PROJECT REPORT

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Subject: Artificial Intelligence

Project Name: Helmet Detection

Helmet Detection

Introduction:-

In Helmet Detection, we will train our custom dataset for the detection. The motive is to detect the people who wearing helmets on main roads and police will easily find those who don't wear a helmet and will take strict action against them. We will use Yolov3 model of training purpose and our dataset consist of more than 500 images.

We made the videos of a helmet and, by using Python script we break the video into images. In the second step, annotation of the dataset by using the Label Image Tool after labeling the dataset, then a process of training will start using a powerful GPU (GTX 1660 Super X).

Tools:-

1. Python

By using python we write two programs for our project, one for real-time helmet detection and another for the helmet detection using video.

2. Yolo

We trained our data set on Yolo architecture with the best's result of mean average precision and benchmark.

3. Ubuntu

We use Ubuntu operating system for the project. Because it professional and easy to train the data set and run on it.

4. Image label tool (Annotation)

Image label tool is used to annotate the data set correctly in order to train and test the data set.

5. Darkflow

Darkflow is used to for the real time helmet detection because the Yolo few version do not support the real time helmet detection. We use this as a secondary.

Problem:-

Nowadays, many accidents are being reported. It has been reported that the majority of cases are youngsters because they do not take safety precautions and not wear the helmet with riding on a motorcycle. According to a survey, studies have shown that wearing a bike helmet reduces your risk of serious head injury by about 70 percent, to avoid motorcycle accidents we are trying to solve this problem by using Helmet detection.

Results:-





Code:

Real Time Helmet Detection:-

```
from darkflow.net.build import TFNet
import matplotlib.pyplot as plt
import tf_slim as slim
import time
import numpy as np
import os
import cv2
options = {
    'model': 'yolov2-obj-helemt.cfg',
    'load':'bin/yolo-obj_best-helmet.weights',
    'threshold': 0.8,
    'gpu': 0
tfnet = TFNet(options)
filename = 'video125.avi'
frames_per_second = 244.0
res = '720p'
# Set resolution for the video capture
# Function adapted from https://kirr.co/016qmh
def change_res(capture, width, height):
    capture.set(3, width)
    capture.set(4, height)
# Standard Video Dimensions Sizes
```

