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## MODEL ORDER REDUCTION

GIVEN A SYSTEM  $\Sigma_m$  OF ORDER  $n$  WITH PROPERTY  $\textcircled{P}$

FIND

ANOTHER SYSTEM  $\Sigma_v$  OF ORDER  $v \ll n$  WITH THE SAME PROPERTY  $\textcircled{P}$  + ADDITIONAL PROPERTIES

$\textcircled{P} \equiv$  POLES

MOR BY POLE MATCHING

$$\Sigma_m: \begin{cases} \dot{x} = Ax + Bu \\ y = Cx \end{cases} \quad (1) \quad \begin{matrix} x \in \mathbb{R}^n & u \in \mathbb{R} \\ A \in \mathbb{R}^{n \times n} & B \in \mathbb{R}^{n \times 1} \\ C \in \mathbb{R}^{1 \times n} \end{matrix}$$

$$W(s) = C(sI - A)^{-1}B$$

ASSUMPTION:  $\Sigma_m$  IS MINIMAL. I.E.  $\Sigma_m$  IS OBSERVABLE AND REACH-  
ABLE

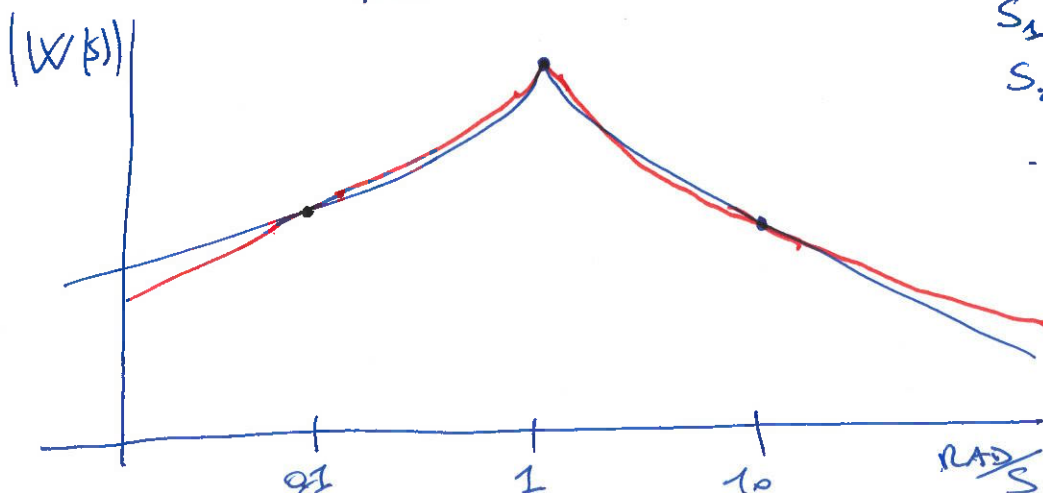
DEFINITION 1: LET  $s_i \in \mathbb{C} \setminus \sigma(A)$ . THE O-POLE OF SYSTEM

(1) AT  $s_i$  IS

$$\eta(s_i) = \left. \frac{d}{ds} W(s) \right|_{s=s_i}$$

THE K-POLE OF SYSTEM (1) AT  $s_i$  IS

$$\eta_k(s_i) = \frac{(-1)^k}{k!} \left[ \frac{d^k}{ds^k} W(s) \right]_{s=s_i}$$



$$\begin{matrix} s_1 = +i & s_3 = 10i \\ s_2 = -i & s_4 = -10i \end{matrix}$$

...

Lemma 1 Let  $s_i \in \mathbb{C} \setminus \sigma(A)$ . Consider

$$C \tilde{\Pi} \Psi_k = [\eta_0(s_i) \quad \eta_1(s_i) \quad \dots \quad \eta_n(s_i)]$$

$(k+1) \times (k+1)$

$$\Psi_k = \text{DIAG}(1, -1, 1, \dots, (-1)^k) \in \mathbb{R}^{k+1}$$

$\tilde{\Pi}$  is the unique solution of the Sylvester equation

$$\tilde{\Pi} \Sigma_k = A \tilde{\Pi} + B L_k$$

$$L_k = [1 \ 0 \ \dots \ 0] \in \mathbb{R}^{k+1}$$

$$\Sigma_k = \begin{bmatrix} s_i & 1 & 0 & \dots & 0 \\ 0 & s_i & 1 & 0 & \dots \\ & & \ddots & \ddots & \ddots \\ & & & 1 & s_i \end{bmatrix} \in \mathbb{R}^{(k+1) \times (k+1)}$$

Lemma 2 Consider the pair  $(S, L)$  where  $S$  has characteristic polynomial

$$p(s) = \prod_{i=1}^{\bar{n}} (s - s_i)^{k_i}$$

$$V = \sum_{i=1}^{\bar{n}} k_i (S \in \mathbb{R}^{n \times n}), \text{ and } L \in \mathbb{R}^{1 \times n} \text{ is such that}$$

