ARTIFICIAL INTELLEGNECE

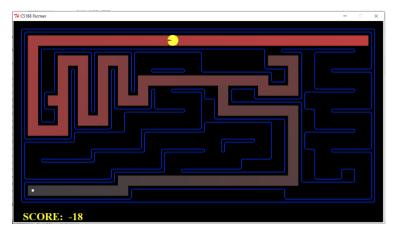
Lab 03

Abstract

Depth First Search, Breath First Search and Varying Cost Function

TASK 01

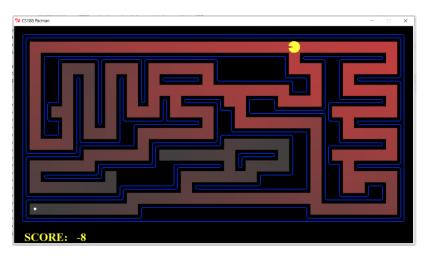
```
import util
Next = util.Stack()
Visited = []
current_position = problem.getStartState()
Next.push((current position, []))
Visited.append(current position)
while Next.isEmpty() == 0:
    current_position, actions = Next.pop()
    for next in problem.getSuccessors(current position):
        next position = next[0]
        next direction = next[1]
        if next position not in Visited:
            if problem.isGoalState(next position):
                return actions + [next_direction]
            else:
                print(Next)
                Next.push((next position, actions + [next direction]))
                Visited.append(next position)
```



```
<util.Queue instance at 0x0000000003949788>
<util.Queue instance at 0x0000000003949788>
<util.Queue instance at 0x0000000003949788>
<util.Queue instance at 0x0000000003949788>
Path found with total cost of 68 in 0.3 seconds
Search nodes expanded: 267
Pacman emerges victorious! Score: 442
Average Score: 442.0
Scores: 442.0
Win Rate: 1/1 (1.00)
Record: Win
```

TASK 02

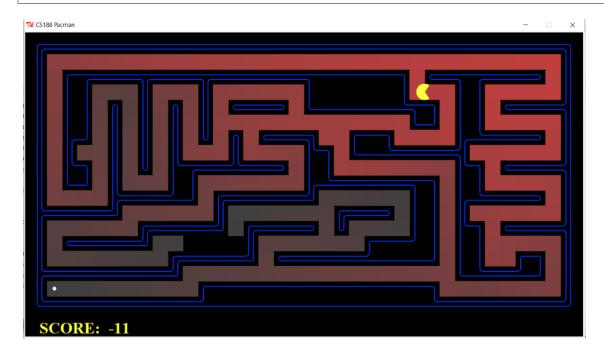
```
import util
Next = util.Queue()
Visited = []
current position = problem.getStartState()
Next.push((current position, []))
Visited.append(current position)
while Next.isEmpty() == 0:
   current_position, actions = Next.pop()
    for next in problem.getSuccessors(current_position):
        next_position = next[0]
        next direction = next[1]
        if next position not in Visited:
            if problem.isGoalState(next position):
                return actions + [next direction]
            else:
                print(Next)
                Next.push((next position, actions + [next direction]))
                Visited.append(next position)
```



```
<util.Queue instance at 0x00000000039B9788>
   <util.Queue instance at 0x00000000039B9788>
  <util.Queue instance at 0x00000000039B9788>
  <util.Queue instance at 0x00000000039B9788>
  Path found with total cost of 68 in 0.2 seconds
Favorites
  Search nodes expanded: 267
  Pacman emerges victorious! Score: 442
ċίΙ
  Average Score: 442.0
  Scores:
                  442.0
  Win Rate:
                 1/1 (1.00)
  Record:
                  Win
```

TASK 03

```
import util import heapq
def update(Next, item, priority):
    for index, (p, c, i) in enumerate(Next.heap):
        if i[0] == item[0]:
            if p <= priority:</pre>
                                  del Next.heap[index]
               break
            Next.heap.append((priority, c, item))
            heapq.heapify(Next.heap)
            break else:
        Next.push(item, priority)
Next = util.PriorityQueue()
Visited = []
current position = problem.getStartState()
Next.push((current_position, []), 0)
Visited.append(current position)
while Next.isEmpty() == 0:
   current_position, current_direction = Next.pop()
    if problem.isGoalState(current position):
        return current direction
    if current position not in Visited:
        Visited.append(current_position)
    for next in problem.getSuccessors(current position):
        next_position = next[0]
        next direction = next[1]
        if next_position not in Visited:
            update(Next, (next position, current direction +
[next_direction]), problem.getCostOfActions(current direction +
[next direction]))
```



```
(venv) D:\Assignments\AI\Lab03\search>python pacman.py -1 mediumMaze -p SearchAgent -a fn=ucs
[SearchAgent] using function ucs
[SearchAgent] using problem type PositionSearchProblem
Path found with total cost of 68 in 0.0 seconds
Search nodes expanded: 269
Pacman emerges victorious! Score: 442
Average Score: 442.0
Scores: 442.0
Win Rate: 1/1 (1.00)
Record: Win
```