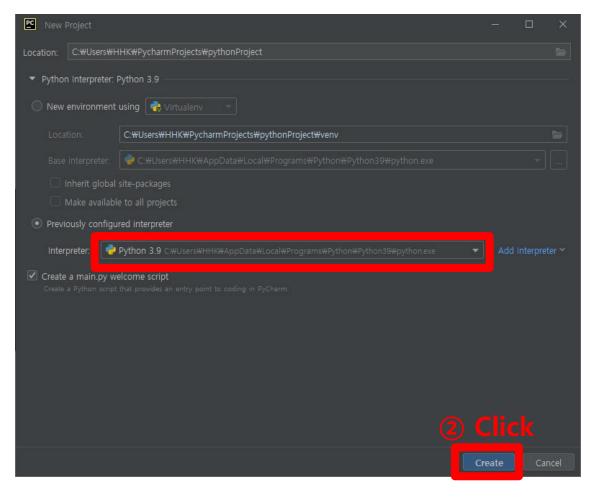
■ Interpreter setting



When you encounter the following error: Reinstall to 2022.1.4 version

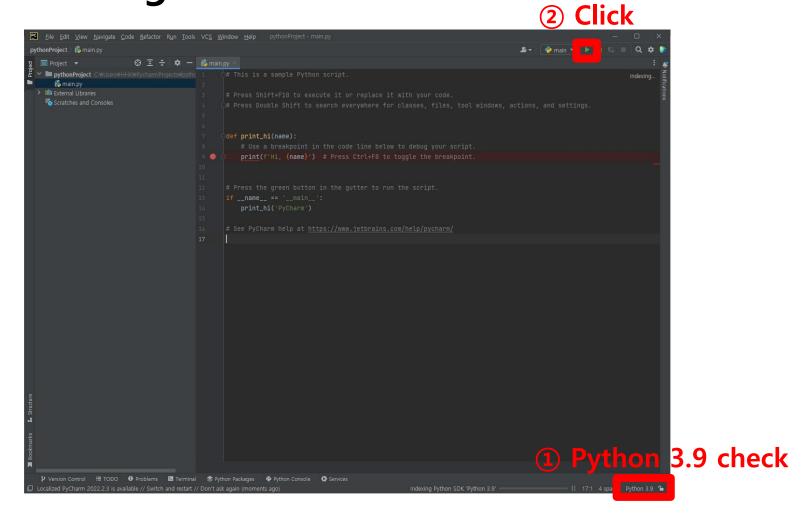


■ Interpreter setting



1 interpreter check (Python 3.9)

