OSVP Clip Documentation

Introduction

The OSVP Clip (clip) is a collection of metadata parameters sampled over a specified duration. Each parameter is either:

- static: the parameter has at constant value over the duration of the clip
- dynamic: the parameter is sampled at regular intervals over the duration of the clip

Each parameter is identified by a unique name. It also has a general description as well as a specific set of constraints.

The OSVP Frame (frame) is a collection of metadata parameters that is dynamic and has a synchronous relationship with a video frame. In an OSVP environment this describes live camera position ('tracking') and lens data.

Clip Parameters

`duration`

Description

Duration of the clip

Units

second

Sampling

Static

Constraints

The parameter shall be a rational number whose numerator is in the range [0..2,147,483,647] and denominator in the range (0..4,294,967,295].

`captureFrameRate`

Description

Capture frame rate of the camera

Units

hertz

Sampling

Static

Constraints

The parameter shall be a rational number whose numerator is in the range [0..2,147,483,647] and denominator in the range (0..4,294,967,295].

`activeSensorPhysicalDimensions`

Description

Height and width of the active area of the camera sensor in millimeters

Units

millimeter

Sampling

Static

Constraints

The height and width shall be each be real non-negative numbers.

`activeSensorResolution`

Description

Photosite resolution of the active area of the camera sensor in pixels

Units

pixel

Sampling

Static

Constraints

The height and width shall be each be an integer in the range [0..2,147,483,647].

`make`

Description

Non-blank string naming camera manufacturer

Units

None

Sampling

Static

Constraints

The parameter shall be a Unicode string between 0 and 1023 codepoints.

`model`

Description

Non-blank string identifying camera model

Units

None

Sampling

Static

Constraints

The parameter shall be a Unicode string between 0 and 1023 codepoints.

`serialNumber`

Description

Non-blank string uniquely identifying the camera

Units

None

Sampling

Static

Constraints

The parameter shall be a Unicode string between 0 and 1023 codepoints.

`firmwareVersion`

Description

Non-blank string identifying camera firmware version

Units

None

Sampling

Static

Constraints

The parameter shall be a Unicode string between 0 and 1023 codepoints.

`label`

Description

Non-blank string containing user-determined camera identifier

Units

None

Sampling

Static

Constraints

The parameter shall be a Unicode string between 0 and 1023 codepoints.

`anamorphicSqueeze`

Description

Nominal ratio of height to width of the image of an axis-aligned square captured by the camera sensor. It can be used to de-squeeze images but is not however an exact number over the entire captured area due to a lens' intrinsic analog nature.

Units

None

Sampling

Static

Constraints

The parameter shall be a rational number whose numerator is in the range [0..2,147,483,647] and denominator in the range (0..4,294,967,295].

`isoSpeed`

Description

Arithmetic ISO scale as defined in ISO 12232

Units

None

Sampling

Static

Constraints

The parameter shall be a integer in the range (1..4,294,967,295].

`fdlLink`

Description

URN identifying the ASC Framing Decision List used by the camera.

Units

None

Sampling

Static

Constraints

The parameter shall be a UUID URN as specified in IETF RFC 4122. Only lowercase characters shall be
used. Example: `f81d4fae-7dec-11d0-a765-00a0c91e6bf6`

`shutterAngle`

Description

Shutter speed as a fraction of the capture frame rate. The shutter speed (in units of 1/s) is equal to the value of
the parameter divided by 360 times the capture frame rate.

Units

degree

Sampling

Static

Constraints

The parameter shall be a real number in the range (0..360].

`distortionOverscanMax`

Description

Static maximum overscan factor on lens distortion. This is an alternative to providing dynamic overscan values each frame. Note it should be the maximum of both projection-matrix-based and field-of-view-based rendering as per the OpenLensIO documentation.

Units

None

Sampling

Static

Constraints

The parameter shall be a real number >= 1.

`undistortionOverscanMax`

Description

Static maximum overscan factor on lens undistortion. This is an alternative to providing dynamic overscan values each frame. Note it should be the maximum of both projection-matrix-based and field-of-view-based rendering as per the OpenLensIO documentation.

Units

None

Sampling

Static

Constraints

The parameter shall be a real number >= 1.

`make`

Description

Non-blank string naming lens manufacturer

Units

None

Sampling

Static

Constraints

The parameter shall be a Unicode string between 0 and 1023 codepoints.

`model`

Description

Non-blank string identifying lens model

Units

None

Sampling

Static

Constraints

The parameter shall be a Unicode string between 0 and 1023 codepoints.

`serialNumber`

Description

Non-blank string uniquely identifying the lens

Units

None

Sampling

Static

Constraints

The parameter shall be a Unicode string between 0 and 1023 codepoints.

