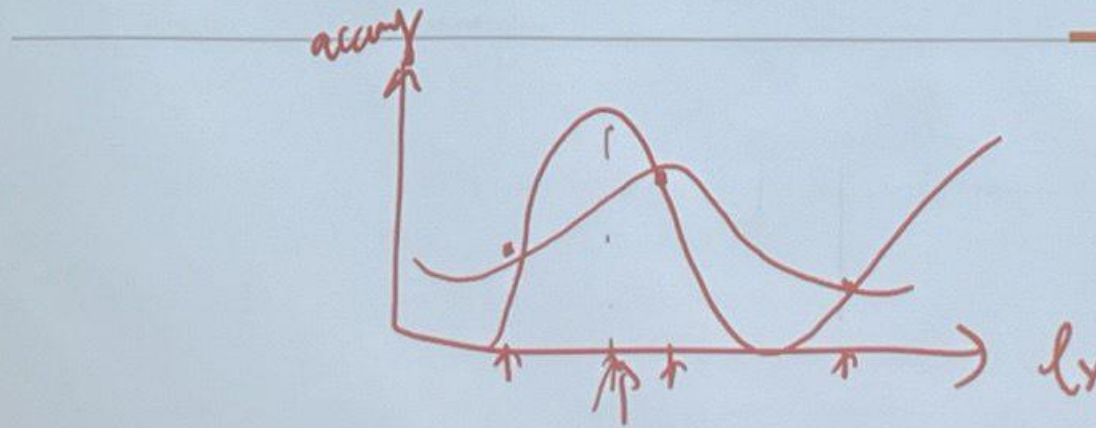Financial Data Science

Lecture 10
Bayesian Optimization for Financial Decision Making

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Video tutorial

Bayesian optimization
https://youtu.be/luQLG3ZEtYc

Gaussian process and acquisition function
https://youtu.be/laziyKsImQY

Improving pairs trading strategy using Bayesian optimization https://youtu.be/621QTVIkUfo

Introducing trend trading

- Trend trading is a type of trading strategy that captures gains by analyzing an asset's momentum in a particular direction.

- The trend refers to an asset price that is moving in one overall direction, such as up or down. The momentum refers to the capacity for the asset's price trend to sustain itself going forward.

- The trend-following strategy is designed to take advantage of forward-looking uptrends with new highs or anticipated downtrends with new lows.
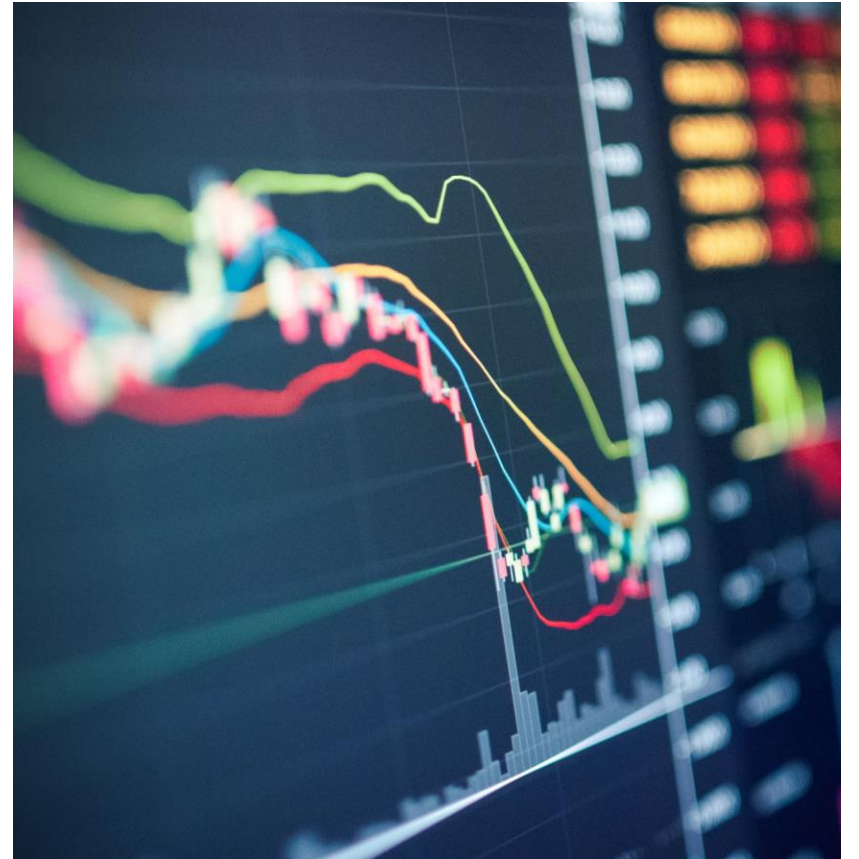
Understanding technical indicators
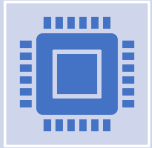
Technical indicators are mathematical calculations based on historical price (high, low, open, close, etc.) or volume, and can be used to determine entry and exit points for trades.

