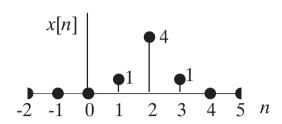
Representation of Discrete-Time Signals

1. Graphical representation:



2. Functional representation:

$$x[n] = \begin{cases} 1, & n = 1, 3 \\ 4, & n = 2 \\ 0, & \text{otherwise} \end{cases}$$

or

$$y[n] = \begin{cases} (0.8)^n, & n \ge 0 \\ 0, & n < 0 \end{cases}$$

3. Tabular representation:

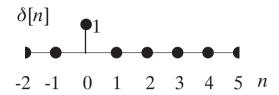
4. Sequence representation: Note: unless otherwise specified the arrow points to the n = 0location.

$$x[n] = \{..., 0, 0, 1, 4, 1, 0, 0, ...\}$$
or
 $x[n] = \{0, 1, 4, 1, 0, 0, ...\}$

Commonly Used Discrete-Time Signals

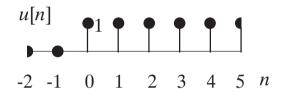
1. Unit Sample Sequence or Unit Impulse or Kronecker Delta, $\delta[n]$:

$$\delta[n] = \begin{cases} 1, & n = 0 \\ 0, & \text{otherwise} \end{cases}$$



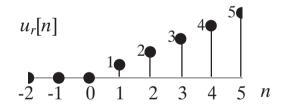
2. Unit Step Sequence, u[n]:

$$u[n] = \begin{cases} 1, & n \ge 0 \\ 0, & \text{otherwise} \end{cases}$$



3. Unit Ramp Sequence, $u_r[n]$:

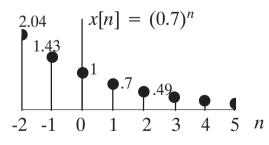
$$u_r[n] = \begin{cases} n, & n \ge 0 \\ 0, & \text{otherwise} \end{cases}$$



4. Exponential Sequence:

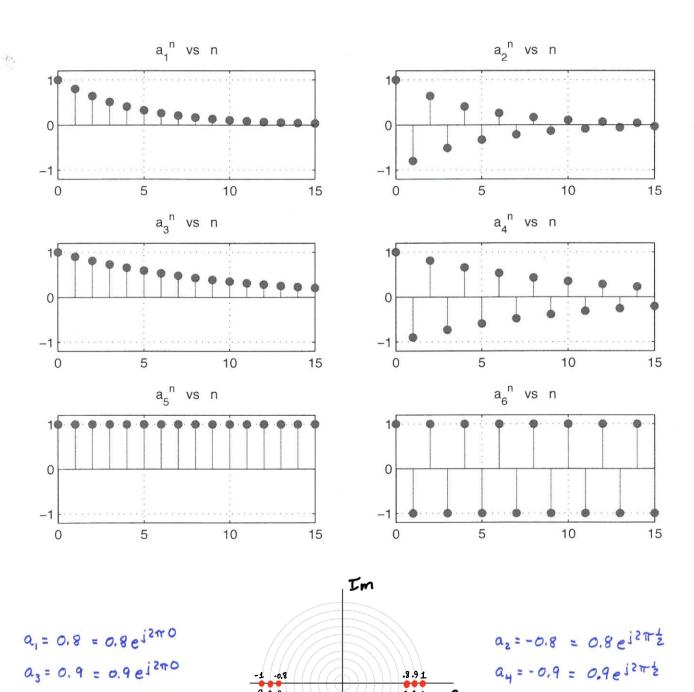
$$x[n] = a^n$$

note: in general, a can be real-valued or complex-valued. For the signal shown to the right, a is real (a=0.7), and there is



no oscillation. In the case that *a* is complex-valued, the signal will be complex-valued; the real and imaginary parts will oscillate in accordance with the phase of *a* and will decay or grow according to the magnitude of *a* as shown by the equations below.