`firmwareVersion`

Description

Non-blank string identifying lens firmware version

Units

None

Sampling

Static

Constraints

The parameter shall be a Unicode string between 0 and 1023 codepoints.

`nominalFocalLength`

Description

Nominal focal length of the lens. The number printed on the side of a prime lens, e.g. 50 mm, and undefined in the case of a zoom lens.

Units

millimeter

Sampling

Static

Constraints

The parameter shall be a real number greater than 0.

`calibrationHistory`

Description

List of free strings that describe the history of calibrations of the lens.

Units

None

Sampling

Static

`make`

Description

Non-blank string naming tracking device manufacturer

Units

None

Sampling

Static

Constraints

The parameter shall be a Unicode string between 0 and 1023 codepoints.

`model`

Description

Non-blank string identifying tracking device model

Units

None

Sampling

Static

Constraints

The parameter shall be a Unicode string between 0 and 1023 codepoints.

`serialNumber`

Description

Non-blank string uniquely identifying the tracking device

Units

None

Sampling

Static

Constraints

The parameter shall be a Unicode string between 0 and 1023 codepoints.

`firmwareVersion`

Description

Non-blank string identifying tracking device firmware version

Units

None

Sampling

Static

Constraints

The parameter shall be a Unicode string between 0 and 1023 codepoints.

`notes`

Description

Non-blank string containing notes about tracking system

Units

None

Sampling

Regular

Constraints

The parameter shall be a Unicode string between 0 and 1023 codepoints.

`recording`

Description

Boolean indicating whether tracking system is recording data

Units

None

Sampling

Regular

Constraints

The parameter shall be a boolean.

`slate`

Description

Non-blank string describing the recording slate

Units

None

Sampling

Regular

Constraints

The parameter shall be a Unicode string between 0 and 1023 codepoints.

`status`

Description

Non-blank string describing status of tracking system

Units

None

Sampling

Regular

Constraints

The parameter shall be a Unicode string between 0 and 1023 codepoints.

`mode`

Description

Enumerated value indicating whether the sample transport mechanism provides inherent ('external') timing, or whether the transport mechanism lacks inherent timing and so the sample must contain a PTP timestamp itself ('internal') to carry timing information.

Units

None

Sampling

Regular

Constraints

The parameter shall be one of the allowed values.

`recordedTimestamp`

Description

PTP timestamp of the data recording instant, provided for convenience during playback of e.g. pre-recorded tracking data. The timestamp comprises a 48-bit unsigned integer (seconds), a 32-bit unsigned integer

(nanoseconds)

Units

second

Sampling

Regular

Constraints

The parameter shall contain valid number of seconds, nanoseconds elapsed since the start of the epoch.

`sampleRate`

Description

Sample frame rate as a rational number. Drop frame rates such as 29.97 should be represented as e.g. 30000/1001. In a variable rate system this should be estimated from the last sample delta time.

Units

None

Sampling

Regular

Constraints

The parameter shall be a rational number whose numerator is in the range [0..2,147,483,647] and denominator in the range (0..4,294,967,295].

`sampleTimestamp`

Description

PTP timestamp of the data capture instant. Note this may differ from the packet's transmission PTP timestamp. The timestamp comprises a 48-bit unsigned integer (seconds), a 32-bit unsigned integer (nanoseconds)

Units

second

Sampling

Regular

Constraints

The parameter shall contain valid number of seconds, nanoseconds elapsed since the start of the epoch.

sequenceNumber

Description

Integer incrementing with each sample.

Units

None

Sampling

Regular

Constraints

The parameter shall be a integer in the range (0..4,294,967,295].

synchronization

Description

Object describing how the tracking device is synchronized for this sample.

frequency: The frequency of a synchronization signal.This may differ from the sample frame rate for example in a genlocked tracking device. This is not required if the synchronization source is PTP or NTP. locked: Is the tracking device locked to the synchronization source offsets: Offsets in seconds between sync and sample. Critical for e.g. frame remapping, or when using different data sources for position/rotation and lens encoding present: Is the synchronization source present (a synchronization source can be present but not locked if frame rates differ for example) ptp: If the synchronization source is a PTP leader, then this object contains:

- "profile": Specifies the PTP profile in use. This defines the operational rules and parameters for synchronization. For example "SMPTE ST2059-2:2021" for SMPTE 2110 based systems, or "IEEE Std 1588-2019" or "IEEE Std 802.1AS-2020" for industrial applications
- "domain": Identifies the PTP domain the device belongs to. Devices in the same domain can synchronize with each other
- "leaderIdentity": The unique identifier (usually MAC address) of the current PTP leader (grandmaster)
- "leaderPriorities": The priority values of the leader used in the Best Master Clock Algorithm (BMCA). Lower values indicate higher priority
- "priority1": Static priority set by the administrator
- "priority2": Dynamic priority based on the leader's role or clock quality
- "leaderAccuracy": The timing offset in seconds from the sample timestamp to the PTP timestamp
- "meanPathDelay": The average round-trip delay between the device and the PTP leader, measured in seconds source: The source of synchronization must be defined as one of the following:
- "vlan": Integer representing the VLAN ID for PTP traffic (e.g., 100 for VLAN 100)
- "leaderTimeSource": Indicates the leader's source of time, such as GNSS, atomic clock, or NTP
- "genlock": The tracking device has an external black/burst or tri-level analog sync signal that is triggering the capture of tracking samples