Technical indicators are highly security-dependent: what can be a good technical indicator for a particular security might not hold the case for the other.
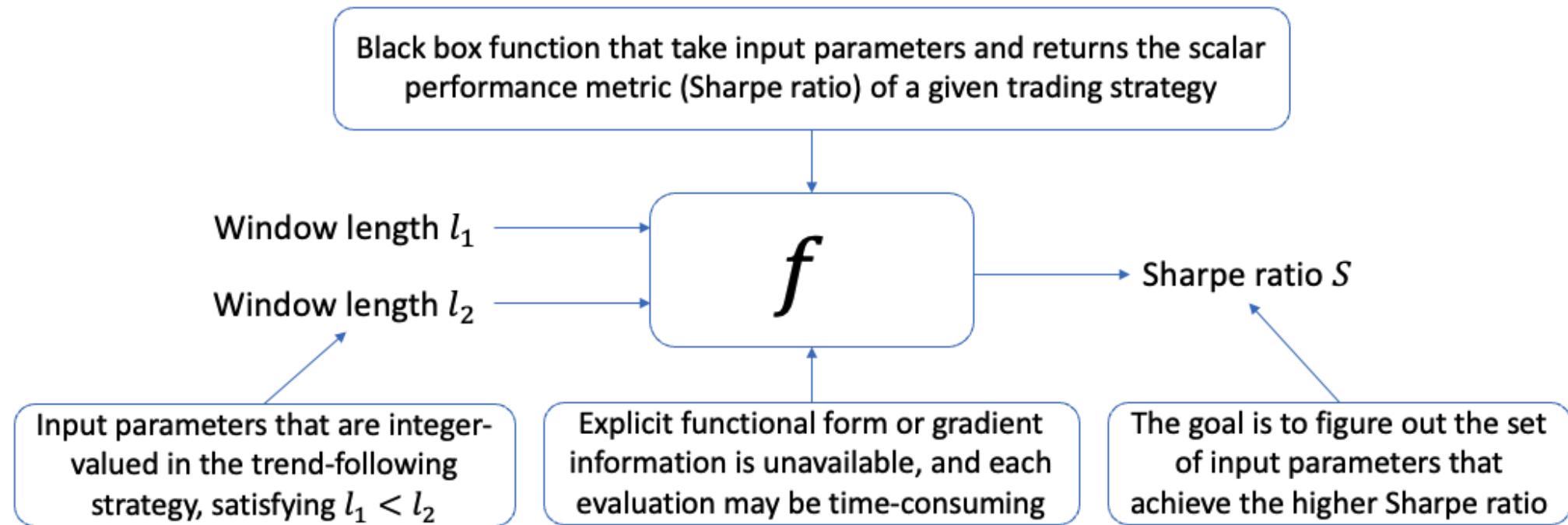
Technical indicators help confirm if the market is following a trend or in a range-bound situation, oscillating within a price range.

Optimizing trading strategies

- Since different testing periods likely exhibit different characteristics in terms of the asset price curve, a robust approach is to backtest a specific set of parameters over different test periods that cover most representative scenarios.

- However, manually fine-tuning a trading strategy by setting different parameter values is an extremely time-consuming process. On the one hand, the number of possible parameter values to test out may simply be too large.

- On the other hand, backtesting each specific set of parameters is not instantaneous. Instead, each round of execution may take very long, thus further exacerbating the challenge in the global search for the optimal strategy.

Parameters in trading strategies

- The parameters serve as the input variables to a specific trading strategy. A typical trading strategy has one or more parameters, each assuming a particular value within the pre-specified range.

- Example: the trend following strategy covered earlier. This trading strategy relies on two moving averages to generate a trading signal: a short-term moving average and a long-term moving average.

- This results in an objective function, where the output is the Sharpe ratio S over a specific backtesting period, the input parameters are window lengths l_1 and l_2, and we can represent the objective function as $S = f(l_1, l_2)$. Here, f represents a black-box function, which means we do not have its explicit mathematical form or its derivative information.

Black box function that take input parameters and returns the scalar performance metric (Sharpe ratio) of a given trading strategy

Window length l_1

Window length l_2

f

Sharpe ratio S

Input parameters that are integer-valued in the trend-following strategy, satisfying $l_1 < l_2$

Explicit functional form or gradient information is unavailable, and each evaluation may be time-consuming

The goal is to figure out the set of input parameters that achieve the higher Sharpe ratio

The optimization problem

- The selected trading strategy manifests as an unknown function, and our goal is to search for the optimal set of window lengths that deliver the highest performance metric, the Sharpe ratio in this case.

Global optimization

- Optimization aims to locate the optimal set of parameters of interest across the whole search domain by carefully allocating limited resources.