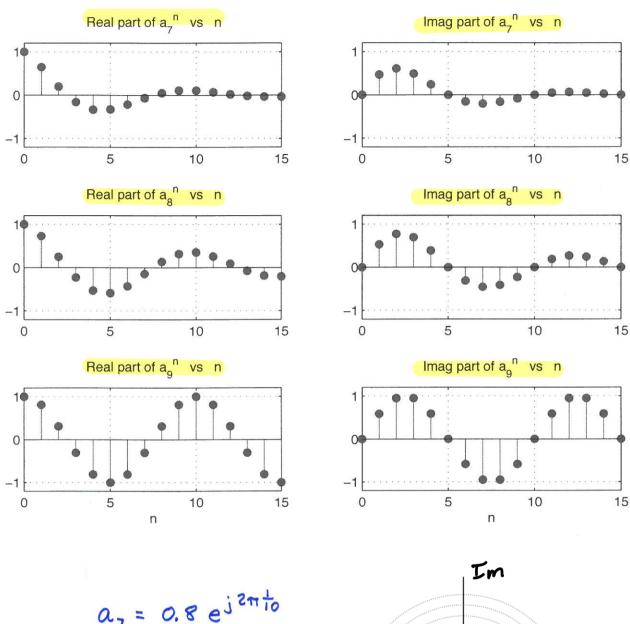
if:
$$a = re^{j2\pi F_0}$$
, then: $x[n] = r^n e^{j2\pi F_0 n} = r^n (\cos(2\pi F_0 n) + j\sin(2\pi F_0 n))$

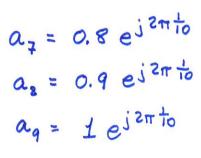


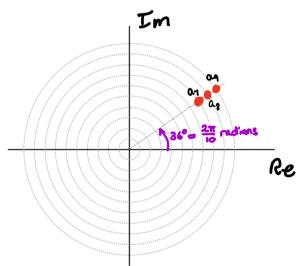
a6 = -1 = 1 e j 2 m = 2

0,0,0,

 $a_5 = 1 = 1 e^{j2\pi 0}$







Energy Signals vs Power Signals

The **energy**, E_x , of a discrete-time signal, x[n], is defined as:

$$E_x = \sum_{n=-\infty}^{\infty} |x[n]|^2$$

If $0 \le E_x < \infty$, then x[n] is an energy signal.

The energy of a discrete-time signal, x[n], with respect to the interval, $n_1 \le n \le n_2$, is denoted by $E_{x,[n_1,n_2]}$ and defined as:

$$E_{x, [n_1, n_2]} = \sum_{n=n_1}^{n_2} |x[n]|^2$$

The average power, P_x , of a discrete-time signal, x[n], is defined as:

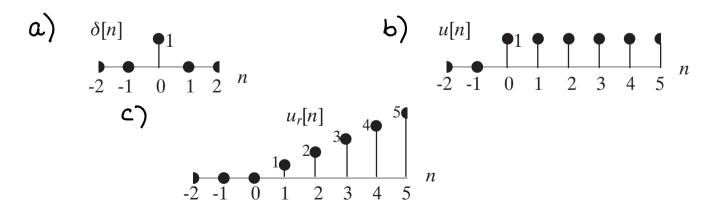
$$P_{x} = \lim_{N \to \infty} \left[\frac{1}{2N+1} \sum_{n=-N}^{N} |x[n]|^{2} \right]$$

If $0 < P_x < \infty$, then x[n] is a *power signal*.

If x[n] is periodic with period N, the average power of x[n] can be computed as:

$$P_x = \frac{1}{N} \sum_{n=n_0}^{n_0+N-1} |x[n]|^2$$

Exercise: Determine whether each of the following is a power signal, energy signal, or neither.



Exercise: Determine whether each of the following is a power signal, energy signal, or neither.

a)
$$\frac{\delta[n]}{-2 - 1} = \frac{1}{0 + 1 + 2} = \frac{1}{N + 20} = \frac{1}{2N + 1} = \frac{1}{N + 20} = \frac{1}{N + 1} =$$

b)
$$u[n]$$
 $u[n]$
 $u[n]$

$$E_{u_{r}} = \sum_{n=-\infty}^{\infty} |u_{r}[n]|^{2} = \sum_{n=-\infty}^{\infty} |u_{r}[n]|^{2} = \sum_{n=-\infty}^{\infty} |u_{r}[n]|^{2} = \lim_{n\to\infty} \frac{1}{2^{n+1}} \sum_{n\to\infty}^{\infty} |u_{r}[n]|^{2} = \lim_{n\to\infty} \frac{1}{2^{n+1}} \left(\sum_{n\to\infty}^{\infty} |u_{r}[n]|^{2} \right)$$

Average Power Examples

a) Find the average power, Py, of y[n].