- "videoIn": The tracking device has an external video signal that is triggering the capture of tracking samples
- "ptp": The tracking device is locked to a PTP leader
- "ntp": The tracking device is locked to an NTP server

Units

None

Sampling

Regular

Constraints

The parameter shall contain the required valid fields.

`timecode`

Description

SMPTE timecode of the sample. Timecode is a standard for labeling individual frames of data in media systems and is useful for inter-frame synchronization. Frame rate is a rational number, allowing drop frame rates such as that colloquially called 29.97 to be represented exactly, as 30000/1001. The timecode frame rate may differ from the sample frequency. The zero-based sub-frame field allows for finer division of the frame, e.g. interlaced frames have two sub-frames, one per field.

Units

None

Sampling

Regular

Constraints

The parameter shall contain a valid format and hours, minutes, seconds and frames with appropriate min/max values.

`custom`

Description

This list provides optional additional custom coefficients that can extend the existing lens model. The meaning of and how these characteristics are to be applied to a virtual camera would require negotiation between a particular producer and consumer.

Units

None

Sampling

Regular

Constraints

The parameter shall be a tuple of items of the class itemClass. The tuple can be empty

`distortion`

Description

A list of Distortion objects that each define the coefficients for calculating the distortion characteristics of a lens comprising radial distortion coefficients of the spherical distortion (k1-N) and (optionally) the tangential distortion (p1-N). The key 'model' names the distortion model. Typical values for 'model' include "Brown-Conrady D-U" when mapping distorted to undistorted coordinates, and "Brown-Conrady U-D" when mapping undistorted to undistorted coordinates. If not provided, the default model is "Brown-Conrady D-U".

Units

None

Sampling

Regular

Constraints

The list shall contain at least one Distortion object, and in each object the radial and tangential coefficients shall each be real numbers.

`distortionOffset`

Description

Offset in x and y of the centre of distortion of the virtual camera

Units

millimeter

Sampling

Regular

Constraints

X and Y centre shift shall each be real numbers.

`encoders`

Description

Normalised real numbers (0-1) for focus, iris and zoom. Encoders are represented in this way (as opposed to raw integer values) to ensure values remain independent of encoder resolution, minimum and maximum (at an acceptable loss of precision). These values are only relevant in lenses with end-stops that demarcate the 0 and 1 range. Value should be provided in the following directions (if known): Focus: 0=infinite 1=closest Iris: 0=open 1=closed Zoom: 0=wide angle 1=telephoto

Units

None

Sampling

Regular

Constraints

The parameter shall contain at least one normalised values (0..1) for the FIZ encoders.

`entrancePupilOffset`

Description

Offset of the entrance pupil relative to the nominal imaging plane (positive if the entrance pupil is located on the side of the nominal imaging plane that is towards the object, and negative otherwise). Measured in meters as in a render engine it is often applied in the virtual camera's transform chain.

Units

meter

Sampling

Regular

Constraints

The parameter shall be a real number.

`exposureFalloff`

Description

Coefficients for calculating the exposure fall-off (vignetting) of a lens

Units

None

Sampling

Regular

Constraints

The coefficients shall each be real numbers.

`fStop`

Description

The linear f-number of the lens, equal to the focal length divided by the diameter of the entrance pupil.

Units

None

Sampling

Regular

Constraints

The parameter shall be a real number greater than 0.

`pinholeFocalLength`

Description

Distance between the pinhole and the image plane in the simple CGI pinhole camera model.

Units

millimeter

Sampling

Regular

Constraints

The parameter shall be a real number greater than 0.

`focusDistance`

Description

Focus distance/position of the lens

Units

meter

Sampling

Regular

Constraints

The parameter shall be a real number greater than 0.

`projectionOffset`

Description

Offset in x and y of the centre of perspective projection of the virtual camera

Units

millimeter

Sampling

Regular

Constraints

X and Y projection offset shall each be real numbers.

`rawEncoders`

Description

Raw encoder values for focus, iris and zoom. These values are dependent on encoder resolution and before any homing / ranging has taken place.

Units

None

Sampling

Regular

Constraints

The parameter shall contain at least one integer value for the FIZ encoders.

`tStop`

Description

Linear t-number of the lens, equal to the F-number of the lens divided by the square root of the transmittance of the lens.