- The optimization procedure tries to locate the global maximum f^* or its corresponding location x^* in a principled and systematic manner. Mathematically, we wish to locate f^* where
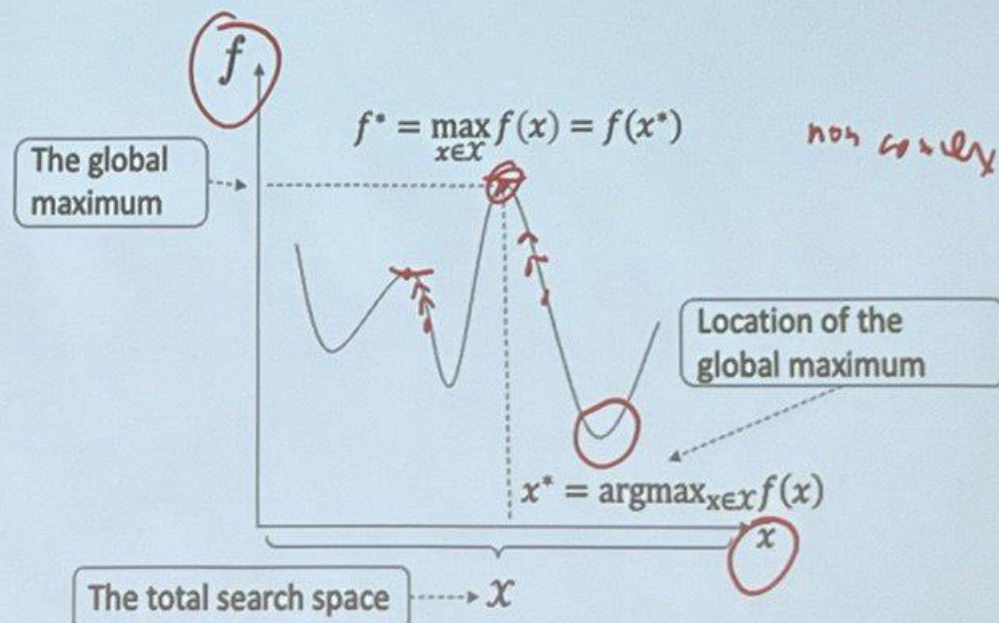
$$f^* = \max_{x \in \mathcal{X}} f(x) = f(x^*)$$

- Or equivalently, we are interested in its location x^* where

$$x^* = \text{argmax}_{x \in \mathcal{X}} f(x)$$

Global optimization

- An example objective function with the global maximum f^* and its location x^*. The goal of global optimization is to systematically reason about a series of sampling decisions so as to locate the global maximum as fast as possible.

$f^* = \max_{x \in X} f(x) = f(x^*)$

non convex

The global maximum

Location of the global maximum

$x^* = \mathrm{argmax}_{x \in X} f(x)$

The total search space $\cdots\rightarrow x$

Objective function

Three possible functional forms. On the left is a convex function whose optimization is easy. In the middle is a nonconvex function with multiple local minina, and on the right is also a nonconvex function with a wide flat region full of saddle points. Optimization for the latter two cases takes a lot more work than for the first case.

Convex function with a unique global minimum

Non-convex function with multiple local minima

Non-convex function with a flat region consisting of many saddle points
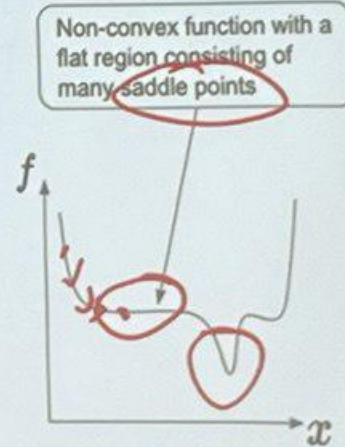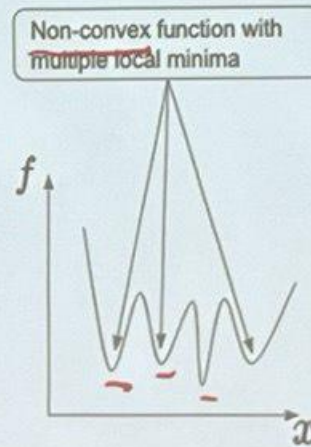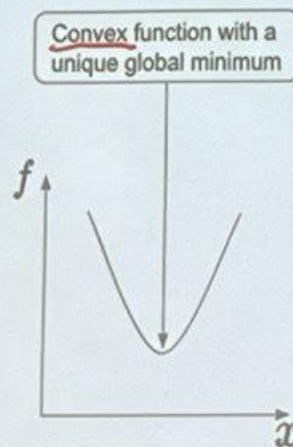
function with a nsisting of points