Since y[n] is periodic with period 5, we may find Py as follows:

$$P_{y} = \frac{1}{5} \sum_{n=0}^{4} |y[n]|^{2} = \frac{1}{5} \sum_{n=0}^{4} A^{2} \cos^{2}(2\pi \frac{1}{5}n)$$

$$= \frac{1}{5} \sum_{n=0}^{4} \frac{A^{2}}{2} \left[1 + \cos \left(2\pi \frac{2}{5} n \right) \right]$$

$$=\frac{1}{5}\sum_{n=0}^{4}\frac{A^{2}}{2}+\frac{1}{5}\sum_{n=0}^{4}\frac{A^{2}}{2}\cos\left(2\pi\frac{2}{5}n\right)$$
a proof of
this is provided
on the next
periodic with
period 5

the sum over one period of a

$$= \frac{1}{5} \left(\frac{A^2}{2} + \frac{A^2}{2} + \frac{A^2}{2} + \frac{A^2}{2} + \frac{A^2}{2} \right) = \frac{A^2}{2}$$

b) Find the RMS value of yen].

RMS stands for Root Mean Square. It is the square root of the mean square value. Py is the mean of the squared magnitude of yen]. RMS ralue of y[n] = JPy = A

Proof that
$$\sum_{n=0}^{4} \cos(2\pi \frac{2}{5}n) = 0$$

$$\sum_{n=0}^{4} \cos(2\pi \frac{2}{5}n) = \sum_{n=0}^{4} \operatorname{Re} \left\{ e^{j2\pi \frac{2}{5}n} \right\}$$

$$= \operatorname{Re} \left\{ \sum_{n=0}^{4} e^{j2\pi \frac{2}{5}n} \right\}$$

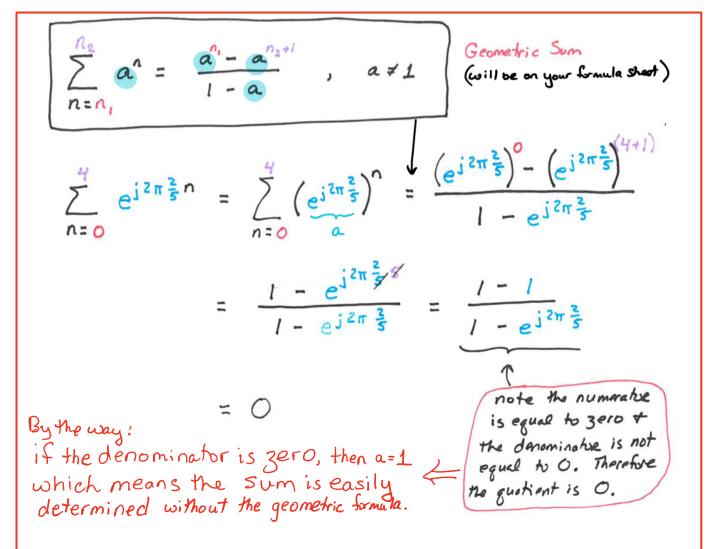
$$= \operatorname{Re} \left\{ \sum_{n=0}^{4} e^{j2\pi \frac{2}{5}n} \right\}$$

the sum of the real parts is equal to the seal part of the Sum

$$= \operatorname{Re} \left\{ 0 + j 0 \right\}$$

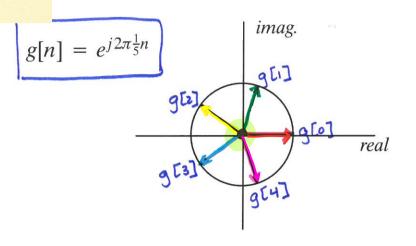
using the geometric sum (see below)

Use of the Geometric Sum in the problem above:



Included this handout from ECE 3511 in case you are interested.