Units

None

Sampling

Regular

Constraints

The parameter shall be a real number greater than 0.

`protocol`

Description

Name of the protocol in which the sample is being employed, and version of that protocol

Units

None

Sampling

Regular

Constraints

Protocol name is nonblank string; protocol version is basic x.y.z semantic versioning string

`sampleId`

Description

URN serving as unique identifier of the sample in which data is being transported.

Units

None

Sampling

Regular

Constraints

The parameter shall be a UUID URN as specified in IETF RFC 4122. Only lowercase characters shall be used. Example: `f81d4fae-7dec-11d0-a765-00a0c91e6bf6`

`sourceId`

Description

URN serving as unique identifier of the source from which data is being transported.

Units

None

Sampling

Regular

Constraints

The parameter shall be a UUID URN as specified in IETF RFC 4122. Only lowercase characters shall be used. Example: `f81d4fae-7dec-11d0-a765-00a0c91e6bf6`

`sourceNumber`

Description

Number that identifies the index of the stream from a source from which data is being transported. This is most important in the case where a source is producing multiple streams of samples.

Units

None

Sampling

Regular

Constraints

The parameter shall be a integer in the range (0..4,294,967,295].

`relatedSampleIds`

Description

List of sampleId properties of samples related to this sample. The existence of a sample with a given sampleId is not guaranteed.

Units

None

Sampling

Regular

Constraints

The parameter shall be a tuple of items of the class itemClass. The tuple can be empty

`globalStage`

Description

Position of stage origin in global ENU and geodetic coordinates (E, N, U, lat0, lon0, h0). Note this may be dynamic if the stage is inside a moving vehicle.

Units

meter

Sampling

Regular

Constraints

Each field in the GlobalPosition shall be a real number

`transforms`

Description

A list of transforms. Transforms are composed in order with the last in the list representing the X,Y,Z in meters of camera sensor relative to stage origin. The Z axis points upwards and the coordinate system is right-handed. Y points in the forward camera direction (when pan, tilt and roll are zero). For example in an LED volume Y would point towards the centre of the LED wall and so X would point to camera-right. Rotation expressed as euler angles in degrees of the camera sensor relative to stage origin Rotations are intrinsic and are measured around the axes ZXY, commonly referred to as [pan, tilt, roll] Notes on Euler angles: Euler angles are human readable and unlike quarternions, provide the ability for cycles (with angles >360 or <0 degrees). Where a tracking system is providing the pose of a virtual camera, gimbal lock does not present the physical challenges of a robotic system. Conversion to and from quarternions is trivial with an acceptable loss of precision.

Units

meter / degree

Sampling

Regular

Constraints

Each component of each transform shall contain Real numbers.

Reader coverage

The following table indicates the camera parameters supported by each of the readers.

Reader	duration	captureFrameRate	activeSensorPhysicalDimensions	activeSensorReso
RED	+	+	+	
ARRI	+	+	+	

Reader	duration	captureFrameRate	activeSensorPhysicalDimensions	activeSensorReso
Venice	+	+	+	
Canon	+			