$$-\left(w^{\mathsf{T}}\mu - \frac{\lambda}{2} w^{\mathsf{T}} \Sigma w \right)$$

$$\left(\hat{y} - y \right)^2 = \left(\beta^{\mathsf{T}} x - y \right)^2 \quad \text{and} \quad \text{and} \, dy \, \text{arti}$$
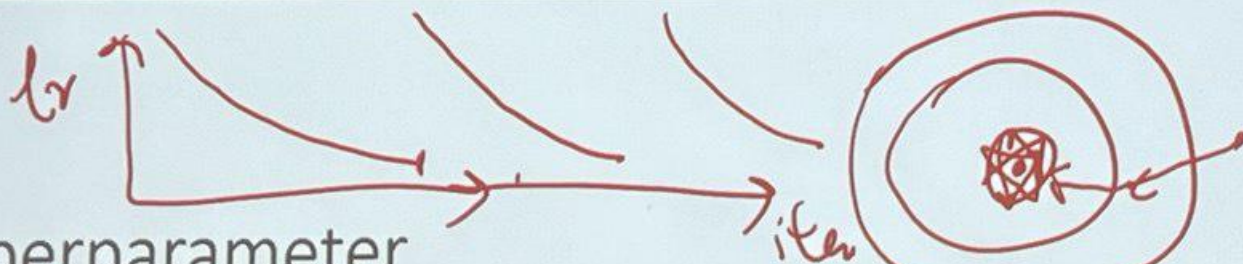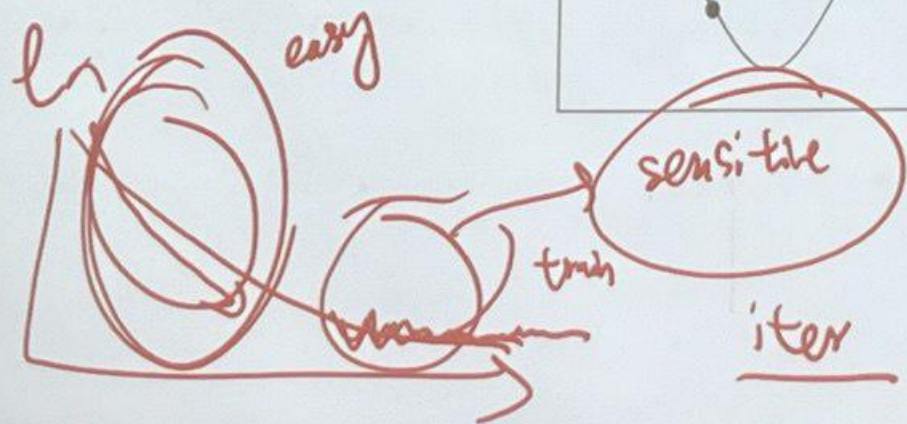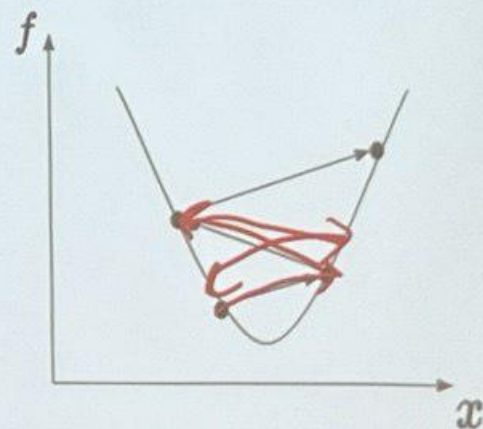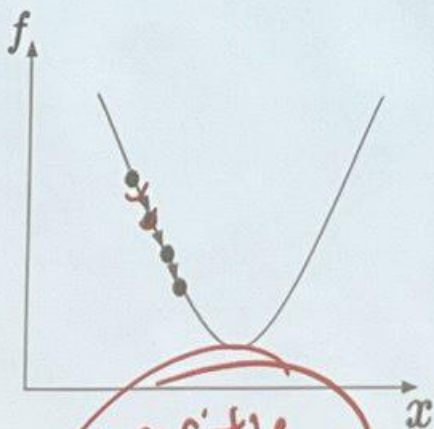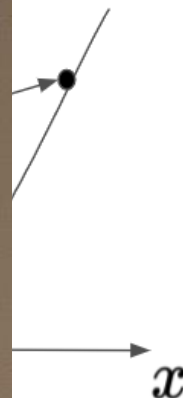
Bayesian optimization

- Bayesian optimization is an area that studies optimization problems using the Bayesian approach.

- Optimization aims at locating the optimal objective value (i.e., a global maximum or minimum) of all possible values or the corresponding location of the optimum over the search domain, also called the environment.

- The search process starts at a specific initial location and follows a particular policy to iteratively guide the following sampling locations, collect new observations, and refresh the guiding search policy.

Bayesian optimization

- The overall bayesian optimization process. The policy digests the historical observations and proposes a new sampling location. The environment governs how the (possibly noise-corrupted) observation at the newly proposed location is revealed to the policy. Our goal is to learn an efficient and effective policy that could navigate toward the global optimum as quickly as possible.