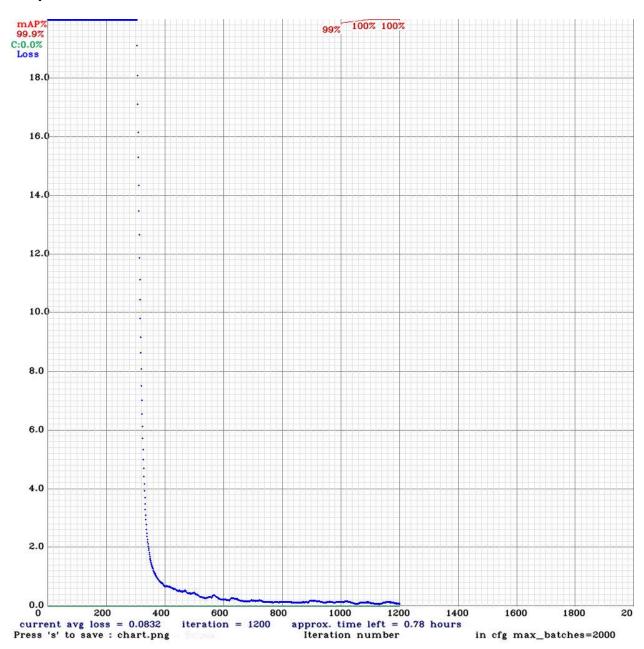
```
STD DIMENSIONS = {
    "480p": (640, 480),
    "720p": (1280, 720),
    "1080p": (1920, 1080),
    "4k": (3840, 2160),
# grab resolution dimensions and set video capture to it.
def get_dims(capture, res='1080p'):
    width, height = STD DIMENSIONS["480p"]
    if res in STD DIMENSIONS:
        width,height = STD DIMENSIONS[res]
    ## change the current caputre device
    ## to the resulting resolution
    change_res(capture, width, height)
    return width, height
# Video Encoding, might require additional installs
# Types of Codes: http://www.fourcc.org/codecs.php
VIDEO_TYPE = {
    'avi': cv2.VideoWriter fourcc(*'XVID'),
    #'mp4': cv2.VideoWriter fourcc(*'H264'),
    'mp4': cv2.VideoWriter fourcc(*'XVID'),
def get_video_type(filename):
   filename, ext = os.path.splitext(filename)
    if ext in VIDEO TYPE:
      return VIDEO TYPE[ext]
    return VIDEO_TYPE['avi']
capture = cv2.VideoCapture(0)
path = 'Helmet-DetectingImage/'
output = cv2.VideoWriter(filename, get_video_type(filename), 25, get_dims(capture
, res))
colors = [tuple(255 * np.random.rand(3)) for _ in range(5)]
i = 0
frame rate divider = 3
while(capture.isOpened()) :
    stime = time.time()
```

```
ret, frame = capture.read()
    if ret:
        if i % frame_rate_divider == 0:
            results = tfnet.return predict(frame)
            for color, result in zip(colors, results):
                tl = (result['topleft']['x'], result['topleft']['y'])
                br = (result['bottomright']['x'], result['bottomright']['y'])
                label = result['label']
                confidence = result['confidence']
                text = '{}: {:.0f}%'.format(label, confidence * 100)
                frame = cv2.rectangle(frame, tl, br, color, 5)
                frame = cv2.putText(frame, text, t1,cv2.FONT_HERSHEY_COMPLEX, 1,
(0, 0, 0), 2)
                image = np.array(frame)
            if confidence > 0.9 and label == "Helmet" :
               cv2.imwrite(os.path.join(path , 'helmet.png'), image)
            output.write(frame)
            cv2.imshow('frame', frame)
            print('FPS {:.1f}'.format(1 / (time.time() - stime)))
            i +=1
        else:
            i +=1
        if cv2.waitKey(1) & 0xFF == ord('q'):
            break
    else:
        break
#while True:
    ret, frame = cap.read()
    out.write(frame)
     cv2.imshow('frame',frame)
     if cv2.waitKey(1) & 0xFF == ord('q'):
        break
capture.release()
output.release()
cv2.destroyAllWindows()
```

Helmet Detection using Video:-

```
import cv2
from darkflow.net.build import TFNet
import matplotlib.pyplot as plt
import numpy as np
import time
import os
import tf_slim as slim
options = {
 'model': 'yolov2-obj-helemt.cfg',
 'load': 'bin/yolo-obj_best-helmet.weights',
 'threshold': 0.6,
 'gpu': 0
tfnet = TFNet(options)
cap = cv2.VideoCapture('h1.mp4')
path = 'HelmetDataset/'
colors=[tuple(255 * np.random.rand(3)) for i in range(5)]
while(cap.isOpened()):
    stime= time.time()
    ret, frame = cap.read()
    results = tfnet.return_predict(frame)
    if ret:
        for color, result in zip(colors, results):
            tl = (result['topleft']['x'], result['topleft']['y'])
            br = (result['bottomright']['x'], result['bottomright']['y'])
            label = result['label']
            confidence = result['confidence']
            frame= cv2.rectangle(frame, tl, br, color, 7)
            frame= cv2.putText(frame, label, t1, cv2.FONT_HERSHEY_TRIPLEX, 1, (0,
0,0), 2)
        cv2.imshow('frame', frame)
        image = np.array(frame)
        if confidence > 0.8 and label == "Helmet" :
          cv2.imwrite(os.path.join(path , 'helmet.png'), image)
        print('FPS {:1f}'.format(1/(time.time() -stime)))
        if cv2.waitKey(1) & 0xFF == ord('q'):
            break
    else:
        break
cap.release()
cv2.destroyAllWindows()
```

Graph:-



Conclusion:-

Helmet detection, mostly in every developed country helmet detection is implemented to charge fine who are not wearing helmet during riding a bike. This is the main motive behind our project is safety of the people who do not wear helmet while riding.

<u>GITHUB LINKS:</u> <u>Syed Muhammad Raza:</u> https://github.com/SMRaza1009/Artificial-Intelligence	