Clip JSON Schema

```
"$id": "https://opentrackio.org/schema.json",
"$schema": "https://json-schema.org/draft/2020-12/schema",
"type": "object",
"properties": {
  "static": {
    "type": "object",
    "properties": {
      "duration": {
        "type": "object",
        "properties": {
          "num": {
            "type": "integer",
            "maximum": 2147483647,
            "minimum": 1
          },
          "denom": {
            "type": "integer",
            "maximum": 4294967295,
            "minimum": 1
          }
        },
        "required": [
          "num",
          "denom"
        ],
        "additionalProperties": false,
        "description": "Duration of the clip",
        "units": "second"
      },
      "camera": {
        "type": "object",
        "properties": {
          "captureFrameRate": {
            "type": "object",
            "properties": {
              "num": {
                "type": "integer",
                "maximum": 2147483647,
                "minimum": 1
              },
              "denom": {
                "type": "integer",
                "maximum": 4294967295,
                "minimum": 1
              }
            },
            "required": [
```

```json
        "num",
        "denom"
      ],
      "additionalProperties": false,
      "description": "Capture frame rate of the camera",
      "units": "hertz"
    },
    "activeSensorPhysicalDimensions": {
      "type": "object",
      "properties": {
        "height": {
          "type": "number",
          "minimum": 0.0
        },
        "width": {
          "type": "number",
          "minimum": 0.0
        }
      },
      "required": [
        "height",
        "width"
      ],
      "description": "Height and width of the active area of the camera sensor in milli
      "additionalProperties": false,
      "units": "millimeter"
    },
    "activeSensorResolution": {
      "type": "object",
      "properties": {
        "height": {
          "type": "integer",
          "maximum": 2147483647,
          "minimum": 0
        },
        "width": {
          "type": "integer",
          "maximum": 2147483647,
          "minimum": 0
        }
      },
      "required": [
        "height",
        "width"
      ],
      "description": "Photosite resolution of the active area of the camera sensor in p
      "additionalProperties": false,
      "units": "pixel"
    },
    "make": {
      "type": "string",
      "minLength": 1,
      "maxLength": 1023,
      "description": "Non-blank string naming camera manufacturer"
    },
    "model": {
      "type": "string",
```

```json
      "minLength": 1,
      "maxLength": 1023,
      "description": "Non-blank string identifying camera model"
    },
    "serialNumber": {
      "type": "string",
      "minLength": 1,
      "maxLength": 1023,
      "description": "Non-blank string uniquely identifying the camera"
    },
    "firmwareVersion": {
      "type": "string",
      "minLength": 1,
      "maxLength": 1023,
      "description": "Non-blank string identifying camera firmware version"
    },
    "label": {
      "type": "string",
      "minLength": 1,
      "maxLength": 1023,
      "description": "Non-blank string containing user-determined camera identifier"
    },
    "anamorphicSqueeze": {
      "type": "object",
      "properties": {
        "num": {
          "type": "integer",
          "maximum": 2147483647,
          "minimum": 1
        },
        "denom": {
          "type": "integer",
          "maximum": 4294967295,
          "minimum": 1
        }
      },
      "required": [
        "num",
        "denom"
      ],
      "additionalProperties": false,
      "description": "Nominal ratio of height to width of the image of an axis-aligned\
    },
    "isoSpeed": {
      "type": "integer",
      "maximum": 4294967295,
      "minimum": 1,
      "description": "Arithmetic ISO scale as defined in ISO 12232"
    },
    "fdlLink": {
      "type": "string",
      "pattern": "^urn:uuid:[0-9a-f]{8}-[0-9a-f]{4}-[0-9a-f]{4}-[0-9a-f]{4}-[0-9a-f]{12
      "description": "URN identifying the ASC Framing Decision List used by the camera.
    },
    "shutterAngle": {
      "type": "number",
      "maximum": 360.0,
```

```json
            "minimum": 0.0,
            "description": "Shutter speed as a fraction of the capture frame rate. The shutte
            "units": "degree"
          }
        },
        "additionalProperties": false
      },
      "lens": {
        "type": "object",
        "properties": {
          "distortionOverscanMax": {
            "type": "number",
            "minimum": 1.0,
            "description": "Static maximum overscan factor on lens distortion. This is an\nal
          },
          "undistortionOverscanMax": {
            "type": "number",
            "minimum": 1.0,
            "description": "Static maximum overscan factor on lens undistortion. This is an\n
          },
          "make": {
            "type": "string",
            "minLength": 1,
            "maxLength": 1023,
            "description": "Non-blank string naming lens manufacturer"
          },
          "model": {
            "type": "string",
            "minLength": 1,
            "maxLength": 1023,
            "description": "Non-blank string identifying lens model"
          },
          "serialNumber": {
            "type": "string",
            "minLength": 1,
            "maxLength": 1023,
            "description": "Non-blank string uniquely identifying the lens"
          },
          "firmwareVersion": {
            "type": "string",
            "minLength": 1,
            "maxLength": 1023,
            "description": "Non-blank string identifying lens firmware version"
          },
          "nominalFocalLength": {
            "type": "number",
            "exclusiveMinimum": 0.0,
            "description": "Nominal focal length of the lens. The number printed on the side\
            "units": "millimeter"
          },