Contains the unknown real objective function, often noise corrupted

Environment

Sampling location

Observation

Proposed recommendation on where to sample next within the environment

Policy

The actual observation revealed due to the sampling action at the proposed location

The guiding principle that determines the sampling decision based on the historically collected observations

Gaussian process

- As a widely used stochastic process (able to model an unknown black-box function and the corresponding uncertainties of modeling), the Gaussian process takes the finite-dimensional probability distributions one step further into a continuous search domain that contains an infinite number of variables

- Any finite set of points in the domain jointly forms a multivariate Gaussian distribution.

- It is a flexible framework to model a broad family of functions and quantify their uncertainties, thus being a powerful surrogate model used to approximate the true underlying function.

Gaussian process

- Three example functions sampled from the prior process, where the majority of the functions fall within the 95% credible interval.
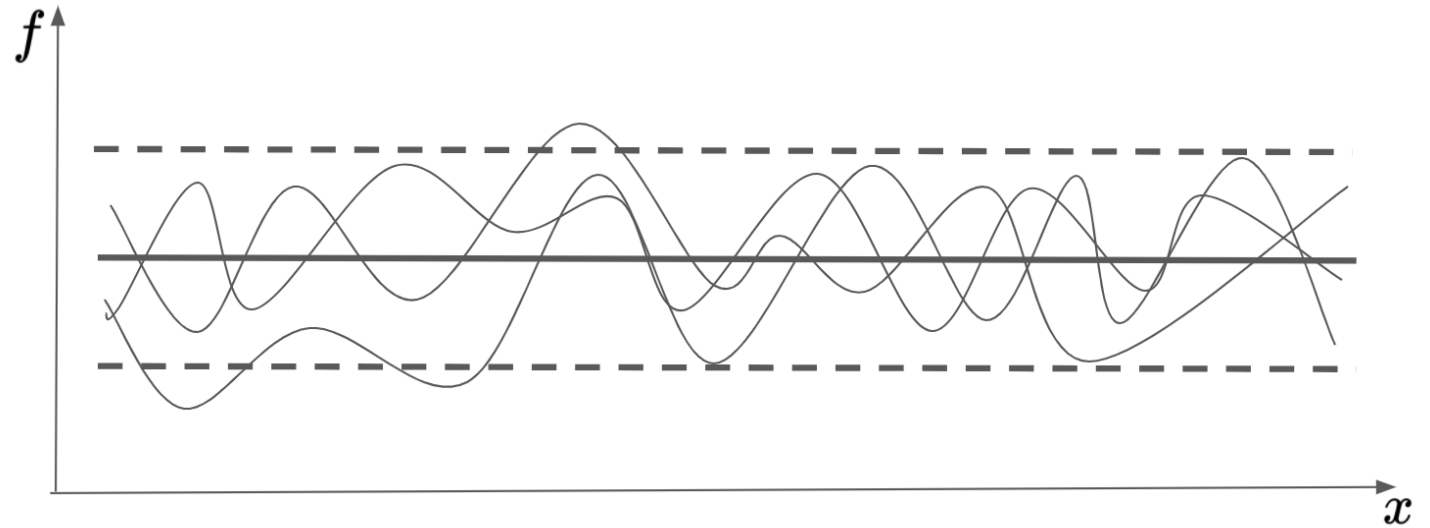
Gaussian process (cont'd)

- Updated posterior process after incorporating two exact observations in the Gaussian process. The posterior mean interpolates through the observations, and the associated variance reduces as we move nearer the observations.