$(S, L)$  is observable. Assume  $\sigma(S) \cap \sigma(A) = \emptyset$

Then there exists a one-to-one relation between

the polynomials  $\eta_0(s_0) \dots \eta_{k_0-1}(s_0), \eta_0(s_1) \dots \eta_{k_1-1}(s_1) \dots$

with the matrix  $C \tilde{\Pi}$  where  $\tilde{\Pi}$  is the unique solution of

$$A \tilde{\Pi} - \tilde{\Pi} S = -B L$$

Definition The polynomials of (4) at  $(S, L)$  and the elements of  $C \tilde{\Pi}$

LETTA 3

CONSIDER AN AUXILIARY SYSTEM

$$\dot{w} = Sw \quad m = Lw$$

$w \in \mathbb{R}^v$ ,  $S \in \mathbb{R}^{v \times v}$ ,  $L \in \mathbb{R}^{1 \times v}$   $(S, L)$  IS OBSERVABLE.

ASSUME  $\sigma(S) \subset \mathbb{C}_0$  AND THE EIGENVALUES OF  $S$  ARE SIMPLE. CONSIDER THE SYSTEM

$$\dot{x} = Ax + Bu \quad y = Cx$$

ASSUME THAT  $\sigma(A) \subset \mathbb{C}_0$ . THEN

$$y(n) = C \cdot \Pi \cdot w(n) + C \cdot e^{Ar} (x(0) - \Pi w(0))$$

AND THE STEADY-STATE IS

$$y_{ss}(n) = C \Pi w(n)$$

PROOF

$$\underline{A \Pi - \Pi S = -BL}$$

$$\underline{BL - \Pi S = -A \Pi}$$

$$z(n) = x(n) - \Pi w(n)$$

$$\dot{z} = \dot{x} - \Pi \dot{w} = Ax + BLw - \Pi Sw =$$

$$= Ax + (BL - \Pi S)w$$

$$= Ax + (-A \Pi)w$$

$$= A(x - \Pi w) = Az$$

$$\dot{z} = Az \quad z(n) = e^{Ar} z(0)$$

$$x(n) - \Pi w(n) = e^{Ar} (x(0) - \Pi w(0))$$

$$x(n) = \Pi w(n) + e^{Ar} (x(0) - \Pi w(0))$$

$$y = Cx = C \Pi w + C e^{Ar} (x(0) - \Pi w(0))$$

$$y_{ss}(n) = C \Pi w(n)$$

DEFINITION | GIVEN (1) AND (S, L). THE SYSTEM

$$\begin{cases} \dot{z} = Fz + Gm \\ y_{\text{red}} = Hz \end{cases} \quad (2)$$

$$z \in \mathbb{R}^V, F \in \mathbb{R}^{V \times V}, G \in \mathbb{R}^{V \times 1}, H \in \mathbb{R}^{TV \times V}$$

IS A REDUCED ORDER MODEL BY MOMENT MATCHING IF  
(2) HAS THE SAME MOMENTS OF (1) AT (S, L)

$$\begin{array}{lcl} \textcircled{P} & \begin{matrix} -\Pi \\ P \end{matrix} & \begin{matrix} A\Pi - \Pi S = -BL \rightarrow C\Pi \\ FP - PS = -GL \rightarrow HP \end{matrix} \end{array}$$

IF P IS THE UNIQUE SOLUTION OF

$$FP - PS = -GL$$

THEN THE MOMENTS OF (2) ARE HP

$$\textcircled{2} \text{ IS A ROM BY RM. } \Leftrightarrow \begin{array}{l} \text{FREE PARAMETERS} \\ V^2 + 2V \\ \begin{cases} FP - PS = -GL \\ C\Pi = HP \end{cases} \\ \underline{C\Pi \in \mathbb{R}^V} \quad \text{CONSTRAINTS } V \end{array}$$

$$\text{SET } P = I$$

$$F - S = -GL \Rightarrow F = S - GL$$

$$C\Pi = H \Rightarrow H = C\Pi$$

$$\begin{array}{l} \dot{z} = (S - GL)z + Gm \quad \text{FOR ANY } G \text{ SUCH THAT} \\ y_{\text{red}} = C\Pi z \quad \sigma(F = S - GL) \cap \sigma(S) = \emptyset \end{array}$$

$$FP = PS - GL$$

$$CTT = HP$$

$$\boxed{\begin{aligned} F &= \underbrace{PSP^{-1}}_S - \underbrace{GLP^{-1}}_{\tilde{L}} \\ H &= \underbrace{C\Pi P^{-1}}_{\tilde{\Pi}} \end{aligned}}$$

PROBLEM ASSIGN THE EIGENVALUES OF  $S - GL$  USING G

SIDE NOTE  $(\tilde{A}, \tilde{B})$  REACHABLE  $\Rightarrow \exists \tilde{K}$  SUCH THAT

$$\sigma(\tilde{A} - \tilde{B}\tilde{K}) = \{\lambda_1, \lambda_2, \dots\} \text{ WHERE } \lambda_i \text{ IS ANY COMPLEX NUMBER}$$