          "calibrationHistory": {
            "type": "array",
            "description": "List of free strings that describe the history of calibrations of
            "items": {
              "type": "string",
              "minLength": 1,
              "maxLength": 1023
```

```json
        }
      }
    },
    "additionalProperties": false
  },
  "tracker": {
    "type": "object",
    "properties": {
      "make": {
        "type": "string",
        "minLength": 1,
        "maxLength": 1023,
        "description": "Non-blank string naming tracking device manufacturer"
      },
      "model": {
        "type": "string",
        "minLength": 1,
        "maxLength": 1023,
        "description": "Non-blank string identifying tracking device model"
      },
      "serialNumber": {
        "type": "string",
        "minLength": 1,
        "maxLength": 1023,
        "description": "Non-blank string uniquely identifying the tracking device"
      },
      "firmwareVersion": {
        "type": "string",
        "minLength": 1,
        "maxLength": 1023,
        "description": "Non-blank string identifying tracking device firmware version"
      }
    },
    "additionalProperties": false
  }
},
"additionalProperties": false
},
"tracker": {
  "type": "object",
  "properties": {
    "notes": {
      "type": "string",
      "minLength": 1,
      "maxLength": 1023,
      "description": "Non-blank string containing notes about tracking system"
    },
    "recording": {
      "type": "boolean",
      "description": "Boolean indicating whether tracking system is recording data"
    },
    "slate": {
      "type": "string",
      "minLength": 1,
      "maxLength": 1023,
      "description": "Non-blank string describing the recording slate"
    },
```

```json
        "status": {
          "type": "string",
          "minLength": 1,
          "maxLength": 1023,
          "description": "Non-blank string describing status of tracking system"
        }
      },
      "additionalProperties": false
    },
    "timing": {
      "type": "object",
      "properties": {
        "mode": {
          "enum": [
            "internal",
            "external"
          ],
          "type": "string",
          "description": "Enumerated value indicating whether the sample transport mechanism\np
        },
        "recordedTimestamp": {
          "type": "object",
          "properties": {
            "seconds": {
              "type": "integer",
              "maximum": 281474976710655,
              "minimum": 0
            },
            "nanoseconds": {
              "type": "integer",
              "maximum": 4294967295,
              "minimum": 0
            }
          },
          "required": [
            "seconds",
            "nanoseconds"
          ],
          "additionalProperties": false,
          "units": "second",
          "description": "PTP timestamp of the data recording instant, provided for convenience
        },
        "sampleRate": {
          "type": "object",
          "properties": {
            "num": {
              "type": "integer",
              "maximum": 2147483647,
              "minimum": 1
            },
            "denom": {
              "type": "integer",
              "maximum": 4294967295,
              "minimum": 1
            }
          },
          "required": [
```

```
        "num",
        "denom"
      ],
      "additionalProperties": false,
      "description": "Sample frame rate as a rational number. Drop frame rates such as\n29.
    },
    "sampleTimestamp": {
      "type": "object",
      "properties": {
        "seconds": {
          "type": "integer",
          "maximum": 281474976710655,
          "minimum": 0
        },
        "nanoseconds": {
          "type": "integer",
          "maximum": 4294967295,
          "minimum": 0
        }
      },
      "required": [
        "seconds",
        "nanoseconds"
      ],
      "additionalProperties": false,
      "units": "second",
      "description": "PTP timestamp of the data capture instant. Note this may differ\nfrom
    },
    "sequenceNumber": {
      "type": "integer",
      "maximum": 4294967295,
      "minimum": 0,
      "description": "Integer incrementing with each sample."
    },
    "synchronization": {
      "type": "object",
      "properties": {
        "locked": {
          "type": "boolean"
        },
        "source": {
          "enum": [
            "genlock",
            "videoIn",
            "ptp",
            "ntp"
          ],
          "type": "string"
        },
        "frequency": {
          "type": "object",
          "properties": {
            "num": {
              "type": "integer",
              "maximum": 2147483647,
              "minimum": 1
            },
```

```json
        "denom": {
          "type": "integer",
          "maximum": 4294967295,
          "minimum": 1
        }
      },
      "required": [
        "num",
        "denom"
      ],
      "additionalProperties": false
    },
    "offsets": {
      "type": "object",
      "properties": {
        "translation": {
          "type": "number"
        },
        "rotation": {
          "type": "number"
        },
        "lensEncoders": {
          "type": "number"
        }
      },
      "additionalProperties": false
    },
    "present": {
      "type": "boolean"
    },
    "ptp": {
      "type": "object",
      "properties": {
        "profile": {
          "enum": [
            "IEEE Std 1588-2019",
            "IEEE Std 802.1AS-2020",
            "SMPTE ST2059-2:2021"
          ],
          "type": "string"
        },
        "domain": {
          "type": "integer",
          "maximum": 127,
          "minimum": 0
        },
        "leaderIdentity": {
          "type": "string",
          "minLength": 1,
          "maxLength": 1023,
          "pattern": "(?:^[0-9a-f]{2}(?::[0-9a-f]{2}){5}$)|(?:^[0-9a-f]{2}(?:-[0-9a-f]{
        },
        "leaderPriorities": {
          "type": "object",
          "properties": {