The mean of the posterior process

Exact observations which the posterior mean passes through

95% credible interval of the posterior process
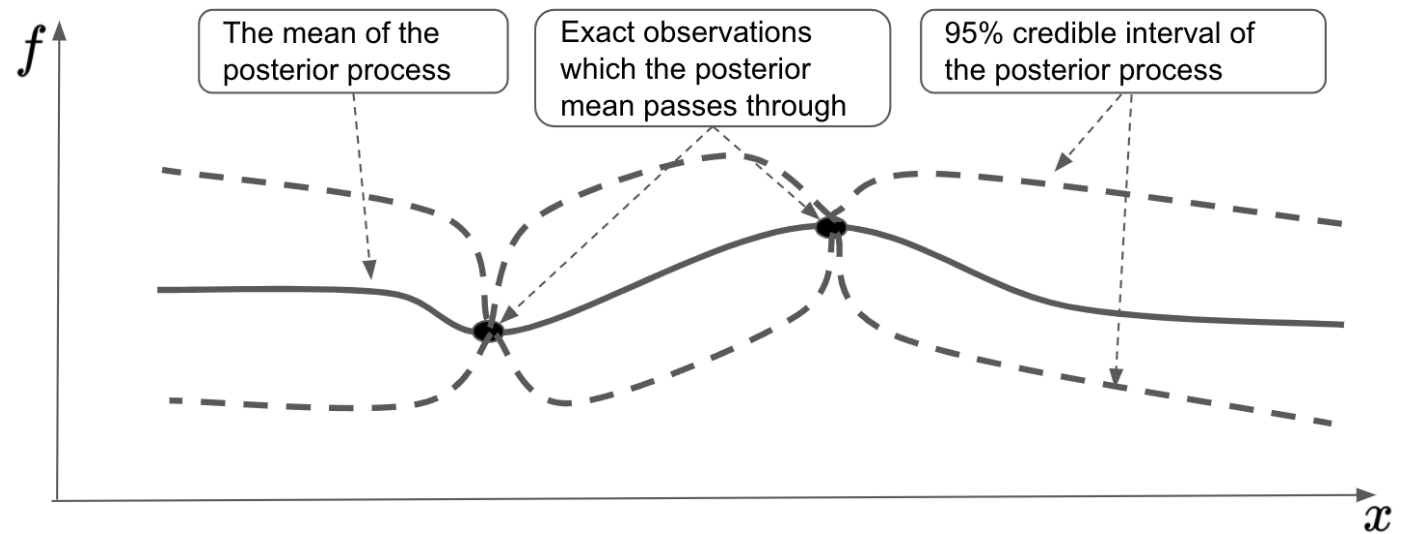
Acquisition function

- We need to build a policy (by maximizing the acquisition function) that absorbs the most updated information on the objective function and recommends the following most-promising sampling location in the face of uncertainties across the domain.

- An acquisition function is a manually designed mechanism that evaluates the relative potential of each candidate location in the form of a scalar score, and the location with the maximum score will be used as the next sampling choice.

- The acquisition function is also cheap to evaluate as a side computation since we need to evaluate it at every candidate location and then locate the maximum utility score, posing another (inner) optimization problem.

Acquisition function

Illustrating a sample acquisition function curve. The location that corresponds to the highest value of the acquisition function is the next location (parameter value of a trading strategy) to sample. Since there is no value-added if we were to sample those locations already sampled earlier, the acquisition function thus reports zero at these locations.

Acquisition function

The maximizer of the acquisition function becomes the next sampling point
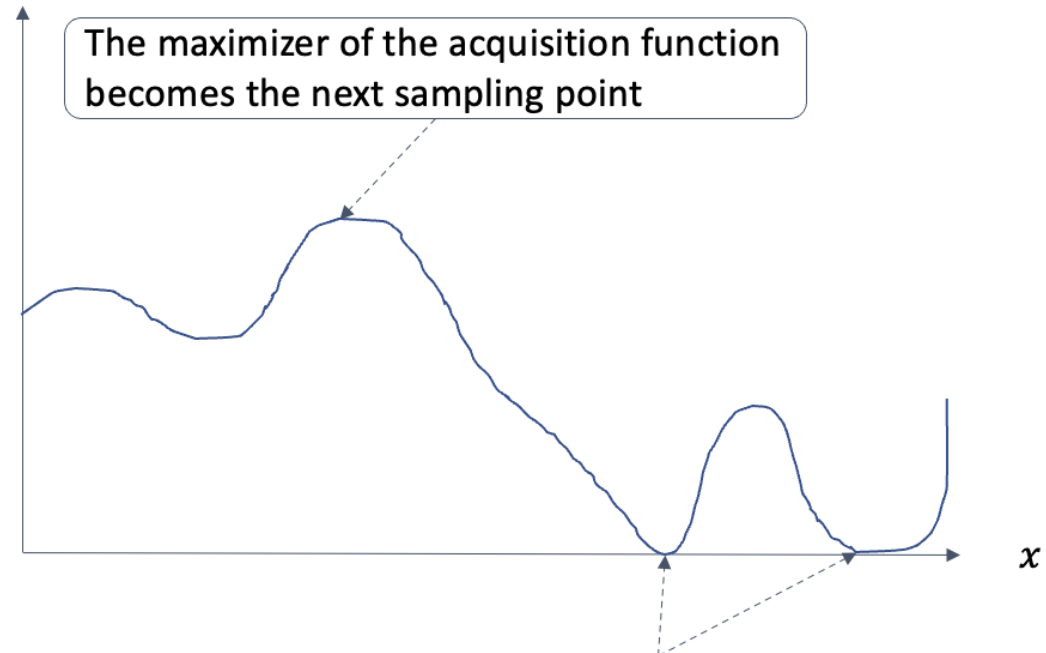
These values are zero as they are historical observations. That is, there is no additional information gained by sampling locations already sampled before.

x

Expected improvement

- The expected improvement chooses the historical maximum of the observed value as the benchmark for comparison upon selecting an additional sampling location.

- It also implicitly assumes that only one more additional sampling is left before the optimization process terminates.

