

# Red-Black Tree Cheatsheet

## Overview

- Red-Black Tree is a self-balancing binary search tree.
- It provides worst-case  $O(\log n)$  time complexity for search, insert, and delete operations.
- Each node is either red or black.
- The root node is always black.
- If a node is red, its children must be black.
- Every path from a given node to any of its descendant leaf nodes contains the same number of black nodes.

## Operations

### Insertion

```
def insert_node(root, key):  
    # Create a new node  
    new_node = Node(key)  
    # Insert the new node as a normal BST  
    root = bst_insert(root, new_node)  
  
    # Fix the Red-Black Tree properties  
    fix_violation(root, new_node)  
  
    # Return the root of the modified tree  
    return root
```

### Deletion

```
def delete_node(root, key):  
    # Find the node to delete  
    node = bst_delete(root, key)  
  
    # Fix the Red-Black Tree properties  
    fix_violation(root, node.parent)  
  
    # Return the root of the modified tree  
    return root
```

## Traversal

### In-order Traversal

```
def in_order_traversal(node):  
    if node:  
        in_order_traversal(node.left)
```

```
print (node.key)
in_order_traversal (node.right)
```

## Time Complexity

- Insertion:  $O(\log n)$
- Deletion:  $O(\log n)$
- Traversal:  $O(n)$

## Resources

- [Red-Black Tree Wikipedia](#)
- [GeeksforGeeks: Red-Black Tree](#)
- [Red-Black Tree Visualization](#)