            "priority1": {
                "type": "integer",
```

```
              "maximum": 255,
              "minimum": 0
            },
            "priority2": {
              "type": "integer",
              "maximum": 255,
              "minimum": 0
            }
          },
          "required": [
            "priority1",
            "priority2"
          ],
          "description": "Data structure for PTP synchronization priorities",
          "additionalProperties": false
        },
        "leaderAccuracy": {
          "type": "number",
          "minimum": 0.0
        },
        "leaderTimeSource": {
          "enum": [
            "GNSS",
            "Atomic clock",
            "NTP"
          ],
          "type": "string"
        },
        "meanPathDelay": {
          "type": "number",
          "minimum": 0.0
        },
        "vlan": {
          "type": "integer",
          "maximum": 4294967295,
          "minimum": 0
        }
      },
      "required": [
        "profile",
        "domain",
        "leaderIdentity",
        "leaderPriorities",
        "leaderAccuracy",
        "meanPathDelay"
      ],
      "additionalProperties": false
    }
  },
  "required": [
    "locked",
    "source"
  ],
  "additionalProperties": false,
  "description": "Object describing how the tracking device is synchronized for this\ns
},
"timecode": {
```

```json
      "type": "object",
      "properties": {
        "hours": {
          "type": "integer",
          "maximum": 23,
          "minimum": 0
        },
        "minutes": {
          "type": "integer",
          "maximum": 59,
          "minimum": 0
        },
        "seconds": {
          "type": "integer",
          "maximum": 59,
          "minimum": 0
        },
        "frames": {
          "type": "integer",
          "maximum": 119,
          "minimum": 0
        },
        "frameRate": {
          "type": "object",
          "properties": {
            "num": {
              "type": "integer",
              "maximum": 2147483647,
              "minimum": 1
            },
            "denom": {
              "type": "integer",
              "maximum": 4294967295,
              "minimum": 1
            }
          },
          "required": [
            "num",
            "denom"
          ],
          "additionalProperties": false
        },
        "subFrame": {
          "type": "integer",
          "maximum": 4294967295,
          "minimum": 0
        }
      },
      "required": [
        "hours",
        "minutes",
        "seconds",
        "frames",
        "frameRate"
      ],
      "description": "SMPTE timecode of the sample. Timecode is a standard for labeling\nir
      "additionalProperties": false
```

```json
          }
        },
        "additionalProperties": false
      },
      "lens": {
        "type": "object",
        "properties": {
          "custom": {
            "type": "array",
            "items": {
              "type": "number"
            },
            "description": "This list provides optional additional custom coefficients that can \
          },
          "distortion": {
            "type": "array",
            "items": {
              "type": "object",
              "properties": {
                "model": {
                  "type": "string",
                  "minLength": 1,
                  "maxLength": 1023
                },
                "radial": {
                  "type": "array",
                  "items": {
                    "type": "number"
                  },
                  "minItems": 1
                },
                "tangential": {
                  "type": "array",
                  "items": {
                    "type": "number"
                  },
                  "minItems": 1
                },
                "overscan": {
                  "type": "number",
                  "minimum": 1.0,
                  "description": "Overscan factor on lens [un]distortion. Overscan may be provide
                }
              },
              "required": [
                "radial"
              ],
              "additionalProperties": false
            },
            "minItems": 1,
            "description": "A list of Distortion objects that each define the coefficients for\n
          },
          "distortionOffset": {
            "type": "object",
            "properties": {
              "x": {
                "type": "number"
```

```
        },
        "y": {
          "type": "number"
        }
      },
      "required": [
        "x",
        "y"
      ],
      "additionalProperties": false,
      "description": "Offset in x and y of the centre of distortion of the virtual camera",
      "units": "millimeter"
    },
    "encoders": {
      "type": "object",
      "properties": {
        "focus": {
          "type": "number",
          "maximum": 1.0,
          "minimum": 0.0
        },
        "iris": {
          "type": "number",
          "maximum": 1.0,
          "minimum": 0.0
        },
        "zoom": {
          "type": "number",
          "maximum": 1.0,
          "minimum": 0.0
        }
      },
      "additionalProperties": false,
      "description": "Normalised real numbers (0-1) for focus, iris and zoom.\nEncoders are
      "anyOf": [
        {
          "required": [
            "focus"
          ]
        },
        {
          "required": [
            "iris"
          ]
        },
        {
          "required": [
            "zoom"
          ]
        }
      ]
    },
    "entrancePupilOffset": {
      "type": "number",
      "description": "Offset of the entrance pupil relative to the nominal imaging plane\n(
      "units": "meter"
    },
```

```json
      "exposureFalloff": {
        "type": "object",
        "properties": {
          "a1": {
            "type": "number"
          },
          "a2": {
            "type": "number"
          },
          "a3": {
            "type": "number"
          }
        },