- The expected marginal gain in utility (i.e., the acquisition function) becomes the expected improvement in the maximal observation, calculated as the expected difference between the observed maximum and the new observation after the additional sampling at an arbitrary sampling location.

EI Closed-Form Expression (optional)

- $u(\mathcal{D}_{n+1}) - u(\mathcal{D}_n) = \max\{f_{n+1}, f_n^*\} - f_n^* = \max\{f_{n+1} - f_n^*, 0\}$

- $\alpha_{\mathrm{EI}}(x_{n+1}; \mathcal{D}_n) = \mathbb{E}[u(\mathcal{D}_{n+1}) - u(\mathcal{D}_n)|x_{n+1}, \mathcal{D}_n]$

$$= \int \max\{f_{n+1} - f_n^*, 0\} p(f_{n+1}|x_{n+1}, \mathcal{D}_n) df_{n+1}$$

- $\alpha_{\mathrm{EI}}(x_{n+1}; \mathcal{D}_n) = (\mu_{n+1} - f_n^*)\Phi\left(\frac{\mu_{n+1} - f_n^*}{\sigma_{n+1}}\right) + \sigma_{n+1}\phi(\frac{\mu_{n+1} - f_n^*}{\sigma_{n+1}})$

- where f_n^* is the best-observed value so far, ϕ and Φ denote the probability and cumulative density function of a standard normal distribution at the tentative point x_{n+1}, respectively. μ_{n+1} and σ_{n+1} denote the posterior mean and standard deviation at x_{n+1}.

- The closed-form EI consists of two components: exploitation (the first term) and exploration (the second term). Exploitation means continuing sampling the neighborhood of the observed region with a high posterior mean, and exploration encourages sampling an unvisited area where the posterior uncertainty is high. The expected improvement acquisition function thus implicitly balances off these two opposing forces.

Upper confidence bound

- $\alpha_{\text{UCB}}(x_{n+1}; \mathcal{D}_n) = \mu_{n+1} + \beta_{n+1}\sigma_{n+1}$

- where β_{n+1} is a user-defined stage-wise hyper-parameter that controls the trade-off between the posterior mean and standard deviation. A low value of β_{n+1} encourages exploitation, and a high value of β_{n+1} leans more towards exploration.

The full BO loop

- The full Bayesian optimization loop featuring an iterative interaction between the unknown (black-box) environment and the decision-making policy that consists of a Gaussian process for probabilistic evaluation and acquisition function for utility assessment of candidate locations in the environment.

The recommended sampling location has a maximum utility based on the acquisition function

The observations are generated by assuming a specific observation model, i.e., a probability distribution conditioned by the true objective value and corrupted by random noise

Environment

Sampling location

Observation

Approximate as a surrogate function

Policy

Acquisition function

Gaussian process

Provides a probabilistic belief in the form of the posterior predictive distribution for decision making

The full BO workflow

- The entire BO loop by iteratively maximizing the current acquisition function, probing additional data, and updating posterior belief
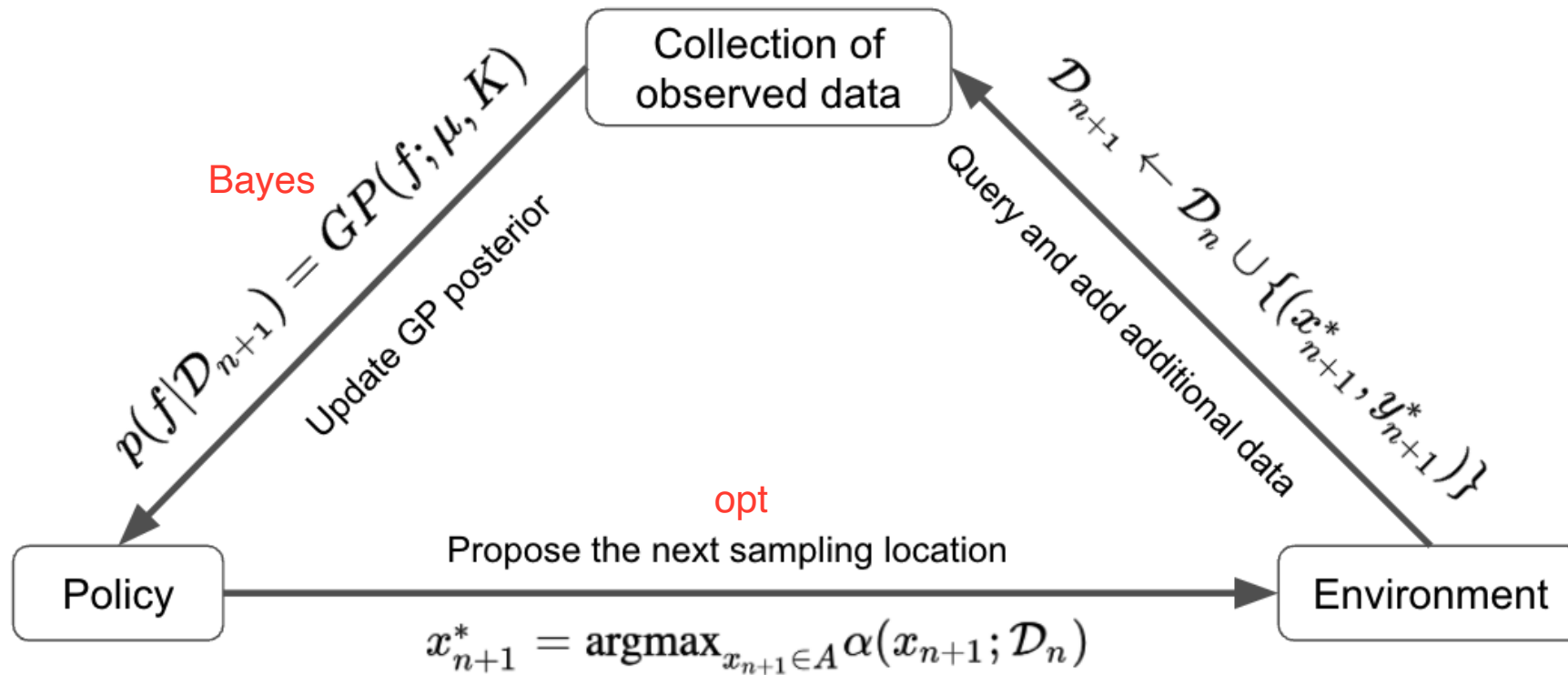
One-step lookahead policy