Illustration that the sum of a d.t. complex exponential Over one period is equal to zero. (This statement assumes that the period, N, is greater than I sample.)





note: the vector sum is zero $\sum_{n=0}^{4} g[n] = 0$

The sum over one period of a complex exponential with period N, amounts to the sum of N points equally spaced around the unit circle.

$$h[n] = e^{j2\pi\frac{2}{5}n}$$

$$h[3]$$

$$h[3]$$

$$h[1] = g[2]$$

$$h[3] = g[1]$$

$$h[3] = g[1]$$

$$h[4] = g[3]$$

$$h[6] = 0$$

$$\Rightarrow \sum_{n=0}^{4} \operatorname{Re} \{h[n]\} = 0$$

$$\Rightarrow \sum_{n=0}^{4} \operatorname{cos}(2\pi\frac{2}{5}n) = 0$$

$$\lim_{n=0}^{4} \operatorname{sin}(2\pi\frac{2}{5}n) = 0$$

$$\lim_{n=0}^{4} \operatorname{sin}(2\pi\frac{2}{5}n) = 0$$

Note: The average power of a sum of signals is not usually equal to the sum of the individual average powers.

if z[n] = x[n] + y[n], we may not conclude that $P_z = P_x + P_y$.

In the case that x[n] + y[n] are orthogonal, we will find that $P_z = P_z + P_y$

Ex. 1 Snow that:

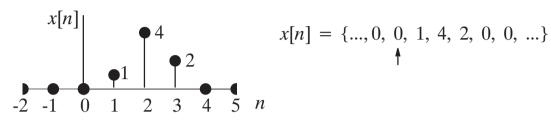
if $z[n] = A\cos(2\pi \frac{1}{5}n) + B\cos(2\pi \frac{1}{5}n + 45^{\circ})$ then $P_z = \frac{A^2}{2} + \frac{B^2}{2} + AB\cos(45^{\circ})$

 $\frac{2x.2}{if}$ Show that! $\frac{2[n]}{if} = A \cos(2\pi \frac{1}{5}n) + B \sin(2\pi \frac{1}{5}n)$ the $P_2 = \frac{A^2}{2} + \frac{B^2}{2}$

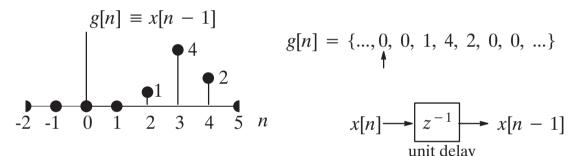
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Simple Manipulations of Discrete-Time Signals

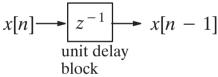
1. time shift: The signal x[n-k], where k is an integer, denotes a shifted version of the signal x[n]. If k > 0, the signal x[n - k] is delayed by k samples relative to the signal x[n]; and if k < 0, the signal x[n - k] is advanced by |k| samples relative to the signal x[n].

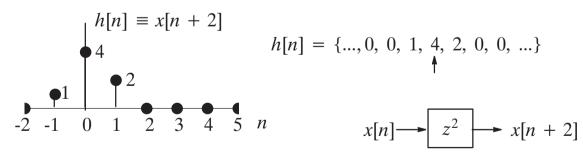


$$x[n] = \{..., 0, 0, 1, 4, 2, 0, 0, ...\}$$



$$g[n] = \{..., 0, 0, 1, 4, 2, 0, 0, ...\}$$





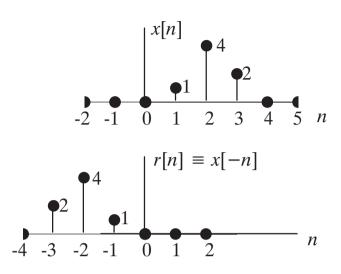
$$h[n] = \{..., 0, 0, 1, 4, 2, 0, 0, ...\}$$

$$x[n] \longrightarrow z^2 \longrightarrow x[n+2]$$

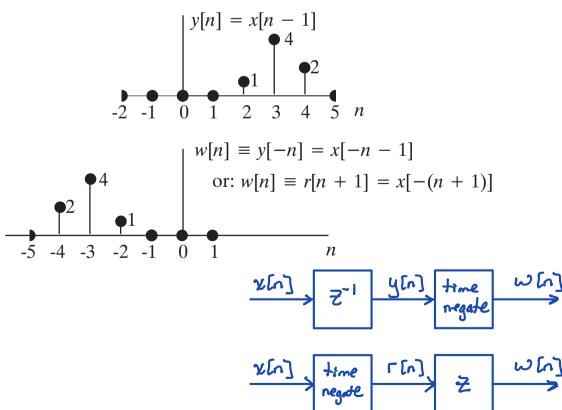
_ or time-negation

2. **Reflection** (or folding) about the time origin. A signal, x[n], may be reflected about the time origin by replacing the independent variable, n, by -n.

