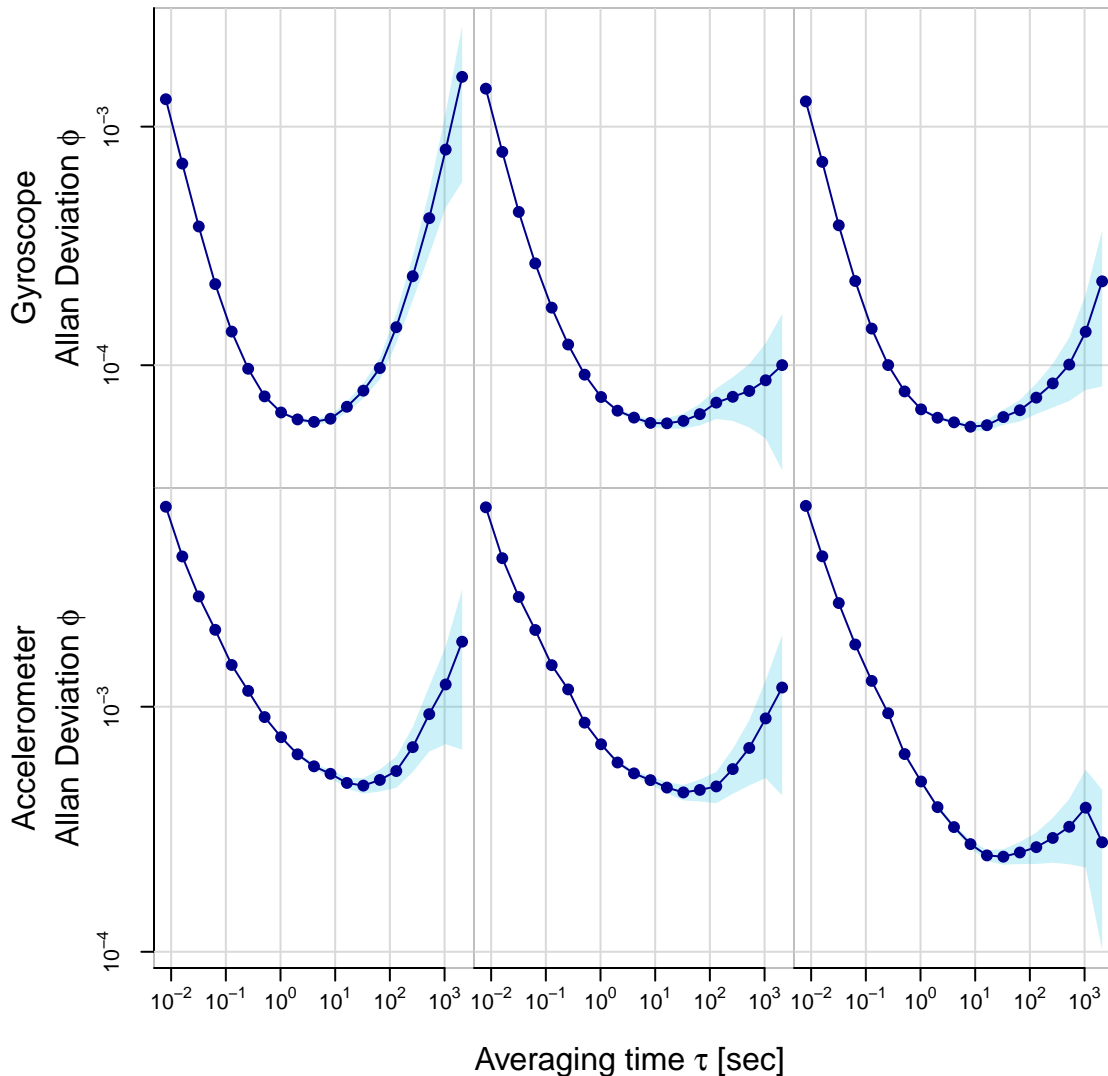


# Allan Variance Representation – NAVCHIP\_FLT @ 250 Hz

Axis – X

Axis – Y

Axis – Z



help("plot.imu\_avar")