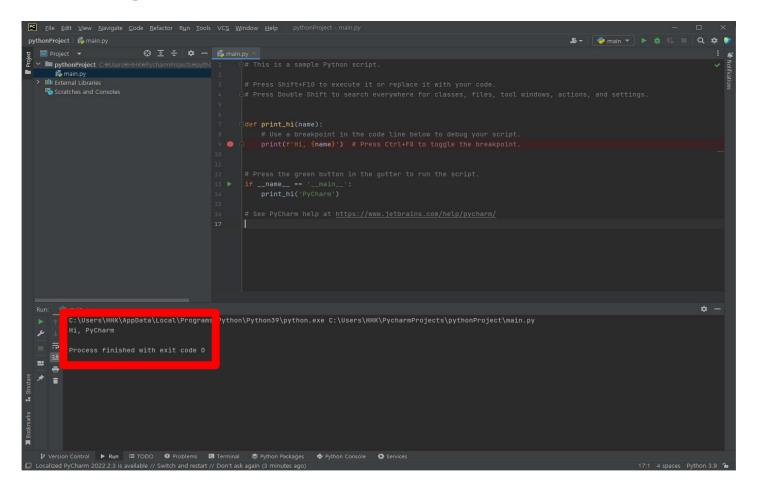






■ Interpreter setting

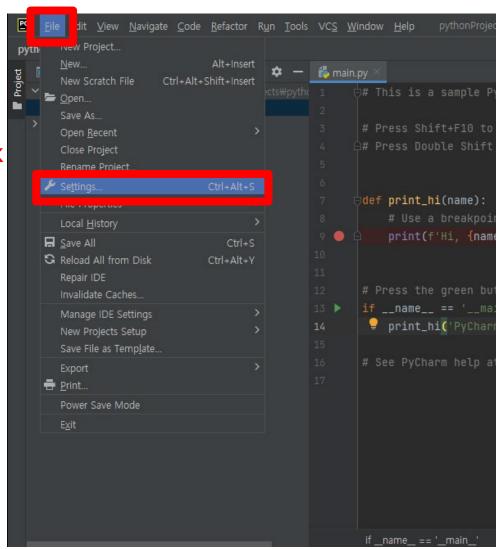
'Hi, PyCharm' is out





■ Install the library

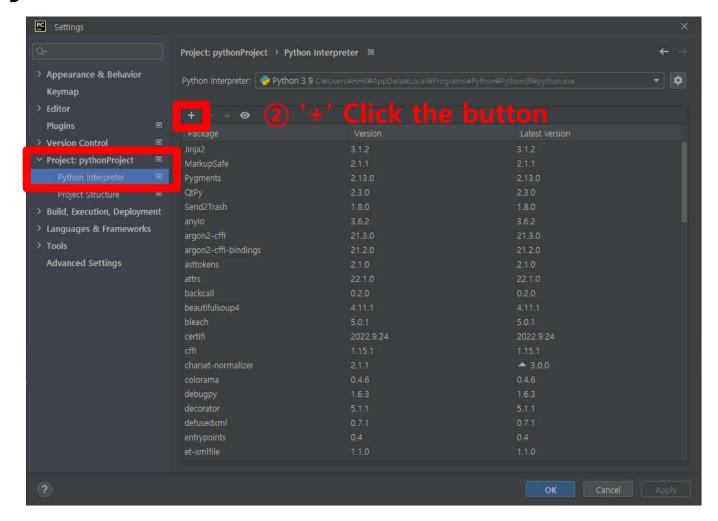
File - Settings Click





■ Install the library

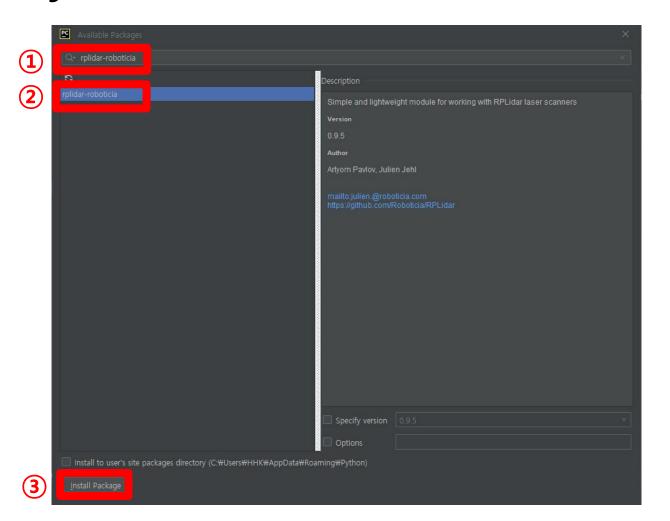
- 1 Project: <Project Name>
- -> Python Interpreter Check





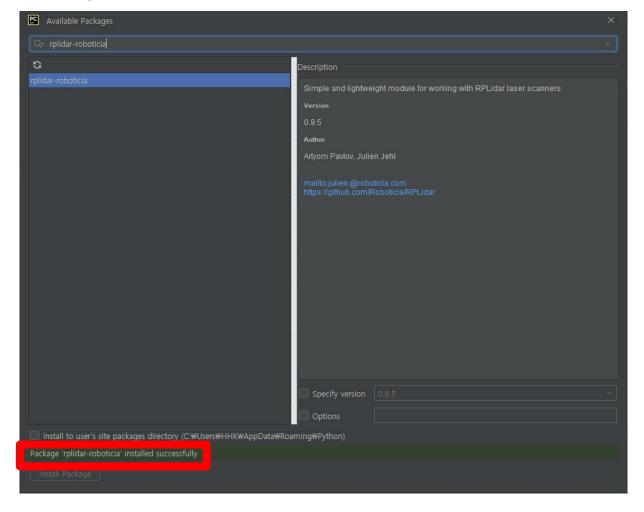
■ Install LiDAR library

- ① rplidar-roboticia search
- ② rplidar-roboticia check
- **③ Install Package Click**