Example 1:

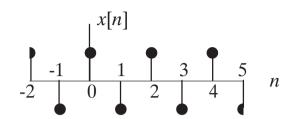


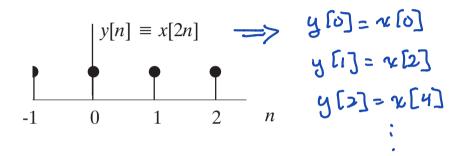
Example 2:



3. **Down-sampling** (or time-scaling). *Down sampling* a signal refers to replacing the independent variable, n, by μn , where μ is an integer.

Example 1:





Note: if the original x[n] was obtained by sampling an continuous-time signal every T_s seconds:

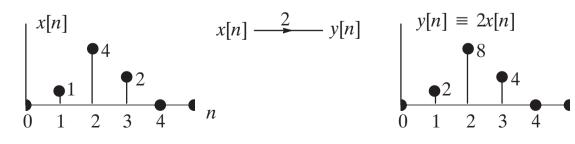
$$x[n] = x_a(nT_s)$$

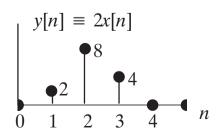
then the sequence y[n] = x[2n] is what you get by sampling the same continuous-time signal once every $2T_s$ seconds:

$$y[n] = x[2n] = x_a(n2T_s)$$

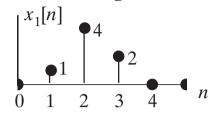
i.e., the sampling rate has been cut in half.

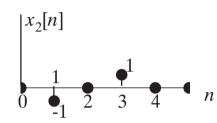
4. Amplitude Scaling by A refers to replacing every signal sample by the original sample multiplied by A.

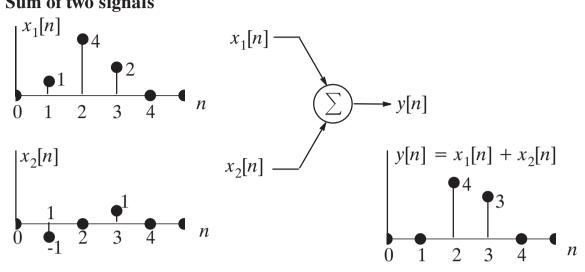




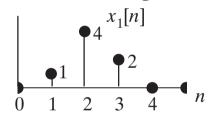
5. Sum of two signals

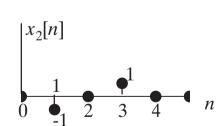


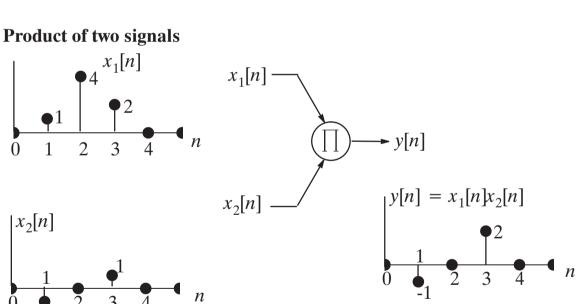




6. Product of two signals



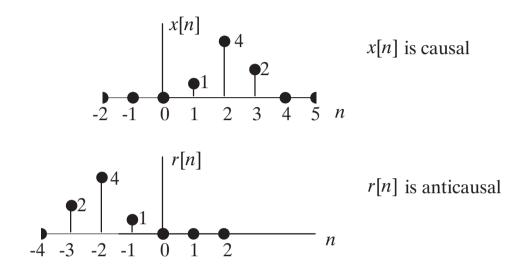


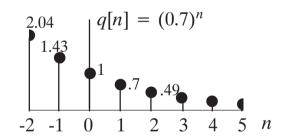


7. Causal, Anticausal, and Noncausal signals:

A signal is said to be *causal* if and only if it is equal to 0 for all n < 0; a signal is said to be *anticausal* if it is equal to 0 for all n > 0; a signal is said to be *non-causal* if it is not causal.

Examples:





q[n] is noncausal