        "required": [
          "a1"
        ],
        "additionalProperties": false,
        "description": "Coefficients for calculating the exposure fall-off (vignetting) of\na
      },
      "fStop": {
        "type": "number",
        "exclusiveMinimum": 0.0,
        "description": "The linear f-number of the lens, equal to the focal length divided\nb
      },
      "pinholeFocalLength": {
        "type": "number",
        "exclusiveMinimum": 0.0,
        "description": "Distance between the pinhole and the image plane in the simple CGI pi
        "units": "millimeter"
      },
      "focusDistance": {
        "type": "number",
        "exclusiveMinimum": 0.0,
        "description": "Focus distance/position of the lens",
        "units": "meter"
      },
      "projectionOffset": {
        "type": "object",
        "properties": {
          "x": {
            "type": "number"
          },
          "y": {
            "type": "number"
          }
        },
        "required": [
          "x",
          "y"
        ],
        "additionalProperties": false,
        "description": "Offset in x and y of the centre of perspective projection of the\nvir
        "units": "millimeter"
      },
      "rawEncoders": {
        "type": "object",
        "properties": {
```

```
      "focus": {
        "type": "integer",
        "maximum": 4294967295,
        "minimum": 0
      },
      "iris": {
        "type": "integer",
        "maximum": 4294967295,
        "minimum": 0
      },
      "zoom": {
        "type": "integer",
        "maximum": 4294967295,
        "minimum": 0
      }
    },
    "additionalProperties": false,
    "description": "Raw encoder values for focus, iris and zoom.\nThese values are depend
    "anyOf": [
      {
        "required": [
          "focus"
        ]
      },
      {
        "required": [
          "iris"
        ]
      },
      {
        "required": [
          "zoom"
        ]
      }
    ]
  },
  "tStop": {
    "type": "number",
    "exclusiveMinimum": 0.0,
    "description": "Linear t-number of the lens, equal to the F-number of the lens\ndivic
  }
},
"additionalProperties": false
},
"protocol": {
  "type": "object",
  "properties": {
    "name": {
      "type": "string",
      "minLength": 1,
      "maxLength": 1023
    },
    "version": {
      "type": "array",
      "items": {
        "type": "integer",
        "maximum": 9,
```

```json
          "minimum": 0
        },
        "minItems": 3,
        "maxItems": 3
      }
    },
    "required": [
      "name",
      "version"
    ],
    "additionalProperties": false,
    "description": "Name of the protocol in which the sample is being employed, and\nversion
  },
  "sampleId": {
    "type": "string",
    "pattern": "^urn:uuid:[0-9a-f]{8}-[0-9a-f]{4}-[0-9a-f]{4}-[0-9a-f]{4}-[0-9a-f]{12}$",
    "description": "URN serving as unique identifier of the sample in which data is\nbeing tr
  },
  "sourceId": {
    "type": "string",
    "pattern": "^urn:uuid:[0-9a-f]{8}-[0-9a-f]{4}-[0-9a-f]{4}-[0-9a-f]{4}-[0-9a-f]{12}$",
    "description": "URN serving as unique identifier of the source from which data is\nbeing
  },
  "sourceNumber": {
    "type": "integer",
    "maximum": 4294967295,
    "minimum": 0,
    "description": "Number that identifies the index of the stream from a source from which\n
  },
  "relatedSampleIds": {
    "type": "array",
    "items": {
      "type": "string",
      "pattern": "^urn:uuid:[0-9a-f]{8}-[0-9a-f]{4}-[0-9a-f]{4}-[0-9a-f]{4}-[0-9a-f]{12}$"
    },
    "description": "List of sampleId properties of samples related to this sample. The\nexist
  },
  "globalStage": {
    "type": "object",
    "properties": {
      "E": {
        "type": "number"
      },
      "N": {
        "type": "number"
      },
      "U": {
        "type": "number"
      },
      "lat0": {
        "type": "number"
      },
      "lon0": {
        "type": "number"
      },
      "h0": {
        "type": "number"
```

```
        }
      },
      "required": [
        "E",
        "N",
        "U",
        "lat0",
        "lon0",
        "h0"
      ],
      "description": "Position of stage origin in global ENU and geodetic coordinates\n(E, N, U
      "additionalProperties": false,
      "units": "meter"
    },
    "transforms": {
      "type": "array",
      "items": {
        "type": "object",
        "properties": {
          "translation": {
            "type": "object",
            "properties": {
              "x": {
                "type": "number"
              },
              "y": {
                "type": "number"
              },
              "z": {
                "type": "number"
              }
            },
            "additionalProperties": false,
            "units": "meter"
          },
          "rotation": {
            "type": "object",
            "properties": {
              "pan": {
                "type": "number"
              },
              "tilt": {
                "type": "number"
              },
              "roll": {
                "type": "number"
              }
            },
            "additionalProperties": false,
            "units": "degree"
          },
          "scale": {
            "type": "object",
            "properties": {
              "x": {
                "type": "number"
              },
```

```json
              "y": {
                "type": "number"
              },
              "z": {
                "type": "number"
              }
            },
            "additionalProperties": false
          },
          "id": {
            "type": "string",
            "minLength": 1,
            "maxLength": 1023
          }
        },
        "required": [
          "translation",
          "rotation"
        ],
        "additionalProperties": false
      },
      "minItems": 1,
      "description": "A list of transforms.\nTransforms are composed in order with the last in
      "units": "meter / degree",
      "uniqueItems": false
    }
  }
}
```