■ Install LiDAR library

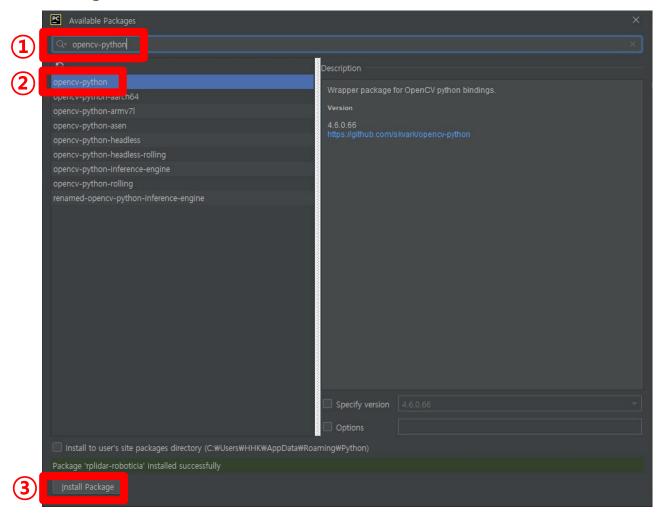


Check the installation success message



■ Install Camera library

- 1 opency-python search
- ② opency-python check
- **③ Install Package click**



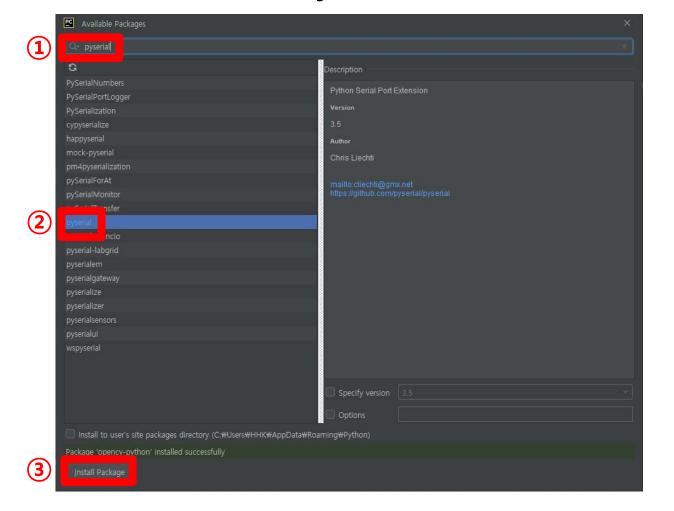


■ Install Camera Library

Check the installation success message

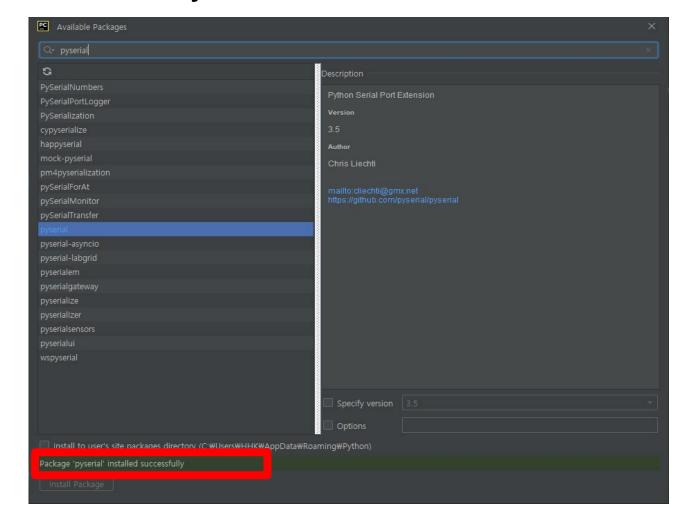


- Install the Serial Communication Library
- 1 pyserial search
- 2 pyserial check
- **③ Install Package Click**





■ Install the Serial Communication Library



Check the installation success message



Exercise

■ Check library and device installation

```
File Edit View Navigate Code Refactor Run Tools VCS Window Help pythonProject - main.py
pythonProject > 💏 main.py
                              😌 \Xi 🛨 🗢 — 👸 main.py × 🎁 rplidar.py × 🞁 _init__py × 🛍 LiDAR_Exercise_2_1.py × 🐉 LiDAR_Exercise_2_2.py × 🛍 LiDAR_Exercise_2_2.py
                                                         atrom rpildar import krildar
       Lib_LiDAR.py
       LiDAR_Exercise_2_1.py
                                                         import serial
       LiDAR_Exercise_2_2.py
       LiDAR_Exercise_2_3.py
       LiDAR_Exercise_2_4.py
       LiDAR_Exercise_2_5.py
                                                         ser = serial.Serial()
       LiDAR_Exercise_3.py
       main.py
                                                         ser.port = 'COM5'
  > Illi External Libraries
    Scratches and Consoles
                                                         ser.baudrate = 9600
                                                         ser.open()
                                                         time.sleep(2)
                                                         print(cv2.
                                                         cap1 = cv2.VideoCapture(cv2.CAP_DSHOW)
                                                         lidar = RPLidar('COM4')
                                                         info = lidar.get_info()
                                                         health = lidar.get_health()
```

Run test code



Exercise

■ Check library and device installation

Printing the following phrase means Installation is done correctly



Thank You!

Automation Lab