- The one-step lookahead policy by maximizing the expected marginal gain in the utility of the acquired observations

Evaluate an arbitrary candidate location for sampling

Putative observation based on the GP posterior belief

Build a larger fantasized dataset

Calculate the expected utility if we were to sample at the candidate location

$$x_{n+1} \rightarrow y_{n+1} \sim p(y_{n+1}|x_{n+1}, \mathcal{D}_n) \rightarrow \mathcal{D}_{n+1} = \mathcal{D}_n \cup (x_{n+1}, y_{n+1}) \rightarrow \mathbb{E}_{y_{n+1}}[u(\mathcal{D}_{n+1})|x_{n+1}, \mathcal{D}_n]$$

Existing utility as of existing dataset serving as the benchmark for comparison

$$\mathcal{D}_n \longrightarrow u(\mathcal{D}_n)$$

$$x^*_{n+1} = \text{argmax}_{x_{n+1} \in A} \alpha_1(x_{n+1}; \mathcal{D}_n) \longleftarrow \begin{aligned} &\alpha_1(x_{n+1}; \mathcal{D}_n) \\ &= \mathbb{E}_{y_{n+1}}[u(\mathcal{D}_{n+1})|x_{n+1}, \mathcal{D}_n] - u(\mathcal{D}_n) \\ &= \int u(\mathcal{D}_{n+1})p(y_{n+1}|x_{n+1}, \mathcal{D}_n)dy_{n+1} - u(\mathcal{D}_n) \end{aligned}$$

Select the optimal action by maximizing the specific one-step lookahead acquisition function

Expected marginal gain in utility used as the acquisition function in the one-step lookahead policy

Multi-step lookahead policy

- The multi-step lookahead optimal policy selects the best sampling location by maximizing the marginal **expected utility of the terminal dataset**.

The terminal dataset whose utility will be used to determine the next sampling location

The dataset containing collected observations, assumed to be noise free

Artificial sets of locations and observations modelled as random variables based on previously accumulated observations, including both actual and putative ones

$$\mathcal{D}_{n+\tau} = \mathcal{D}_n \cup \{(x_{n+1}, y_{n+1})\} \cup \{(x_{n+2}, y_{n+2})\} \cup \cdots \cup \{(x_{n+\tau}, y_{n+\tau})\}$$

The multi-step lookahead acquisition function defined as the expected marginal gain in the utility by acquiring the terminal dataset

Integrate out the randomness in both future locations (except for step one location as it is the current evaluation of interest) and observations

$$\alpha_\tau(x_{n+1}; \mathcal{D}_n) = \mathbb{E}[u(\mathcal{D}_{n+\tau})] - u(\mathcal{D}_n)$$
$$= \int \ldots \int u(\mathcal{D}_{n+\tau}) p(y_{n+1} | x_{n+1}, \mathcal{D}_n) \sum_{i=2}^{\tau} p(x_{n+i}, y_{n+i} | \mathcal{D}_{n+i-1}) dy_{n+1} d\{(x_{n+i}, y_{n+i})\} - u(\mathcal{D}_n)$$

Make the optimal action that maximizes the multi-step lookahead acquisition function

$$x^*_{n+1} = \mathrm{argmax}_{x_{n+1} \in A} \alpha_\tau(x_{n+1}; \mathcal{D}_n)$$