ACKERMAN FORMULA

$$\tilde{K} = \text{PLACE}(\cdot) \text{ MATLAB}$$

$$\tilde{A} = S^T \quad \tilde{B} = L^T \Rightarrow K^T = \text{PLACE}(S^T, L^T, \{\dots\})$$

$$\sigma(S^T - L^T K^T) = \{\dots\}$$

$$(S^T - L^T K^T)^T = (S - \overset{G}{K}L)$$

$$A\Pi - \Pi S = -BL$$

$$\Pi = ?$$

SYLVESTER MATLAB

$$X = \begin{bmatrix} x_{11} & x_{12} & \dots \\ x_{21} & & \\ \vdots & & \end{bmatrix} = \begin{bmatrix} \frac{1}{\bar{x}_1} & \frac{1}{\bar{x}_2} & \dots & \frac{1}{\bar{x}_n} \\ 1 & 1 & & 1 \end{bmatrix}$$

$$\text{VEC}(X) = \begin{bmatrix} \bar{x}_1 \\ \bar{x}_2 \\ \bar{x}_3 \\ \vdots \\ \bar{x}_n \end{bmatrix}$$

$$A = \begin{bmatrix} a_{11} & a_{12} & & \\ a_{21} & a_{22} & & \\ & & \ddots & \\ & & & \ddots \end{bmatrix} \in \mathbb{R}^{n \times n} \quad B = \begin{bmatrix} b_{11} & b_{12} & \dots & \\ b_{21} & b_{22} & & \\ \vdots & & \ddots & \\ \vdots & & & \ddots \end{bmatrix} \in \mathbb{R}^{p \times q}$$

$$A \otimes B = \begin{bmatrix} a_{11}B & a_{12}B & \dots \\ a_{21}B & a_{22}B & \\ \vdots & & \ddots \end{bmatrix} \in \mathbb{R}^{mp \times mq}$$

$$\overline{A}, \overline{B}, \overline{C}$$

$$v_{\mathcal{L}}(\bar{A} \cdot \bar{B} \cdot \bar{C}) = (C^T \otimes A) \cdot v_{\mathcal{L}}(B)$$

$$A\pi - \pi S = -BL$$

$$V_{SC}(A \rightarrow I) - V_{SC}(I \rightarrow S) = -V_{SC}(BL)$$

$$(I \otimes A) v_{\mathcal{L}}(\pi) - (S^T \otimes I) v_{\mathcal{L}}(\pi) = -v_{\mathcal{L}}(BZ)$$

~~$(I \otimes A)$~~       matrix       $V_{sc}(\pi)$        $V_{sc}(\pi)$   
 $(I \otimes A - S^T \otimes I) V_{sc}(\pi) = -V_{sc}(BL)$

$$Ax = b \Rightarrow x = A^{-1}b$$

$$\Rightarrow \lambda_i \mapsto \sigma_i$$

$$V_{SC}(\pi) = (I \otimes A - S^T \otimes I)^{-1} V_{SC}(-BL)$$

$$\Rightarrow \sigma(A) \cap \sigma(S) = \emptyset$$

Recall  $y(n) = C_1 w(n) + C_2 e^{Ar}(x(n) - \pi w(n))$

$$y_{ss}(n) = \underline{CTT} \cdot w(n)$$

$$\begin{bmatrix} y_{ss}(n_1) \\ y_{ss}(n_2) \\ \vdots \\ y_{ss}(n_p) \end{bmatrix} = \underline{CTT} \begin{bmatrix} w(n_1) \\ w(n_2) \\ \vdots \\ w(n_p) \end{bmatrix}$$

NOTE THAT

$$Y_{ss}(k) = \underbrace{C\Pi}_{1 \times V} \underbrace{W(k)}_{V \times 1}$$

SO

$$\underbrace{\begin{bmatrix} Y_{ss}(k_1) & Y_{ss}(k_2) & \dots & Y_{ss}(k_p) \end{bmatrix}}_{Y \in \mathbb{R}^{1 \times p}} = \underbrace{C\Pi}_{1 \times V} \underbrace{\begin{bmatrix} w(k_1) & w(k_2) & \dots & w(k_p) \end{bmatrix}}_{W \in \mathbb{R}^{V \times p}}$$

MULTIPLY ON THE RIGHT BY  $W^T$

$$YW^T = C\Pi \underbrace{WW^T}_{V \times V}$$

UNDER CERTAIN ASSUMPTIONS (SEE THEOREM 4.12 PAG. 133)

$WW^T$  IS INVERTIBLE

$$\Rightarrow C\Pi = YW^T (WW^T)^{-1}$$

NOTE THAT THIS IS CONSISTENT WITH THEOREM 4.12 PAG. 133. IN FACT

$$VBC(C\Pi) = (C\Pi)^T = (WW^T)^{-1} W Y^T$$

$$\text{LET } \hat{R} = W^T \text{ AND } \cancel{\text{SOME OTHER}} Y = Y^T$$

AND WE OBTAIN (4.34) AT PAG. 133