

1. Let  $x[n] = \{1, 2, 3, 0\}$  and let  $y[n] = \{3, 2, 1, 0\}$ .

- ( 2 pts.) a) Let  $z[n] = x[n] * y[n]$ , where  $*$  denotes the convolution operator. Find  $z[n]$ .
- ( 6 pts.) b) Let  $X_{\text{DFT},4}[k]$  denote the 4-point DFT of  $x[n]$ . Use the fft algorithm to find  $X_{\text{DFT},4}[k]$ .
- ( 6 pts.) c) Let  $W_{\text{DFT},4}[k] = X_{\text{DFT},4}[k] \times Y_{\text{DFT},4}[k]$  and let  $w[n]$  denote the 4-point IDFT of  $W_{\text{DFT},4}[k]$ . Work in the time-domain to find  $w[n]$ . You may check your answer using matlab but to get credit you must provide a time-domain solution (*i.e.*, show how you found  $w[n]$  without the need to find  $W_{\text{DFT},4}[k]$  ).
- ( 2 pts.) d) Repeat part (c) for the case when all DFT sizes are changed to 8 (*i.e.*, find  $w[n]$ , the 8-point IDFT of  $W_{\text{DFT},8}[k]$  where  $W_{\text{DFT},8}[k] = X_{\text{DFT},8}[k] \times Y_{\text{DFT},8}[k]$ ). Explain.

2. Every point in the  $z$ -plane can be expressed in terms of its magnitude  $r$  and its phase  $\theta = 2\pi F$  as follows:  $z = re^{j\theta} = re^{j2\pi F}$ . Determine the values of  $r$  and  $F$  which describe the point in the  $z$ -plane to which the Bilinear Transform maps each of the following  $s$ -domain points. Assume a sampling rate of 40 samples per second.

- ( 1 pts.) a)  $s = j2\pi 5$
- ( 1 pts.) b)  $s = j2\pi 10$
- ( 1 pts.) c)  $s = j2\pi 20$
- ( 1 pts.) d)  $s = j2\pi 200$
- ( 1 pts.) e)  $s = -10 + j2\pi 5$
- ( 1 pts.) f)  $s = -20 + j2\pi 5$
- ( 1 pts.) g)  $s = -200 + j2\pi 5$
- ( 1 pts.) h)  $s = -10 + j2\pi 10$
- ( 1 pts.) i)  $s = 10 + j2\pi 5$

- ( 8 pts.) 3. The transfer function of a continuous-time first-order low pass filter (LPF) with 3 dB cutoff frequency  $f_c$  Hz is known to be:

$$H(s) = \frac{2\pi f_c}{s + 2\pi f_c}$$

Use the bilinear transform, together with the analog prototype above to design a discrete-time LPF with 3 dB cutoff  $F_c = 0.2$  cycles/sample.